

Scalable Drawing of Trees and Graphs

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joint work with Dan Archambault, David Auber,
Francois Guimbretiere, Kristian Hildebrand, James
Slack, Serdar Tasiran, Li Zhang, and Yunhong Zhou

Outline

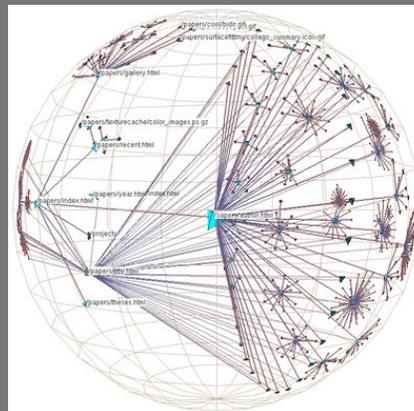
- Introduction
- H3
- TreeJuxtaposer
- TopoLayout
- Conclusion

Scalable Visualization

- Visual representation of node-link graphs useful in many domains
 - many real-world datasets are very large
- Designing for scalability
 - graphics issues
 - guaranteed frame rate
 - interaction issues
 - guidance on where to look next
 - cognitive issues
 - maintain orientation
 - see details in context
 - guaranteed visibility of landmarks

H3

- H3: Laying Out Large Directed Graphs in 3D Hyperbolic Space
 - Tamara Munzner. Proc. InfoVis 97, pp 2-10.
- Drawing Large Graphs with H3Viewer and Site Manager
 - Tamara Munzner. Proc. Graph Drawing 98, pp 384-393.
- video, free software available from <http://graphics.stanford.edu/~munzner/h3>



H3 Features

- 3D hyperbolic geometry shows large local neighborhood
 - single focus
 - fisheye distortion
 - understanding graph topological structure does not require judging distances
 - details for dozens of nodes, aggregate information for thousands of nodes
- uses spanning tree as backbone for layout
 - explore non-tree links through interaction
 - appropriate for quasi-hierarchical graphs

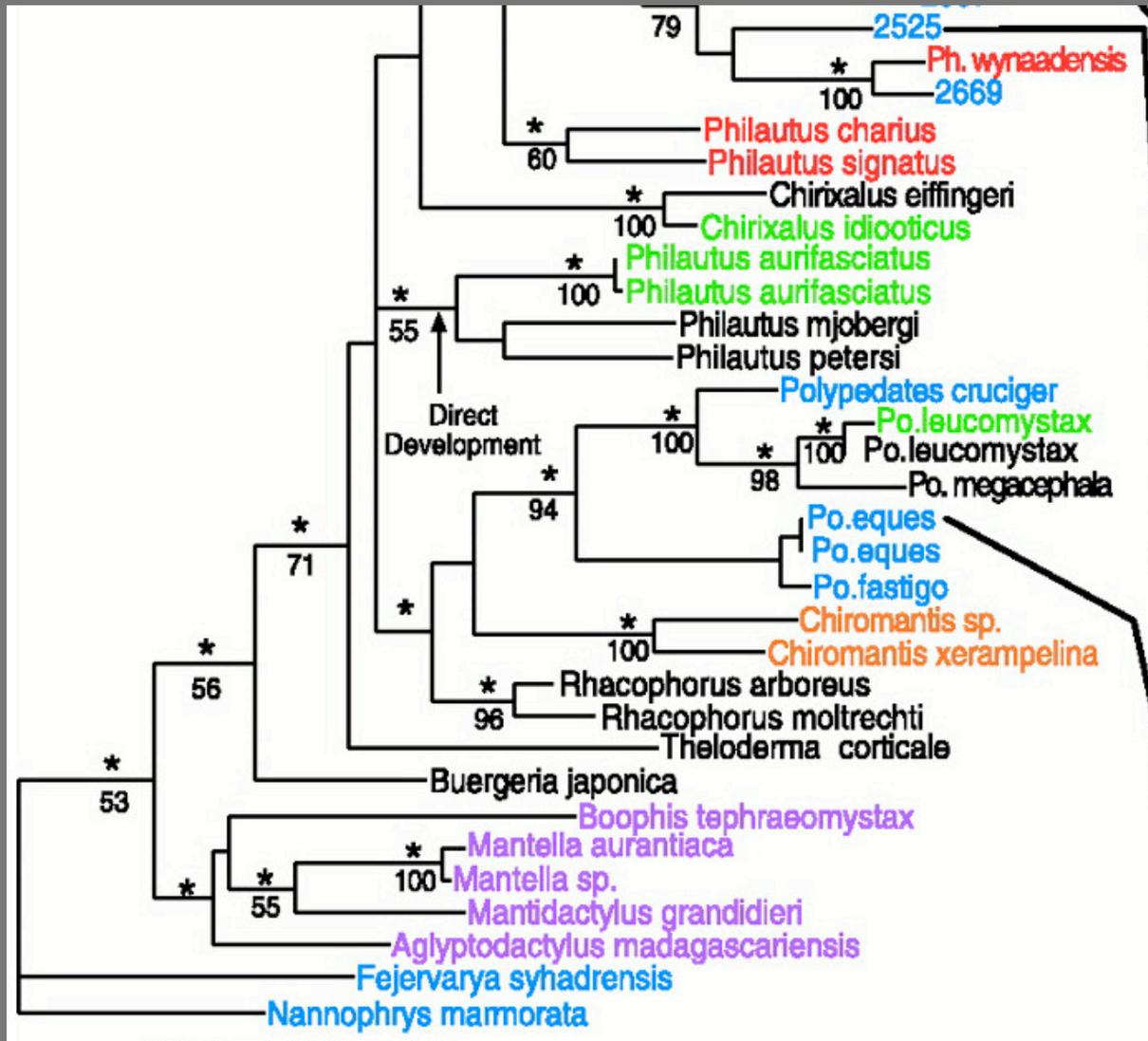
H3 Limitations

- see large neighborhood but not global overview
 - can still get lost
- only single focus
 - intrinsic to hyperbolic geometry

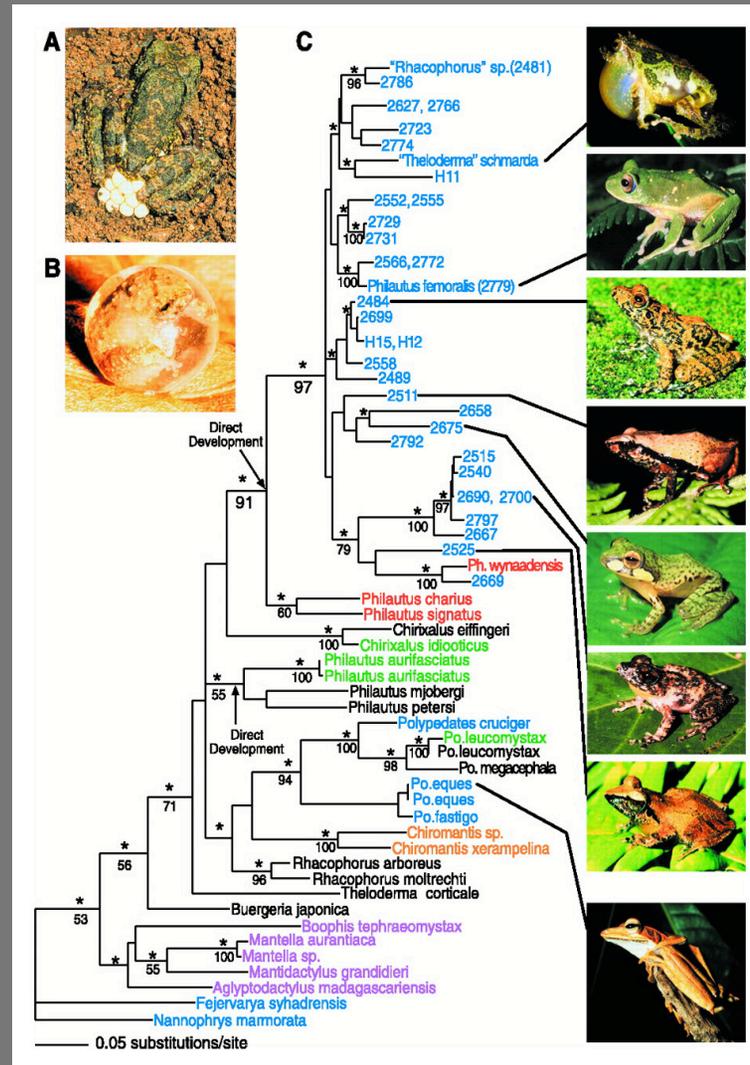
TreeJuxtaposer

- TreeJuxtaposer: Scalable Tree Comparison using Focus+Context with Guaranteed Visibility
 - Tamara Munzner, Francois Guimbretiere, Serdar Tasiran, Li Zhang, and Yunhong Zhou. SIGGRAPH 2003, pp 453--462
 - side by side comparison of evolutionary trees

Phylogenetic/Evolutionary Tree

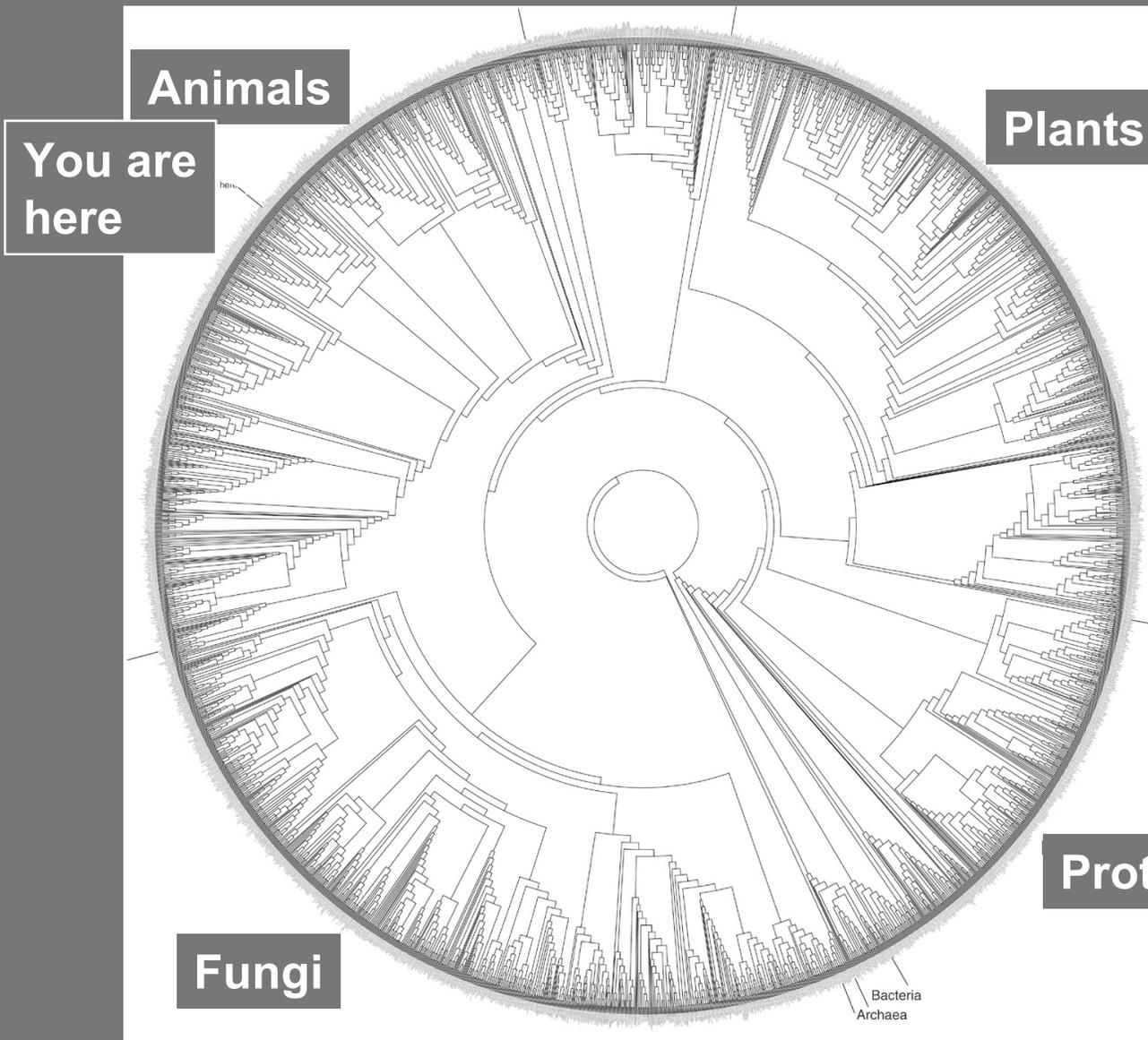


Common Dataset Size Today



M Meegaskumbura et al., Science 298:379 (2002)

