



University of British Columbia
CPSC 314 Computer Graphics
May-June 2005

Tamara Munzner

Intro, Math Review, OpenGL Pipeline

Week 1, Tue May 10

<http://www.ugrad.cs.ubc.ca/~cs314/Vmay2005>

Introduction

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Expectations

- hard course!
 - heavy programming and heavy math
- fun course!
 - graphics programming addictive, create great demos
- programming prereq
 - CPSC 216 (Program Design and Data Structures)
 - course language is C++/C
- math prereq
 - MATH 200 (Calculus III)
 - MATH 221/223 (Matrix Algebra/Linear Algebra)

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Course Structure

- 45% programming projects
 - 9% project 1 (building beasts with cubes and math)
 - 9% project 2 (flying)
 - 9% project 3 (shaded terrain)
 - 18% project 4 (create your own graphics game)
- 25% final
- 15% midterm (week 4, Tue 5/31)
- 15% written assignments
 - 5% each HW 1/2/3
- programming projects and homeworks synchronized

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Programming Projects

- structure
 - C++, Linux
 - OK to cross-platform develop on Windows
 - OpenGL graphics library
 - GLUT for platform-independent windows/UI
 - face to face grading in lab
- Hall of Fame
 - project 1: building beasts
 - previous years: elephants, birds, poodles
 - project 4: create your own graphics game

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Late Work

- 3 grace days
 - for unforeseen circumstances
 - strong recommendation: don't use early in term
 - handing in late uses up automatically unless you tell us
 - otherwise: 25% per 24 hours
 - no work accepted after solutions handed out
 - exception: severe illness or crisis, as per UBC rules
 - let me know ASAP (in person or email)
 - must also turn in form with documentation
- <http://www.ugrad.cs.ubc.ca/~cs314/Vjan2005/illness.html>

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Regrading

- to request assignment or exam regrade
 - must submit detailed written explanation of why you think the grader was incorrect for the particular problem that you are disputing
- I may regrade entire assignment
 - thus even if I agree with your original request, your score may end up higher or lower

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Course Information

- course web page is main resource
 - <http://www.ugrad.cs.ubc.ca/~cs314/Vmay2005>
 - updated often, reload frequently
- newsgroup is `ubc.courses.cpsc.414`
 - note old course number still used
 - readable on or off campus
- (no WebCT)

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Labs

- attend two labs per week, 3 sessions each
 - Tue/Thu 11-12, 3-4, 4-5
 - Thursday afternoon better than Thu morning
 - Tuesdays: example problems in spirit of written assignments and exams
 - Thursdays: help with programming projects
 - no deliverables
 - strongly recommend that you attend

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Teaching Staff

- instructor: Dr. Munzner
 - tmm@cs.ubc.ca
 - office hrs in CICS 011
 - Mon 4:30-5:30
- TAs: Warren Cheung, Greg Kempe
 - wcheung@cs.ubc.ca
 - kempe@cs.ubc.ca
- use newsgroup not email for all questions that other students might care about

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Required Reading



- Fundamentals of Computer Graphics
 - Peter Shirley, AK Peters



- OpenGL Programming Guide, v 1.4
 - OpenGL Architecture Review Board
 - v 1.1 available for free online

- readings posted on schedule page

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Learning OpenGL

- this is a graphics course using OpenGL
 - not a course *on* OpenGL
- upper-level class: learning APIs mostly on your own
 - only minimal lecture coverage
 - basics, some of the tricky bits
 - OpenGL Red Book
 - many tutorial sites on the web
 - nehe.gamedev.net

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Plagiarism and Cheating

- don't cheat, I will prosecute
 - insult to your fellow students and to me
- programming and assignment writeups must be individual work
 - exception: project 3 can be team of two
 - can discuss ideas, browse Web
 - but cannot just copy code or answers
- you must be able to explain algorithms during face-to-face demo
 - or no credit for that part of assignment, possible prosecution

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Citation

- cite all sources of information
 - web sites, study group members, books
 - README for programming projects
 - end of writeup for written assignments
 - <http://www.ugrad.cs.ubc.ca/~cs314/Vmay2005/policies.html#plag>

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What is Computer Graphics?

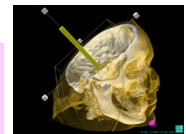
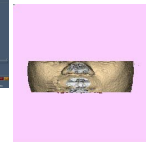
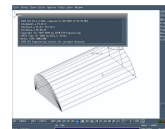
- create or manipulate images with computer
 - this course: algorithms for image generation



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What is CG used for?

- graphical user interfaces
 - modeling systems
 - applications
- simulation & visualization



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What is CG used for?

- movies
 - animation
 - special effects



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What is CG used for?

- computer games



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What is CG used for?

- images
 - design
 - advertising
 - art



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What is CG used for?

- virtual reality / immersive displays

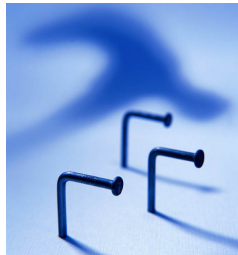


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Real or CG?

<http://www.alias.com/eng/etc/fakeorfoto/quiz.html>

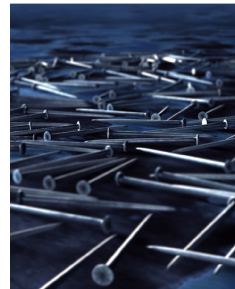
1



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Real or CG?

