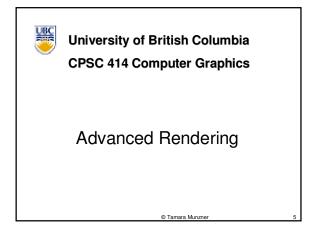
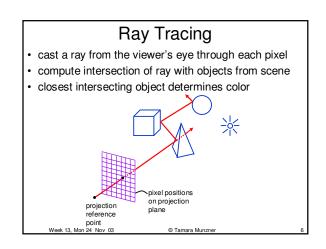
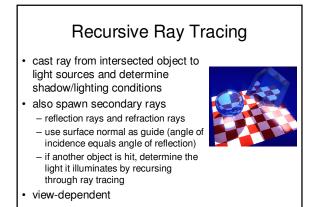


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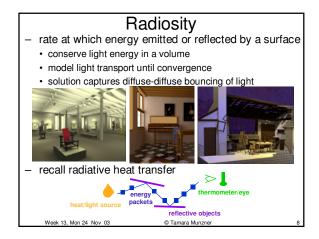


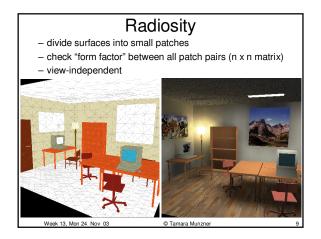


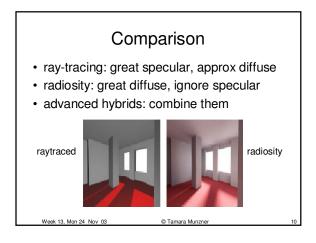


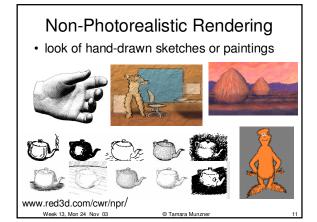
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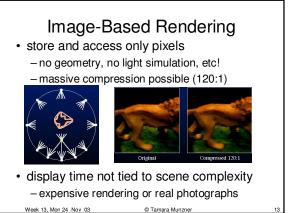


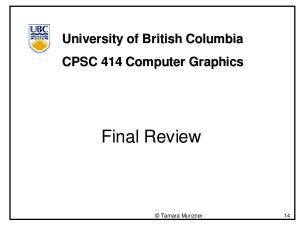


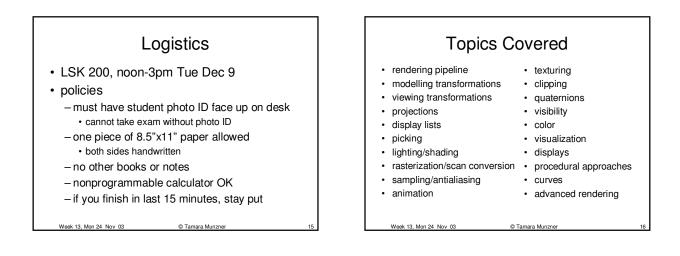


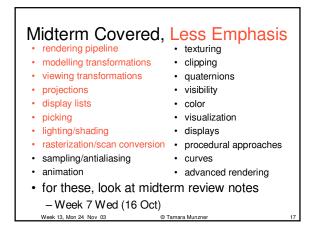










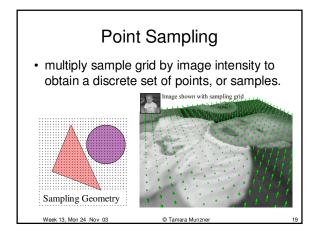


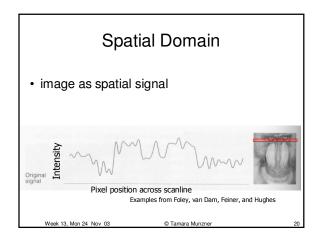


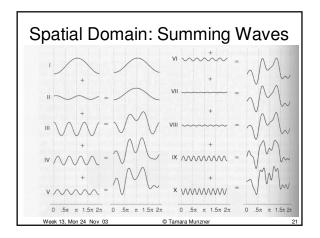
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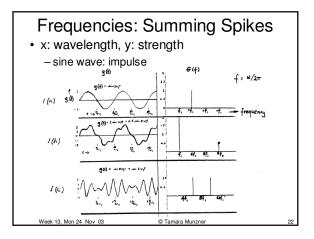
Sampling and Antialiasing