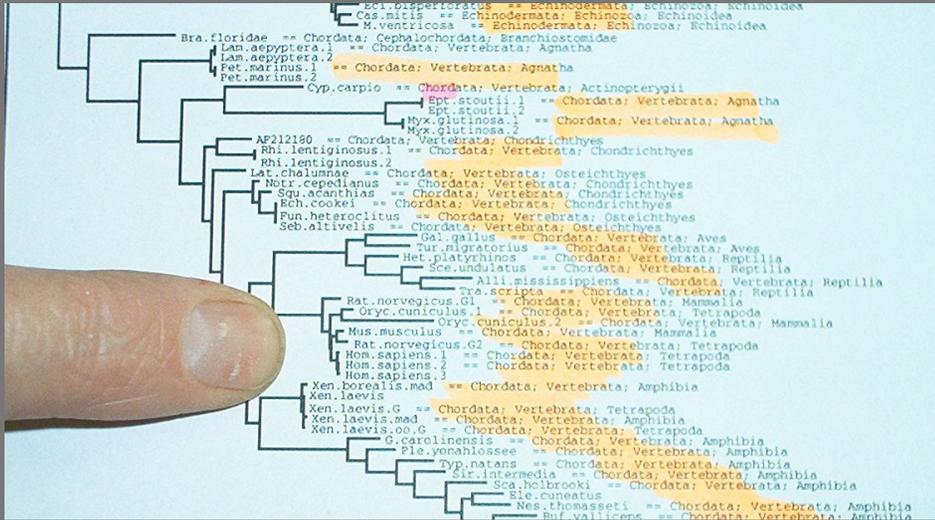
Future Goal: 10M Node Tree of Life



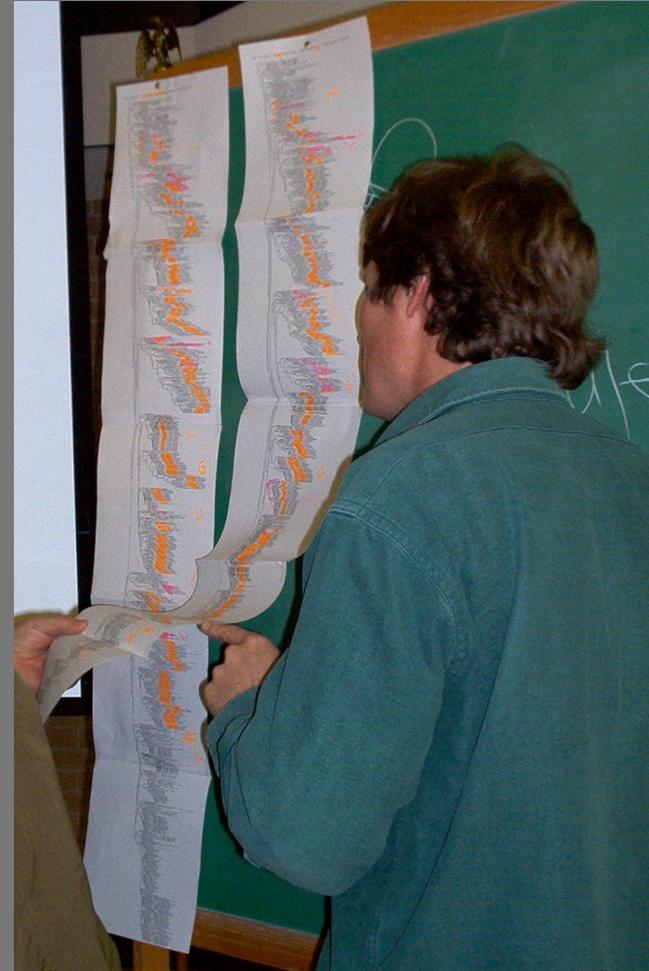
David Hillis, *Science* 300:1687 (2003)

Paper Comparison: Multiple Trees

focus

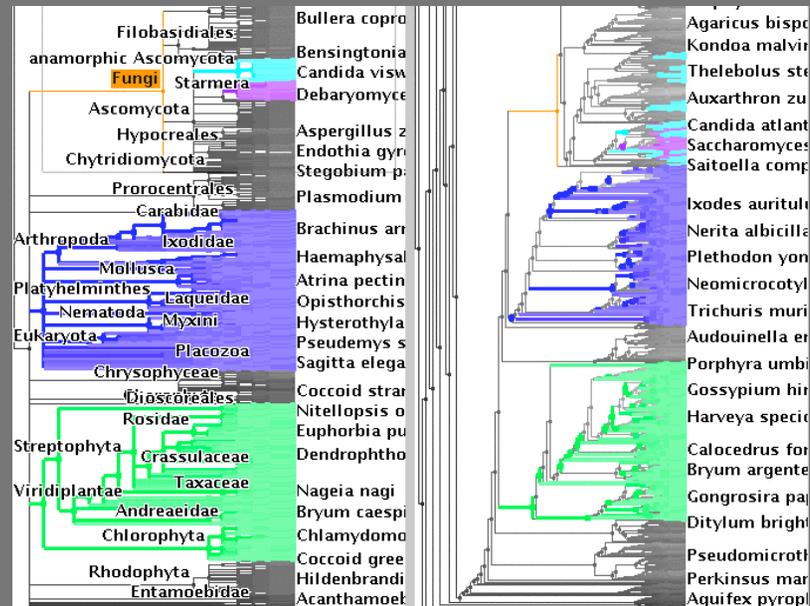
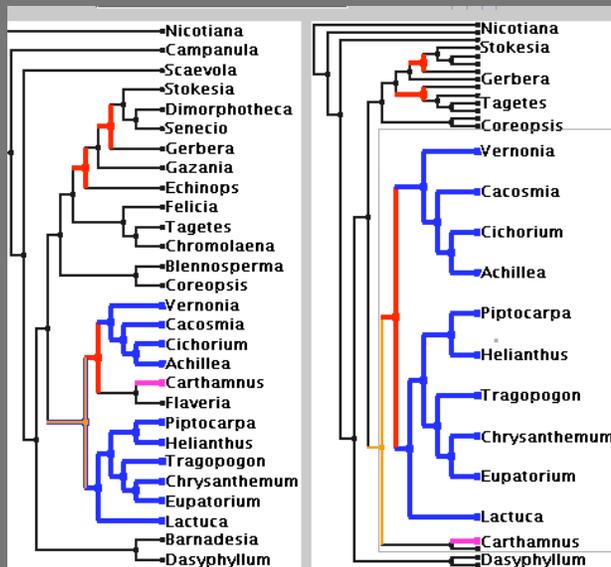


context



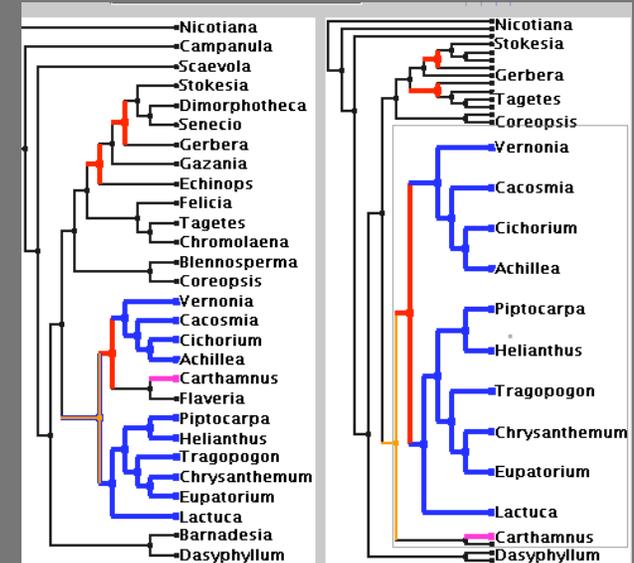
TreeJuxtaposer

- side by side comparison of evolutionary trees
- [video]
 - video and free software downloadable from <http://olduvai.sf.net/tj>



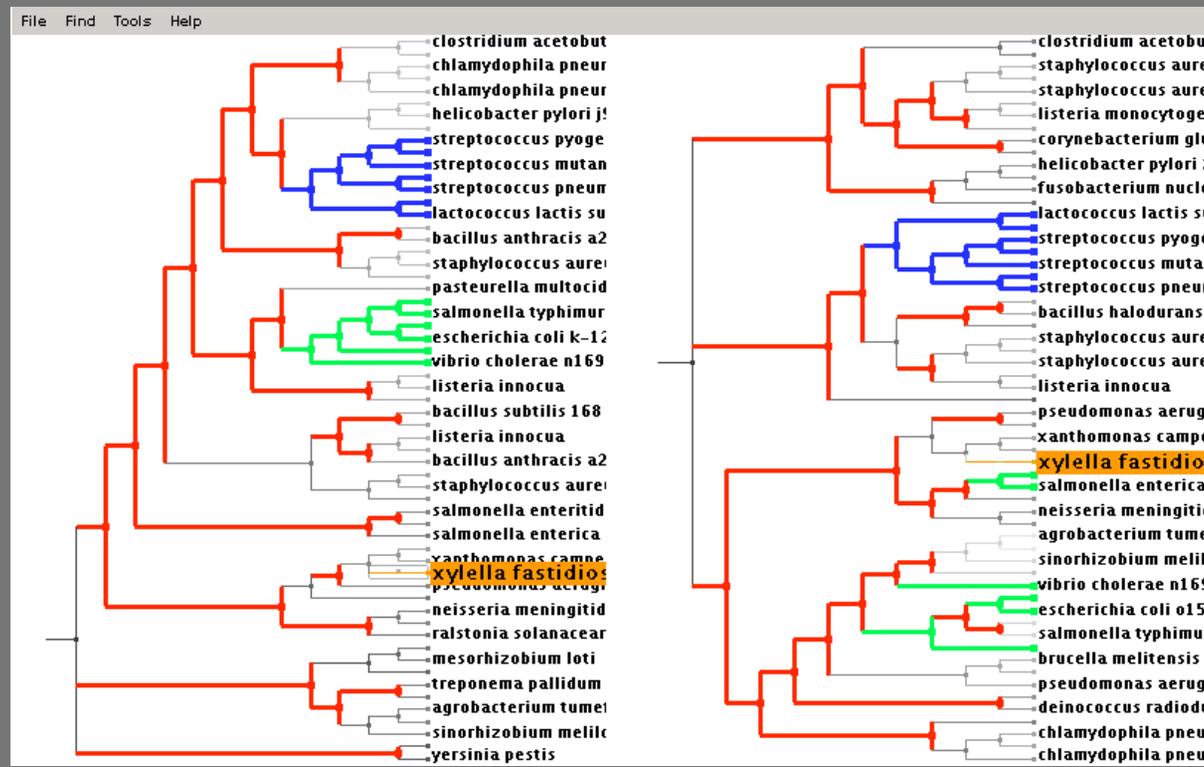
Accordion Drawing

- rubber-sheet navigation
 - stretch out part of surface, the rest squishes
 - borders nailed down
 - Focus+Context technique
 - integrated overview, details
 - old idea
 - [Sarkar et al 93], [Robertson et al 91]
- guaranteed visibility
 - marks always visible
 - important for scalability
 - new idea
 - [Munzner et al 03]



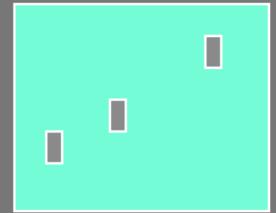
Guaranteed Visibility

- marks are always visible
- easy with small datasets



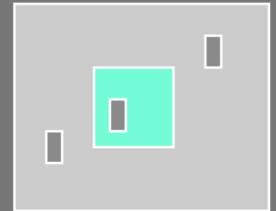
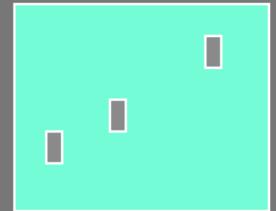
Guaranteed Visibility Challenges

- hard with larger datasets
- reasons a mark could be invisible



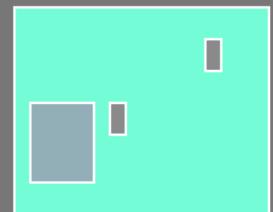
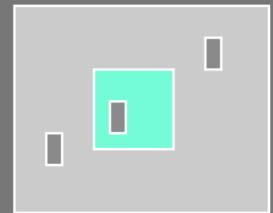
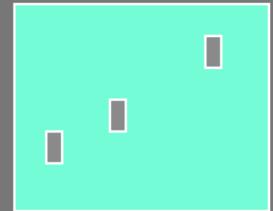
Guaranteed Visibility Challenges

- hard with larger datasets
- reasons a mark could be invisible
 - outside the window
 - AD solution: constrained navigation



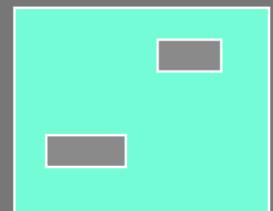
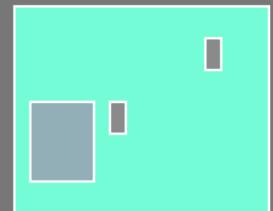
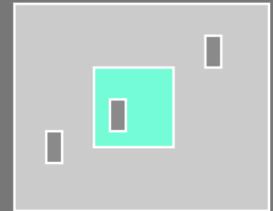
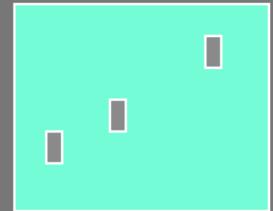
Guaranteed Visibility Challenges

- hard with larger datasets
- reasons a mark could be invisible
 - outside the window
 - AD solution: constrained navigation
 - underneath other marks
 - AD solution: avoid 3D



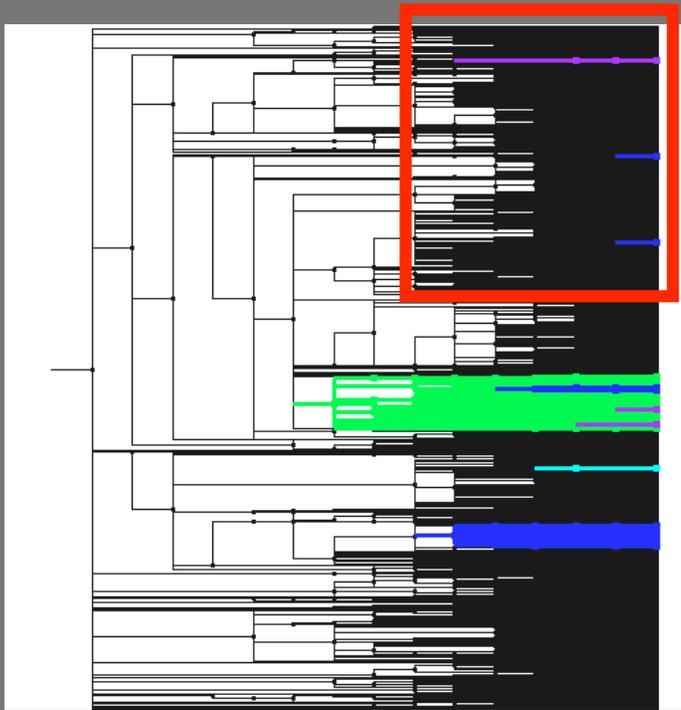
Guaranteed Visibility Challenges

- hard with larger datasets
- reasons a mark could be invisible
 - outside the window
 - AD solution: constrained navigation
 - underneath other marks
 - AD solution: avoid 3D
 - smaller than a pixel
 - AD solution: smart culling

