



University of British Columbia  
CPSC 314 Computer Graphics  
May-June 2005

Tamara Munzner

**Intro, Math Review, OpenGL Pipeline**

**Week 1, Tue May 10**

<http://www.ugrad.cs.ubc.ca/~cs314/Vmay2005>

# Introduction

# Expectations

- hard course!
  - heavy programming and heavy math
- fun course!
  - graphics programming addictive, create great demos
- programming prereq
  - CPSC 216 (Program Design and Data Structures)
  - course language is C++/C
- math prereq
  - MATH 200 (Calculus III)
  - MATH 221/223 (Matrix Algebra/Linear Algebra)

# Course Structure

- 45% programming projects
  - 9% project 1 (building beasties with cubes and math)
  - 9% project 2 (flying )
  - 9% project 3 (shaded terrain)
  - 18% project 4 (create your own graphics game)
- 25% final
- 15% midterm (week 4, Tue 5/31)
- 15% written assignments
  - 5% each HW 1/2/3
- programming projects and homeworks synchronized



# Programming Projects

- structure
  - C++, Linux
    - OK to cross-platform develop on Windows
  - OpenGL graphics library
  - GLUT for platform-independent windows/UI
  - face to face grading in lab
- Hall of Fame
  - project 1: building beasties
    - previous years: elephants, birds, poodles
  - project 4: create your own graphics game

# Late Work

- 3 grace days
  - for unforeseen circumstances
  - strong recommendation: don't use early in term
  - handing in late uses up automatically unless you tell us
- otherwise: 25% per 24 hours
  - no work accepted after solutions handed out
- exception: severe illness or crisis, as per UBC rules
  - let me know ASAP (in person or email)
  - must also turn in form with documentation

<http://www.ugrad.cs.ubc.ca/~cs314/Vjan2005/illness.html>

# Regrading

- to request assignment or exam regrade
  - must submit detailed written explanation of why you think the grader was incorrect for the particular problem that you are disputing
- I may regrade entire assignment
  - thus even if I agree with your original request, your score may end up higher or lower

# Course Information

- course web page is main resource
  - <http://www.ugrad.cs.ubc.ca/~cs314/Vmay2005>
  - updated often, reload frequently
- newsgroup is `ubc.courses.cpsc.414`
  - note old course number still used
  - readable on or off campus
- (no WebCT)

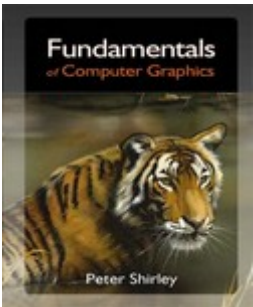
# Labs

- attend two labs per week, 3 sessions each
  - Tue/Thu 11-12, 3-4, 4-5
    - Thursday afternoon better than Thu morning
  - Tuesdays: example problems in spirit of written assignments and exams
  - Thursdays: help with programming projects
  - no deliverables
  - strongly recommend that you attend

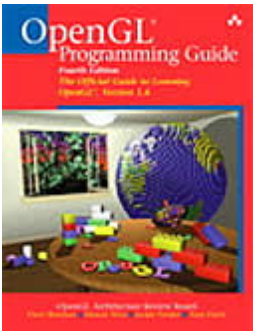
# Teaching Staff

- instructor: Dr. Munzner
  - [tmm@cs.ubc.ca](mailto:tmm@cs.ubc.ca)
  - office hrs in CICSR 011
    - Mon 4:30-5:30
- TAs: Warren Cheung, Greg Kempe
  - [wcheung@cs.ubc.ca](mailto:wcheung@cs.ubc.ca)
  - [kempe@cs.ubc.ca](mailto:kempe@cs.ubc.ca)
- use newsgroup not email for all questions that other students might care about

# Required Reading



- Fundamentals of Computer Graphics
  - Peter Shirley, AK Peters



- OpenGL Programming Guide, v 1.4
  - OpenGL Architecture Review Board
  - v 1.1 **available for free online**
- readings posted on schedule page

# Learning OpenGL

- this is a graphics course using OpenGL
  - not a course \*on\* OpenGL
- upper-level class: learning APIs mostly on your own
  - only minimal lecture coverage
    - basics, some of the tricky bits
  - OpenGL Red Book
  - many tutorial sites on the web
    - [nehe.gamedev.net](http://nehe.gamedev.net)



# Plagiarism and Cheating

- don't cheat, I will prosecute
  - insult to your fellow students and to me
- programming and assignment writeups must be individual work
  - exception: project 3 can be team of two
  - can discuss ideas, browse Web
  - but cannot just copy code or answers
- you must be able to explain algorithms during face-to-face demo
  - or no credit for that part of assignment, possible prosecution

# Citation

- cite all sources of information
  - web sites, study group members, books
  - README for programming projects
  - end of writeup for written assignments
  - <http://www.ugrad.cs.ubc.ca/~cs314/Vmay2005/policies.html#plag>

# What is Computer Graphics?

- create or manipulate images with computer
  - this course: algorithms for image generation

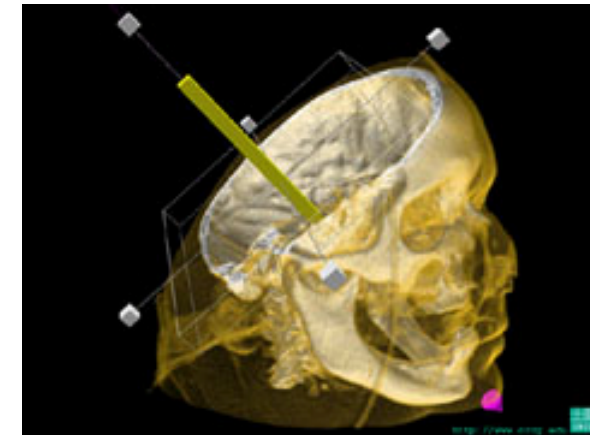
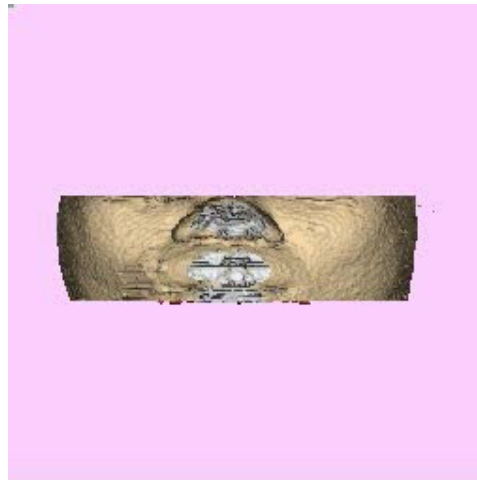
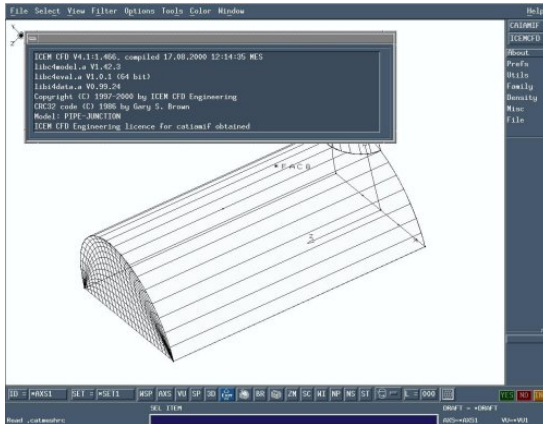
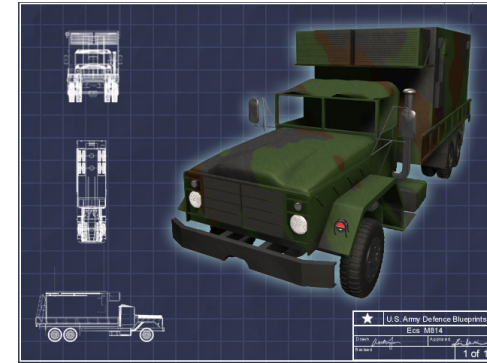


77 K polygons  
24 aera lights  
solution render time : around 7200 sec



# What is CG used for?

- graphical user interfaces
  - modeling systems
  - applications
- simulation & visualization



# What is CG used for?

- movies
  - animation
  - special effects



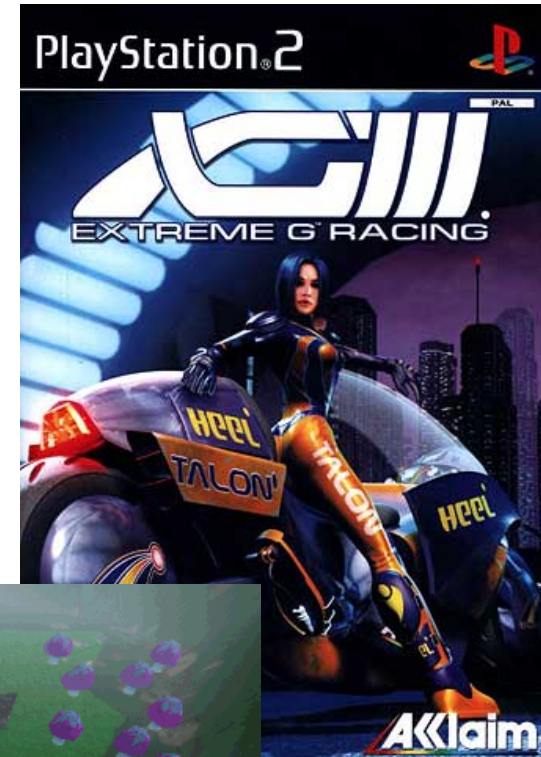
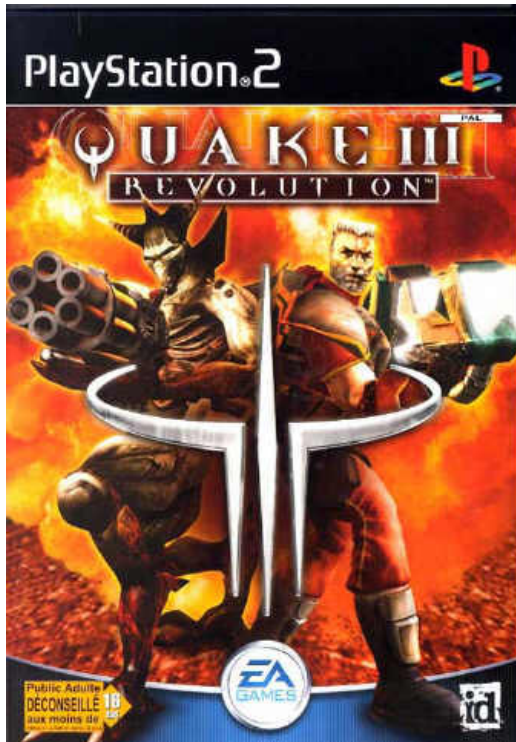
Inspector Gadget © 1999 Walt Disney Pictures.  
Visual Effects by Dream Quest Images.





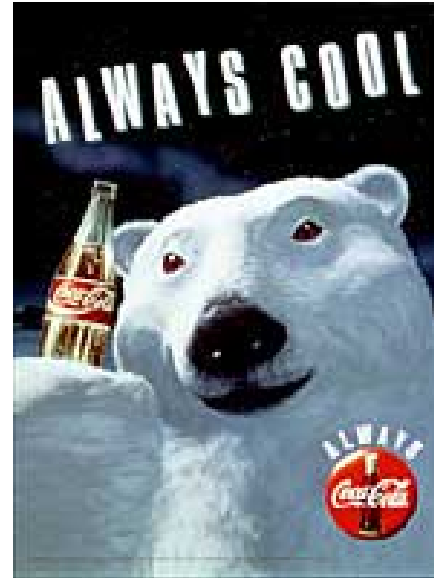
# What is CG used for?

- computer games



# What is CG used for?

- images
  - design
  - advertising
  - art



# What is CG used for?

- virtual reality / immersive displays

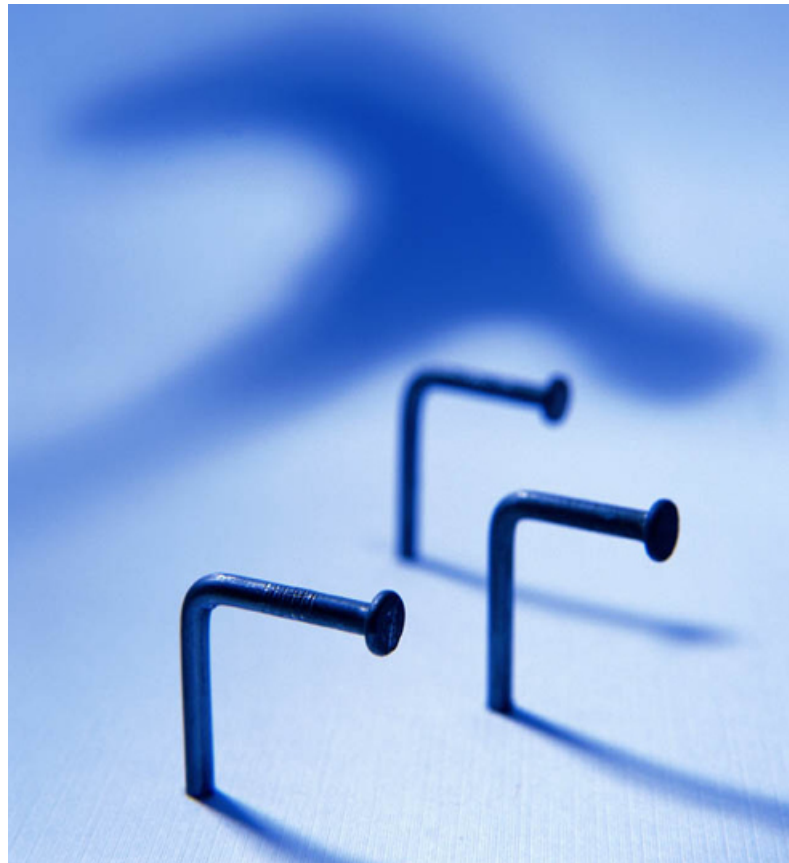




# Real or CG?

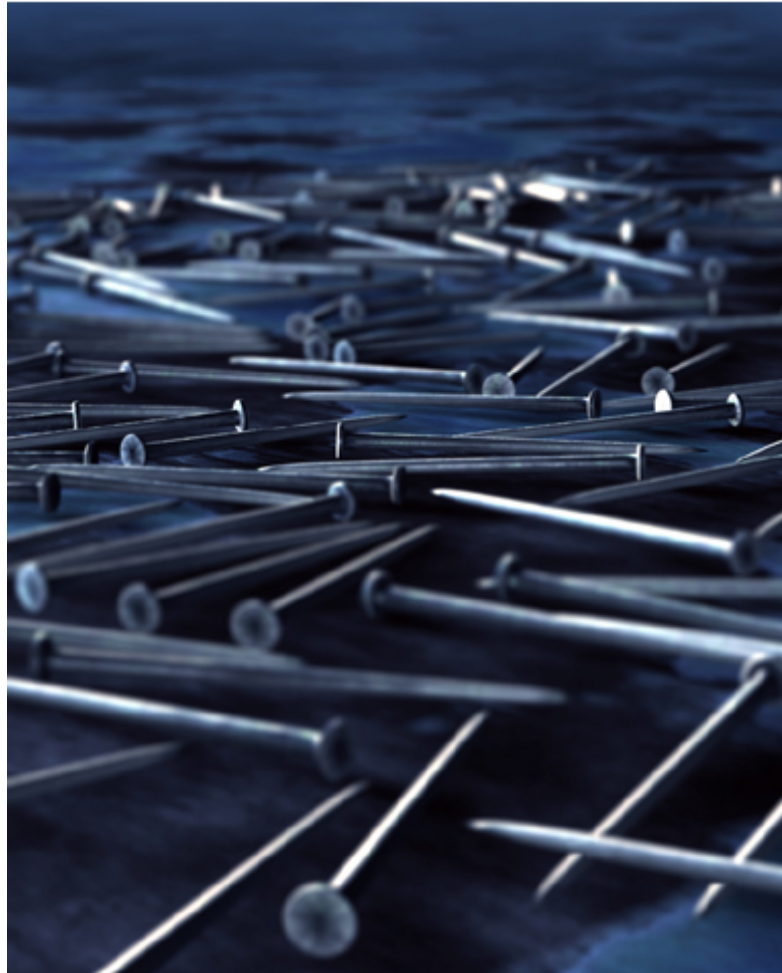
<http://www.alias.com/eng/etc/fakeorfoto/quiz.html>

1



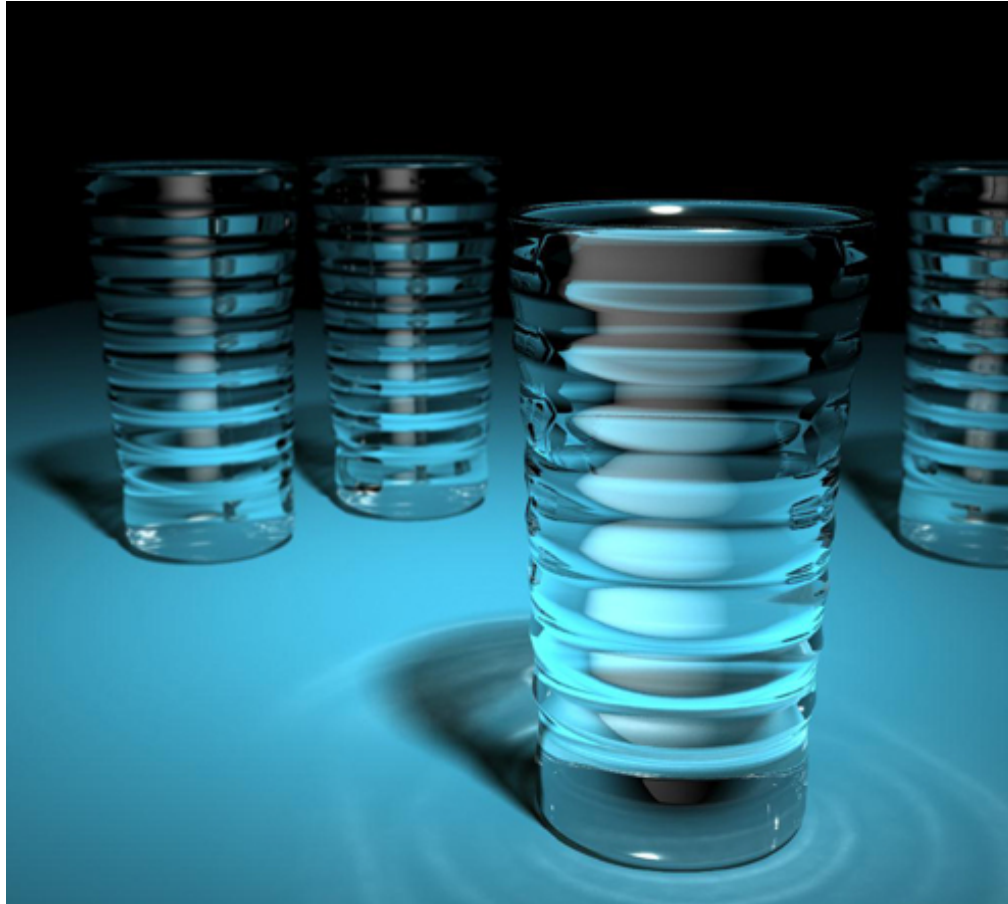
# Real or CG?

