

1. (1 pt) Write down the 4x4 matrix for rotating an object by 90° around the z axis.

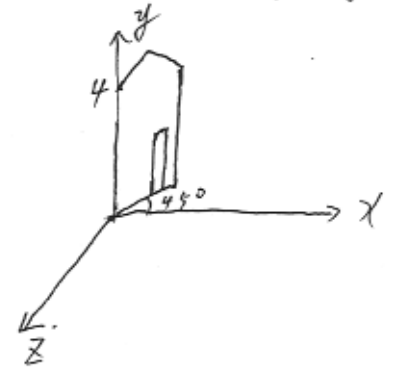
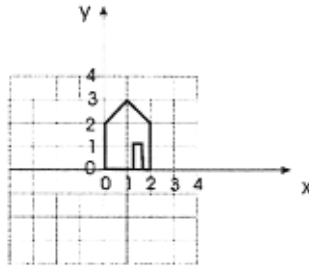
$$\begin{bmatrix} \cos 90^\circ & -\sin 90^\circ & 0 & 0 \\ \sin 90^\circ & \cos 90^\circ & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

2. (2 pts) Describe in words what this matrix does (be specific about the order of operations)

$$\begin{bmatrix} .707 & 0 & .707 & 0 \\ 0 & 2 & 0 & 0 \\ -.707 & 0 & .707 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} .707 & 0 & .707 & 0 \\ 0 & 1 & 0 & 0 \\ -.707 & 0 & .707 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & & & \\ & 2 & & \\ & & 1 & \\ & & & 1 \end{bmatrix}$$

OR =  $\begin{bmatrix} 1 & & & \\ & 2 & & \\ & & 1 & \\ & & & 1 \end{bmatrix} \begin{bmatrix} .707 & 0 & .707 & 0 \\ 0 & 1 & 0 & 0 \\ -.707 & 0 & .707 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$   
 scale in y by 2, then rotate (y, 45°)  
 rotate (y, 45°), then scale in y by 2

3. (1 pt) Draw a picture of the object below transformed by the above matrix

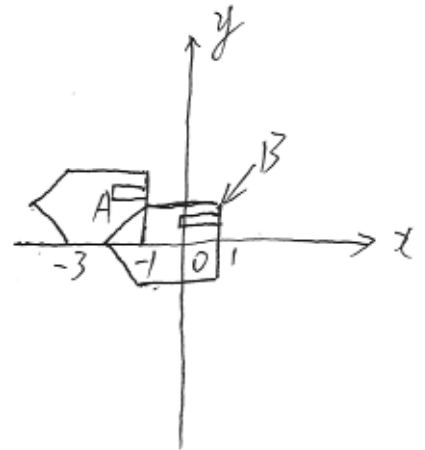
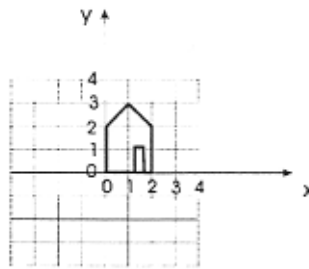


4. (1 pt) Give sequence of OpenGL commands necessary to implement the above transformation.

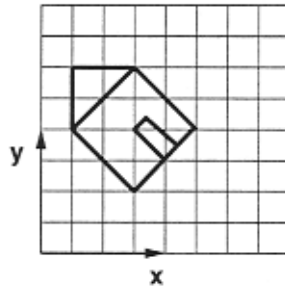
`glRotatef(45, 0, 1, 0)`  
`glScalef(1, 2, 1)`

5. (2 pts) Draw houseA and houseB, transformed by the appropriate OpenGL commands. The untransformed house is below.

```
glLoadIdentity();
glTranslate(1, 0, 0);
glRotate(90, 0, 0, 1);
glPushMatrix();
glTranslate(0, 2, 0);
drawHouseA();
glPopMatrix();
glTranslate(-1, 0, 0);
drawHouseB();
```



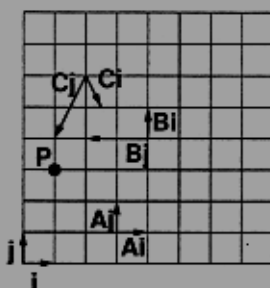
6. (1 pt) Give the series of affine transformations (assuming postmultiplying) needed to create the picture below, assuming the house started from the position shown in the above questions.