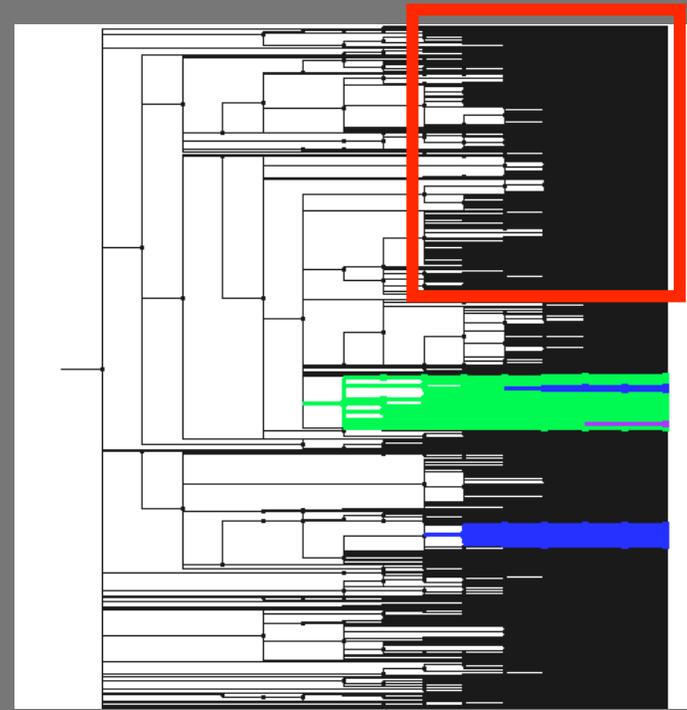


Guaranteed Visibility: Small Items

- Naïve culling may not draw all marked items



Guaranteed visibility
of marks



No guaranteed visibility

TJ Contributions

- first interactive tree comparison system
 - automatic structural difference computation
 - guaranteed visibility of marked areas
- scalable to large datasets
 - 250,000 to 500,000 total nodes
 - all preprocessing subquadratic
 - all realtime rendering sublinear
- scalable to large displays (4000 x 2000)
- introduced
 - guaranteed visibility, accordion drawing

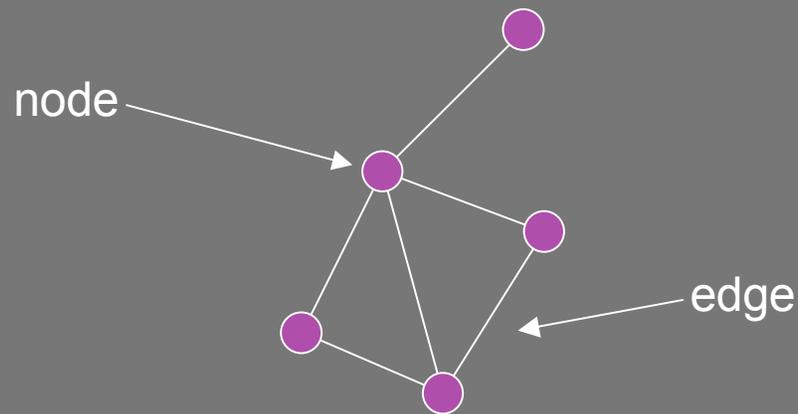
Further Work

- Partitioned Rendering Infrastructure for Scalable Accordion Drawing (Extended Version)
 - James Slack, Kristian Hildebrand, and Tamara Munzner. Information Visualization 5(2), pp 137-151, 2006
 - generic and efficient rendering
 - handles trees over 4,000,000 nodes
- Composite Rectilinear Deformation for Stretch and Squish Navigation
 - James Slack and Tamara Munzner. Proc. InfoVis06, to appear
 - generic navigation
- SequenceJuxtaposer: Fluid Navigation For Large-Scale Sequence Comparison In Context
 - James Slack, Kristian Hildebrand, Tamara Munzner, and Katherine St. John. German Conference on Bioinformatics 2004, pp 37-42
 - accordion drawing for gene sequences

TopoLayout

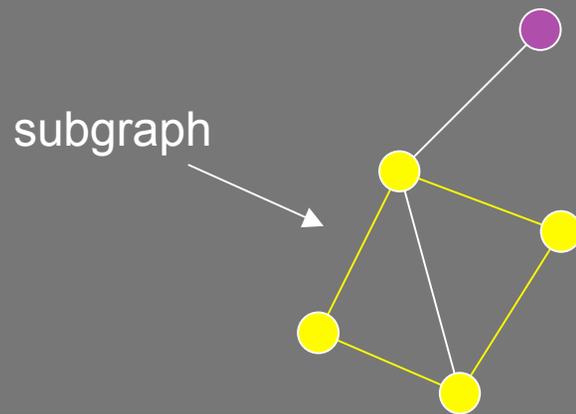
- TopoLayout: Multi-Level Graph Layout by Topological Features
 - Dan Archambault, Tamara Munzner, David Auber
 - Trans. Visualization and Computer Graphics, to appear
- Emphasis on offline computation of best possible static layout, vs. interactive frame rates

Graph



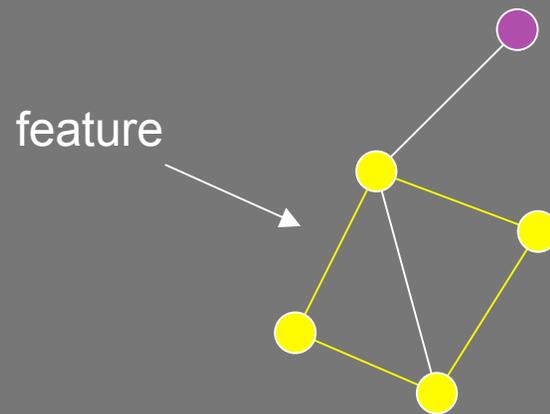
Graph: $G(V, E)$ set V of nodes and set E of edges such that E is subset of $V \times V$

Subgraph and Feature



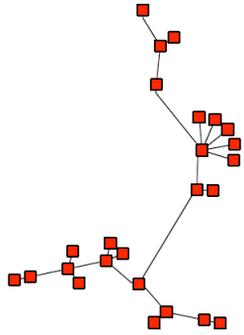
Subgraph: subset of these nodes and subset of the edges between them

Subgraph and Feature

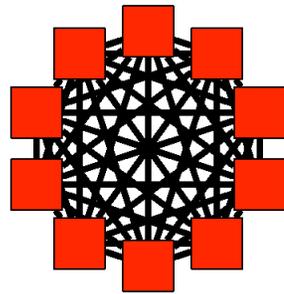


Feature: any subgraph of interest

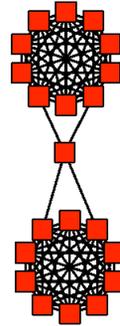
Topological Features



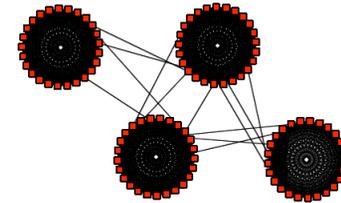
Tree



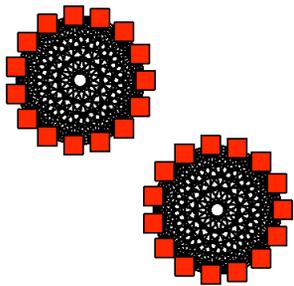
Complete Graph



Biconnected Component



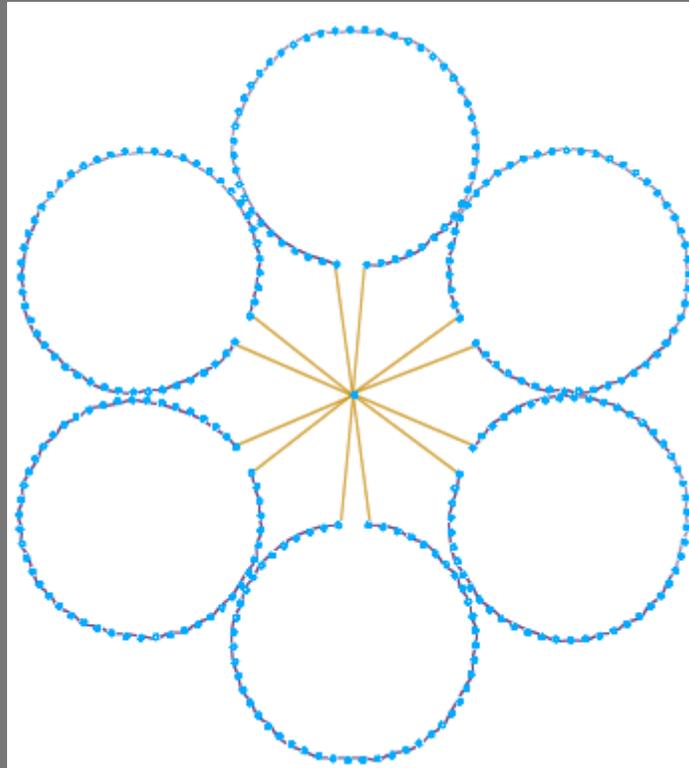
Cluster



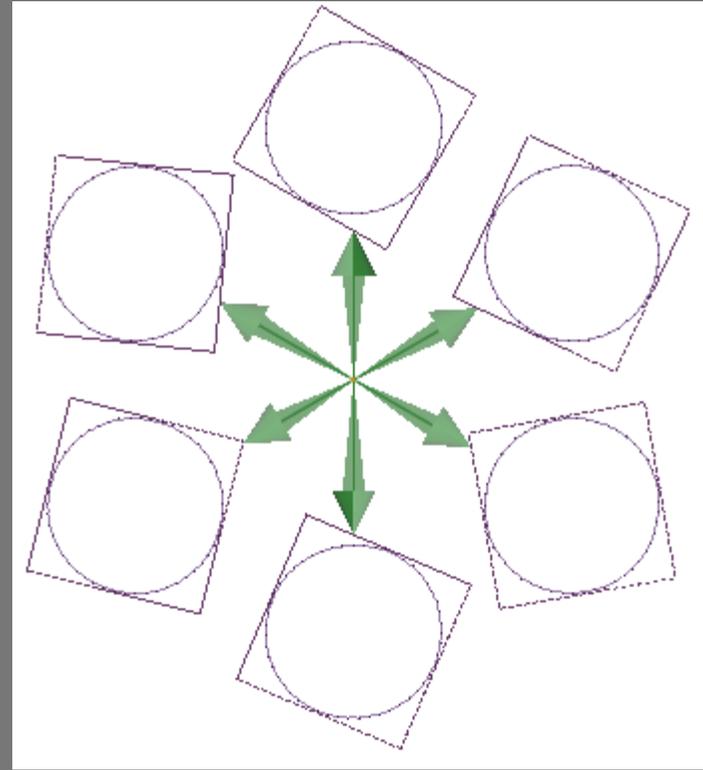
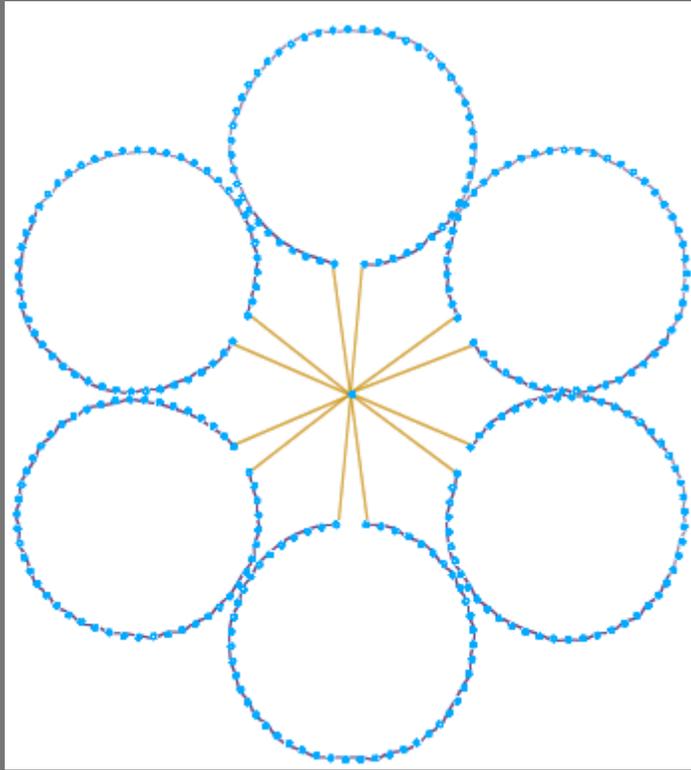
Connected Components

