

# **Graphical Models**

## Bayesian Networks

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# Learning objectives

- what is a Bayesian network?
  - factorization
  - conditional independencies
- || how are they related?
- how to read it from the graph
- equivalent class of Bayesian networks

# Representing distributions

give a large number of random variables  $X_1, \dots, X_n$

how to **represent**  $P(X_1, \dots, X_n)$

- number of parameters **exponential in n** (curse of dimensionality)
- need to leverage some **structure** in **P**

# Independence & representation

for **discrete** domains  $Val(X_i) = \{1, \dots, D\} \quad \forall i$

- representation of  $P(\mathbf{X} = x_1, \dots, x_n) = \theta_{i_1, \dots, i_n}$ 
  - exponential in n:  $\mathcal{O}(D^n)$

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assuming **independence**  $X_i \perp X_j \quad \forall i, j$

- **linear**-sized representation:

$$P(\mathbf{X} = x_1^d, \dots, x_n^d) = \prod_i P(X_i = x_i^d) = \prod_i \theta_{i,d}$$

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a particular assignment (d) in discrete domain

independence assumption is too restrictive

# Independence and representation

For a **Gaussian** distribution:

- *from quadratic*

$$P(\mathbf{X} = \mathbf{x}_1, \dots, \mathbf{x}_n) = \frac{1}{\sqrt{|2\pi\Sigma|}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu})\right)$$

*n x n matrix*

- *to a linear-sized representation*

$$P(\mathbf{X} = \mathbf{x}_1, \dots, \mathbf{x}_n) = \prod_i \frac{1}{\sqrt{2\pi\sigma_i^2}} \exp\left(-\frac{1}{2\sigma_i^2}(x_i - \mu_i)^2\right)$$

# Using the chain rule

- pick an *ordering* of the variables

$$P(\mathbf{X}) = P(X_1)P(X_2 \mid X_1)\dots P(X_n \mid X_1, \dots, X_{n-1})$$

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- parameterize each term
- does it compress the representation?
  - original #params  $D^n - 1$

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- parameterize each term
- does it compress the representation?
  - original #params  $D^n - 1$
  - new #params  $(D - 1) + (D^2 - D) + \dots + (D^n - D^{n-1}) = D^n - 1$ 
$$\overline{P(X_1)} \quad \overline{P(X_2 \mid X_1)} \quad \overline{P(X_n \mid X_1, \dots, X_{n-1})}$$

## Using the **chain rule**

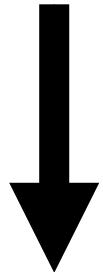
$$P(\mathbf{X}) = P(X_1)P(X_2 \mid X_1)\dots P(X_n \mid X_1, \dots, X_{n-1})$$

simplify the conditionals

- flexible compression of P

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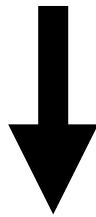
simplify the conditionals

- flexible compression of P

A Bayesian network!

## Chain rule; simplification

$$P(\mathbf{X}) = P(X_1)P(X_2 \mid X_1)P(X_3 \mid X_1, X_2) \dots P(X_n \mid X_1, \dots, X_{n-1})$$

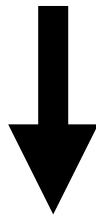


an **extreme** form of simplification

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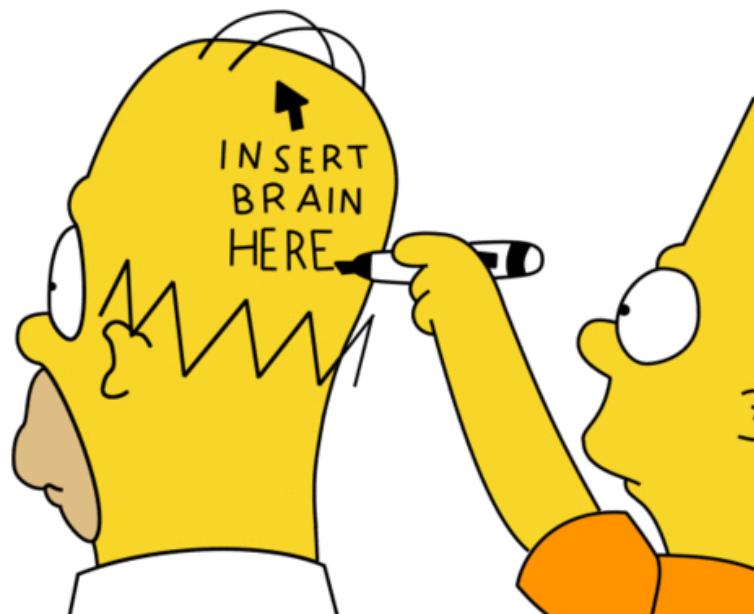
$$P(\mathbf{X}) = P(X_1)P(X_2 \mid X_1)P(X_3 \mid X_1) \dots P(X_n \mid X_1)$$

$$\# \text{ params} \quad (D - 1) + (n - 1)(D^2 - D)$$

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$$\mathcal{O}(nD^2) \quad \text{instead of } \mathcal{O}(D^n)$$

# Idiot Bayes

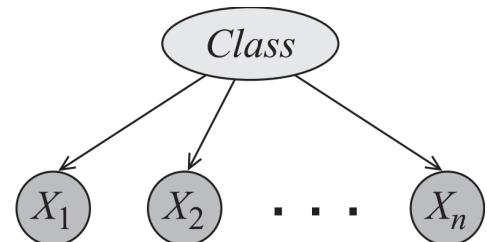


## Or **naive Bayes**

$$P(class, \mathbf{X}) = P(class)P(X_2 | class)P(X_3 | class)\dots P(X_n | class)$$

independence assumption:  $X_i \perp \mathbf{X}_{-i} | class$

for classification (use **Bayes rule**)



