PAC learning + uniform convergence **CPSC 532S: Modern Statistical Learning Theory** 11 January 2022 cs.ubc.ca/~dsuth/532S/22/

Admin

- Now online until (at least) February 7
- A1 is up; get at it!

 - Due 11:59pm Thursday the 20th; do alone Should be able to do all of it after today • Might require brushing up on linear algebra a bit Submission instructions coming by this weekend
- We're making progress towards fitting in the cap :)
 - If you're pretty sure you'll drop, please don't wait until the last day, so people on the waitlist can plan appropriately
 - (But also, please don't drop if you want to stay!)

Last time: definitions • $x \sim \mathcal{D}_x$, a distribution over \mathcal{X} ; $y = f(x) \in \mathcal{Y}$; $S = ((x_1, y_1), \dots, (x_n, y_n))$ • Want $h: \mathcal{X} \to \mathcal{Y}$ minimizing $L_{\mathcal{D}_x, f}(h) = \Pr_{x \sim \mathcal{D}_x} \left(h(x) \neq f(x) \right)$ • Training loss $L_S(h) = \frac{1}{n} \sum_{i=1}^n \begin{cases} 1 & \text{if } h(x_i) \neq y_i \\ 0 & \text{if } h(x_i) = y_i \end{cases}$

- Empirical risk minimization (ERM): choose h minimizing $L_{s}(h)$ from a *hypothesis class* \mathcal{H} of functions $h: \mathcal{X} \to \mathcal{Y}$
- To start with something simple, assume realizability: there is an $h^* \in \mathcal{H}$ with $L_{\mathcal{D}_r, f}(h^*) = 0$
 - Implies (a.s.) that $L_{S}(h^{*}) = 0$

Realizable, finite \mathcal{H}

- Would like to show $\Pr_{\mathbf{c}}\left(L_{\mathscr{D}_x,f}(h_S) \leq \varepsilon\right) \geq 1 \delta$, i.e. $\Pr(L(h_S) > \varepsilon) < \delta$
- Call \mathscr{H}_B the set of "bad" hypotheses, $\left\{h \in \mathscr{H} : L_{\mathscr{D}_x, f}(h) > \varepsilon\right\}$
- $M = \{S : \exists h \in \mathcal{H}_B . L_S(h) = 0\}$ is set of "bad" samples
 - If $L_{\mathcal{D}_r,f}(h_S) > \varepsilon$, then $S \in M$
- For a "worst-case ERM", we have

• $h_S \in \arg\min_{h \in \mathscr{H}} L_S(h)$: realizable means $L_S(h_S) = 0$, but maybe $L_{\mathscr{D}_r, f}(h_S) > 0$ **Union bound** $Pr(A \cup B) = Pr(A) + Pr(B) - Pr(A \cap B)$ $\leq \Pr(A) + \Pr(B)$

$\Pr(L(h_{S}) > \varepsilon) = \mathcal{D}_{x}^{n}(M) = \mathcal{D}_{x}^{n} \left(\bigcup_{h \in \mathcal{H}_{B}} \{S : L_{S}(h) = 0\} \right) \leq \sum_{h \in \mathcal{H}_{B}} \mathcal{D}_{x}^{n} \left(\{S : L_{S}(h) = 0\} \right)$



 $\Pr(L(h_S) > \varepsilon) \le \sum \mathscr{D}_x^n \left(\{ S : L_S(h) = 0 \} \right)$ $h \in \mathcal{H}_{R}$

- $\mathscr{D}_{r}^{n}(\{S: L_{S}(h)=0\}) = \mathscr{D}_{r}^{n}(\{S: \forall i, h(x_{i})=f(x_{i})\})$
- Because it's iid, this is just $\iint \mathscr{D}_{\chi}(x)$ i=1• But $\mathscr{D}_{x}(\{x_{i}:h(x_{i})=y_{i}\})=1-L$ $\Pr(L(h_S) > \varepsilon) < \sum (1 - \varepsilon)^n$ $h \in \mathcal{H}_{B}$ $\leq |\mathscr{H}_B|(1-\varepsilon)^n \leq$





$$\{x_i : h(x_i) = f(x_i)\})$$

If a hypothesis is bad, we're likely to sample at least one x_i where it's wrong

$$L_{\mathcal{D}_x,f}(h) < 1 - \varepsilon \quad \text{since } h \in \mathcal{H}_B$$

