

Stochastic Variational Inference

Reza Babanezhad

rezababa@cs.ubc.ca

Outline

- VI
- Monte Carlo Gradient Approximation
- Stochastic Variational Inference(SVI)
- Bridging the GAP

VI

- VI can be used to approximate the posterior distribution
- Objective is minimizing the KL divergence between the approximate q and joint distribution p

$$\begin{aligned}\log p(x) &= \mathbb{E}_{q_\theta(z|x)}[\log p(x, z) - \log q_\theta(z|x)] + D_{KL}(q_\theta(z|x)||p(z|x)) \\ &\geq \mathbb{E}_{q_\theta(z|x)}[\log p(x, z) - \log q_\theta(z|x)] = \mathcal{L}.\end{aligned}$$

- To optimize ELBO, we can use the coordinate descent or ascent.
- Problems:
 - Computing the gradient of expectation
 - In each iteration, we need to go over all data.

Monte Carlo Gradient Approximation

- In ELBO some expectations cannot be computed in closed form.
- To solve it, let divide it to two parts:
$$\underline{\mathcal{L}} = \mathbb{E}_q[f] + h(X, \Psi)$$
 - h : closed form part.
 - f : its expectation does not have closed form
- The gradient:
$$\nabla_{\psi} \mathcal{L} = \nabla_{\psi} \mathbb{E}_q[f(\theta)] + \nabla_{\psi} h(X, \Psi)$$
- The first term in RHS is intractable.
- Goal: finding a Monte Carlo approximation for intractable term.

Monte Carlo Gradient Approximation

$$\begin{aligned}\nabla_{\psi} \mathbb{E}_q[f(\theta)] &= \nabla_{\psi} \int_{\theta} f(\theta) q(\theta|\psi) d\theta \\&= \int_{\theta} f(\theta) \nabla_{\psi} q(\theta|\psi) d\theta \\&= \int_{\theta} f(\theta) q(\theta|\psi) \nabla_{\psi} \ln q(\theta|\psi) d\theta.\end{aligned}$$

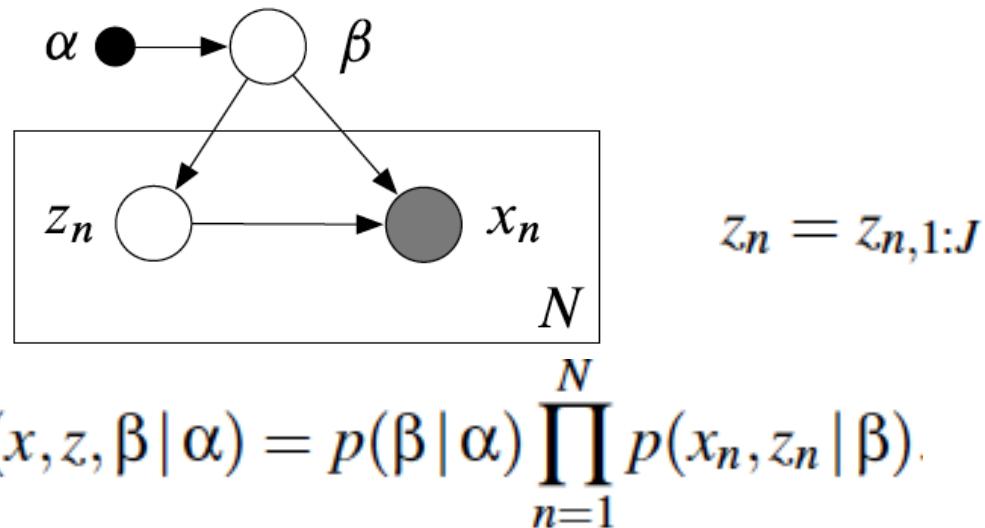
$$\nabla_{\psi} \mathbb{E}_q[f(\theta)] = \mathbb{E}_q[f(\theta) \nabla_{\psi} \ln q(\theta|\psi)]$$

$$\nabla_{\psi} \mathbb{E}_q[f(\theta)] \approx \frac{1}{S} \sum_{s=1}^S f(\theta^{(s)}) \nabla_{\psi} \ln q(\theta^{(s)}|\psi), \quad \theta^{(s)} \stackrel{iid}{\sim} q(\theta|\psi)$$

$$\psi^{(t+1)} = \psi^{(t)} + \rho_t \nabla_{\psi} h(X, \Psi^{(t)}) + \rho_t \zeta_t \quad \zeta_t = \nabla_{\psi_t} \mathbb{E}_q[f(\theta)]$$

