Value of Information and Control

Computer Science cpsc322, Lecture 35 (Textbook Chpt 9.4)

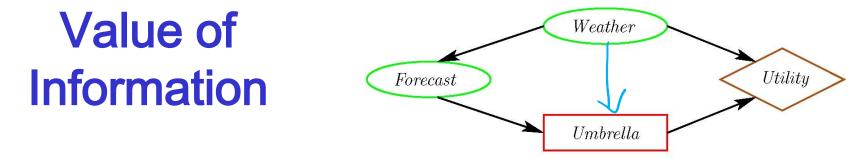
April, 14, 2010



CPSC 322, Lecture 35

Lecture Overview

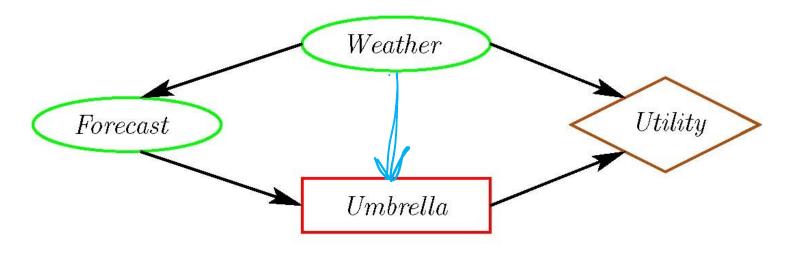
- Value of Information
- Value of Control
- Course Summary



- What would help the agent make a better *Umbrella* decision?
- The value of information of a random variable X for decision D is: EU(Knowing X)-EU(Tknowing X)^L
 the utility of the network with an arc from X to D minus the utility of the network without the arc.
- Intuitively:
 - The value of information is always >>
 - It is positive only if the agent changes the policy

Value of Information (cont.)

• The value of information provides a bound on how much you should be prepared to pay for a sensor. How much is a **perfect** weather forecast worth?



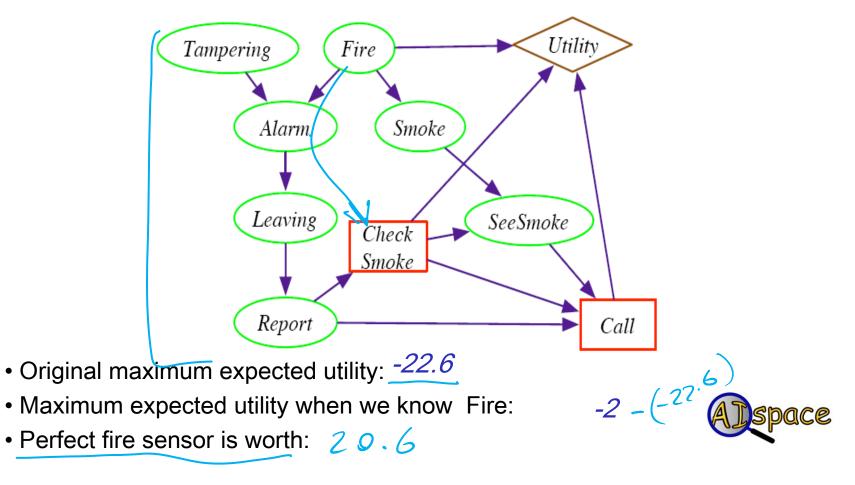
- Original maximum expected utility:
- Maximum expected utility when we know Weather: 91
- Better forecast is worth at most

CPSC 322, Lecture 33

77

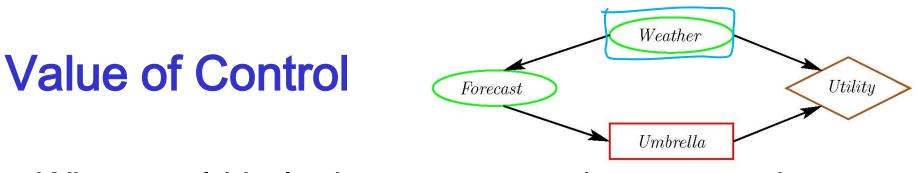
Value of Information

• The value of information provides a bound on how much you should be prepared to pay for a sensor. How much is a **perfect** fire sensor worth?



