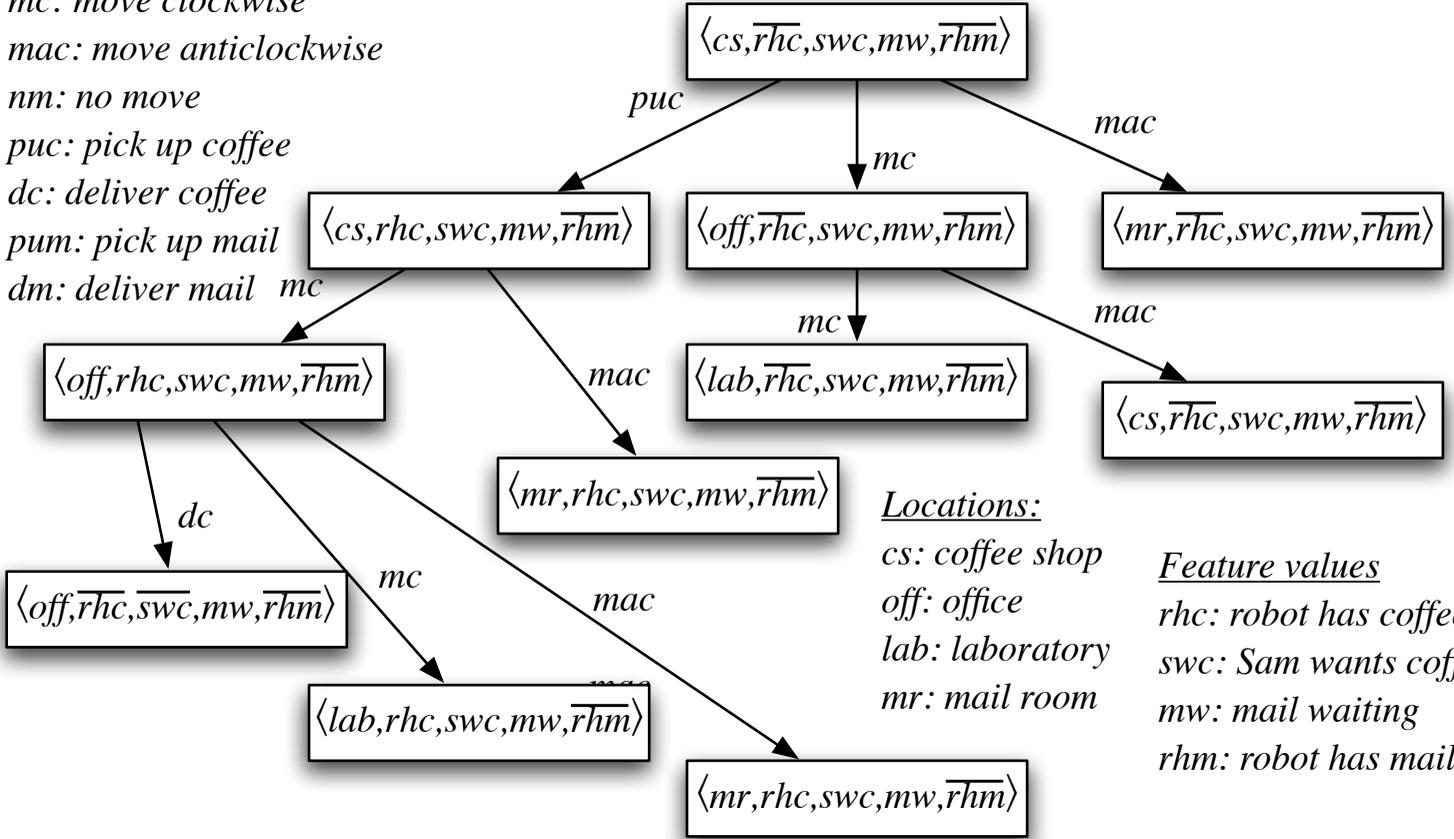


Actions

- mc*: move clockwise
- mac*: move anticlockwise
- nm*: no move
- puc*: pick up coffee
- dc*: deliver coffee
- pum*: pick up mail
- dm*: deliver mail



Locations:

- cs*: coffee shop
- off*: office
- lab*: laboratory
- mr*: mail room

Feature values

- rhc*: robot has coffee
- swc*: Sam wants coffee
- mw*: mail waiting
- rhm*: robot has mail