2



# Real or CG?

3



# Real or CG?

4



# This Course

- we cover
  - basic **algorithms** for
    - rendering – displaying models
    - (modeling – generating models)
    - (animation – generating motion)
  - programming in OpenGL, C++
- we do not cover
  - art/design issues
  - commercial software packages

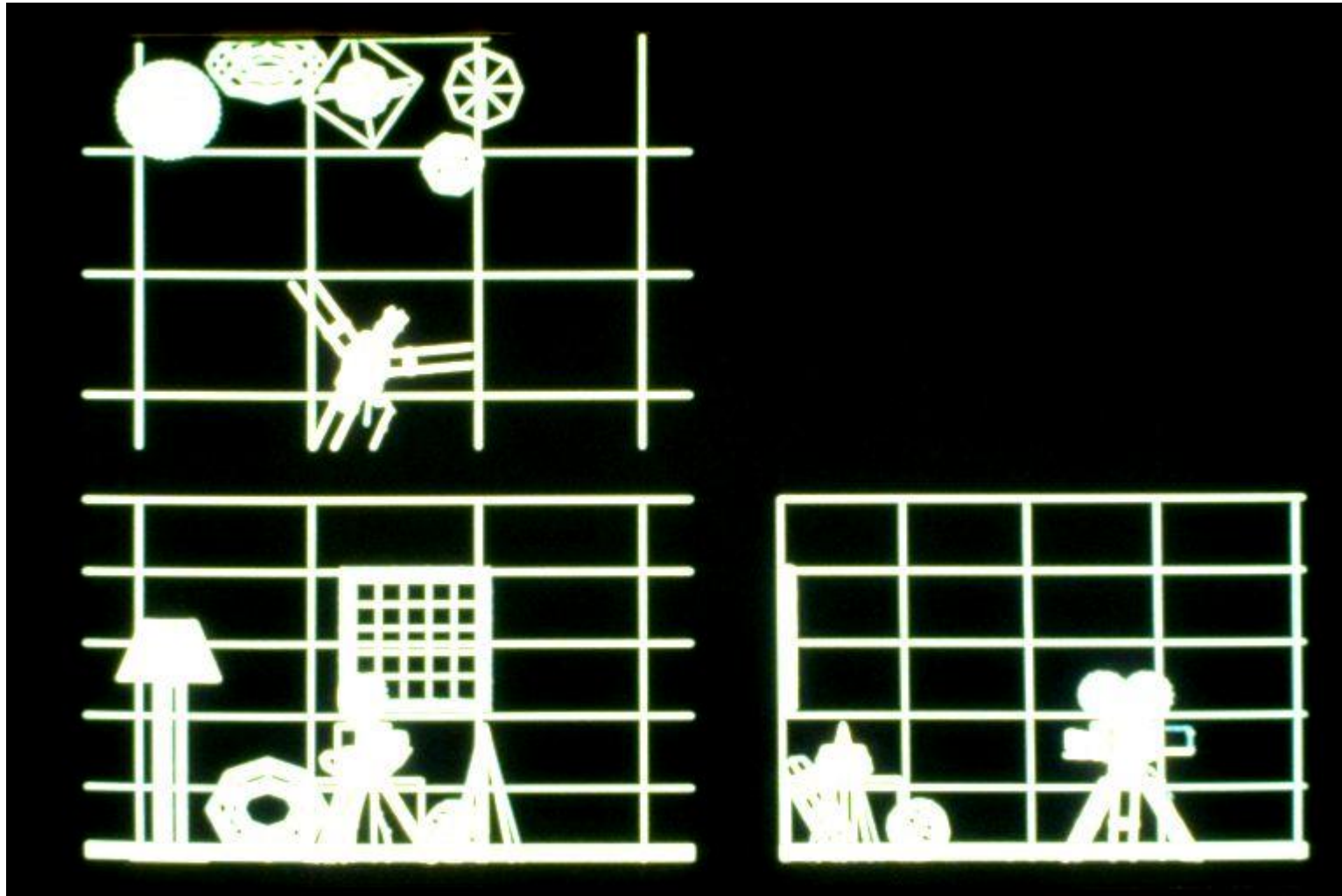
## Other Graphics Courses

- CPSC 424: Geometric Modeling
- CPSC 426: Computer Animation
  
- CPSC 514: Image-based Modeling and Rendering
- CPSC 526: Computer Animation
- CPSC 533A: Digital Geometry
- CPSC 533B: Animation Physics
- CPSC 533C: Information Visualization

# Rendering

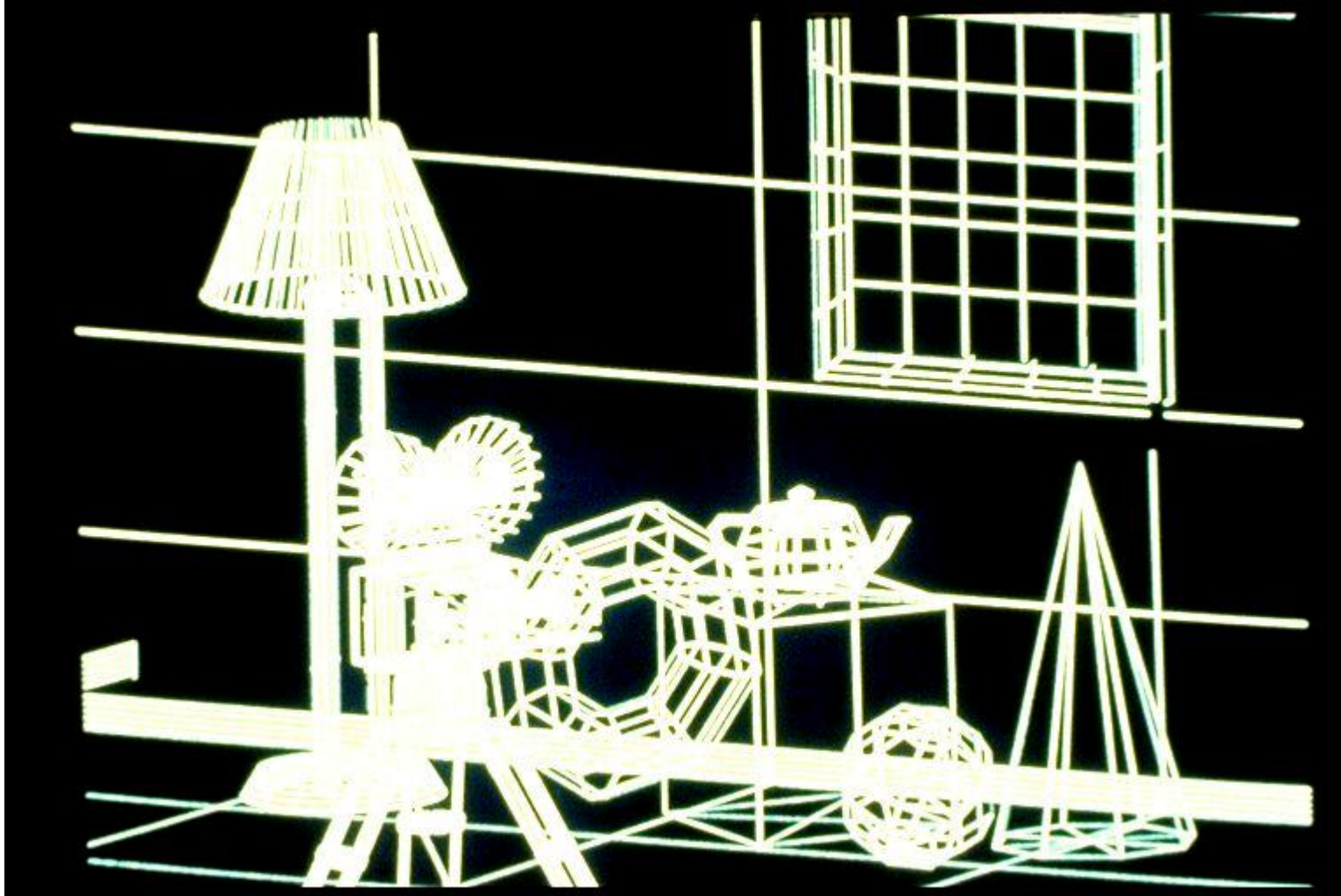
- creating images from models
  - geometric objects
    - lines, polygons, curves, curved surfaces
  - camera
    - pinhole camera, lens systems, orthogonal
  - shading
    - light interacting with material
- Pixar Shutterbug series
  - Williams and Siegel using Renderman, 1990
  - [www.siggraph.org/education/materials/HyperGraph/shutbug.htm](http://www.siggraph.org/education/materials/HyperGraph/shutbug.htm)

# Modelling Transformation: Object Placement

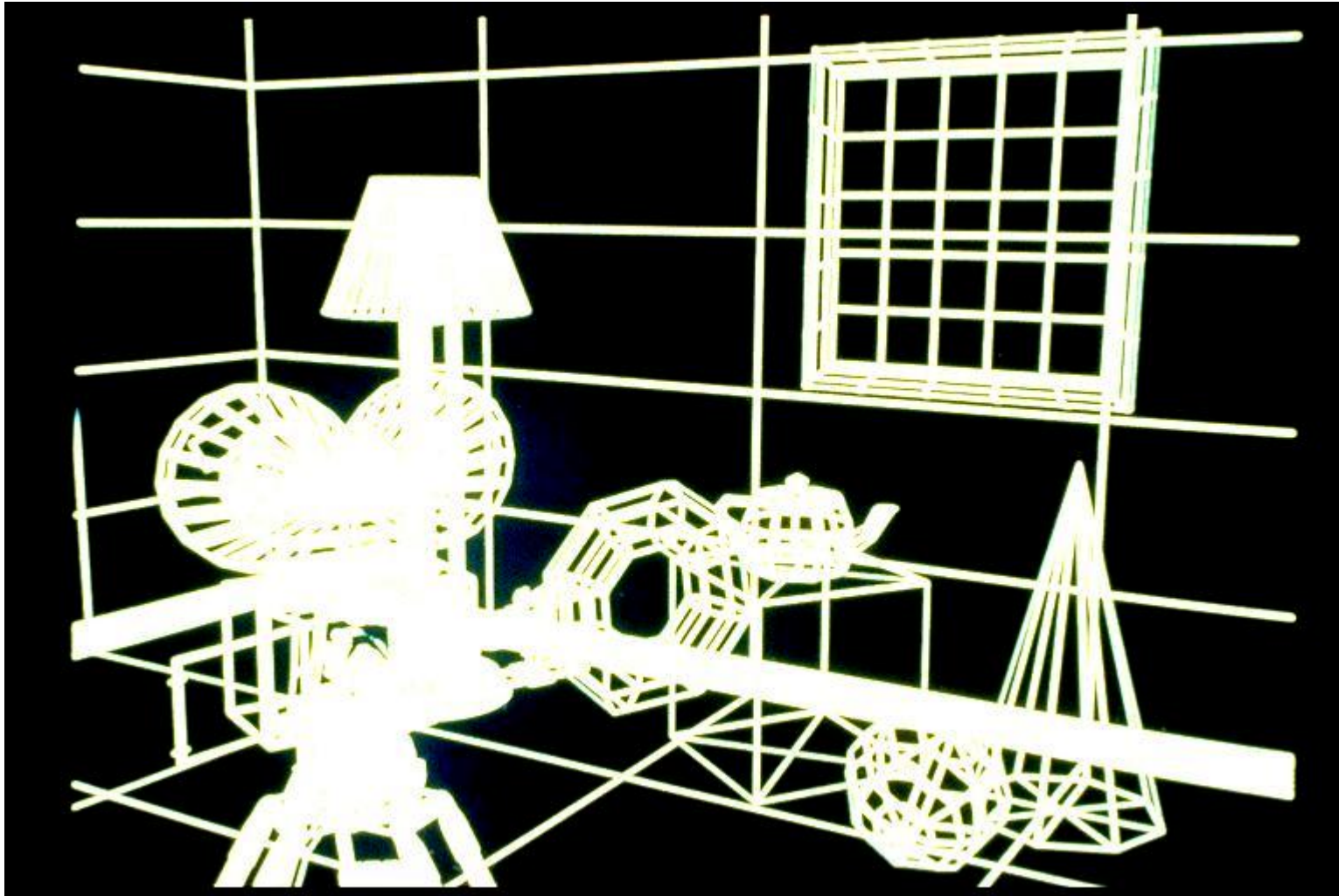




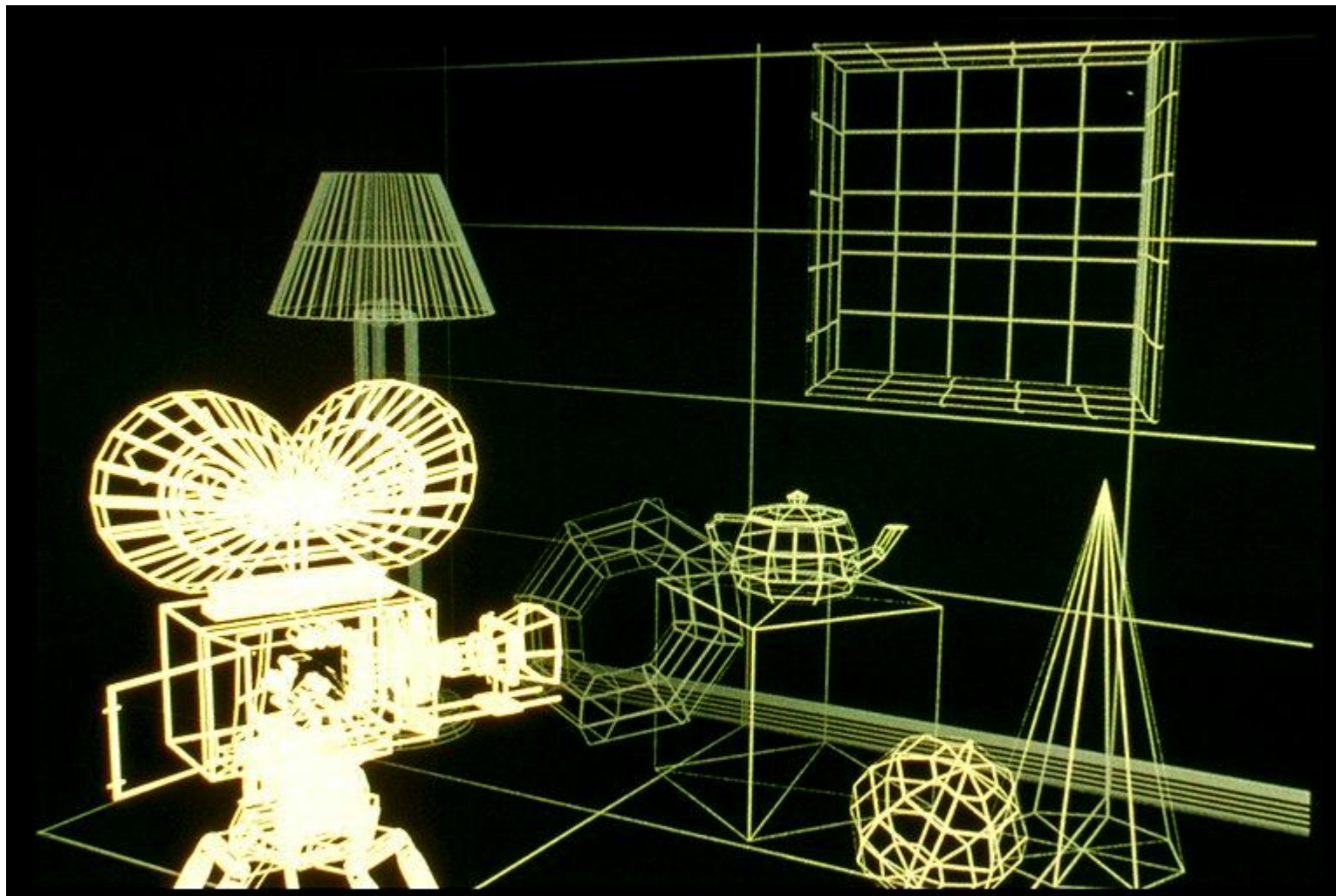
# Viewing Transformation: Camera Placement