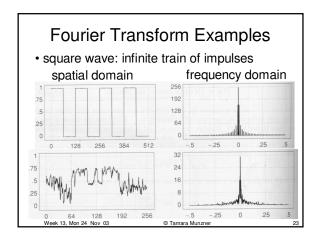
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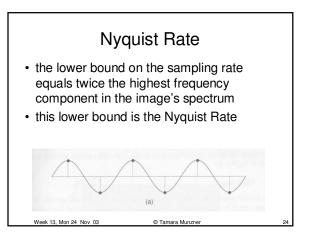


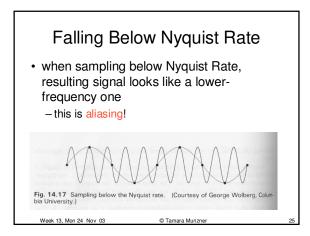


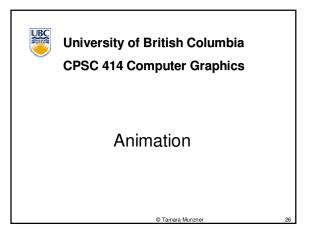


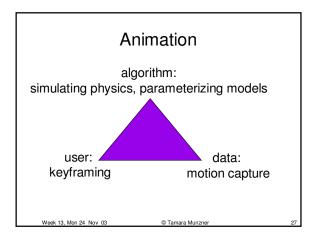


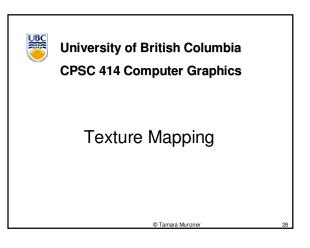


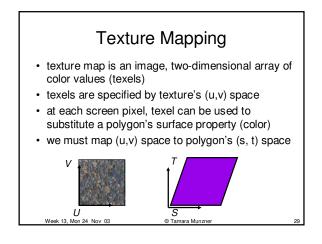


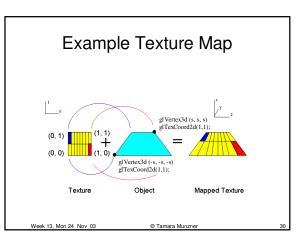


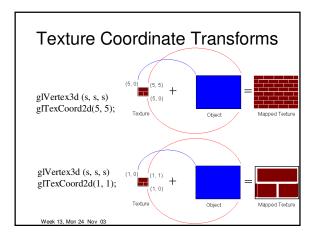


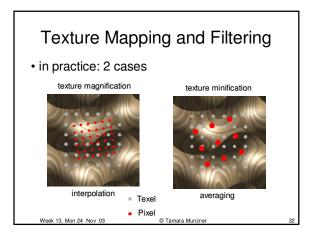


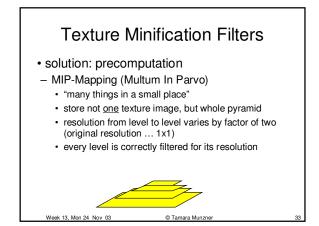


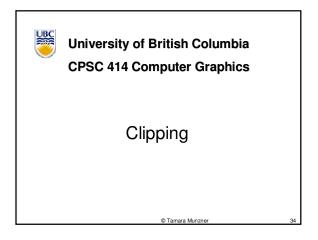


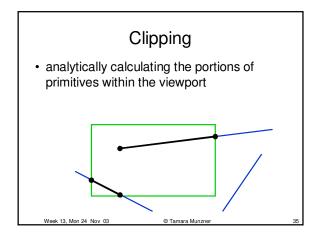


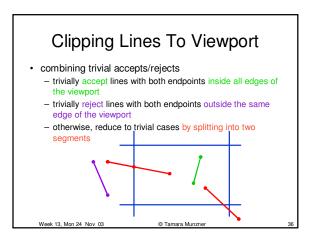


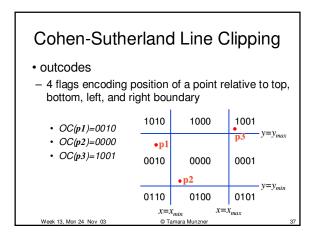


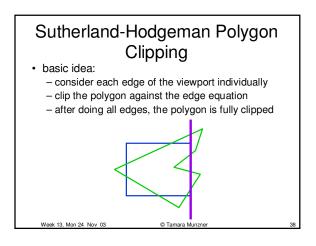


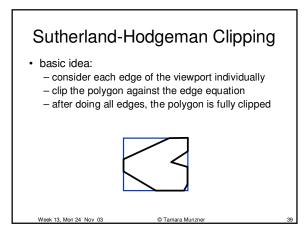


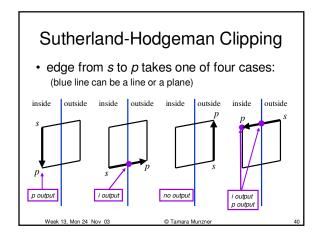


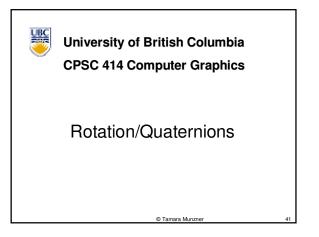














- 3x3 matrices
  good: simple. bad: drifting, can't interpolate
- Euler angles

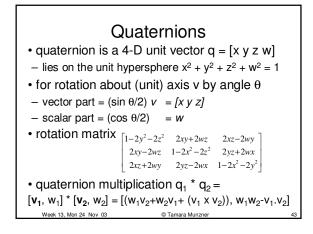
  - good: can interpolate, no drift
  - bad: gimbal lock
- axis-angle

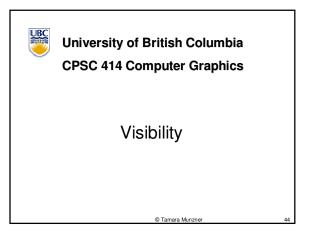
