

University of British Columbia CPSC 314 Computer Graphics May-June 2005

Tamara Munzner
Animation, Advanced Rendering,
Final Review

Week 6, Tue Jun 14

http://www.ugrad.cs.ubc.ca/~cs314/Vmay2005

News

- P4 grading
 - 4:30-5:45 Wed Jun 22

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Review: Volume Graphics

- for some data, difficult to create polygonal mesh
- voxels: discrete representation of 3D object
- volume rendering: create 2D image from 3D object
- translate raw densities into colors and transparencies
 - different aspects of the dataset can be emphasized via changes in transfer functions









Review: Volume Graphics

- pros
 - formidable technique for data exploration
- cons
 - rendering algorithm has high complexity!
 - special purpose hardware costly (~\$3K-\$10K)









Review: Isosurfaces

- 2D scalar fields: isolines
 - contour plots, level sets
 - topographic maps
- 3D scalar fields: isosurfaces

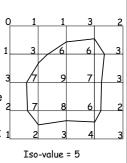


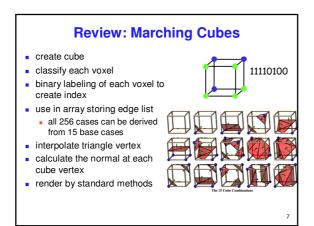


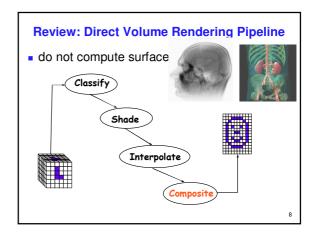


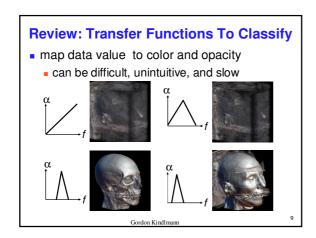
Review: Isosurface Extraction

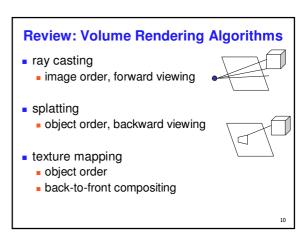
- array of discrete point samples at grid points
 - 3D array: voxels
- find contours
 - closed, continuous
 - determined by iso-value
- several methods
 - marching cubes is most 1 common

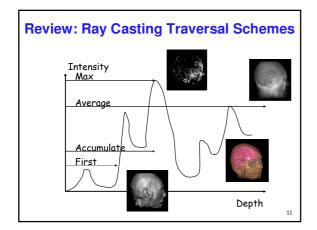






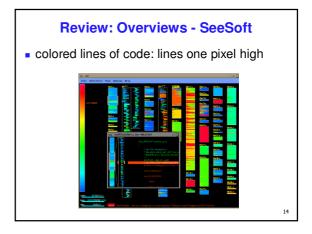


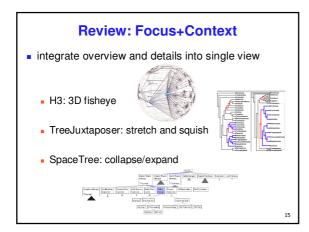


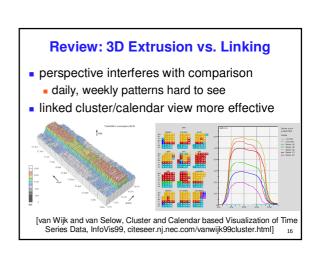


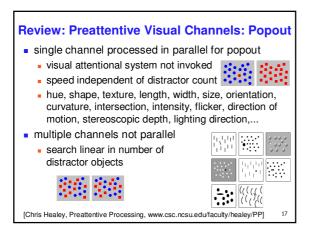
Review: Information Visualization interactive visual representation of abstract data help human perform some task more effectively bridging many fields graphics: interacting in realtime cognitive psych: finding appropriate representation HCI: using task to guide design and evaluation external representation reduces load on working memory offload cognition familiar example: multiplication/division infovis example: topic graphs

