

# Introduction to Scientific Visualization

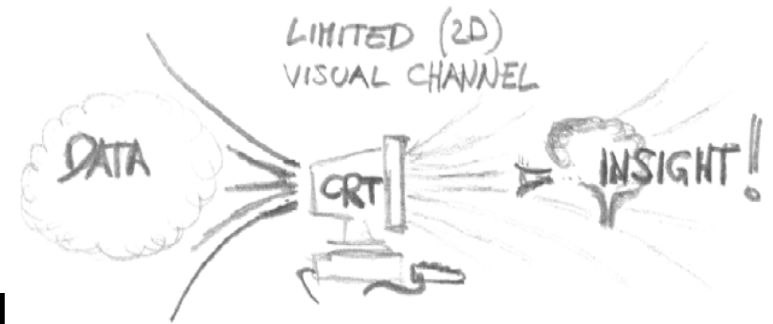
Stefan Bruckner

Simon Fraser University /  
Vienna University of Technology



**visualization:** to form a **mental vision, image,** or **picture** of (something not visible or present to the sight, or of an abstraction); to make **visible to the mind or imagination**

[Oxford Engl. Dict., 1989]



**tool to enable a user insight into data**

“The purpose of computing is **insight**, not numbers.”

[R. Hamming, 1962]



## ■ Visualization, ...

### ◆ ... to explore

- Nothing is known,  
Vis used for data exploration

### ◆ ... to analyze

- There are hypotheses,   
Vis used for verification or falsification

### ◆ ... to present

- “everything” known about the data,   
Vis used for communication of results



## ■ Three major areas

◆ Volume  
Visualization

◆ Flow  
Visualization

Scientific  
Visualization

inherent spatial  
reference

2D/3D

◆ Information  
Visualization

nD

usually no spatial  
reference



## ■ **N-dimensional vs. 2/3-dimensional**

- ◆ SciVis can be N-dimensional too (time series, simulation data, ...)

## ■ **Abstract data vs. spatial data**

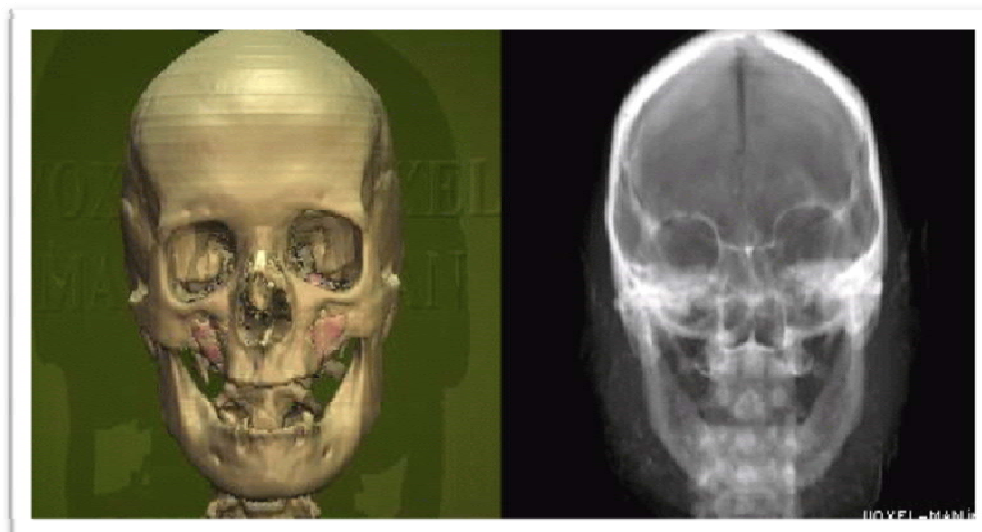
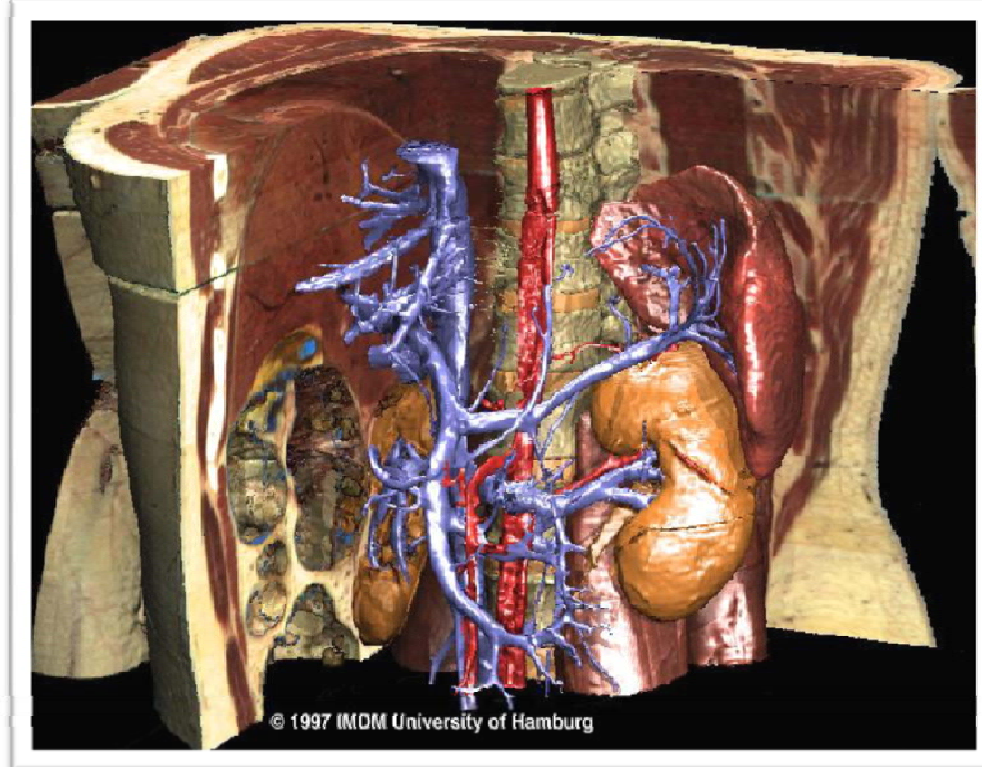
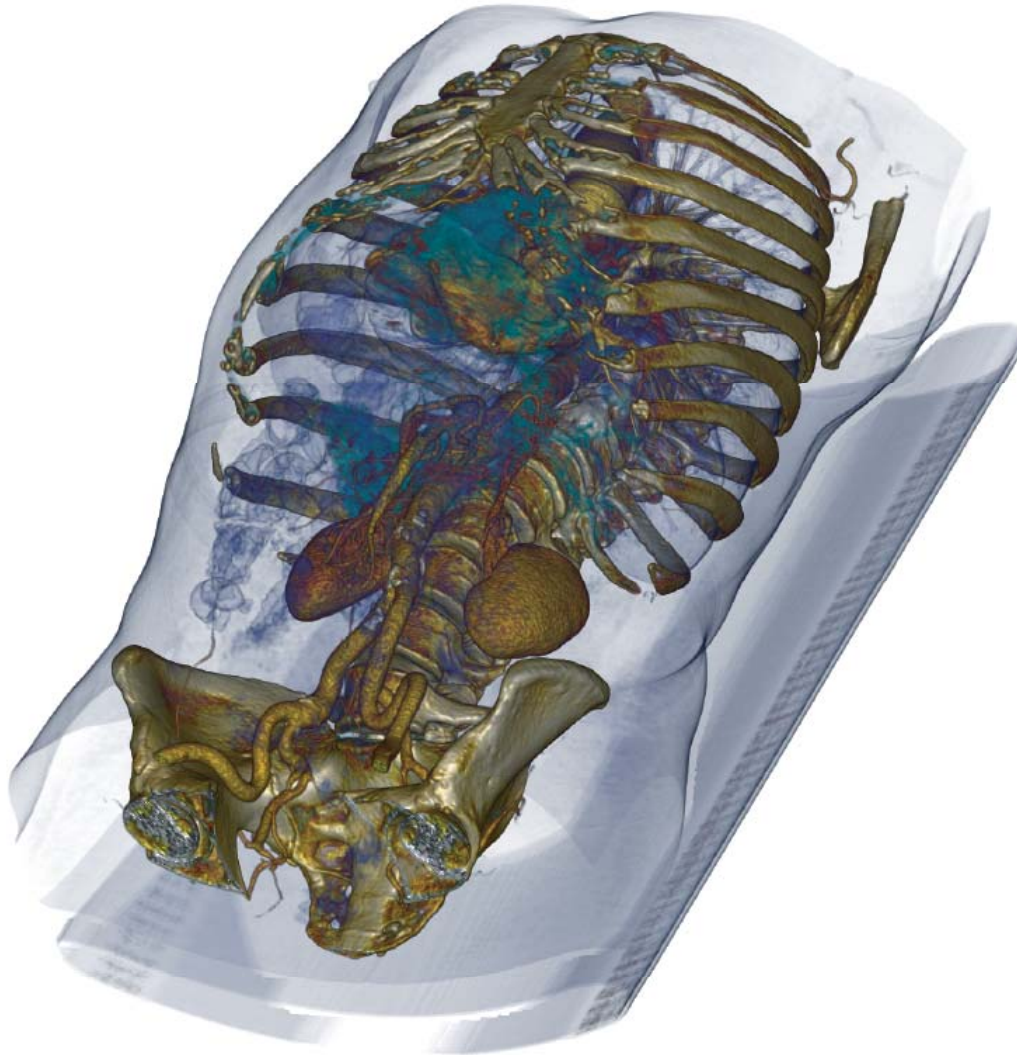
- ◆ InfoVis data may also have spatial attributes (country, state, ...)

## ■ **Discrete data vs. continuous data**

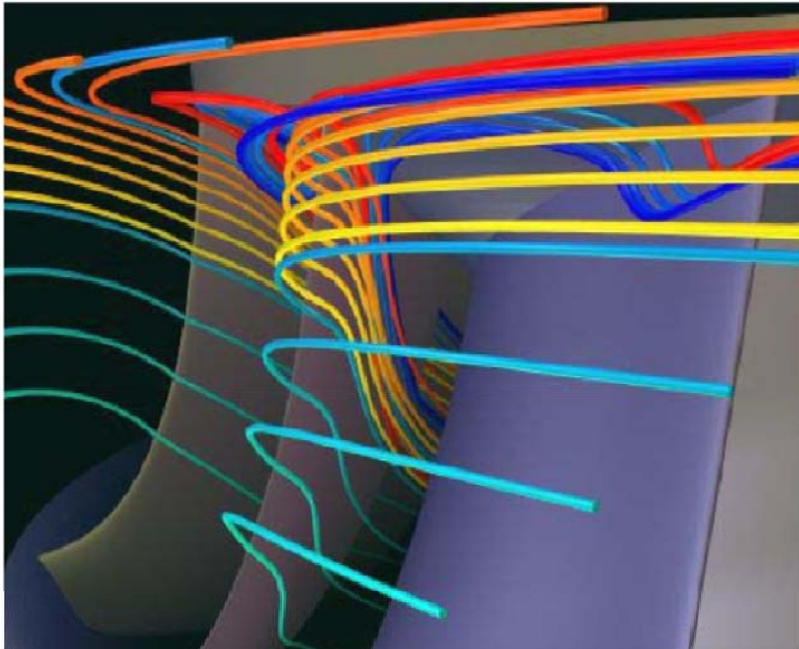
- ◆ InfoVis data may be sampled from a continuous domain



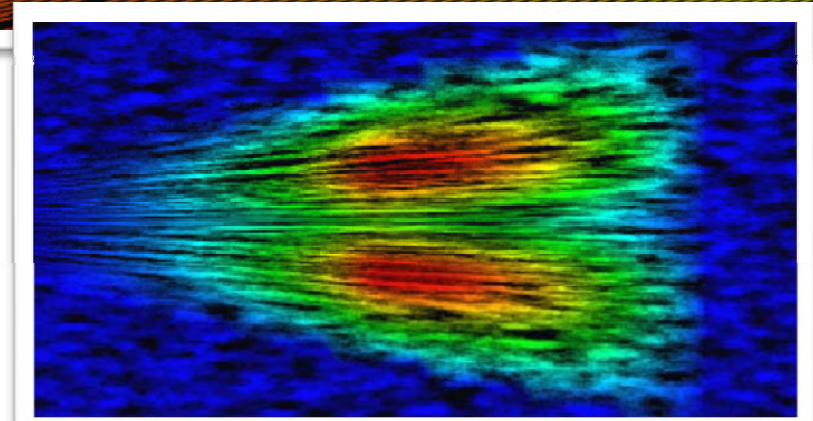
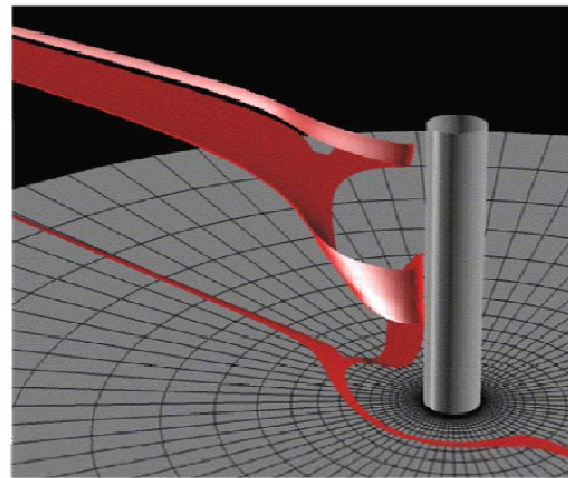
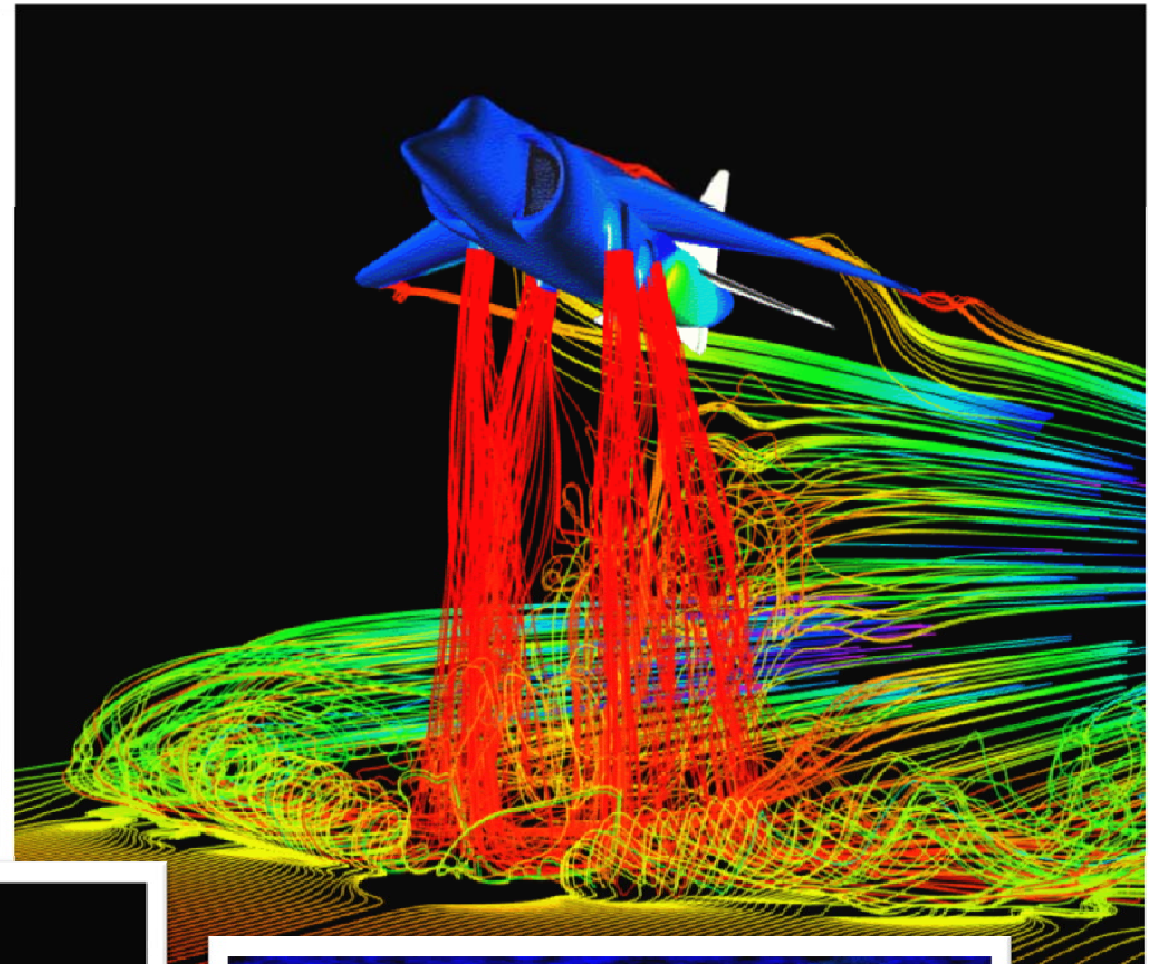
## ■ Volume data

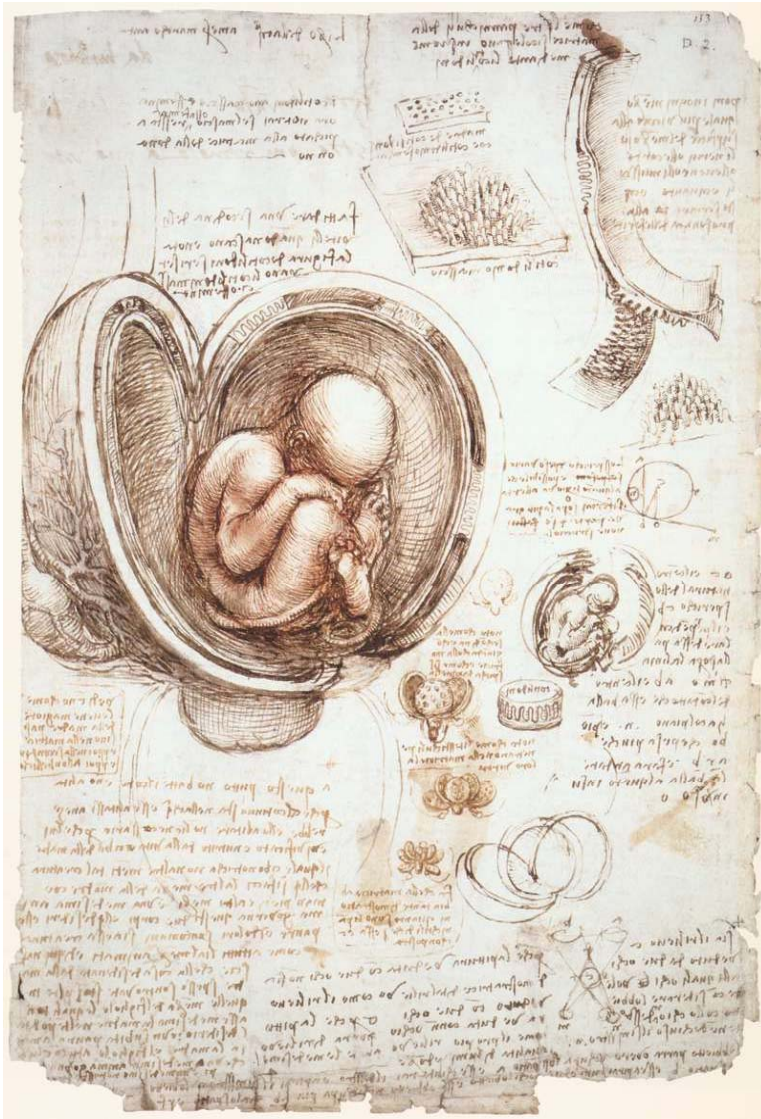


## ■ Flow data

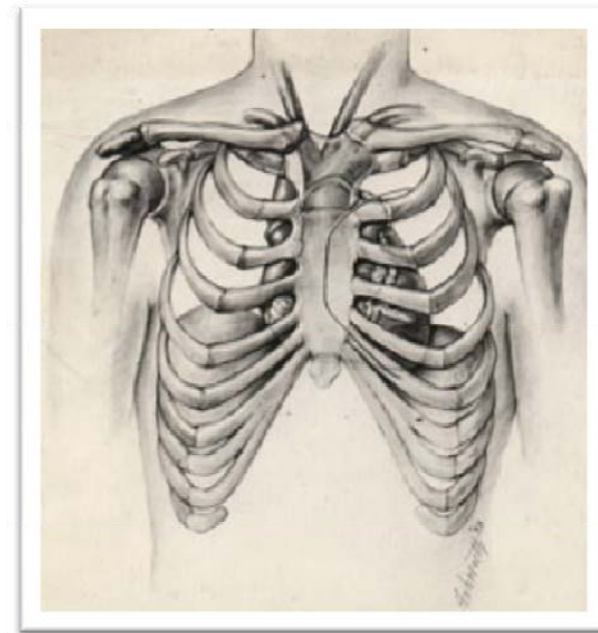
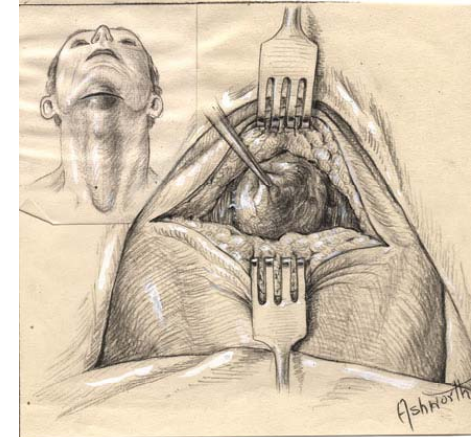
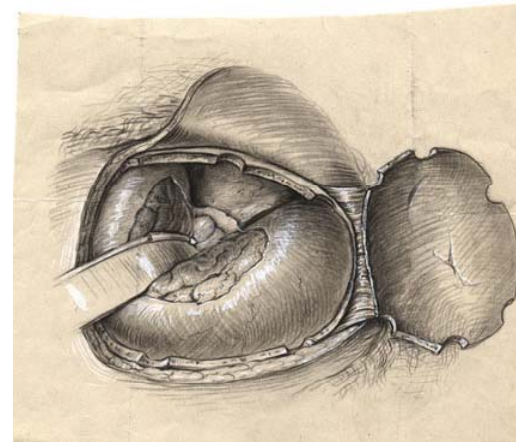


Visualization: Martin Roth, ETH Zurich  
Simulation: Sulzer Hydro Ltd., Zurich  
<http://www.spsc.ethz.ch/SV/turbo>





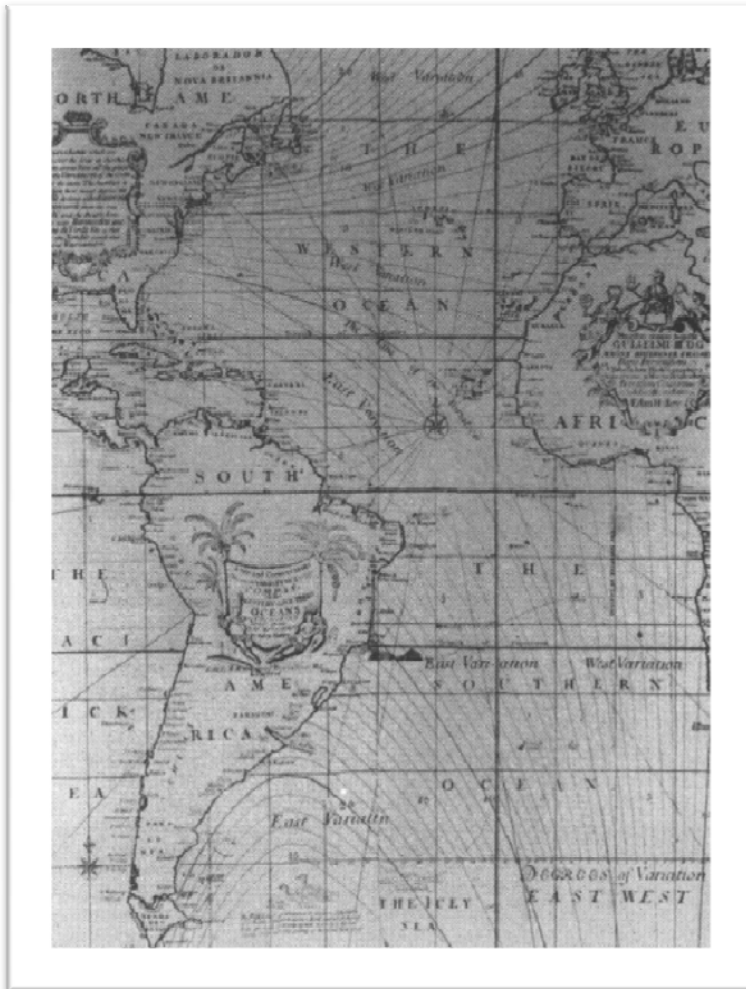
sketch from Leonardo Da Vinci's anatomical notebooks



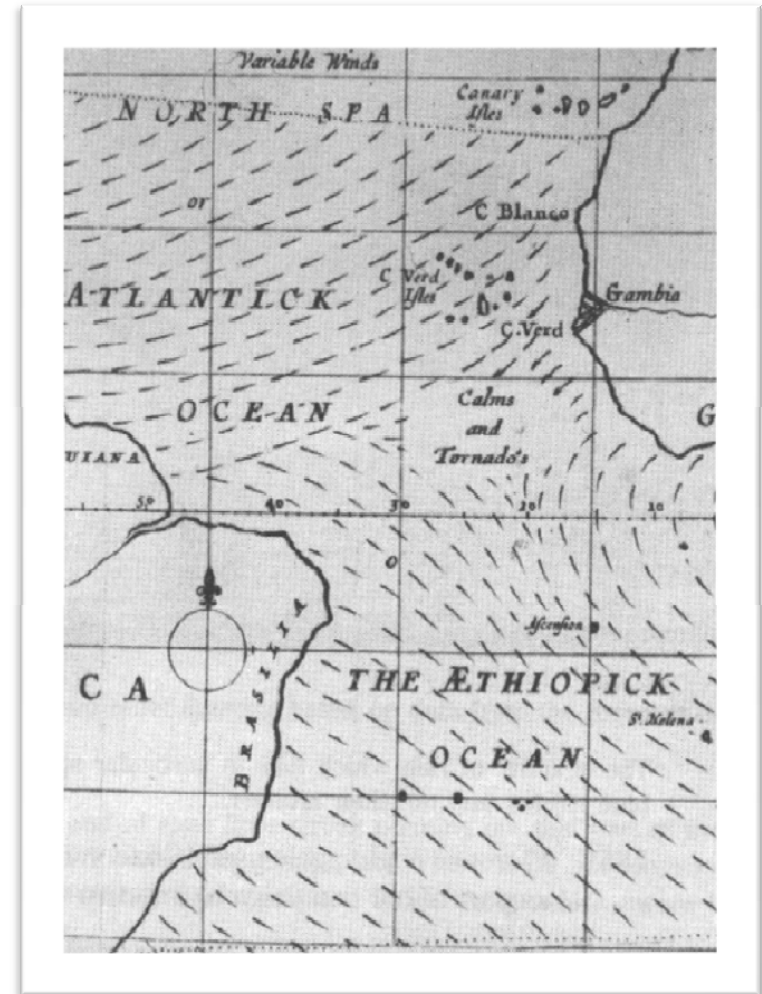
medical illustrations by Clarice Ashworth Francone







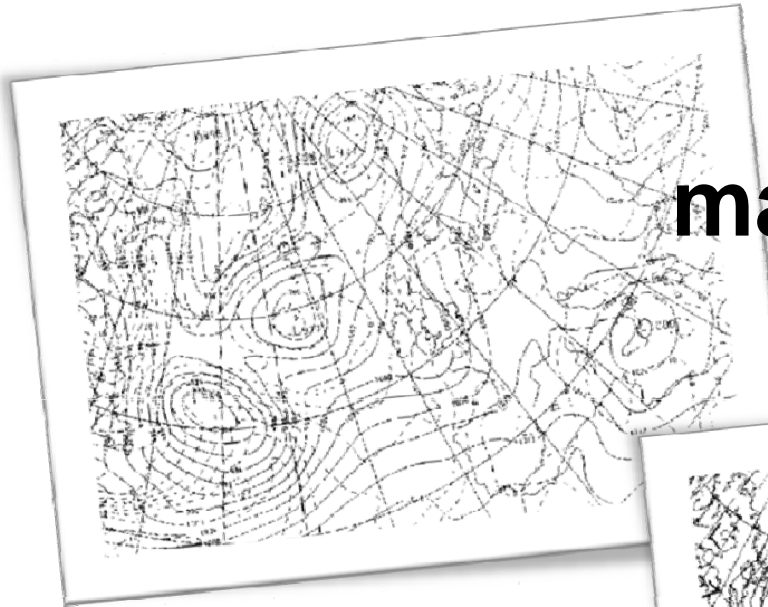
**isolines to visualize  
compass deviations**