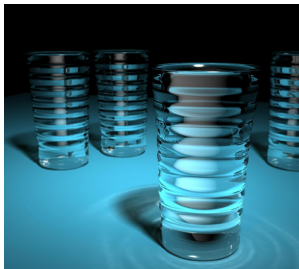
2



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Real or CG?

3



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Real or CG?

4



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This Course

- we cover
 - basic **algorithms** for
 - rendering – displaying models
 - (modeling – generating models)
 - (animation – generating motion)
 - programming in OpenGL, C++
- we do not cover
 - art/design issues
 - commercial software packages

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Other Graphics Courses

- CPSC 424: Geometric Modeling
- CPSC 426: Computer Animation

- CPSC 514: Image-based Modeling and Rendering
- CPSC 526: Computer Animation
- CPSC 533A: Digital Geometry
- CPSC 533B: Animation Physics
- CPSC 533C: Information Visualization

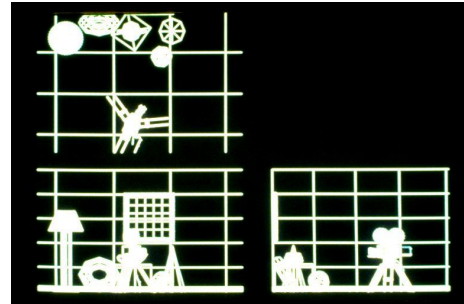
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Rendering

- creating images from models
 - geometric objects
 - lines, polygons, curves, curved surfaces
 - camera
 - pinhole camera, lens systems, orthogonal
 - shading
 - light interacting with material
- Pixar Shutterbug series
 - Williams and Siegel using Renderman, 1990
 - www.siggraph.org/education/materials/HyperGraph/shutbug.htm

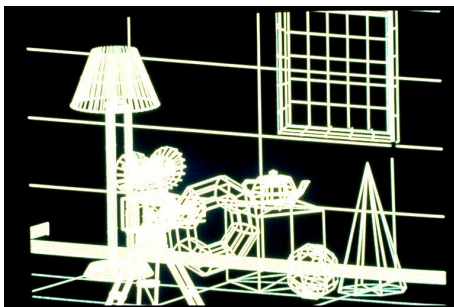
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Modelling Transformation: Object Placement



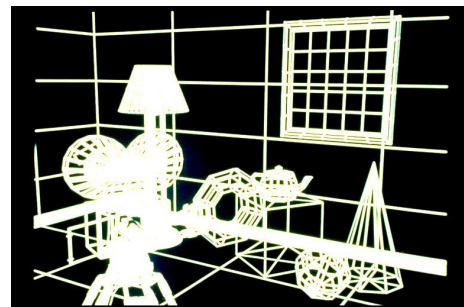
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Viewing Transformation: Camera Placement



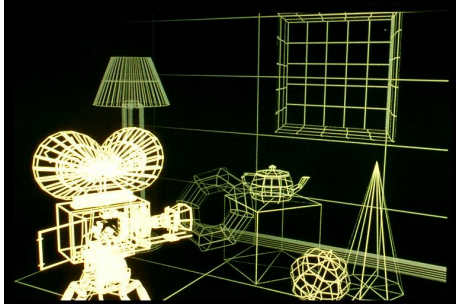
29

Perspective Projection



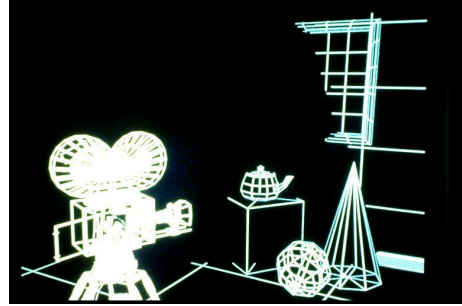
30

Depth Cueing



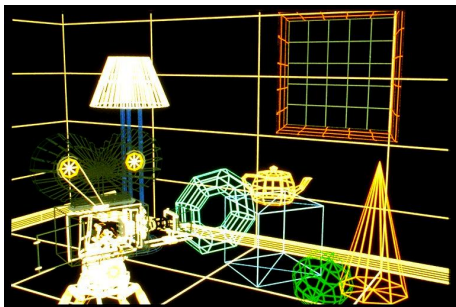
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Depth Clipping



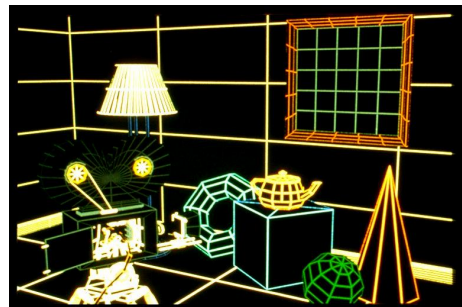
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Colored Wireframes



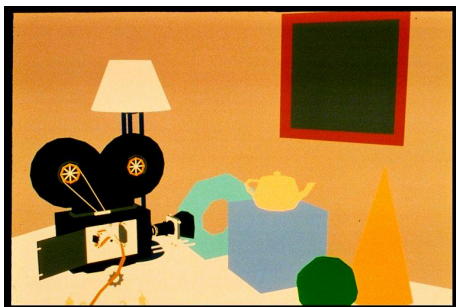
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Hidden Line Removal



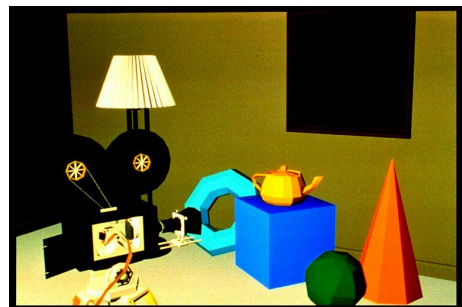
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Hidden Surface Removal



