- Rules discussion:
    - Happy with the prior knowledge and 3D information as is.
    - OC dropped the living room context, but will still try to make it realistic. We are a bit unhappy with this so might want to request that this is made as clear as possible [Dave]
    - Now that they give 3D models, I assume we can use 3D information for recognition, but they still mention that visual sensors must be used. We will email to confirm that the laser range data is acceptable to be used directly in the recognition method (this kind of goes against the exact wording of the rules) [Dave]
    - We want to know what the data formats are as soon as possible. Pooyan mentioned that the organizers will list the data sources (websites to use) rather than providing the actual models.
    - We want to suggest adding contextual information between objects (as in, "keys on top of TV" is listed in the list.txt file). Team thinks we could use this. Would make up partially for not having proper context like [Tristram to send to Dave]
- Catherine investigated Gigabit router and will get it soon
- Everyone should get on the mailing lists:
    - https://mailman.srv.cs.cmu.edu/mailman/listinfo/semantic-robot-vision-challenge
    - https://mailman.srv.cs.cmu.edu/mailman/listinfo/semantic-robot-vision-challenge-discuss
- Things from last week which still need to be looked at:
    - Bumblebee driver in ROS still needs to be done [Marius and Dave and Catherine]
    - We should look at wrapping player into ROS and using this for our bot [Marius, I forgot if you going to look at this, or should someone here do that?]
    - Look at how to add the robot into Gazebo [Dave and Thomas]
    - Buy another several bumblebee cables [Dave]
- Ankur talked with Sancho about his recognition code. Plans to have it running by Friday dry-run.
- Catherine ran Scott's code a bit, and Catherine and Ankur will look at it more Thursday.
- Plan is to run a full dry-run Friday at 1pm in x209.
- Dave to add James to the SVN group.
- Web download script is fixed.