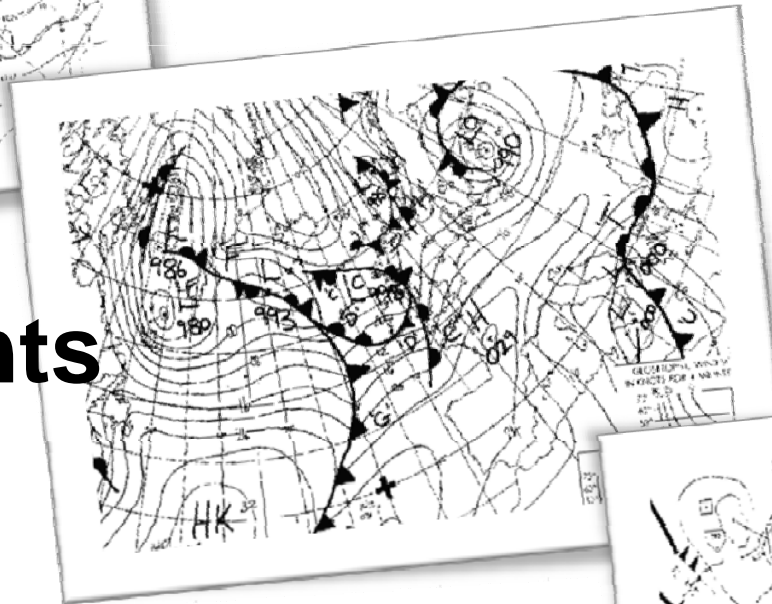
**wind flow  
visualization**



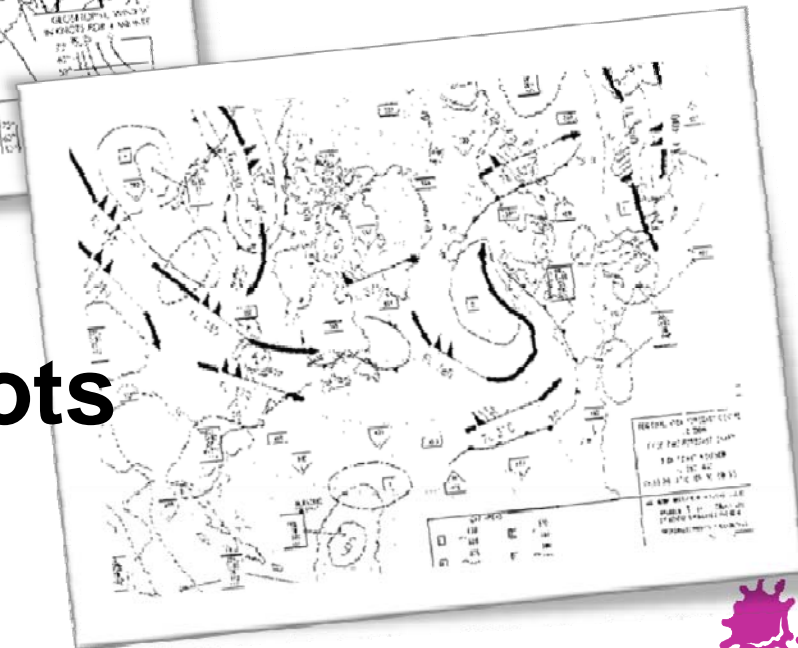
**map with iso-pressure lines**



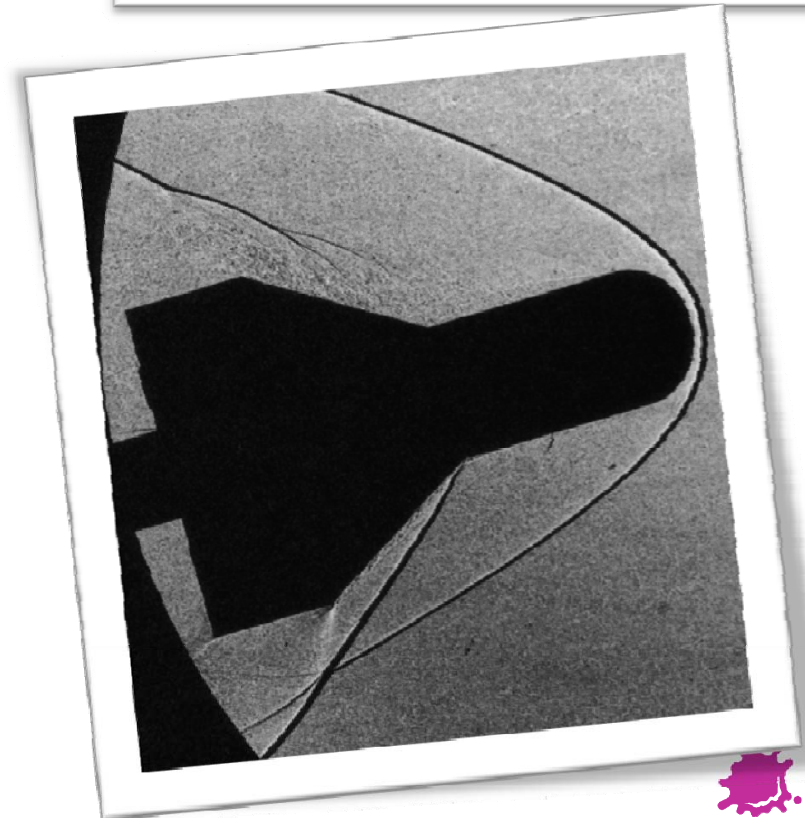
**weather fronts**

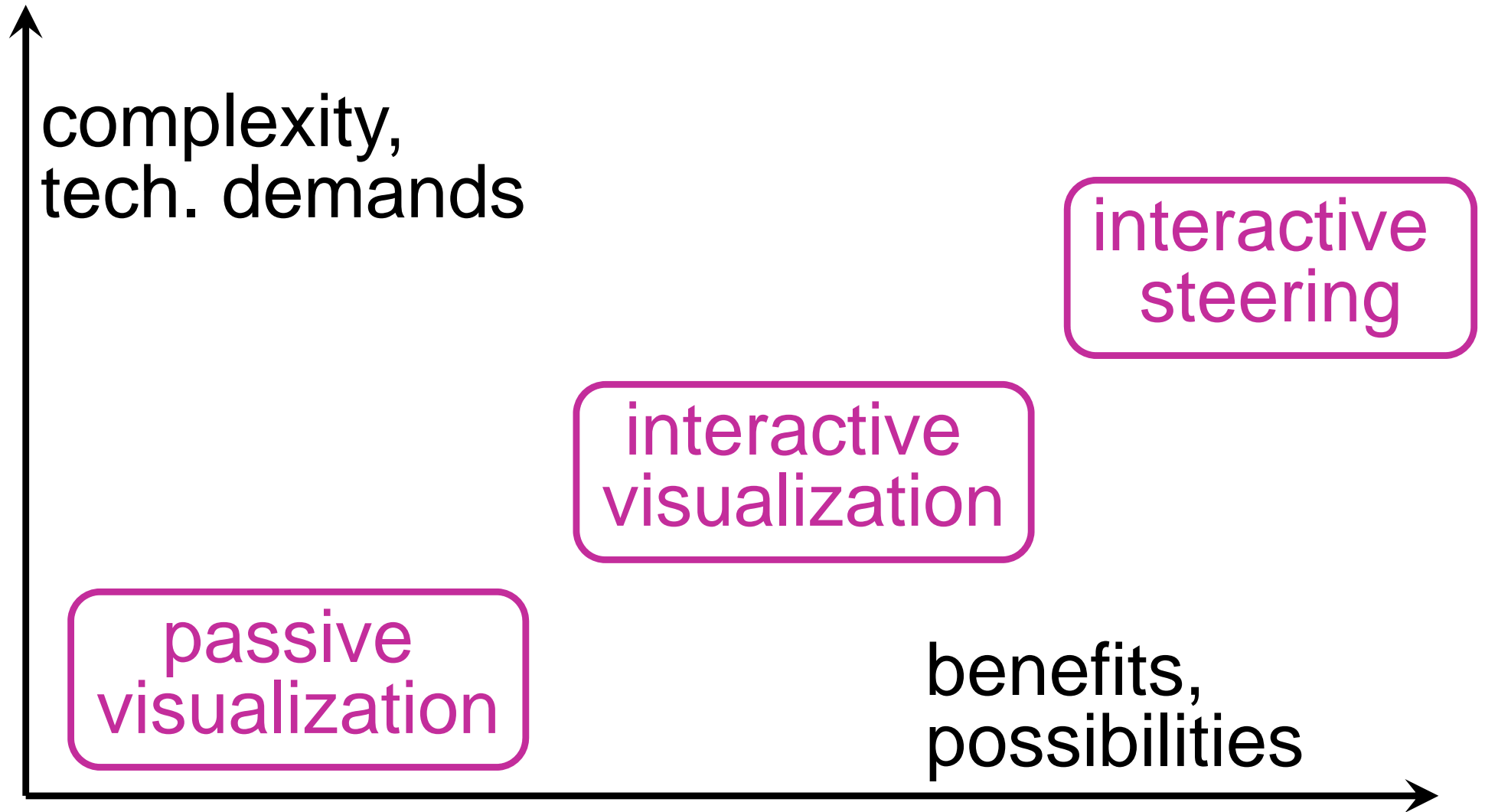


**map for pilots**



- Fixation of tufts, ribbons on ...
  - ◆ aircraft in wind tunnels
  - ◆ ship hull in fluid tanks
- Introduction of smoke particles (in wind tunnel)
- Introduction of dye (in fluids)





Acquisition

Data are given

Enhancement

Data are processed

Mapping

Data are mapped to,  
e.g., geometry

Rendering

Images generated



- Focus of visualization, everything is centered around the data
- Driving factor (besides user) in choice and attribution of the visualization technique
- Important questions
  - ◆ In what domain are the data given?  
(**data space**)
  - ◆ What is the type of data?  
(**data characteristics**)
  - ◆ Which **representation** makes sense?



# Data Space vs. Data Characteristics

data characteristics

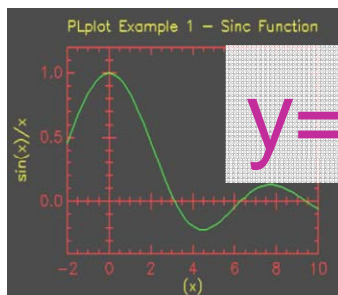
1D

2D

3D

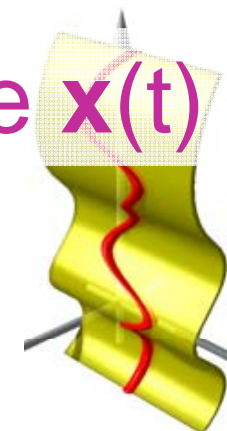
data space

1D

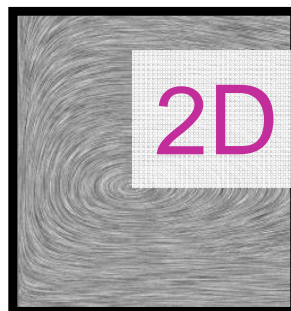


$y=f(x)$

spatial curve  $x(t)$



2D



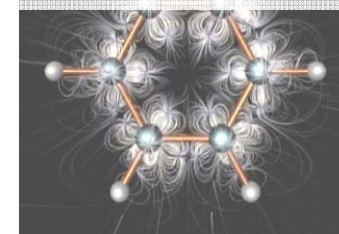
2D flow  $v(x)$

3D

scalar field  $d(x)$



3D flow  $v(x)$



## ■ Important questions

- ◆ Which data organization is optimal?
- ◆ Where do the data come from?
- ◆ Is there a neighborhood relationship?
- ◆ How is the neighborhood information stored?
- ◆ How is navigation within the data possible?
- ◆ Calculations with the data possible ?
- ◆ Are the data structured?



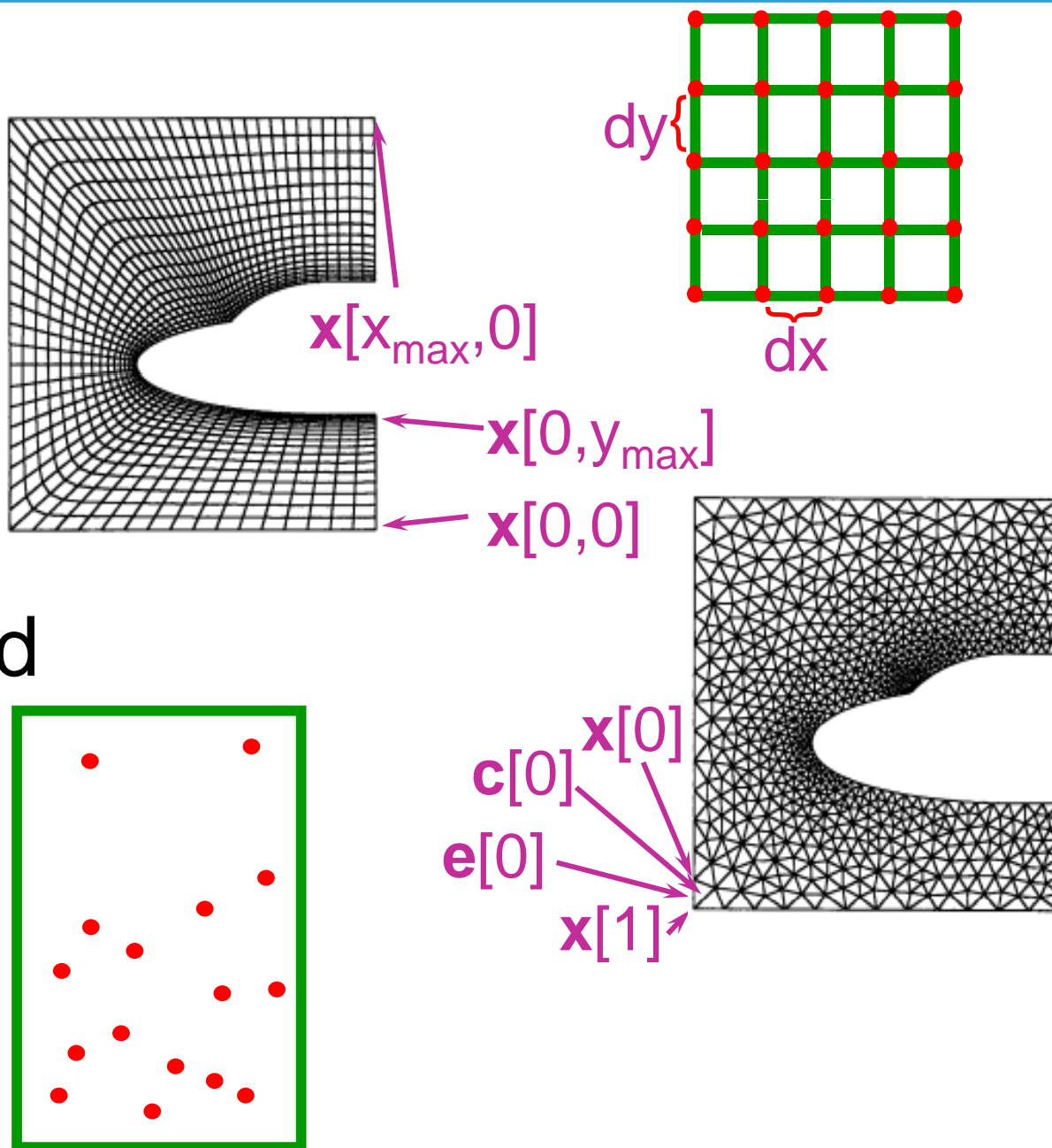


- Cartesian grid

- Curvilinear grid

- Unstructured grid

- Scattered data



structured  
grids

ortho-  
gonal  
grids

equi-  
dist.  
grids

cartesian  
grids ( $dx=dy$ )

regular  
grids ( $dx \neq dy$ )

rectilinear grids

curvi-linear grids

block-structured grids

unstructured grids

hybrid grids

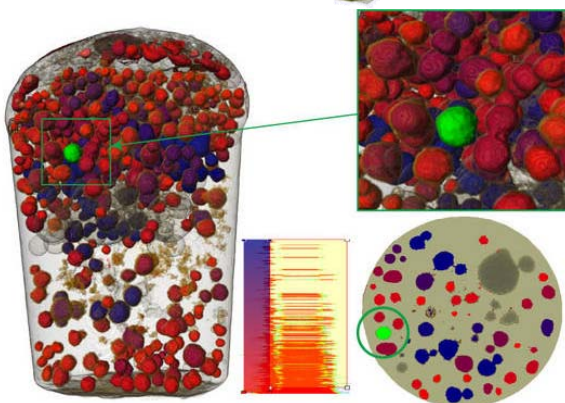
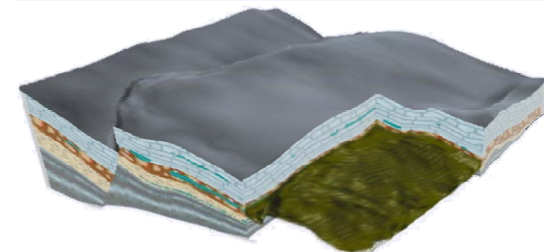
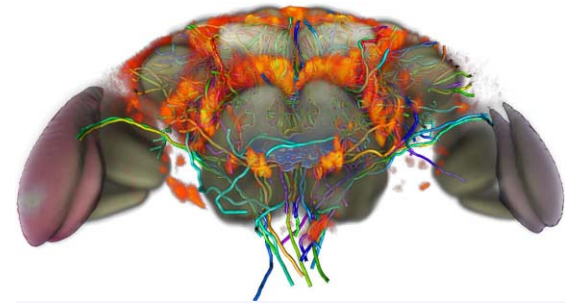
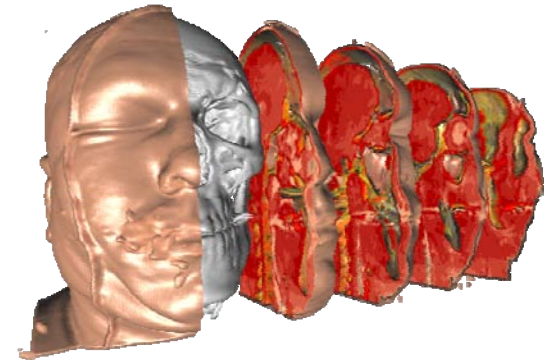
miscell.



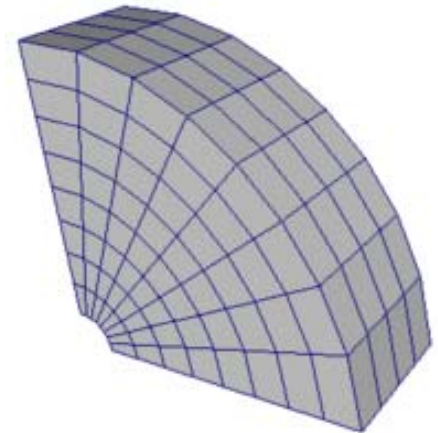
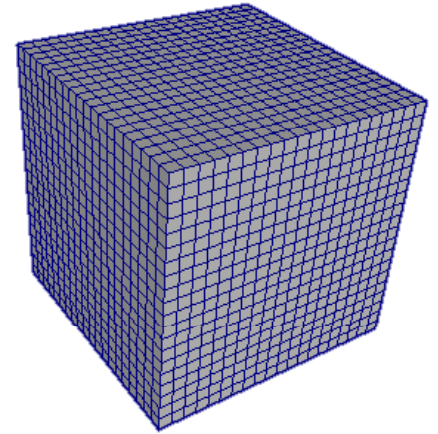
- VolVis = visualization of volume data
  - ◆ Mapping 3D→2D
- Volume data
  - ◆ 3D×1D data
  - ◆ Scalar data, 3D data space, space filling
- User goals
  - ◆ Gain insight in 3D data
  - ◆ Structures of special interest + context



- **Medicine**
  - ◆ CT, MRI, PET, Ultrasound
- **Biology**
  - ◆ Confocal microscopy, histological cuts
- **Geology**
  - ◆ Seismic surveys
- **Material testing**
  - ◆ Industrial CT



- Cartesian/regular grid
  - ◆ Most common, e.g., CT/MRI scans
- Curvilinear/unstructured grid
  - ◆ Less frequently, e.g., simulation data



sampled data  
(measurement)

analytical data  
(modelling)



voxel space  
(discrete)

iso-surfacing

voxelization

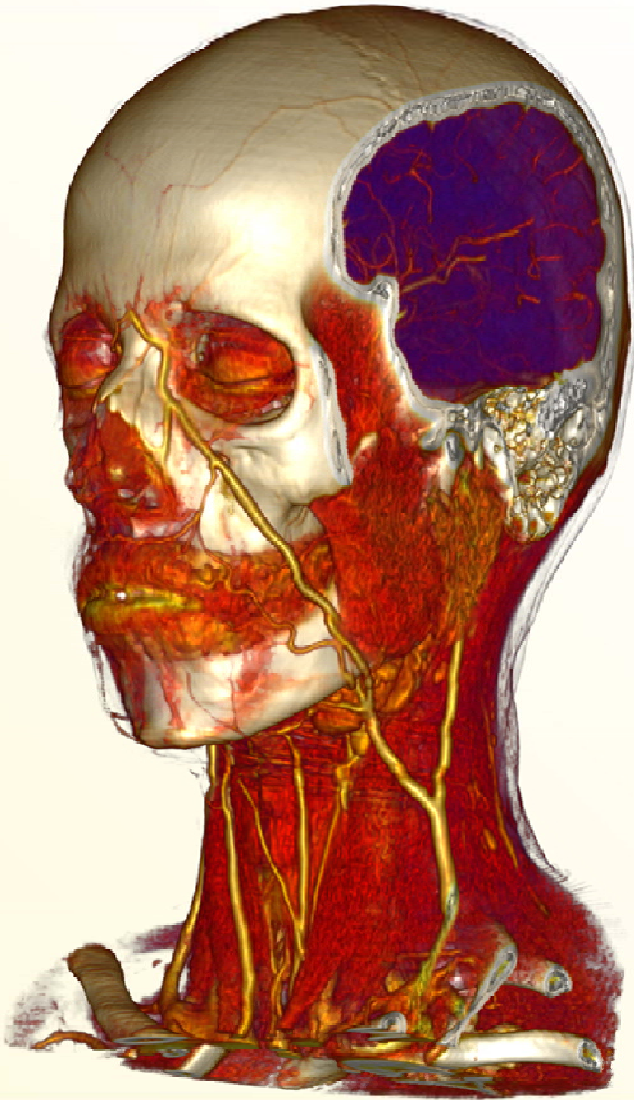
geometric surfaces  
(analytic)

(direct) volume  
rendering

surface  
rendering

pixel space  
(discrete)





- Deals with the visual representation of 3D functions
- Frequently, but not exclusively, functions are scalar-valued
- Often acquired using sampling (e.g., medical domain)



- Initially volumes were visualized using two-dimensional cuts
- Extraction of surface geometry for isosurfaces in the volume (e.g. Marching Cubes [Lorenson and Cline 1987])
- Volume rendering introduced almost simultaneously by [Levoy 1988] and [Drebin et al. 1988]

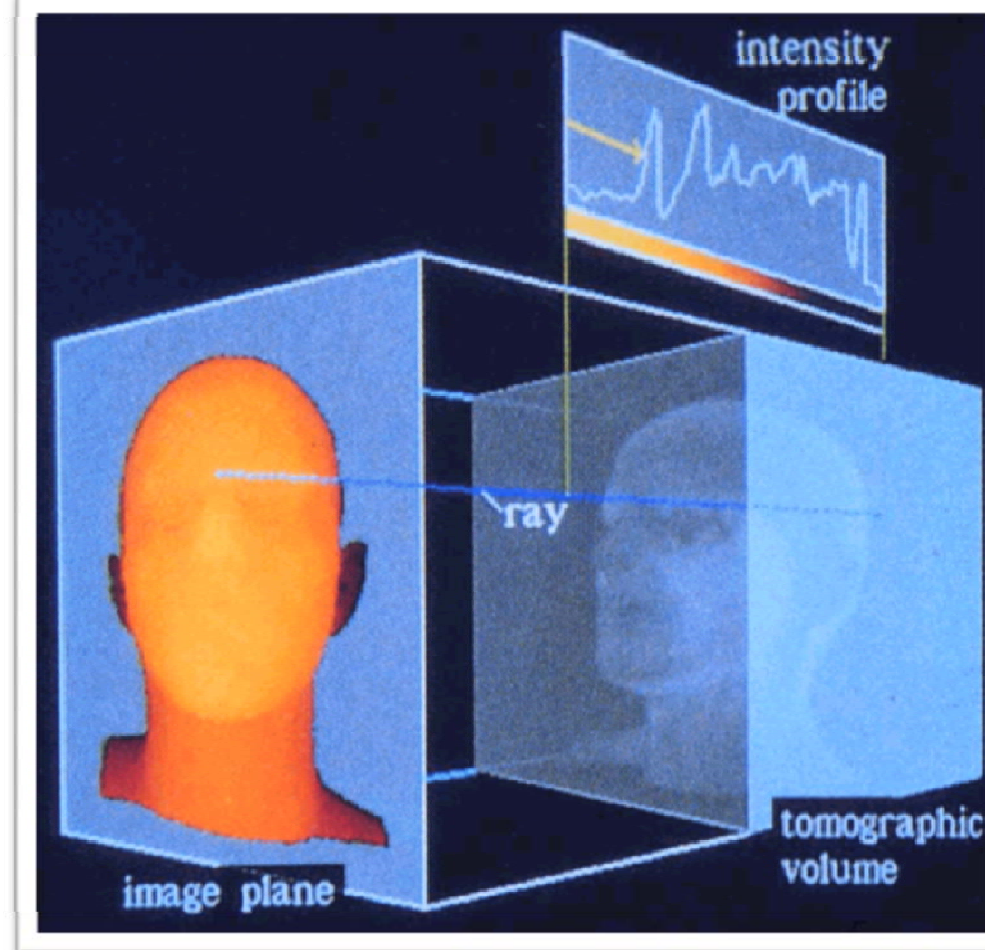




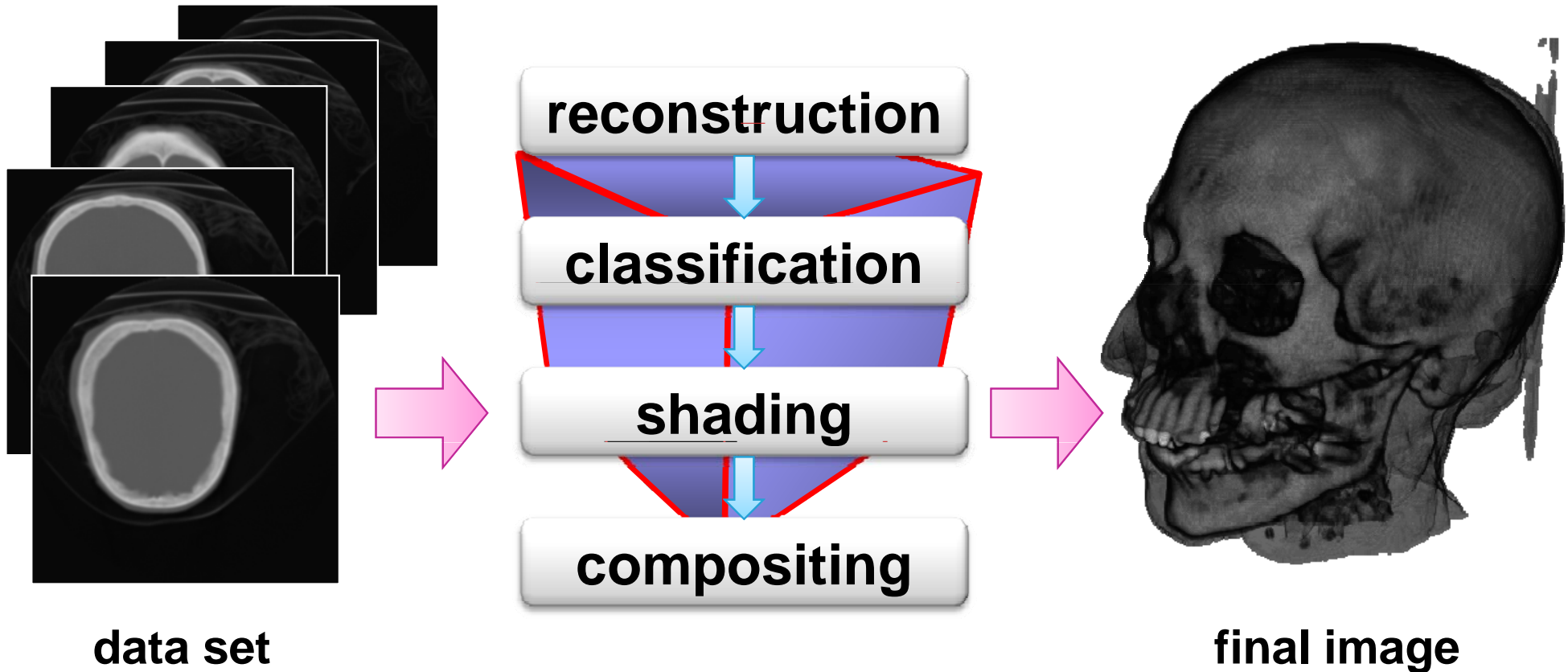
- Surface rendering
  - ◆ **Indirect** volume visualization
  - ◆ Intermediate representation: iso-surface
  - ◆ Pros: Less memory, fast rendering
- Volume rendering
  - ◆ **Direct** volume visualization
  - ◆ Usage of transfer functions
  - ◆ Pros: illustrate the interior, semi-transparency



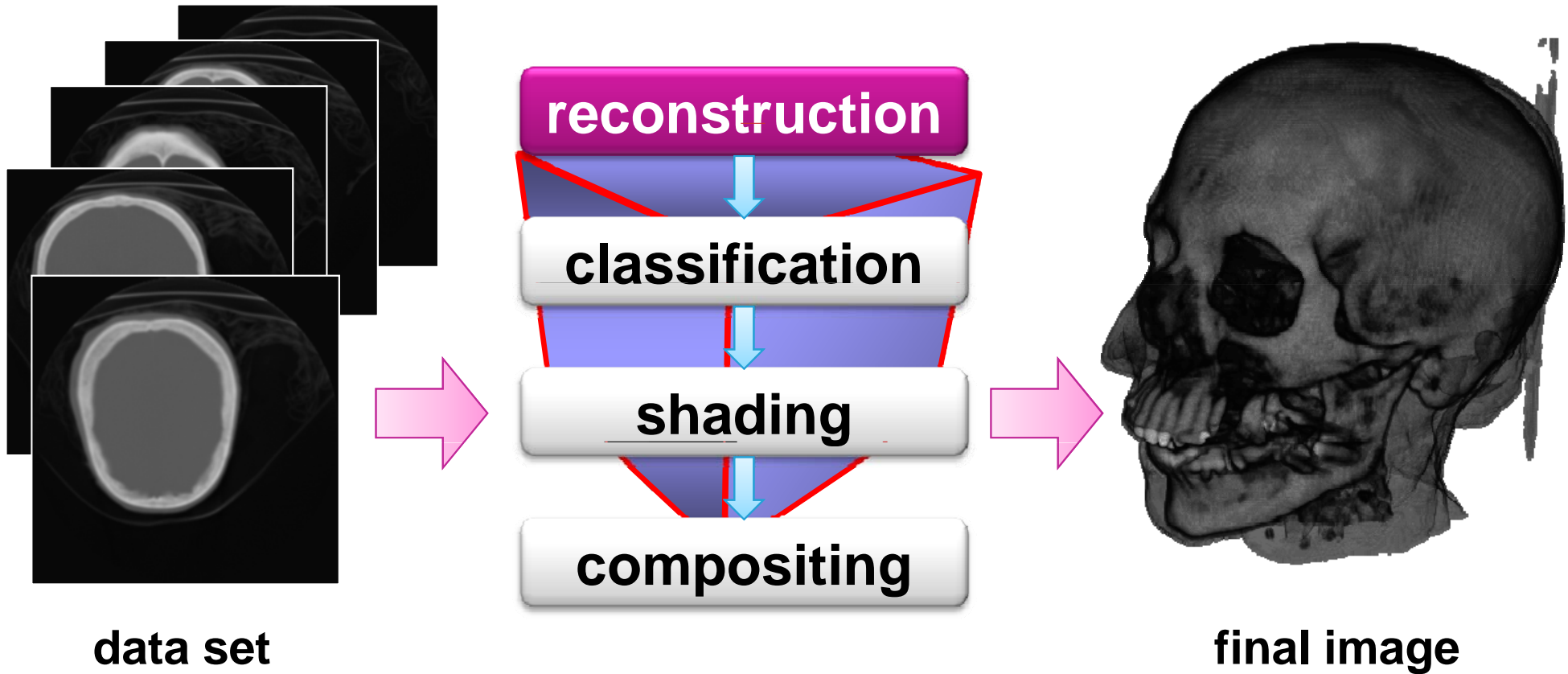
- **Volume:** 1D value defined in 3D  
 $f(\mathbf{x}) \in \mathbb{R}^1, \mathbf{x} \in \mathbb{R}^3$
- **Ray:** Half-line  
 $\mathbf{r}(t) \in \mathbb{R}^3, t \in \mathbb{R}^1 > 0$
- **Intensity profile:** values along a ray  
 $f(\mathbf{r}(t)) \in \mathbb{R}^1, t \in \mathbb{R}^1 > 0$
- **Image plane:** starting points of rays



## volume rendering pipeline



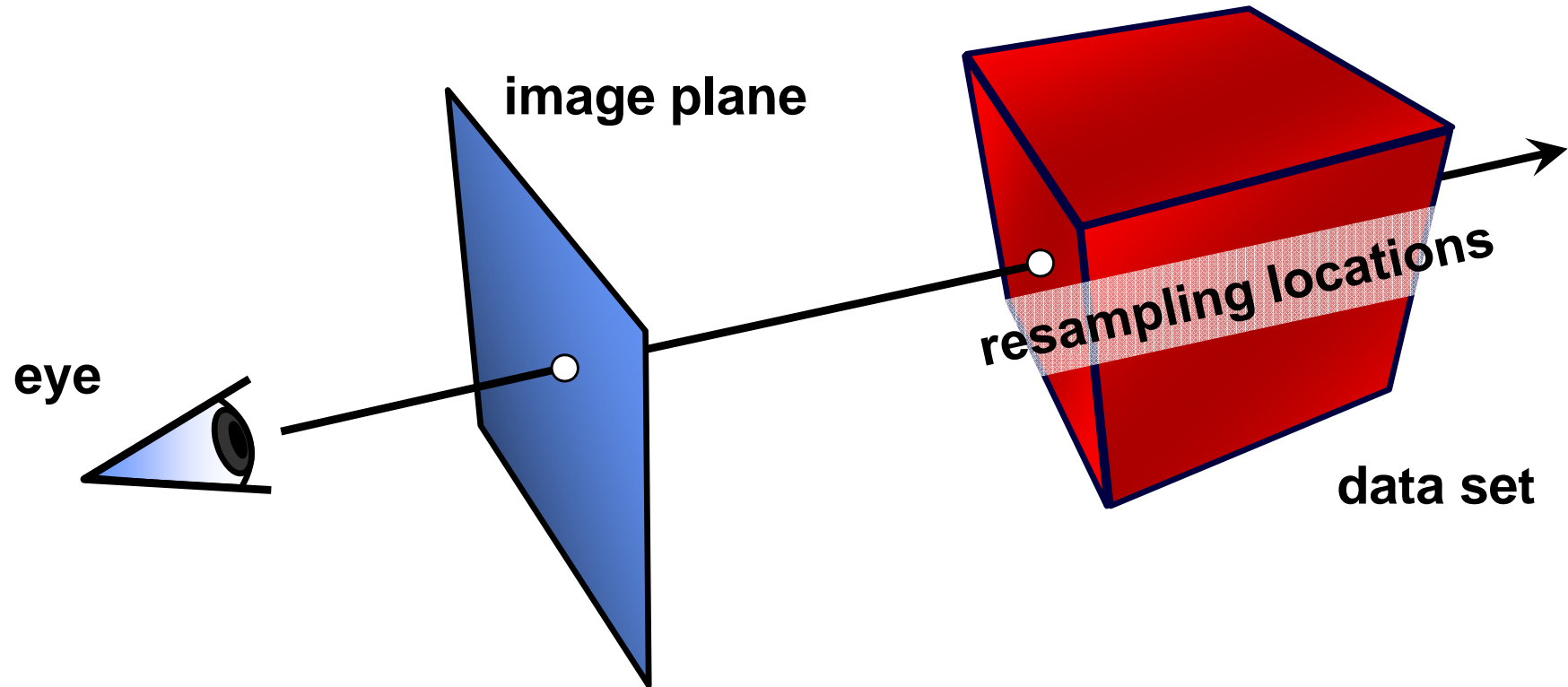
## volume rendering pipeline

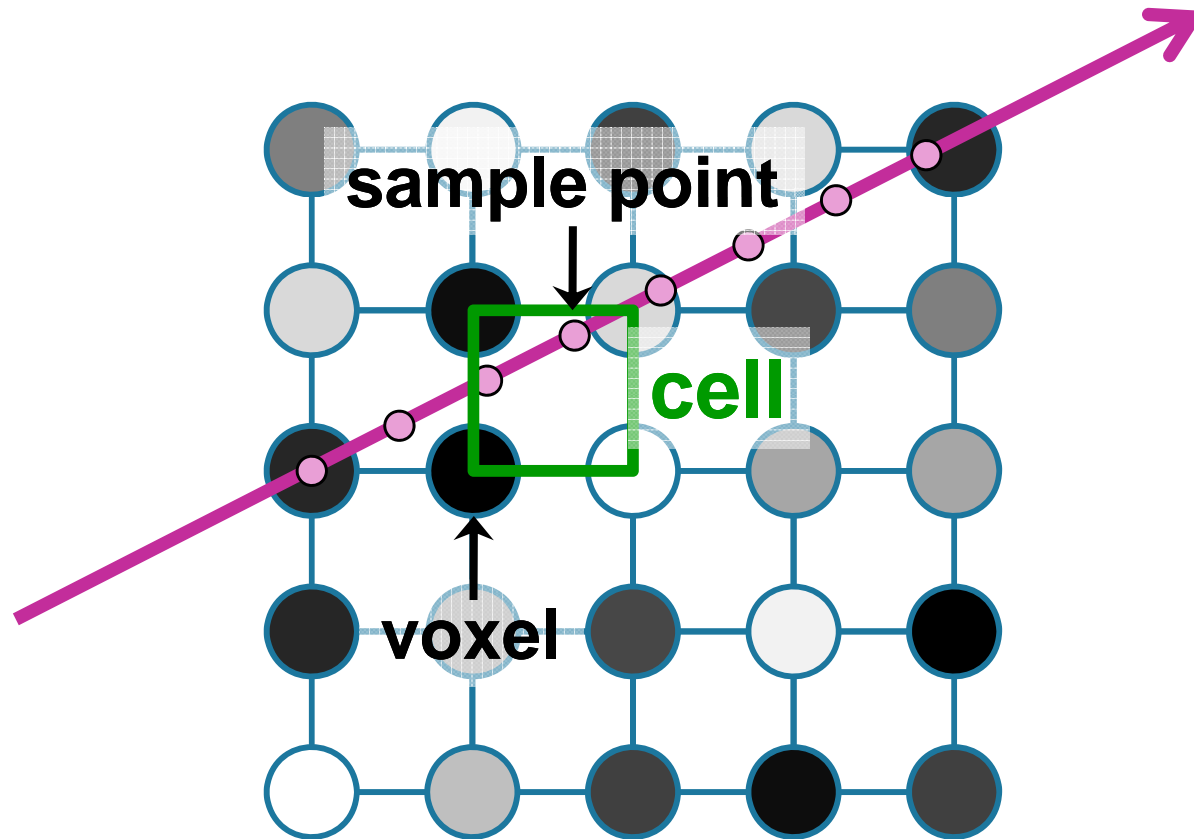


- Usually volume data sets are given as a grid of discrete samples
- For rendering purposes, we want to treat them as continuous three-dimensional functions
- We need to choose an appropriate reconstruction filter
- Requirements: high-quality reconstruction, but small performance overhead