- Interconnection beyond direct adjacency
- Not hole counting in meshes

Multi-level Structure

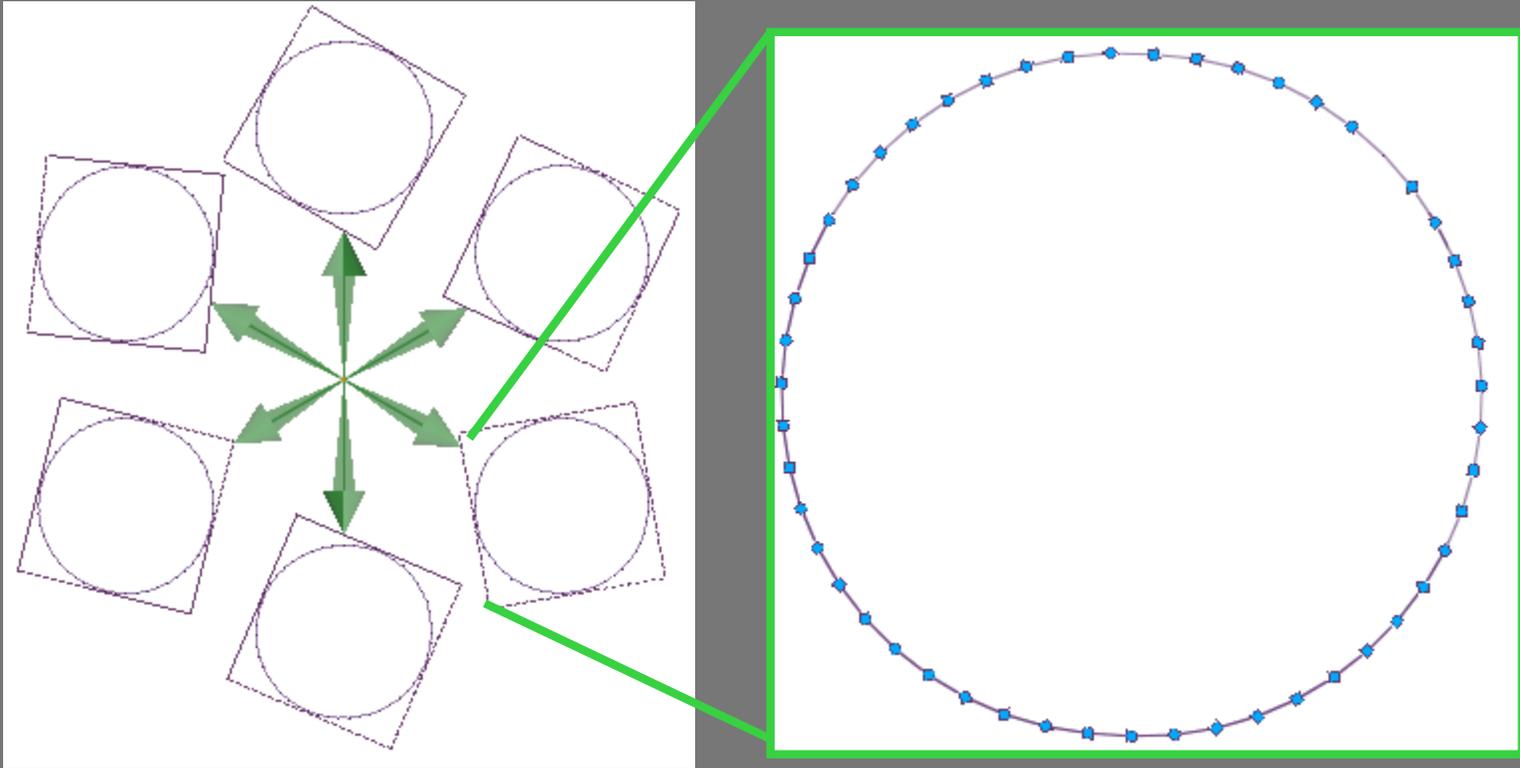


High-Level Structure



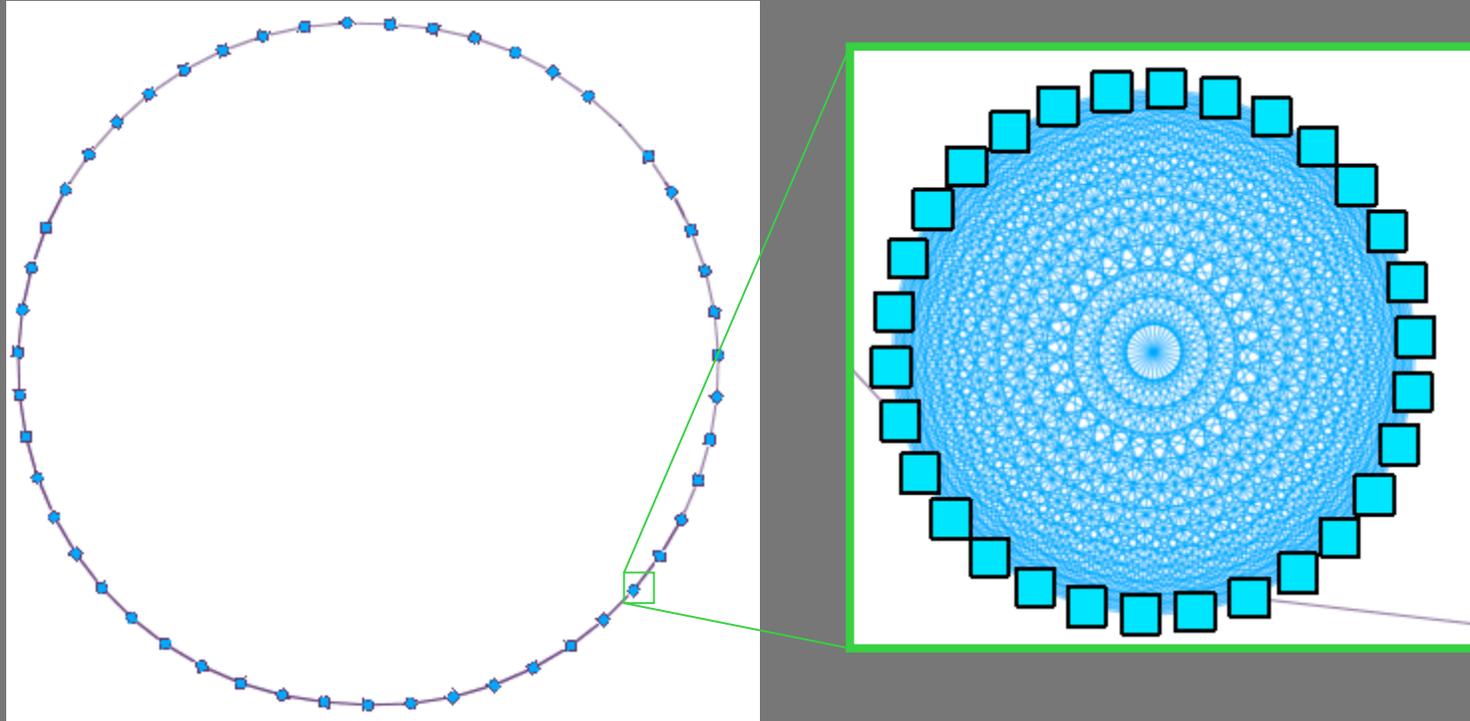
- Small tree

Mid-level Structure



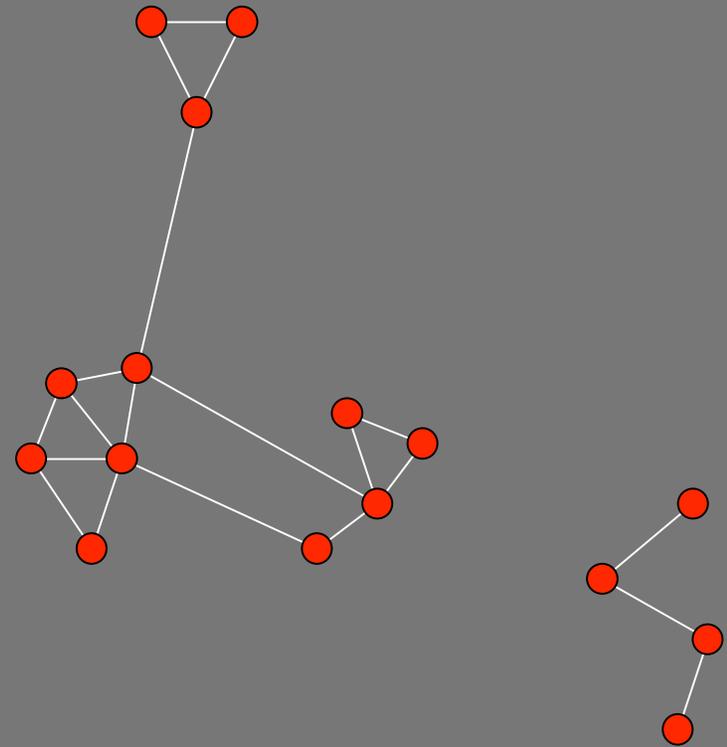
- Multiple levels of mid-level structure possible
 - Loop

Low-level Structure

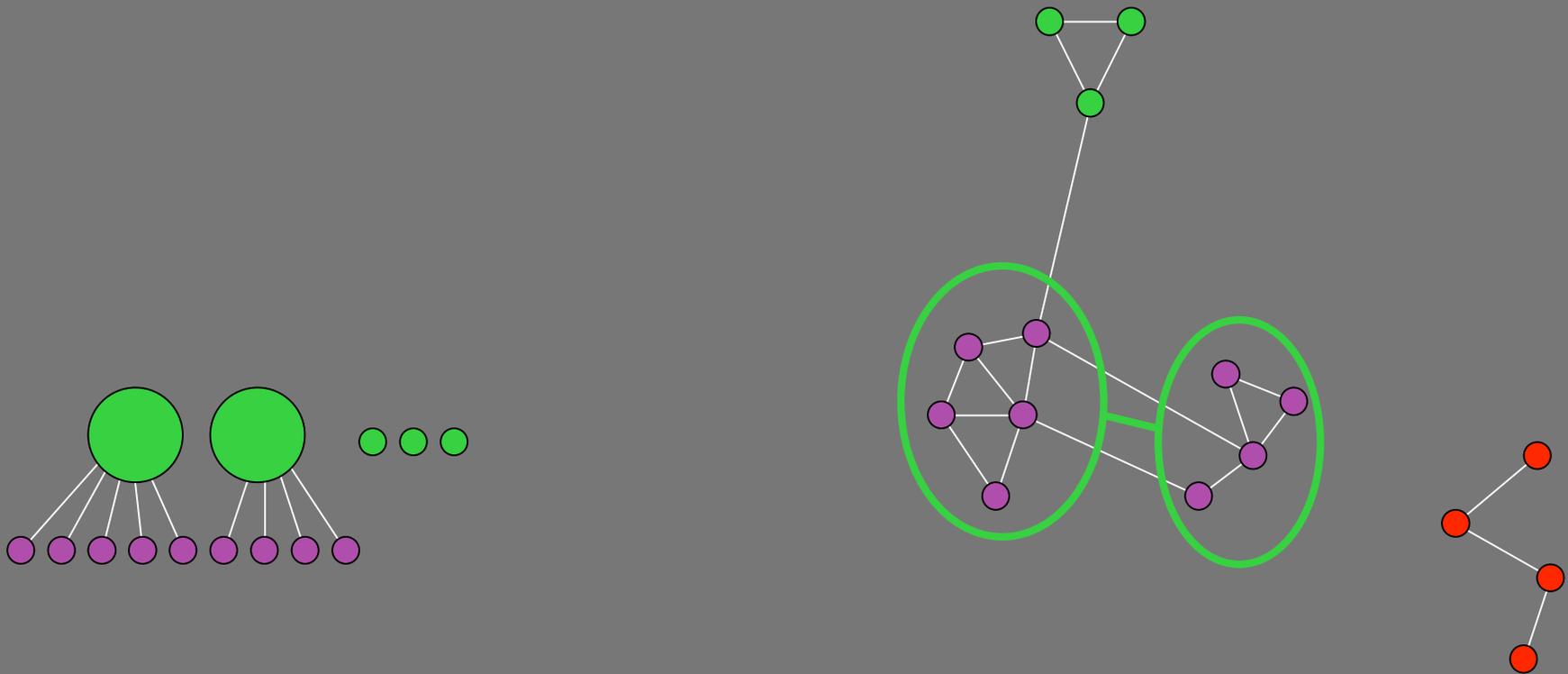


- Features involving original nodes and edges
- Lowest level is direct adjacencies, paths
 - Complete subgraph