# Perspective Projection

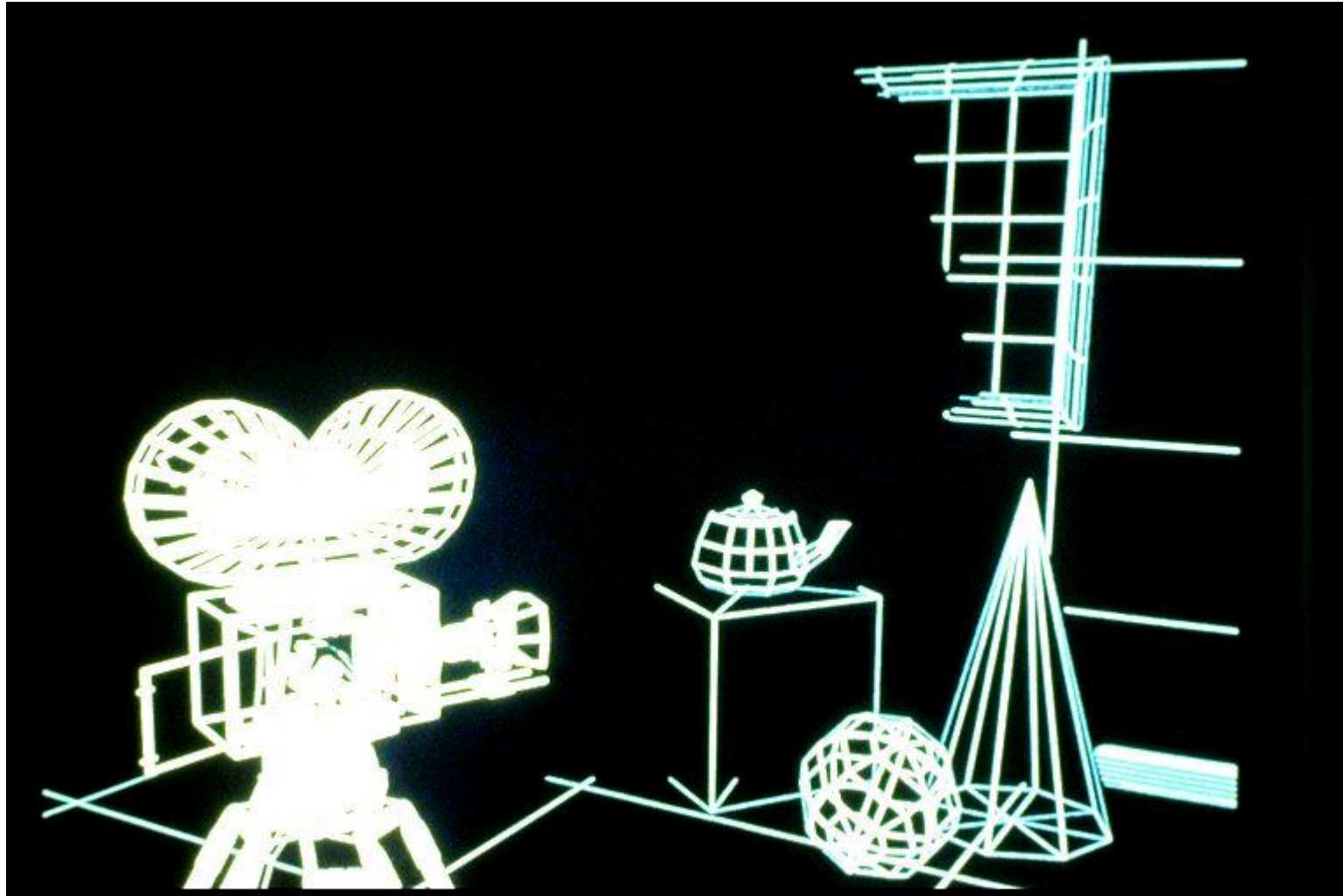


# Depth Cueing

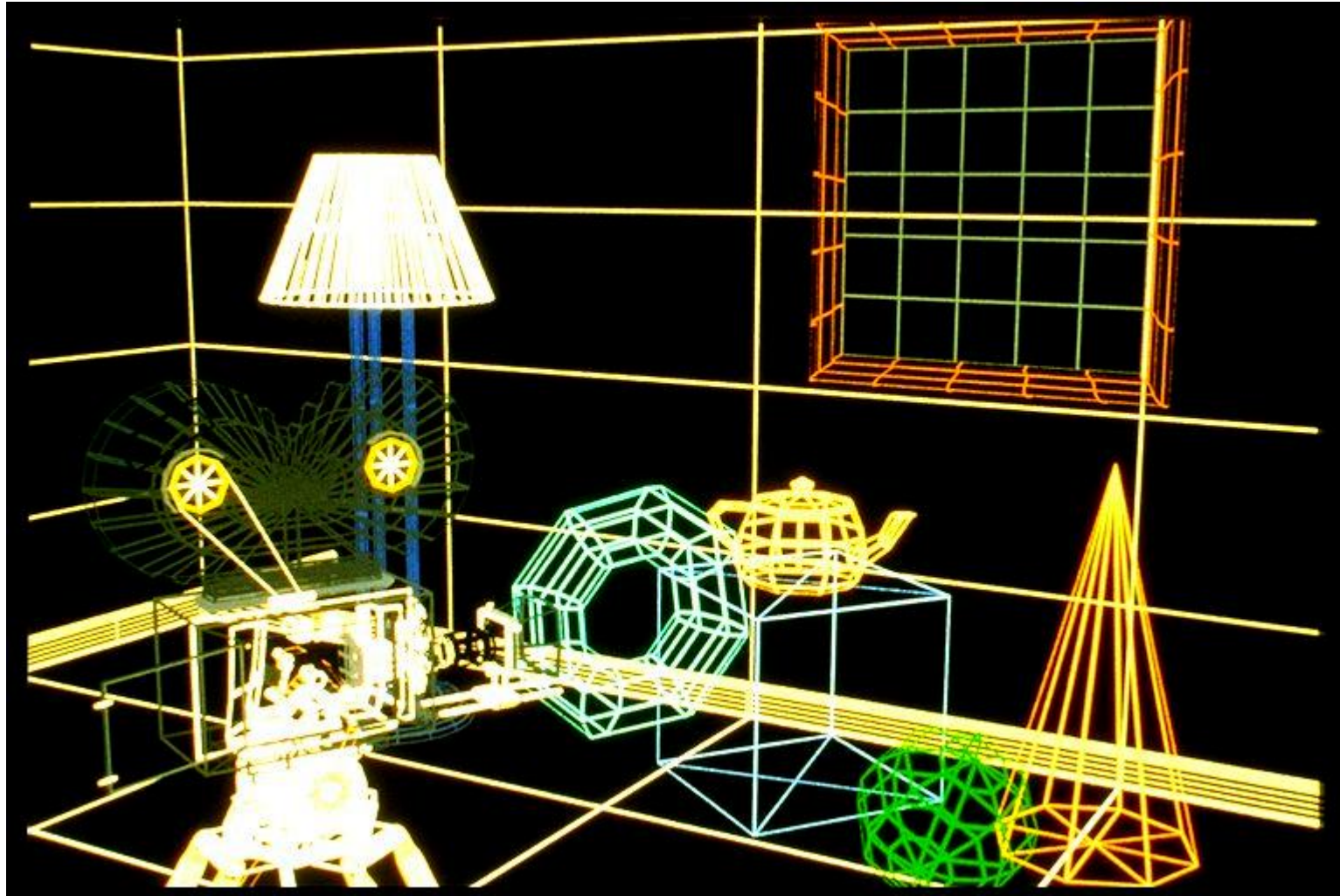




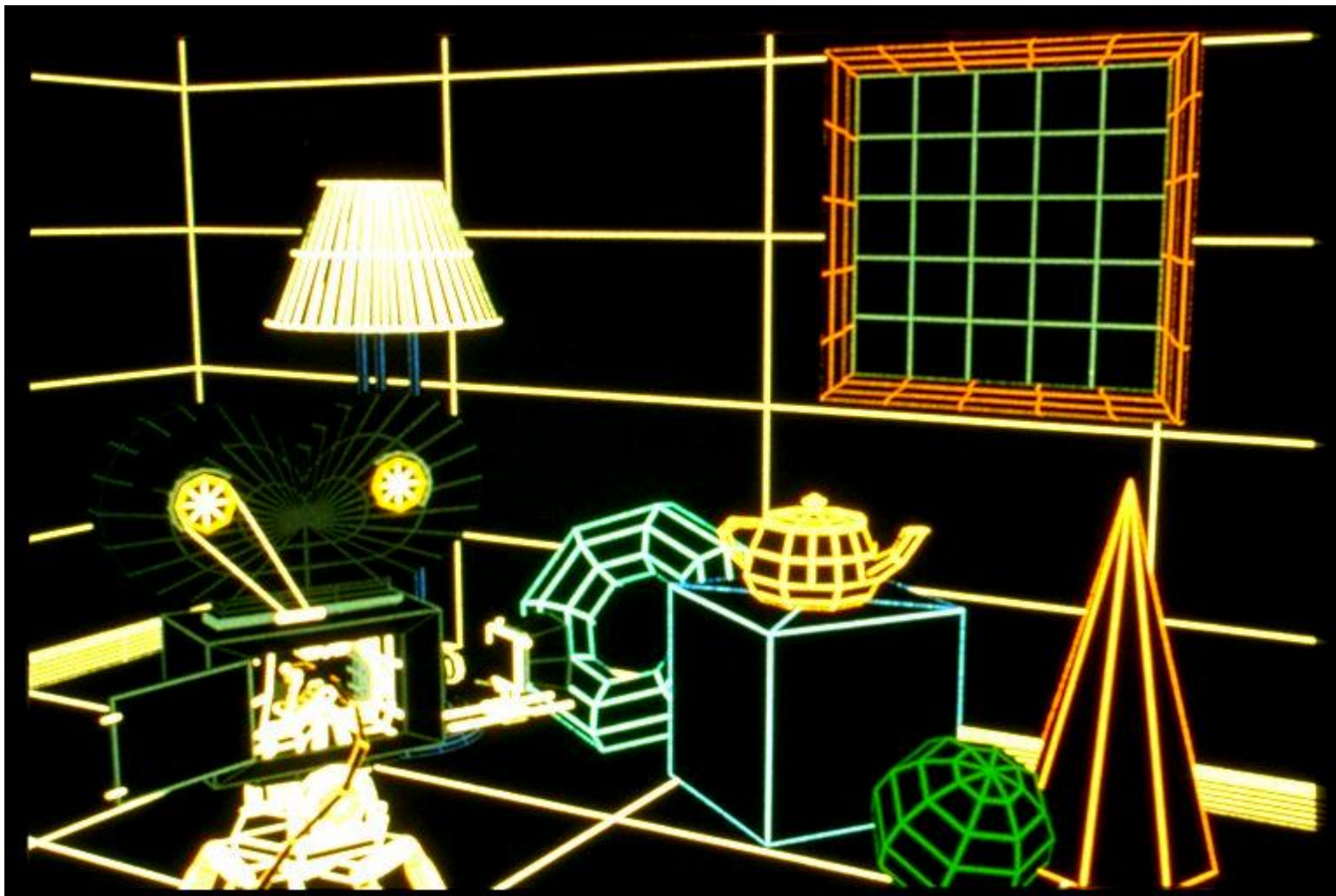
# Depth Clipping



# Colored Wireframes

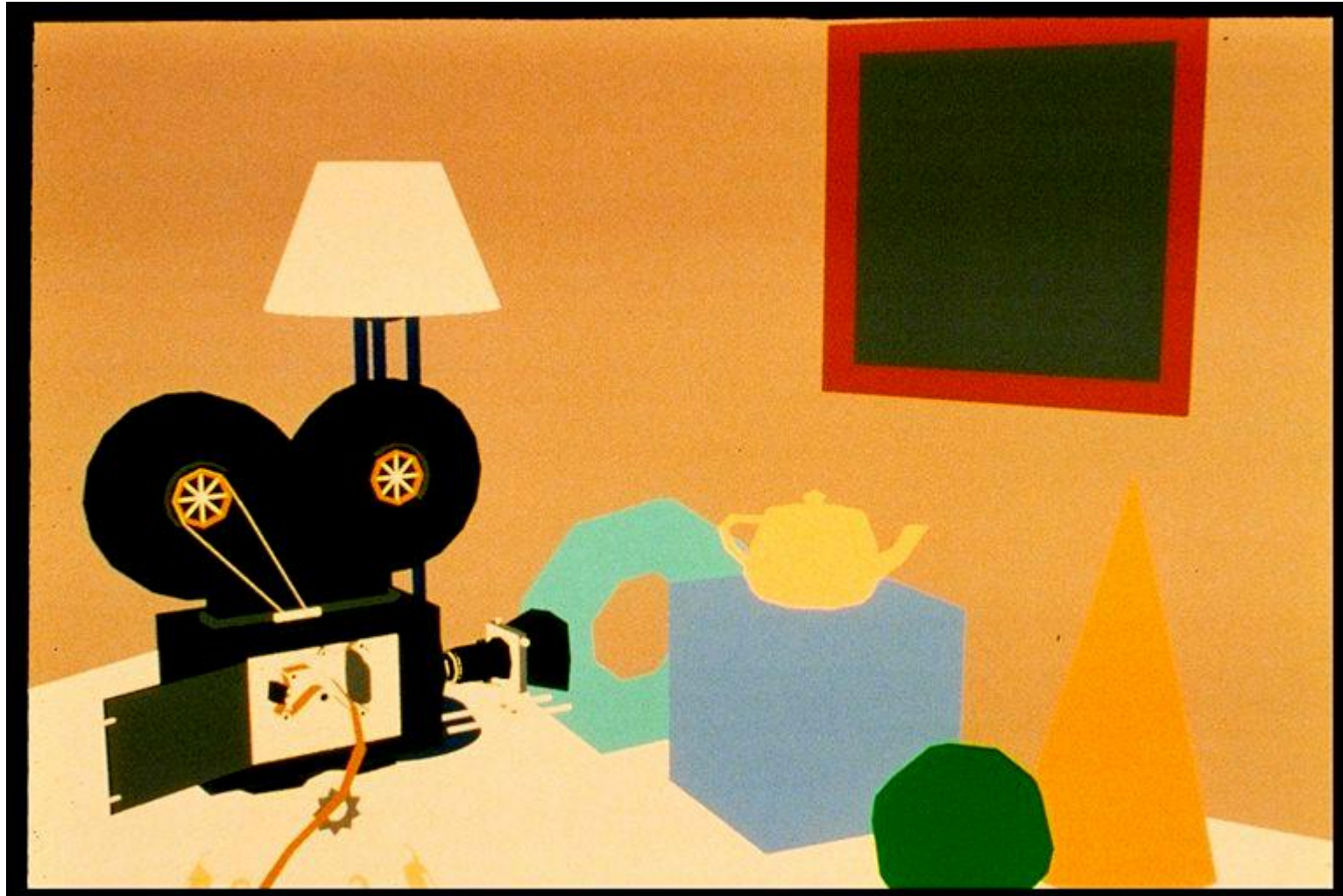


# Hidden Line Removal

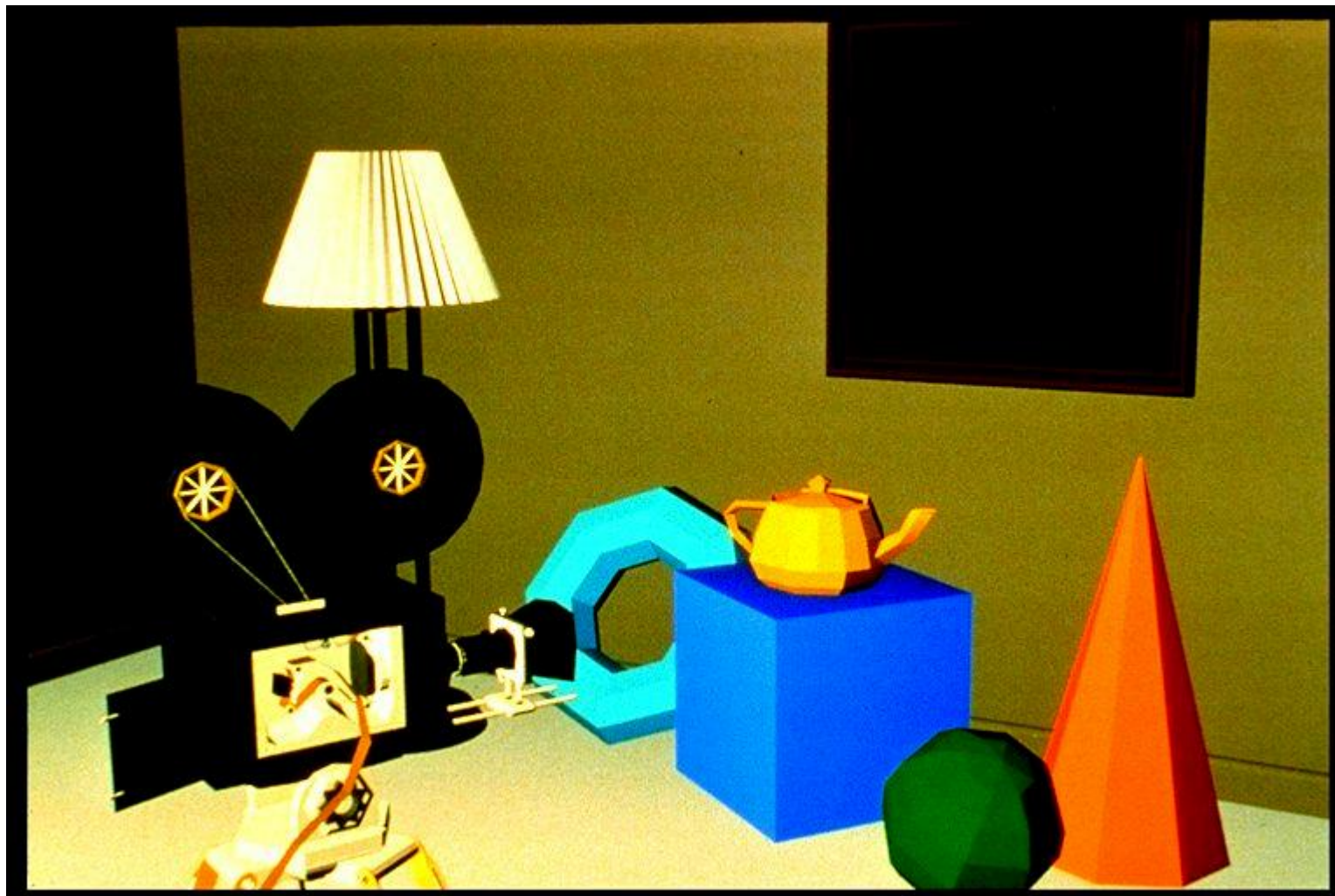




# Hidden Surface Removal

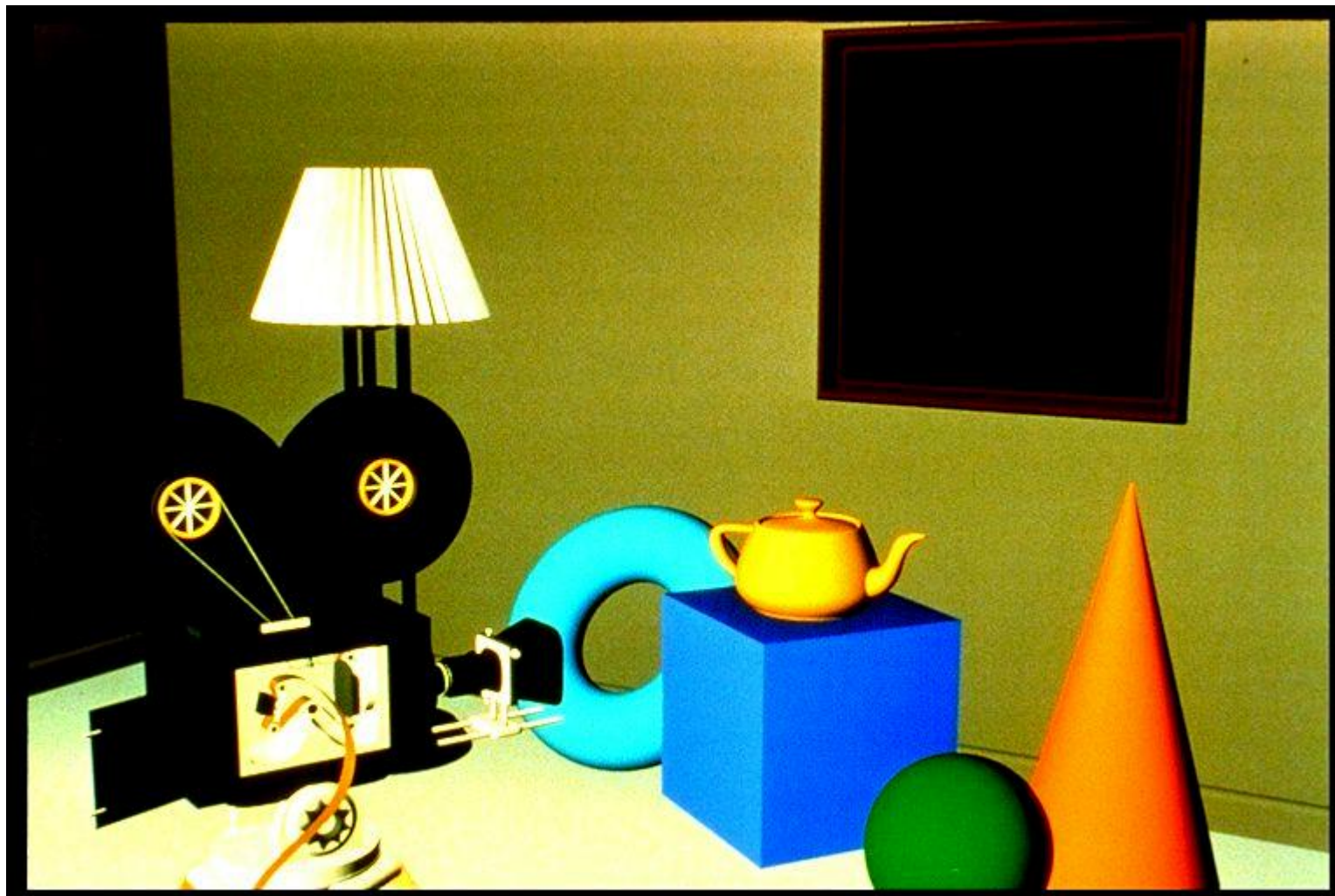


# Per-Polygon Shading

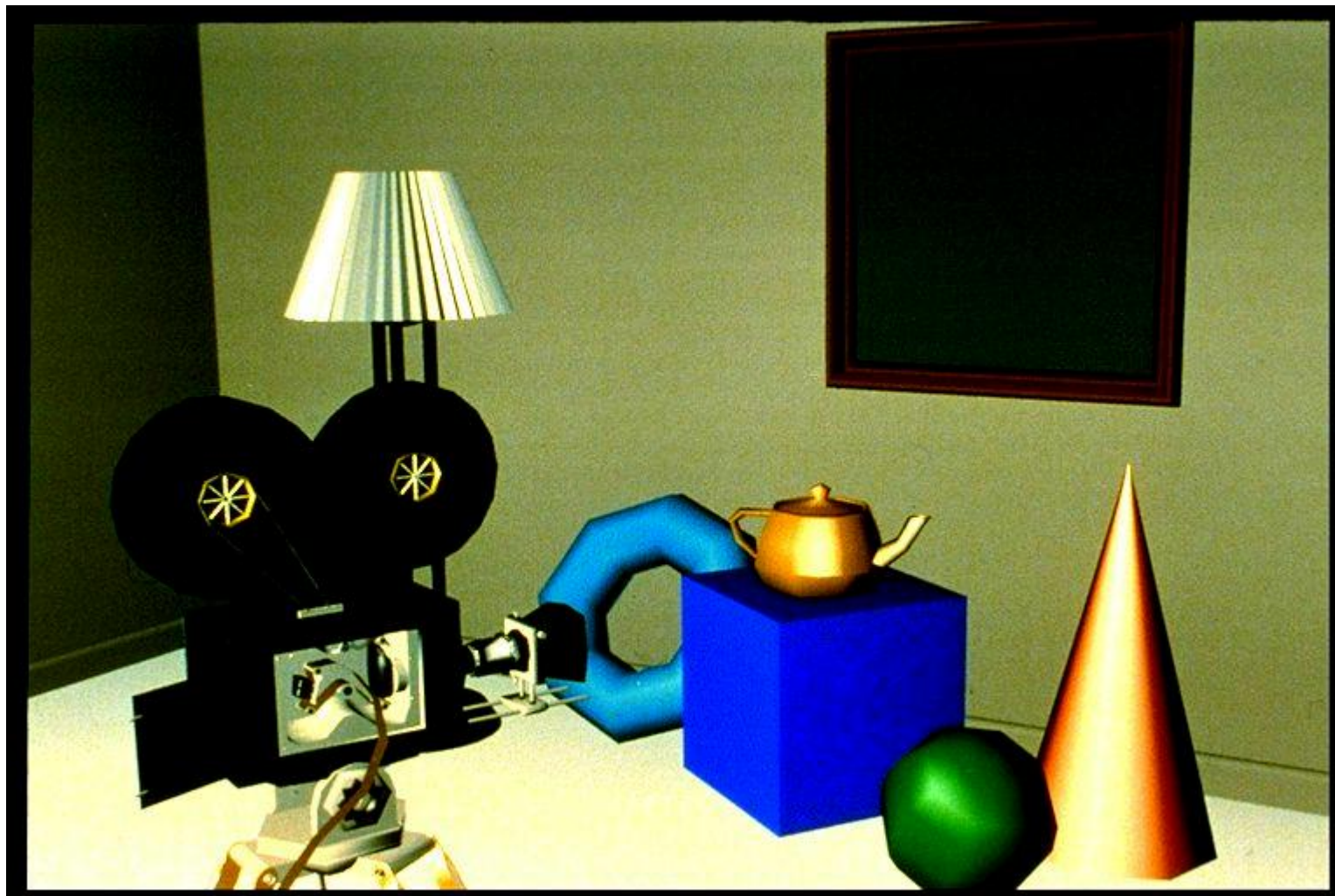




# Gouraud Shading

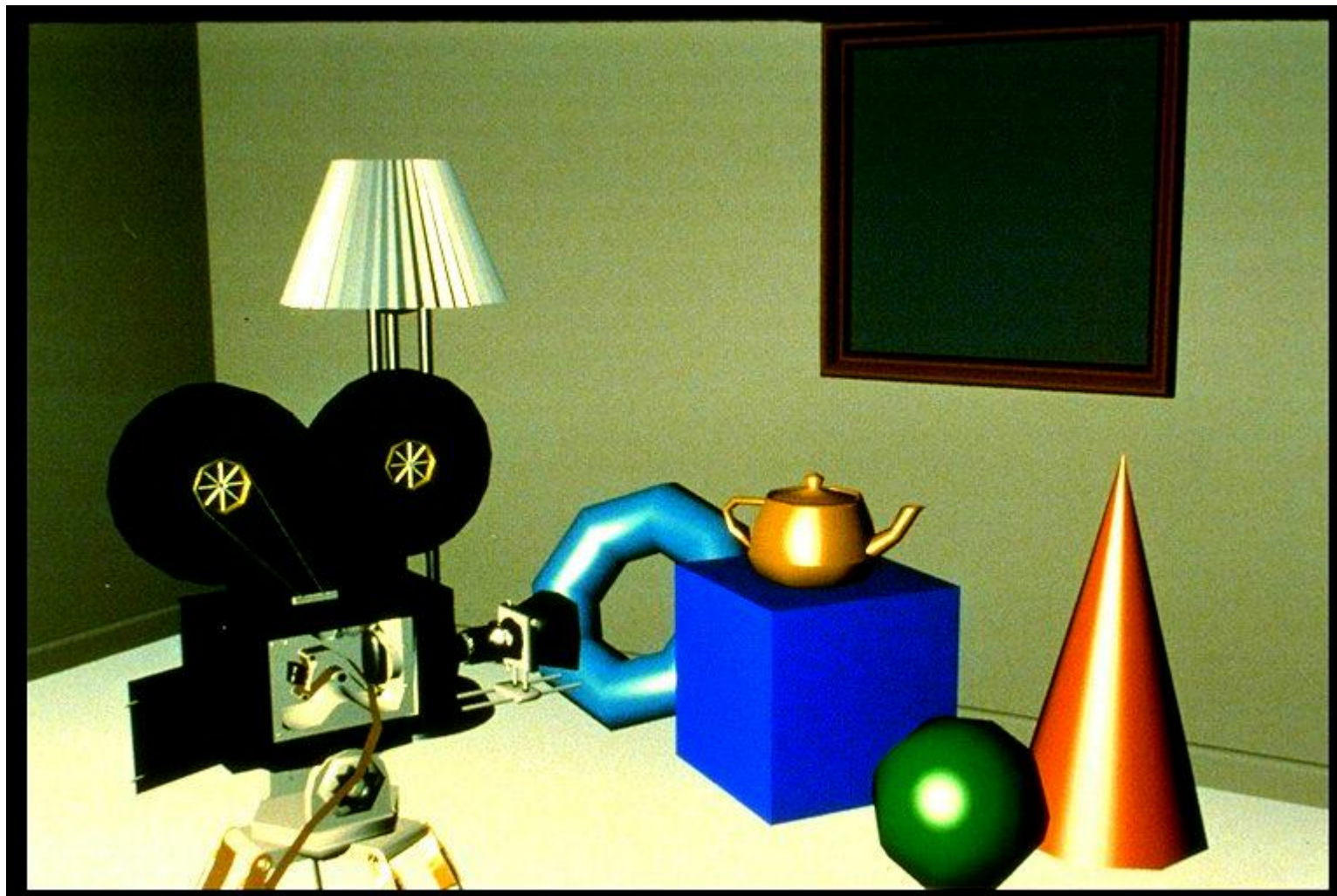


# Specular Reflection





# Phong Shading



# Curved Surfaces





# Complex Lighting and Shading



# Texture Mapping

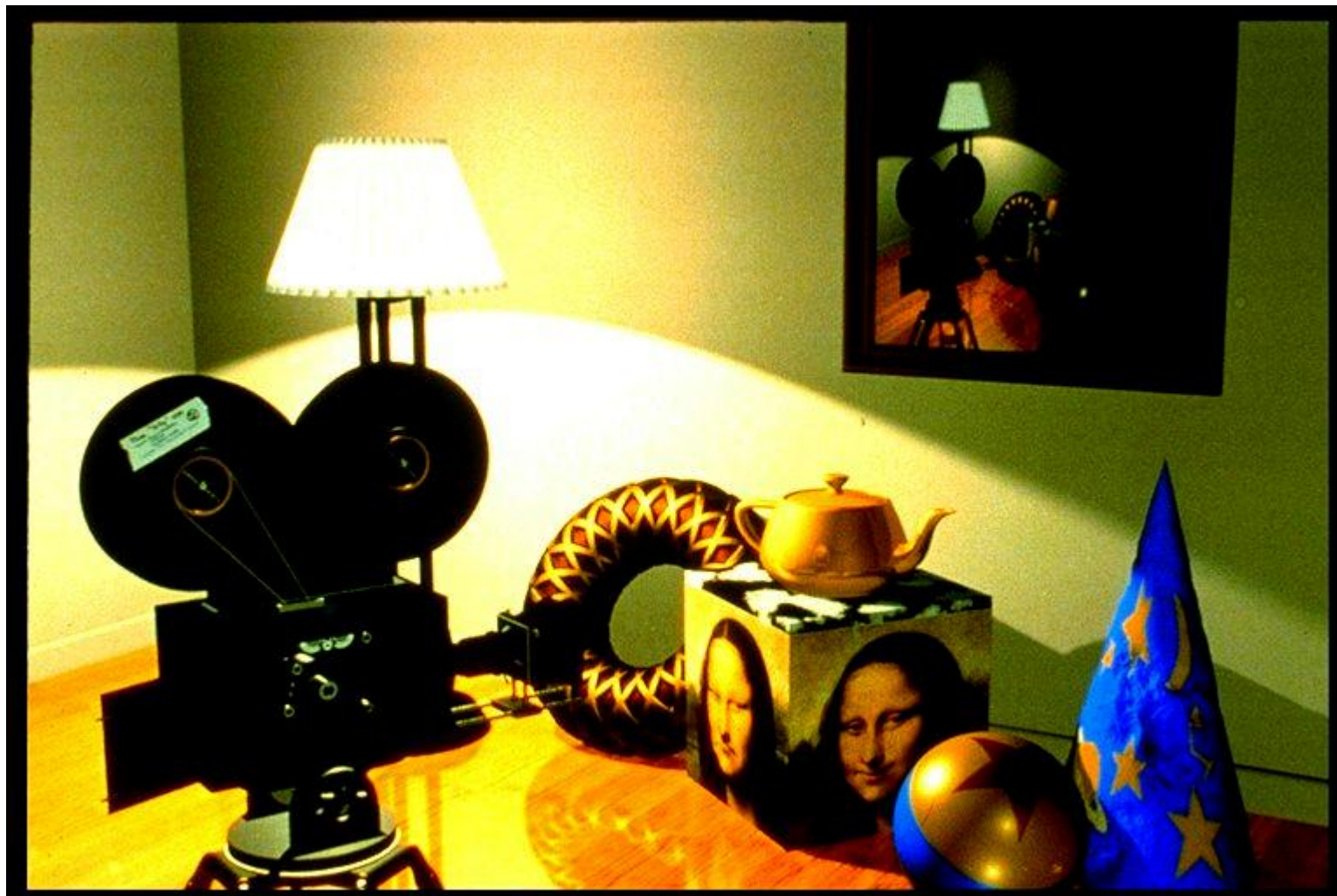




# Displacement Mapping



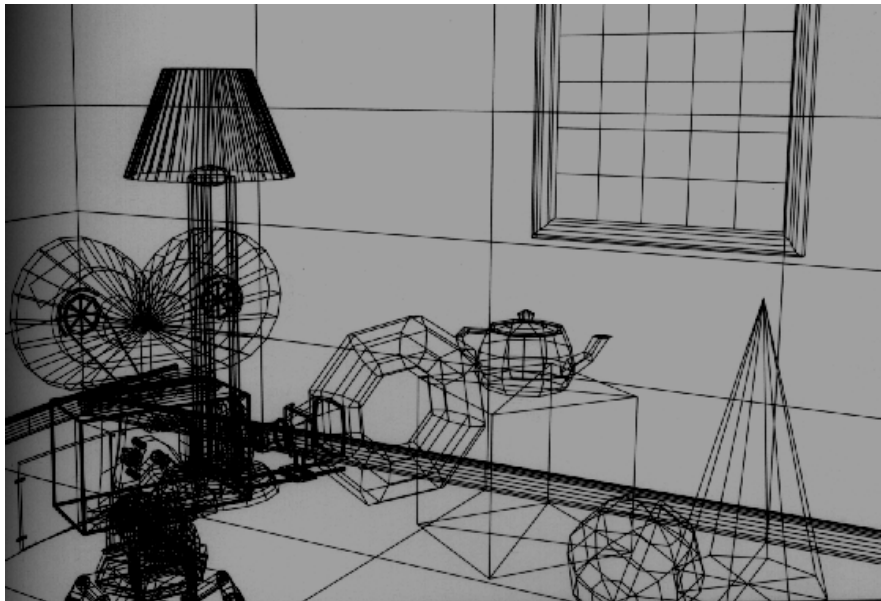
# Reflection Mapping





# Modelling

- generating models
  - lines, curves, polygons, smooth surfaces
  - digital geometry