Not too likely to get unlucky with any bad hypothesis

$$\leq |\mathscr{H}|(1-\varepsilon)^n \leq |\mathscr{H}|e^{-\varepsilon n}$$



Finite \mathscr{H} are (realizable) PAC-learnable . We showed that $\Pr\left(L_{\mathscr{D}_{x},f}(h_{S}) < \varepsilon\right) \ge 1 - |\mathscr{H}|e^{-\varepsilon n}$ • Or: if we have $n \ge \frac{1}{\varepsilon} \left(\log |\mathscr{H}| + \log \frac{1}{\delta} \right)$, $L_{\mathscr{D}_x, f}(h) \le \varepsilon$ with prob. at least $1 - \delta$. • Or: error is at most $\frac{1}{n} \left(\log |\mathcal{H}| + \log \frac{1}{\delta} \right)$ with high probability

- - If \mathcal{H} is realizable for \mathcal{D}_{x} and f,

 - will return a hypothesis h with $L_{\mathcal{D}_r,f}(h) \leq \varepsilon$
 - with probability at least 1δ over the choice of examples

• \mathscr{H} is PAC learnable if there is a function $n_{\mathscr{H}}: (0,1)^2 \to \mathbb{N}$ and a learning alg. s.t.: • For every $\varepsilon, \delta \in (0,1)$, for every \mathscr{D}_x over \mathscr{X} , and every labeler $f: \mathscr{X} \to \{0,1\}$:

• then running the algorithm on $n \ge n_{\mathscr{H}}(\varepsilon, \delta)$ i.i.d. examples from \mathscr{D}_x labeled by f,









a	b	С	d	е	f	У
0	1	1	0	1	1	+
0	0	1	0	0	1	+
0	1	1	1	1	1	-
1	1	1	0	1	1	+
0	1	0	0	1	0	-
1	0	1	0	0	0	-
1	1	1	1	0	1	?

\mathscr{H} : conjunctions of the form $a \wedge \overline{c} \wedge f$

- Start with $a \wedge \bar{a} \wedge \cdots \wedge f \wedge f$
- Cross out bits inconsistent with the positives



a	b	С	d	е	f	У
0	1	1	0	1	1	+
0	0	1	0	0	1	+
0	1	1	1	1	1	-
1	1	1	0	1	1	+
0	1	0	0	1	0	_
1	0	1	0	0	0	
1	1	1	1	0	1	?

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a	b	С	d	е	f	У
0	1	1	0	1	1	+
0	0	1	0	0	1	+
0	1	1	1	1	1	-
1	1	1	0	1	1	+
0	1	0	0	1	0	-
1	0	1	0	0	0	-
1	1	1	1	0	1	?

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a	b	С	d	е	f	У
0	1	1	0	1	1	+
0	0	1	0	0	1	+
0	1	1	1	1	1	-
1	1	1	0	1	1	+
0	1	0	0	1	0	_
1	0	1	0	0	0	-
1	1	1	1	0	1	?

\mathscr{H} : conjunctions of the form $a \wedge \overline{c} \wedge f$

- Start with $a \wedge \bar{a} \wedge \cdots \wedge f \wedge f$
- Cross out bits inconsistent with the positives



Example: Boolean conjunctions $c \wedge \overline{d} \wedge f$ $|\mathcal{H}| = 3^d: \left[\frac{1}{\varepsilon} \left(d \log(3) + \log \frac{1}{\delta}\right)\right]$ samples enough \mathcal{H} : conjunctions of the form $a \wedge \overline{c} \wedge f$

a	b	С	d	е	f	У
0	1	1	0	1	1	+
0	0	1	0	0	1	+
0	1	1	1	1	1	-
1	1	1	0	1	1	+
0	1	0	0	1	0	-
1	0	1	0	0	0	-
1	1	1	1	0	1	?