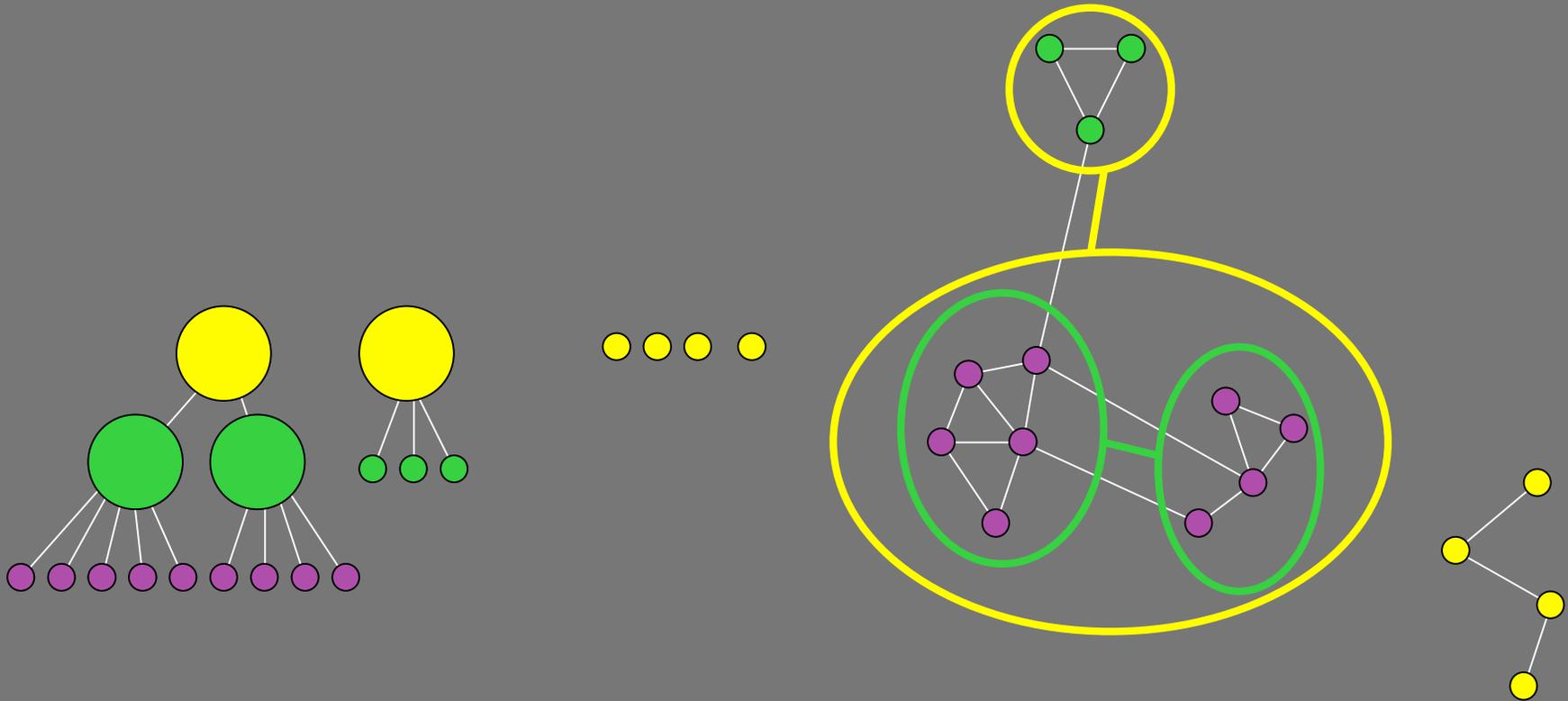
Multi-Level Hierarchy



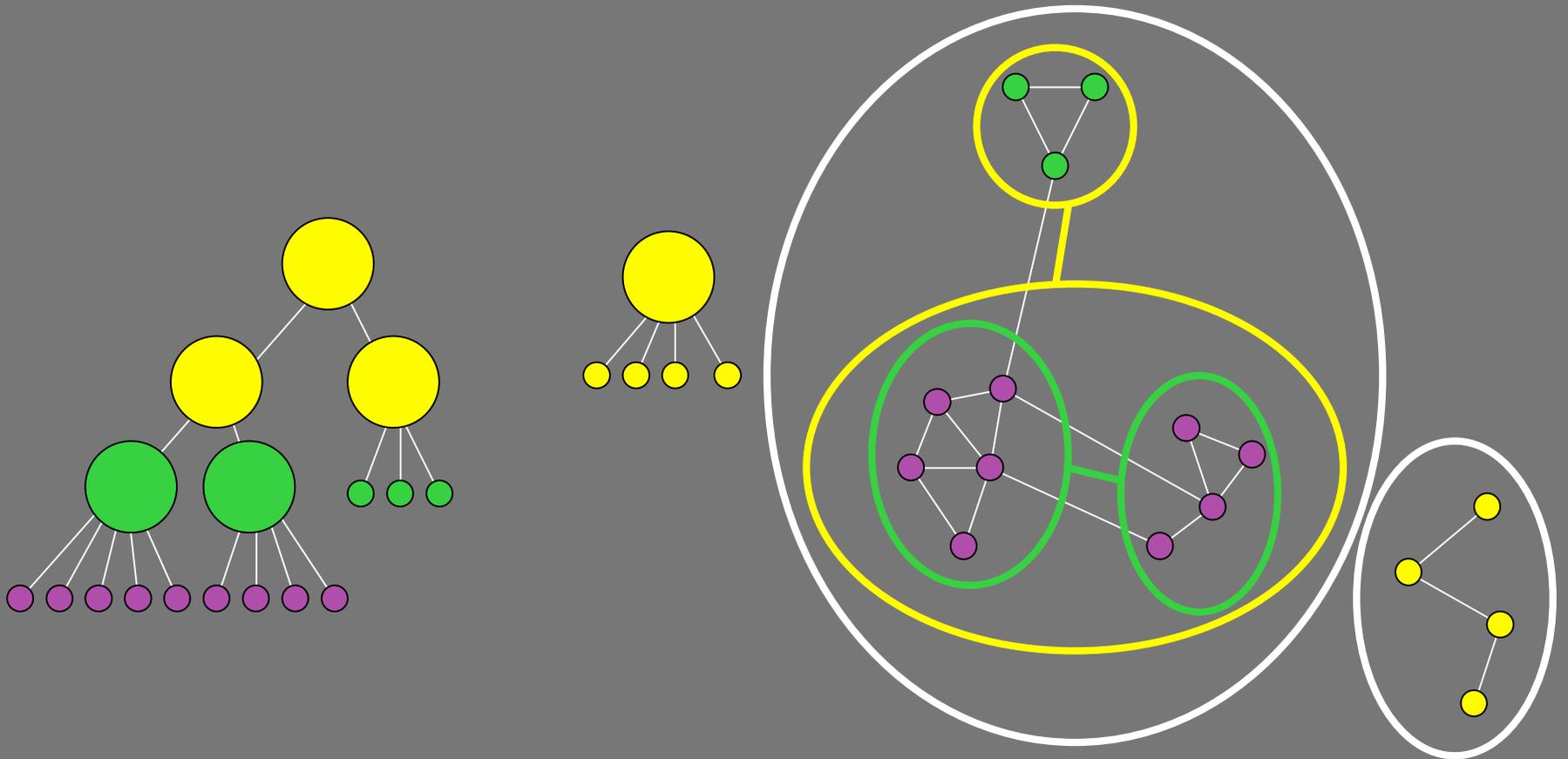
Multi-Level Hierarchy



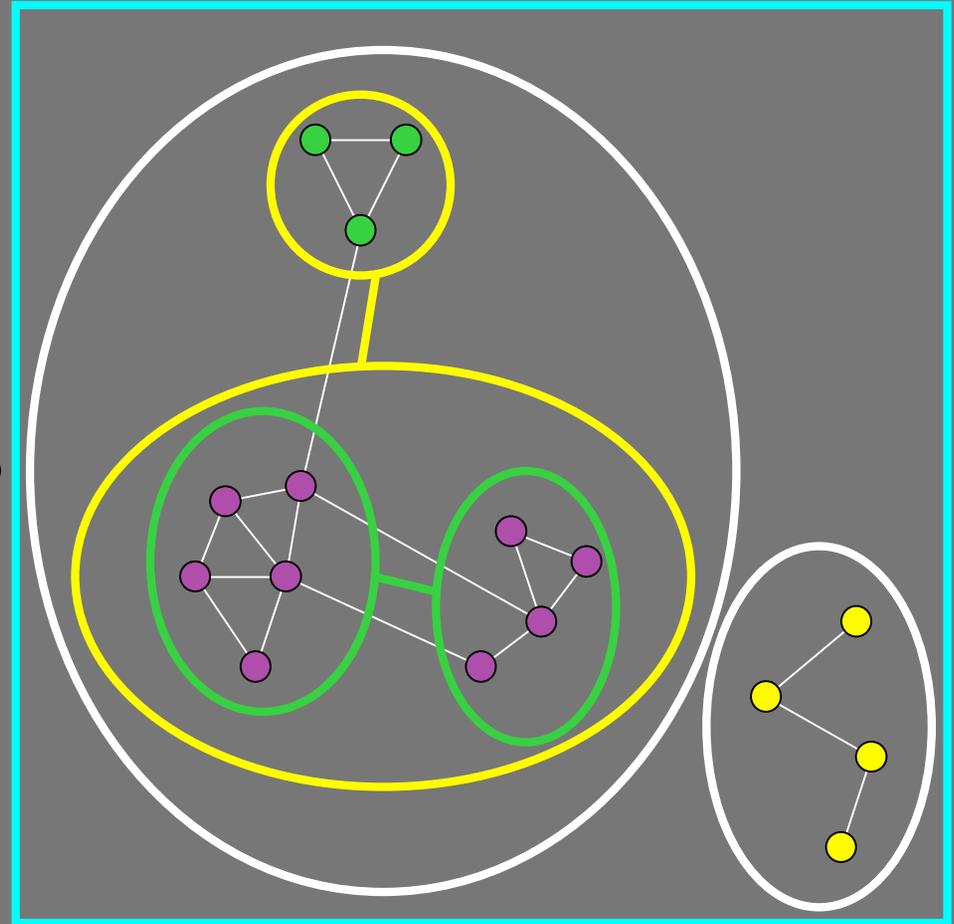
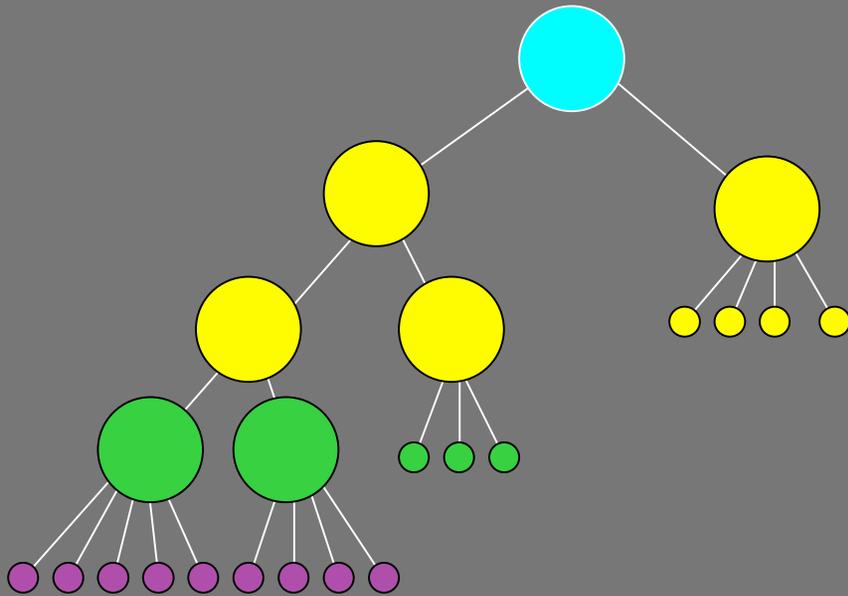
Multi-Level Hierarchy



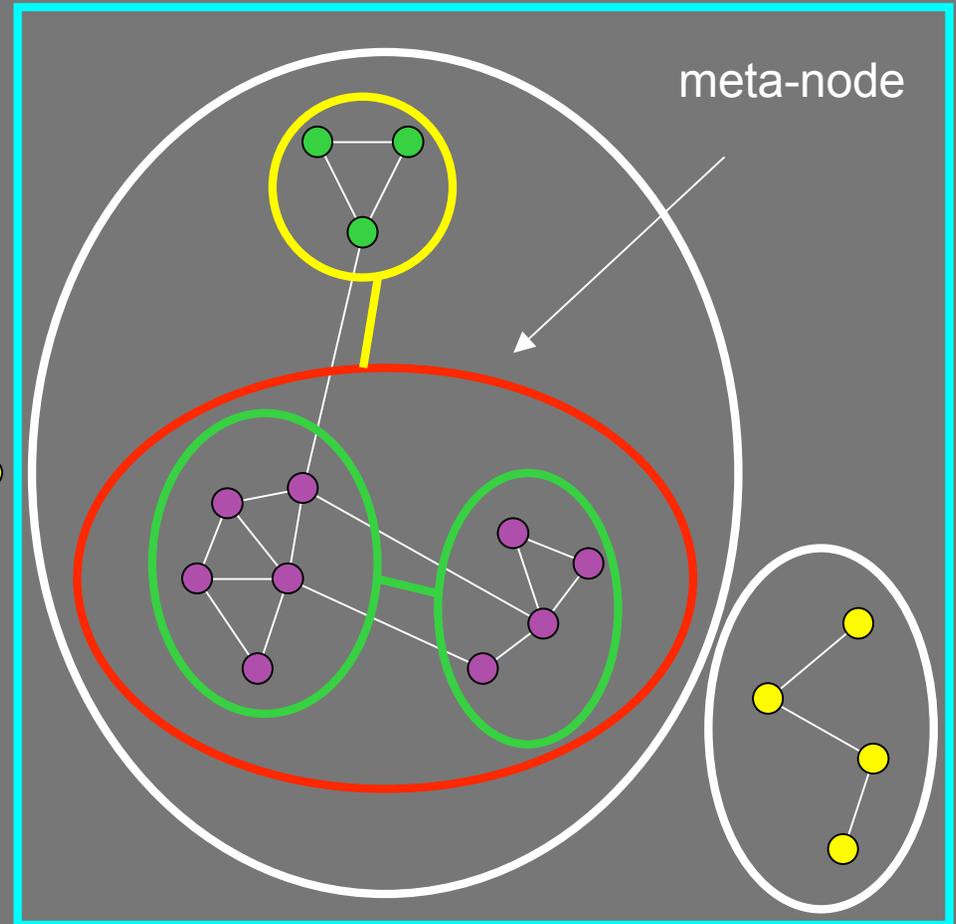
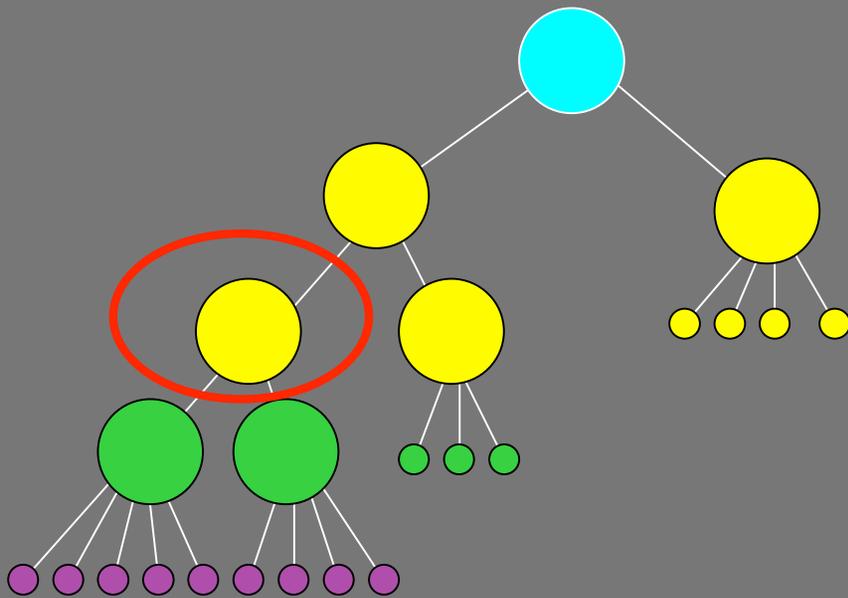
Multi-Level Hierarchy