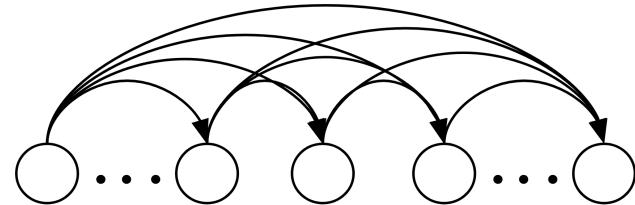
$$P(class | \mathbf{X}) \propto P(class)P(X_2 | class)P(X_3 | class)\dots P(X_n | class)$$

**Example:** medical diagnosis (what if two symptoms are correlated?)

## Simplifying the chain rule; general case

simplify the full conditionals:

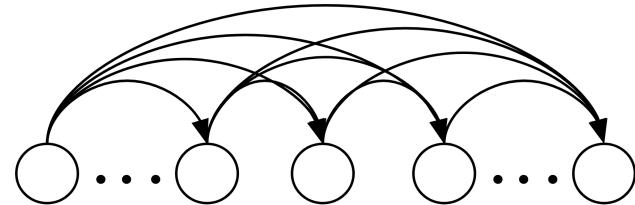
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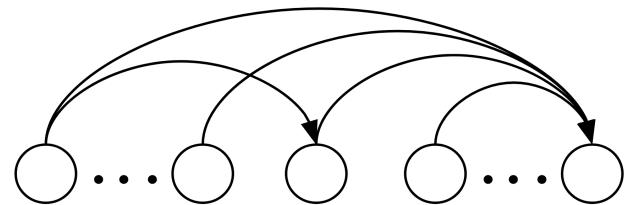
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Bayesian network

represent it using a  
**Directed Acyclic Graph (DAG)**

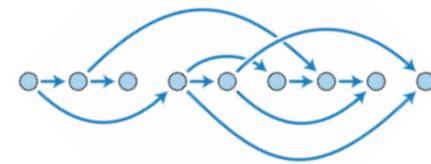
$$P(\mathbf{X}) = \prod_i P(X_i \mid Pa_{X_i})$$



a topological ordering

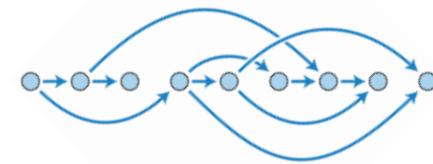
## DAG; identification

- identifying a DAG
  - has a topological ordering?
  - no directed path from a node to itself?



# DAG; identification

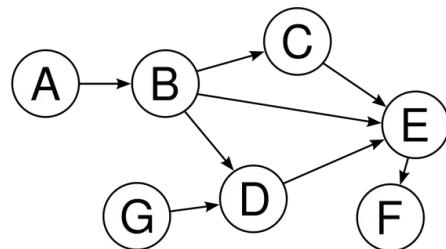
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## Example:

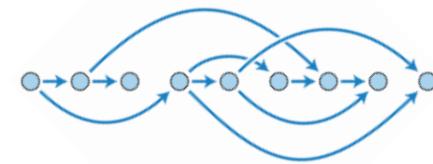
is this a DAG?

a topological ordering:  $G, A, B, D, C, E, F$



# DAG; identification

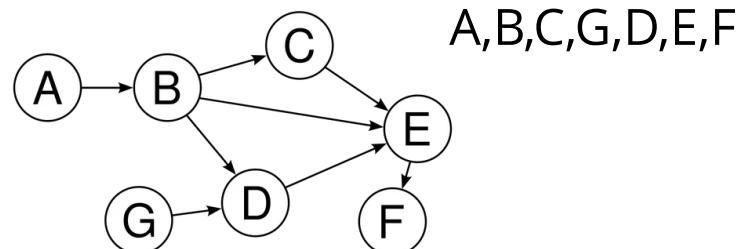
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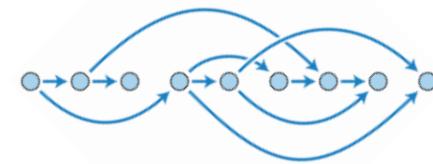
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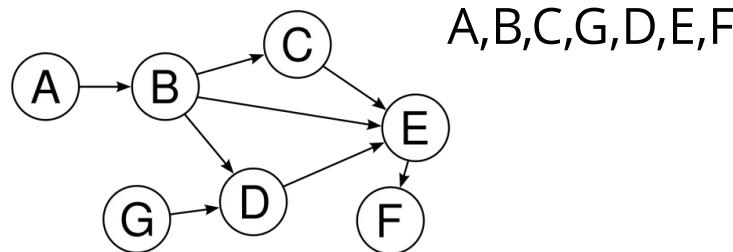
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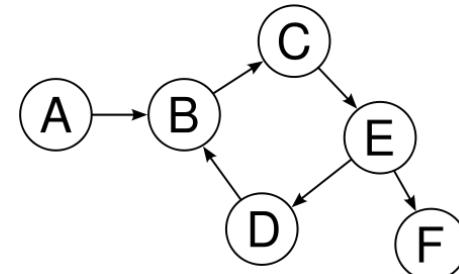
## Example:

is this a DAG?

a topological ordering:  $G, A, B, D, C, E, F$

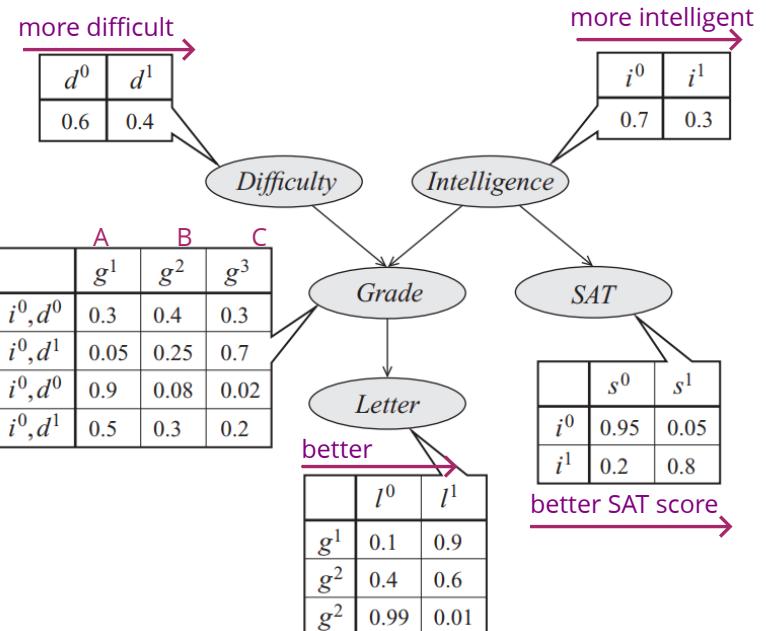


how about this?