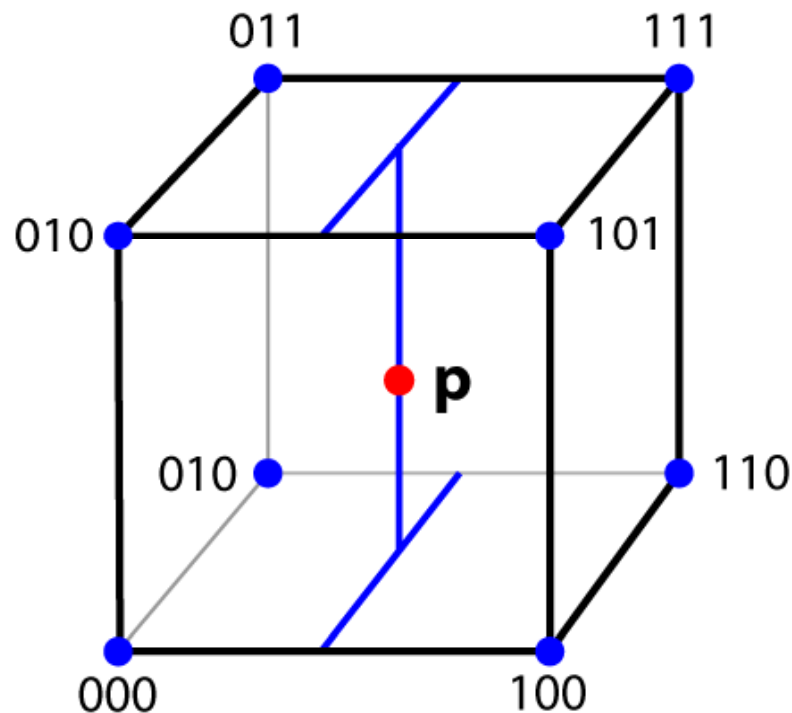


# Reconstruction (2)





- Simple extension of linear interpolation to three dimensions
- Advantage: current GPUs automatically do trilinear interpolation of 3D textures



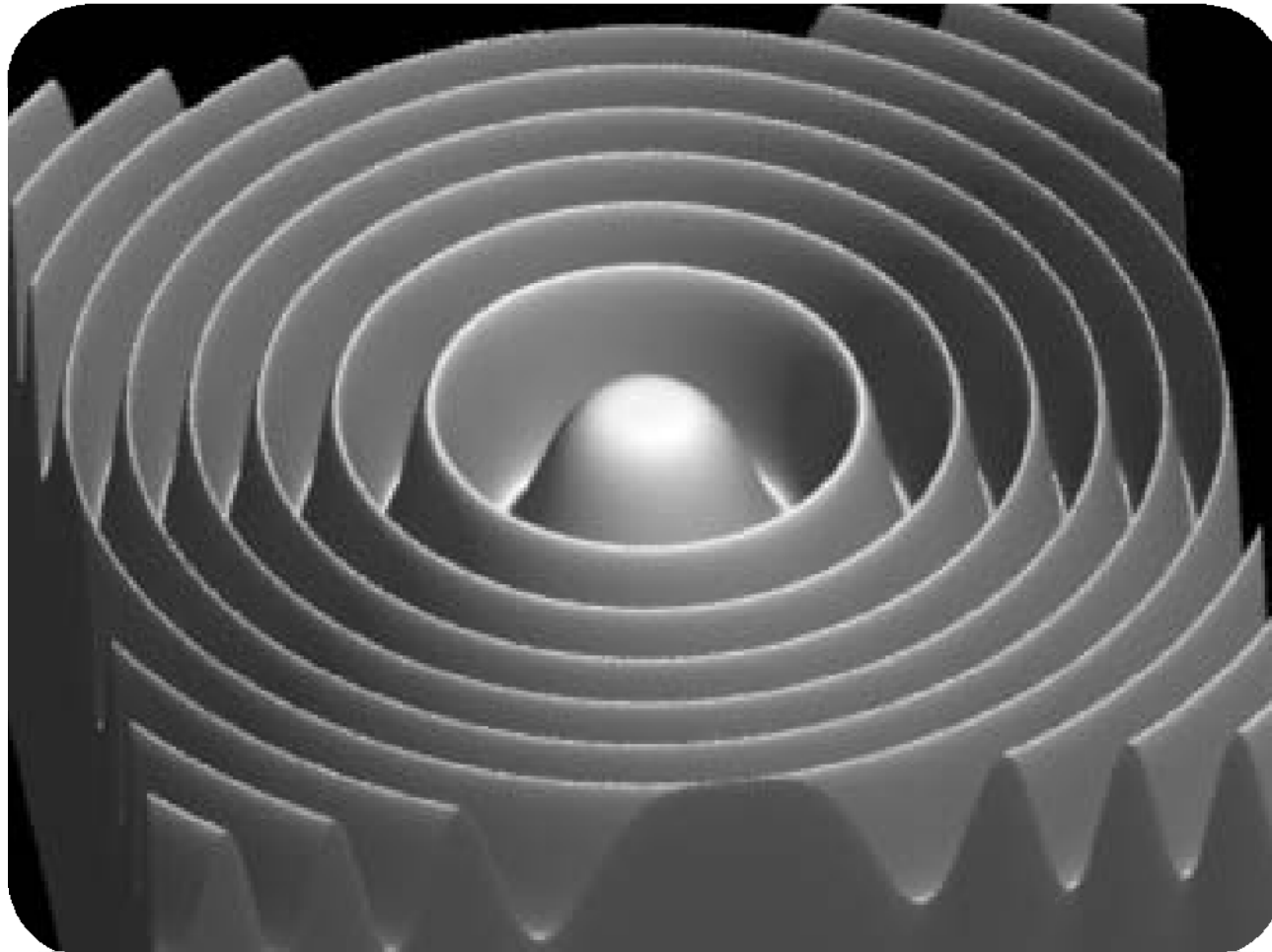
$$\begin{aligned}v_p = & v_{000}(1 - x_p)(1 - y_p)(1 - z_p) + \\ & v_{100}x_p(1 - y_p)(1 - z_p) + \\ & v_{010}(1 - x_p)y_p(1 - z_p) + \\ & v_{001}(1 - x_p)(1 - y_p)z_p + \\ & v_{011}(1 - x_p)y_pz_p + \\ & v_{101}x_p(1 - y_p)z_p + \\ & v_{110}x_py_p(1 - z_p) + \\ & v_{111}x_py_pz_p\end{aligned}$$



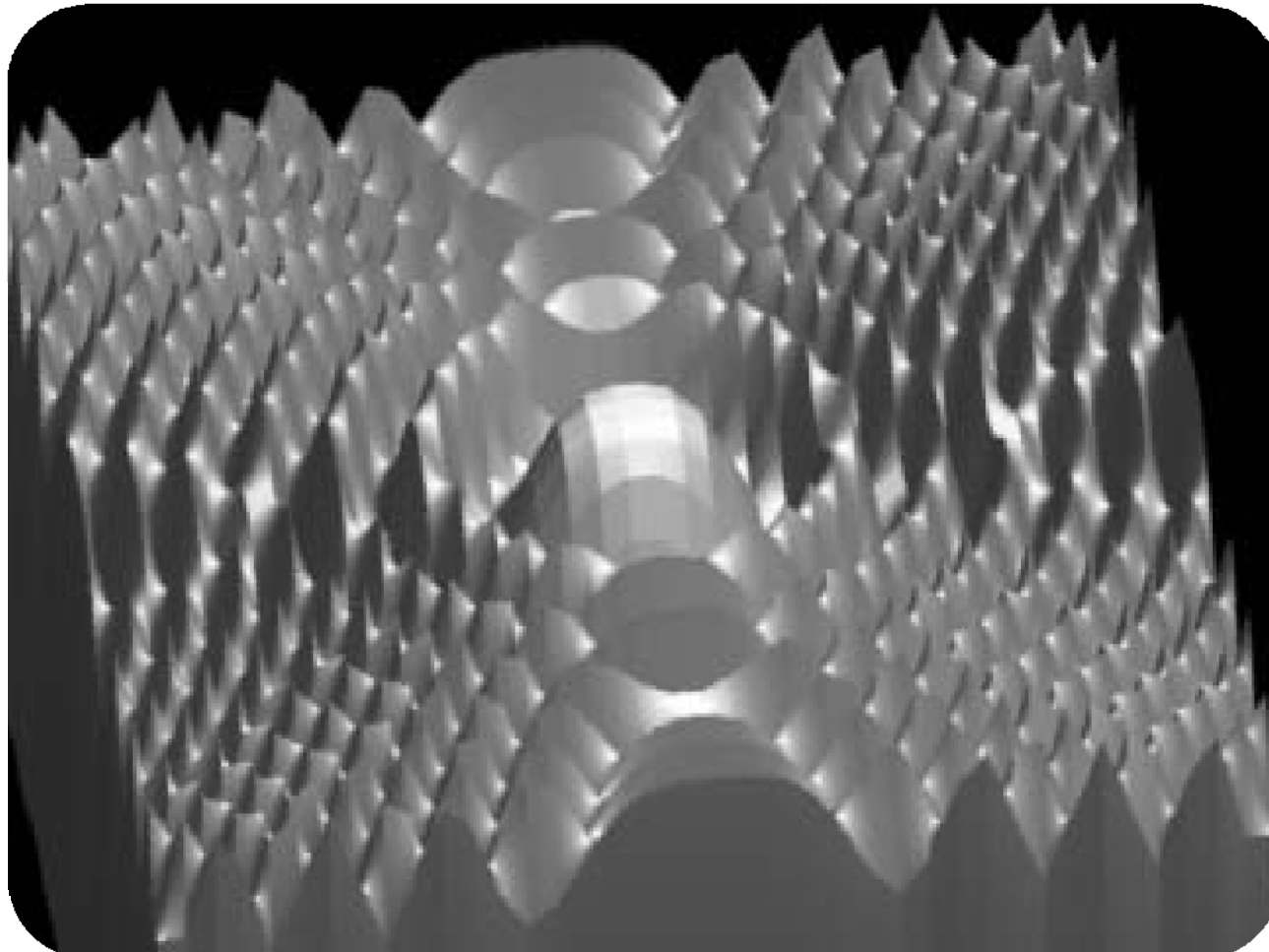
- If very high quality is required, more complex reconstruction filters may be required
- Marschner-Lobb function is a common test signal to evaluate the quality of reconstruction filters [Marschner and Lobb 1994]
- The signal has a high amount of its energy near its Nyquist frequency
- Makes it a very demanding test for accurate reconstruction



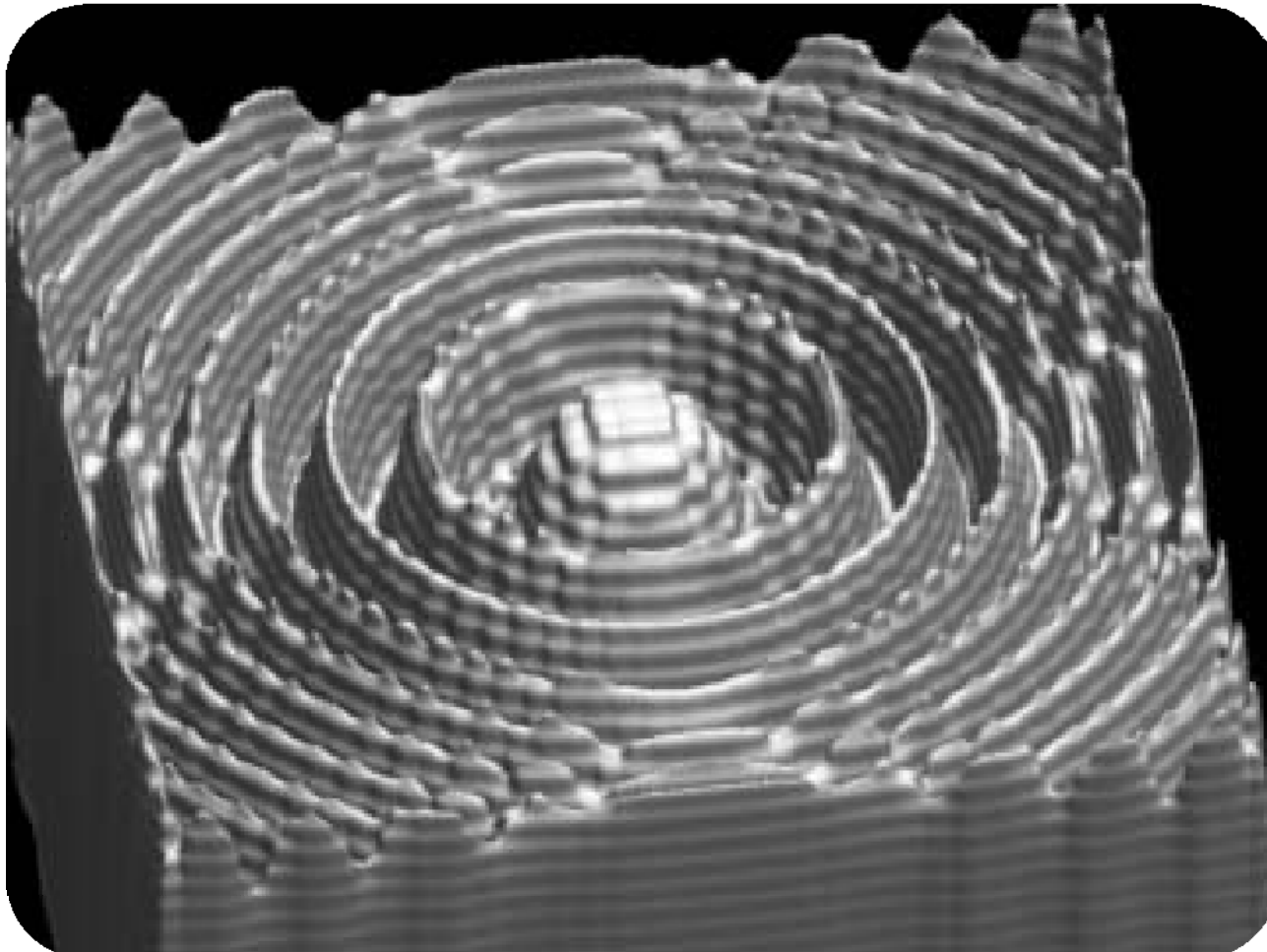
- Marschner-Lobb test signal (analytically evaluated)



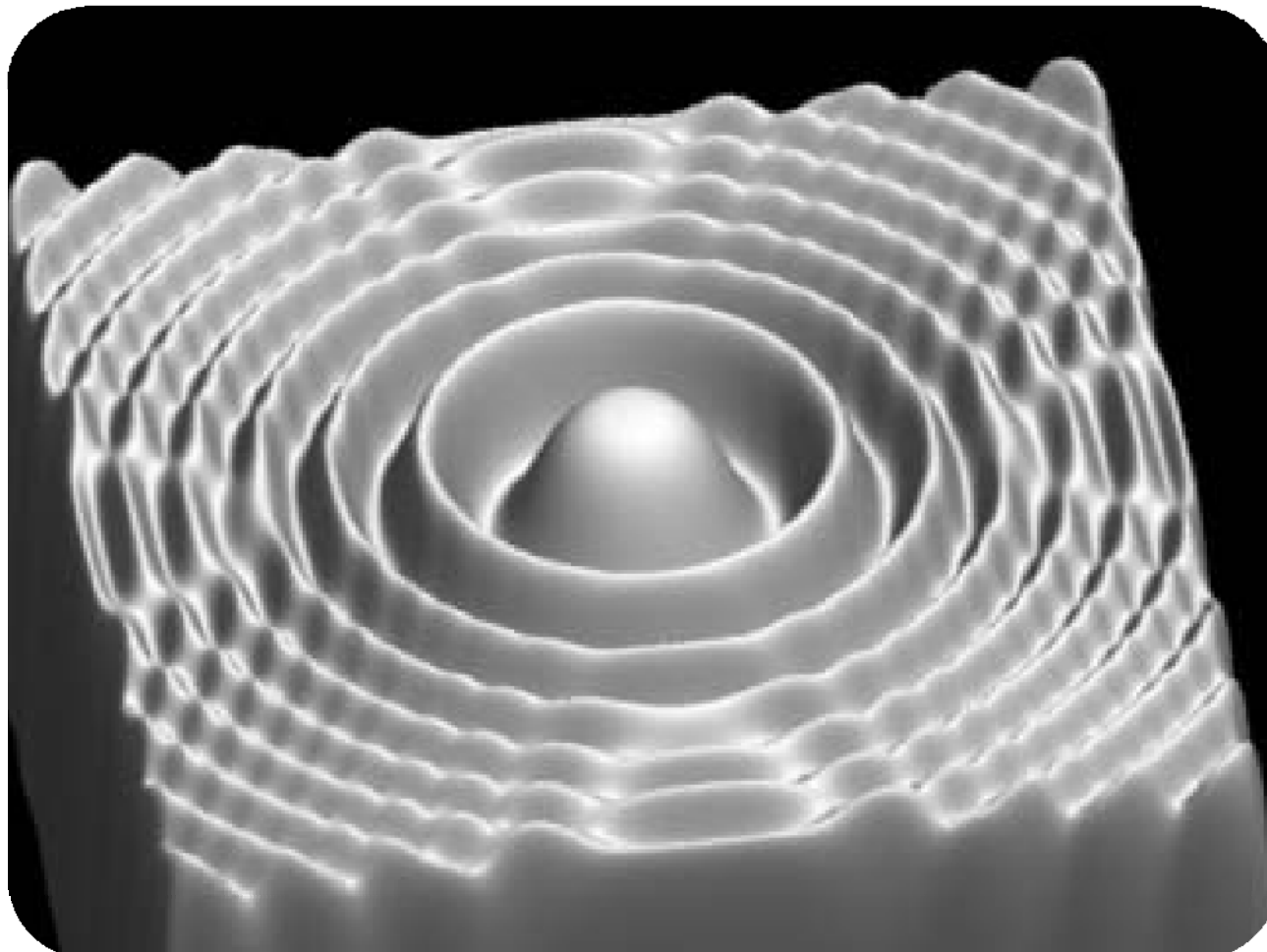
- **Trilinear** reconstruction of Marschner-Lobb test signal



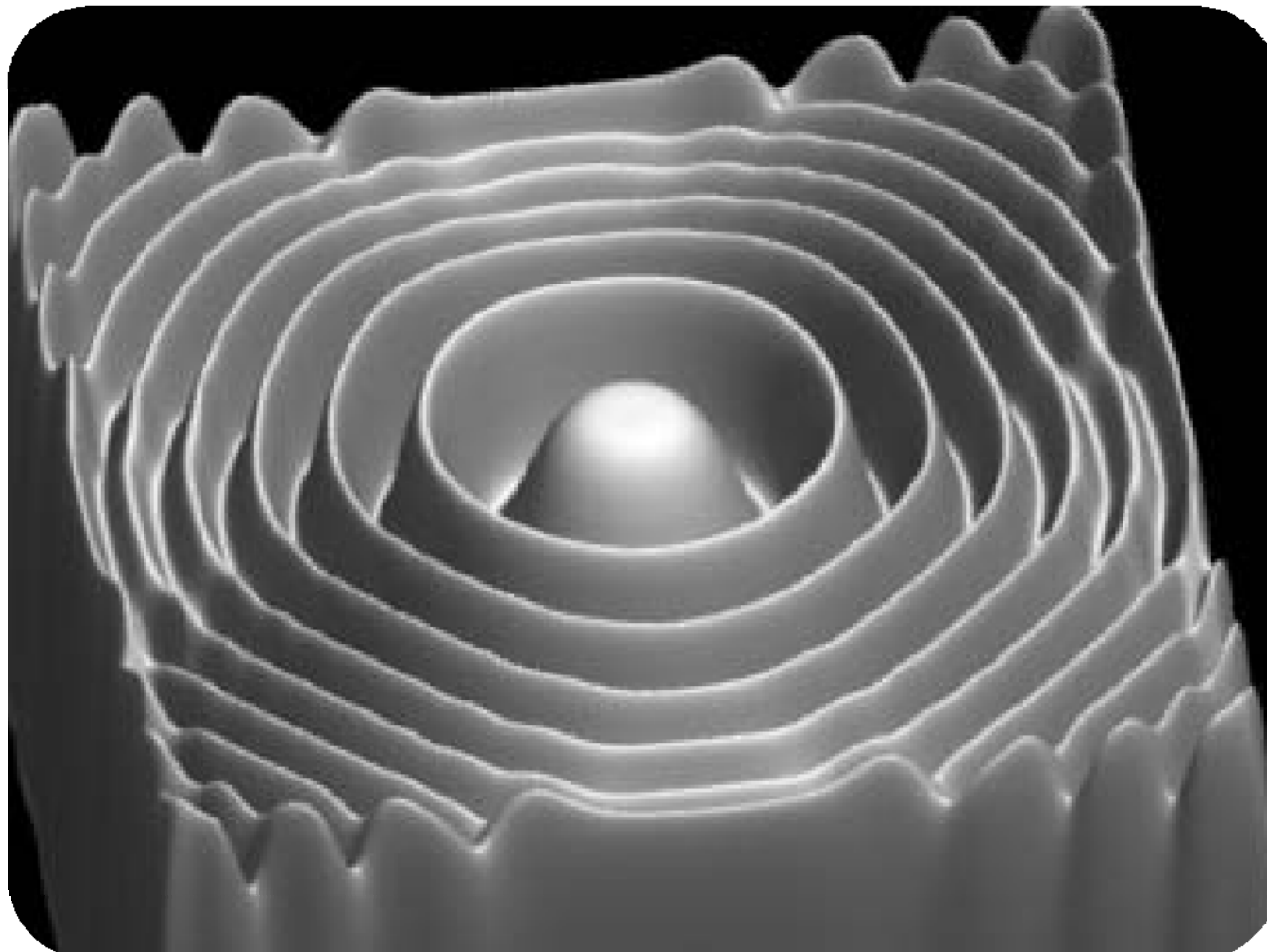
- **Cubic** reconstruction of Marschner-Lobb test signal



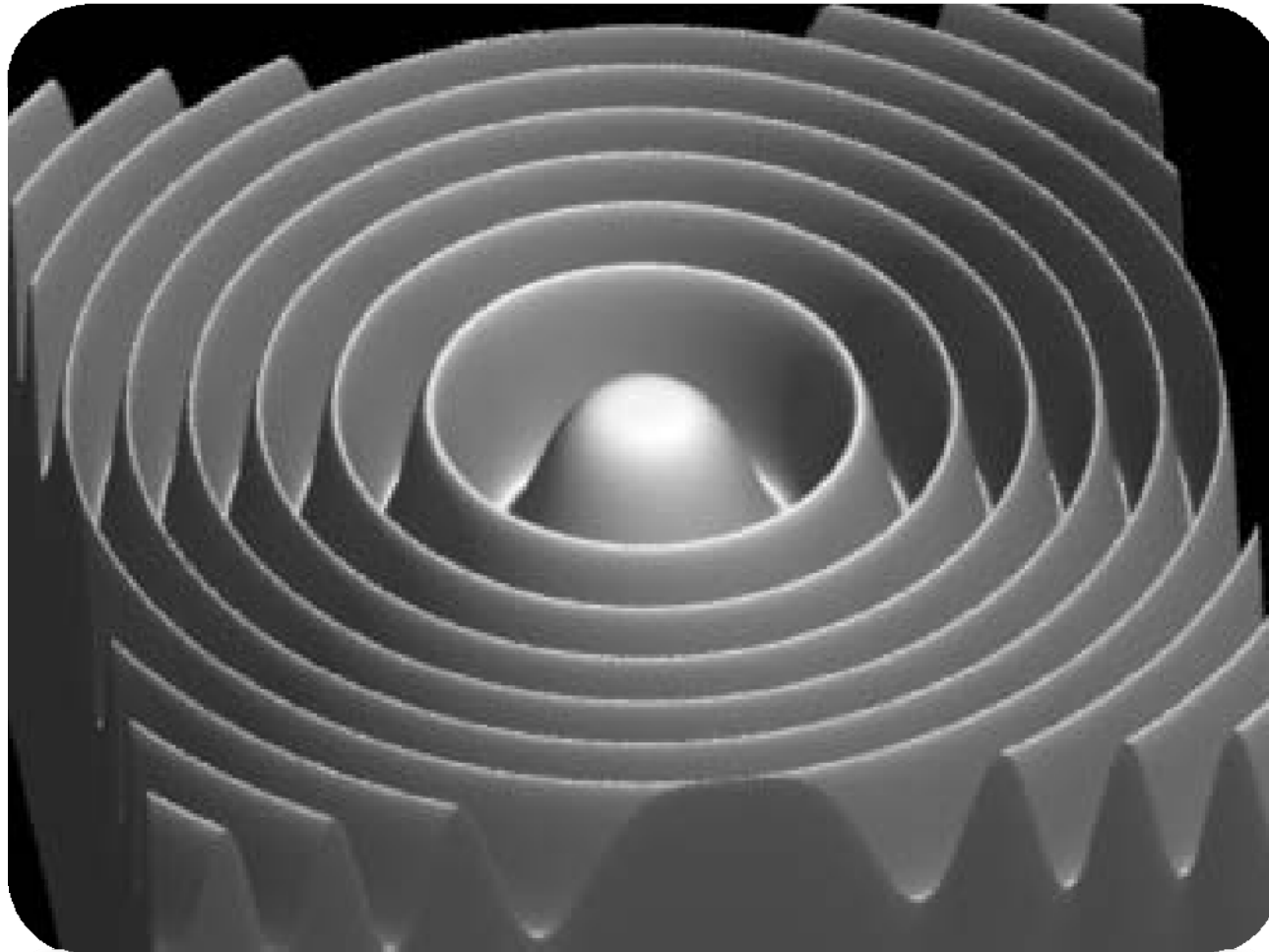
- **B-Spline** reconstruction of Marschner-Lobb test signal



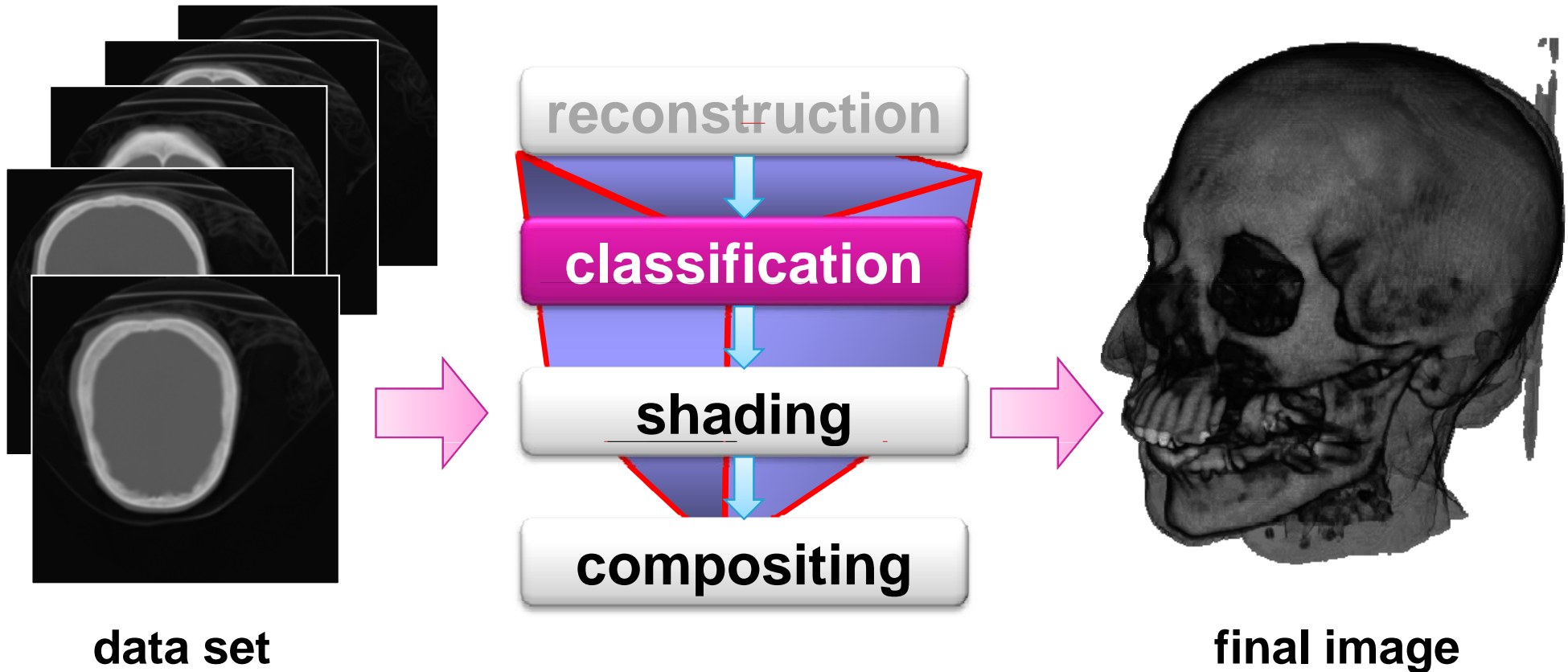
- **Windowed sinc** reconstruction of Marschner-Lobb test signal



- Marschner-Lobb test signal (analytically evaluated)