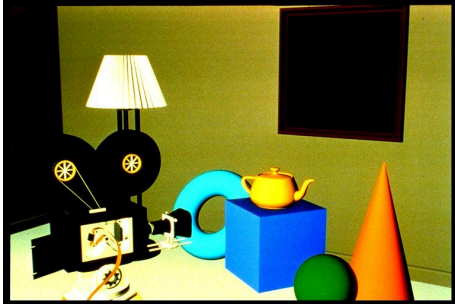
35

Per-Polygon Shading



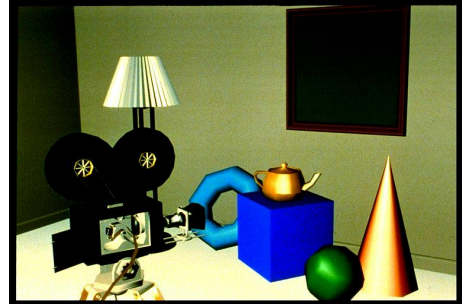
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Gouraud Shading



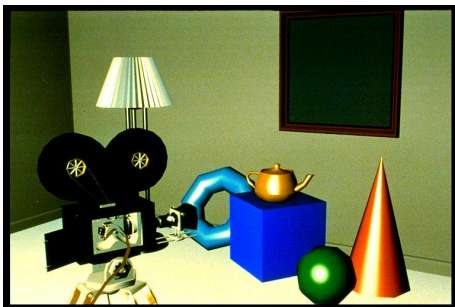
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Specular Reflection



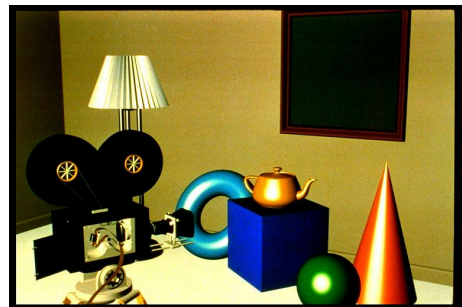
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Phong Shading



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Curved Surfaces



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Complex Lighting and Shading



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Texture Mapping



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Displacement Mapping



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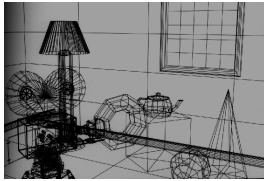
Reflection Mapping



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Modelling

- generating models
 - lines, curves, polygons, smooth surfaces
 - digital geometry



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Animation

- generating motion
 - interpolating between frames, states

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Math Review

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Reading

- FCG Chapter 2: Miscellaneous Math
 - except for 2.11 (covered later)
 - skim 2.2 (sets and maps), 2.3 (quadratic eqns)
 - important: 2.3 (trig), 2.4 (vectors), 2.5-6 (lines) 2.10 (linear interpolation)
 - skip 2.5.1, 2.5.3, 2.7.1, 2.7.3, 2.8, 2.9
- FCG Chapter 4.1-4.25: Linear Algebra
 - skim 4.1 (determinants)
 - important: 4.2.1-4.2.2, 4.2.5 (matrices)
 - skip 4.2.3-4, 4.2.6-7 (matrix numerical analysis)

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Textbook Errata

- list at <http://www.cs.utah.edu/~shirley/fcg/errata>
 - p 29, 32, 39 have potential to confuse

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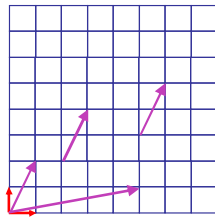
Notation: Scalars, Vectors, Matrices

- scalar a
 - (lower case, italic)
- vector $\mathbf{a} = [a_1 \ a_2 \ \dots \ a_n]$
 - (lower case, bold)
- matrix $\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$
 - (upper case, bold)

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Vectors

- arrow: length and direction
 - oriented segment in nD space
- offset / displacement
 - location if given origin



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Column vs. Row Vectors

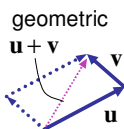
- row vectors $\mathbf{a}_{row} = [a_1 \ a_2 \ \dots \ a_n]$
- column vectors $\mathbf{a}_{col} = \begin{bmatrix} a_1 \\ a_2 \\ \dots \\ a_n \end{bmatrix}$
- switch back and forth with transpose

$$\mathbf{a}_{col}^T = \mathbf{a}_{row}$$

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Vector-Vector Addition

- add: vector + vector = vector
- parallelogram rule
 - tail to head, complete the triangle



algebraic

$$\mathbf{u} + \mathbf{v} = \begin{bmatrix} u_1 + v_1 \\ u_2 + v_2 \\ u_3 + v_3 \end{bmatrix}$$

examples:

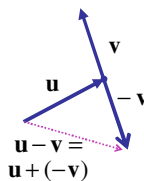
$$(3,2) + (6,4) = (9,6)$$

$$(2,5,1) + (3,1,-1) = (5,6,0)$$

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Vector-Vector Subtraction

- subtract: vector - vector = vector
- $$\mathbf{u} - \mathbf{v} = \begin{bmatrix} u_1 - v_1 \\ u_2 - v_2 \\ u_3 - v_3 \end{bmatrix}$$



$$(3,2) - (6,4) = (-3,-2)$$

$$(2,5,1) - (3,1,-1) = (-1,4,0)$$

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Vector-Vector Subtraction

- subtract: vector - vector = vector

$\mathbf{u} - \mathbf{v} = \mathbf{u} + (-\mathbf{v})$

$$\mathbf{u} - \mathbf{v} = \begin{bmatrix} u_1 - v_1 \\ u_2 - v_2 \\ u_3 - v_3 \end{bmatrix}$$