# Bayesian network (BN); example

$$P(I, D, G, S, L) = P(I)P(D)P(G | I, D)P(S | I)P(L | G)$$



# Bayesian network (BN); example

$$P(I, D, G, S, L) = P(I)P(D)P(G | I, D)P(S | I)P(L | G)$$

Conditional Probability Table (CPT)

	$d^0$	$d^1$
$d^0$	0.6	0.4
$d^1$		

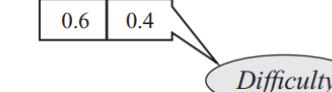
more difficult

	A	B	C
$i^0, d^0$	0.3	0.4	0.3
$i^0, d^1$	0.05	0.25	0.7
$i^1, d^0$	0.9	0.08	0.02
$i^1, d^1$	0.5	0.3	0.2

	$l^0$	$l^1$
$g^1$	0.1	0.9
$g^2$	0.4	0.6
$g^3$	0.99	0.01

	$s^0$	$s^1$
$i^0$	0.95	0.05
$i^1$	0.2	0.8

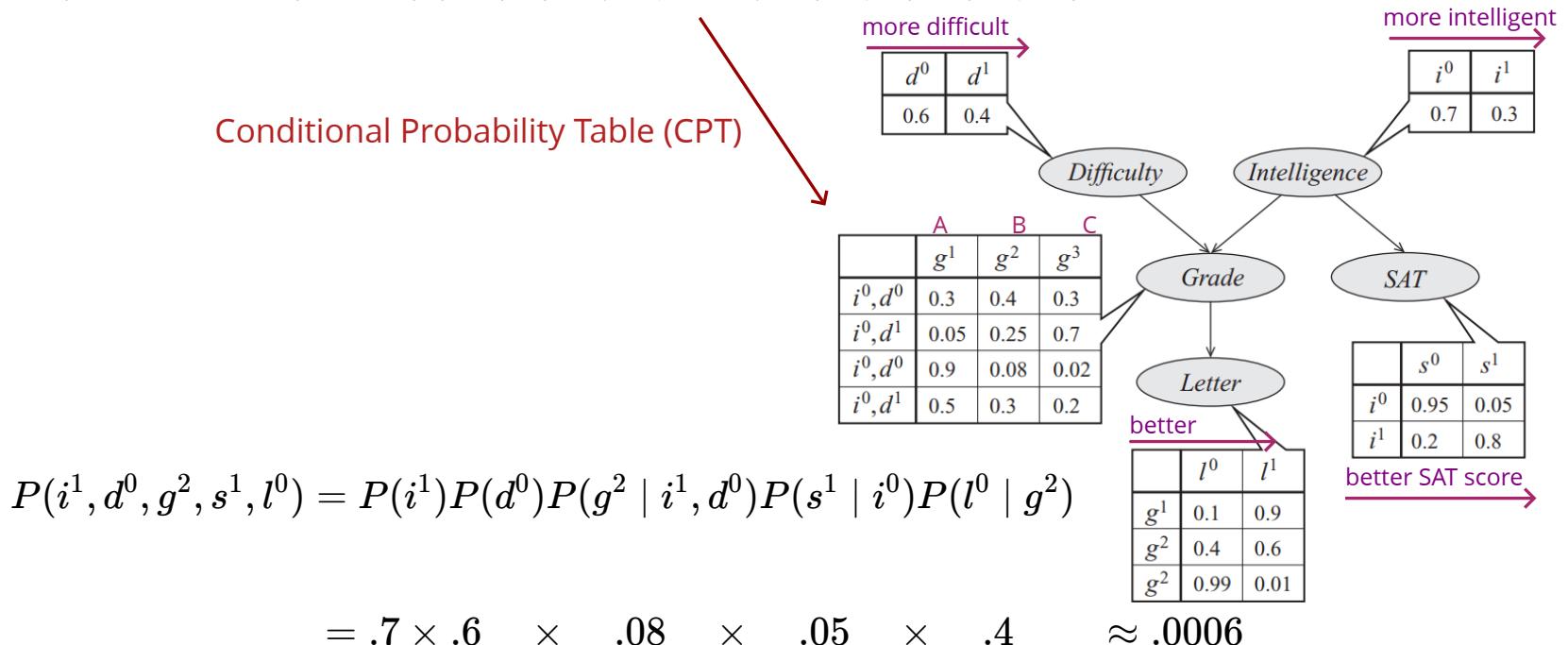
better SAT score



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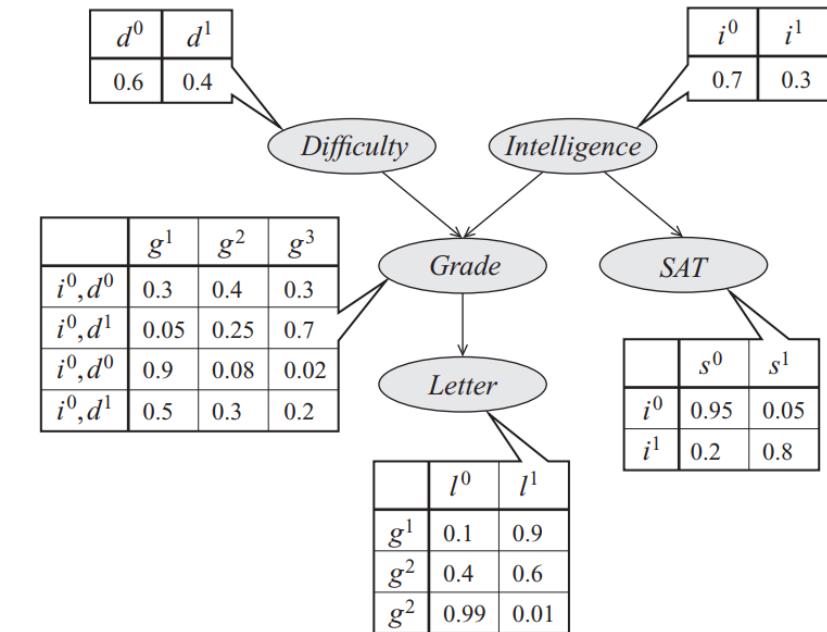