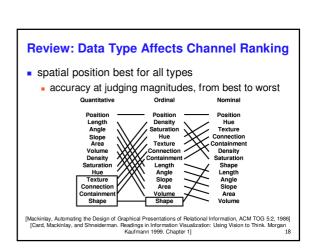










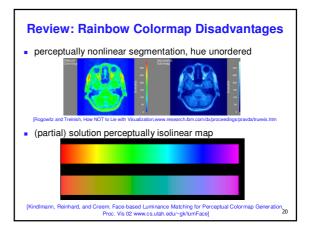


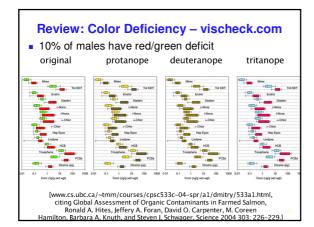


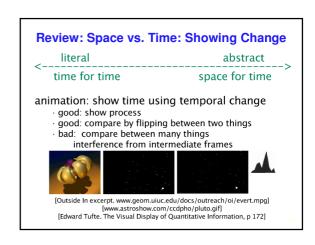
- discrete small patches separated in space
- limited distinguishability: around 8-14
 - channel dynamic range: low
 - choose bins explicitly for maximum mileage
- maximally discriminable colors from Ware
 - maximal saturation for small areas
 - vs. minimal saturation for large areas

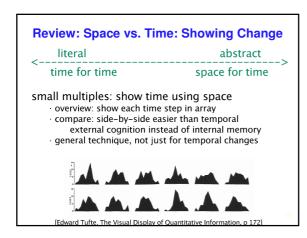


Colin Ware, Information Visualization: Perception for Design. Morgan Kaufmann 1999. Figure 4.21]









Animation

(slides based on Robert Bridson's CPSC 426 preview)
www.ugrad.cs.ubc.ca/~cs426

Computer Animation

- offline: generate a film, play it back later
- long ago reached the point of being able to render anything an artist could model
- problem is: how to model?
 - tools/UI for directly specifying model+motion (the traditional technique)
 - procedural modeling (e.g. particle systems)
 - data-driven modeling (e.g. motion capture)
 - physics-based modeling (e.g. fluid simulation)

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Real-Time Animation

- for example, games
- rendering limited, modeling even more limited
- "traditional" technique replay scripted motions
 - but scalability/realism are becoming a problem
 - need to generate more new motion on the fly

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Traditional CG Animation

- Grew out of traditional animation
- [Pixar]
- every detail of every model is parameterized
 - e.g. position and orientation of base of lamp, joint angles, lengths, light intensity, control points for spline curve of power cord, ...
- associate a "motion curve" with each parameter how it changes in time
- animating == designing motion curves

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Motion Curves

- keyframe approach:
 - artist sets extreme values at important frames
 - computer fills in the rest with splines
 - artist adjusts spline controls, slopes, adds more points, adjusts, readjusts, re-readjusts, ...
- straight-ahead approach:
 - artist simply sets parameters in each successive frame
- layering approach:
 - design the basic motion curves first, layer detail on afterwards

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Motion Curve Tools

- retiming: keep the shape of the trajectory, but change how fast we go along it
 - add a new abstract motion curve controlling distance traveled along trajectory
- Inverse Kinematics (IK):
 - given a skeleton (specified by joint angles)
 - artist directly controls where parts of the skeleton go, computer solves for the angles that achieve that

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Procedural Modeling

- write programs to automatically generate models and motion
- for example, "flocking behaviour"
- build a flock of birds by specifying simple rules of motion:
 - accelerate to avoid collisions
 - accelerate to fly at preferred distance to nearby birds
 - accelerate to fly at same velocity as nearby birds
- accelerate to follow "migratory" impulse
- let it go, hope the results look good

Data-Driven Modeling

- measure the real world, use that data to synthesize models
 - laser scanners
 - camera systems for measuring reflectance properties
 - Image-Based Rendering e.g. Spiderman
 - ...

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Data-Driven Motion

- record real motion (motion capture = mocap)
- then play it back
- but life is never that simple
 - real motion is hard to measure
 - measurements are noisy
 - won't quite fit what you needed
 - not obviously adaptable to new environments, interactive control, etc.