SVI

- Model



- Our goal: approximate the posterior

$$p(\beta, z | x)$$

- Locally independence $p(x_n, z_n | x_{-n}, z_{-n}, \beta, \alpha) = p(x_n, z_n | \beta, \alpha).$

SVI

- Extra assumption
 - posterior is from exponential family

$$p(\beta | x, z, \alpha) = h(\beta) \exp\{\eta_g(x, z, \alpha)^\top t(\beta) - a_g(\eta_g(x, z, \alpha))\},$$

$$p(z_{nj} | x_n, z_{n,-j}, \beta) = h(z_{nj}) \exp\{\eta_\ell(x_n, z_{n,-j}, \beta)^\top t(z_{nj}) - a_\ell(\eta_\ell(x_n, z_{n,-j}, \beta))\}.$$

- h : base measure
- t : sufficient statistics
- η : natural parameter
- a : partition function or log normalizer

SVI

- Conjugacy relation between the global variable and local variable

$$p(x_n, z_n | \beta) = h(x_n, z_n) \exp\{\beta^\top t(x_n, z_n) - a_\ell(\beta)\}.$$

- Prior of global variable is also exponential

$$p(\beta) = h(\beta) \exp\{\alpha^\top t(\beta) - a_g(\alpha)\}$$

- Posterior

$$p(z, \beta | x) = \frac{p(x, z, \beta)}{\int p(x, z, \beta) dz d\beta}.$$

SVI: Exp. Family

$$p(x|\lambda) = h(x)e^{\theta T(x) - A(\theta)}$$

- 2 main properties:

$$\mathbb{E}_p[T(x)] = \nabla_\lambda A(\theta)$$

$$\mathbb{E}_p[(T(x) - \mathbb{E}_p[T(x)])(T(x) - \mathbb{E}_p[T(x)])^T] = \nabla_\lambda^2 A(\theta)$$

SVI

- Example of exp. family

Gaussian $p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\|x-\mu\|^2/(2\sigma^2)}$

$$x \in \mathbb{R}$$

Bernoulli $p(x) = \alpha^x (1 - \alpha)^{1-x}$

$$x \in \{0, 1\}$$

Binomial $p(x) = \binom{n}{x} \alpha^x (1 - \alpha)^{n-x}$

$$x \in \{0, 1, 2, \dots, n\}$$

Multinomial $p(x) = \frac{n!}{x_1!x_2!\dots x_n!} \prod_{i=1}^n \alpha_i^{x_i}$

$$x_i \in \{0, 1, 2, \dots, n\}, \sum_i x_i = n$$

Exponential $p(x) = \lambda e^{-\lambda x}$

$$x \in \mathbb{R}^+$$

Poisson $p(x) = \frac{e^{-\lambda}}{x!} \lambda^x$

$$x \in \{0, 1, 2, \dots\}$$

Dirichlet $p(x) = \frac{\Gamma(\sum_i \alpha_i)}{\prod_i \Gamma(\alpha_i)} \prod_i x_i^{\alpha_i - 1}$

$$x_i \in [0, 1], \sum_i x_i = 1$$

SVI

- Natural parameterization of Bernoulli

$$\begin{aligned} p(x) &= \alpha^x (1 - \alpha)^{1-x} \\ &= \exp \left[\log(\alpha^x (1 - \alpha)^{1-x}) \right] \\ &= \exp [x \log \alpha + (1 - x) \log (1 - \alpha)] \\ &= \exp \left[x \log \frac{\alpha}{1 - \alpha} + \log (1 - \alpha) \right] \\ &= \exp [x \theta - \log(1 + e^\theta)] \end{aligned}$$

$$T(x) = x \quad \theta = \log \frac{\alpha}{1 - \alpha} \quad A(\theta) = \log(1 + e^\theta)$$