## volume rendering pipeline

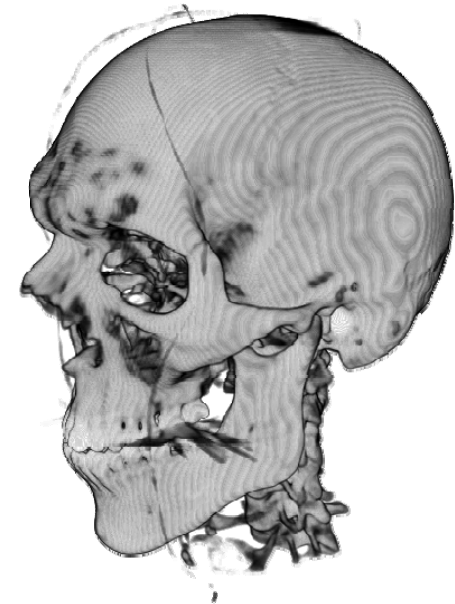
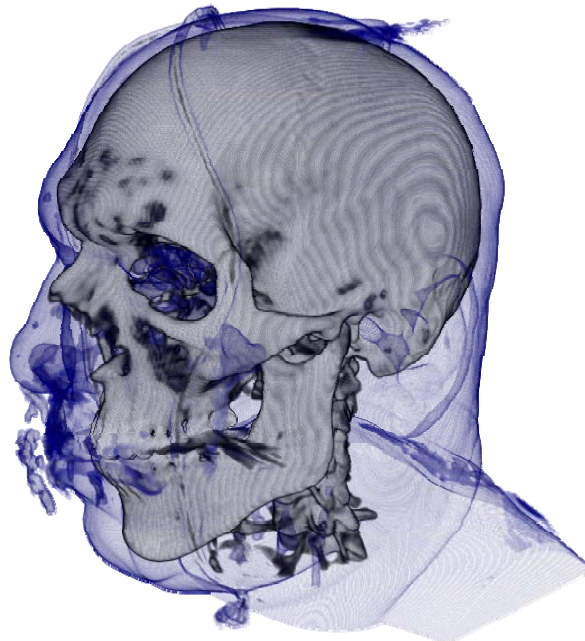
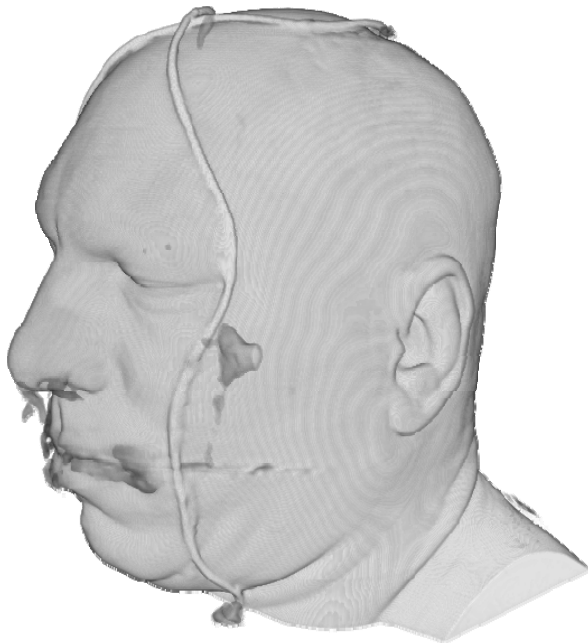




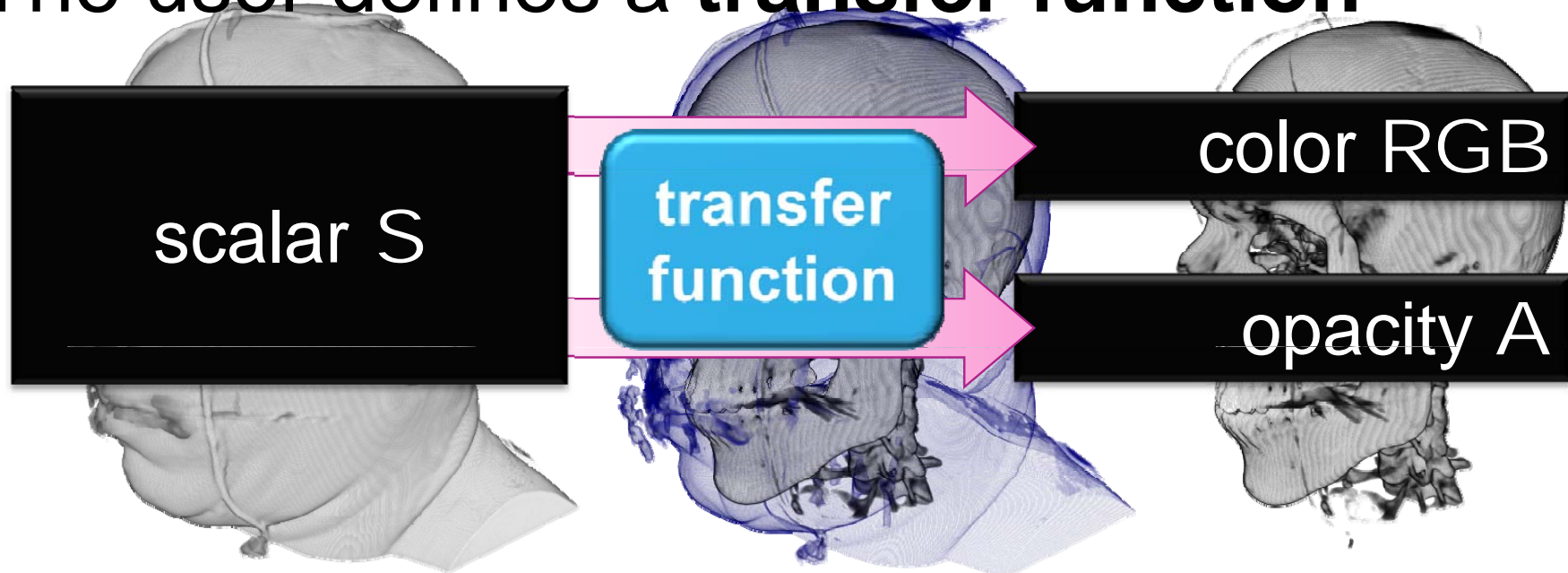
- Projecting a 3D data set onto a 2D image is problematic
- Not all information contained in the volume is relevant to the user
- Classification allows the user to extract the important parts of the data

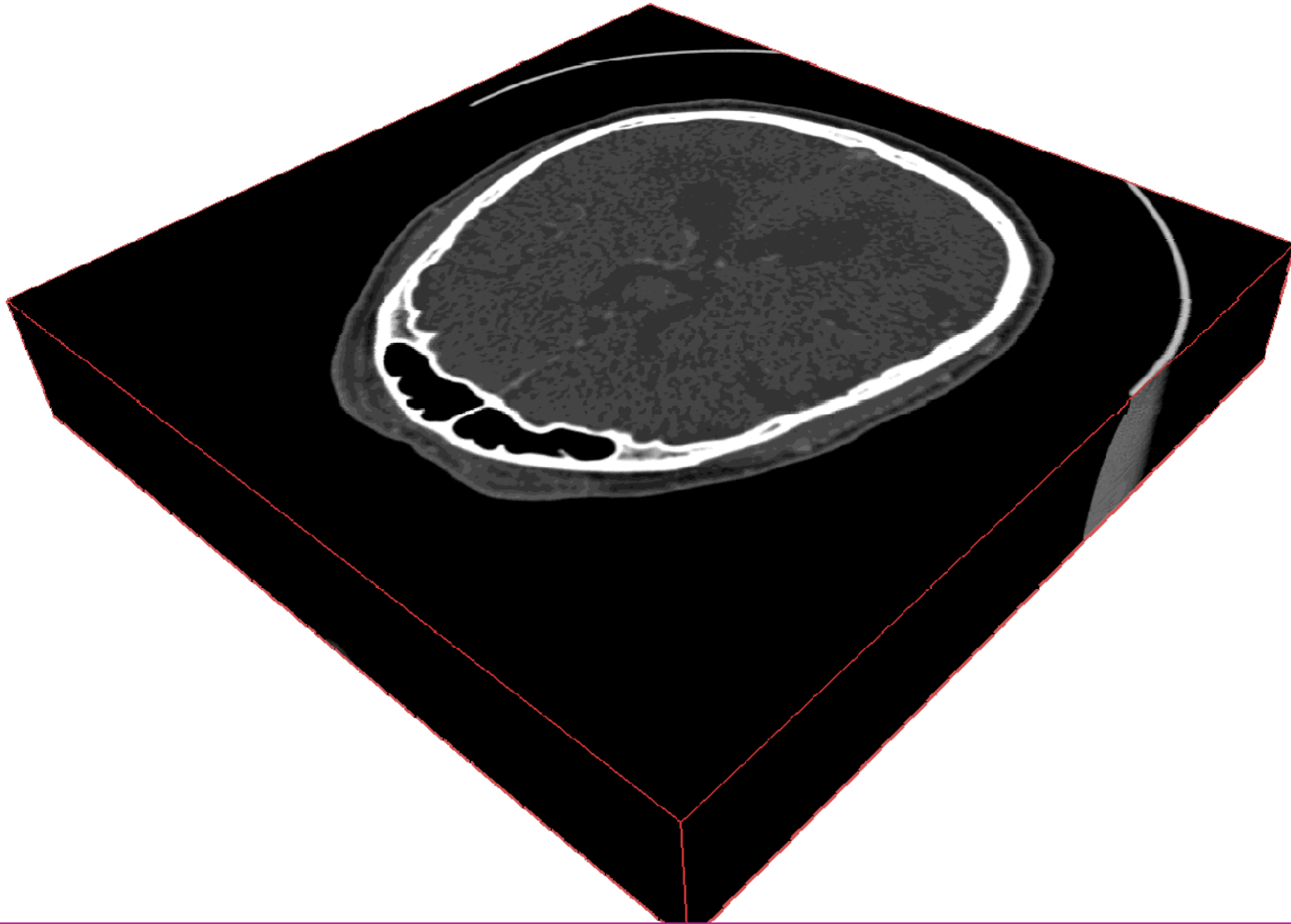


- During Classification the user defines the appearance of the data
  - ◆ Which parts are transparent?
  - ◆ Which parts have which color?



- During Classification the user defines the appearance of the data
  - ◆ Which parts are transparent?
  - ◆ Which parts have which color?
- The user defines a **transfer function**

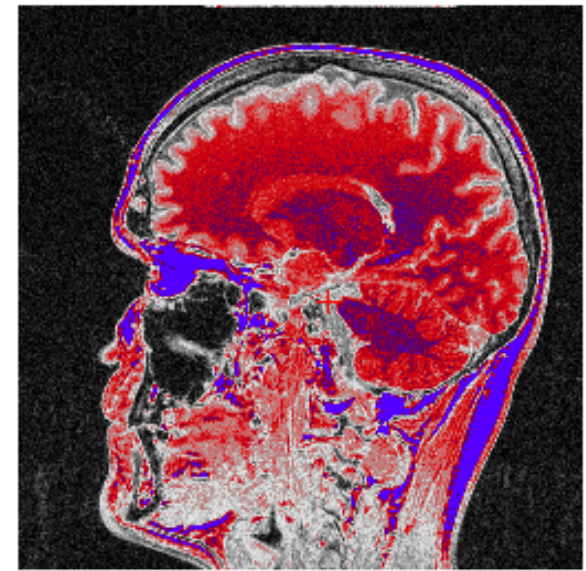
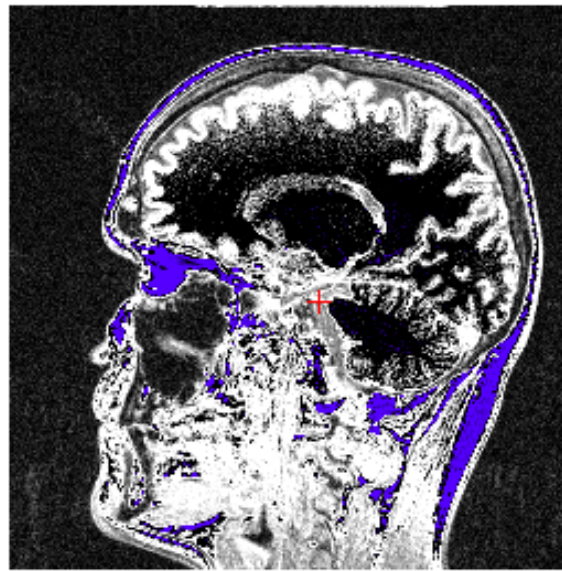
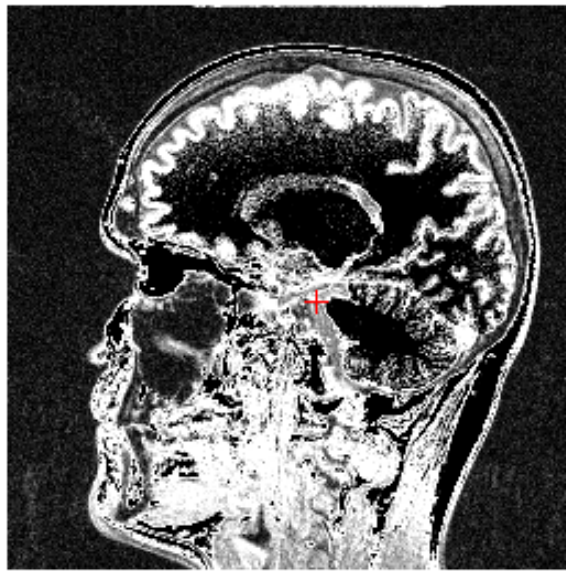
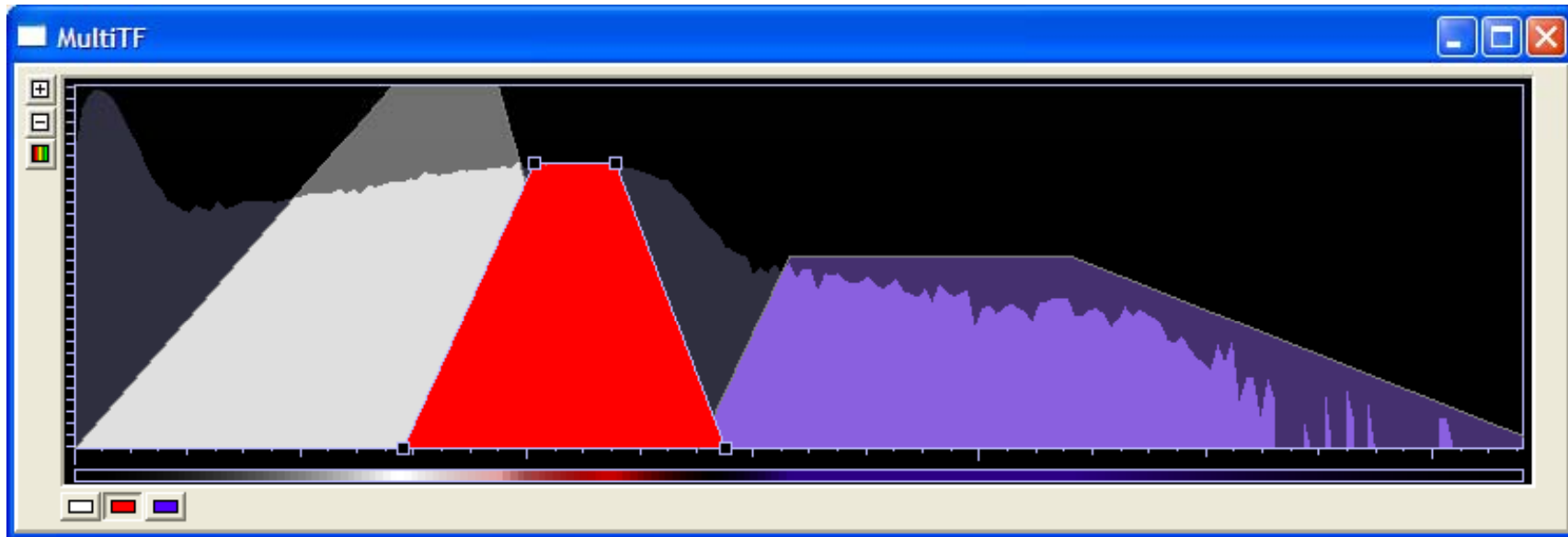




**real-time update of the transfer function important**



# Transfer Functions (2)

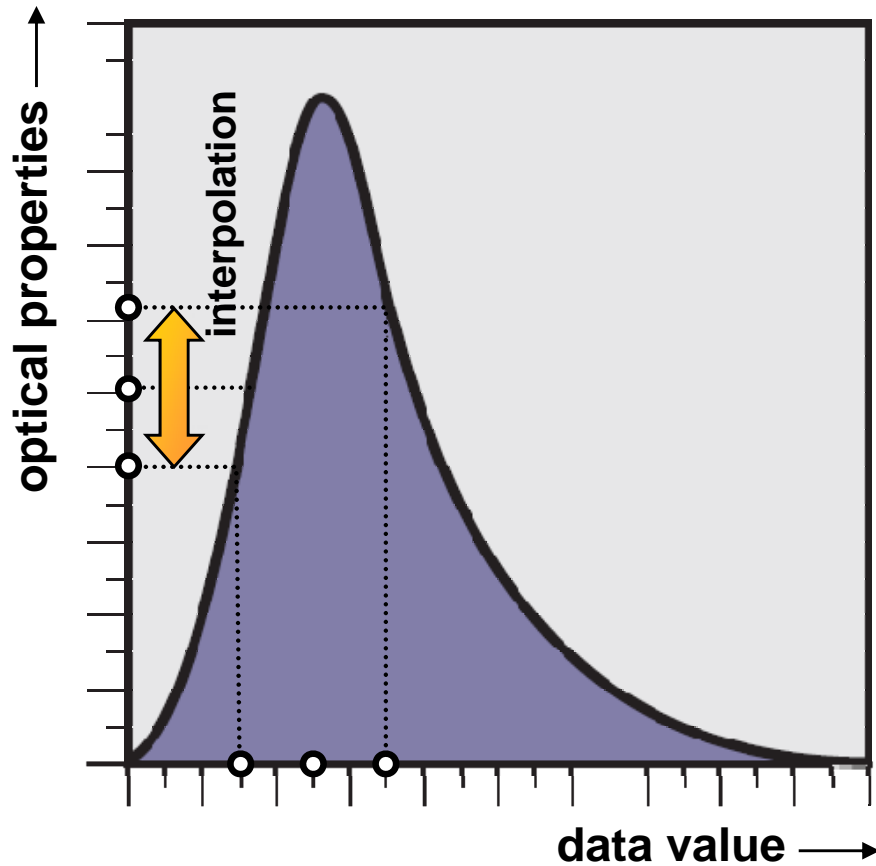


- Classification can occur before or after reconstruction
- **Pre-interpolative:** classify all data values and then interpolate between RGBA-tuples
- **Post-interpolative:** interpolate between scalar data values and then classify the result

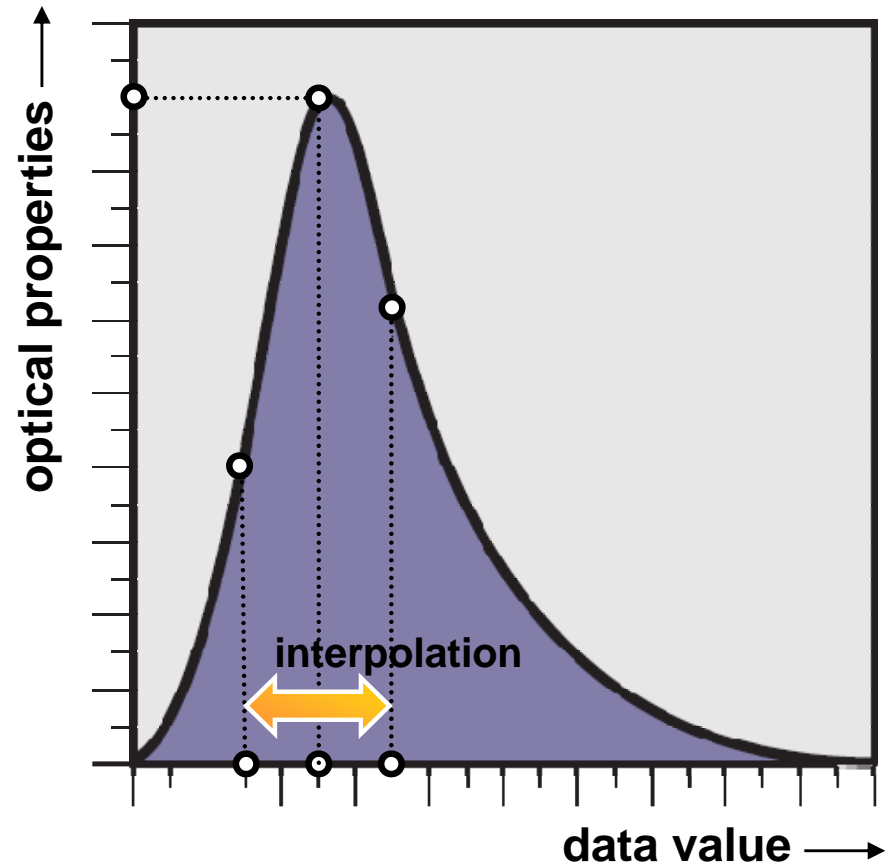


# Classification Order (2)

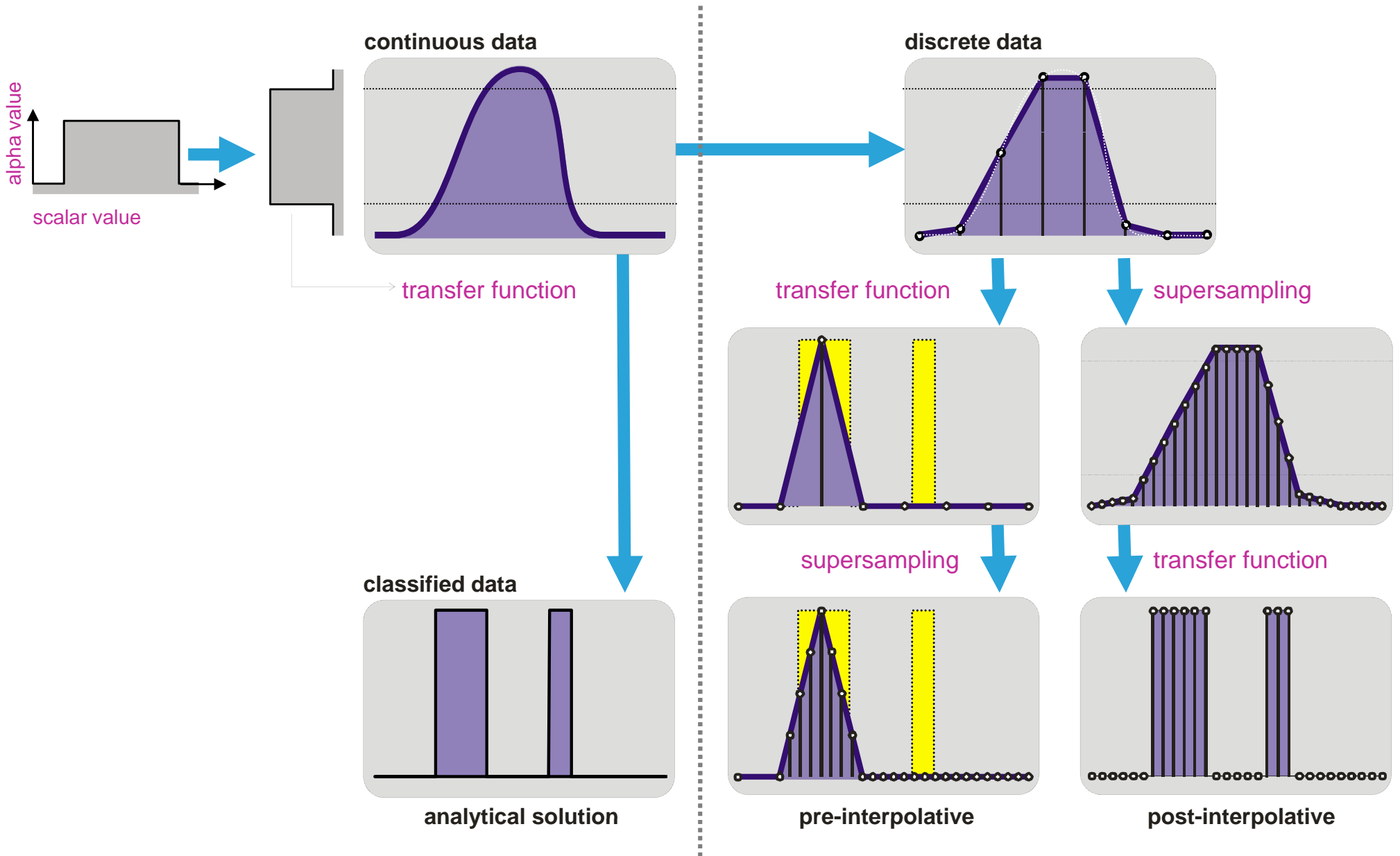
## PRE-INTERPOLATIVE



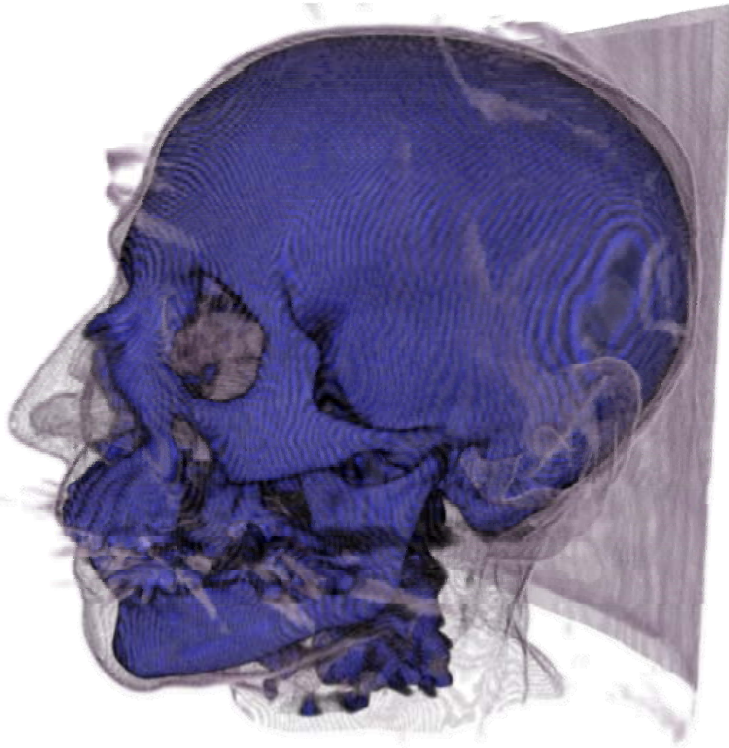
## POST-INTERPOLATIVE



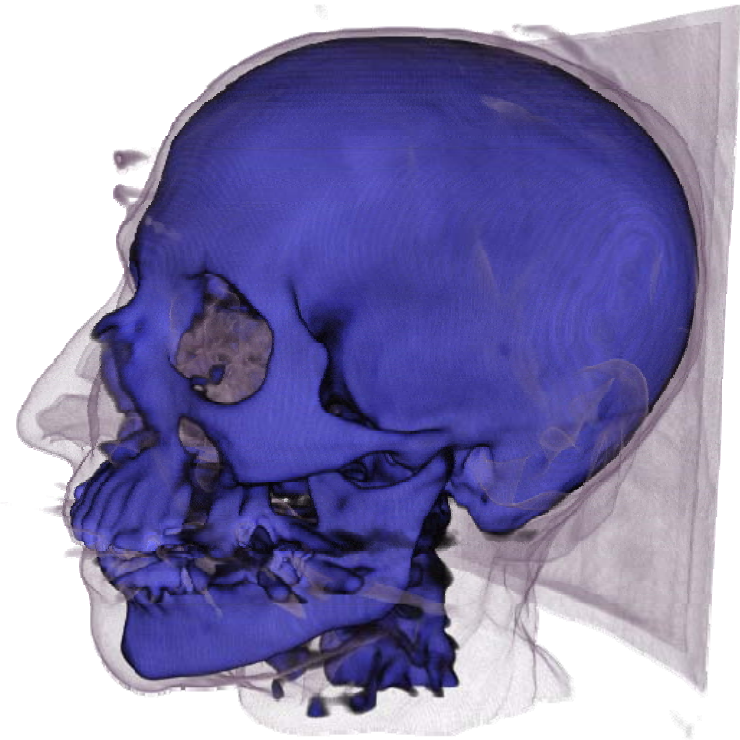
# Classification Order (3)