# Intuition for reasoning in a BN

answering probabilistic queries

$$P(\mathbf{Y} = \mathbf{y} \mid \mathbf{E} = e) \quad ?$$

evidence



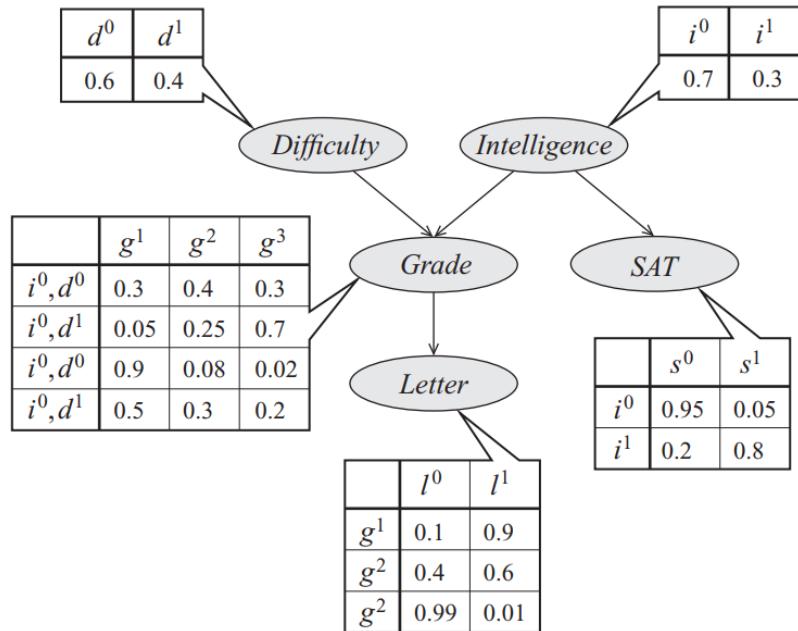
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$$P(L = l^1 \mid S = s^1) = \frac{P(L=l^1, S=s^1)}{P(S=s^1)}$$



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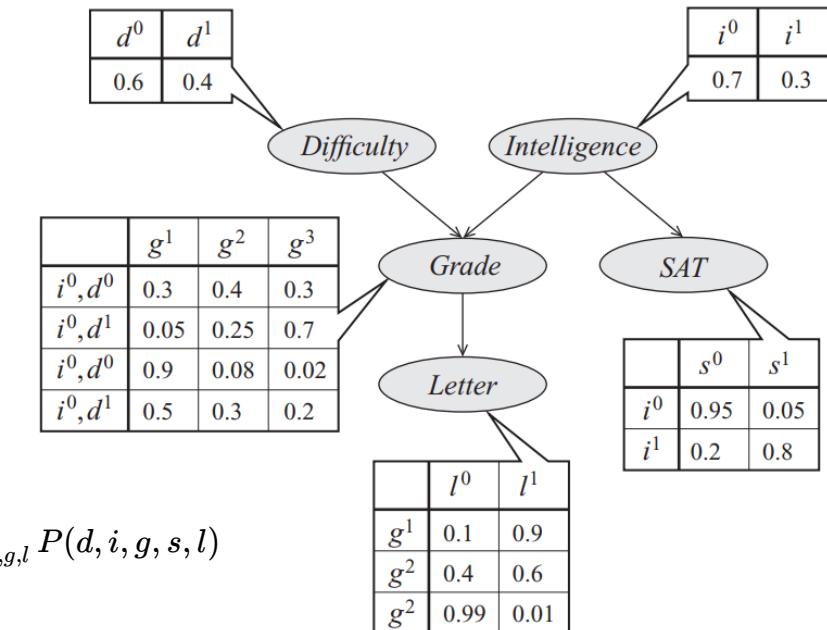
$$P(L = l^1 \mid S = s^1) = \frac{P(L=l^1, S=s^1)}{P(S=s^1)}$$