SVI: ELBO

$$\begin{aligned}\log p(x) &= \log \int p(x, z, \beta) dz d\beta \\&= \log \int p(x, z, \beta) \frac{q(z, \beta)}{q(z, \beta)} dz d\beta \\&= \log \left(\mathbb{E}_q \left[\frac{p(x, z, \beta)}{q(z, \beta)} \right] \right) \\&\geq \mathbb{E}_q[\log p(x, z, \beta)] - \mathbb{E}_q[\log q(z, \beta)] \\&\triangleq \mathcal{L}(q).\end{aligned}$$

SVI: Mean Field VI

- Mean field variational family

$$q(z, \beta) = q(\beta | \lambda) \prod_{n=1}^N \prod_{j=1}^J q(z_{nj} | \phi_{nj}).$$

- Our approx. dist. is from exp. family

$$\begin{aligned} q(\beta | \lambda) &= h(\beta) \exp\{\lambda^\top t(\beta) - a_g(\lambda)\}, \\ q(z_{nj} | \phi_{nj}) &= h(z_{nj}) \exp\{\phi_{nj}^\top t(z_{nj}) - a_\ell(\phi_{nj})\}. \end{aligned}$$

- Entropy term:

$$-\mathbb{E}_q[\log q(z, \beta)] = -\mathbb{E}_\lambda[\log q(\beta)] - \sum_{n=1}^N \sum_{j=1}^J \mathbb{E}_{\phi_{nj}}[\log q(z_{nj})].$$

- $\mathbb{E}_{\phi_{nj}}[\cdot]$ an $\mathbb{E}_\lambda[\cdot]$ denote expectation w.r.t. $q(z_{nj} | \phi_{nj})$ an $q(\beta | \lambda)$

SVI: coordinate ascent inference

- Updating one variational parameter while holding others fixed.
 - ~~Updating global parameter~~

$$\mathcal{L}(\lambda) = \mathbb{E}_q[\log p(\beta | x, z)] - \mathbb{E}_q[\log q(\beta)] + \text{const.}$$

$$\mathcal{L}(\lambda) = \mathbb{E}_q[\eta_g(x, z, \alpha)]^\top \nabla_\lambda a_g(\lambda) - \lambda^\top \nabla_\lambda a_g(\lambda) + a_g(\lambda) + \text{const.}$$

SVI: coordinate ascent inference

- Similarly for local parameters

$$\nabla_{\phi_{nj}} \mathcal{L} = \nabla_{\phi_{nj}}^2 a_\ell(\phi_{nj}) (\mathbb{E}_q[\eta_\ell(x_n, z_{n,-j}, \beta)] - \phi_{nj}).$$

$$\phi_{nj} = \mathbb{E}_q[\eta_\ell(x_n, z_{n,-j}, \beta)]$$

```
1: Initialize  $\lambda^{(0)}$  randomly.  
2: repeat  
3:   for each local variational parameter  $\phi_{nj}$  do  
4:     Update  $\phi_{nj}$ ,  $\phi_{nj}^{(t)} = \mathbb{E}_{q^{(t-1)}}[\eta_{\ell,j}(x_n, z_{n,-j}, \beta)]$ .  
5:   end for  
6:   Update the global variational parameters,  $\lambda^{(t)} = \mathbb{E}_{q^{(t)}}[\eta_g(z_{1:N}, x_{1:N})]$ .  
7: until the ELBO converges
```



We need to go over all data before updating λ

SVI: Natural Gradient

- Classical gradient method

$$\lambda^{(t+1)} = \lambda^{(t)} + \rho \nabla_{\lambda} f(\lambda^{(t)})$$

- Equal formulation

$$\arg \max_{d\lambda} f(\lambda + d\lambda) \quad \text{subject to } \|d\lambda\|^2 < \varepsilon^2$$