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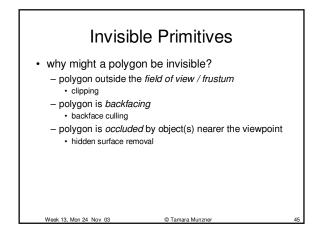
- good: no gimbal lock, can interpolate
- bad: can't concatenate
- quaternions
  good: solve all problems. bad: complex

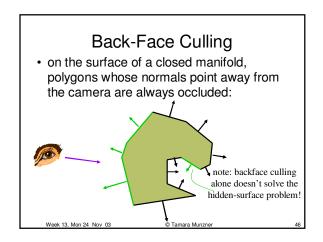
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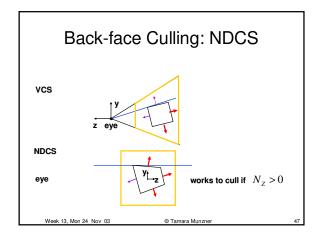
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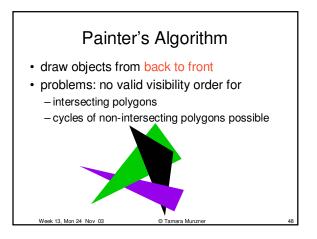


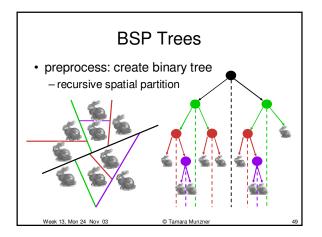


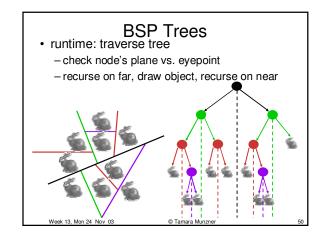


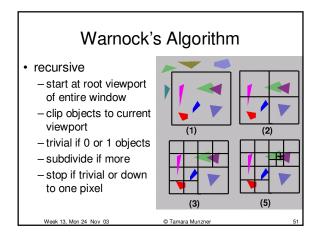


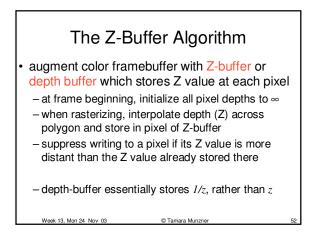












## Hidden Surface Removal

- image-space algorithms
  - · Z-buffer, Warnock's
  - perform visibility test for every pixel independently
  - · performed late in rendering pipeline, resolution dependent
- object-space algorithms
  - · painter's algorithm: depth-sorting, BSP trees
  - determine visibility on a polygon level in camera coordinates
  - early in rendering pipeline (after clipping)
  - resolution independent
  - expensive

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Color

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