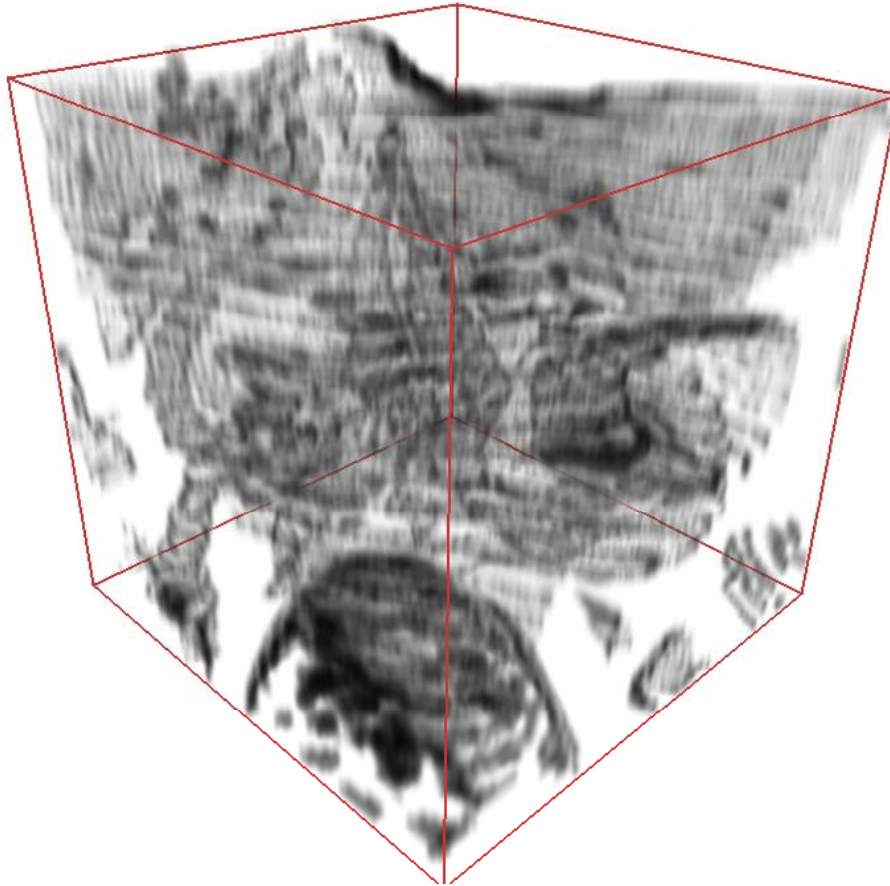
**pre-interpolative**



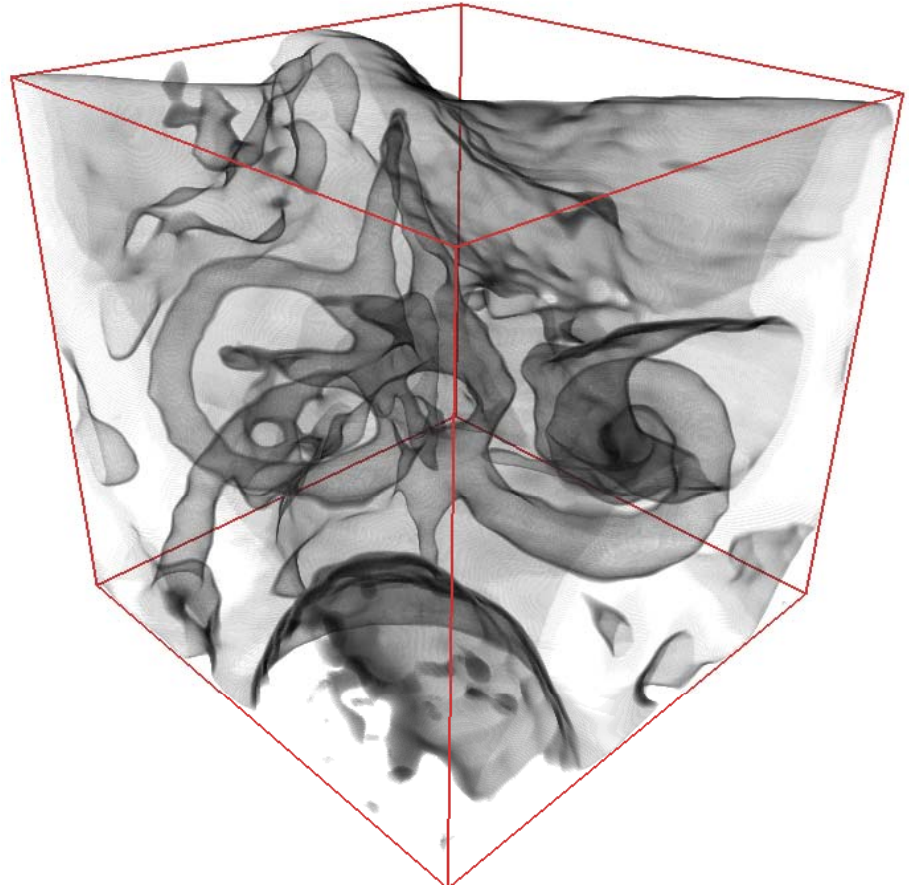
**post-interpolative**

same transfer function, resolution, and sampling rate





**pre-interpolative**

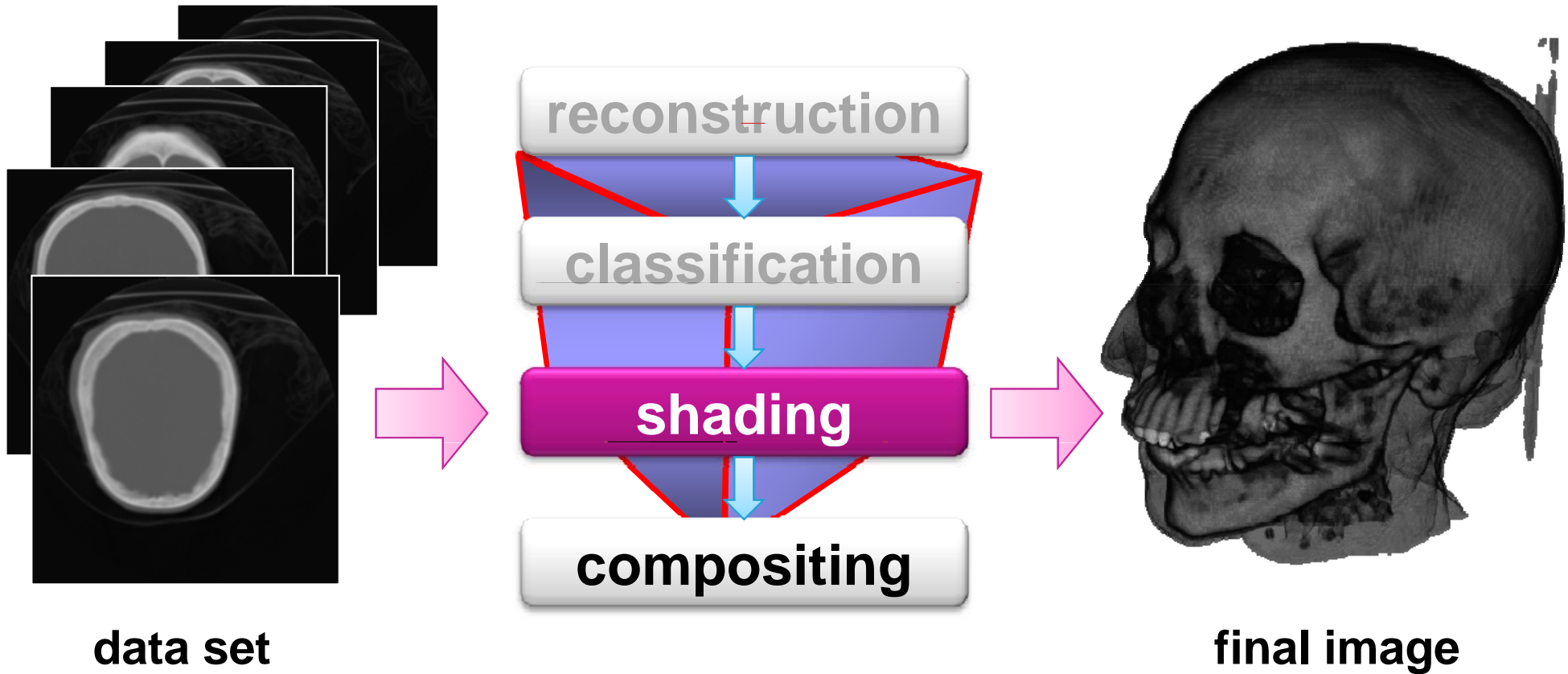


**post-interpolative**

same transfer function, resolution, and sampling rate



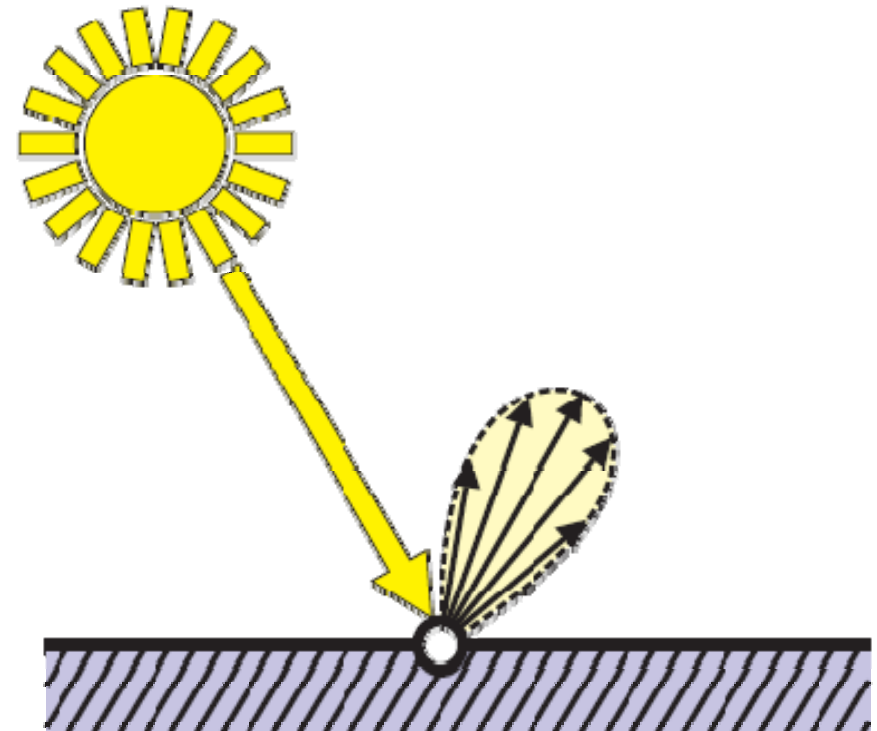
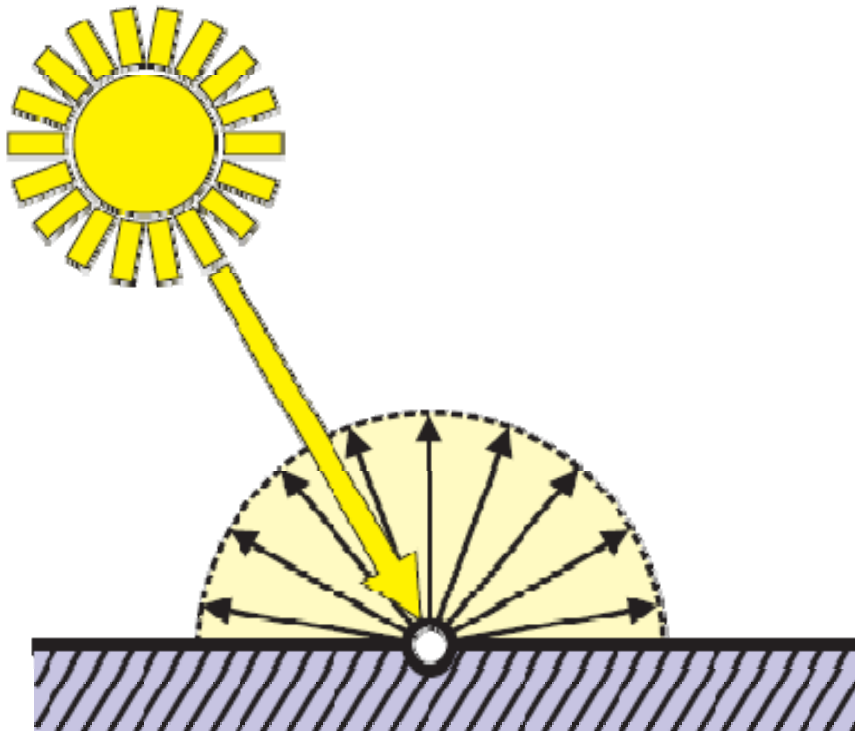
## volume rendering pipeline



- Make structures in volume data sets more realistic by applying an illumination model
- Shade each sample in the volume like a surface
- Any model used in real-time surface graphics suitable
- Common choice: Blinn-Phong illumination model



- Local illumination, similar to surface lighting
  - ◆ **Lambertian reflection**  
light is reflected equally in all directions
  - ◆ **Specular reflection**  
light is reflected scattered around the direction of perfect reflection



**shaded volume rendering**



**unshaded volume rendering**



- Normalized gradient vector of the scalar field is used to substitute for the surface normal
- The gradient vector is the first-order derivative of the scalar field

$$\nabla f(\mathbf{x}) = \begin{pmatrix} \frac{\partial f(\mathbf{x})}{\partial x} \\ \frac{\partial f(\mathbf{x})}{\partial y} \\ \frac{\partial f(\mathbf{x})}{\partial z} \end{pmatrix}$$

partial derivative in x-direction

partial derivative in y-direction

partial derivative in z-direction



- We can estimate the gradient vector using finite differencing schemes, e.g. central differences:

$$\nabla f(x, y, z) \approx \frac{1}{2h} \begin{pmatrix} f(x+h, y, z) - f(x-h, y, z) \\ f(x, y+h, z) - f(x, y-h, z) \\ f(x, y, z+h) - f(x, y, z-h) \end{pmatrix}$$

- Noisy data may require more complex estimation schemes

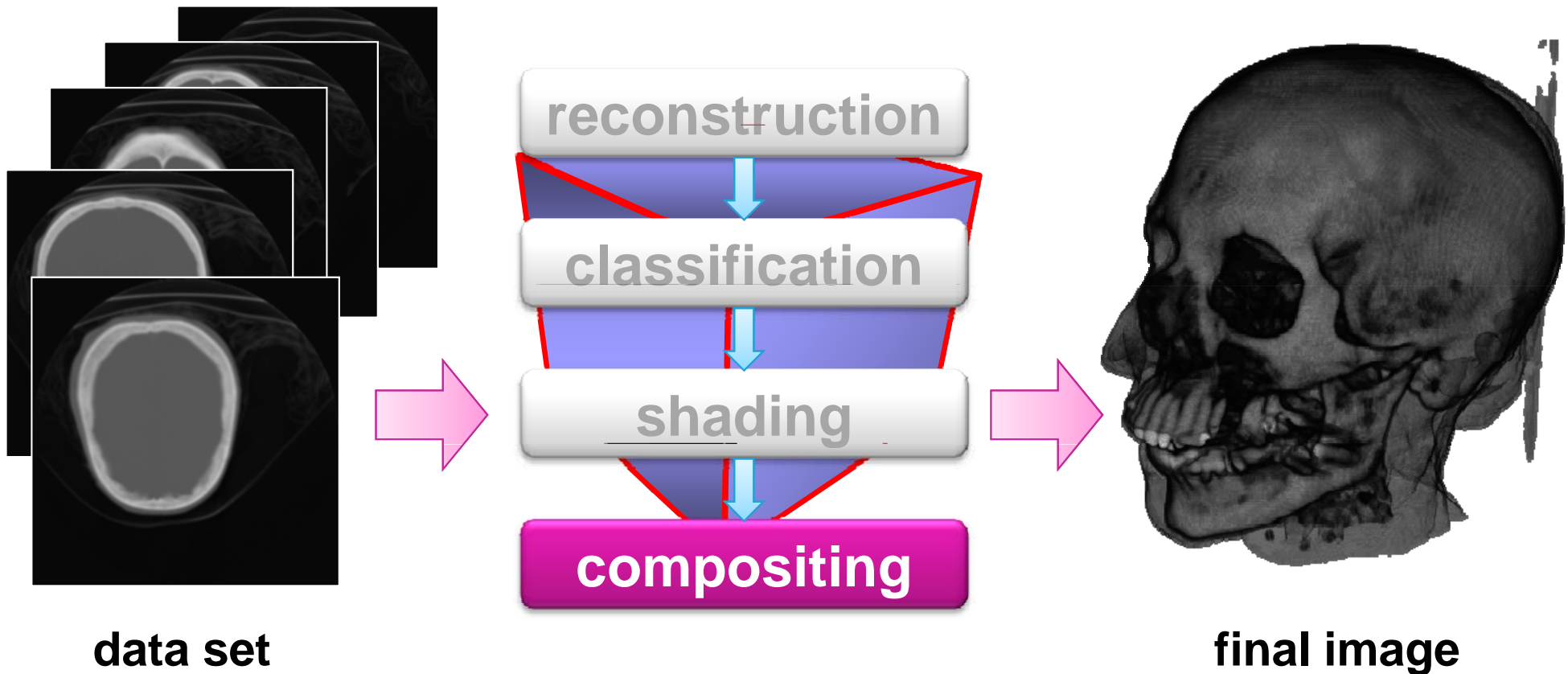




- Magnitude of gradient vector can be used to measure the “surfaceness” of a point
  - ◆ Strong changes  $\rightarrow$  high gradient magnitude
  - ◆ Homogeneity  $\rightarrow$  low gradient magnitude
- Applications
  - ◆ Use gradient magnitude to modulate opacity of sample
  - ◆ Interpolate between unshaded and shaded sample color using gradient magnitude as weight

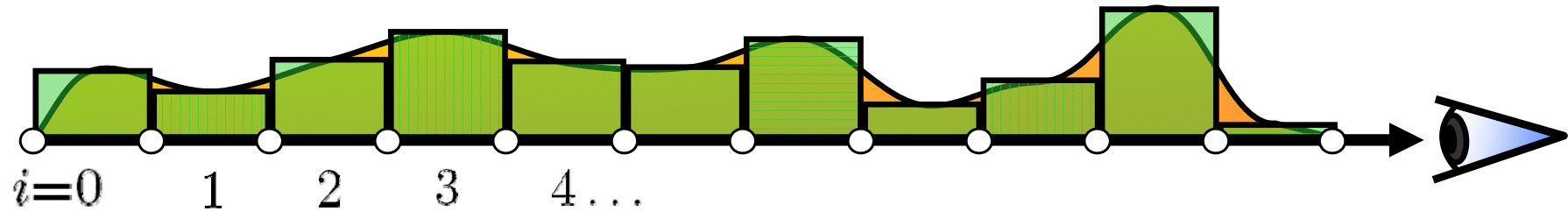


## volume rendering pipeline



- So far, everything discussed applies to single sample points along a viewing ray
- How to subsequence sample when traversing the ray?
- Common models
  - ◆ Maximum Intensity Projection
  - ◆ Emission-Absorption Model





- Always display the maximum value along a viewing ray
- Motivation: visualization of contrast-enhanced tomographic scans
- Parameterless rendering, very common in medical domain



- Problem: loss of spatial relationships between different structures

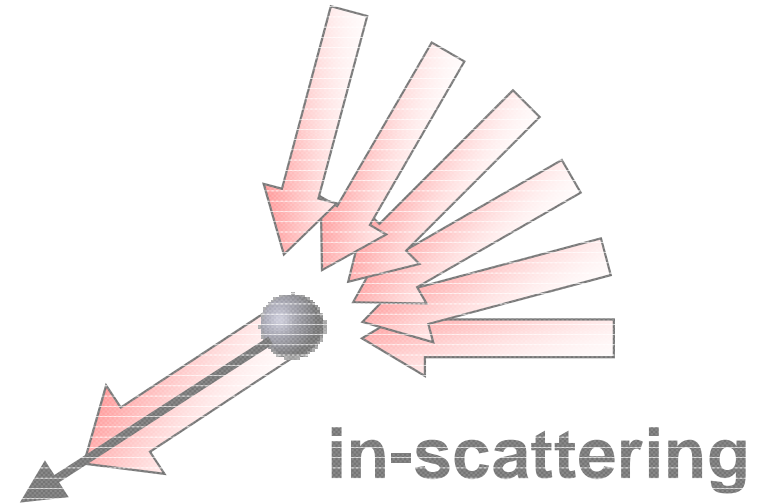
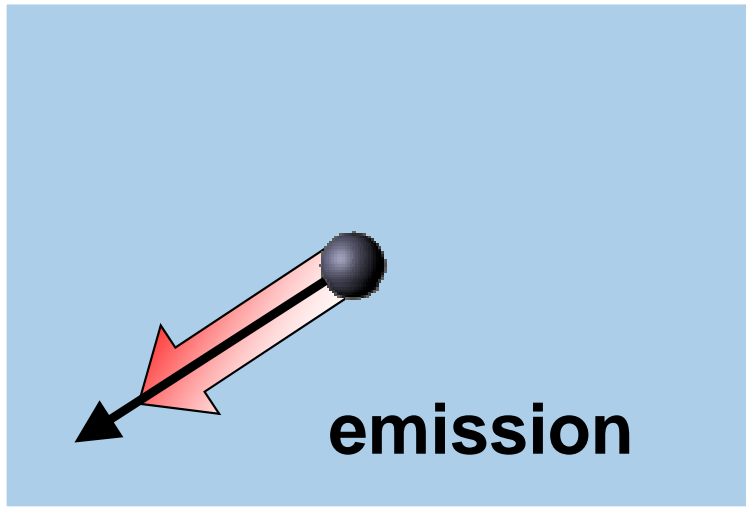


- Conventional volume rendering uses an emission-absorption model
- Scattering effects are usually ignored due to high computational complexity
- For each pixel on the image plane, a the ray integral has to be solved
- For each step along he viewing ray, perform accumulate RGBA from transfer function

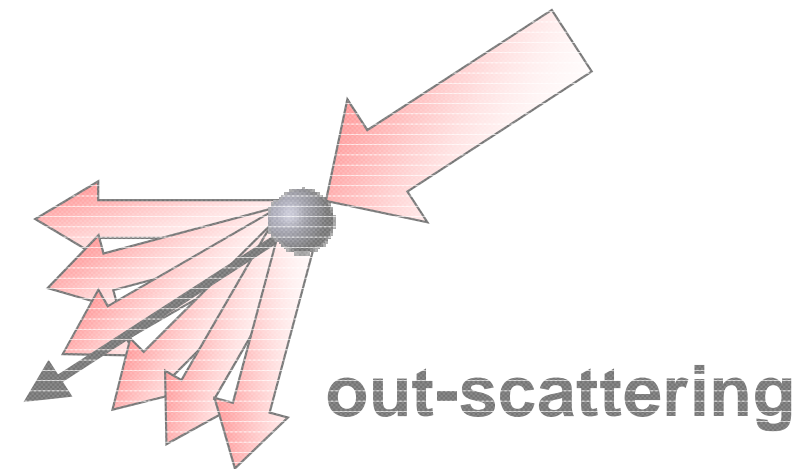
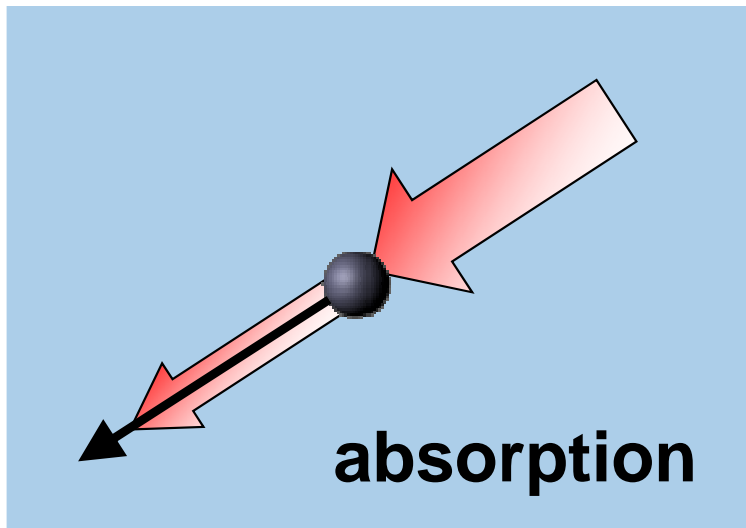


# Emission-Absorption Model (2)

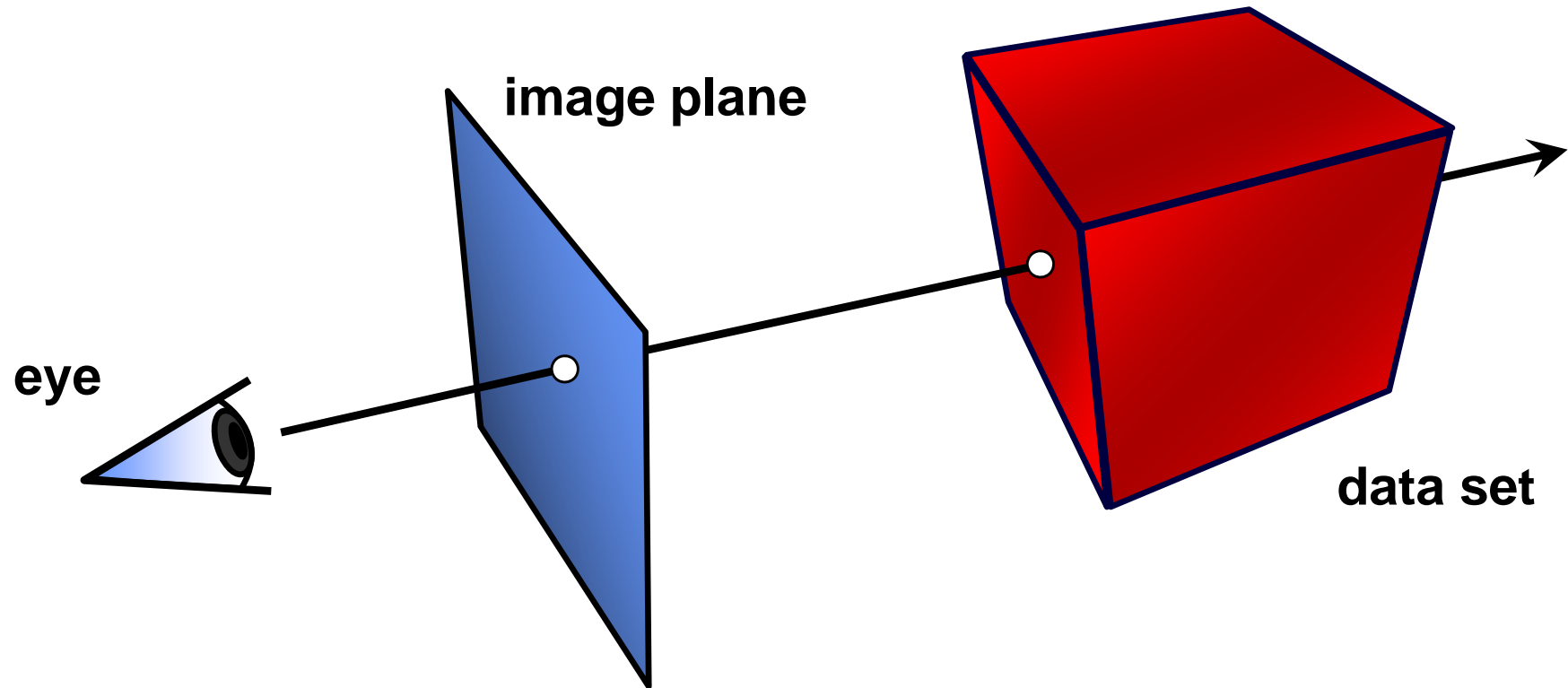
increase



decrease



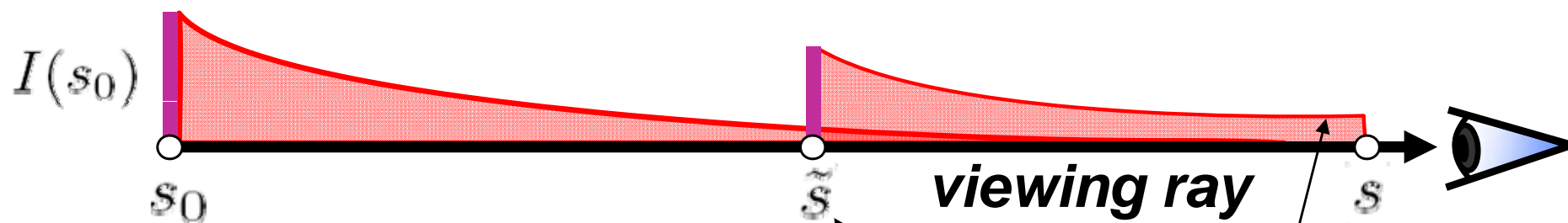
# Ray Integration (1)





How do we determine the radiant energy along the ray?

**Physical model:** emission and absorption, no scattering



**Every** point  $\tilde{s}$  along the viewing ray emits additional radiant energy

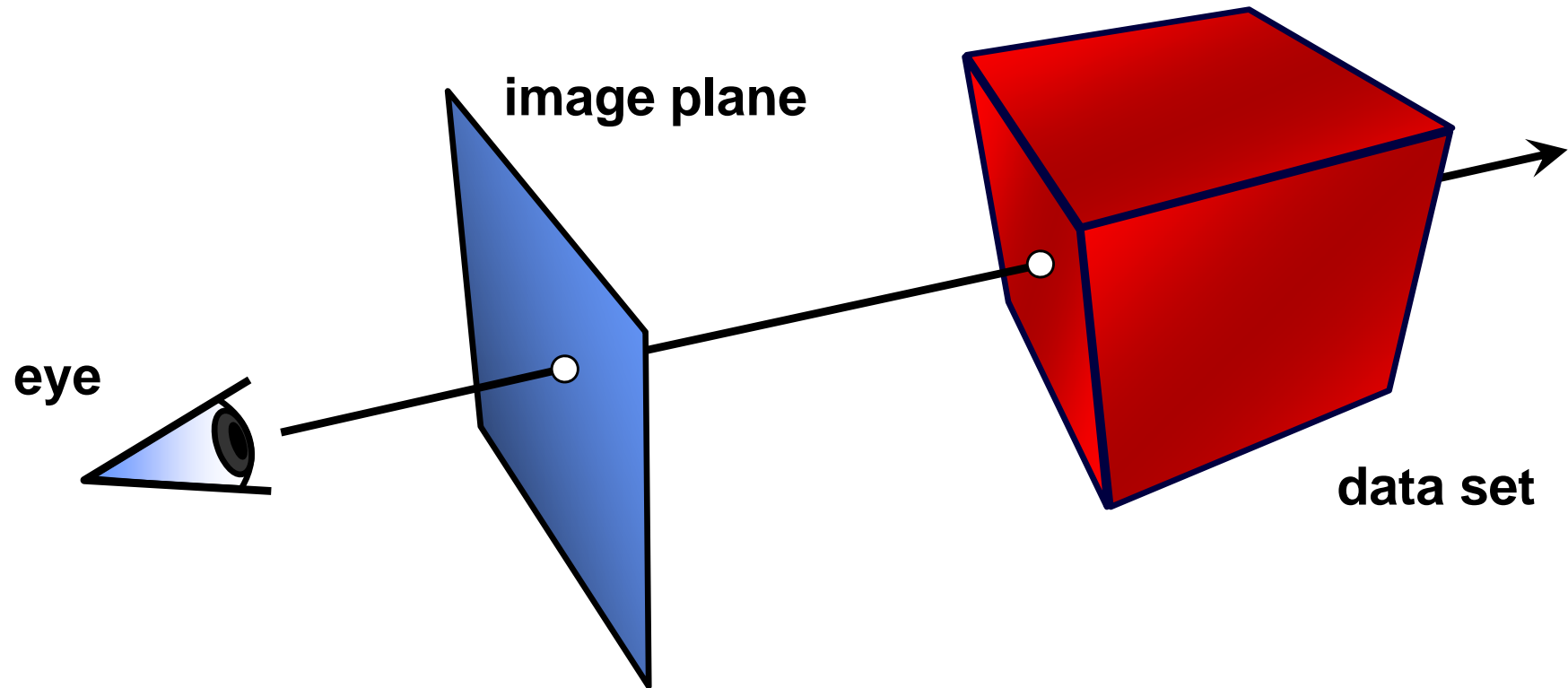
active emission  
at point  $\tilde{s}$

absorption along the  
distance  $s - \tilde{s}$

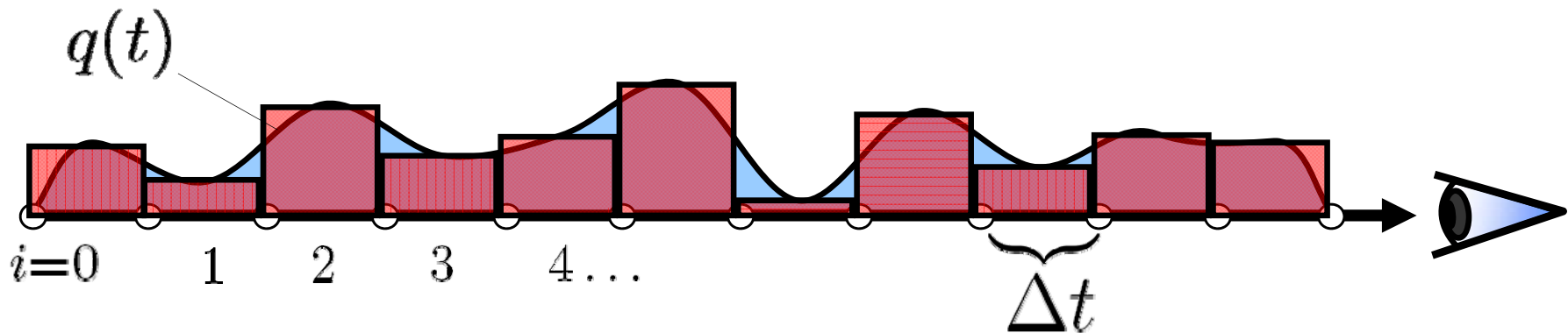
$$I(s) = I(s_0) e^{-\tau(s_0, s)} + \int_{s_0}^s q(\tilde{s}) e^{-\tau(\tilde{s}, s)} d\tilde{s}$$



# Numerical Solution (1)



# Numerical Solution (2)



$$\tilde{C} = \sum_{i=0}^{\lfloor T/\Delta t \rfloor} C_i \prod_{j=0}^{i-1} (1 - A_j)$$

can be computed recursively

$$C'_i = C_i + (1 - A_i)C'_{i-1}$$

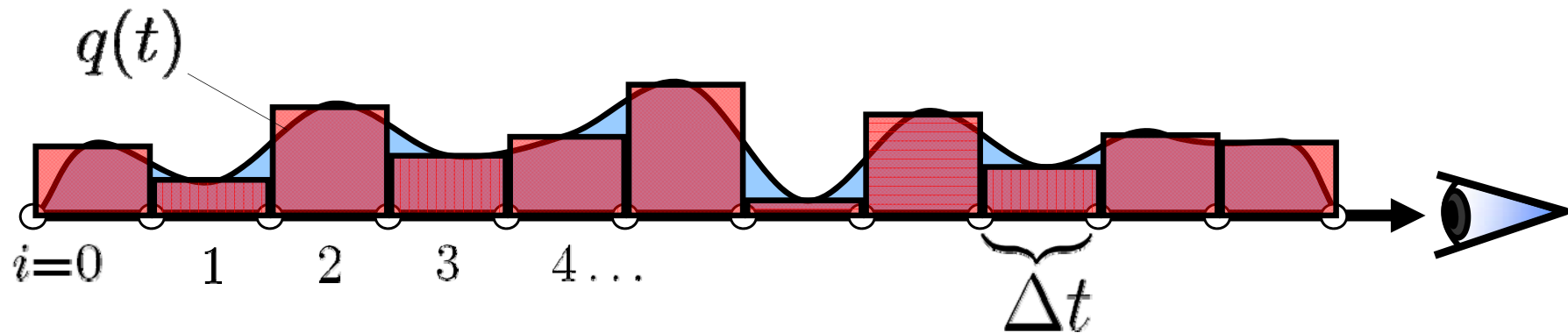
radiant energy  
observed at position  $i$

radiant energy  
emitted at position  $i$

absorption at  
position  $i$

radiant energy  
observed at position  $i-1$





**back-to-front  
compositing**

$$C'_i = C_i + (1 - A_i)C'_{i-1}$$

**front-to-back  
compositing**

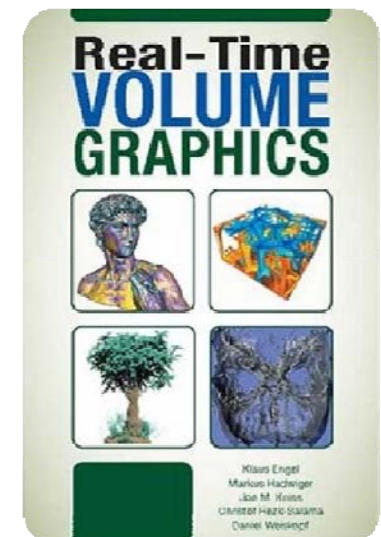
$$C'_i = C'_{i+1} + (1 - A'_{i+1})C_i$$
$$A'_i = A'_{i+1} + (1 - A'_{i+1})A_i$$

**early ray termination:**  
stop the calculation  
when

$$A'_i \approx 1$$



- M. Levoy. Display of Surfaces from Volume Data. *IEEE Computer Graphics and Applications*, 8(3):29-37, 1988.
- R. Drebin, L. Carpenter, P. Hanrahan. Volume Rendering. *ACM SIGGRAPH Computer Graphics*, 22(4):65-74, 1988.
- W. Lorensen, H. Cline. Marching cubes: A high resolution 3D surface construction algorithm. *ACM SIGGRAPH Computer Graphics*, 21(4):163-169, 1987.
- C. Rezk-Salama, K. Engel, M. Hadwiger, J. Kniss, D. Weiskopf. *Real-Time Volume Graphics*, AK Peters, 1-56881-266-3, 2006.