# Animation

- generating motion
  - interpolating between frames, states

# Math Review

# Reading

- FCG Chapter 2: Miscellaneous Math
  - except for 2.11 (covered later)
  - skim 2.2 (sets and maps), 2.3 (quadratic eqns)
  - important: 2.3 (trig), 2.4 (vectors), 2.5-6 (lines)  
2.10 (linear interpolation)
    - skip 2.5.1, 2.5.3, 2.7.1, 2.7.3, 2.8, 2.9
- FCG Chapter 4.1-4.25: Linear Algebra
  - skim 4.1 (determinants)
  - important: 4.2.1-4.2.2, 4.2.5 (matrices)
    - skip 4.2.3-4, 4.2.6-7 (matrix numerical analysis)

# Textbook Errata

- list at <http://www.cs.utah.edu/~shirley/fcg/errata>
  - p 29, 32, 39 have potential to confuse

# Notation: Scalars, Vectors, Matrices

- scalar
  - (lower case, italic)
- vector
  - (lower case, bold)
- matrix
  - (upper case, bold)

$a$

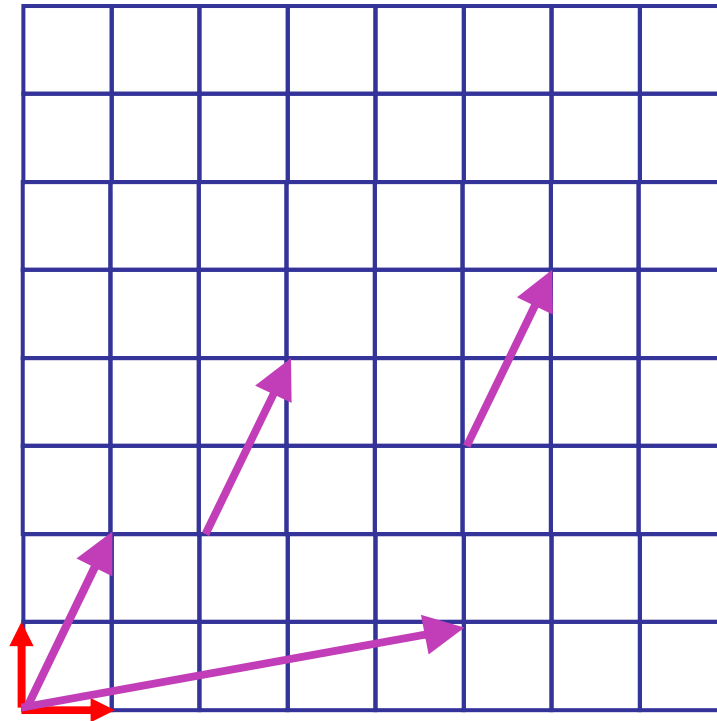
$$\mathbf{a} = [a_1 \quad a_2 \quad \dots \quad a_n]$$