Algorithm:

- Start with $a \wedge \bar{a} \wedge \cdots \wedge f \wedge \bar{f}$
- Cross out bits inconsistent with the positives

Assuming realizability, this gives an ERM

- Algorithm makes every + example a +
- True function f is only "less specific" that h(x) = - for anything truly -





nc	h	

- Every practical \mathscr{H} is finite if you put it on a computer
- Total size of weights in a big deep network is typically up to ~1GB
- Say 100MB, $8 * 100 * 2^{20}$ bits, so there are $2^{25 \cdot 2^{25}}$ possible networks

•
$$\log\left(2^{25 \cdot 2^{25}}\right) = 252^{25}\log(2)$$

- If we want, say, $\varepsilon = 0.1$ (90% accuracy): 2.5 billion training points
- (Plus, we don't actually do ERM with realizable, fixed hypothesis classes...)

So, are we done?

 ≈ 252 million

PAC learnability and computational efficiency

- Valiant (1984)'s formulation required the algorithm to run in polynomial time
- We're going to think about runtime separately, but be aware many authors keep that in the definition
- in the USSR; much more on their work soon

RESEARCH CONTRIBUTIONS

Artificial Intelligence and Language Processing

A Theory of the Learnable

David Waltz Editor

L. G. VALIANT



Communications of the ACM, 1984

Independent(?), closely related development by Vapnik and Chervonenkis







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PAC learnability and computational efficiency

- A class that can be PAC-learned but not in polynomial time (assuming P = BPP and $P \neq NP$):
- 3-DNF: 3-term clauses in *disjunctive normal form* $T_1 \vee T_2 \vee T_3$

terms are conjunctions: $T_1 = a \wedge \overline{c} \wedge \cdots$

- Graph 3-coloring reduces to learning 3-DNFs
- But: 3-DNF \subset 3-CNF, $\bigwedge (a \lor b \lor c)$, $T_1 \lor T_2 \lor T_3 = \qquad \bigwedge \qquad (u \lor v \lor w)$ $u \in T_1, v \in T_2, w \in T_3$
- and 3-CNF can be efficiently PAC-learned

(Sec 1.4-1.5 PDF through UBC: log in here)



Computational Limitations on Learning from Examples

(1988)

LEONARD PITT

University of Illinois, Urbana-Champaign, Urbana, Illinois

AND

LESLIE G. VALIANT

Harvard University, Cambridge, Massachusetts







(pause)

Non-realizable (agnostic) learning

- What if there's some noise in the data?
 - e.g. two identical xs might have different ys
- Instead of saying $x \sim \mathscr{D}_x$ and y = f(x), have joint distribution $(x, y) \sim \mathscr{D}_x$
- \mathscr{D} is a distribution over domain $\mathscr{X} = \mathscr{X} \times \mathscr{Y}$ • Population loss is now $L_{\mathcal{D}}(h) = \Pr(h(x) \neq y) = \mathcal{D}\left(\left\{(x, y) : h(x) \neq y\right\}\right)$ • Empirical loss still $L_S(h) = \frac{1}{n} \sum_{i=1}^n \begin{cases} 1 & \text{if } h(x_i) \neq y_i \\ 0 & \text{if } h(x_i) = y_i \end{cases}$

• Notice this is the population loss over the empirical distribution on S



Empirical loss still $L_{S}(h) = \frac{1}{n} \sum_{i=1}^{n} \begin{cases} 1 & \text{if } h(x_{i}) \neq y_{i} \\ 0 & \text{if } h(x_{i}) = y_{i} \end{cases}$

Non-realizable (agnostic) learning Empirical distribution \hat{P} : discrete distribution, uniform over samples $\hat{P}(s) = \frac{1}{h} \frac{2}{\epsilon_{1}} \mathbb{1}(x \in S)$ density $\rho(x) = d P(x)$ • Population loss is now $L_{\mathcal{D}}(h) = \Pr(h(x) \neq y) = \mathcal{D}\left(\left\{(x, y) : h(x) \neq y\right\}\right)$

• Notice this is the population loss over the empirical distribution on S

General loss functions

- So far we've only looked at the error rate
- More generation

ally, allow a loss function
$$\ell : \mathcal{H} \times \mathcal{Z} \to \mathbb{R}$$