- FlowVis = visualization of flows
  - ◆ Visualization of change information
- Flow data
  - ◆  $nD \times nD$  data,  $1D^2 / 2D^2 / nD^2$  (models),  $2D^2 / 3D^2$
  - ◆ Vector data ( $nD$ ) in  $nD$  data space
  - ◆ Steady vs. time-dependent flow
- User goals
  - ◆ Overview vs. details (with context)



## ■ Simulation

- ◆ Flow space modelled with grid
- ◆ FEM (finite elements method),  
CfD (computational fluid dynamics)

## ■ Measurements

- ◆ Optical methods + pattern recognition,  
e.g.: PIV (particle image velocimetry)

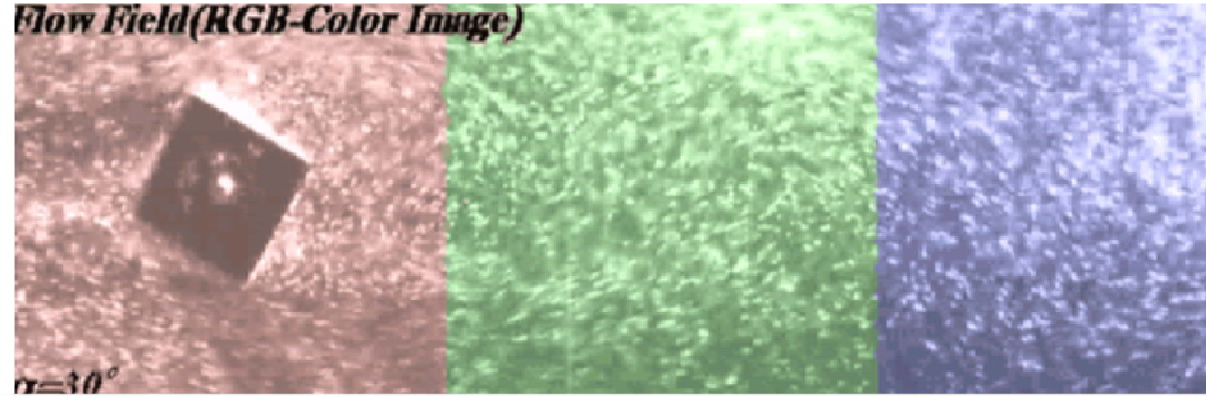
## ■ Models

- ◆ Differential equation systems  $d\mathbf{x}/dt$

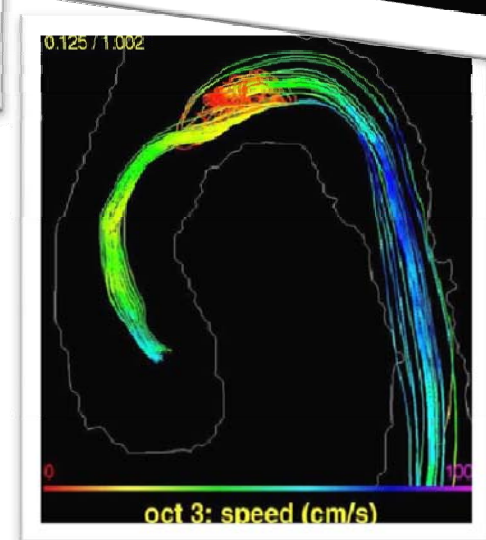
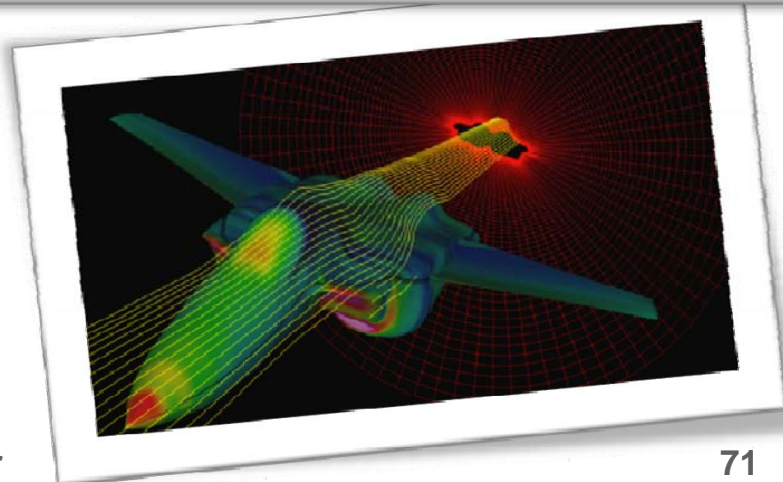
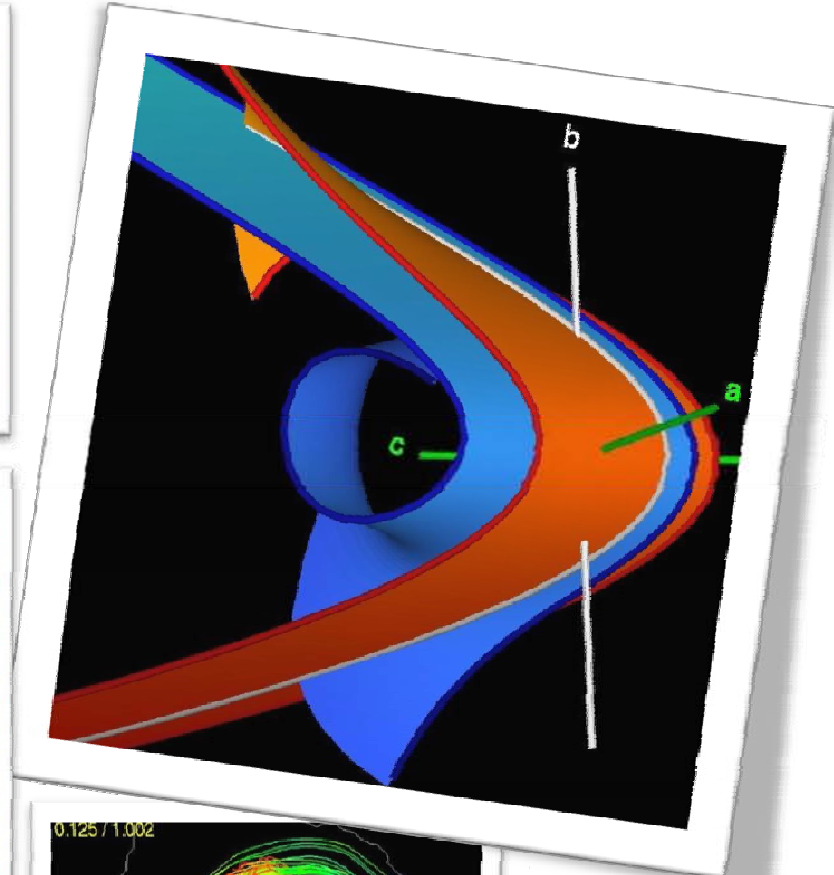
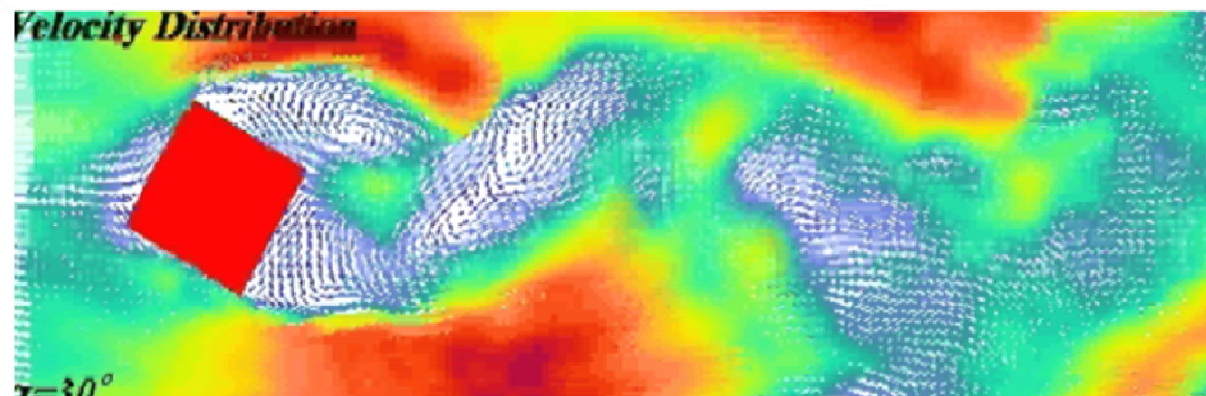


# Flow Data (2)

Flow Field (RGB-Color Image)



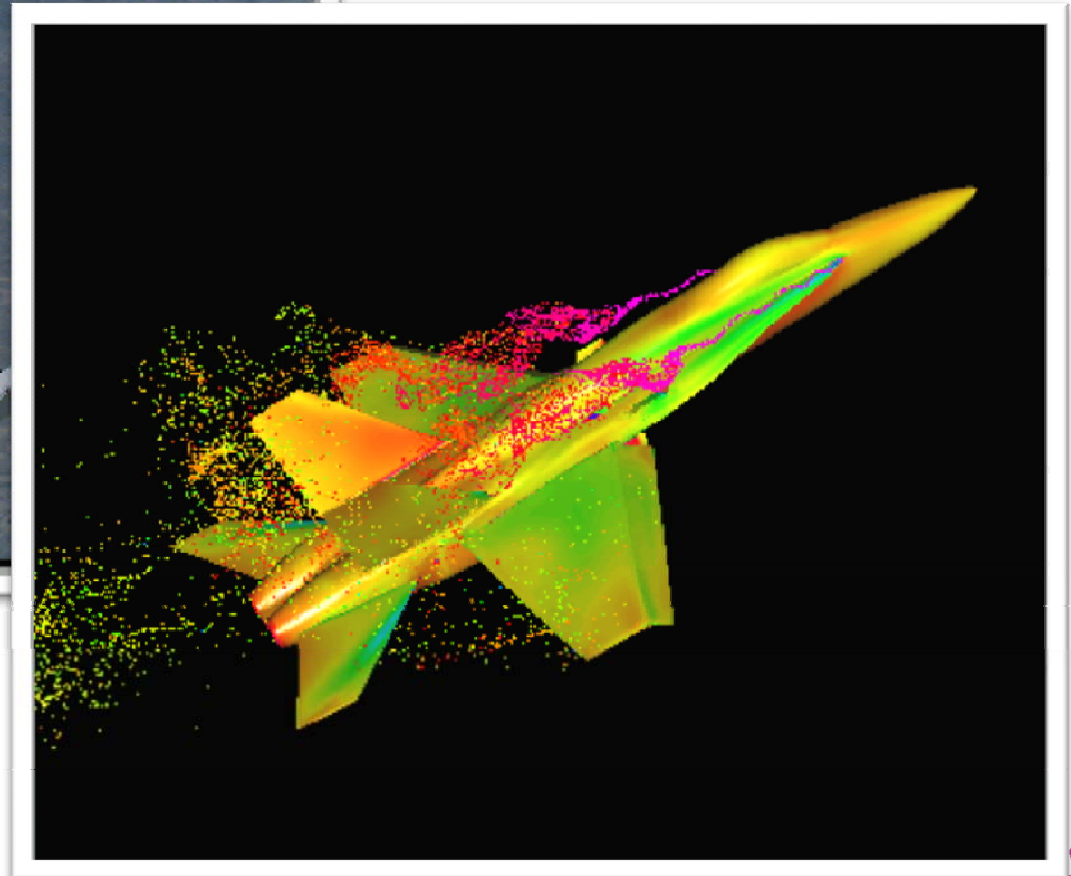
Velocity Distribution







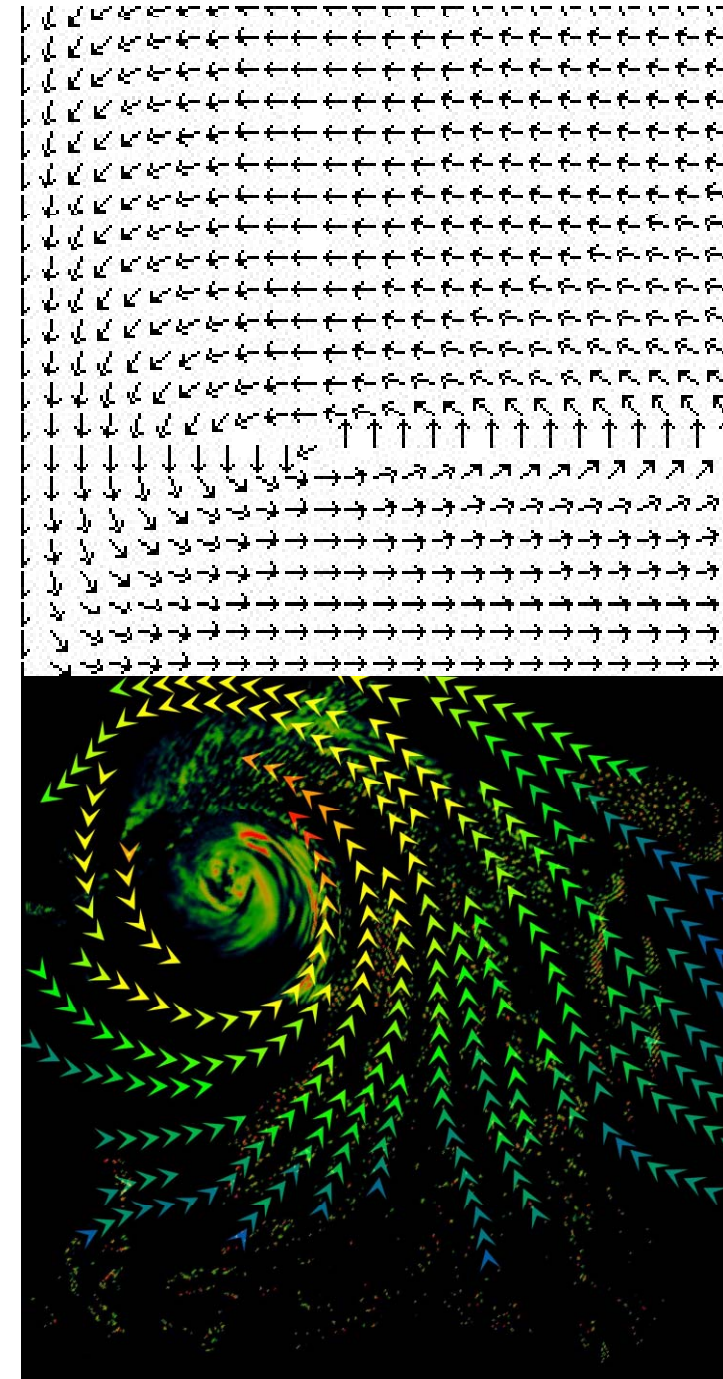
**experiment**



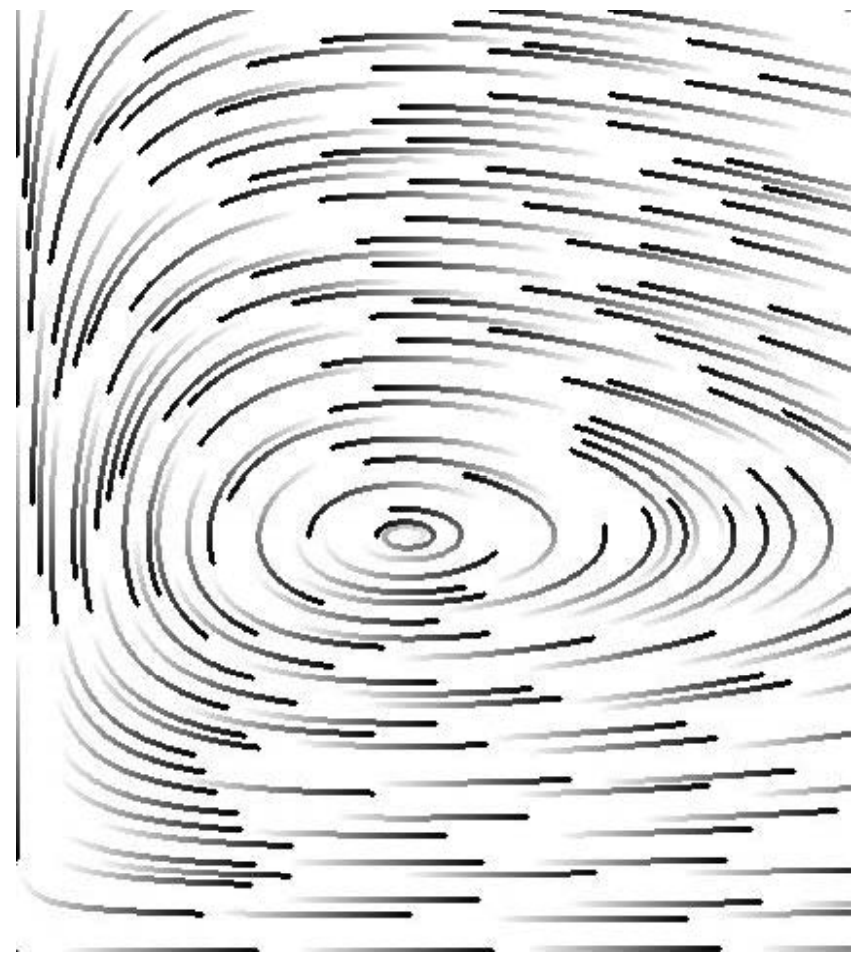
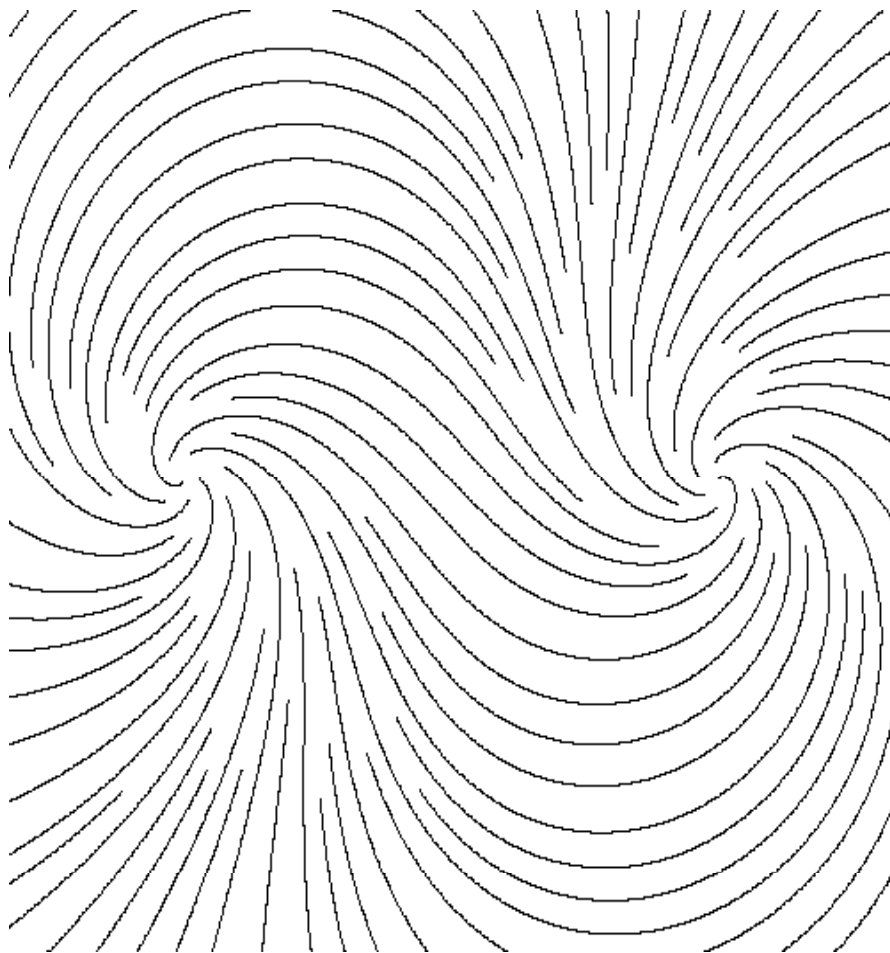
**simulation**



- Grid of arrows to visualize flow directions
- Normalized arrows vs. scaling with velocity
- Quite effective in 2D, problematic in 3D
- Sometimes limited expressivity (temporal component missing)



- Idea: follow the flow in time (integration) to extract the path of a particle



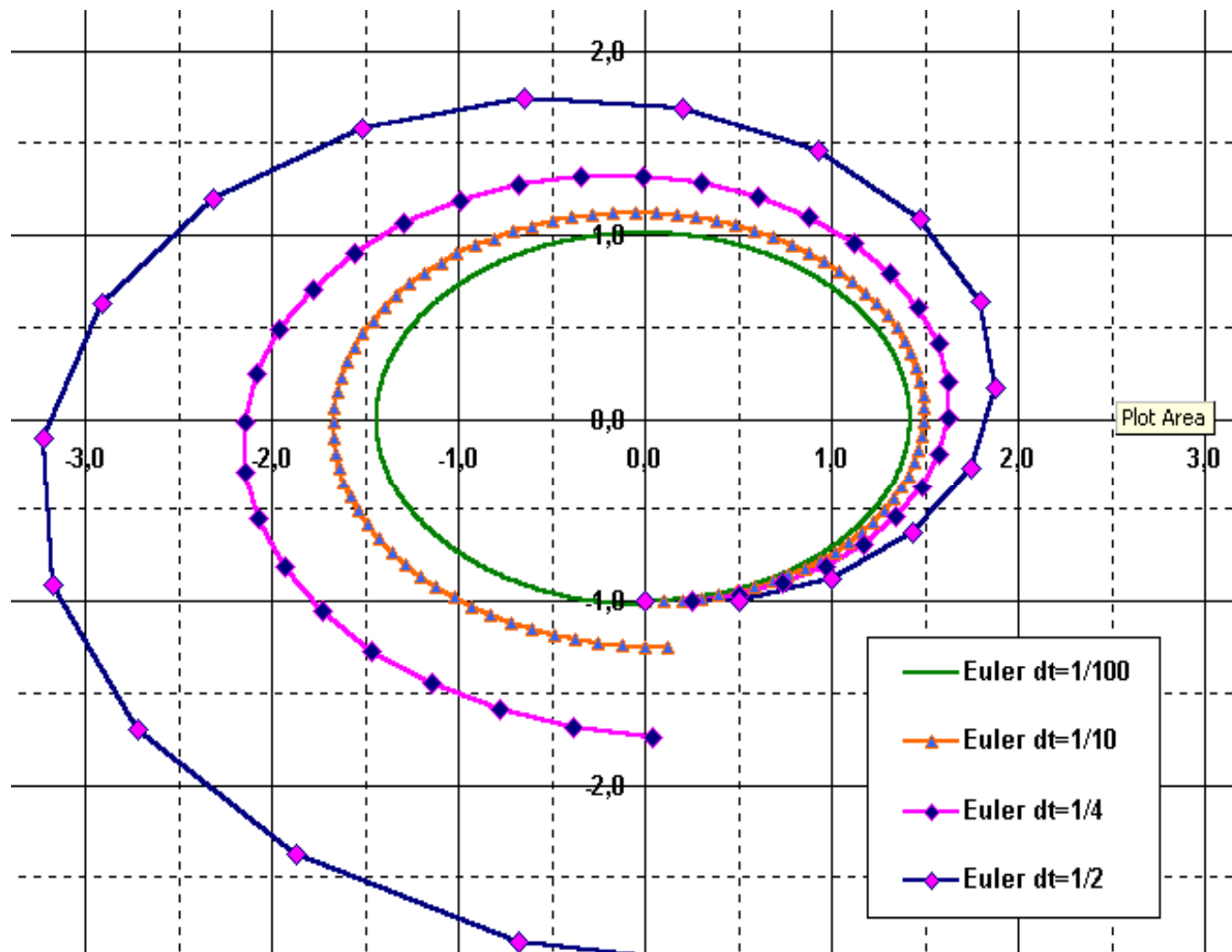
- Flow data  $\mathbf{v}$ : derivative information
  - ◆  $d\mathbf{x}/dt = \mathbf{v}(\mathbf{x})$   
spatial points  $\mathbf{x} \in \mathbb{R}^n$ , flow vectors  $\mathbf{v} \in \mathbb{R}^n$ , time  $t \in \mathbb{R}$
- Streamline  $\mathbf{s}$ : integration over time, also called trajectory, solution, curve
  - ◆  $\mathbf{s}(t) = \mathbf{s}_0 + \int_{0 \leq u \leq t} \mathbf{v}(\mathbf{s}(u)) du$   
seed point  $\mathbf{s}_0$ , integration variable  $u$
- Difficulty: result  $\mathbf{s}$  also in the integral, analytical solution usually impossible



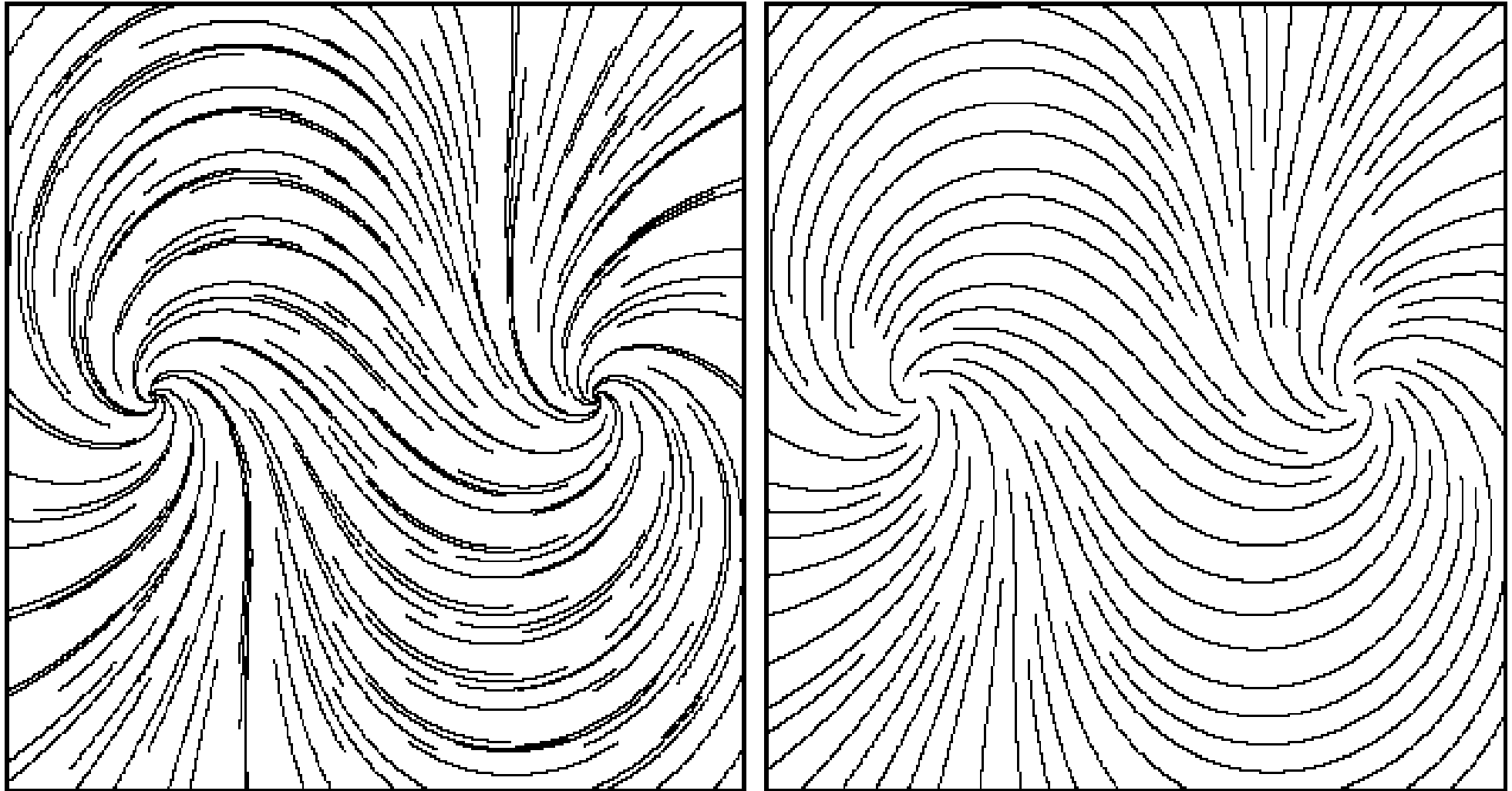
- Solve using numerical integration techniques
- Assume that locally the solution is approximately linear
- Euler integration
  - ◆  $\mathbf{s}_{i+1} = \mathbf{s}_i + dt \cdot \mathbf{v}(\mathbf{s}_i)$   
Follow the current flow vector  $\mathbf{v}(\mathbf{s}_i)$  from the current streamline point  $\mathbf{s}_i$  for a short time ( $dt$ )