$$P(S = s^1) = \sum_{d,i,g,l} P(d, i, g, s, l)$$

an **inference** problem

- how to calculate? ... later



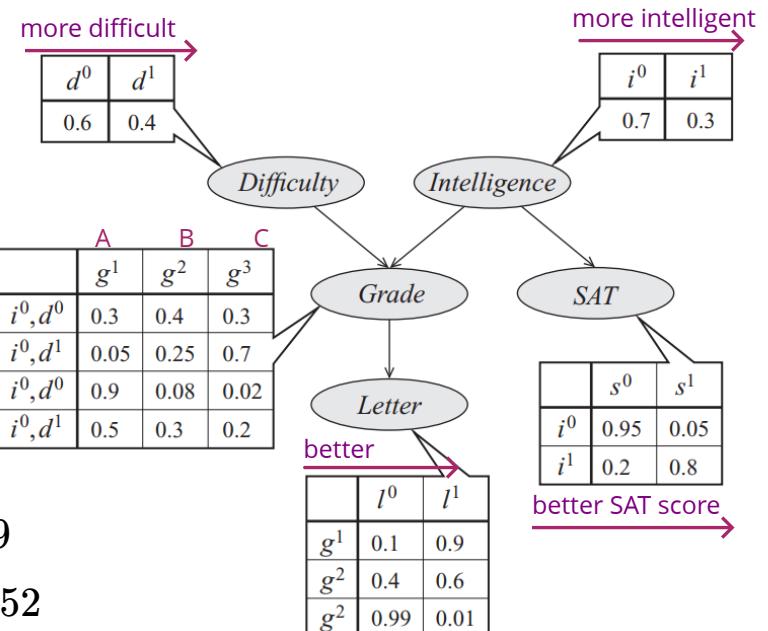
# Intuition for reasoning in a BN

## causal reasoning (top-down)

- marginal (prior) probability
  - of getting a good letter

$$P(l^1) \approx .50$$

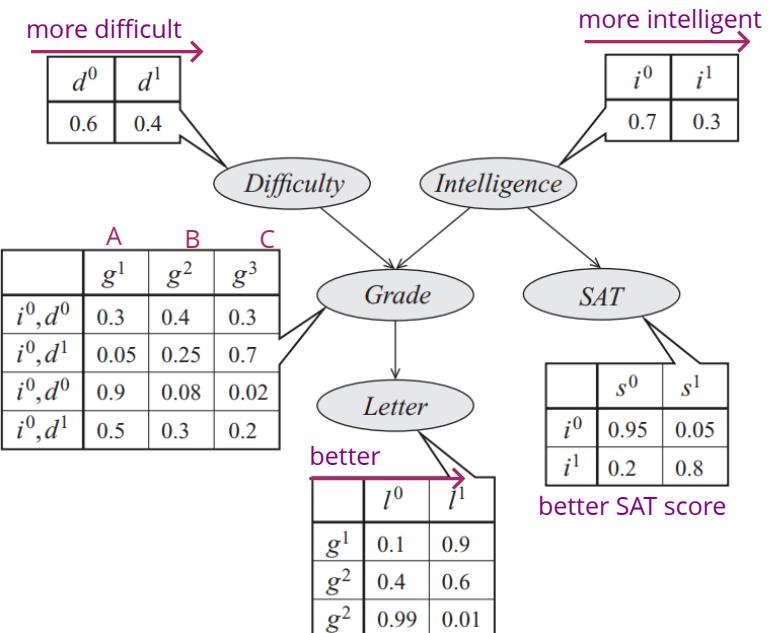
- marginal posterior
  - given low intelligence  $P(l^1 | i^0) \approx .389$
  - ... and an easy exam  $P(l^1 | i^0, d^0) \approx .52$



# Intuition for reasoning in a BN

## evidential reasoning (bottom-up)

- (marginal) prior
  - of a high intelligence  $P(i^1) \approx .30$
- (marginal) posterior
  - given a bad letter  $P(i^1 | l^0) \approx .14$
  - ... and a bad grade  $P(i^1 | l^0, g^3) \approx .08$

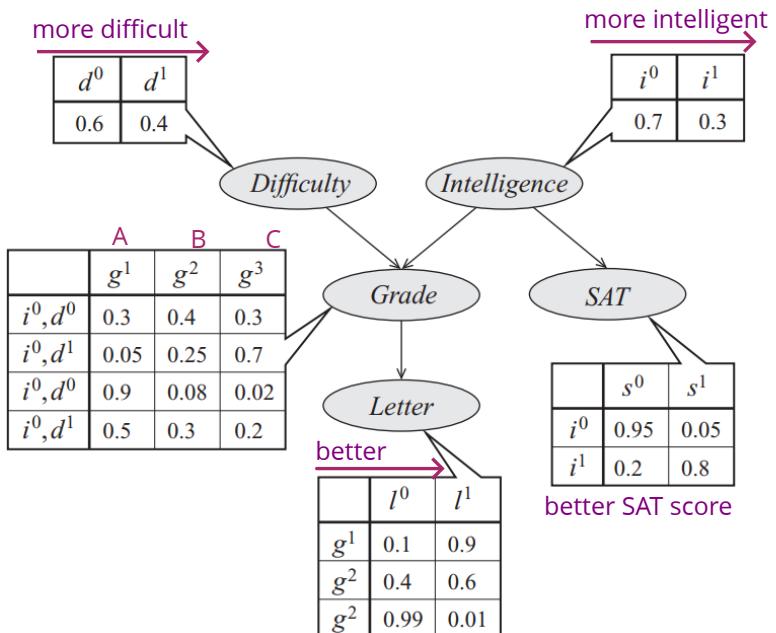


# Intuition for Reasoning in BN

## Explaining away (v-structure)

- prior
  - of a high intelligence  $P(i^1) \approx .30$
- posterior
  - given a bad letter  $P(i^1 | l^0) \approx .14$
  - ... and a bad grade  $P(i^1 | l^0, g^3) \approx .08$
  - a difficult exam **explains away** the grade

$$P(i^1 | l^0, g^3, d^1) \approx .11$$



# DAG; semantics

associating  $P$  with a DAG:

- *factorization* of the joint probability:

$$P(\mathbf{X}) = \prod_i P(X_i \mid Pa_{X_i})$$

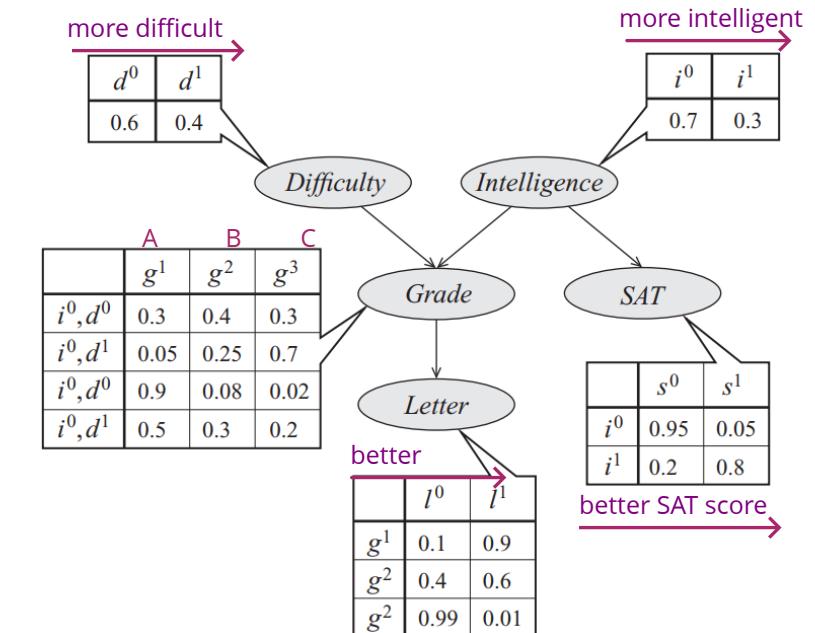
- *conditional independencies* in  $P$  from the DAG