$glTranslate(3, 2, 0)$   
 $glRotate(45, 0, 0, 1)$   
 $glScale(\sqrt{2}, \sqrt{2}, 1)$

$$\begin{aligned}
 & \begin{bmatrix} \text{Translate} \\ \text{Rotate} \\ \text{scale} \end{bmatrix} \\
 = & \begin{bmatrix} 1 & & & 3 \\ & 1 & & 2 \\ & & 1 & \\ & & & 1 \end{bmatrix} \begin{bmatrix} \cos 45^\circ & -\sin 45^\circ & & \\ \sin 45^\circ & \cos 45^\circ & & \\ & & 1 & \\ & & & 1 \end{bmatrix} \begin{bmatrix} \sqrt{2} & & & \\ & \sqrt{2} & & \\ & & 1 & \\ & & & 1 \end{bmatrix}
 \end{aligned}$$

7. (1 pt) The point coordinate P, as shown below to the right, can be thought of as  $P = 1i + 3j$ , where i and j are basis vectors of unit length along the x and y axes, respectively. In effect, a coordinate system is defined by the location of its origin, and its basis vectors. Describe the point P in terms of the 3 other coordinate systems given below.



$$\left. \begin{aligned} P &= -2A_i + 2A_j \\ P &= -1B_i + 1.5B_j \end{aligned} \right\} \frac{1}{2}$$

$$P = 0.5C_i + 1.25C_j - \frac{1}{2}$$

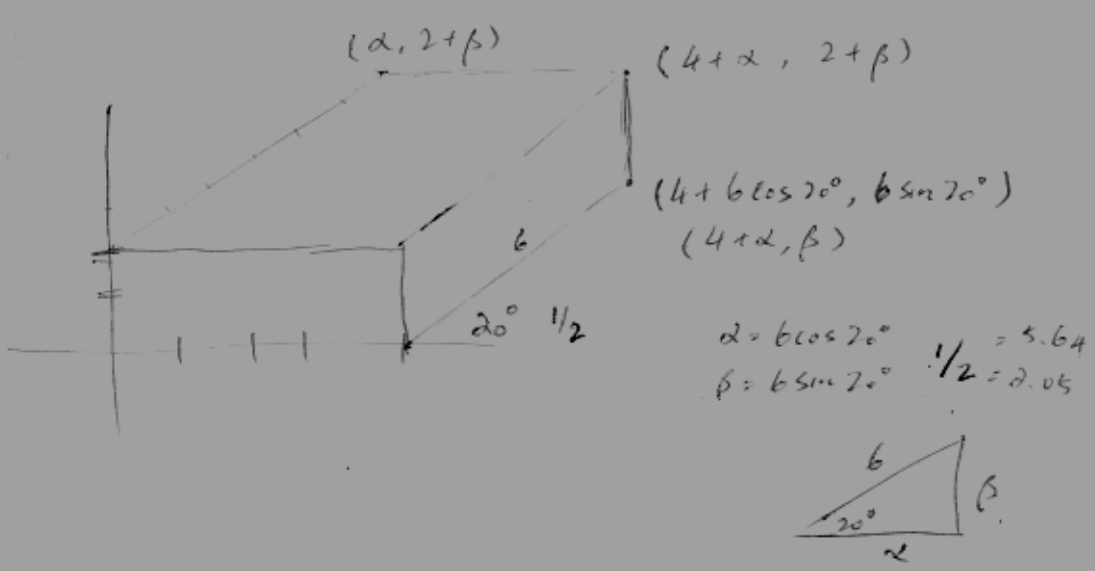
$$\begin{pmatrix} 1 \\ 3 \end{pmatrix} = a \begin{pmatrix} 0.5 \\ -1 \end{pmatrix} + b \begin{pmatrix} -1 \\ -2 \end{pmatrix} + \begin{pmatrix} 2 \\ 6 \end{pmatrix}$$

$$\begin{aligned} 0.5a - b &= -1 & a - 2b &= 2 & 2a &= 1 & a &= \frac{1}{2} \\ -a - 2b &= -3 & -a - 2b &= -3 & -\frac{1}{2} - 2b &= -3 & 2b &= \frac{5}{2} & b &= \frac{5}{4} \end{aligned}$$

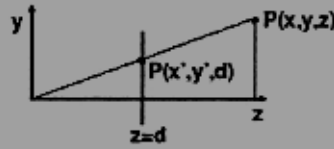
8. (1 pt) Normalize the homogenous point (2,4,6,2).

$$(1, 2, 3, 1) = \left( \frac{2}{2}, \frac{4}{2}, \frac{6}{2}, \frac{2}{2} \right)$$

9. (1 pt) Draw the cavalier projection of a box of size  $x=4, y=2, z=6$ . Use a  $20^\circ$  projection (that is, the z axis in the scene should make a  $20^\circ$  angle with the x axis in the projection). The drawing doesn't have to be exactly to scale, but you must label the point locations.