$(3,2) - (6,4) = (-3,-2)$
 $(2,5,1) - (3,1,-1) = (-1,4,0)$

argument reversal

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Scalar-Vector Multiplication

- multiply: scalar * vector = vector
- vector is scaled

$$a * \mathbf{u} = (a * u_1, a * u_2, a * u_3)$$

$2 * (3,2) = (6,4)$
 $.5 * (2,5,1) = (1,2.5,.5)$

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Vector-Vector Multiplication

- multiply: vector * vector = scalar
- dot product, aka inner product

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} \bullet \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = (u_1 * v_1) + (u_2 * v_2) + (u_3 * v_3)$$

$\mathbf{u} \bullet \mathbf{v}$

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Vector-Vector Multiplication

- multiply: vector * vector = scalar
- dot product, aka inner product
- geometric interpretation
 - lengths, angles
 - can find angle between two vectors

$$\mathbf{u} \bullet \mathbf{v} = \|\mathbf{u}\| \|\mathbf{v}\| \cos \theta$$

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Dot Product Geometry

- can find length of projection of u onto v

$$\mathbf{u} \bullet \mathbf{v} = \|\mathbf{u}\| \|\mathbf{v}\| \cos \theta$$

$$\|\mathbf{u}\| \cos \theta = \frac{\mathbf{u} \bullet \mathbf{v}}{\|\mathbf{v}\|}$$

- as lines become perpendicular, $\mathbf{u} \bullet \mathbf{v} \rightarrow 0$

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Dot Product Example

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} \bullet \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = (u_1 * v_1) + (u_2 * v_2) + (u_3 * v_3)$$

$$\begin{bmatrix} 6 \\ 1 \\ 2 \end{bmatrix} \bullet \begin{bmatrix} 1 \\ 7 \\ 3 \end{bmatrix} = (6 * 1) + (1 * 7) + (2 * 3) = 6 + 7 + 6 = 19$$

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Vector-Vector Multiplication, The Sequel

- multiply: vector * vector = vector
- cross product
 - algebraic
 - geometric

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} \times \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} u_2v_3 - u_3v_2 \\ u_3v_1 - u_1v_3 \\ u_1v_2 - u_2v_1 \end{bmatrix}$$

$\|\mathbf{a} \times \mathbf{b}\| = \|\mathbf{u}\|\|\mathbf{v}\|\sin \theta$

- $\|\mathbf{a} \times \mathbf{b}\|$ parallelogram area
- $\mathbf{a} \times \mathbf{b}$ perpendicular to parallelogram

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RHS vs LHS Coordinate Systems

- right-handed coordinate system **convention**
 - right hand rule: index finger x, second finger y; right thumb points up
 - $\mathbf{z} = \mathbf{x} \times \mathbf{y}$
- left-handed coordinate system
 - left hand rule: index finger x, second finger y; left thumb points down
 - $\mathbf{z} = \mathbf{x} \times \mathbf{y}$

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Basis Vectors

- take any two vectors that are **linearly independent** (nonzero and nonparallel)
 - can use linear combination of these to define any other vector:

$$\mathbf{c} = w_1\mathbf{a} + w_2\mathbf{b}$$

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Orthonormal Basis Vectors

- if basis vectors are **orthonormal** (orthogonal and unit length)
 - we have Cartesian coordinate system
 - familiar Pythagorean definition of distance

orthonormal algebraic properties

$$\|\mathbf{x}\| = \|\mathbf{y}\| = 1,$$

$$\mathbf{x} \cdot \mathbf{y} = 0$$

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Basis Vectors and Origins

- coordinate system**: just basis vectors
 - can only specify offset: vectors
- coordinate frame**: basis vectors and origin
 - can specify location as well as offset: points

$$\mathbf{p} = \mathbf{o} + x\mathbf{i} + y\mathbf{j}$$

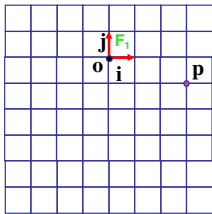
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Working with Frames

$$\mathbf{p} = \mathbf{o} + x\mathbf{i} + y\mathbf{j}$$

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Working with Frames

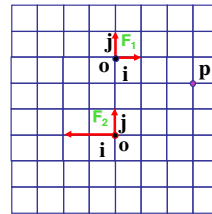


$$\mathbf{p} = \mathbf{o} + x\mathbf{i} + y\mathbf{j}$$

$$\mathbf{F}_1 \quad \mathbf{p} = (3, -1)$$

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Working with Frames



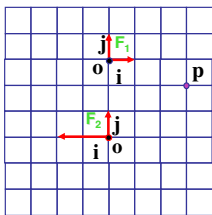
$$\mathbf{p} = \mathbf{o} + x\mathbf{i} + y\mathbf{j}$$

$$\mathbf{F}_1 \quad \mathbf{p} = (3, -1)$$

$$\mathbf{F}_2$$

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Working with Frames



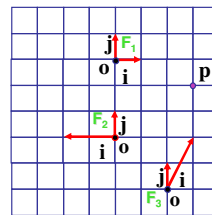
$$\mathbf{p} = \mathbf{o} + x\mathbf{i} + y\mathbf{j}$$