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Marker-Based Mocap

- stick performer in a tight black suit, stick markers on body, limbs, ...
- film motion with an infrared strobe light and multiple calibrated cameras
- reconstruct 3D trajectories of markers, filling in gaps and eliminating noise
- infer motion of abstract skeleton
- clean up data
- drive CG skeleton with recorded motion curves

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What it looks like...





n Popovic's website)

Footskate and Clean Up

- most common problem: footskate
 - feet that in reality were stuck to floor hover and slip around
- fix using IK: determine target footplants, automatically adjust joint angles to keep feet planted
 - often OK to even adjust limb lengths...

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Motion Control

- how do you adapt mocap data to new purposes?
 - motion graphs (remixing)
 - motion parameterization (adjust mocap data)
 - motion texturing (add mocap details to traditional animation)

Motion Graphs

- chop up recorded data into tiny clips
 - aim to cut at common poses
- build graph on clips: connect two clips if the end pose of one is similar to the start pose of another
- then walk the graph
 - figure out smooth transitions from clip to clip
 - navigate a small finite graph instead of infinite space of all possible motions

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Physics-based modeling

- like procedural modeling, only based on laws of physics
- if you want realistic motion, simulate reality
- human motion:
 - specify muscle forces (joint torques), simulate actual motion
 - has to conserve momentum etc.
 - can handle the unexpected (e.g. a tackle)
 - but need to write motion controllers
- passive motion:
 - figure out physical laws behind natural phenomena
 - simulate (close cousin of scientific computing)

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Advanced Rendering

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Reading

- FCG Chapter 9: Ray Tracing
 - only 9.1-9.7
- FCG Chap 22: Image-Based Rendering

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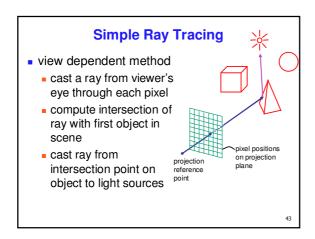
Errata

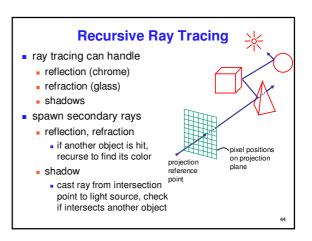
- p 155
 - line 1: p(t)=e+td, not p(t)=o+td
 - equation 5: 2nd term 2d*(e-c), not 2d*(o-e)
- **p** 157
- matrices: c_x->x_c, c_y->y_c, c_z->z_c
- p 162
 - r = d 2(d.n)n, not r = d + 2(d.n)n
- p 163
 - eqn 4 last term: n cos θ not n cos θ'
 - eqn 5: no θ term at end

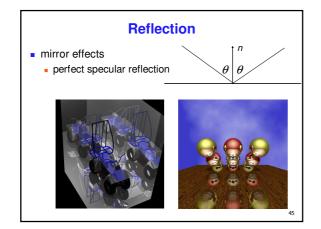
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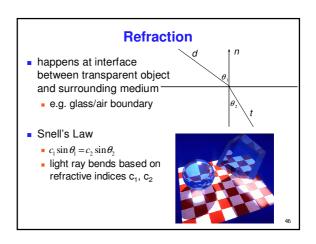
Global Illumination Models

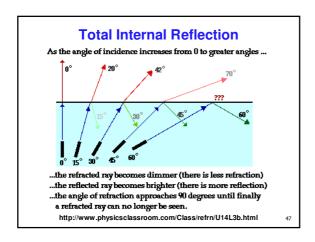
- simple shading methods simulate local illumination models
 - no object-object interaction
- global illumination models
 - more realism, more computation
- approaches
 - ray tracing
 - subsurface scattering
 - radiosity

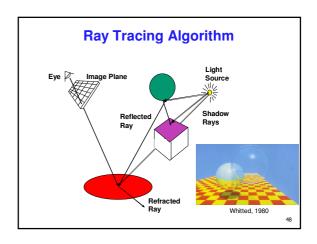












Basic Ray Tracing Algorithm

Algorithm Termination Criteria

- termination criteria
 - no intersection
 - reach maximal depth
 - number of bounces
 - contribution of secondary ray attenuated below threshold
 - each reflection/refraction attenuates ray