# Bayesian networks; factorization

$$P(I, D, G, S, L) = P(I)P(D)P(G \mid I, D)P(S \mid I)P(L \mid G)$$

In general

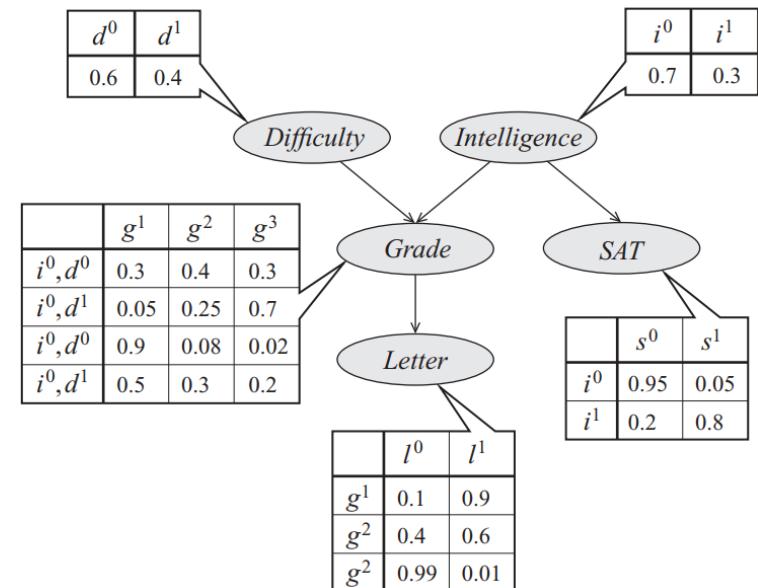
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# Bayesian networks; conditional independencies

- quality of the letter (L) only depends on the grade (G)

$$L \perp D, I, S \mid G \quad \checkmark$$



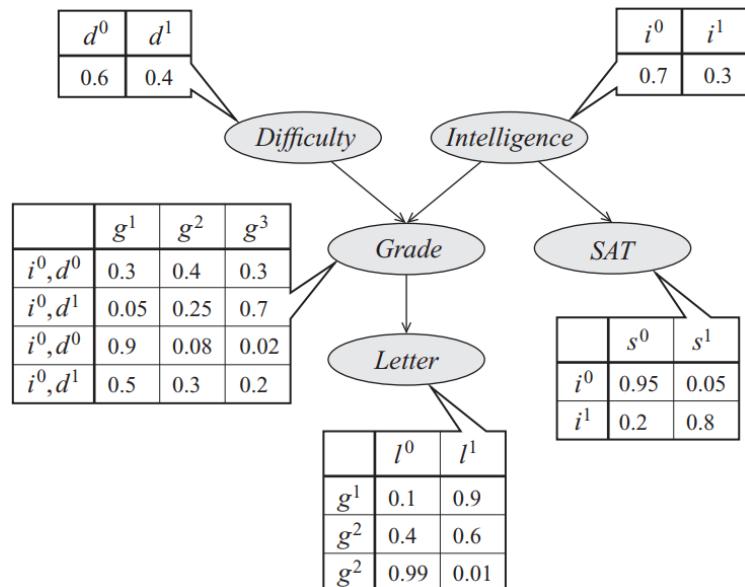
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- How about the following assertions?