Lecture Overview

- Sequential Decisions
 - Optimal Policy
 - Variable Elimination
- Value of Information
- Value of Control



• What would help the agent to make an even better *Umbrella* decision? To maximize its utility.

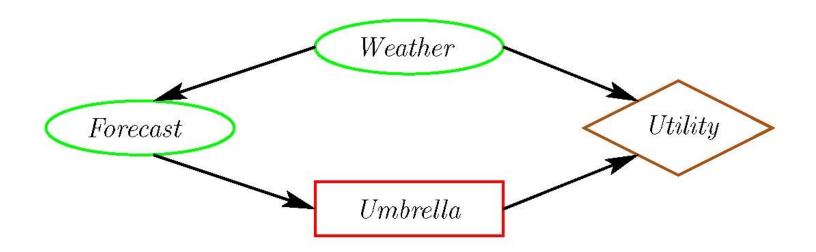
	Weather	Umbrella		Value	
	Rain	true		70	
	Rain	false		0	
	noRain	true		20	
$\overline{\langle}$	noRain	false		100	
	_				

• The value of control of a variable X is :

the utility of the network when you make X a decision variable **minus** the utility of the network when X is a random variable.

Value of Control

• What if we could control the weather?

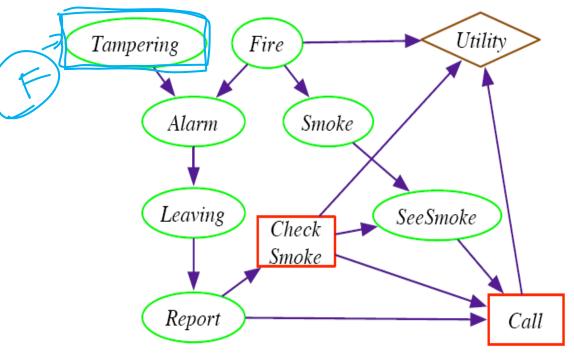


- Original maximum expected utility: 77
- Maximum expected utility when we control the weather: 100
- Value of control of the weather: 23



Value of Control

What if we control Tampering?



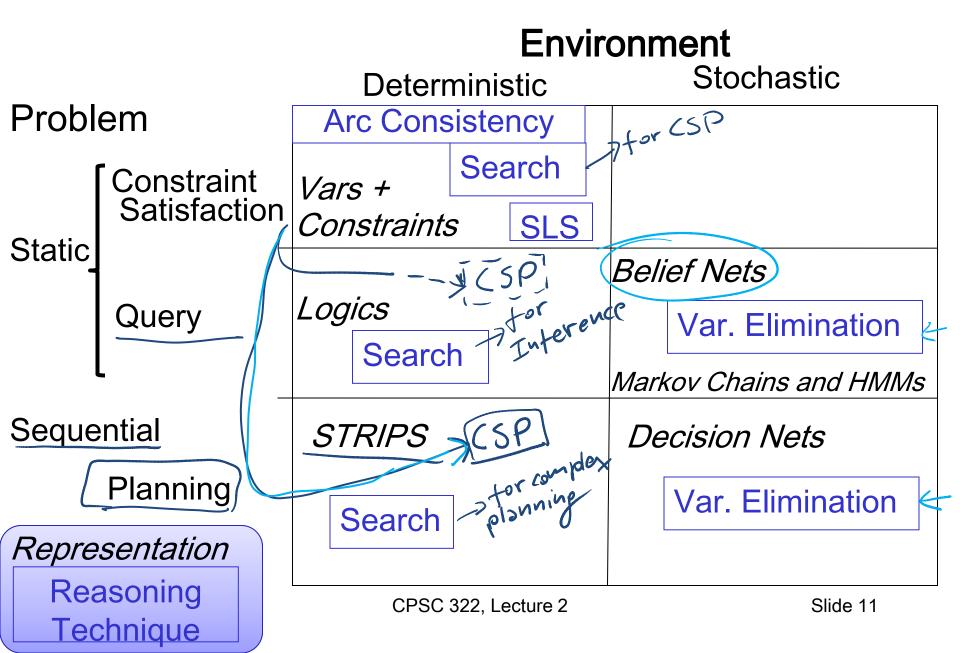
- Original maximum expected utility:
- Maximum expected utility when we control the Tampering: -20.7
- Useful to estimate how much it is worth to add..... security to mparing OPSC 322, Lecture 33