$$\mathbf{F}_1 \quad \mathbf{p} = (3, -1)$$

$$\mathbf{F}_2 \quad \mathbf{p} = (-1.5, 2)$$

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Working with Frames



$$\mathbf{p} = \mathbf{o} + x\mathbf{i} + y\mathbf{j}$$

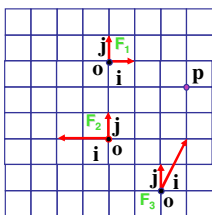
$$\mathbf{F}_1 \quad \mathbf{p} = (3, -1)$$

$$\mathbf{F}_2 \quad \mathbf{p} = (-1.5, 2)$$

$$\mathbf{F}_3$$

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Working with Frames



$$\mathbf{p} = \mathbf{o} + x\mathbf{i} + y\mathbf{j}$$

$$\mathbf{F}_1 \quad \mathbf{p} = (3, -1)$$

$$\mathbf{F}_2 \quad \mathbf{p} = (-1.5, 2)$$

$$\mathbf{F}_3 \quad \mathbf{p} = (1, 2)$$

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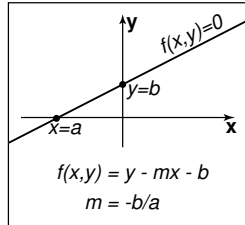
Named Coordinate Frames

- origin and basis vectors $\mathbf{p} = \mathbf{o} + ax + by + cz$
- pick canonical frame of reference
 - then don't have to store origin, basis vectors
 - just $\mathbf{p} = (a, b, c)$
 - convention: Cartesian orthonormal one on previous slide
- handy to specify others as needed
 - airplane nose, looking over your shoulder, ...
 - really common ones given names in CG
 - object, world, camera, screen, ...

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Lines

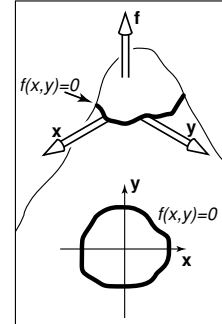
- slope-intercept form
 - $y = mx + b$
- implicit form
 - $y - mx - b = 0$
 - $Ax + By + C = 0$
 - $f(x,y) = 0$



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Implicit Functions

- find where function is 0
 - plug in (x,y) , check if
 - 0: on line
 - < 0 : inside
 - > 0 : outside
- analogy: terrain
 - sea level: $f=0$
 - altitude: function value
 - topo map: equal-value contours (level sets)



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Implicit Circles

- $f(x,y) = (x - x_c)^2 + (y - y_c)^2 - r^2$
 - circle is points (x,y) where $f(x,y) = 0$
- $p = (x,y), c = (x_c, y_c): (\mathbf{p} - \mathbf{c}) \cdot (\mathbf{p} - \mathbf{c}) - r^2 = 0$
 - points \mathbf{p} on circle have property that vector from \mathbf{c} to \mathbf{p} dotted with itself has value r^2
- $\|\mathbf{p} - \mathbf{c}\|^2 - r^2 = 0$
 - points \mathbf{p} on the circle have property that squared distance from \mathbf{c} to \mathbf{p} is r^2
- $\|\mathbf{p} - \mathbf{c}\| - r = 0$
 - points \mathbf{p} on circle are those a distance r from center point \mathbf{c}

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Parametric Curves

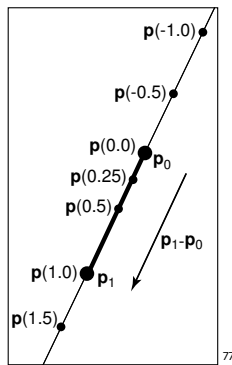
- parameter: index that changes continuously
 - (x,y) : point on curve
 - t : parameter
- vector form
 - $\mathbf{p} = f(t)$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} g(t) \\ h(t) \end{bmatrix}$$

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2D Parametric Lines

- $\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} x_0 + t(x_1 - x_0) \\ y_0 + t(y_1 - y_0) \end{bmatrix}$
- $\mathbf{p}(t) = \mathbf{p}_0 + t(\mathbf{p}_1 - \mathbf{p}_0)$
- $\mathbf{p}(t) = \mathbf{o} + t(\mathbf{d})$
- start at point \mathbf{p}_0 , go towards \mathbf{p}_1 , according to parameter t
 - $\mathbf{p}(0) = \mathbf{p}_0, \mathbf{p}(1) = \mathbf{p}_1$



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Linear Interpolation

- parametric line is example of general concept
 - $\mathbf{p}(t) = \mathbf{p}_0 + t(\mathbf{p}_1 - \mathbf{p}_0)$
 - interpolation
 - \mathbf{p} goes through \mathbf{a} at $t = 0$
 - \mathbf{p} goes through \mathbf{b} at $t = 1$
 - linear
 - weights $t, (1-t)$ are linear polynomials in t

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Matrix-Matrix Addition

- add: matrix + matrix = matrix

$$\begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} + \begin{bmatrix} n_{11} & n_{12} \\ n_{21} & n_{22} \end{bmatrix} = \begin{bmatrix} n_{11} + m_{11} & n_{12} + m_{12} \\ n_{21} + m_{21} & n_{22} + m_{22} \end{bmatrix}$$

- example

$$\begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix} + \begin{bmatrix} -2 & 5 \\ 7 & 1 \end{bmatrix} = \begin{bmatrix} 1+(-2) & 3+5 \\ 2+7 & 4+1 \end{bmatrix} = \begin{bmatrix} -1 & 8 \\ 9 & 5 \end{bmatrix}$$