10. (2 pts) Derive a 4x4 matrix that when applied to the point  $(x, y, z, 1)^T$  would result in the projection in the picture below. Show your work.

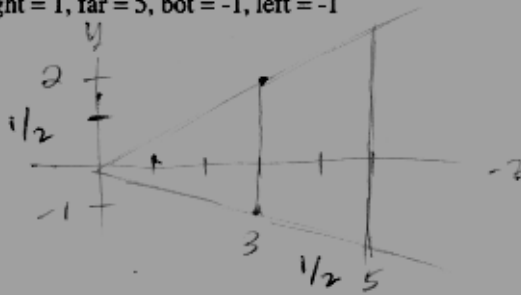


$$\frac{x'}{d} = \frac{x}{z} \quad x' = \frac{xd}{z}$$

$$\frac{y'}{d} = \frac{y}{z} \quad y' = \frac{yd}{z}$$

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1/d & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \\ z/d \end{pmatrix} \rightarrow \begin{pmatrix} xd/z \\ yd/z \\ d \\ 1 \end{pmatrix} = \begin{pmatrix} x' \\ y' \\ d \\ 1 \end{pmatrix}$$

11. (1 pt) Sketch a side view (yz plane) of the perspective view frustum, in VCS, that is specified by the following parameters: near = 3, top = 2, right = 1, far = 5, bot = -1, left = -1



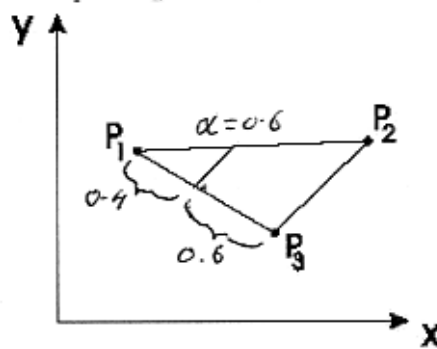
12. (1 pt) Write out the OpenGL perspective transformation matrix for the above configuration.

$$\begin{pmatrix} \frac{6}{2} & 0 & \frac{0}{2} & 0 \\ 0 & \frac{6}{3} & \frac{1}{3} & 0 \\ 0 & 0 & -\frac{8}{2} & -\frac{30}{2} \\ 0 & 0 & -1 & 0 \end{pmatrix} = \begin{pmatrix} 3 & 0 & 0 & 0 \\ 0 & 2 & \frac{1}{3} & 0 \\ 0 & 0 & -4 & -15 \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

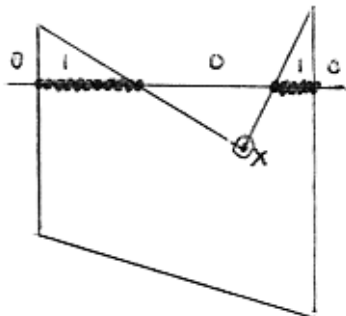
13. (1 pt) Briefly describe how to implement per-object picking using the back buffer.

STORE A UNIQUE COLOR FOR EACH OBJECT (PICKABLE) IN SCENE IN A TABLE.  
 RENDER SCENE TO BACK BUFFER WITH SHADING TURNED OFF. READ BACK  
 PIXEL AT CURSOR LOCATION AND CHECK AGAINST TABLE.

14. (1 pt) A point in a triangle can be expressed using barycentric coordinates as follows:  $P = \alpha P_1 + \beta P_2 + \gamma P_3$ , where  $0 \leq \alpha, \beta, \gamma \leq 1$  and  $-\alpha + \beta + \gamma = 1$ . Draw the line corresponding to  $\alpha = .6$  on the following triangle which sits in the  $xy$ -plane.