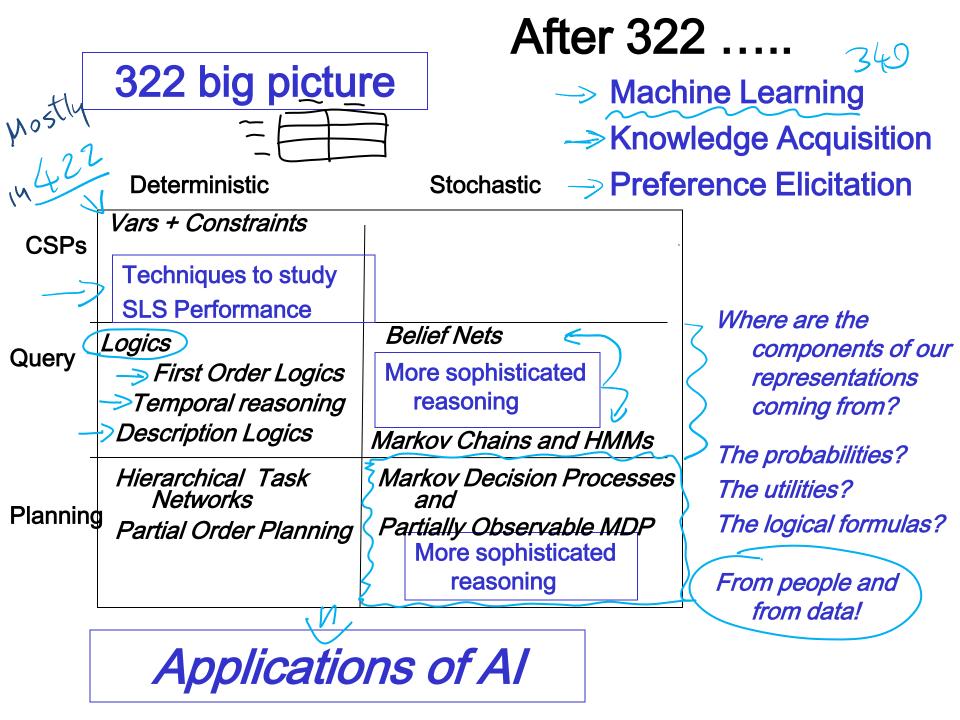
-22.6

Learning Goals for today's (and Mon) classes You can:

- Represent sequential decision problems as decision networks. And explain the non forgetting property
- Verify whether a possible world satisfies a policy and define the expected value of a policy
- Compute the <u>number of policies</u> for a decision problem
- Compute the optimal policy by Variable Elimination
- Compute value of information and control

Cpsc 322 Big Picture





TA Evaluation Forms

Please, evaluate only TAs you have interacted with for this course 15c **Teaching Assistants**

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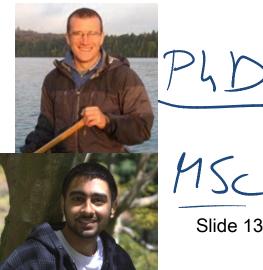




- Kenneth Alton kalton@cs.ubc.ca (will be starting Jan 18)
- Scott Helmer shelmer@cs.ubc.ca
- Sunjeet Singh

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CPSC 322. Lecture 1



Announcements

- Fill out Online Teaching Evaluations Survey.
- It closes on Apr 17th

• FINAL EXAM: Mon Apr 19, 12:00-3:00 pm DMP 310 (NOT regular room) 67p5

Final will comprise: 10 -15 short questions + 3-4 problems

- · Work on all practice exercises USTA assessments
- While you revise the learning goals, work on review questions
 I may even reuse some verbatim ^(C)
- Come to remaining Office hours! I am offering two hours on Fri (10-12)