$$D \perp S \quad ?$$



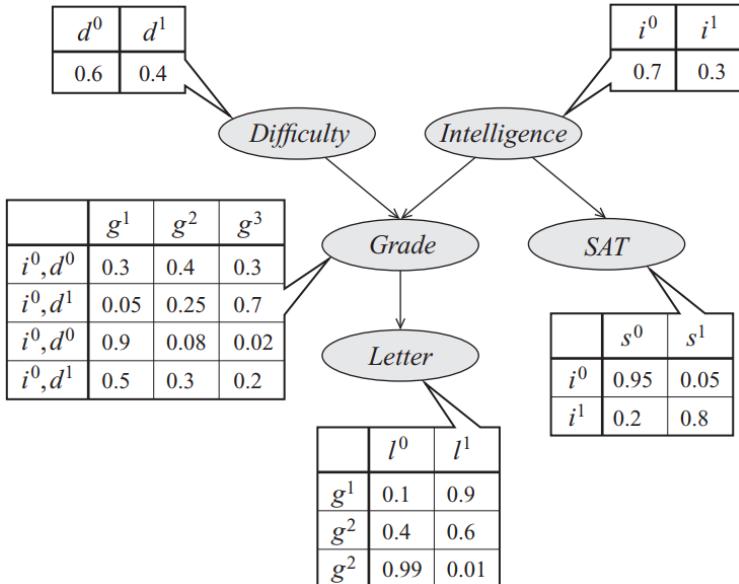
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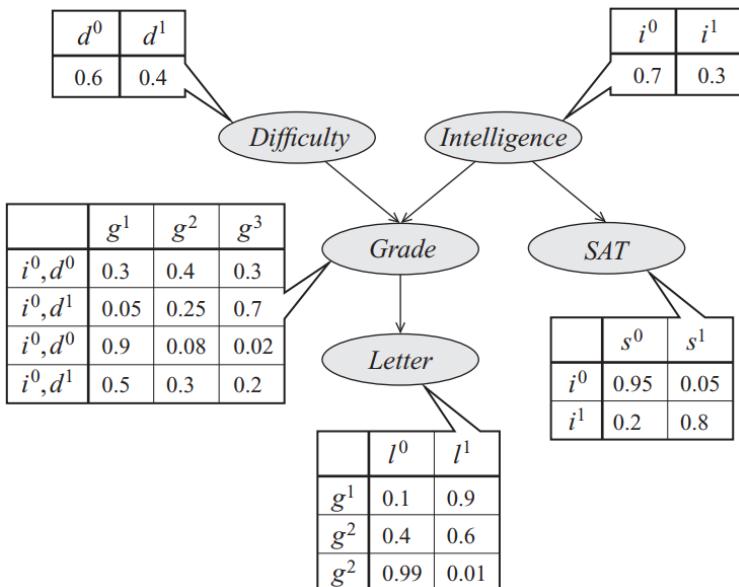
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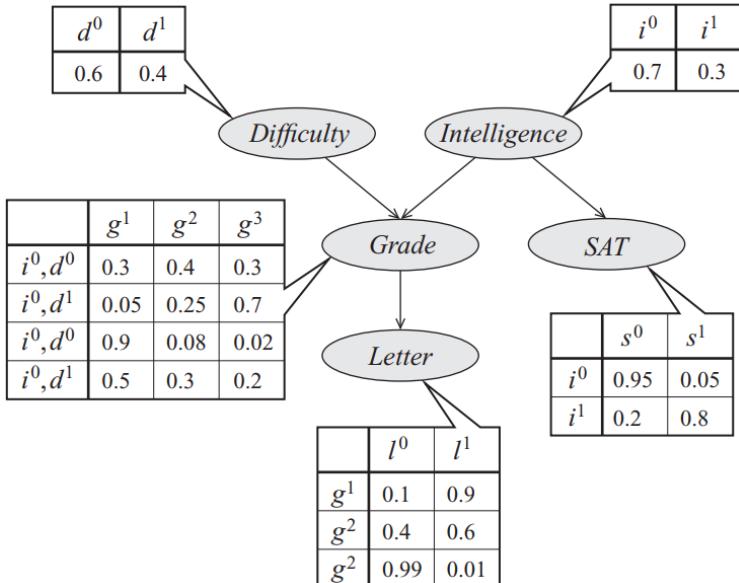
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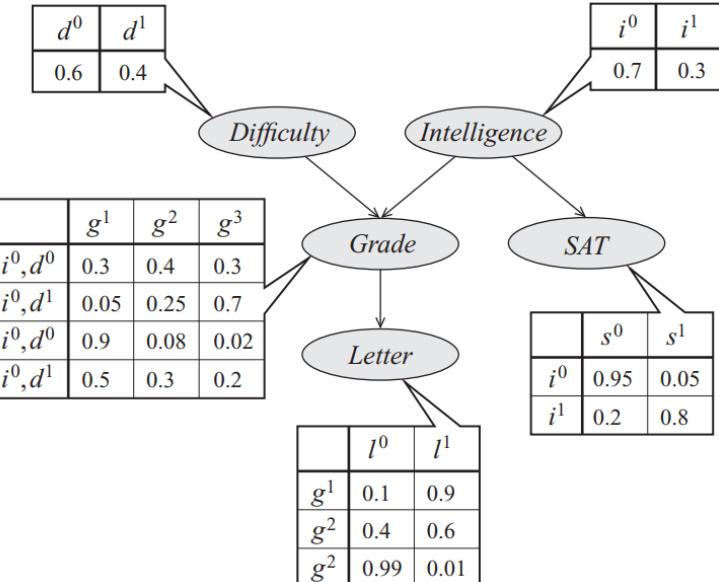
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$$D \perp S \mid L \quad ?$$



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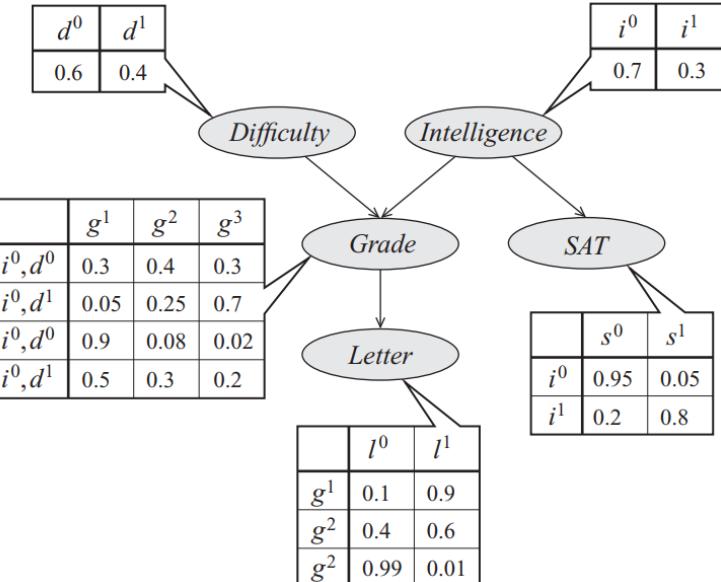
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$$D \perp S \mid L \quad ? \quad \times \quad \text{why?}$$



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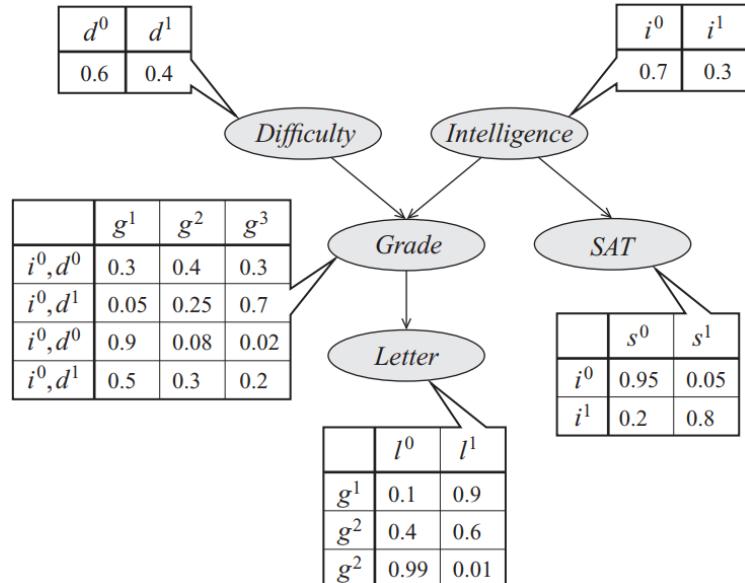
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$$D \perp S \mid I \quad ? \quad \checkmark$$

$$D \perp S \mid L \quad ? \quad \times \quad \text{why?}$$

- read from the graph?