15. (1 pt) Briefly describe how to use parity when scan converting a general polygon.



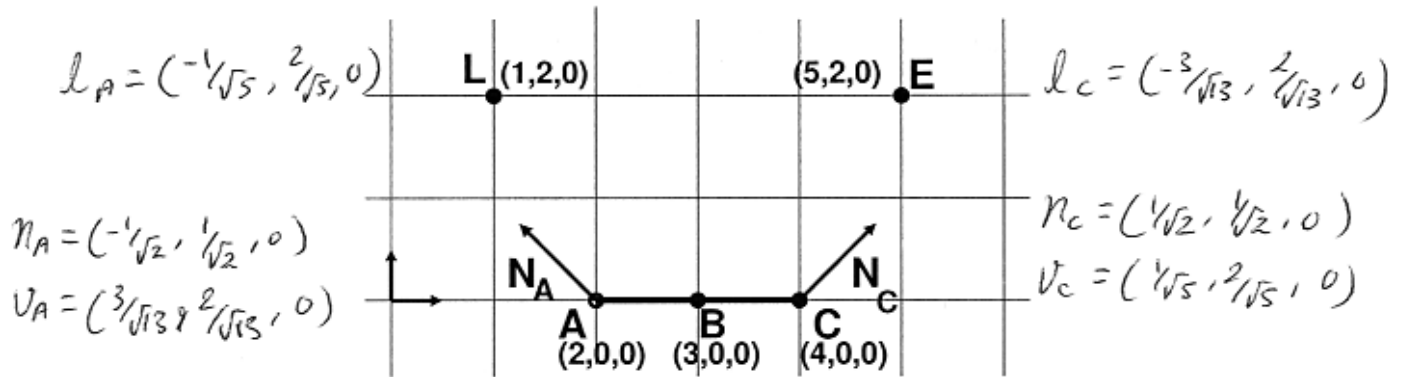
PARITY TEST:

SCAN ALONG EACH SCANLINE. ON ODD  
 NUMBER OF EDGE CROSSINGS, RASTERIZE  
 PIXELS. ON EVEN EDGE CROSSINGS STOP  
 RASTERIZING.

SPECIAL CASES:

- (i) COUNT CONCAVE (SPLIT) VERTICES TWICE (E.G. X)
- (ii) DON'T RASTERIZE BOTTOM HORIZONTAL EDGE.

In the problems below, use the Phong illumination model given by  $I = I_a k_a + k_d I_L (N \cdot L) + k_s I_L (R \cdot V)^n$  with parameters  $I_a = .8, I_L = 1.0, k_a = .2, k_d = .9, k_s = .5, n = 30$ .



16. (2 pts) Give the specular component of B, using the Gouraud shading model.

$$R_A = 2 \times n_A \times (n_A \cdot l_A) - l_A = (-\frac{2}{\sqrt{5}}, \frac{1}{\sqrt{5}}, 0) \quad \therefore R_A \cdot v_A = 0$$

$$\therefore \text{SPECULAR}_A = k_s \times I_L \times (R_A \cdot v_A)^n = 0$$

$$R_C = 2 \times n_C \times (n_C \cdot l_C) - l_C = -l_C \quad [n_C \cdot l_C = 0] \quad \therefore R_C \cdot v_C = 0$$

$$\therefore \text{SPECULAR}_C = k_s \times I_L \times (R_C \cdot v_C)^n = 0$$

$$\therefore \text{SPECULAR}_B = \underline{\text{SPECULAR}_A + \text{SPECULAR}_C} = 0$$

17. (2 pts) Give the specular component of B, using the Phong shading model.

$$n_B = \frac{n_A + n_C}{|n_A + n_C|} = (0, 1, 0)$$

$$l_B = (-\frac{2}{\sqrt{8}}, \frac{2}{\sqrt{8}}, 0)$$

$$v_B = (\frac{2}{\sqrt{8}}, \frac{2}{\sqrt{8}}, 0)$$

$$R_B = 2 \times n_B \times (n_B \cdot l_B) - l_B = (\frac{2}{\sqrt{8}}, \frac{2}{\sqrt{8}}, 0)$$

$$\therefore R_B \cdot v_B = (\frac{4}{8} + \frac{4}{8} + 0) = 1.0$$

$$\therefore \text{SPECULAR}_B = 0.5 \times 1.0 \times 1.0 = 0.5$$