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Scalar-Matrix Multiplication

- multiply: scalar * matrix = matrix

$$a \begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} = \begin{bmatrix} a * m_{11} & a * m_{12} \\ a * m_{21} & a * m_{22} \end{bmatrix}$$

- example

$$3 \begin{bmatrix} 2 & 4 \\ 1 & 5 \end{bmatrix} = \begin{bmatrix} 3*2 & 3*4 \\ 3*1 & 3*5 \end{bmatrix} = \begin{bmatrix} 6 & 12 \\ 3 & 15 \end{bmatrix}$$

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Matrix-Matrix Multiplication

- row by column

$$\begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} \begin{bmatrix} n_{11} & n_{12} \\ n_{21} & n_{22} \end{bmatrix} = \begin{bmatrix} p_{11} & p_{12} \\ p_{21} & p_{22} \end{bmatrix}$$

$$p_{11} = m_{11}n_{11} + m_{12}n_{21}$$

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Matrix-Matrix Multiplication

- row by column

$$\begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} \begin{bmatrix} n_{11} & n_{12} \\ n_{21} & n_{22} \end{bmatrix} = \begin{bmatrix} p_{11} & p_{12} \\ p_{21} & p_{22} \end{bmatrix}$$

$$p_{11} = m_{11}n_{11} + m_{12}n_{21}$$

$$p_{21} = m_{21}n_{11} + m_{22}n_{21}$$

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Matrix-Matrix Multiplication

- row by column

$$\begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} \begin{bmatrix} n_{11} & n_{12} \\ n_{21} & n_{22} \end{bmatrix} = \begin{bmatrix} p_{11} & p_{12} \\ p_{21} & p_{22} \end{bmatrix}$$

$$p_{11} = m_{11}n_{11} + m_{12}n_{21}$$

$$p_{21} = m_{21}n_{11} + m_{22}n_{21}$$

$$p_{12} = m_{11}n_{12} + m_{12}n_{22}$$

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Matrix-Matrix Multiplication

- row by column

$$\begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} \begin{bmatrix} n_{11} & n_{12} \\ n_{21} & n_{22} \end{bmatrix} = \begin{bmatrix} p_{11} & p_{12} \\ p_{21} & p_{22} \end{bmatrix}$$

$$p_{11} = m_{11}n_{11} + m_{12}n_{21}$$

$$p_{21} = m_{21}n_{11} + m_{22}n_{21}$$

$$p_{12} = m_{11}n_{12} + m_{12}n_{22}$$

$$p_{22} = m_{21}n_{12} + m_{22}n_{22}$$

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Matrix-Matrix Multiplication

- row by column

$$\begin{bmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{bmatrix} \begin{bmatrix} n_{11} & n_{12} \\ n_{21} & n_{22} \end{bmatrix} = \begin{bmatrix} p_{11} & p_{12} \\ p_{21} & p_{22} \end{bmatrix}$$

$$p_{11} = m_{11}n_{11} + m_{12}n_{21}$$

$$p_{21} = m_{21}n_{11} + m_{22}n_{21}$$

$$p_{12} = m_{11}n_{12} + m_{12}n_{22}$$

$$p_{22} = m_{21}n_{12} + m_{22}n_{22}$$

- noncommutative: $\mathbf{AB} \neq \mathbf{BA}$

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Matrix Multiplication

- can only multiply if
number of left rows = number of right cols

- legal

$$\begin{bmatrix} a & b & c \\ e & f & g \end{bmatrix} \begin{bmatrix} h & i \\ j & k \\ l & m \end{bmatrix}$$

- undefined

$$\begin{bmatrix} a & b & c \\ e & f & g \\ o & p & q \end{bmatrix} \begin{bmatrix} h & i \\ j & k \end{bmatrix}$$

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Matrix-Vector Multiplication

- points as column vectors: postmultiply

$$\begin{bmatrix} x' \\ y' \\ z' \\ h' \end{bmatrix} = \begin{bmatrix} m_{11} & m_{12} & m_{13} & m_{14} \\ m_{21} & m_{22} & m_{23} & m_{24} \\ m_{31} & m_{32} & m_{33} & m_{34} \\ m_{41} & m_{42} & m_{43} & m_{44} \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ h \end{bmatrix} \quad \mathbf{p}' = \mathbf{M}\mathbf{p}$$

- points as row vectors: premultiply

$$[x' \ y' \ z' \ h'] = [x \ y \ z \ h] \begin{bmatrix} m_{11} & m_{12} & m_{13} & m_{14} \\ m_{21} & m_{22} & m_{23} & m_{24} \\ m_{31} & m_{32} & m_{33} & m_{34} \\ m_{41} & m_{42} & m_{43} & m_{44} \end{bmatrix} \quad \mathbf{p}'^T = \mathbf{p}^T \mathbf{M}^T$$

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Matrices

- transpose

$$\begin{bmatrix} m_{11} & m_{12} & m_{13} & m_{14} \\ m_{21} & m_{22} & m_{23} & m_{24} \\ m_{31} & m_{32} & m_{33} & m_{34} \\ m_{41} & m_{42} & m_{43} & m_{44} \end{bmatrix}^T = \begin{bmatrix} m_{11} & m_{21} & m_{31} & m_{41} \\ m_{12} & m_{22} & m_{32} & m_{42} \\ m_{13} & m_{23} & m_{33} & m_{43} \\ m_{14} & m_{24} & m_{34} & m_{44} \end{bmatrix}$$