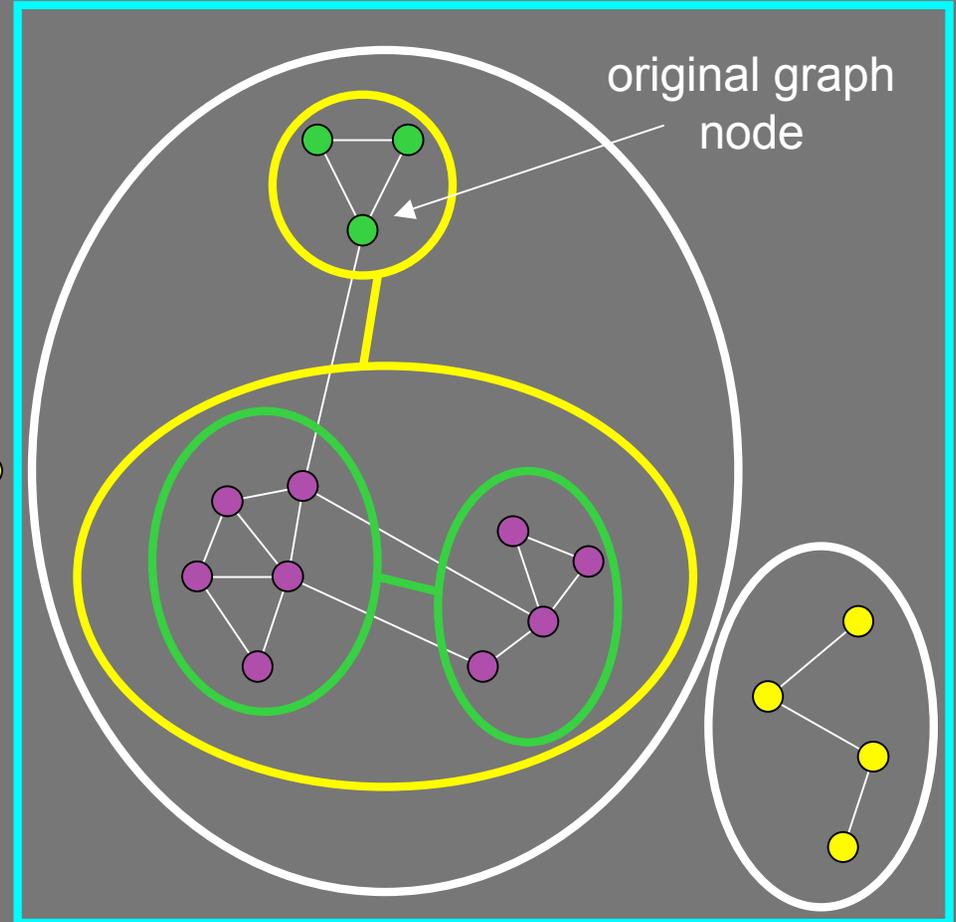
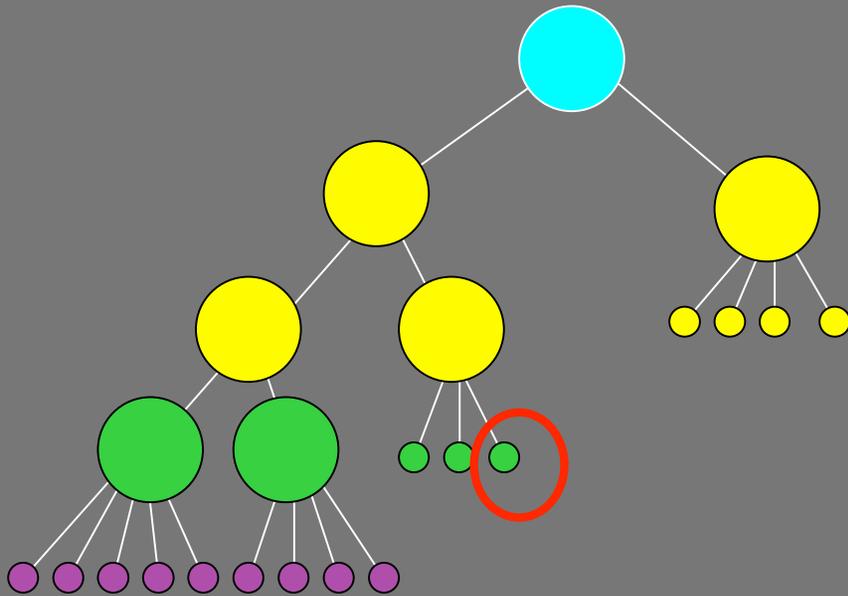
Multi-Level Hierarchy



Multi-Level Hierarchy

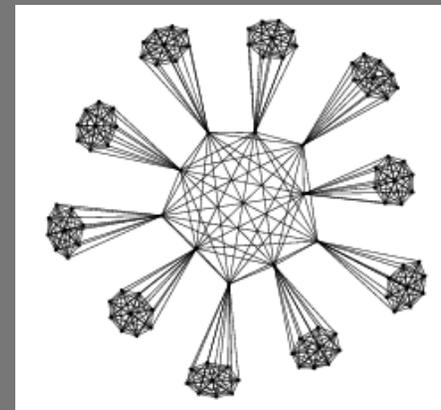
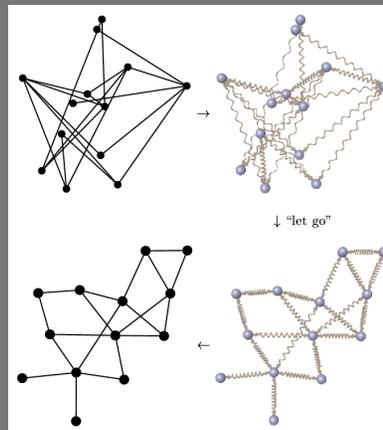


Multi-Level Hierarchy



Previous: Force-Directed Approaches

- Spring-Electrical: nodes repel, edges attract
 - Eades 1984, Fruchterman and Reingold 1991, Frick *et al.* (GEM) 1995
- Energy-Based: maxima/minima of energy function
 - Kamada and Kawai 1989, Davidson and Harel 1996, Noack 2003
- Limitation: $O(|V|^3)$ complexity

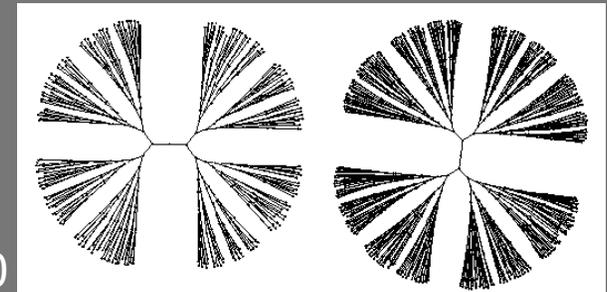
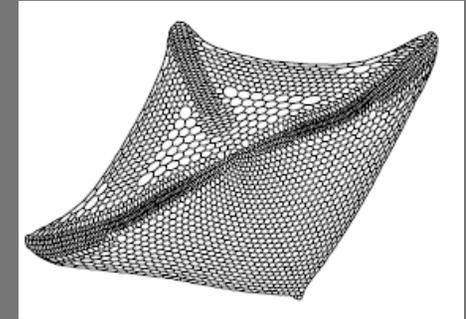


Frick et al. (GEM)

Previous: Multi-Level Approaches

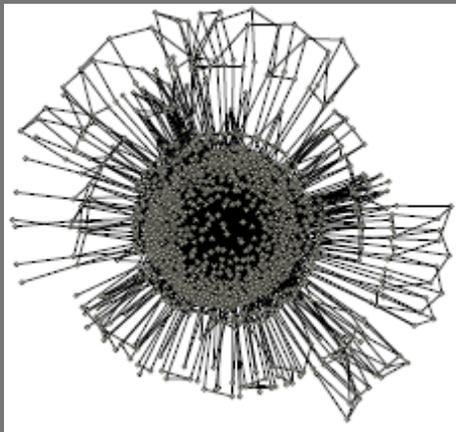
- Recursively coarsen into hierarchy
- Limitations
 - Lowest level features
 - Force-directed each level
- FM³ current state of the art
 - Provable $O(|V|\log|V| + |E|)$ complexity

Walshaw 2000

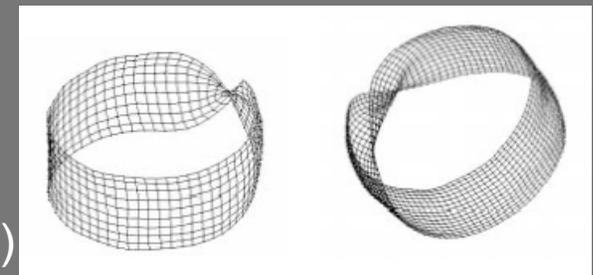


Harel and Koren 2000

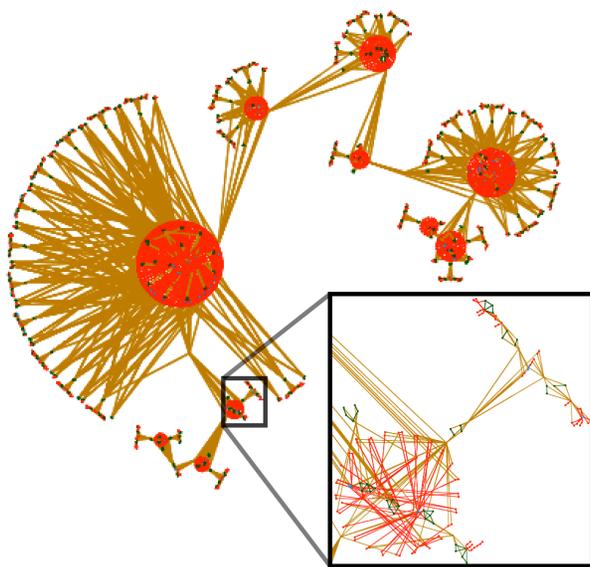
Hachul and Junger 2004 (FM³)



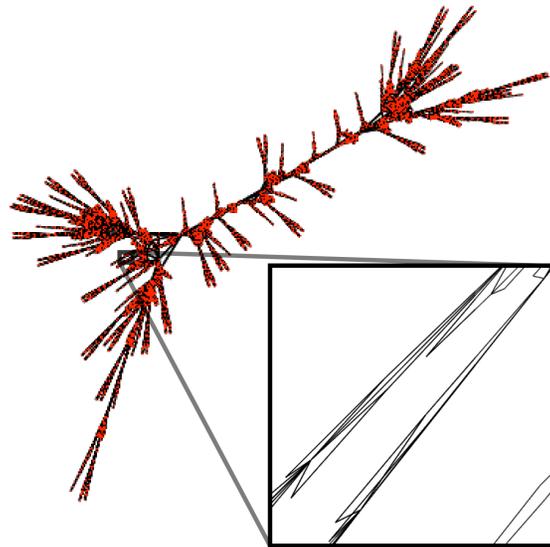
Gajer et al 2002 (GRIP)