Ray - Sphere Intersection

• ray: $x(t) = p_x + v_x t$, $y(t) = p_y + v_y t$, $z(t) = p_z + v_z t$

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Ray - Object Intersections

- inner loop of ray-tracing
 - must be extremely efficient
- solve a set of equations
 - ray-sphere
 - ray-triangle
 - ray-polygon

quadratic equation in t:

• unit sphere: $x^2 + y^2 + z^2 = 1$

$$0 = (p_x + v_x t)^2 + (p_y + v_y t)^2 + (p_z + v_z t)^2 - 1$$

$$= t^2 (v_x^2 + v_y^2 + v_z^2) + 2t(p_x v_x + p_y v_y + p_z v_z)$$

$$+ (p_x^2 + p_y^2 + p_z^2) - 1$$

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Optimized Ray-Tracing

- basic algorithm simple but very expensive
- optimize by reducing:
 - number of rays traced
 - number of ray-object intersection calculations
- methods
 - bounding volumes: boxes, spheres
 - spatial subdivision
 - uniform
 - BSP trees
- (not required reading)

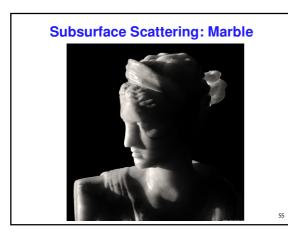


Subsurface Scattering: Translucency

- light enters and leaves at different locations on the surface
 - bounces around inside
- technical Academy Award, 2003
 - Jensen, Marschner, Hanrahan



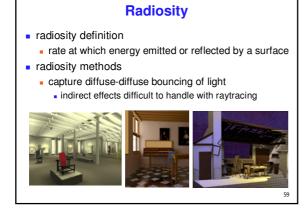


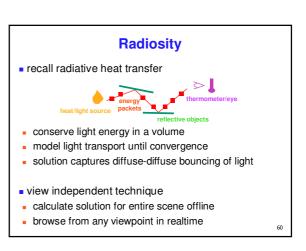














- divide surfaces into small patches
- loop: check for light exchange between all pairs
 - form factor: orientation of one patch wrt other patch (n x n matrix)



Raytracing vs. Radiosity Comparison

- ray-tracing: great specular, approx. diffuse
 - view dependent
- radiosity: great diffuse, specular ignored
 - view independent, mostly-enclosed volumes
- advanced hybrids: combine them





radiosity

Image-Based Rendering

- store and access only pixels
 - no geometry, no light simulation, ...
 - input: set of images
 - output: image from new viewpoint
 - surprisingly large set of possible new viewpoints







IBR Characteristics

- display time not tied to scene complexity
 - expensive rendering or real photographs
- massive compression possible (120:1)





- can point camera in or out
 - QuickTimeVR: camera rotates, no translation

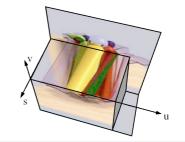
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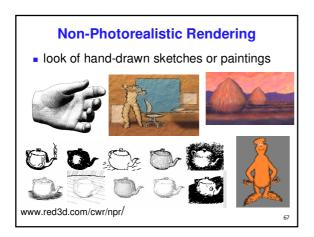
Characterizing Light

- 7D plenoptic function: $P(x, y, z, \theta, \phi, \lambda, t)$
 - (x,y,z): every position in space
 - (θ, φ): every angle
 - λ: every wavelength of light
 - t: every time
- can simplify to 4D function
 - fix time: static scene
 - fix wavelength: static lighting
 - partially fix position: empty space between camera and object

4D Light Field / Lumigraph

- P(u,v,s,t)
 - images: just one kind of 2D slice







Advanced Rendering

- so many more algorithms, so little class time!
 - Renderman REYES
 - photon mapping
 - and lots more...