- identity

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

- inverse $\mathbf{A}\mathbf{A}^{-1} = \mathbf{I}$
 - not all matrices are invertible

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Matrices and Linear Systems

- linear system of n equations, n unknowns

$$3x + 7y + 2z = 4$$

$$2x - 4y - 3z = -1$$

$$5x + 2y + z = 1$$

- matrix form $\mathbf{Ax} = \mathbf{b}$

$$\begin{bmatrix} 3 & 7 & 2 \\ 2 & -4 & -3 \\ 5 & 2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 4 \\ -1 \\ -1 \end{bmatrix}$$

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Rendering Pipeline

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Reading

- RB Chap. Introduction to OpenGL
- RB Chap. State Management and Drawing Geometric Objects
- RB Appendix Basics of GLUT
 - (Basics of Aux in v 1.1)

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Rendering

- goal
 - transform computer models into images
 - may or may not be photo-realistic
- interactive rendering
 - fast, but limited quality
 - roughly follows a fixed patterns of operations
 - rendering pipeline
- offline rendering
 - ray-tracing
 - global illumination

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Rendering

- tasks that need to be performed (in no particular order):
 - project all 3D geometry onto the image plane
 - geometric transformations
 - determine which primitives or parts of primitives are visible
 - hidden surface removal
 - determine which pixels a geometric primitive covers
 - scan conversion
 - compute the color of every visible surface point
 - lighting, shading, texture mapping

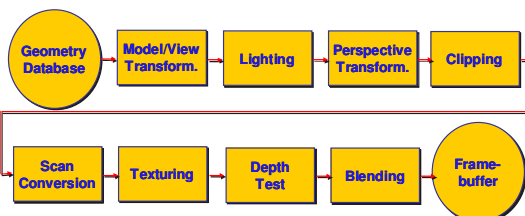
93

Rendering Pipeline

- what is the pipeline?
 - abstract model for sequence of operations to transform geometric model into digital image
 - abstraction of the way graphics hardware works
 - underlying model for application programming interfaces (APIs) that allow programming of graphics hardware
 - OpenGL
 - Direct 3D
- actual implementation details of rendering pipeline will vary

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Rendering Pipeline



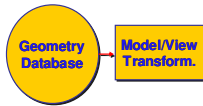
95

Geometry Database

- geometry database
 - application-specific data structure for holding geometric information
 - depends on specific needs of application
 - triangle soup, points, mesh with connectivity information, curved surface

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Model/View Transformation



- modeling transformation
 - map all geometric objects from local coordinate system into world coordinates
- viewing transformation
 - map all geometry from world coordinates into camera coordinates

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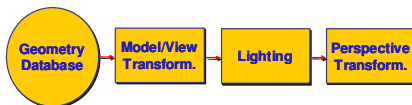
Lighting



- lighting
 - compute brightness based on property of material and light position(s)
 - computation is performed *per-vertex*

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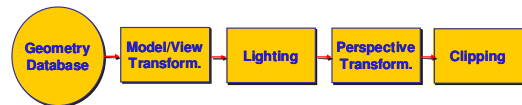
Perspective Transformation



- perspective transformation
 - projecting the geometry onto the image plane
 - projective transformations and model/view transformations can all be expressed with 4x4 matrix operations

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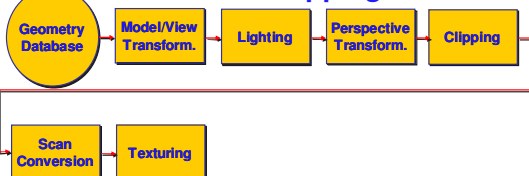
Clipping



- clipping
 - removal of parts of the geometry that fall outside the visible screen or window region
 - may require *re-tessellation* of geometry

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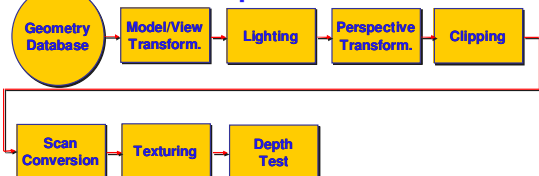
Texture Mapping



- texture mapping
 - “gluing images onto geometry”
 - color of every fragment is altered by looking up a new color value from an image

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Depth Test



- depth test
 - remove parts of geometry hidden behind other geometric objects
 - perform on every individual fragment
 - other approaches (later)

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Pipeline Advantages

- modularity: logical separation of different components
- easy to parallelize
 - earlier stages can already work on new data while later stages still work with previous data
 - similar to pipelining in modern CPUs
 - but much more aggressive parallelization possible (special purpose hardware!)
 - important for hardware implementations
- only local knowledge of the scene is necessary

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Pipeline Disadvantages

- limited flexibility
- some algorithms would require different ordering of pipeline stages
 - hard to achieve while still preserving compatibility
- only local knowledge of scene is available
 - shadows
 - global illumination

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OpenGL (briefly)

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OpenGL

- started in 1989 by Kurt Akeley
 - based on IRIS_GL by SGI
- API to graphics hardware
- designed to exploit hardware optimized for display and manipulation of 3D graphics
- implemented on many different platforms
- low level, powerful flexible
- pipeline processing
 - set state as needed

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Graphics State

- set the state once, remains until overwritten
 - glColor3f(1.0, 1.0, 0.0) → set color to yellow
 - glClearColor(0.0, 0.0, 0.2) → dark blue bg
 - glEnable(LIGHT0) → turn on light
 - glEnable(GL_DEPTH_TEST) → hidden surf.

