

# **Approximate Bayesian Computation**

Alireza Shafaei - April 2016



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$$\mathcal{P}(\mathcal{D}) = \int_{\Theta} \mathcal{P}(\mathcal{D}|\theta)\pi(\theta) d\theta$$



# The Problem - A Review

- Previously we looked at the general problem of handling **high-dimensional integrals** and **unnormalized probability** functions.

$$\mathcal{P}(x) = \frac{1}{Z} p^*(x)$$



# The Problem - A Review

- Rejection Sampling

- Given  $p^*(x), q(x), M$  s.t.  $\frac{p^*(x)}{q(x)} \leq M \forall x.$
- $x \sim q(x)$
- Accept  $x$  with probability

$$\frac{p^*(x)}{M \cdot q(x)}$$



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- Importance Sampling

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$$\int_x f(x)p(x) dx = \frac{\int_x f(x)p^*(x) dx}{\int_x p^*(x) dx} = \frac{\int_x f(x)\frac{p^*(x)}{q(x)}q(x) dx}{\int_x \frac{p^*(x)}{q(x)}q(x) dx}$$



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$$\int_x f(x)p(x) dx = \frac{\int_x f(x)p^*(x) dx}{\int_x p^*(x) dx} = \frac{\int_x f(x) \frac{p^*(x)}{q(x)} q(x) dx}{\int_x \frac{p^*(x)}{q(x)} q(x) dx}$$

$$\int_x f(x)p(x) dx \approx \frac{\sum_{l=1}^L f(x_l) \frac{p^*(x_l)}{q(x_l)}}{\sum_{l=1}^L \frac{p^*(x_l)}{q(x_l)}}$$



# The Problem - A Review

- Markov chain Monte Carlo



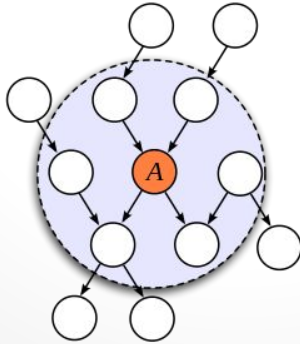
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  - Gibbs sampling.
  - Metropolis-Hastings algorithm.
  - Reversible Jump MCMC (non-parametric)



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- What if we can't calculate  $\mathcal{P}(\mathcal{D}|\theta)$ ?



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- Apparently applies to a lot of problems in biology.
- Given a parameter  $\theta$  you can simulate the execution.
- $\mathcal{P}(\mathcal{D}|\theta)$  Could be intractable or simply no mathematical derivation of it exists.



# Approximate Bayesian Computation

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# Discussion

- Randomly sampling  $\theta$  from the prior each time is ‘too wasteful’.
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  - We want to explore the space to accept more often.
  - Sampling from the prior does not incorporate current observations.
- How do we choose  $\rho(\cdot, \cdot)$ ,  $\mathcal{S}(\cdot)$ ,  $\epsilon$ ?



# Approximate MCMC

1. Propose  $\theta' \sim Q(\theta'|\theta)$



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1. Propose  $\theta' \sim Q(\theta'|\theta)$
2. Simulate  $\tilde{\mathcal{D}} \sim \mathcal{P}(\cdot|\theta')$
3. If  $\rho(\mathcal{S}(\mathcal{D}), \mathcal{S}(\tilde{\mathcal{D}})) < \epsilon$ 
  - a. Accept  $\theta'$  with probability

$$\min\left(1, \frac{\pi(\theta')Q(\theta|\theta')}{\pi(\theta)Q(\theta'|\theta)}\right)$$





# Approximate Gibbs

- Let's assume  $\theta = (\theta_1, \theta_2)$ 
  - $\mathcal{P}(\theta_1 | \mathcal{D}, \theta_2)$  is known.
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  2.  $\theta_2^* \sim \pi(\theta_2)$



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  2.  $\theta_2^* \sim \pi(\theta_2)$ 
    - $\tilde{\mathcal{D}} \sim \mathcal{P}(\cdot | \theta_1^{t+1}, \theta_2^*)$



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  - $\mathcal{P}(\theta_2 | \mathcal{D}, \theta_1)$  is unknown.
- 1.  $\theta_1^{t+1} \sim \mathcal{P}(\theta_1 | \mathcal{D}, \theta_2)$
- 2.  $\theta_2^* \sim \pi(\theta_2)$ 
  - $\tilde{\mathcal{D}} \sim \mathcal{P}(\cdot | \theta_1^{t+1}, \theta_2^*)$
  - $\rho(\mathcal{S}(\mathcal{D}), \mathcal{S}(\tilde{\mathcal{D}})) < \epsilon \Rightarrow \theta_2^{t+1} = \theta_2^*$
  - else go to 2.



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## Cons

- Lot's of tuning.
- For complex problems, sampling from the prior is frustrating because it does not incorporate the evidence.
- How good is our approximation?



Thank you!



# References

1. Wilkinson, Richard, and Simon Tavaré. "Approximate Bayesian Computation: a simulation based approach to inference."
2. [https://en.wikipedia.org/wiki/Gibbs\\_sampling](https://en.wikipedia.org/wiki/Gibbs_sampling)
3. Barber, David. Bayesian reasoning and machine learning. Cambridge University Press, 2012.
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