 $L_{\mathcal{D}}(h) = \mathbb{E}_{z \sim \mathcal{D}}[\ell(h, z)]$
 $L_{S}(h) = \frac{1}{n} \sum_{i=1}^{n} \ell(h, z_{i})$

- 0-1 loss: $\mathscr{Z} = \mathscr{X} \times \mathscr{Y}, \ \mathscr{E}_{0-1}(h,$ gives classification error rate
- Square loss ($\mathcal{Y} \subseteq \mathbb{R}$) is $\mathcal{C}_{SO}(h, (x \in \mathbb{R}))$
- Tons of other options!

$$(x, y)) = \begin{cases} 0 & \text{if } h(x) = y \\ 1 & \text{if } h(x) \neq y \end{cases}$$

$$(x, y)) = (h(x) - y)^2$$

Agnostic PAC

• \mathcal{H} is agnostically PAC learnable for a set \mathcal{I} and loss $\ell : \mathcal{H} \times \mathcal{I} \to \mathbb{R}$ if there is a function $n_{\mathscr{H}}: (0,1)^2 \to \mathbb{N}$ and a learning algorithm such that: For every $\varepsilon, \delta \in (0,1)$ and every distribution \mathcal{D} over \mathcal{X} , then running the algorithm on $n \ge n_{\mathscr{H}}(\varepsilon, \delta)$ i.i.d. examples from \mathscr{D} will return a hypothesis $h \in \mathcal{H}$ with $L_{\mathcal{D}}(h) \leq \inf L_{\mathcal{D}}(h') + \varepsilon$ $h' \subset \mathcal{H}$

with probability at least $1 - \delta$ over the choice of examples

- We don't (necessarily) get error arbitrarily close to 0 anymore! . Realizable means $\inf_{h'\in \mathcal{H}} L_{\mathscr{D}}(h') = 0$: then, this is same as realizable PAC
 - Otherwise, $\inf L_{\mathscr{D}}(h')$ is the best loss achievable in \mathscr{H} $h' \in \mathcal{H}$

Improper Agnostic PAC

• \mathscr{H} is improperly agnostically PAC learnable in \mathscr{H}' for \mathscr{I} , loss $\mathscr{l} : \mathscr{H}' \times \mathscr{I} \to \mathbb{R}$ if there is a function $n_{\mathscr{H}}: (0,1)^2 \to \mathbb{N}$ and a learning algorithm such that: For every $\varepsilon, \delta \in (0,1)$ and every distribution \mathcal{D} over \mathcal{X} , then running the algorithm on $n \ge n_{\mathscr{H}}(\varepsilon, \delta)$ i.i.d. examples from \mathscr{D} will return a hypothesis $h \in \mathcal{H}' \supset \mathcal{H}$

with probability at least $1 - \delta$ over the choice of examples

- e.g.: learn a polynomial classifier almost as good as the best linear classifier, or learn a 3-DNF function with a 3-CNF
- Shai+Shai: "there is nothing improper about representation-independent learning"

$$\mathscr{V} \text{ with } L_{\mathscr{D}}(h) \leq \inf_{h' \in \mathscr{H}} L_{\mathscr{D}}(h') + \varepsilon$$







- What can we say about $\inf L_{\mathscr{D}}(h)$? $h \in \mathcal{H}$
- It's at least as big as the **Bayes error**: error of the Bayes-optimal classifier $f_{\mathcal{D}}(x) = \begin{cases} 1 & \text{if } \Pr(y = 1 \mid x) \ge \frac{1}{2} \\ 0 & \text{otherwise} \end{cases}$
- This is the best conceivable classifier. (See homework!) The best classifier in \mathscr{H} might be this good, or it might be worse
- Other losses have corresponding Bayes-optimal predictors; for reasonable classification losses, it's this same $f_{\mathcal{O}}$.

Bayes error rate

Summary

- PAC learnability: realizable, agnostic, improper
 - Finite classes: realizable PAC by ERM with $n \ge \frac{1}{\varepsilon} \left(\log |\mathcal{H}| + \log \frac{1}{\delta} \right)$
- Extended definition to general loss functions on $\mathcal{X},$ e.g. $\mathcal{X}\times\mathcal{Y}$
- Bayes classifier / Bayes error rate
- Next time: finite classes in the agnostic case + uniform convergence