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Final Review

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Final Logistics

- 12:0pm-2:30pm Thu Jun 16 here (MCLD 202)
- notes: both sides 8.5"x11" handwritten page
- calculator OK if you want
- have photo ID face up on desk
- spread out, sit where there is an exam

Reading from OpenGL Red Book

- 1: Introduction to OpenGL
- 2: State Management and Drawing Geometric Objects
- 3: Viewing
- 4: Display Lists
- 6: Lighting
- 9: Texture Mapping
- 12: Selection and Feedback
- 13: Now That You Know
 - only section Object Selection Using the Back Buffer
- Appendix: Basics of GLUT (Aux in v 1.1)
- Appendix: Homogeneous Coordinates and Transformation Matrices

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Reading from Shirley: Foundations of CG

- 2: Misc Math
- 3: Raster Algs
- except for 3.8
- 4: Linear Algebra
 - only 4.1-4.2.5
- 5: Transforms
- except 5.1.6
- 2 V/ '
- 6: Viewing
- 7: Hidden Surfaces
- 8: Surface Shading
- 9: Ray Tracing
 - only 9.1-9.7

- 10: Texture Mapping
- 11: Graphics Pipeline
- only 11.1-11.4
- 12: Data Structures
- only 12.3
- 13: Curves and Surfaces
- 17: Human Vision
- 18: Color
 - only 18.1-18.8
- 22: Image-Based Rendering
- 23: Visualization

Studying Advice

- do problems!
 - work through old homeworks, exams

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Midterm Topics Covered

- rendering pipeline
- projective rendering pipeline
 - coordinate systems
- transformations
- viewing
- projections

Review: Rendering Pipeline

• pros and cons of pipeline approach

Geometry
Database

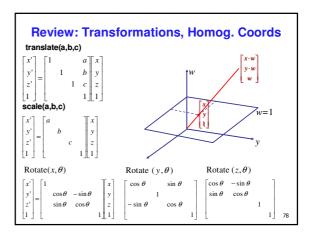
Transform.

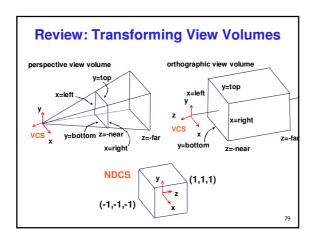
Lighting
Perspective
Transform.
Clipping
Frame-buffer

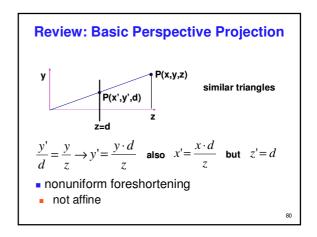
Test

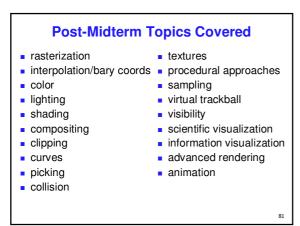
Blending
Frame-buffer

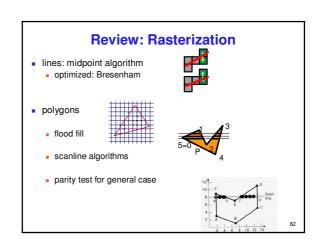
Review: Projective Rendering Pipeline glVertex3f(x,y,z) viewing/ object world camera ocs wcs vcs projection modelina viewina transformation transformation clipping glTranslatef(x,y,z) gluLookAt(...) CCS glRotatef(th,x,y,z) perspective division OCS - object coordinate system glutlnitWindowSiz normalized device NDCS WCS - world coordinate system glViewport(x,y,a,b) viewport VCS - viewing coordinate system transformation CCS - clipping coordinate system device DCS NDCS - normalized device coordinate system DCS - device coordinate system