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$



# Vectors

- arrow: length and direction
  - oriented segment in nD space
- offset / displacement
  - location if given origin



# Column vs. Row Vectors

- row vectors  $\mathbf{a}_{row} = [a_1 \ a_2 \ \dots \ a_n]$

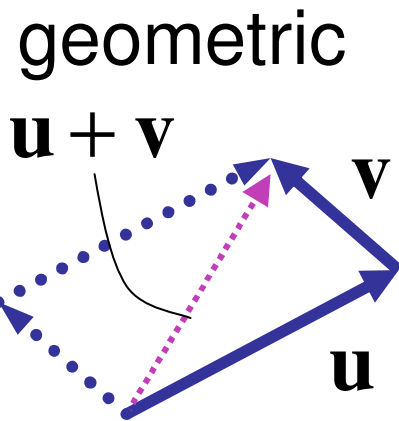
- column vectors  $\mathbf{a}_{col} = \begin{bmatrix} a_1 \\ a_2 \\ \dots \\ a_n \end{bmatrix}$

- switch back and forth with transpose

$$\mathbf{a}_{col}^T = \mathbf{a}_{row}$$

# Vector-Vector Addition

- add: vector + vector = vector
- parallelogram rule
  - tail to head, complete the triangle



algebraic

$$\mathbf{u} + \mathbf{v} = \begin{bmatrix} u_1 + v_1 \\ u_2 + v_2 \\ u_3 + v_3 \end{bmatrix}$$

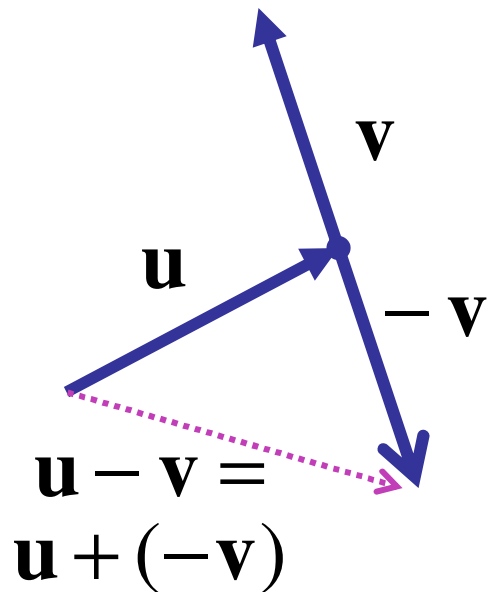
examples:

$$(3,2) + (6,4) = (9,6)$$
$$(2,5,1) + (3,1,-1) = (5,6,0)$$

# Vector-Vector Subtraction

- subtract: vector - vector = vector

$$\mathbf{u} - \mathbf{v} = \begin{bmatrix} u_1 - v_1 \\ u_2 - v_2 \\ u_3 - v_3 \end{bmatrix}$$



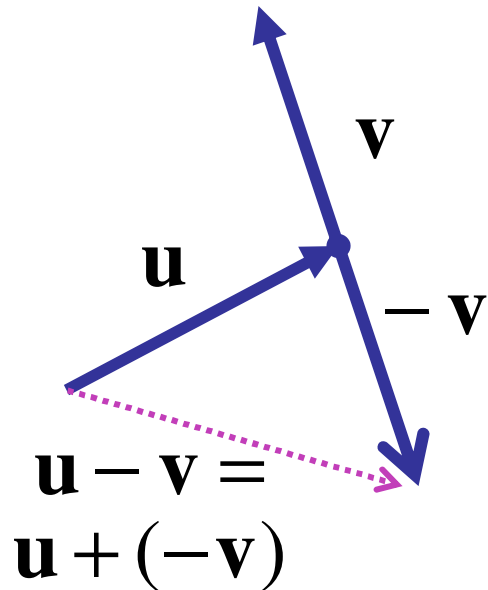
$$(3, 2) - (6, 4) = (-3, -2)$$

$$(2, 5, 1) - (3, 1, -1) = (-1, 4, 0)$$

# Vector-Vector Subtraction

- subtract: vector - vector = vector

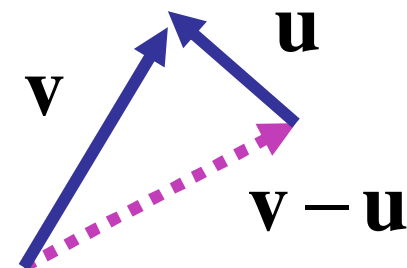
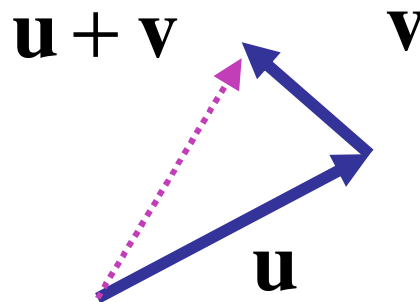
$$\mathbf{u} - \mathbf{v} = \begin{bmatrix} u_1 - v_1 \\ u_2 - v_2 \\ u_3 - v_3 \end{bmatrix}$$



$$(3, 2) - (6, 4) = (-3, -2)$$

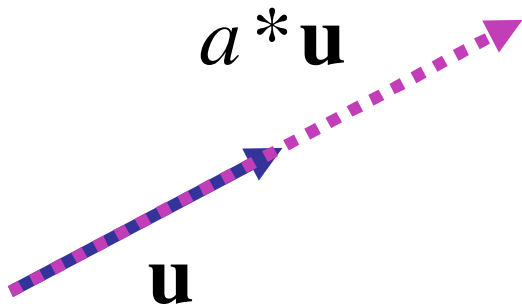
$$(2, 5, 1) - (3, 1, -1) = (-1, 4, 0)$$

argument reversal



# Scalar-Vector Multiplication

- multiply: scalar \* vector = vector
  - vector is scaled



$$a * \mathbf{u} = (a * u_1, a * u_2, a * u_3)$$

$$2 * (3, 2) = (6, 4)$$

$$.5 * (2, 5, 1) = (1, 2.5, .5)$$



# Vector-Vector Multiplication

- multiply: vector \* vector = scalar
- dot product, aka inner product

$$\mathbf{u} \bullet \mathbf{v}$$

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} \bullet \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = (u_1 * v_1) + (u_2 * v_2) + (u_3 * v_3)$$

# Vector-Vector Multiplication

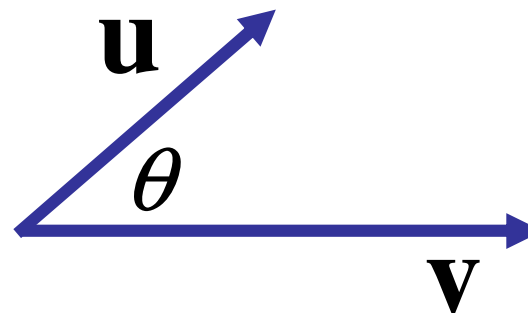
- multiply: vector \* vector = scalar
- dot product, aka inner product

$$\mathbf{u} \bullet \mathbf{v}$$

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} \bullet \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = (u_1 * v_1) + (u_2 * v_2) + (u_3 * v_3)$$

- geometric interpretation
  - lengths, angles
  - can find angle between two vectors

$$\mathbf{u} \bullet \mathbf{v} = \|\mathbf{u}\| \|\mathbf{v}\| \cos \theta$$

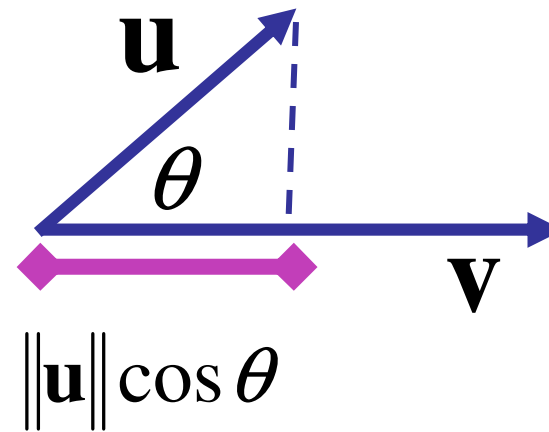


# Dot Product Geometry

- can find length of projection of  $\mathbf{u}$  onto  $\mathbf{v}$

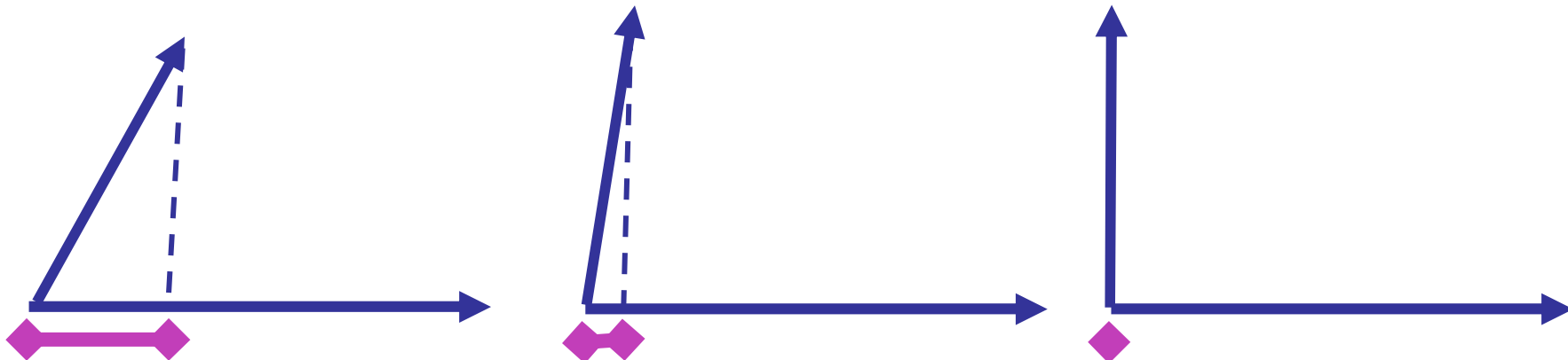
$$\mathbf{u} \cdot \mathbf{v} = \|\mathbf{u}\| \|\mathbf{v}\| \cos \theta$$

$$\|\mathbf{u}\| \cos \theta = \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{v}\|}$$



- as lines become perpendicular,

$$\mathbf{u} \cdot \mathbf{v} \rightarrow 0$$



# Dot Product Example

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} \bullet \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = (u_1 * v_1) + (u_2 * v_2) + (u_3 * v_3)$$

$$\begin{bmatrix} 6 \\ 1 \\ 2 \end{bmatrix} \bullet \begin{bmatrix} 1 \\ 7 \\ 3 \end{bmatrix} = (6 * 1) + (1 * 7) + (2 * 3) = 6 + 7 + 6 = 19$$

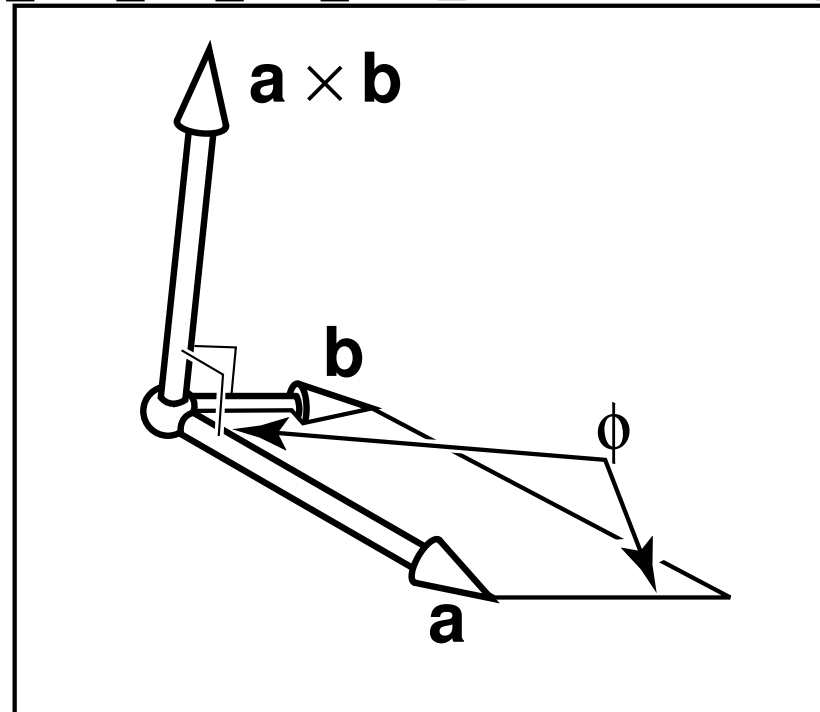
# Vector-Vector Multiplication, The Sequel

- multiply: vector \* vector = vector
- cross product
  - algebraic
  - geometric

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} \times \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} u_2 v_3 - u_3 v_2 \\ u_3 v_1 - u_1 v_3 \\ u_1 v_2 - u_2 v_1 \end{bmatrix}$$

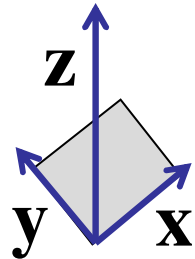
$$\|\mathbf{a} \times \mathbf{b}\| = \|\mathbf{a}\| \|\mathbf{b}\| \sin \theta$$

- $\|\mathbf{a} \times \mathbf{b}\|$  parallelogram area
- $\mathbf{a} \times \mathbf{b}$  perpendicular to parallelogram



# RHS vs LHS Coordinate Systems

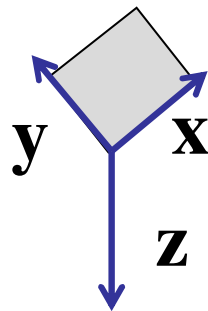
- right-handed coordinate system **convention**



right hand rule:  
index finger x, second finger y;  
right thumb points up

$$\mathbf{z} = \mathbf{x} \times \mathbf{y}$$

- left-handed coordinate system



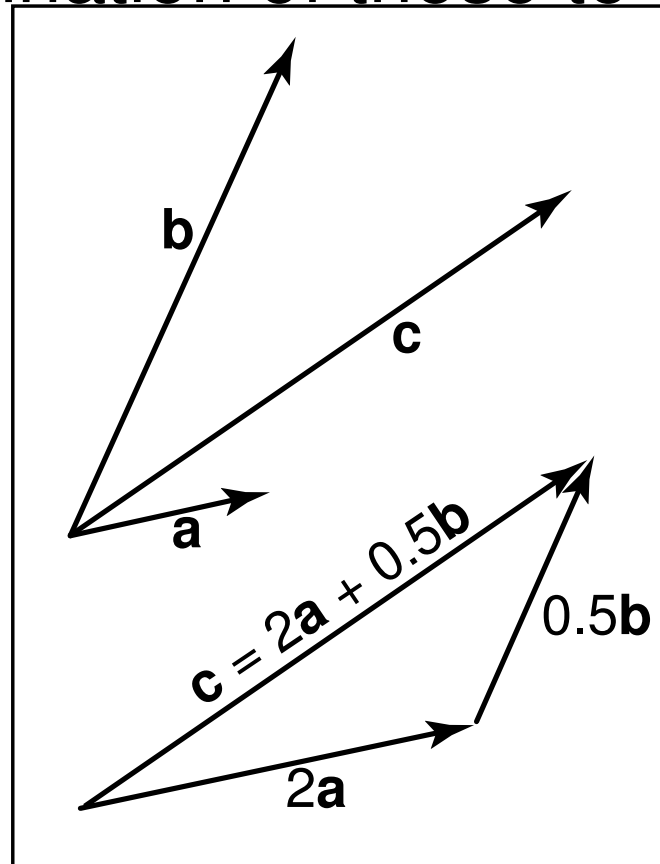
left hand rule:  
index finger x, second finger y;  
left thumb points down

$$\mathbf{z} = \mathbf{x} \times \mathbf{y}$$

# Basis Vectors

- take any two vectors that are **linearly independent** (nonzero and nonparallel)
  - can use linear combination of these to define any other vector:

$$\mathbf{c} = w_1 \mathbf{a} + w_2 \mathbf{b}$$



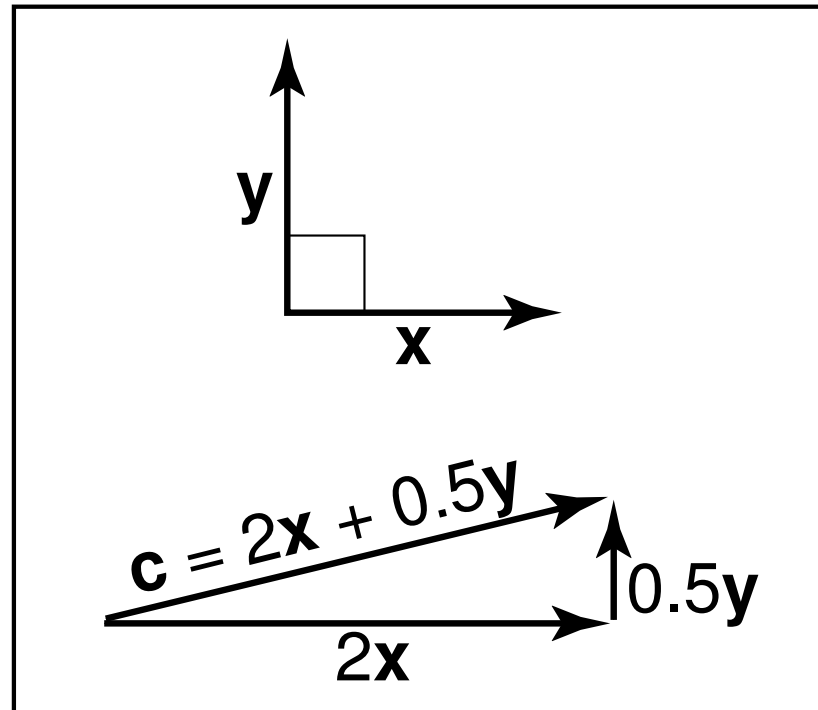
# Orthonormal Basis Vectors

- if basis vectors are **orthonormal** (**orthogonal** (mutually perpendicular) and unit length)
  - we have Cartesian coordinate system
  - familiar Pythagorean definition of distance