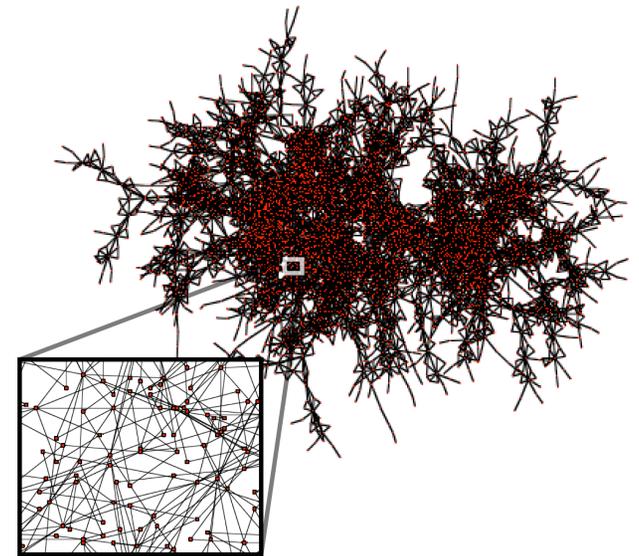
Results



TopoLayout
14 seconds



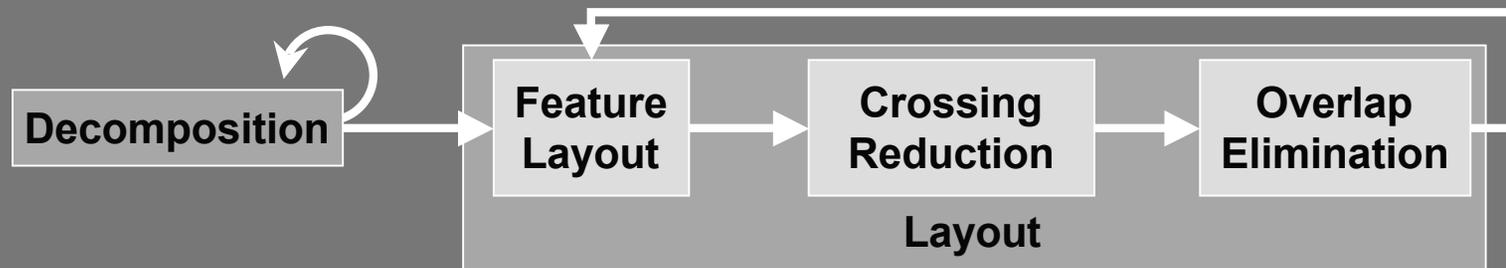
FM³
12 seconds



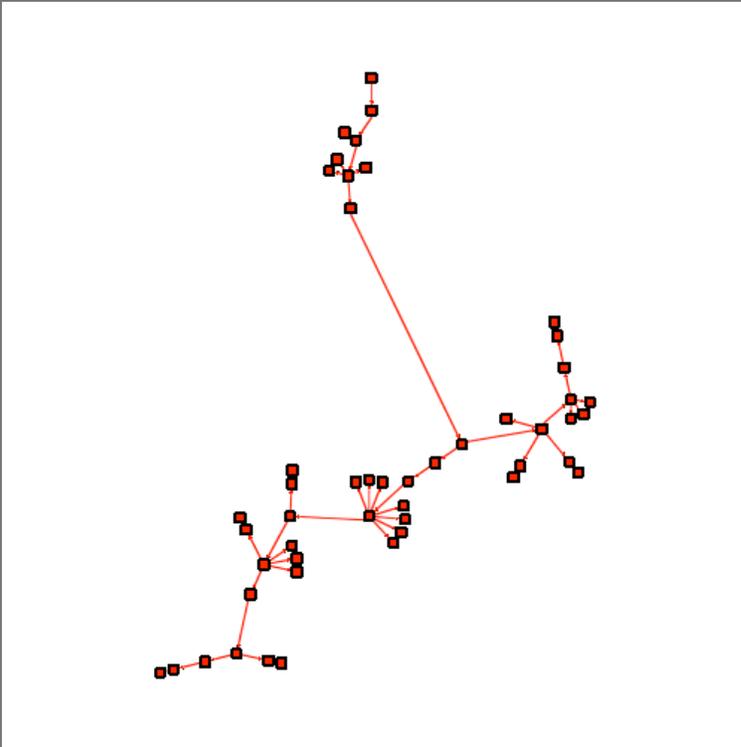
GRIP
1 second

TopoLayout Phases

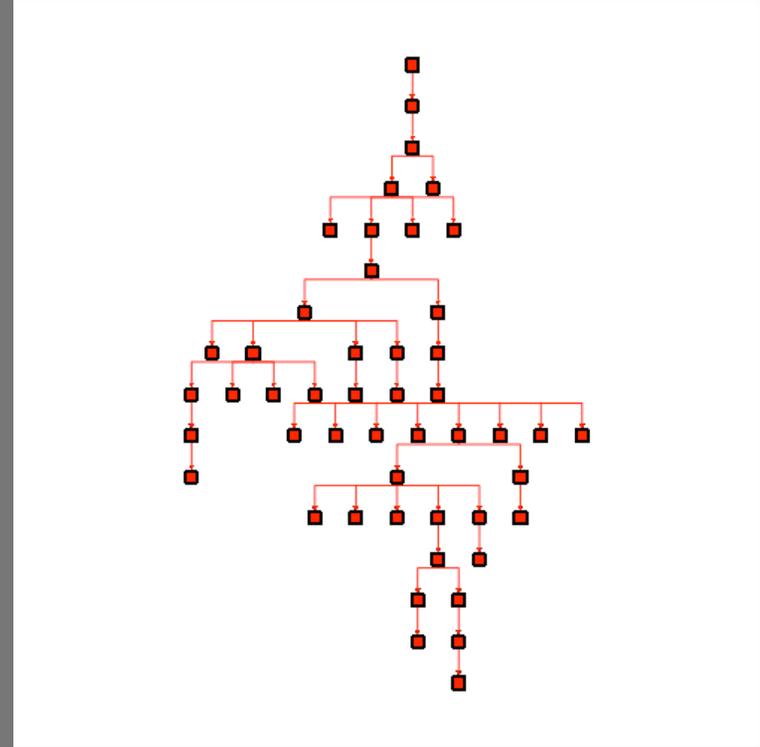
- Recursively decompose by feature
 - detectors
- Lay out each piece with appropriate algorithm
- Refine: reduce crossings, eliminate overlaps



Trees

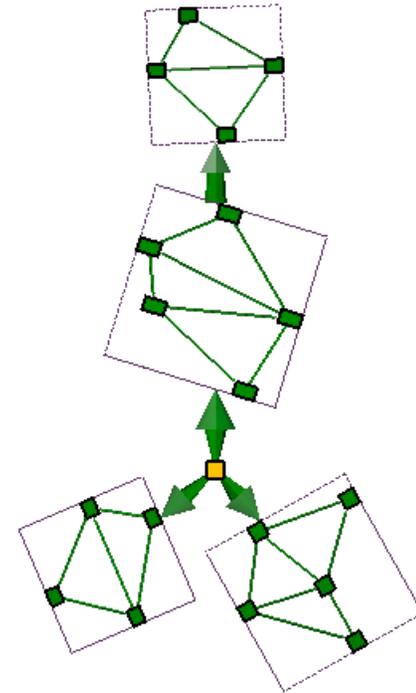
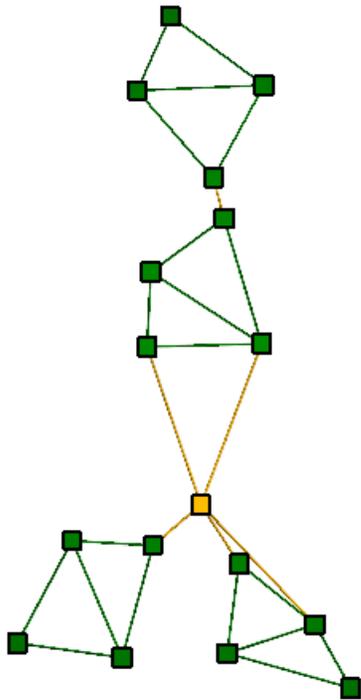


Bubble Tree, Bushy



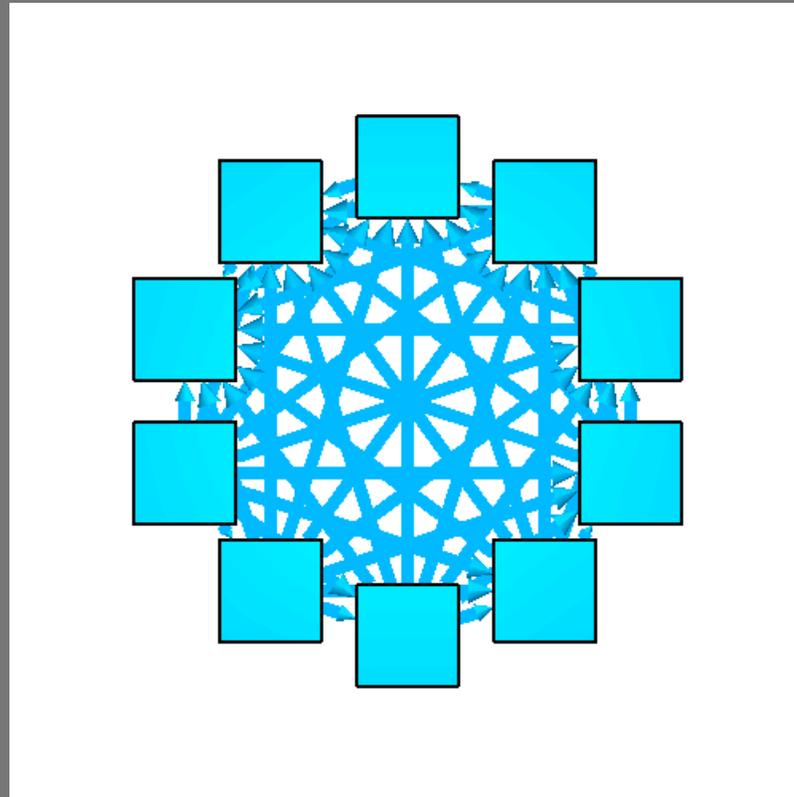
Reingold and Tilford, Deep

Biconnected



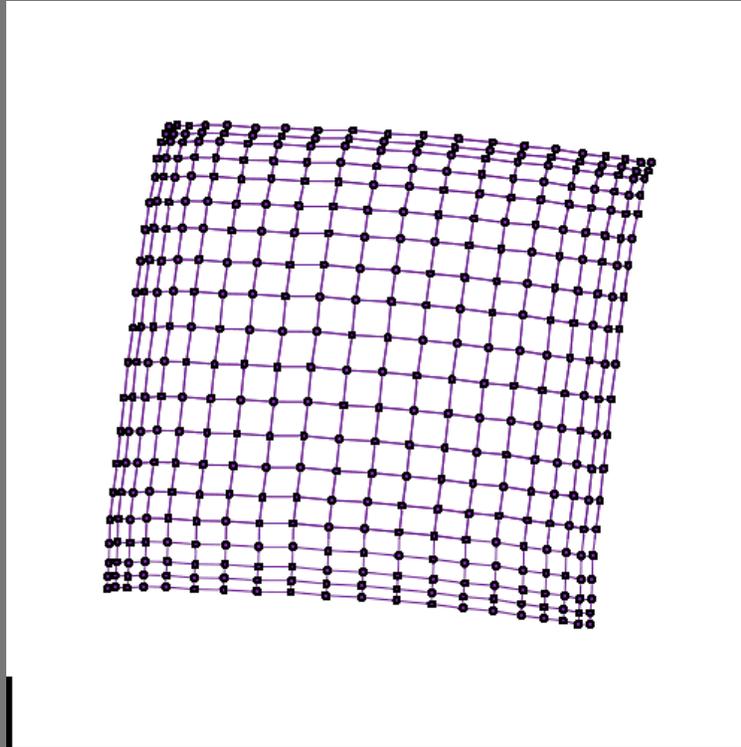
Higher level structure biconnected is a tree

Complete Graphs



Circular Layout

HDE Components

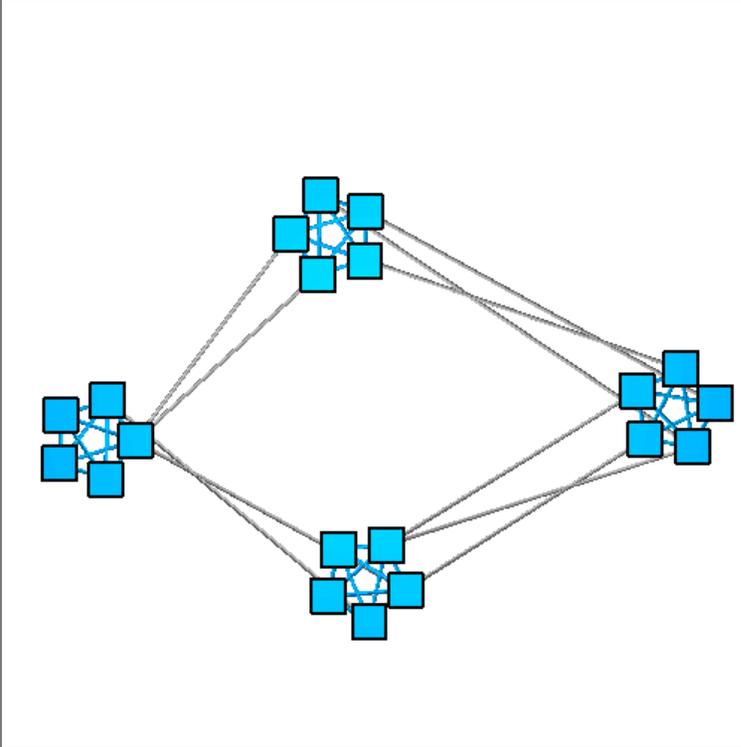


HDE

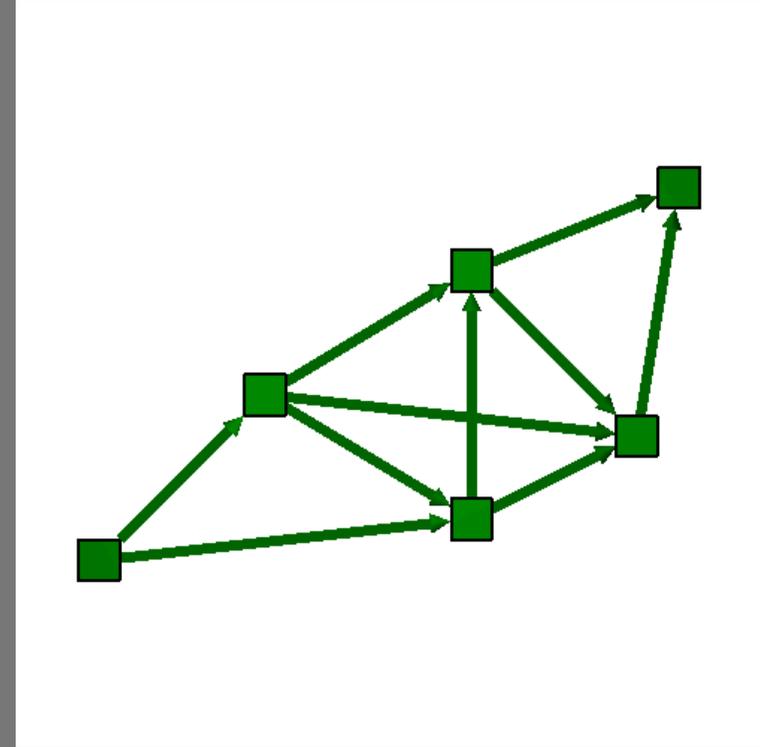
Mesh-like

Detected using eigenvalues

Cluster and Unknown



Clusters

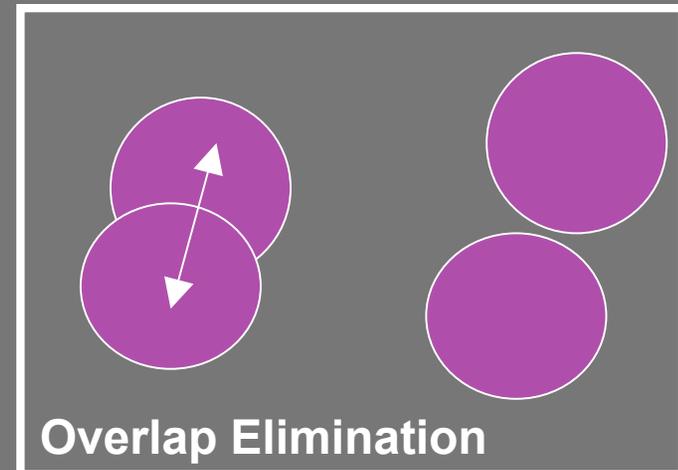
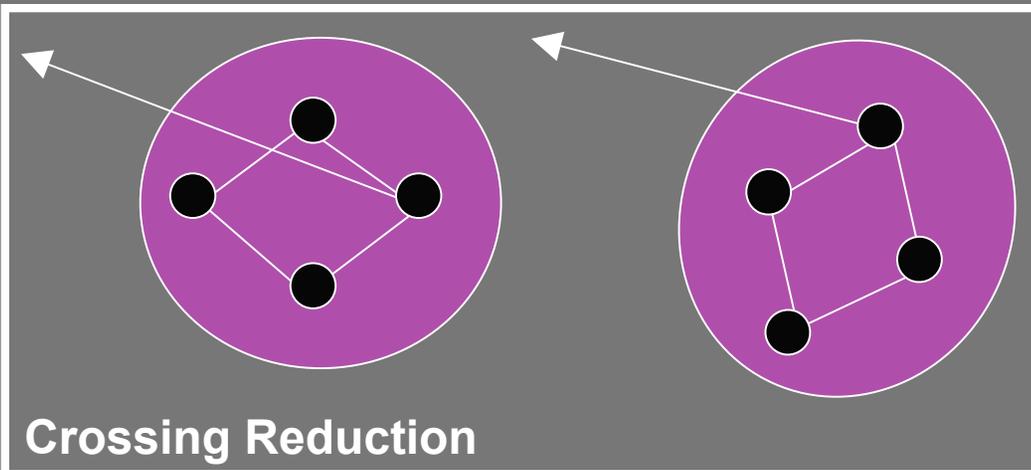