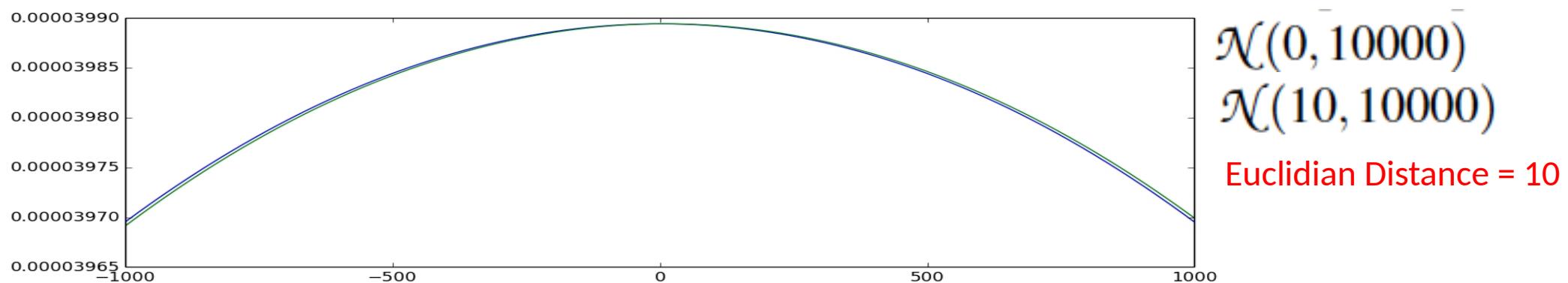
- needs to be small enough.

SVI: Natural Gradient

- Which of these two distributions are more different?



Euclidian Distance = 0.1



Euclidian Distance = 10

SVI: Natural Gradient

- Natural Measure of dissimilarity between probability measures:

$$D_{KL}^{\text{sym}}(\lambda, \lambda') = \mathbb{E}_\lambda \left[\log \frac{q(\beta|\lambda)}{q(\beta|\lambda')} \right] + \mathbb{E}_{\lambda'} \left[\log \frac{q(\beta|\lambda')}{q(\beta|\lambda)} \right]$$

$$\arg \max_{d\lambda} f(\lambda + d\lambda) \quad \text{subject to } D_{KL}^{\text{sym}}(\lambda, \lambda + d\lambda) < \varepsilon.$$

- Riemannian Metric : $d\lambda^T G(\lambda) d\lambda = D_{KL}^{\text{sym}}(\lambda, \lambda + d\lambda),$

- Natural Gradient $\hat{\nabla}_\lambda f(\lambda) \triangleq G(\lambda)^{-1} \nabla_\lambda f(\lambda),$

SVI: Natural Gradient

- Here, G is Fisher information matrix

$$G(\lambda) = \mathbb{E}_\lambda \left[(\nabla_\lambda \log q(\beta | \lambda)) (\nabla_\lambda \log q(\beta | \lambda))^T \right]$$

- We need to find G for exponential family.

SVI: Natural Gradient

$$\log q(\beta|\lambda + d\lambda) = O(d\lambda^2) + \log q(\beta|\lambda) + d\lambda^\top \nabla_\lambda \log q(\beta|\lambda),$$

$$q(\beta|\lambda + d\lambda) = O(d\lambda^2) + q(\beta|\lambda) + q(\beta|\lambda)d\lambda^\top \nabla_\lambda \log q(\beta|\lambda),$$

$$\begin{aligned} D_{KL}^{\text{sym}}(\lambda, \lambda + d\lambda) &= \int_{\beta} (q(\beta|\lambda + d\lambda) - q(\beta|\lambda))(\log q(\beta|\lambda + d\lambda) - \log q(\beta|\lambda))d\beta \\ &= O(d\lambda^3) + \int_{\beta} q(\beta|\lambda)(d\lambda^\top \nabla_\lambda \log q(\beta|\lambda))^2 d\beta \\ &= O(d\lambda^3) + \mathbb{E}_q[(d\lambda^\top \nabla_\lambda \log q(\beta|\lambda))^2] = O(d\lambda^3) + d\lambda^\top G(\lambda)d\lambda. \end{aligned}$$