orthonormal algebraic properties

$$\|\mathbf{x}\| = \|\mathbf{y}\| = 1,$$

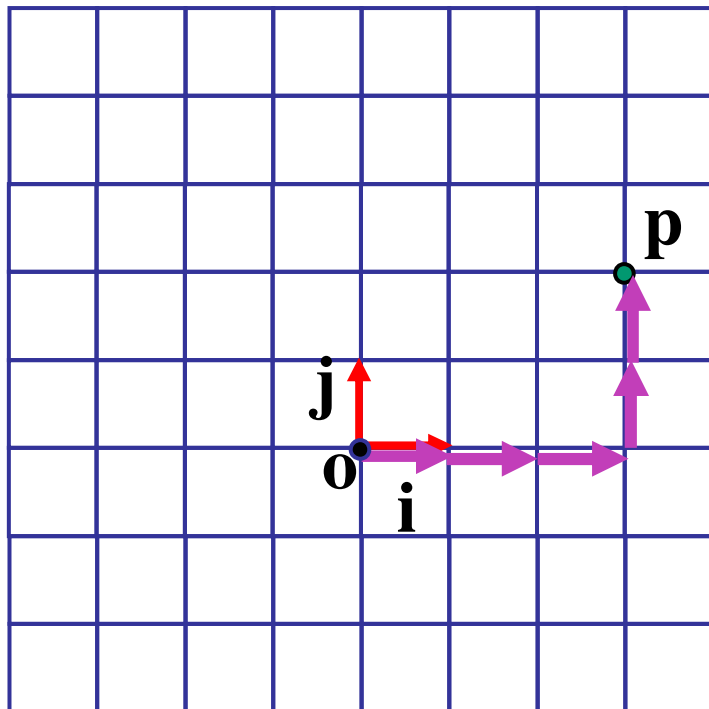
$$\mathbf{x} \bullet \mathbf{y} = 0$$





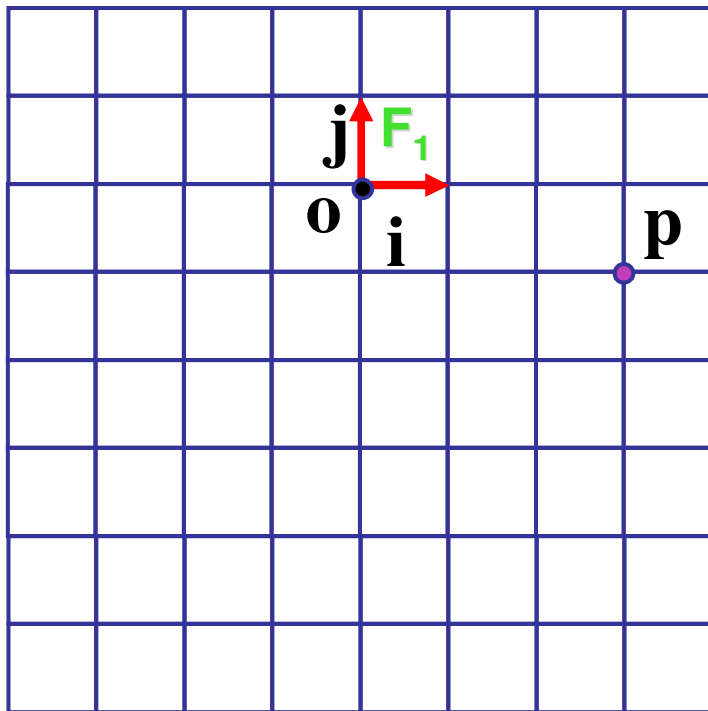
# Basis Vectors and Origins

- **coordinate system**: just basis vectors
  - can only specify offset: vectors
- **coordinate frame**: basis vectors and origin
  - can specify location as well as offset: points



$$\mathbf{p} = \mathbf{o} + x\mathbf{i} + y\mathbf{j}$$

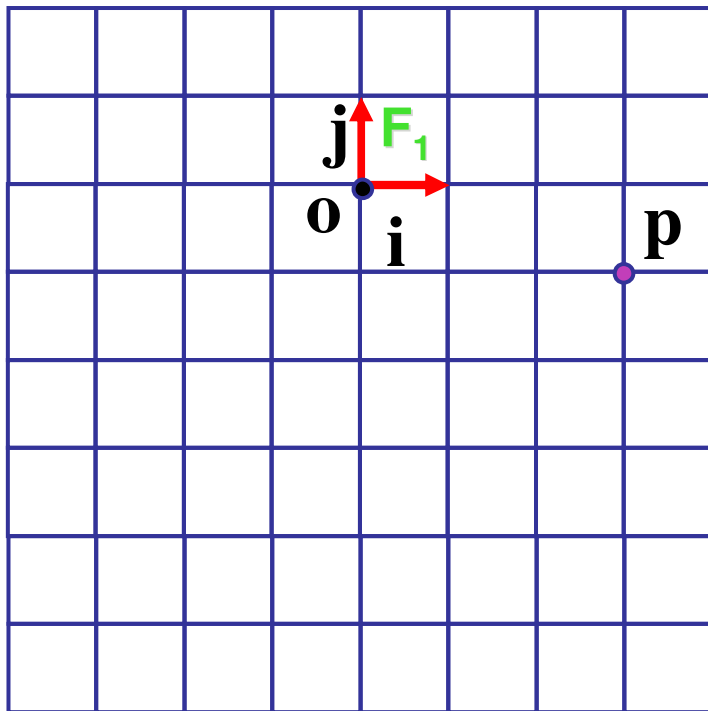
# Working with Frames



$$\mathbf{p} = \mathbf{o} + x\mathbf{i} + y\mathbf{j}$$

$F_1$

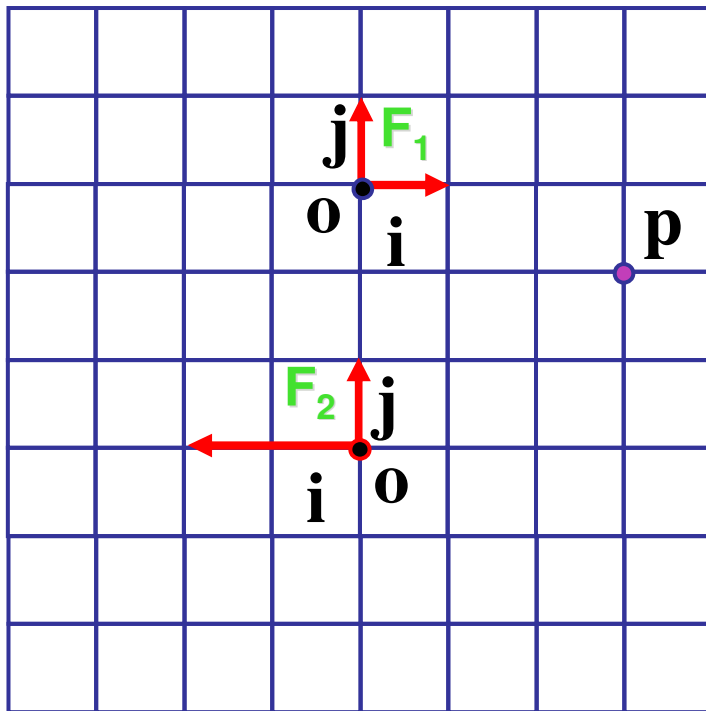
# Working with Frames



$$\mathbf{p} = \mathbf{o} + x\mathbf{i} + y\mathbf{j}$$

$$F_1 \quad \mathbf{p} = (3, -1)$$

# Working with Frames

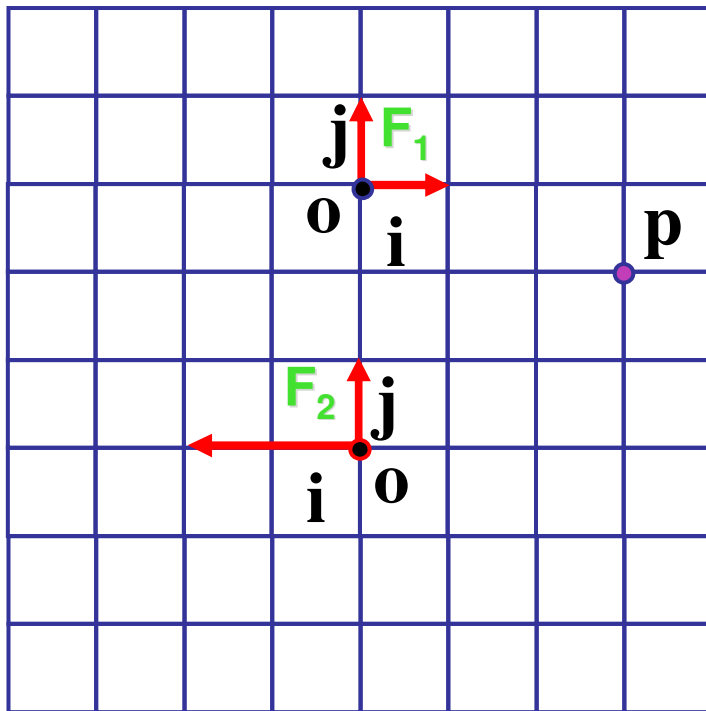


$$\mathbf{p} = \mathbf{o} + x\mathbf{i} + y\mathbf{j}$$

$$F_1 \quad \mathbf{p} = (3, -1)$$

$$F_2$$

# Working with Frames

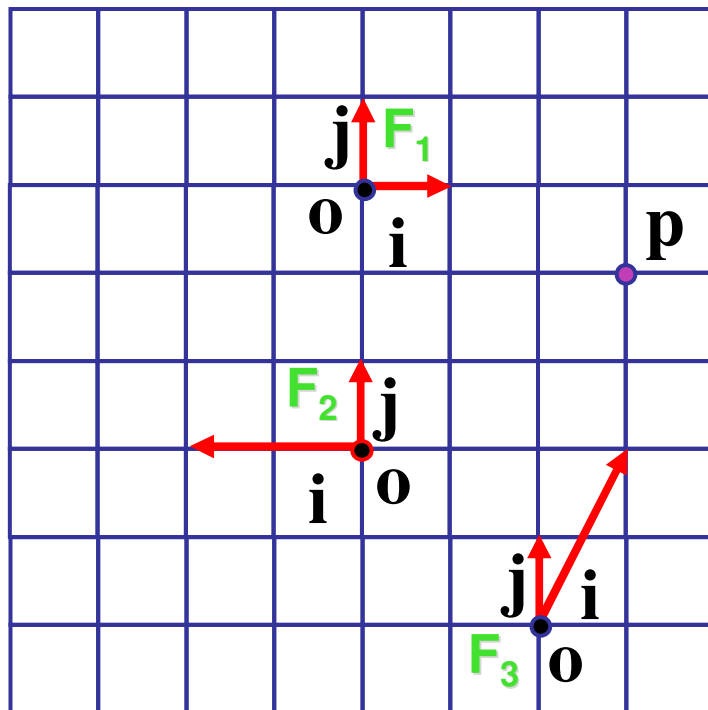


$$\mathbf{p} = \mathbf{o} + x\mathbf{i} + y\mathbf{j}$$

$$F_1 \quad \mathbf{p} = (3, -1)$$

$$F_2 \quad \mathbf{p} = (-1.5, 2)$$

# Working with Frames



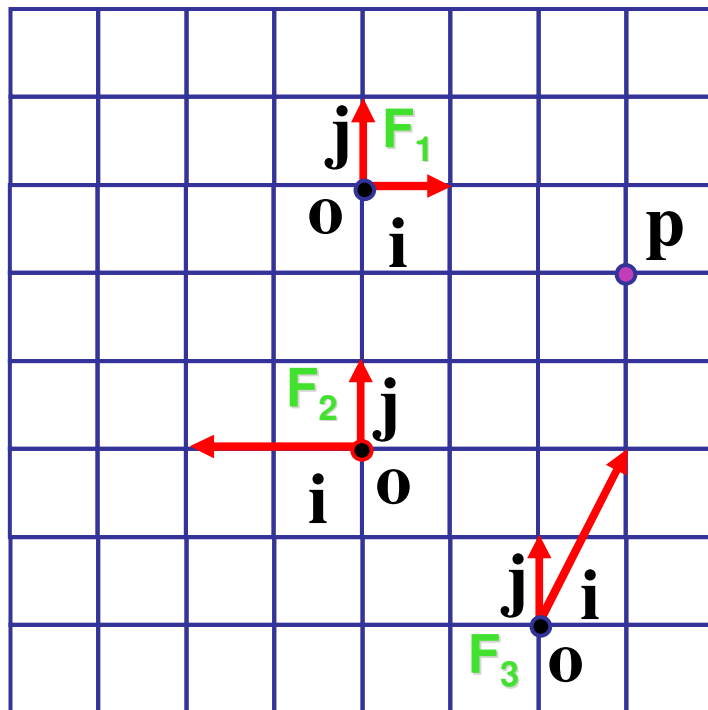
$$\mathbf{p} = \mathbf{o} + x\mathbf{i} + y\mathbf{j}$$

$$F_1 \quad \mathbf{p} = (3, -1)$$

$$F_2 \quad \mathbf{p} = (-1.5, 2)$$

$$F_3$$

# Working with Frames



$$\mathbf{p} = \mathbf{o} + x\mathbf{i} + y\mathbf{j}$$

$$F_1 \quad \mathbf{p} = (3, -1)$$

$$F_2 \quad \mathbf{p} = (-1.5, 2)$$

$$F_3 \quad \mathbf{p} = (1, 2)$$

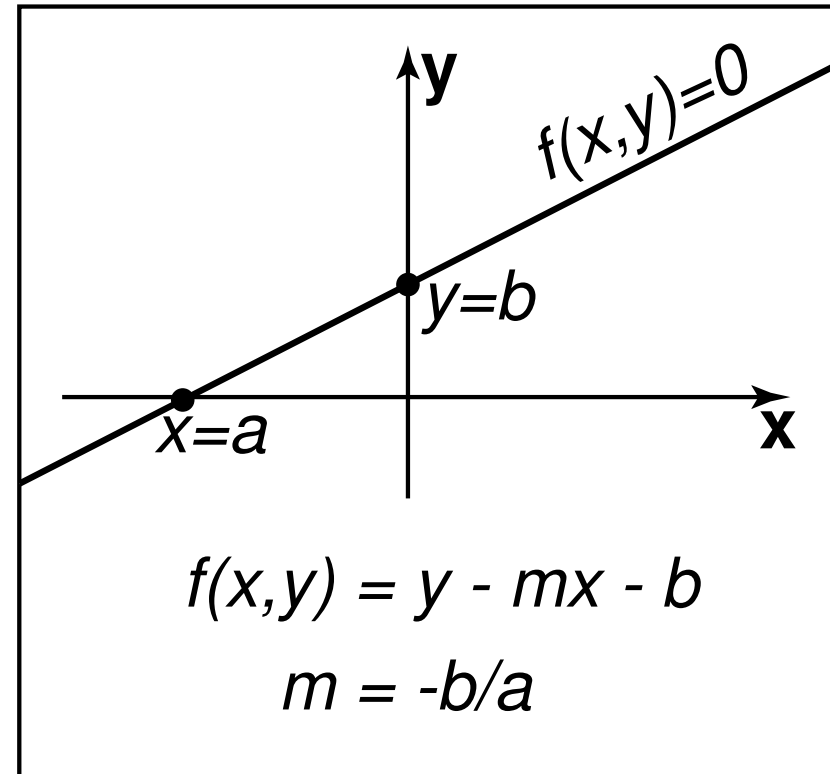
# Named Coordinate Frames

- origin and basis vectors  $\mathbf{p} = \mathbf{o} + a\mathbf{x} + b\mathbf{y} + c\mathbf{z}$
- pick canonical frame of reference
  - then don't have to store origin, basis vectors
  - just  $\mathbf{p} = (a, b, c)$
  - convention: Cartesian orthonormal one on previous slide
- handy to specify others as needed
  - airplane nose, looking over your shoulder, ...
  - really common ones given names in CG
    - object, world, camera, screen, ...