- Accuracy of results is strongly dependent on step size  $dt$



- Seed fill with streamlines to achieve equal density

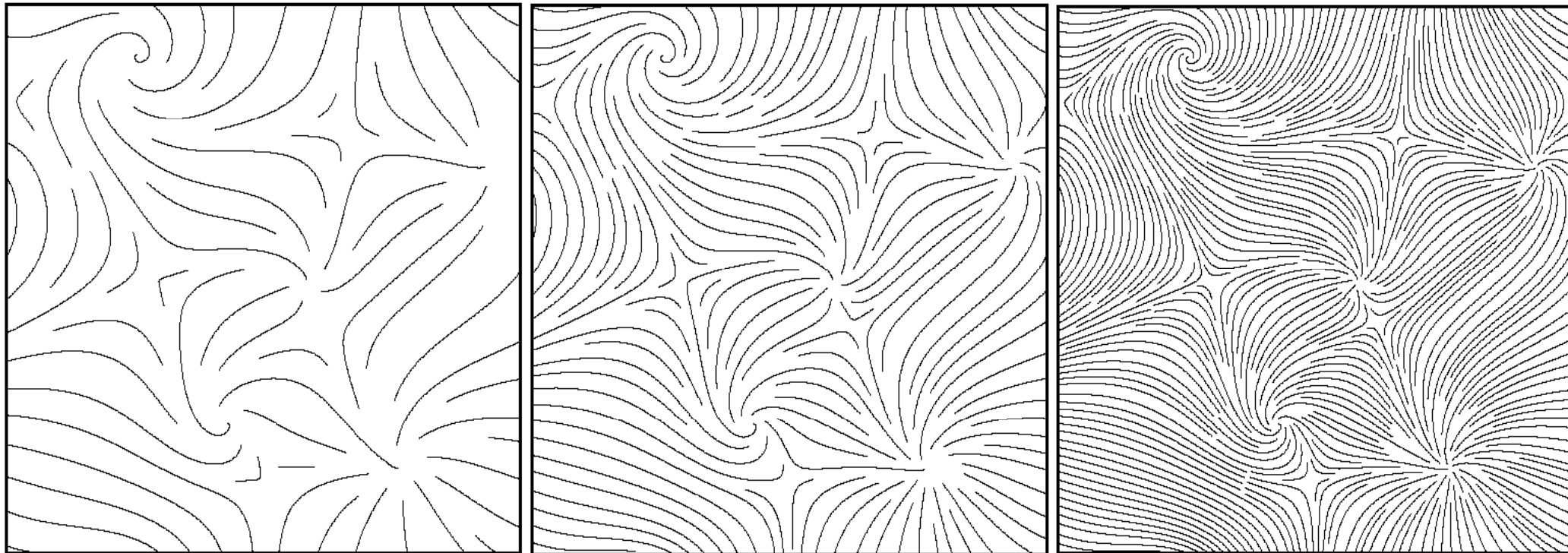


- Variations of distance in relation to image width

**6%**

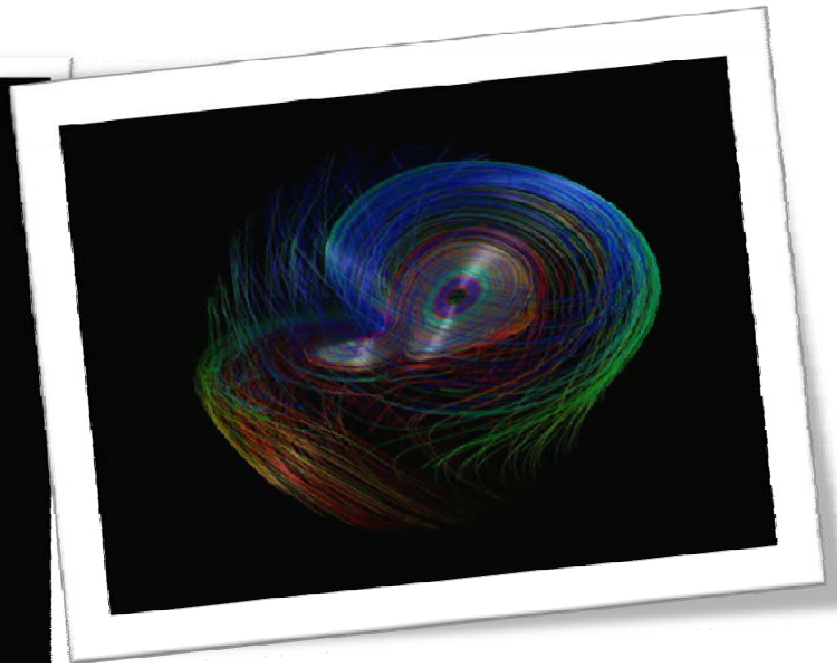
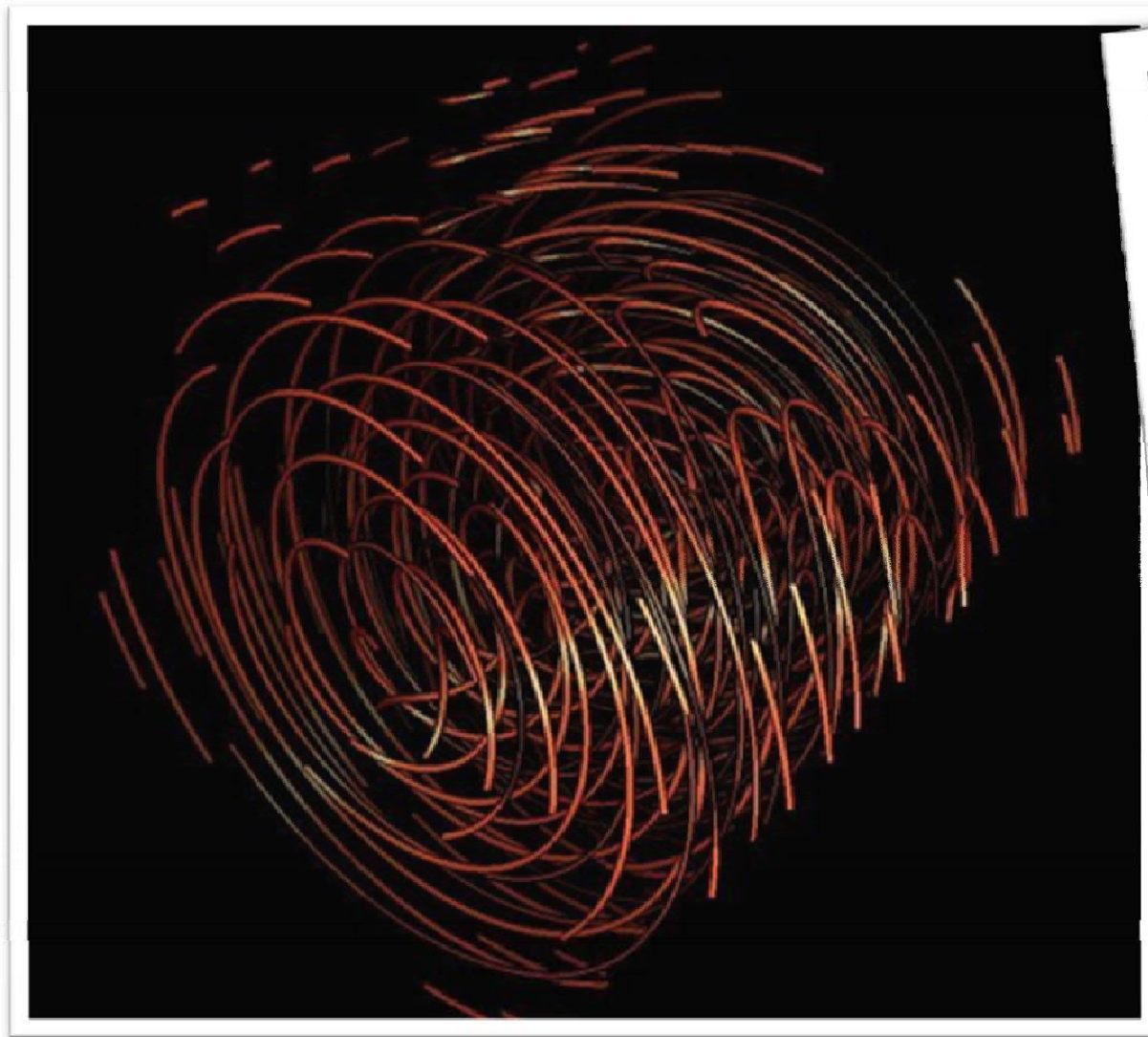
**3%**

**1.5%**

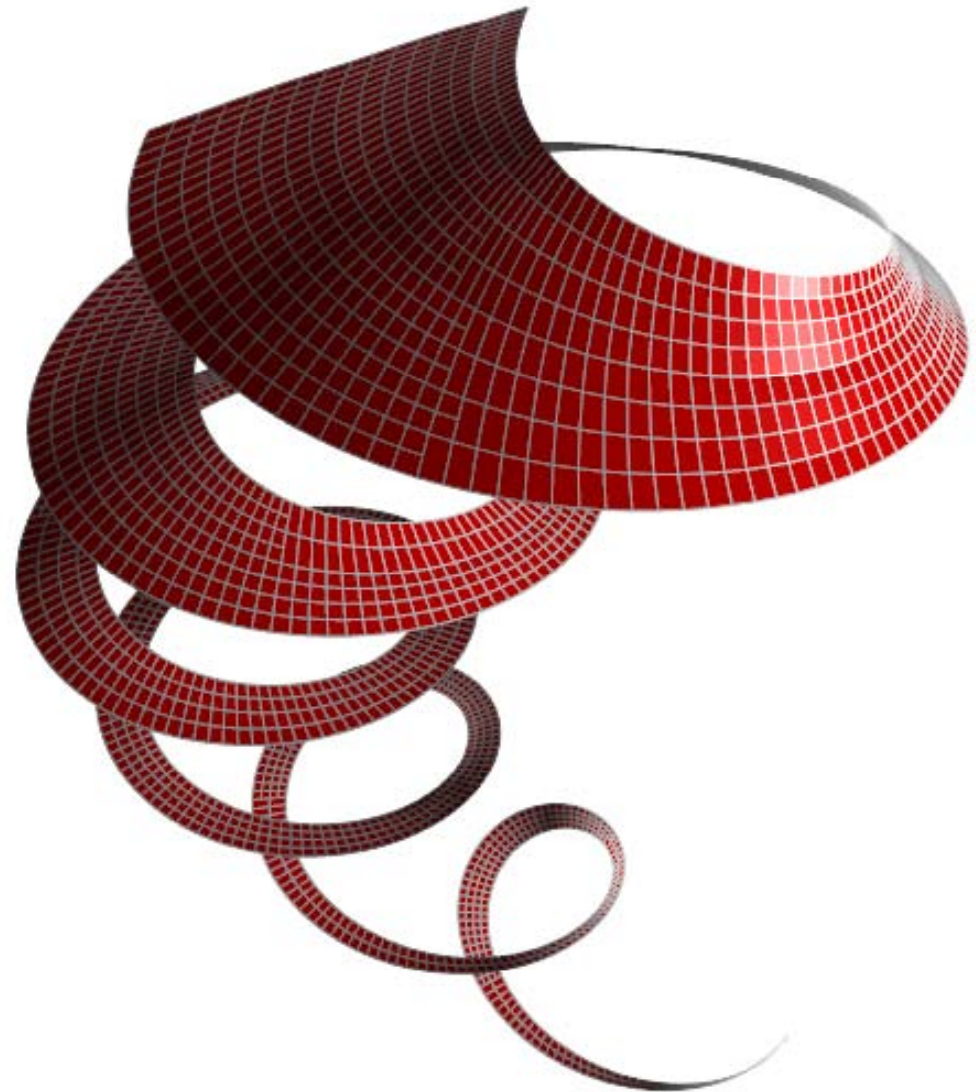




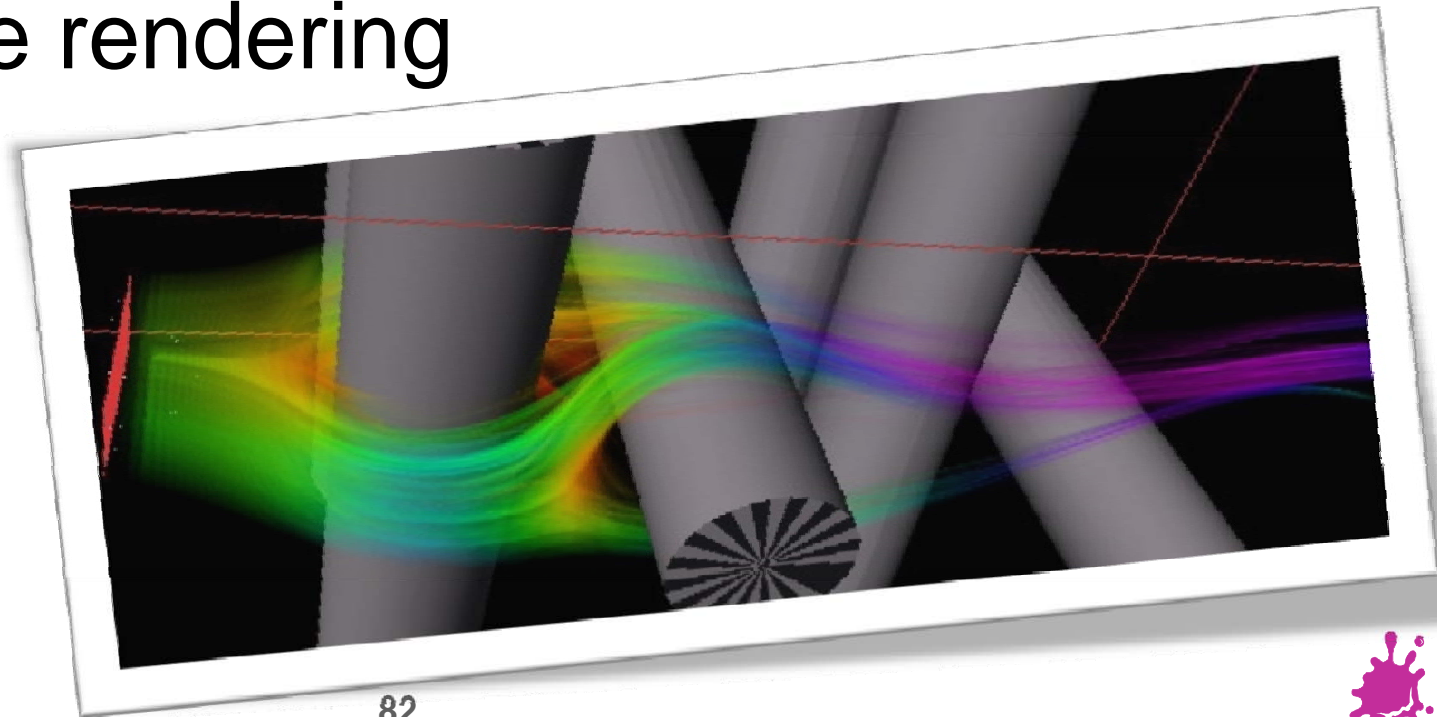
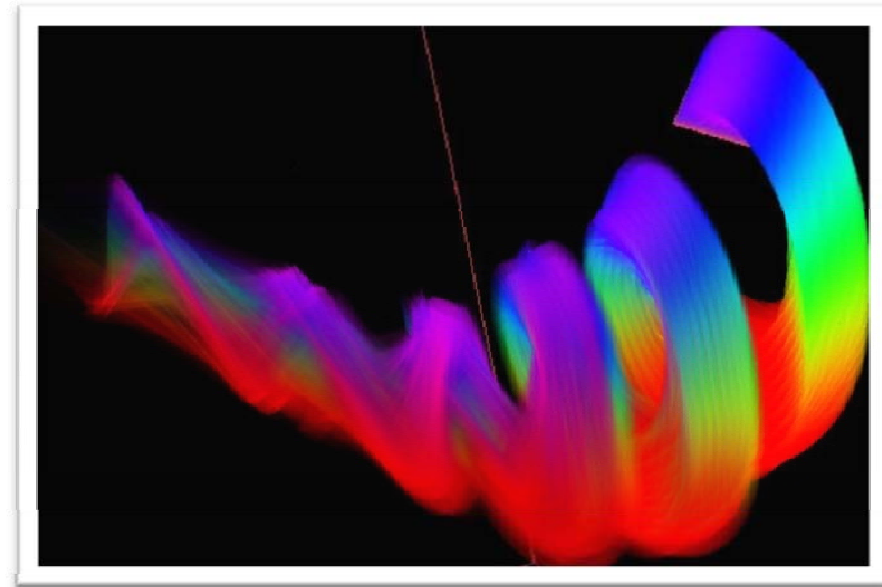
- Illuminated 3D curves improve perception



- Natural extension of streamlines to 3D
- Surfaces which are tangential to the vector field everywhere
- Challenges related to occlusion and visual complexity



- Volumetric equivalents of streamlines, subset of a 3D flow domain is traced in time
- Can be visualized with direct volume rendering methods



## ■ Path line

- ◆ Trajectory of an individual particle in the fluid flow

## ■ Timeline

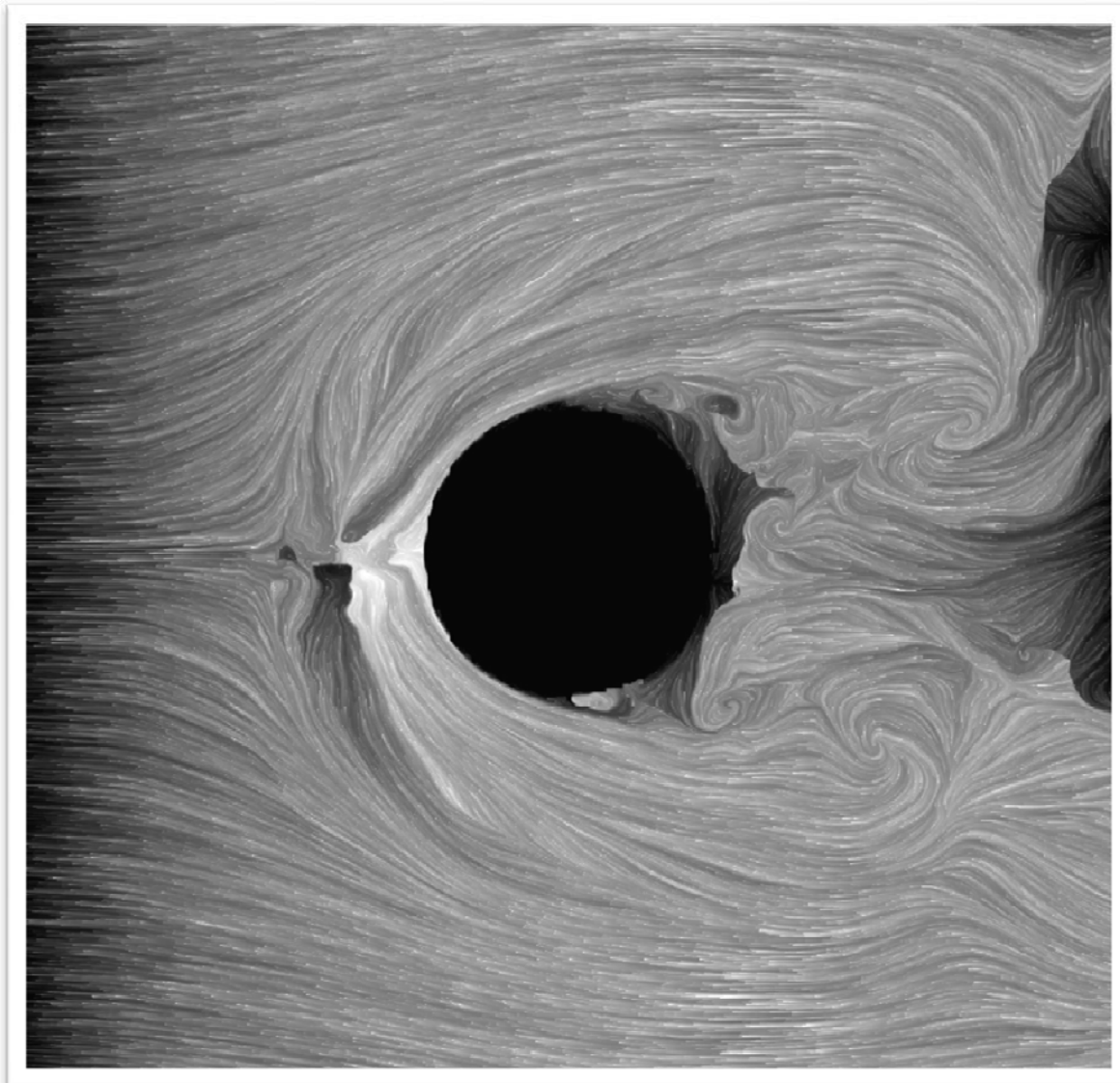
- ◆ Joins the positions of particles released at the same instant in time

## ■ Streak line

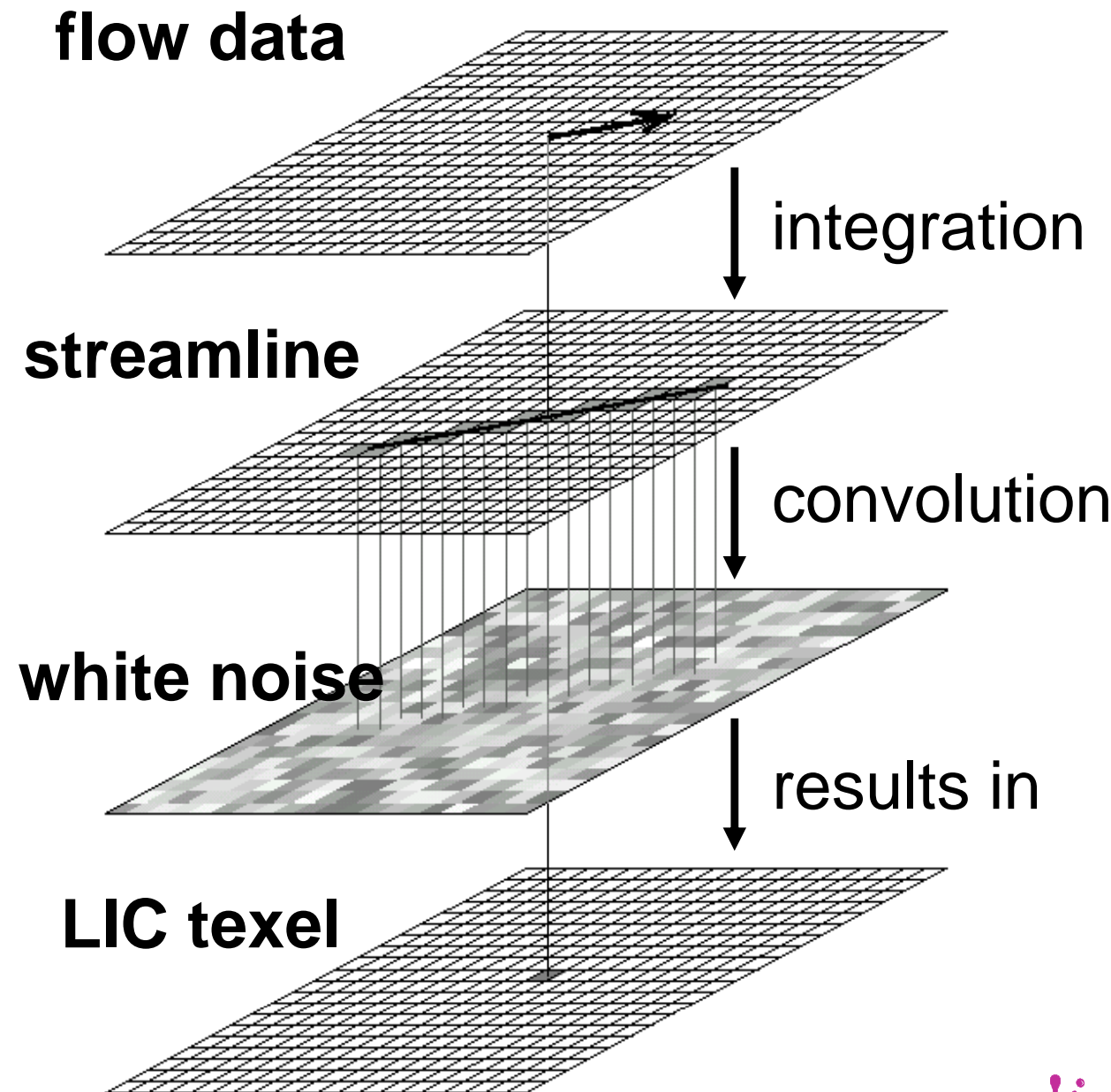
- ◆ Connects particles that have passed through a certain point in space



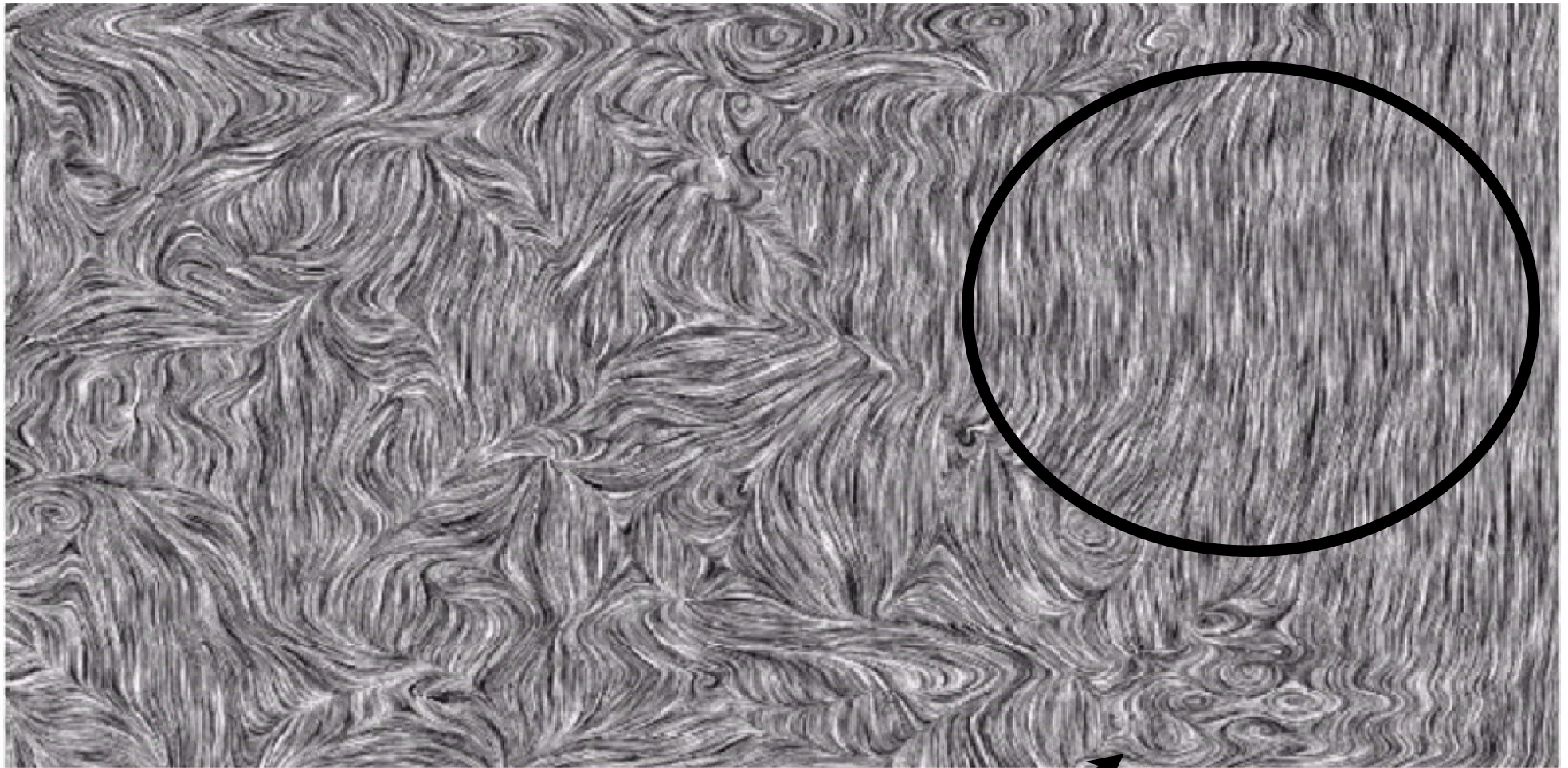
- Idea: exploit visual correlations to provide a dense visualization of the flow



- Calculation of a texture value
  - ◆ look at streamline through point
  - ◆ filter white noise along streamline



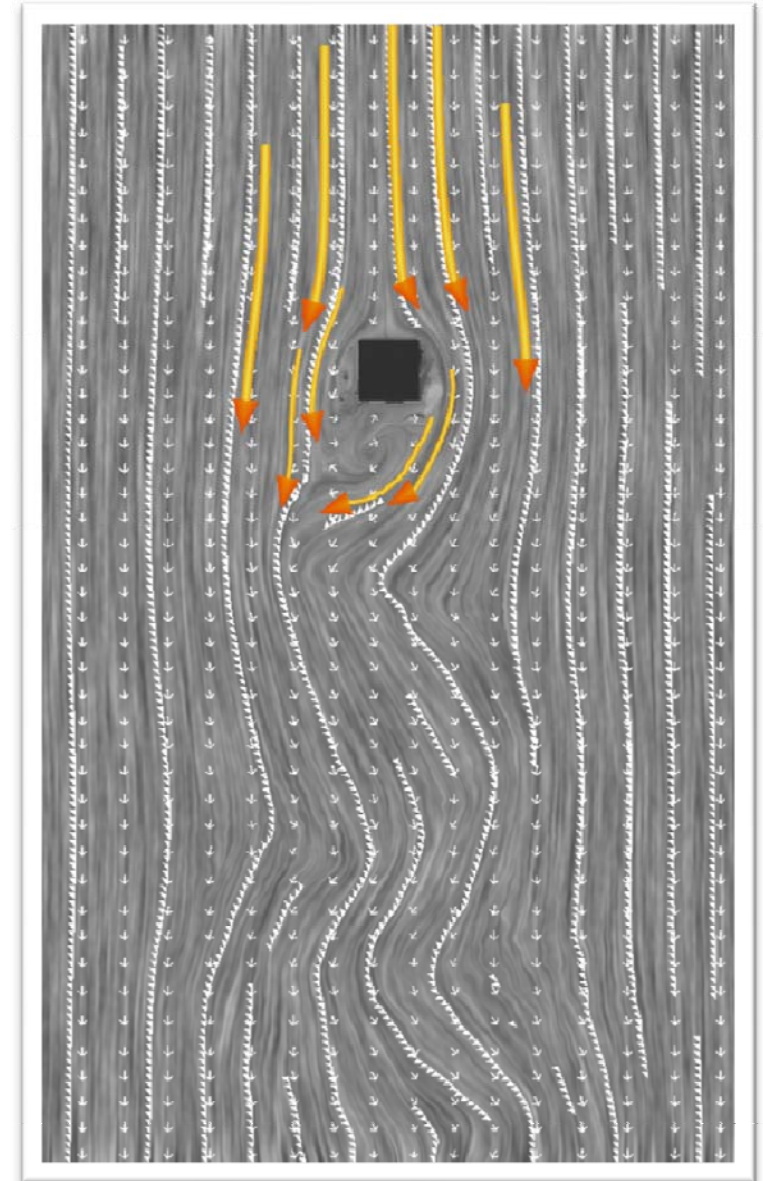
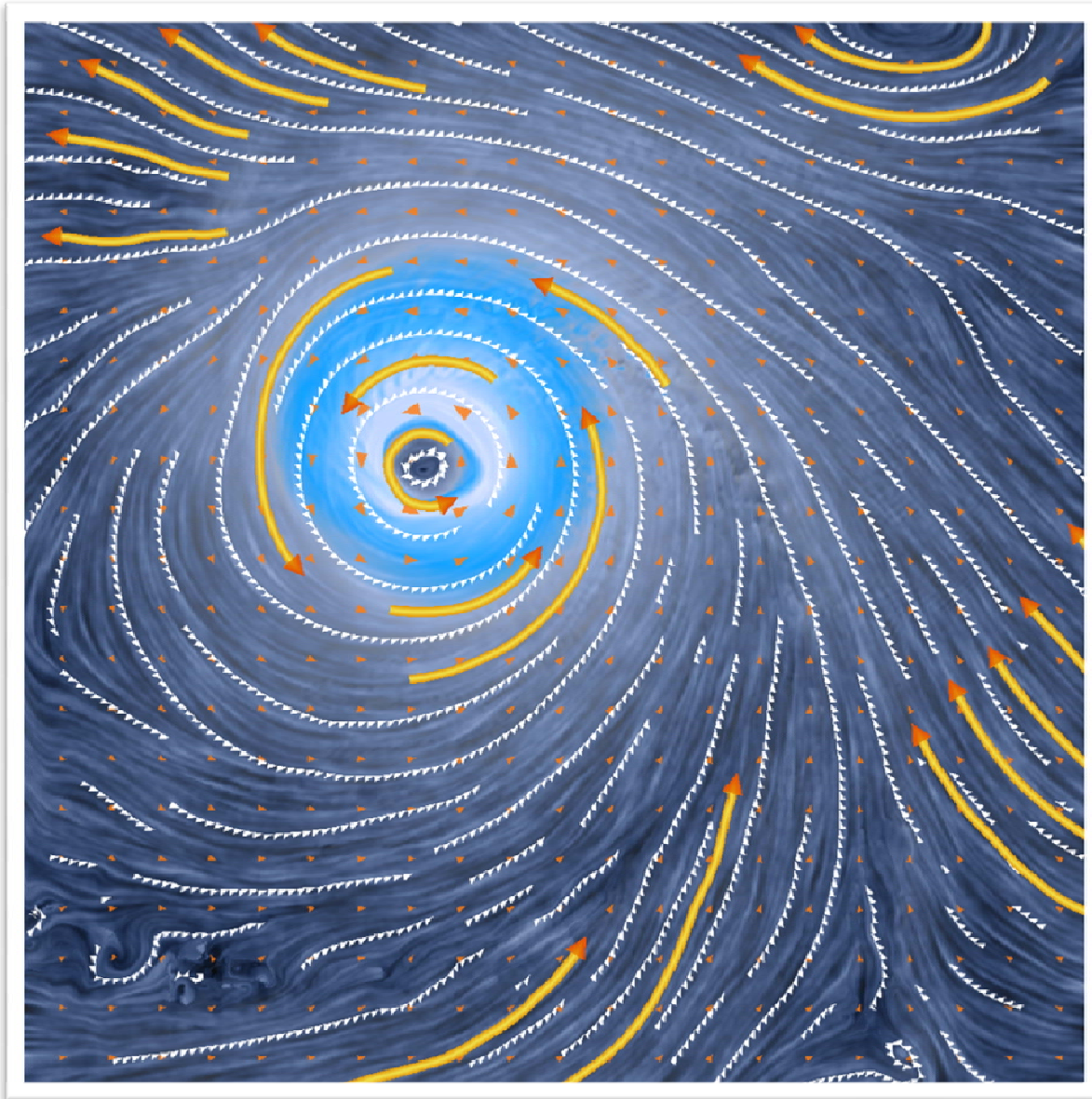
**laminar flow**