$$\begin{aligned} G(\lambda) &= \mathbb{E}_\lambda \left[(\nabla_\lambda \log p(\beta|\lambda))(\nabla_\lambda \log p(\beta|\lambda))^\top \right] \\ &= \mathbb{E}_\lambda \left[(t(\beta) - \mathbb{E}_\lambda[t(\beta)])(t(\beta) - \mathbb{E}_\lambda[t(\beta)])^\top \right] \\ &= \nabla_\lambda^2 a_g(\lambda). \end{aligned}$$

SVI: Natural Gradient

- Using natural gradient for variational parameters

$$\hat{\nabla}_\lambda \mathcal{L} = \mathbb{E}_\phi[\eta_g(x, z, \alpha)] - \lambda.$$

$$\hat{\nabla}_{\phi_{nj}} \mathcal{L} = \mathbb{E}_{\lambda, \phi_{n,-j}}[\eta_\ell(x_n, z_{n,-j}, \beta)] - \phi_{nj}.$$

SVI: Stochastic elbo

- Elbo for λ

$$\mathcal{L}(\lambda) = \mathbb{E}_q[\log p(\beta)] - \mathbb{E}_q[\log q(\beta)] + \sum_{n=1}^N \max_{\phi_n} (\mathbb{E}_q[\log p(x_n, z_n | \beta)] - \mathbb{E}_q[\log q(z_n)]).$$

- Stochastic Elbo for λ

$$\mathcal{L}_I(\lambda) \triangleq \mathbb{E}_q[\log p(\beta)] - \mathbb{E}_q[\log q(\beta)] + N \max_{\phi_I} (\mathbb{E}_q[\log p(x_I, z_I | \beta)] - \mathbb{E}_q[\log q(z_I)]).$$

SVI: Stochastic Natural Gradient

- Natural Gradient and update

$$\hat{\nabla} \mathcal{L}_i = \mathbb{E}_q \left[\eta_g \left(x_i^{(N)}, z_i^{(N)}, \alpha \right) \right] - \lambda,$$

$$\eta_g \left(x_i^{(N)}, z_i^{(N)}, \alpha \right) = \alpha + N \cdot (t(x_n, z_n), 1). \quad \hat{\nabla}_\lambda \mathcal{L}_i = \alpha + N \cdot (\mathbb{E}_{\phi_i(\lambda)} [t(x_i, z_i)], 1) - \lambda,$$

$$\hat{\lambda}_t \triangleq \alpha + N \mathbb{E}_{\phi_i(\lambda)} [(t(x_i, z_i), 1)].$$

$$\begin{aligned} \lambda^{(t)} &= \lambda^{(t-1)} + \rho_t \left(\hat{\lambda}_t - \lambda^{(t-1)} \right) \\ &= (1 - \rho_t) \lambda^{(t-1)} + \rho_t \hat{\lambda}_t. \end{aligned}$$

SVI algorithm

- 1: Initialize $\lambda^{(0)}$ randomly.
- 2: Set the step-size schedule ρ_t appropriately.
- 3: **repeat**
- 4: Sample a data point x_i uniformly from the data set.
- 5: Compute its local variational parameter,

$$\phi = \mathbb{E}_{\lambda^{(t-1)}} [\eta_g(x_i^{(N)}, z_i^{(N)})].$$

- 6: Compute intermediate global parameters as though x_i is replicated N times,

$$\hat{\lambda} = \mathbb{E}_\phi [\eta_g(x_i^{(N)}, z_i^{(N)})].$$

- 7: Update the current estimate of the global variational parameters,

$$\lambda^{(t)} = (1 - \rho_t) \lambda^{(t-1)} + \rho_t \hat{\lambda}.$$

- 8: **until** forever

Bridging the GAP

- What if taking samples from posterior approximate is not easy?
- Basic Idea:
 - Use monte carlo method to generate samples from posterior approximate.

Thank you!