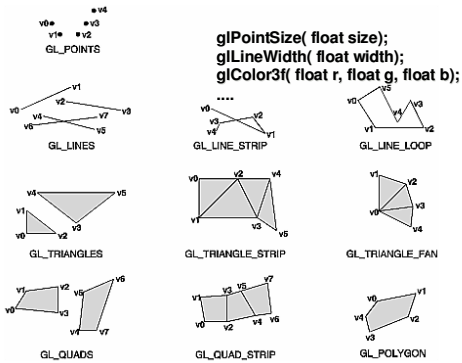
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Geometry Pipeline

- tell it how to interpret geometry
 - glBegin(<mode of geometric primitives>)
 - mode = GL_TRIANGLE, GL_POLYGON, etc.
- feed it vertices
 - glVertex3f(-1.0, 0.0, -1.0)
 - glVertex3f(1.0, 0.0, -1.0)
 - glVertex3f(0.0, 1.0, -1.0)
- tell it you're done
 - glEnd()

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Open GL: Geometric Primitives



Code Sample

```

void display()
{
    glClearColor(0.0, 0.0, 0.0, 0.0);
    glClear(GL_COLOR_BUFFER_BIT);
    glColor3f(0.0, 1.0, 0.0);
    glBegin(GL_POLYGON);
        glVertex3f(0.25, 0.25, -0.5);
        glVertex3f(0.75, 0.25, -0.5);
        glVertex3f(0.75, 0.75, -0.5);
        glVertex3f(0.25, 0.75, -0.5);
    glEnd();
    glFlush();
}

```

- more OpenGL as course continues

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GLUT

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GLUT: OpenGL Utility Toolkit

- developed by Mark Kilgard (also from SGI)
 - simple, portable window manager
 - opening windows
 - handling graphics contexts
 - handling input with callbacks
 - keyboard, mouse, window reshape events
 - timing
 - idle processing, idle events
 - designed for small-medium size applications
 - distributed as binaries
 - free, but not open source
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GLUT Draw World

```

int main(int argc, char **argv)
{
    glutInit( &argc, argv );
    glutInitDisplayMode( GLUT_RGB |
                        GLUT_DOUBLE | GLUT_DEPTH);
    glutInitWindowSize( 640, 480 );
    glutCreateWindow( "openGLDemo" );
    glutDisplayFunc( DrawWorld );
    glutIdleFunc(Idle);
    glClearColor( 1,1,1 );
    glutMainLoop();

    return 0;    // never reached
}

```

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Event-Driven Programming

- main loop not under your control
 - vs. procedural
 - control flow through event **callbacks**
 - redraw the window now
 - key was pressed
 - mouse moved
 - callback functions called from main loop when events occur
 - mouse/keyboard state setting vs. redrawing
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GLUT Callback Functions

```
// you supply these kind of functions
void reshape(int w, int h);
void keyboard(unsigned char key, int x, int y);
void mouse(int but, int state, int x, int y);
void idle();
void display();

// register them with glut
glutReshapeFunc(reshape);
glutKeyboardFunc(keyboard);
glutMouseFunc(mouse);
glutIdleFunc(idle);
glutDisplayFunc(display);

void glutDisplayFunc(void (*func)(void));
void glutKeyboardFunc(void (*func)(unsigned char key, int x, int y));
void glutIdleFunc(void (*func)());
void glutReshapeFunc(void (*func)(int width, int height));
```

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Display Function

```
void DrawWorld() {
    glMatrixMode( GL_PROJECTION );
    glLoadIdentity();
    glMatrixMode( GL_MODELVIEW );
    glLoadIdentity();
    glClear( GL_COLOR_BUFFER_BIT );
    angle += 0.05; //animation
    glRotatef(angle,0,0,1); //animation
    ... // redraw triangle in new position
    glutSwapBuffers();
}
```

- directly update value of angle variable
 - so, why doesn't it spin?
 - only called in response to window/input event!

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Idle Function

```
void Idle() {
    angle += 0.05;
    glutPostRedisplay();
}
```

- called from main loop when no user input
- should return control to main loop quickly
 - update value of angle variable here
 - then request redraw event from GLUT
 - draw function will be called next time through
- continues to rotate even when no user action

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Keyboard/Mouse Callbacks

- do minimal work
- request redraw for display
- example: keypress triggering animation
 - do not create loop in input callback!
 - what if user hits another key during animation?
 - shared/global variables to keep track of state
 - display function acts on current variable value

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Labs

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Thursday Lab

- labs start Thursday
 - 11-12: morning not ideal, it's before lecture
 - 3-4,4-5: better, try to attend afternoon if possible
- project 0
 - make sure you can compile OpenGL/GLUT
 - useful to test home computing environment
 - template: spin around obj files
 - todo: change rotation axis
 - do not hand in, not graded
 - <http://www.ugrad.cs.ubc.ca/~cs314/Vmay2005/a0>
- project 1
 - transformations
 - more on Thursday after transformations lecture

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Remote Graphics

- OpenGL does not work well remotely
 - very slow
- only one user can use graphics at a time
 - current X server doesn't give priority to console, just does first come first served
 - problem: FCFS policy = confusion/chaos
- solution: console user gets priority
 - only use graphics remotely if nobody else logged on
 - with 'who' command, ":0" is console person
 - stop using graphics if asked by console user via email
 - or console user can reboot machine out from under you

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