Unknown

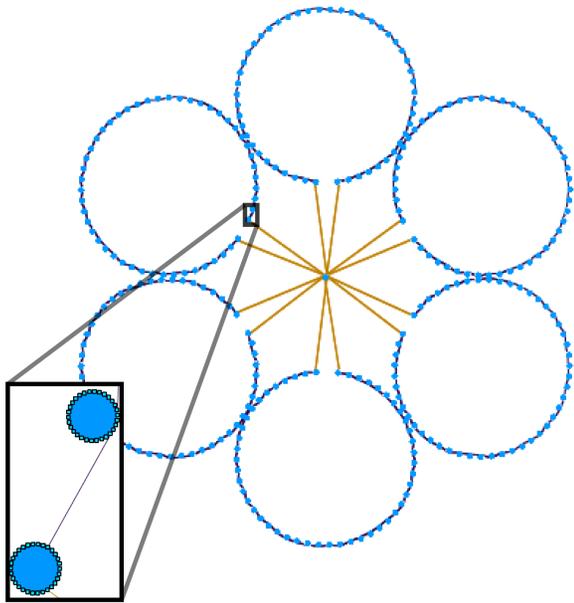
Force-directed layout - GEM

Crossing Reduction and Overlap Resolution

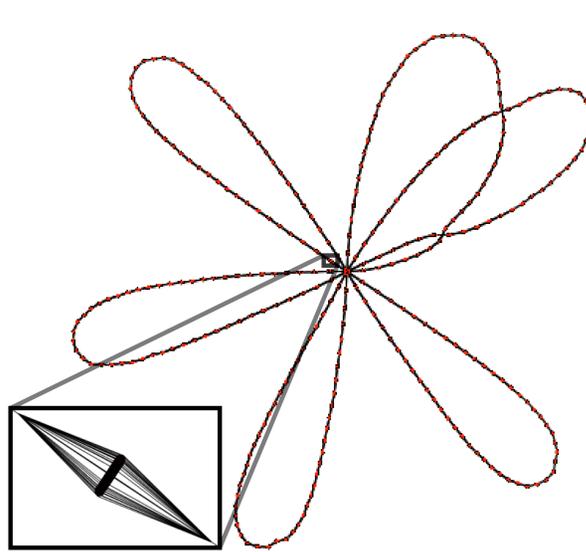
- Crossing reduction
 - Rotate features to reduce edge crossings
 - Novel algorithm described in paper
- Overlap resolution
 - No overlapping pairs features
 - Use Dwyer *et al.* $O(|V|\log|V|)$ approach



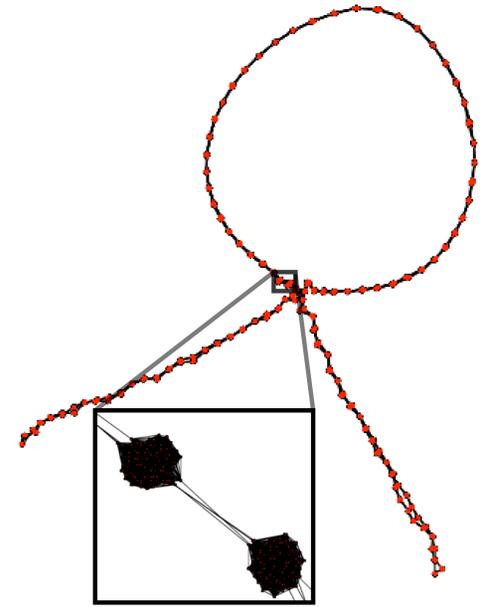
Results



TopoLayout
70 seconds

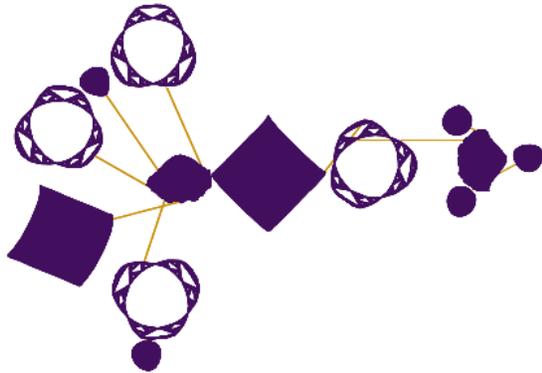


FM³
11 seconds

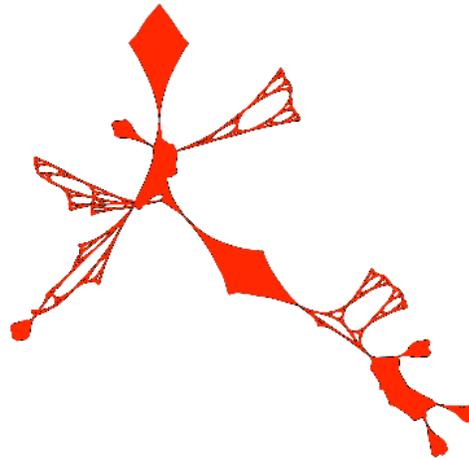


GRIP
4 seconds

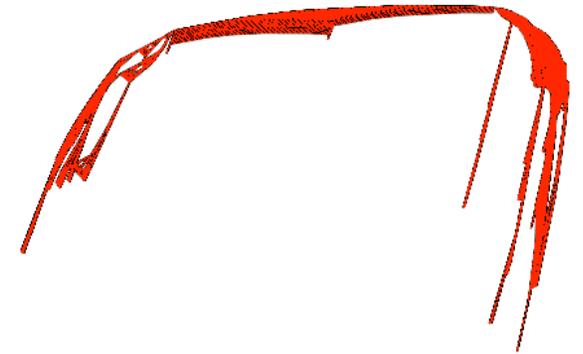
Results



TopoLayout
26 seconds



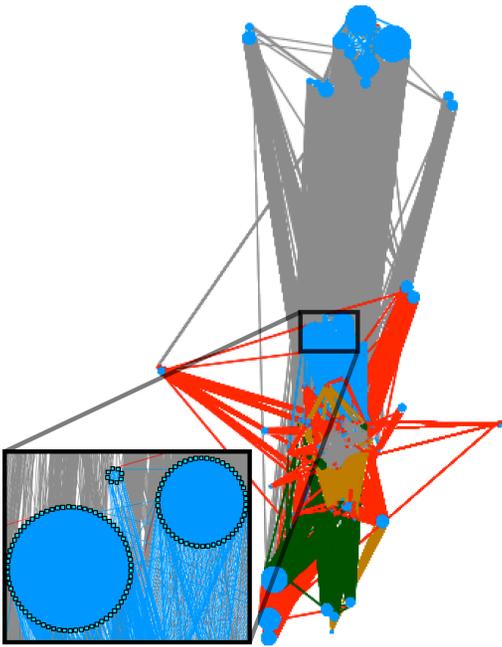
FM³
134 seconds



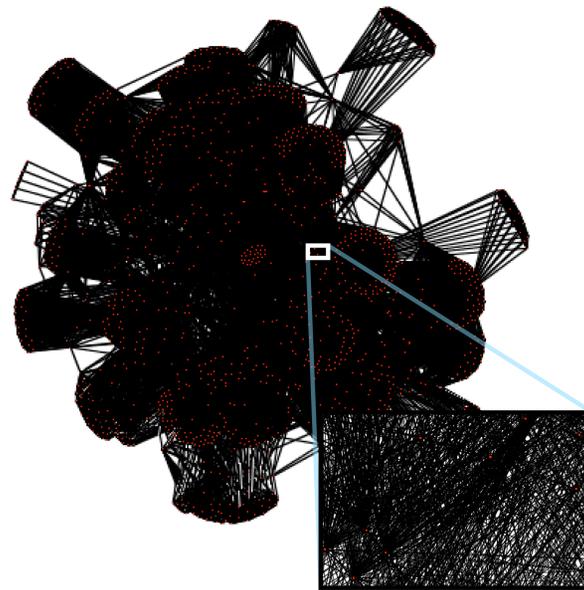
HDE
1 second

- GRIP unable to produce drawing

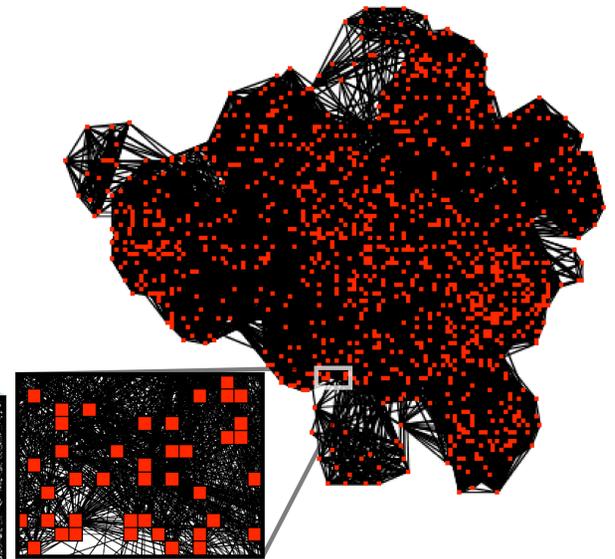
Results



TopoLayout
76 seconds



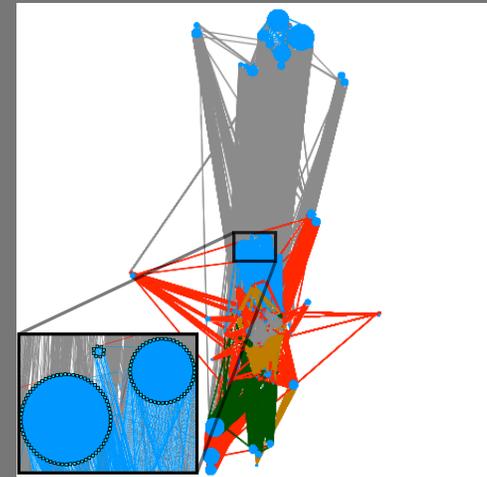
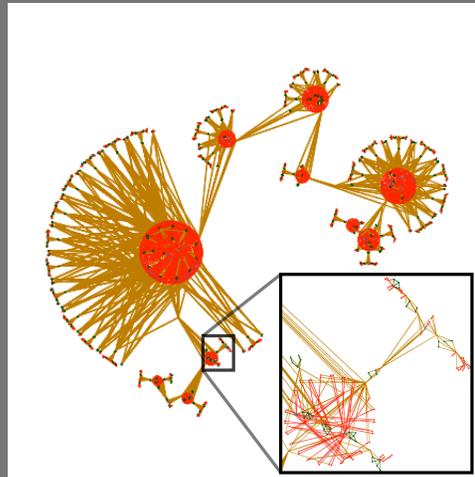
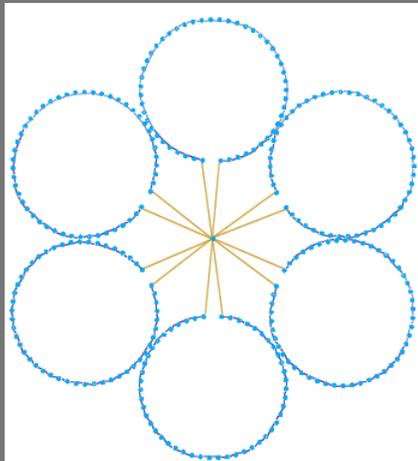
FM³
3 seconds



GRIP
1 second

Benefits and Limitations

- Benefits
 - Faster and/or better visual quality showing high-level and low-level structure
- Limitations
 - Some mid-level structure still hidden
 - Running time and visual quality degrade when no detected features are present



Outline

- Introduction
- H3
- TreeJuxtaposer
- TopoLayout
- Conclusion

Challenges

- determining appropriate information density
 - clutter vs. wasted space
- automatic detection of when given layout algorithm is appropriate
- scalability along different dimensions
 - addressed here
 - dataset size, display size
 - not addressed
 - heterogeneous vs. homogeneous datasets