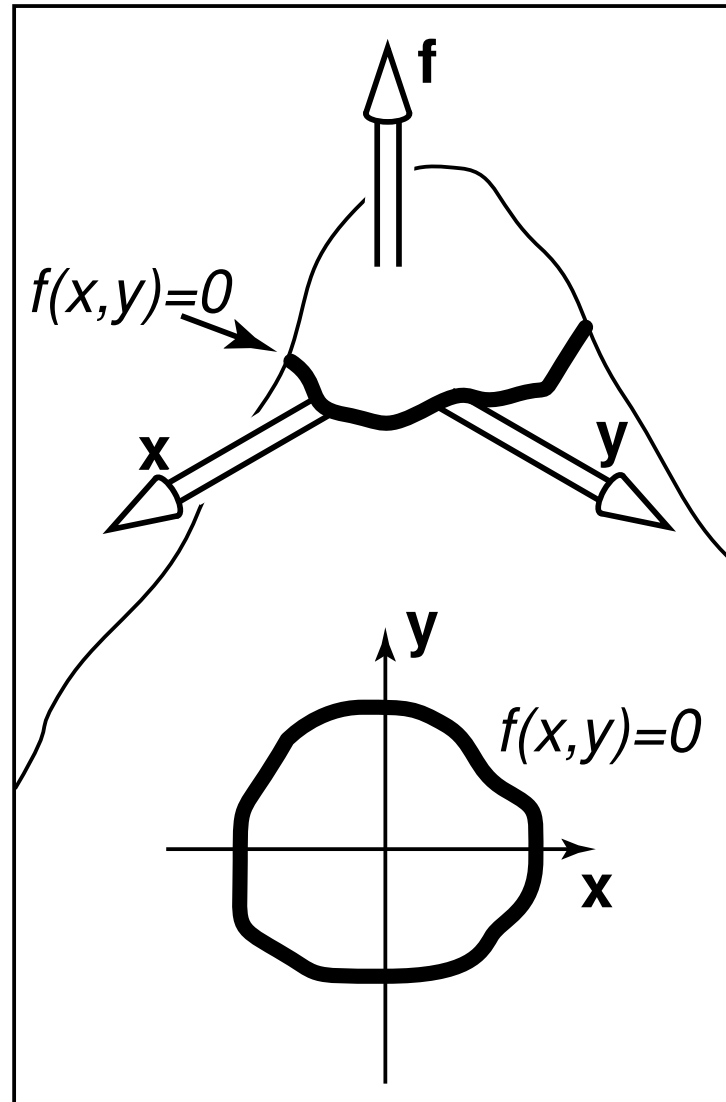
# Lines

- slope-intercept form
  - $y = mx + b$
- implicit form
  - $y - mx - b = 0$
  - $Ax + By + C = 0$
  - $f(x,y) = 0$



# Implicit Functions

- find where function is 0
  - plug in  $(x,y)$ , check if
    - 0: on line
    - $< 0$ : inside
    - $> 0$ : outside
- analogy: terrain
  - sea level:  $f=0$
  - altitude: function value
  - topo map: equal-value contours (level sets)



# Implicit Circles

- $f(x, y) = (x - x_c)^2 + (y - y_c)^2 - r^2$ 
  - circle is points  $(x, y)$  where  $f(x, y) = 0$
- $p = (x, y), c = (x_c, y_c) : (\mathbf{p} - \mathbf{c}) \bullet (\mathbf{p} - \mathbf{c}) - r^2 = 0$ 
  - points  $\mathbf{p}$  on circle have property that vector from  $\mathbf{c}$  to  $\mathbf{p}$  dotted with itself has value  $r^2$
- $\|\mathbf{p} - \mathbf{c}\|^2 - r^2 = 0$ 
  - points  $\mathbf{p}$  on the circle have property that squared distance from  $\mathbf{c}$  to  $\mathbf{p}$  is  $r^2$
- $\|\mathbf{p} - \mathbf{c}\| - r = 0$ 
  - points  $\mathbf{p}$  on circle are those a distance  $r$  from center point  $\mathbf{c}$

# Parametric Curves

- parameter: index that changes continuously

- $(x,y)$ : point on curve

- $t$ : parameter

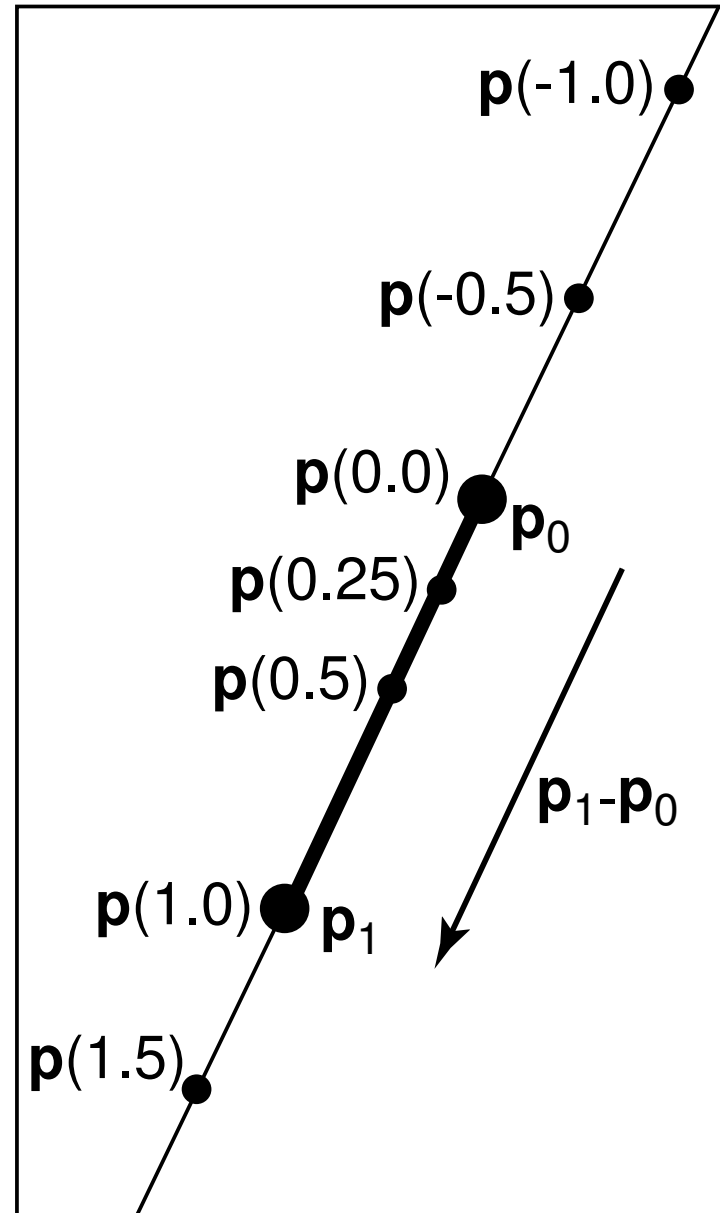
$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} g(t) \\ h(t) \end{bmatrix}$$

- vector form

- $\mathbf{p} = f(t)$

## 2D Parametric Lines

- $$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x_0 + t(x_1 - x_0) \\ y_0 + t(y_1 - y_0) \end{bmatrix}$$
- $\mathbf{p}(t) = \mathbf{p}_0 + t(\mathbf{p}_1 - \mathbf{p}_0)$
- $\mathbf{p}(t) = \mathbf{o} + t(\mathbf{d})$
- start at point  $\mathbf{p}_0$ ,  
go towards  $\mathbf{p}_1$ ,  
according to parameter  $t$ 
  - $\mathbf{p}(0) = \mathbf{p}_0$ ,  $\mathbf{p}(1) = \mathbf{p}_1$



# Linear Interpolation

- parametric line is example of general concept
  - $\mathbf{p}(t) = \mathbf{p}_0 + t(\mathbf{p}_1 - \mathbf{p}_0)$
  - interpolation
    - $\mathbf{p}$  goes through  $\mathbf{a}$  at  $t = 0$
    - $\mathbf{p}$  goes through  $\mathbf{b}$  at  $t = 1$
  - linear
    - weights  $t, (1-t)$  are linear polynomials in  $t$



# Matrix-Matrix Addition

- add: matrix + matrix = matrix

$$\begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} + \begin{bmatrix} n_{11} & n_{12} \\ n_{21} & n_{22} \end{bmatrix} = \begin{bmatrix} n_{11} + m_{11} & n_{12} + m_{12} \\ n_{21} + m_{21} & n_{22} + m_{22} \end{bmatrix}$$

- example

$$\begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix} + \begin{bmatrix} -2 & 5 \\ 7 & 1 \end{bmatrix} = \begin{bmatrix} 1 + (-2) & 3 + 5 \\ 2 + 7 & 4 + 1 \end{bmatrix} = \begin{bmatrix} -1 & 8 \\ 9 & 5 \end{bmatrix}$$

# Scalar-Matrix Multiplication

- multiply: scalar \* matrix = matrix

$$a \begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} = \begin{bmatrix} a * m_{11} & a * m_{12} \\ a * m_{21} & a * m_{22} \end{bmatrix}$$

- example

$$3 \begin{bmatrix} 2 & 4 \\ 1 & 5 \end{bmatrix} = \begin{bmatrix} 3 * 2 & 3 * 4 \\ 3 * 1 & 3 * 5 \end{bmatrix} = \begin{bmatrix} 6 & 12 \\ 3 & 15 \end{bmatrix}$$

# Matrix-Matrix Multiplication

- row by column

$$\begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} \begin{bmatrix} n_{11} & n_{12} \\ n_{21} & n_{22} \end{bmatrix} = \begin{bmatrix} p_{11} & p_{12} \\ p_{21} & p_{22} \end{bmatrix}$$

$$p_{11} = m_{11}n_{11} + m_{12}n_{21}$$

# Matrix-Matrix Multiplication

- row by column

$$\begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} \begin{bmatrix} n_{11} & n_{12} \\ n_{21} & n_{22} \end{bmatrix} = \begin{bmatrix} p_{11} & p_{12} \\ p_{21} & p_{22} \end{bmatrix}$$

$$p_{11} = m_{11}n_{11} + m_{12}n_{21}$$

$$p_{21} = m_{21}n_{11} + m_{22}n_{21}$$

# Matrix-Matrix Multiplication

- row by column

$$\begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} \begin{bmatrix} n_{11} & n_{12} \\ n_{21} & n_{22} \end{bmatrix} = \begin{bmatrix} p_{11} & p_{12} \\ p_{21} & p_{22} \end{bmatrix}$$

$$p_{11} = m_{11}n_{11} + m_{12}n_{21}$$

$$p_{21} = m_{21}n_{11} + m_{22}n_{21}$$

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# Matrix-Matrix Multiplication

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$$p_{22} = m_{21}n_{12} + m_{22}n_{22}$$

# Matrix-Matrix Multiplication

- row by column

$$\begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} \begin{bmatrix} n_{11} & n_{12} \\ n_{21} & n_{22} \end{bmatrix} = \begin{bmatrix} p_{11} & p_{12} \\ p_{21} & p_{22} \end{bmatrix}$$

$$p_{11} = m_{11}n_{11} + m_{12}n_{21}$$

$$p_{21} = m_{21}n_{11} + m_{22}n_{21}$$

$$p_{12} = m_{11}n_{12} + m_{12}n_{22}$$

$$p_{22} = m_{21}n_{12} + m_{22}n_{22}$$

- noncommutative: **AB**  $\neq$  **BA**

# Matrix Multiplication

- can only multiply if  
number of left rows = number of right cols

- legal

$$\begin{bmatrix} a & b & c \\ e & f & g \end{bmatrix} \begin{bmatrix} h & i \\ j & k \\ l & m \end{bmatrix}$$

- undefined

$$\begin{bmatrix} a & b & c \\ e & f & g \\ o & p & q \end{bmatrix} \begin{bmatrix} h & i \\ j & k \end{bmatrix}$$



# Matrix-Vector Multiplication

- points as column vectors: postmultiply

$$\begin{bmatrix} x' \\ y' \\ z' \\ h' \end{bmatrix} = \begin{bmatrix} m_{11} & m_{12} & m_{13} & m_{14} \\ m_{21} & m_{22} & m_{23} & m_{24} \\ m_{31} & m_{32} & m_{33} & m_{34} \\ m_{41} & m_{42} & m_{43} & m_{44} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ h \end{bmatrix} \quad \mathbf{p}' = \mathbf{M}\mathbf{p}$$

- points as row vectors: premultiply

$$\begin{bmatrix} x' & y' & z' & h' \end{bmatrix} = \begin{bmatrix} x & y & z & h \end{bmatrix} \begin{bmatrix} m_{11} & m_{12} & m_{13} & m_{14} \\ m_{21} & m_{22} & m_{23} & m_{24} \\ m_{31} & m_{32} & m_{33} & m_{34} \\ m_{41} & m_{42} & m_{43} & m_{44} \end{bmatrix}^T \quad \mathbf{p}'^T = \mathbf{p}^T \mathbf{M}^T$$

# Matrices

■ transpose

$$\begin{bmatrix} m_{11} & m_{12} & m_{13} & m_{14} \\ m_{21} & m_{22} & m_{23} & m_{24} \\ m_{31} & m_{32} & m_{33} & m_{34} \\ m_{41} & m_{42} & m_{43} & m_{44} \end{bmatrix}^T = \begin{bmatrix} m_{11} & m_{21} & m_{31} & m_{41} \\ m_{12} & m_{22} & m_{32} & m_{42} \\ m_{13} & m_{23} & m_{33} & m_{43} \\ m_{14} & m_{24} & m_{34} & m_{44} \end{bmatrix}$$

■ identity

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

■ inverse  $\mathbf{A}\mathbf{A}^{-1} = \mathbf{I}$

- not all matrices are invertible

# Matrices and Linear Systems

- linear system of n equations, n unknowns

$$3x + 7y + 2z = 4$$

$$2x - 4y - 3z = -1$$

$$5x + 2y + z = 1$$

- matrix form  **$Ax=b$**

$$\begin{bmatrix} 3 & 7 & 2 \\ 2 & -4 & -3 \\ 5 & 2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 4 \\ -1 \\ -1 \end{bmatrix}$$

# Rendering Pipeline

# Reading

- RB Chap. Introduction to OpenGL
- RB Chap. State Management and Drawing Geometric Objects
- RB Appendix Basics of GLUT
  - (Basics of Aux in v 1.1)

# Rendering

- goal
  - transform computer models into images
  - may or may not be photo-realistic
- interactive rendering
  - fast, but limited quality
  - roughly follows a fixed patterns of operations
    - rendering pipeline
- offline rendering
  - ray-tracing
  - global illumination

# Rendering

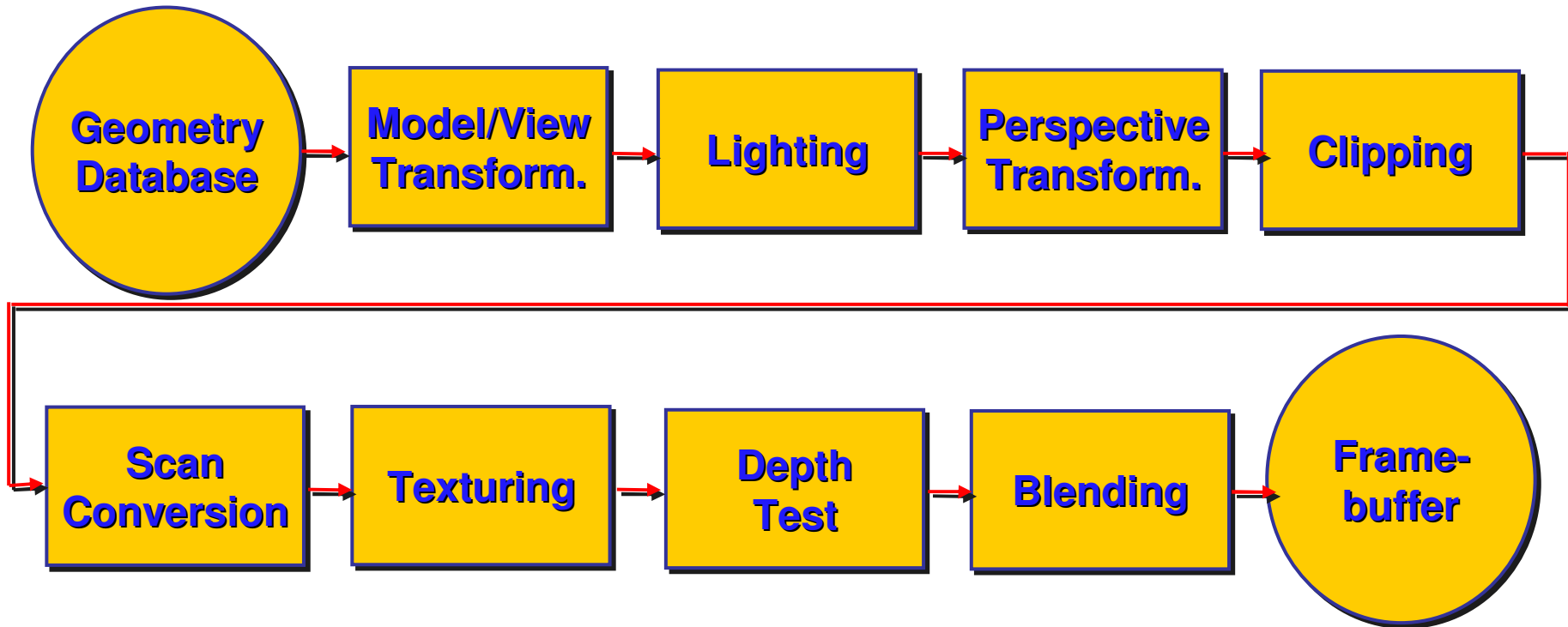
- tasks that need to be performed (in no particular order):
  - project all 3D geometry onto the image plane
    - geometric transformations
  - determine which primitives or parts of primitives are visible
    - hidden surface removal
  - determine which pixels a geometric primitive covers
    - scan conversion
  - compute the color of every visible surface point
    - lighting, shading, texture mapping

# Rendering Pipeline

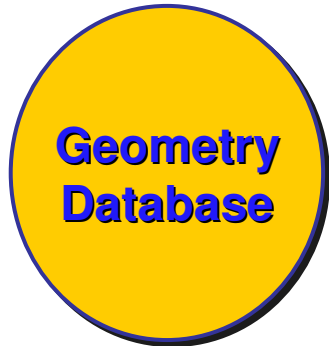
- what is the pipeline?
  - abstract model for sequence of operations to transform geometric model into digital image
  - abstraction of the way graphics hardware works
  - underlying model for application programming interfaces (APIs) that allow programming of graphics hardware
    - OpenGL
    - Direct 3D
- actual implementation details of rendering pipeline will vary



# Rendering Pipeline

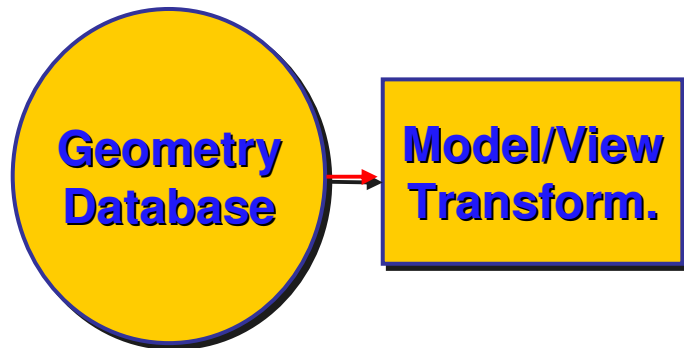


# Geometry Database



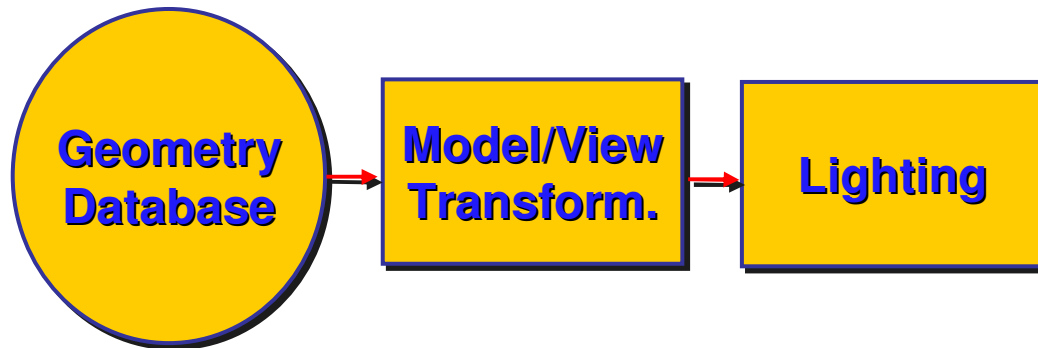
- geometry database
  - application-specific data structure for holding geometric information
  - depends on specific needs of application
    - triangle soup, points, mesh with connectivity information, curved surface