**turbulent flow**

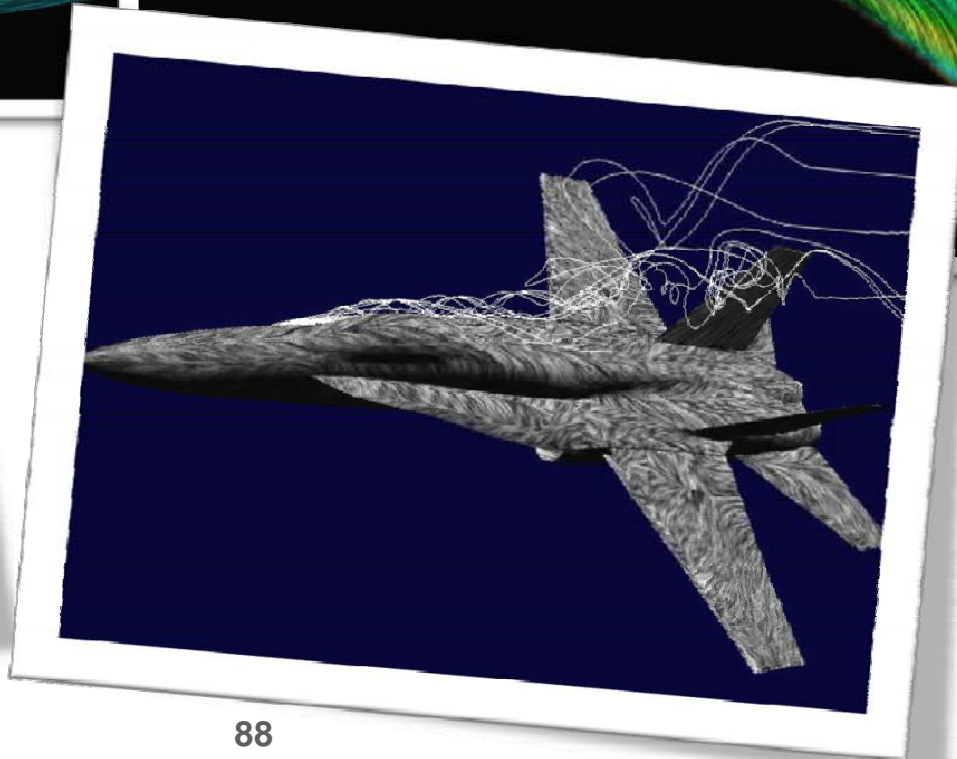
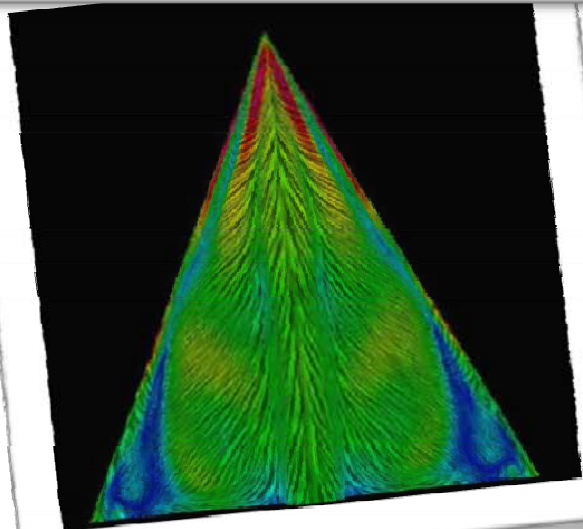
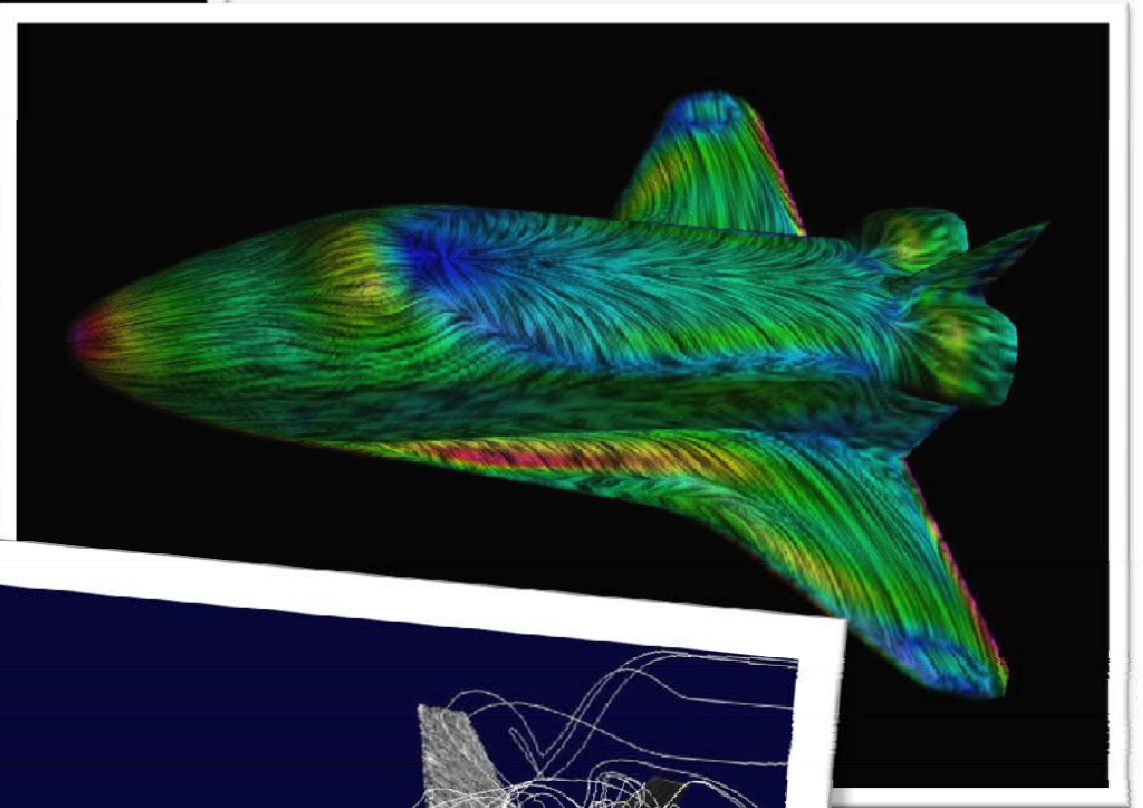
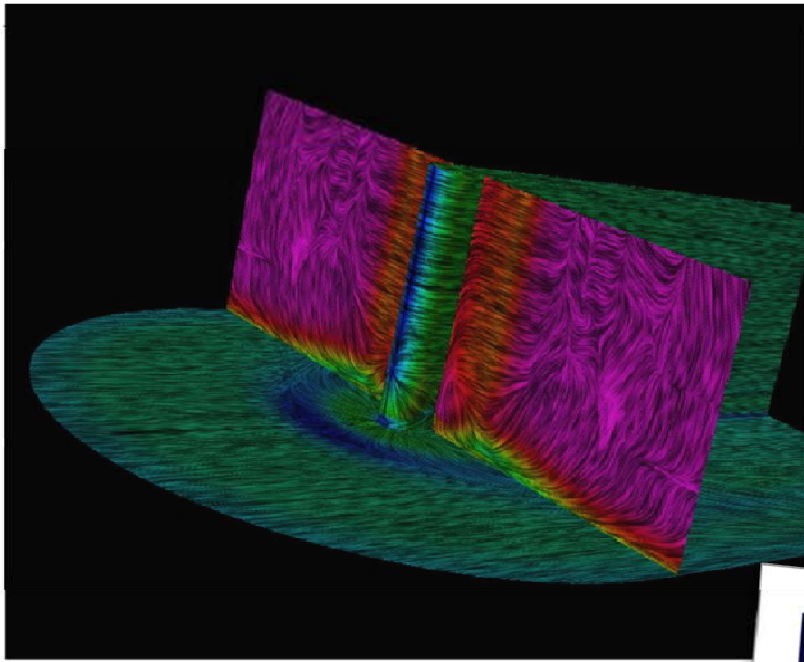


# Line Integral Convolution – Examples (2)

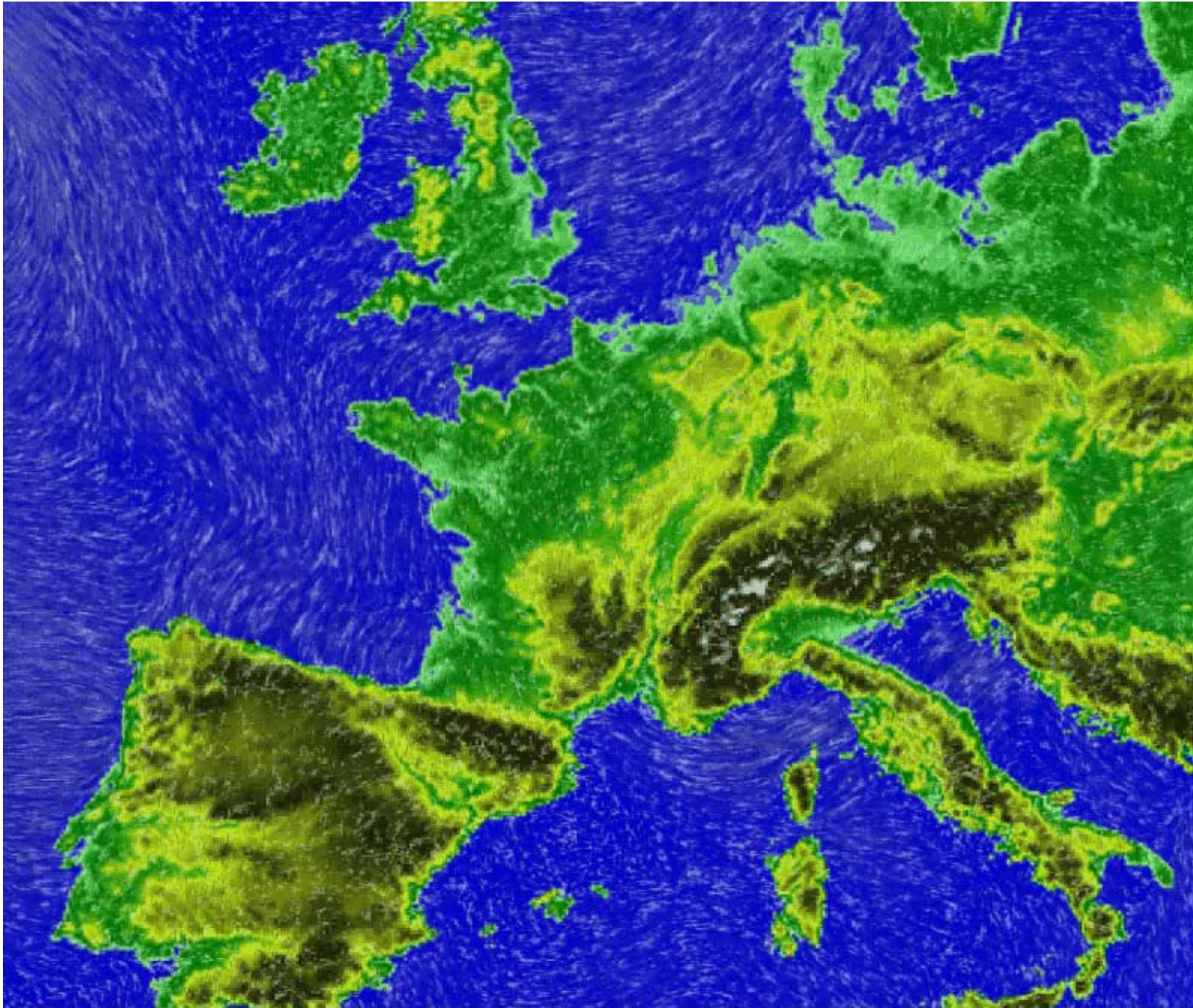




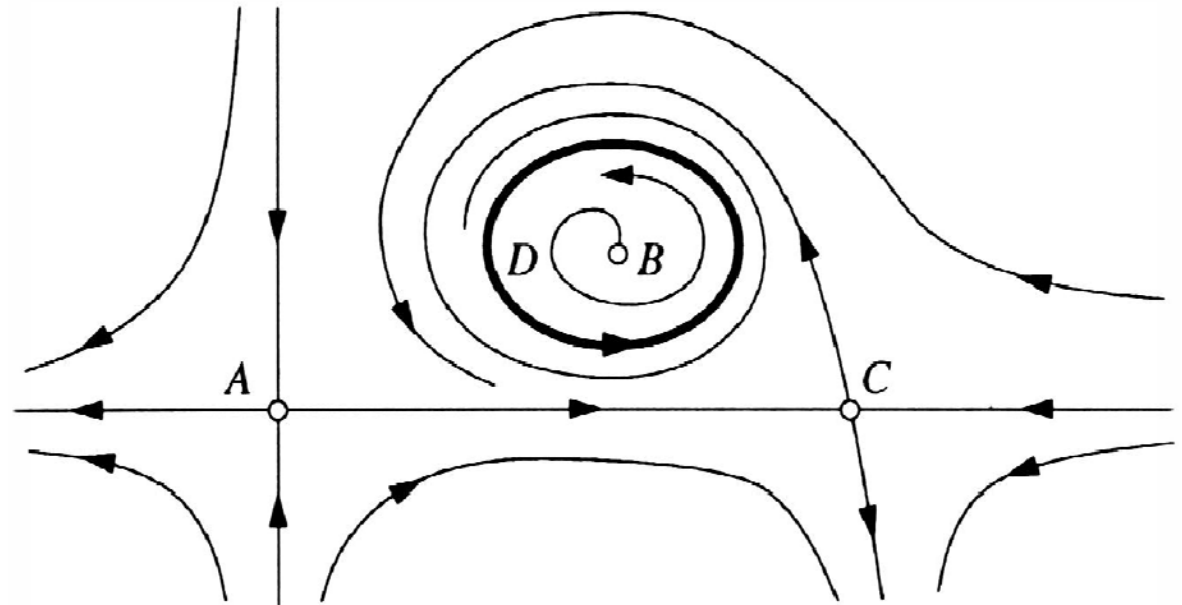
# Line Integral Convolution on Surfaces



# Texture Advection – Unsteady Flows

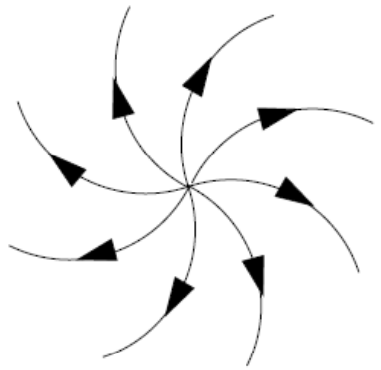


- Extract and visualize the abstract structure of a flow

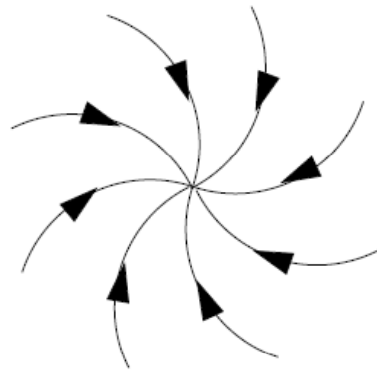


- Different elements
  - ◆ Checkpoints, defined through  $v(x)=0$
  - ◆ Cycles, defined through  $sx(t+T)=sx(t)$
  - ◆ Connecting structures (separatrices, etc.)

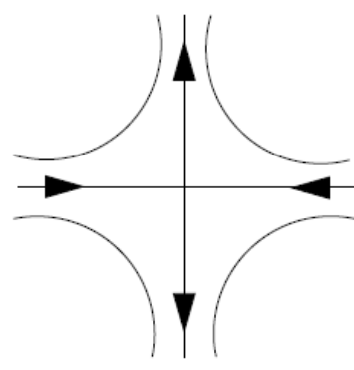




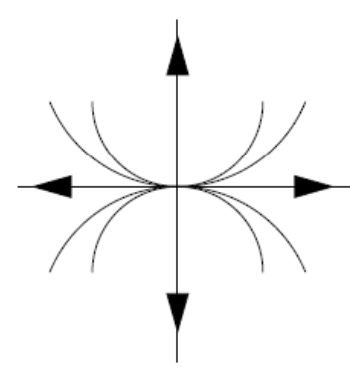
**Repelling Focus**  
 $R_1, R_2 > 0$   
 $I_1, I_2 \neq 0$



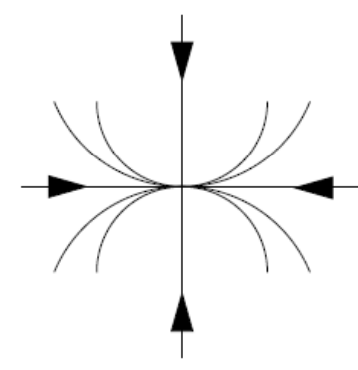
**Attracting Focus**  
 $R_1, R_2 < 0$   
 $I_1, I_2 \neq 0$



**Saddle Point**  
 $R_1 * R_2 < 0$   
 $I_1, I_2 = 0$



**Repelling Node**  
 $R_1, R_2 > 0$   
 $I_1, I_2 = 0$

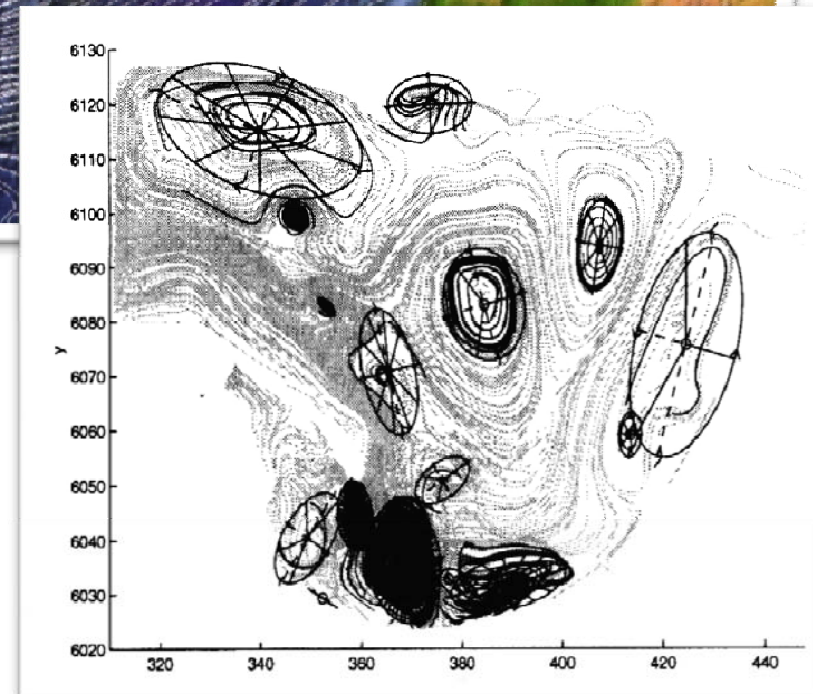
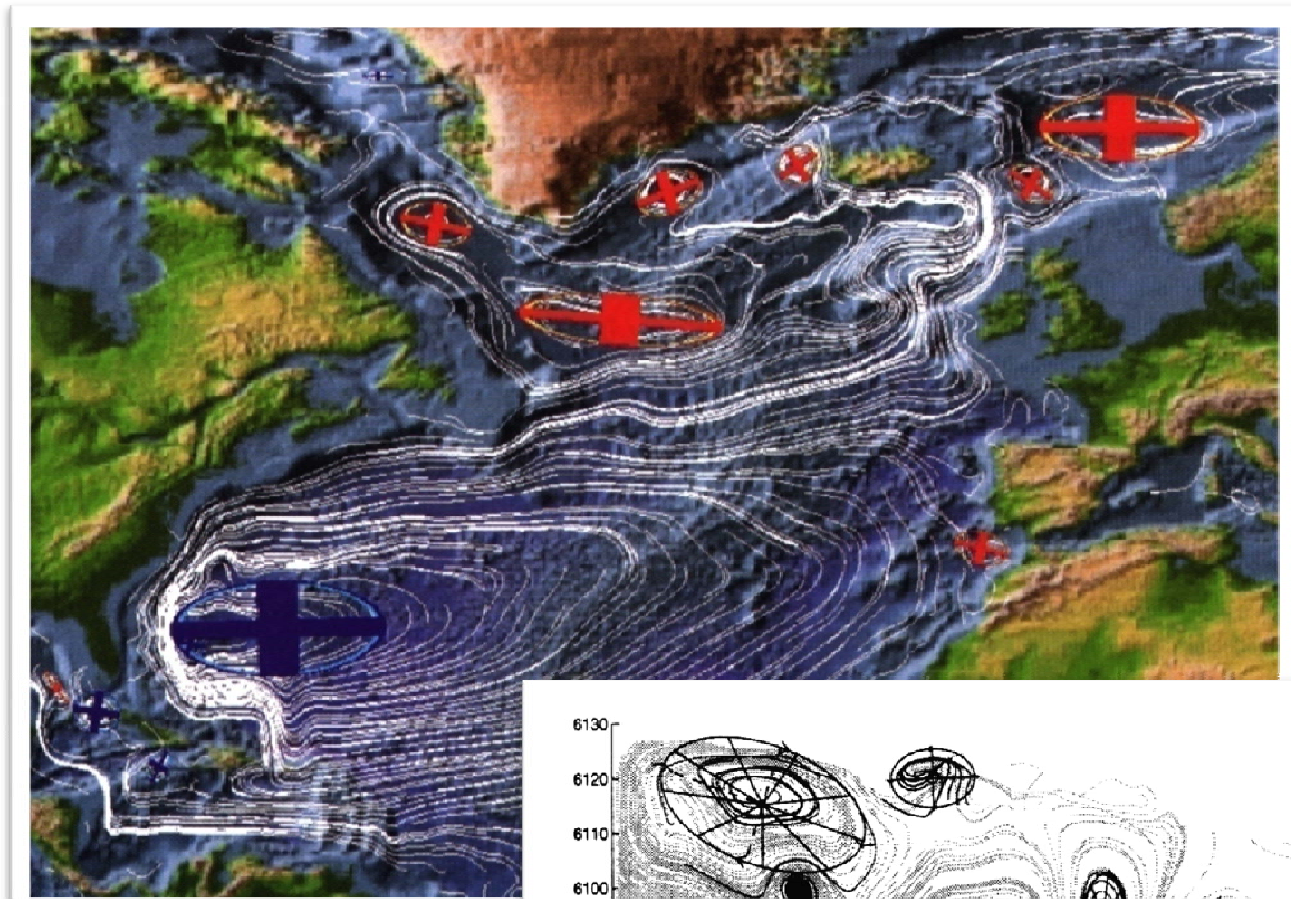
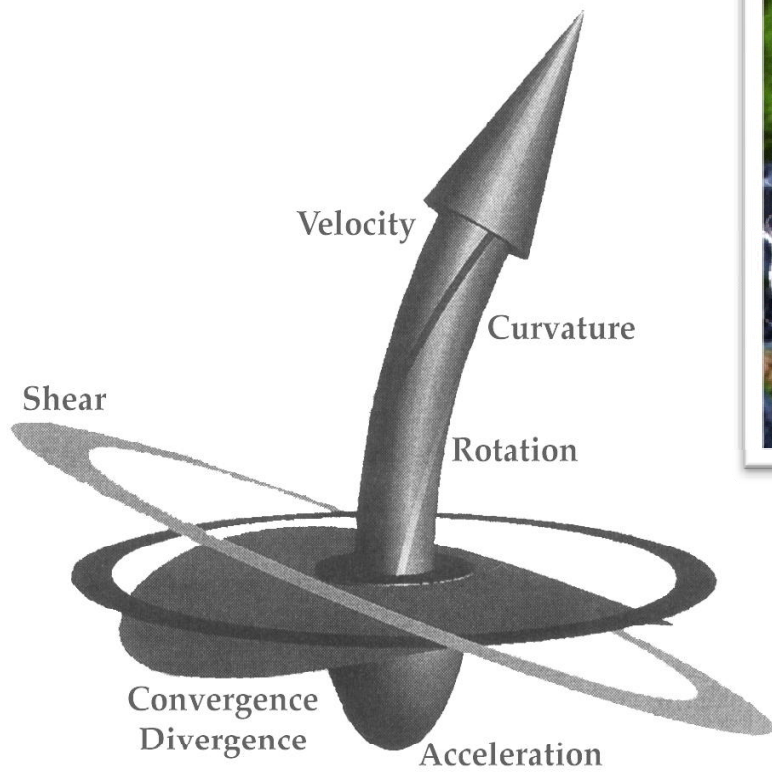


**Attracting Node**  
 $R_1, R_2 < 0$   
 $I_1, I_2 = 0$

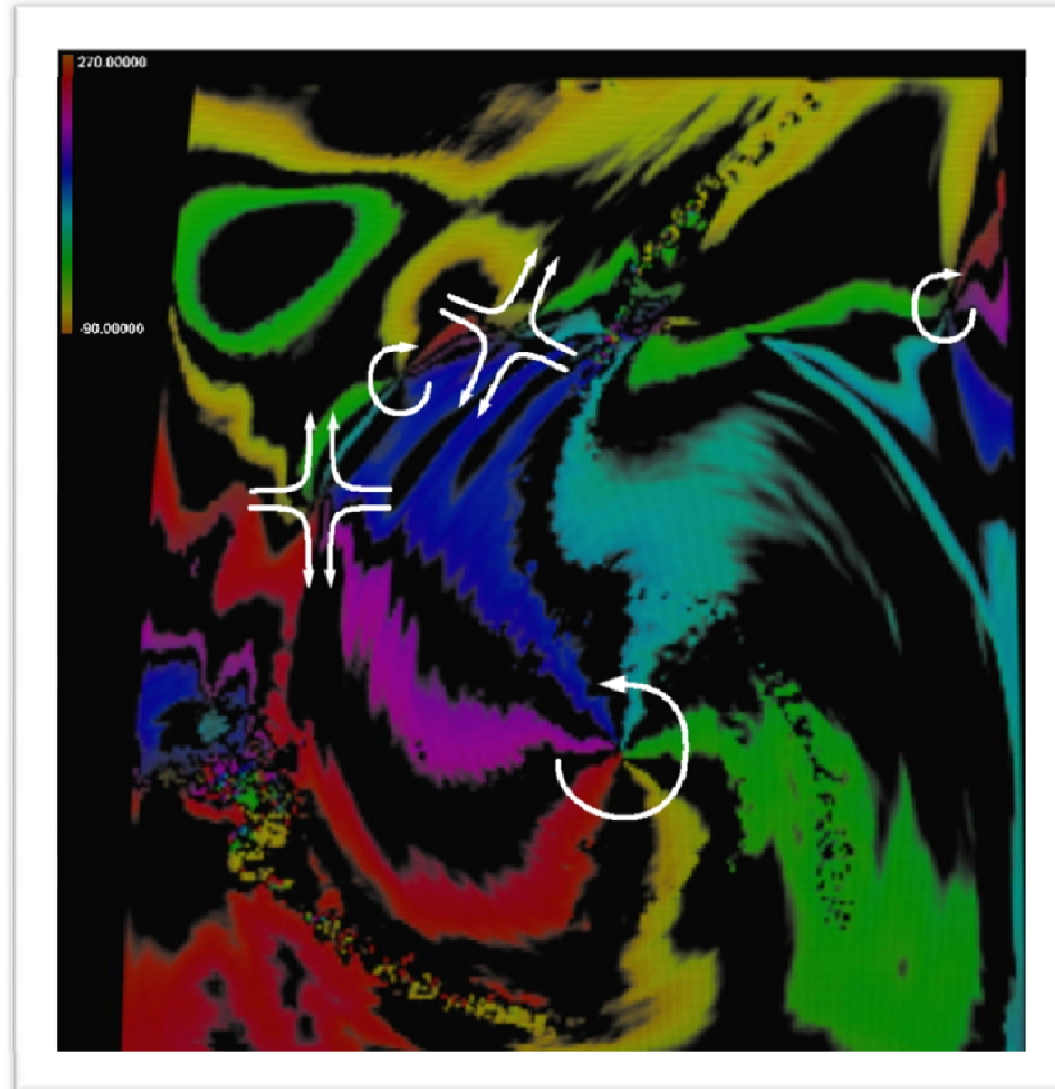
- Critical points can be classified by the Eigenvalues of the Jacobian  
R = real components, I = imaginary components



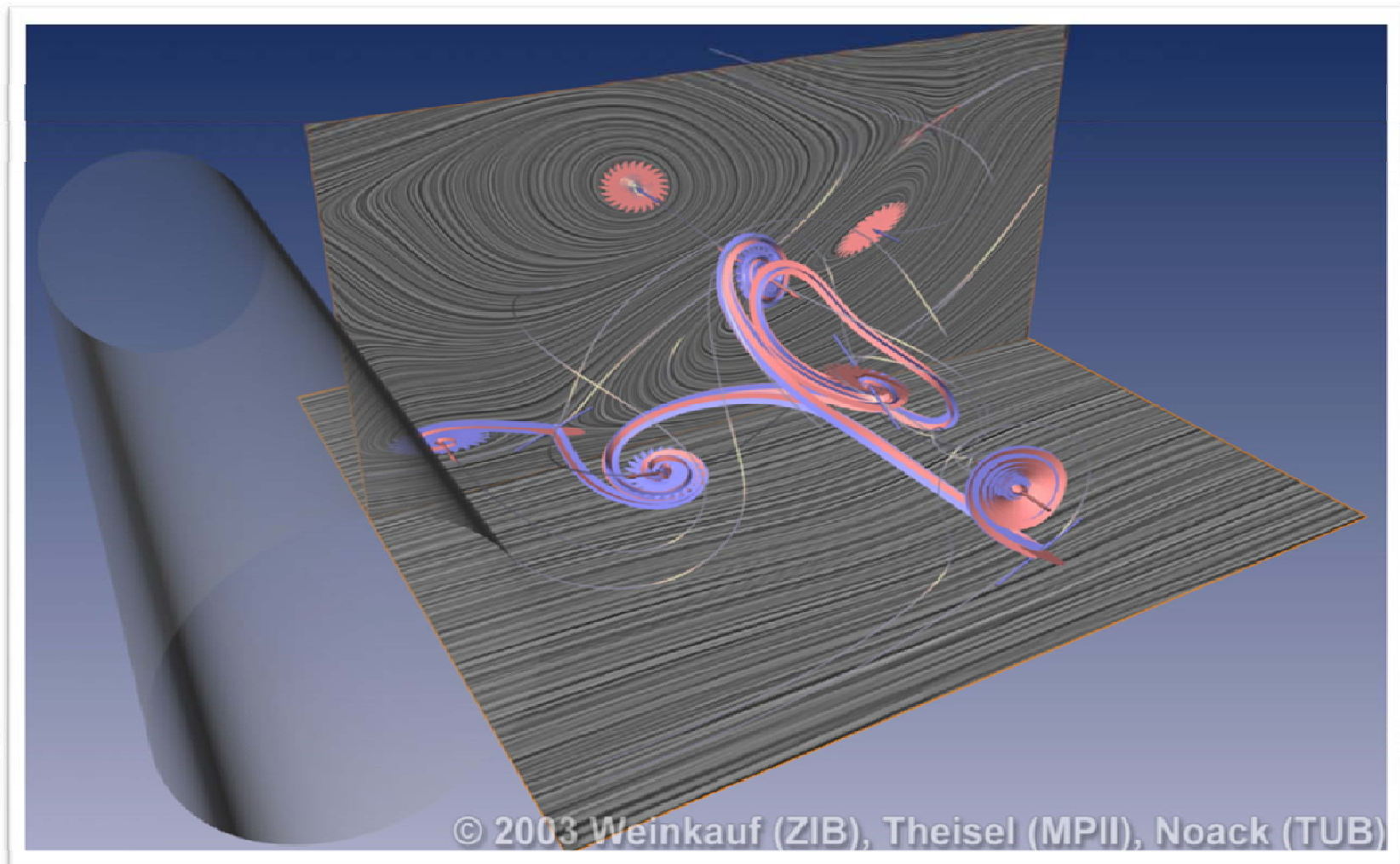
- Local/topological properties



- Topology of a hurricane simulation



- Visualization of flow past a circular cylinder using critical points and saddle connectors



- R. Laramee, H. Hauser, H. Doleisch, B. Vrolijk, F. Post, D. Weiskopf. The State of the Art in Flow Visualization: Dense and Texture-Based Techniques. *Computer Graphics Forum*, 23(2):203-221, 2004.
- F. Post, B. Vrolijk, H. Hauser, R. Laramee, H. Doleisch. The State of the Art in Flow Visualization: Feature Extraction and Tracking. *Computer Graphics Forum*, 22(4):775-792, 2003.



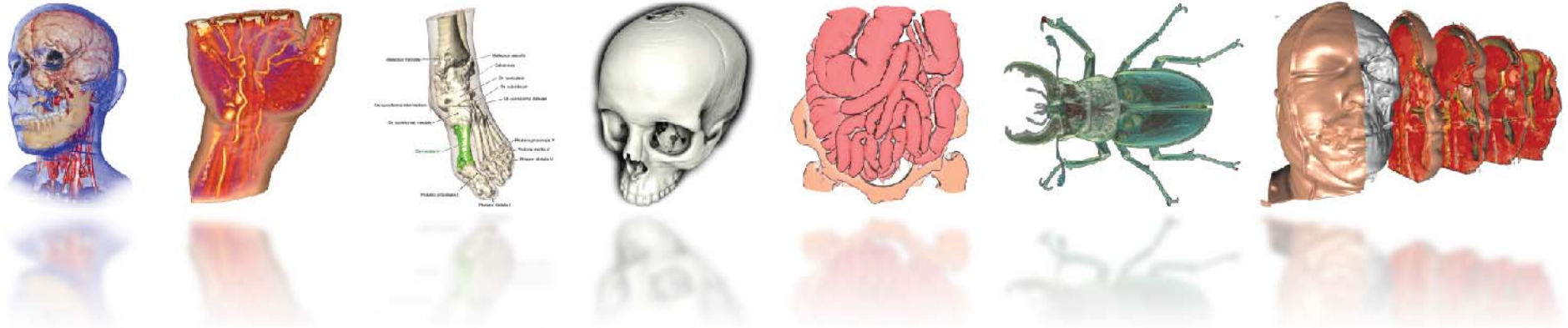


- Scientific visualization is data-driven, but it is crucial to keep the goal of the user in mind
- **Volume visualization**  
3D scalar data
  - ◆ Important to provide detailed view of structures of interest
- **Flow visualization**  
2D/3D vector data
  - ◆ Provide overview and characterize flow behavior



# Thank you for your attention!

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## Acknowledgements

Meister Eduard Gröller

Heliwg Hauser

Christof Rezk-Salama

