

# CPSC 213

## Introduction to Computer Systems

Unit 1c

### Instance Variables and Structs

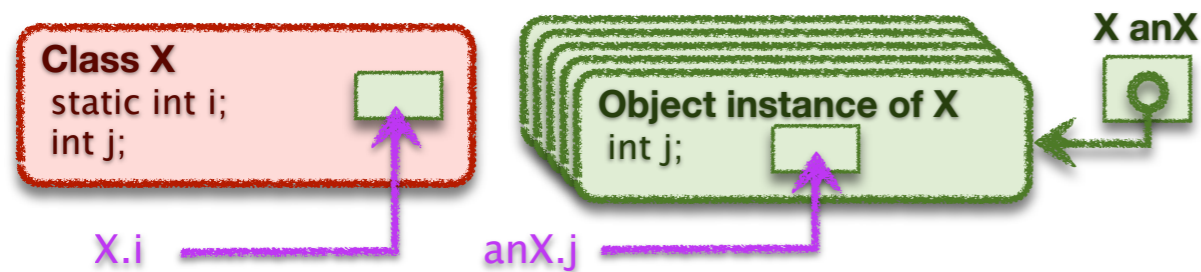
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## Reading

- ▶ Companion
  - 2.4.4-2.4.6
- ▶ Textbook
  - 2ed: 3.9.1
  - 1ed: 3.9.1

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## Instance Variables



- ▶ Variables that are an instance of a class or struct
  - created dynamically
  - many instances of the same variable can co-exist
- ▶ Java vs C
  - Java: **objects** are instances of non-static variables of a **class**
  - C: **structs** are named variable groups, instance is also called a struct
- ▶ Accessing an instance variable
  - requires a reference to a particular object (pointer to a struct)
  - then variable name chooses a variable in that object (struct)

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## Structs in C (S4-instance-var)



- ▶ A struct is a
  - collection of variables of arbitrary type, allocated and accessed together
- ▶ Declaration
  - similar to declaring a Java class without methods
  - name is “struct” plus name provided by programmer
  - static `struct D d0;`
  - dynamic `struct D* d1;`
- ▶ Access
  - static `d0.e = d0.f;`
  - dynamic `d1->e = d1->f;`

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# Struct Allocation

```
struct D {
  int e;
  int f;
};
```

▶ Static structs are allocated by the compiler

### Static Memory Layout

```
struct D d0;
```

0x1000: value of d0.e  
0x1004: value of d0.f

▶ Dynamic structs are allocated at runtime

- the variable that stores the struct pointer may be static or dynamic
- the struct itself is allocated when the program calls **malloc**

### Static Memory Layout

```
struct D* d1;
```

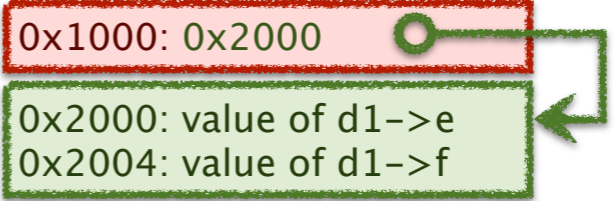
0x1000: value of d1

```
struct D {
  int e;
  int f;
};
```

• runtime allocation of dynamic struct

```
void foo () {
  d1 = (struct D*) malloc (sizeof(struct D));
}
```

• assume that this code allocates the struct at address 0x2000



# Struct Access

```
struct D {
  int e;
  int f;
};
```

▶ Static and dynamic differ by an extra memory access

- dynamic structs have dynamic address that must be read from memory
- in both cases the offset to variable from base of struct is static

```
d0.e = d0.f;
```

```
d1->e = d1->f;
```

```
m[0x1000] ← m[0x1004]
```

```
m[m[0x1000]+0] ← m[m[0x1000]+4]
```

```
r[0] ← 0x1000
r[1] ← m[r[0]+4]
m[r[0]] ← r[1]
```

```
r[0] ← 0x1000
r[1] ← m[r[0]]
r[2] ← m[r[1]+4]
m[r[1]] ← r[2] load d1
```

```
struct D {
  int e;
  int f;
};
```

```
d0.e = d0.f;
```

```
d1->e = d1->f;
```

```
r[0] ← 0x1000
r[1] ← m[r[0]+4]
m[r[0]] ← r[1]
```

```
r[0] ← 0x1000
r[1] ← m[r[0]]
r[2] ← m[r[1]+4]
m[r[1]] ← r[2] load d1
```

```
ld $0x1000, r0 # r0 = address of d0
ld 4(r0), r1 # r0 = d0.f
st r1, (r0) # d0.e = d0.f
```

```
ld $0x1000, r0 # r0 = address of d1
ld (r0), r1 # r1 = d1
ld 4(r1), r2 # r2 = d1->f
st r2, (r1) # d1->e = d1->f
```

▶ The revised load/store base plus offset instructions

- dynamic base address in a register plus a static offset (displacement)

```
ld 4(r1), r2
```

# The Revised Load-Store ISA

## ▶ Machine format for base + offset

- note that the offset will in our case always be a multiple of 4
- also note that we only have a single hex digit in instruction to store it
- and so, we will store offset / 4 in the instruction

## ▶ The Revised ISA

Name	Semantics	Assembly	Machine
<i>load immediate</i>	$r[d] \leftarrow v$	ld \$v, rd	0d-- vvvvvvvv
<i>load base+offset</i>	$r[d] \leftarrow m[r[s]+(o=p*4)]$	ld o(rs), rd	1psd
<i>load indexed</i>	$r[d] \leftarrow m[r[s]+4*r[i]]$	ld (rs,ri,4), rd	2sid
<i>store base+offset</i>	$m[r[d]+(o=p*4)] \leftarrow r[s]$	st rs, o(rd)	3spd
<i>store indexed</i>	$m[r[d]+4*r[i]] \leftarrow r[s]$	st rs, (rd,ri,4)	4sdi