# Model/View Transformation



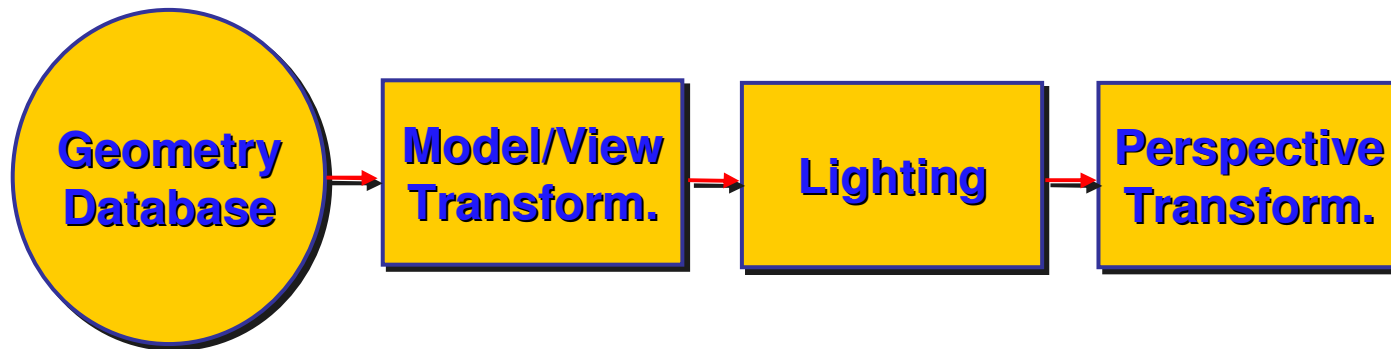
- modeling transformation
  - map all geometric objects from local coordinate system into world coordinates
- viewing transformation
  - map all geometry from world coordinates into camera coordinates

# Lighting



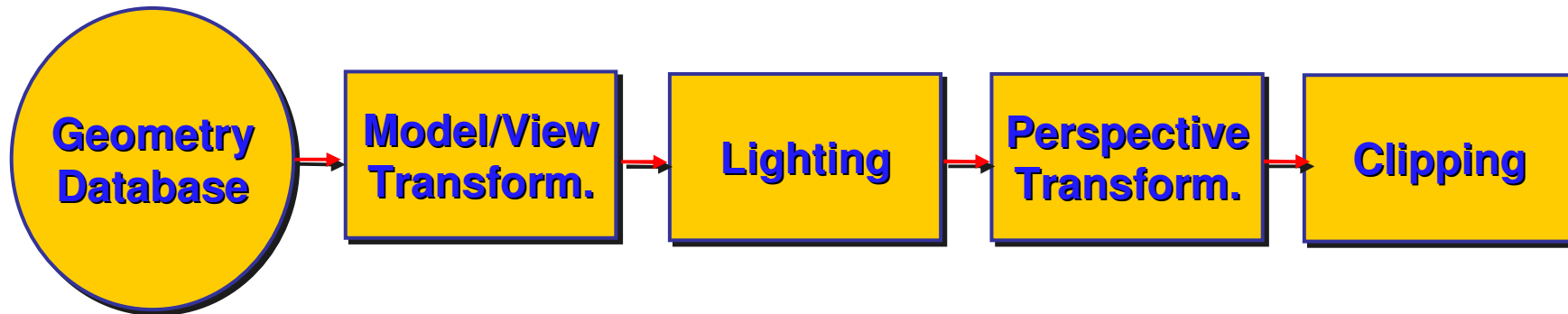
- lighting
  - compute brightness based on property of material and light position(s)
  - computation is performed *per-vertex*

# Perspective Transformation



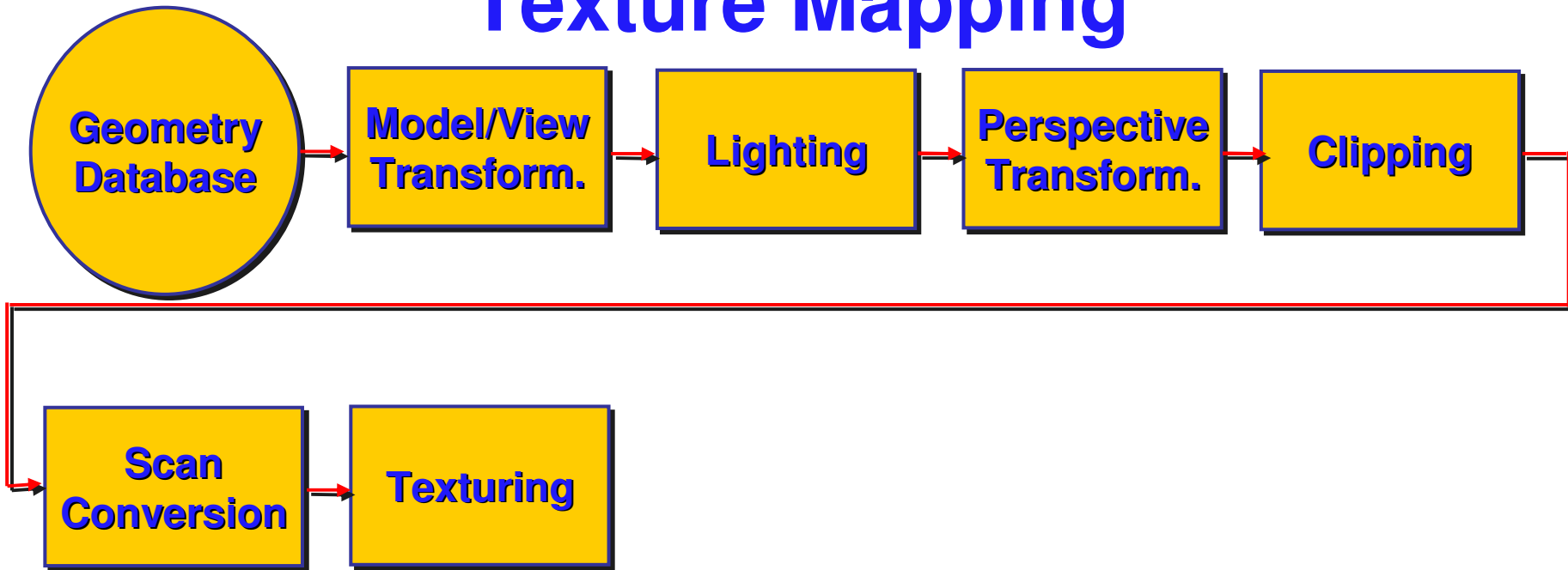
- perspective transformation
  - projecting the geometry onto the image plane
  - projective transformations and model/view transformations can all be expressed with 4x4 matrix operations

# Clipping



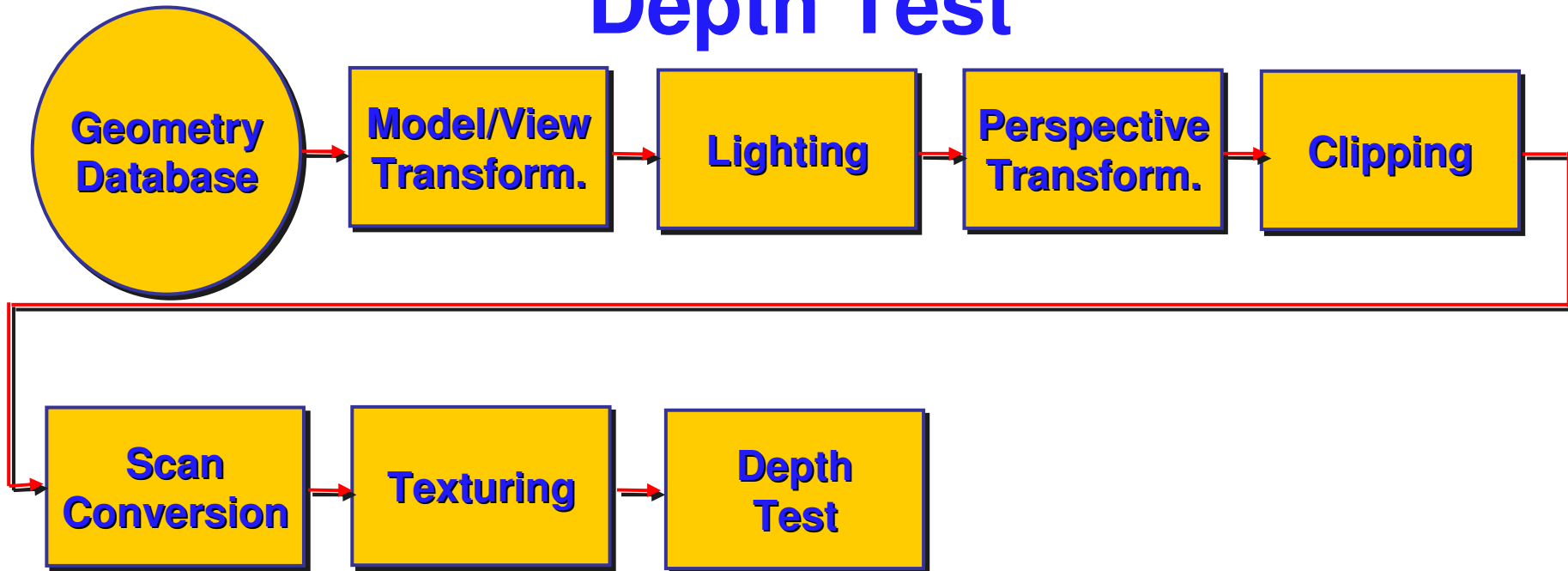
- clipping
  - removal of parts of the geometry that fall outside the visible screen or window region
  - may require *re-tessellation* of geometry

# Texture Mapping



- texture mapping
  - “gluing images onto geometry”
  - color of every fragment is altered by looking up a new color value from an image

# Depth Test



- depth test
  - remove parts of geometry hidden behind other geometric objects
  - perform on every individual fragment
    - other approaches (later)



# Pipeline Advantages

- modularity: logical separation of different components
- easy to parallelize
  - earlier stages can already work on new data while later stages still work with previous data
  - similar to pipelining in modern CPUs
  - but much more aggressive parallelization possible (special purpose hardware!)
  - important for hardware implementations
- only local knowledge of the scene is necessary

# Pipeline Disadvantages

- limited flexibility
- some algorithms would require different ordering of pipeline stages
  - hard to achieve while still preserving compatibility
- only local knowledge of scene is available
  - shadows
  - global illumination

# OpenGL (briefly)

# OpenGL

- started in 1989 by Kurt Akeley
  - based on IRIS\_GL by SGI
- API to graphics hardware
- designed to exploit hardware optimized for display and manipulation of 3D graphics
- implemented on many different platforms
- low level, powerful flexible
- pipeline processing
  - set state as needed

# Graphics State

- set the state once, remains until overwritten
  - `glColor3f(1.0, 1.0, 0.0)` → set color to yellow
  - `glClearColor(0.0, 0.0, 0.2)` → dark blue bg
  - `glEnable(LIGHT0)` → turn on light
  - `glEnable(GL_DEPTH_TEST)` → hidden surf.

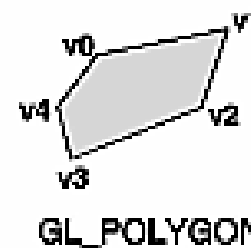
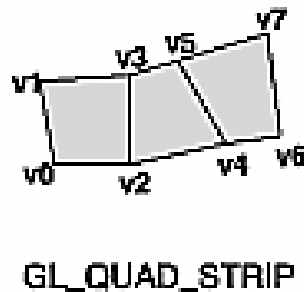
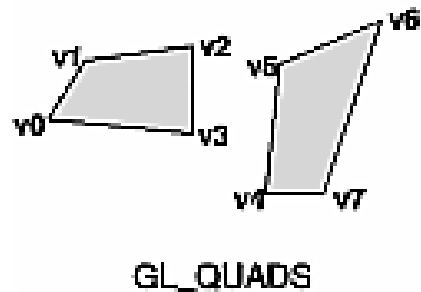
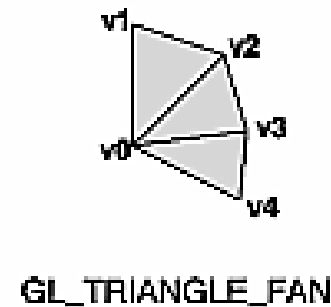
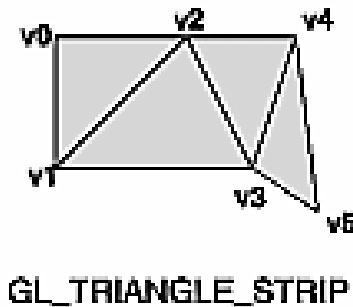
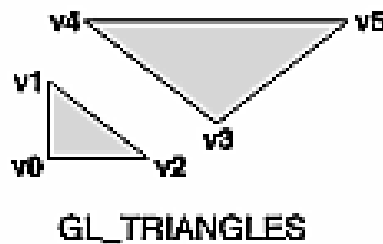
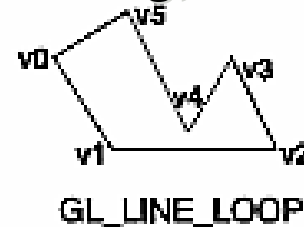
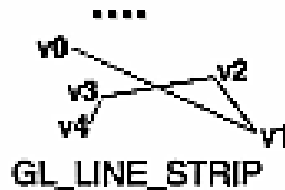
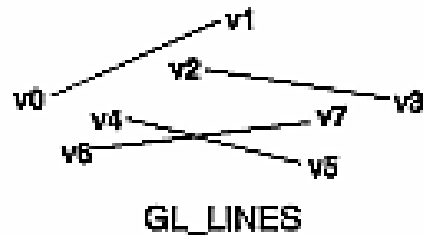
# Geometry Pipeline

- tell it how to interpret geometry
  - `glBegin(<mode of geometric primitives>)`
  - `mode = GL_TRIANGLE, GL_POLYGON, etc.`
- feed it vertices
  - `glVertex3f(-1.0, 0.0, -1.0)`
  - `glVertex3f(1.0, 0.0, -1.0)`
  - `glVertex3f(0.0, 1.0, -1.0)`
- tell it you're done
  - `glEnd()`

# Open GL: Geometric Primitives

● v4  
 ● v0 ● v3  
 ● v1 ● v2  
 GL\_POINTS

**glPointSize( float size);**  
**glLineWidth( float width);**  
**glColor3f( float r, float g, float b);**



# Code Sample

```
void display()
{
    glClearColor(0.0, 0.0, 0.0, 0.0);
    glClear(GL_COLOR_BUFFER_BIT);
    glColor3f(0.0, 1.0, 0.0);
    glBegin(GL_POLYGON);
        glVertex3f(0.25, 0.25, -0.5);
        glVertex3f(0.75, 0.25, -0.5);
        glVertex3f(0.75, 0.75, -0.5);
        glVertex3f(0.25, 0.75, -0.5);
    glEnd();
    glFlush();
}
```

- more OpenGL as course continues



**GLUT**

# GLUT: OpenGL Utility Toolkit

- developed by Mark Kilgard (also from SGI)
- simple, portable window manager
  - opening windows
    - handling graphics contexts
  - handling input with callbacks
    - keyboard, mouse, window reshape events
  - timing
    - idle processing, idle events
- designed for small-medium size applications
- distributed as binaries
  - free, but not open source

# GLUT Draw World

```
int main(int argc, char **argv)
{
    glutInit( &argc, argv );
    glutInitDisplayMode( GLUT_RGB |
                        GLUT_DOUBLE | GLUT_DEPTH );
    glutInitWindowSize( 640, 480 );
    glutCreateWindow( "openGLDemo" );
    glutDisplayFunc( DrawWorld );
    glutIdleFunc(Idle);
    glClearColor( 1,1,1 );
    glutMainLoop();

    return 0;          // never reached
}
```

# Event-Driven Programming

- main loop not under your control
  - vs. procedural
- control flow through event **callbacks**
  - redraw the window now
  - key was pressed
  - mouse moved
- callback functions called from main loop when events occur
  - mouse/keyboard state setting vs. redrawing

# GLUT Callback Functions

```
// you supply these kind of functions
```

```
void reshape(int w, int h);  
void keyboard(unsigned char key, int x, int y);  
void mouse(int but, int state, int x, int y);  
void idle();  
void display();
```

```
// register them with glut
```

```
glutReshapeFunc(reshape);  
glutKeyboardFunc(keyboard);  
glutMouseFunc(mouse);  
glutIdleFunc(idle);  
glutDisplayFunc(display);
```

```
void glutDisplayFunc (void (*func)(void));  
void glutKeyboardFunc (void (*func)(unsigned char key, int x, int y));  
void glutIdleFunc (void (*func)());  
void glutReshapeFunc (void (*func)(int width, int height));
```

# Display Function

```
void DrawWorld() {
    glMatrixMode( GL_PROJECTION );
    glLoadIdentity();
    glMatrixMode( GL_MODELVIEW );
    glLoadIdentity();
    glClear( GL_COLOR_BUFFER_BIT );
    angle += 0.05;           //animation
    glRotatef(angle,0,0,1);  //animation
    ... // redraw triangle in new position
    glutSwapBuffers();
}
```

- directly update value of angle variable
  - so, why doesn't it spin?
  - only called in response to window/input event!

# Idle Function

```
void Idle() {  
    angle += 0.05;  
    glutPostRedisplay();  
}
```

- called from main loop when no user input
- should return control to main loop quickly
  - update value of angle variable here
  - then request redraw event from GLUT
    - draw function will be called next time through
- continues to rotate even when no user action

# Keyboard/Mouse Callbacks

- do minimal work
- request redraw for display
- example: keypress triggering animation
  - do not create loop in input callback!
    - what if user hits another key during animation?
  - shared/global variables to keep track of state
  - display function acts on current variable value



# Labs

# Thursday Lab

- labs start Thursday
  - 11-12: morning not ideal, it's before lecture
  - 3-4,4-5: better, try to attend afternoon if possible
- project 0
  - make sure you can compile OpenGL/GLUT
    - useful to test home computing environment
  - template: spin around obj files
  - todo: change rotation axis
  - do not hand in, not graded
  - <http://www.ugrad.cs.ubc.ca/~cs314/Vmay2005/a0>
- project 1
  - transformations
  - more on Thursday after transformations lecture

# Remote Graphics

- OpenGL does not work well remotely
  - very slow
- only one user can use graphics at a time
  - current X server doesn't give priority to console, just does first come first served
  - problem: FCFS policy = confusion/chaos
- solution: console user gets priority
  - only use graphics remotely if nobody else logged on
    - with 'who' command, ":0" is console person
  - stop using graphics if asked by console user via email
  - or console user can reboot machine out from under you