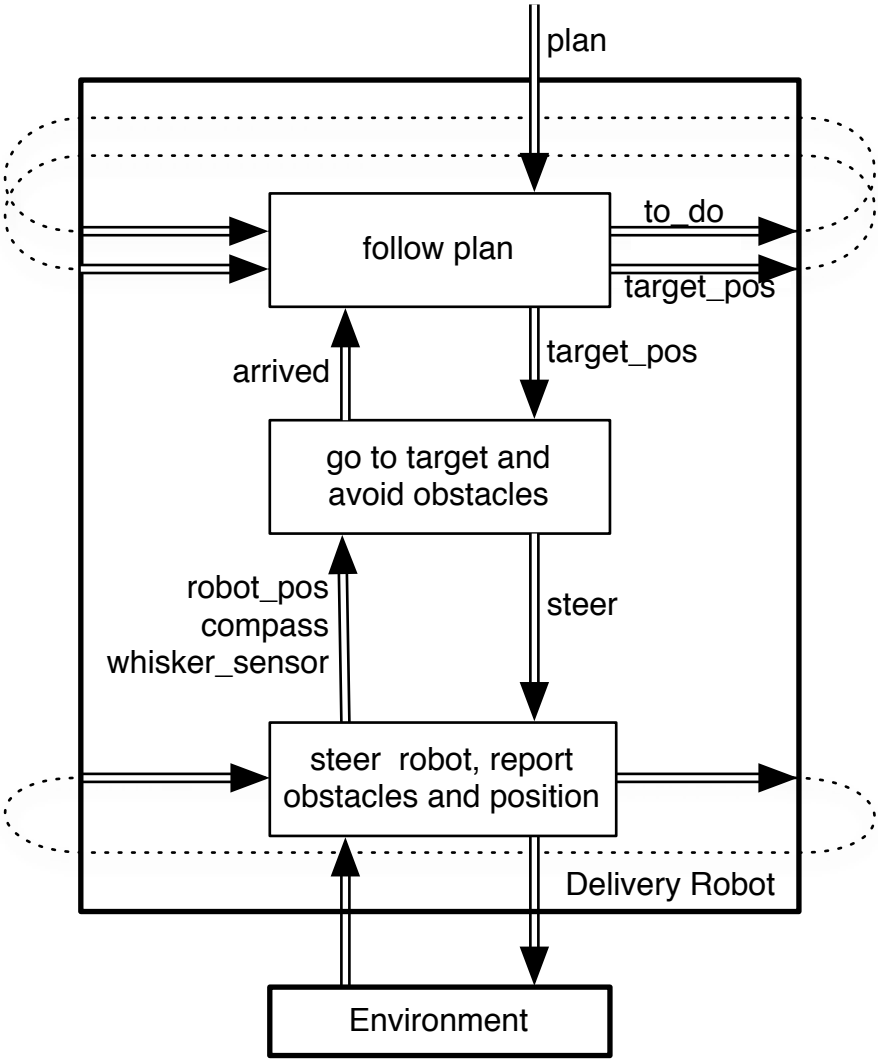
plan
follow plan
to_do
target_pos
target_pos
arrived
go to target and
avoid obstacles
robot_pos
compass
whisker_sensor
steer
steer robot, report
obstacles and position
Delivery Robot
Environment