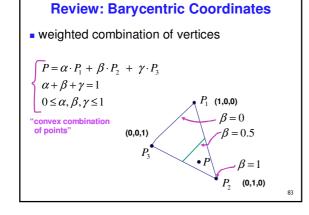


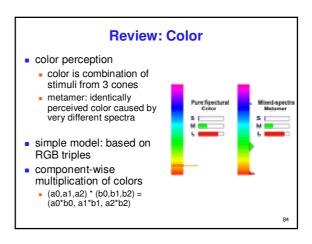


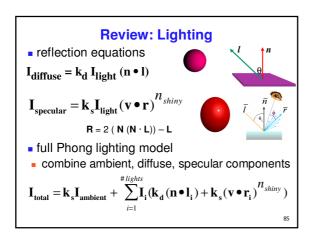






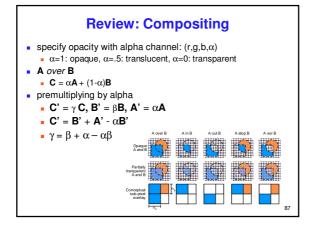


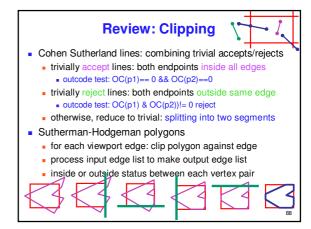


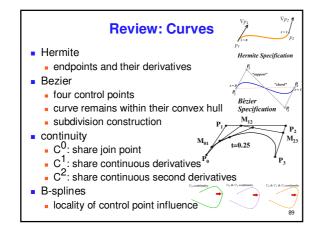


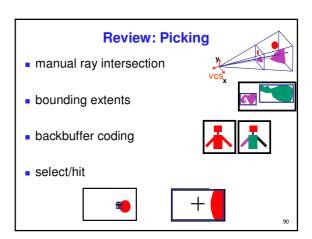


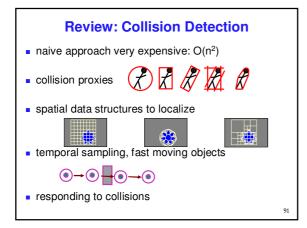
- flat shading
 - compute Phong lighting once for entire polygon
- Gouraud shading
 - compute Phong lighting at the vertices and interpolate lighting values across polygon
- Phong shading
 - compute averaged vertex normals
 - interpolate normals across polygon and perform Phong lighting across polygon

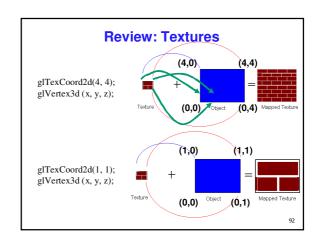


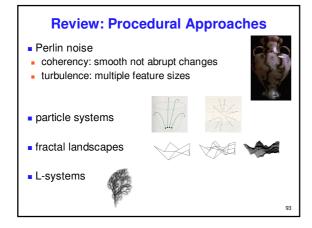


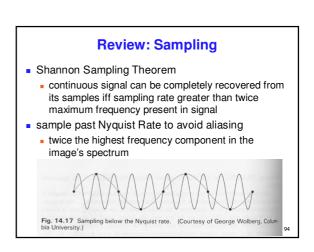


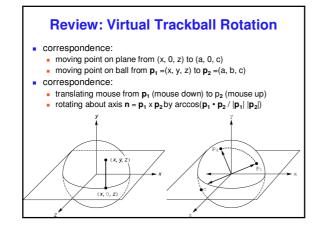


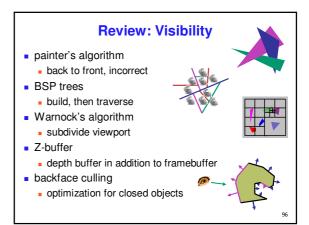












Review: Scientific Visualization

- volume graphics
- isosurfaces
 - extracting with Marching Cubes
- direct volume rendering
 - transfer functions to classify

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Review: Information Visualization

- interactive visual representation of abstract data
 - help human perform some task more effectively
- techniques
 - overview, zoom and filter, details on demand
 - focus+context
 - linked views
 - small multiples
- visual channels
 - preattentive visual popout
 - categorical, ordered, quantitative data types

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Review: Animation

- traditional direct specification of motion curves
 - key framing: straight-ahead, layering
 - retiming
- inverse kinematics
- procedural modeling
 - particle systems
- data-driven modeling
 - motion capture
- physics-based modeling
 - cloth, fluid simulation

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Review: Advanced Rendering

- ray tracing
 - reflection, refraction, hard shadows
- subsurface scattering
 - marble, milk
- radiosity
 - diffuse lighting, soft shadows
- image-based rendering
 - store/access only pixels





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Other Graphics Courses

- 424: Geometric Modelling
 - not offered next year
- 426: Computer Animation
 - will be offered next year
- 514: Image-Based Rendering Heidrich
- 526: Algorithmic Animation- van de Panne
- 533A: Digital Geometry Sheffer
- 533B: Animation Physics Bridson
- 533C: Information Visualization Munzner