# Conditional independencies (CI); notation

1. set of all CIs of the **distribution**  $P$   $\mathcal{I}(P)$

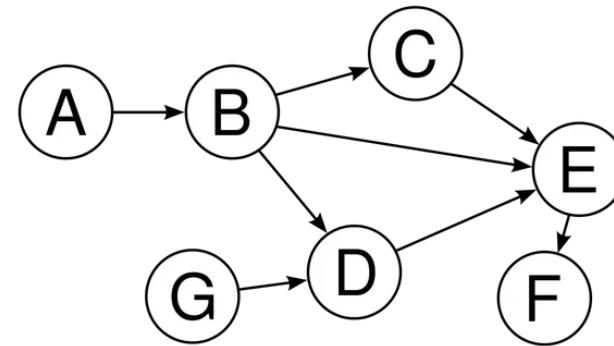
2. set of **local** CIs from the **graph** (DAG)  $\mathcal{I}_{\ell}(\mathcal{G})$

3. set of all **(global)** CIs from the **graph**  $\mathcal{I}(\mathcal{G})$

## Local conditional independencies (CIs)

for any node  $X_i \quad X_i \perp NonDescendents_{X_i} \mid Parents_{X_i}$

$$\begin{aligned}\mathcal{I}_\ell(\mathcal{G}) = \{ \quad & A \perp G \mid \emptyset \\ & B \perp G \mid A \\ & C \perp G, D, A \mid B \\ & D \perp A, C \mid B, G \\ & E \perp A, G \mid B, C, D \\ & F \perp A, B, C, D, G \mid E \\ & \} \quad G \perp A, B, C\end{aligned}$$

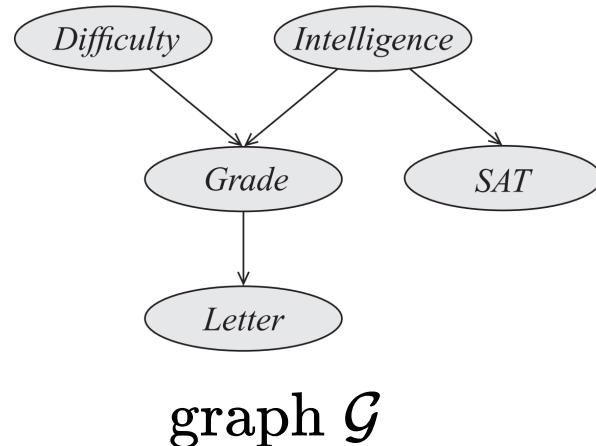


graph  $\mathcal{G}$

## Local CIs

for any node  $X_i \quad X_i \perp NonDescendents_{X_i} \mid Parents_{X_i}$

$$\begin{aligned}\mathcal{I}_\ell(\mathcal{G}) = \{ & \quad D \perp I, S \\ & \quad I \perp D \\ & \quad G \perp S \mid I \\ & \quad S \perp G, L, D \mid I \\ & \quad L \perp D, I, S \mid G\}\end{aligned}$$



## Local CIs from factorization

use the **factorized form**

$$P(\mathbf{X}) = \prod_i P(X_i \mid Pa_{X_i})$$

to show  $\forall X_i$

$$P(X_i, NonDesc_{X_i} \mid Pa_{X_i}) = P(X_i \mid Pa_{X_i})P(NonDesc_{X_i} \mid Pa_{X_i})$$

which means

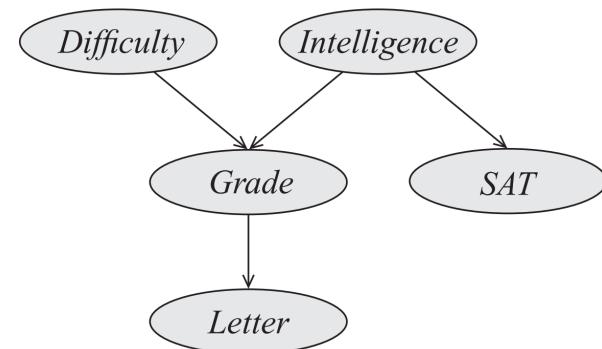
$$X_i \perp NonDesc_{X_i} \mid Pa_{X_i}$$

# Local CIs from factorization; example

$$S \perp G \mid I$$

given

$$P(D, I, G, S, L) = P(D)P(I)P(G \mid D, I)P(S \mid I)P(L \mid G)$$



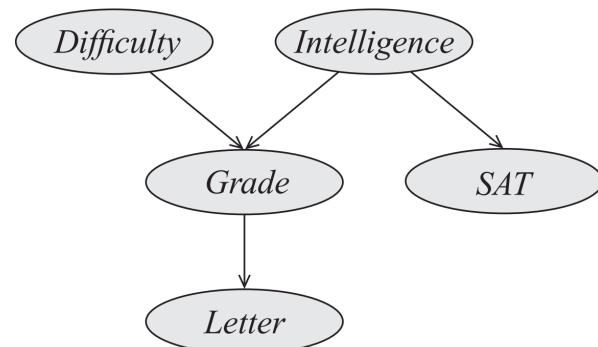
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given

$$P(D, I, G, S, L) = P(D)P(I)P(G \mid D, I)P(S \mid I)P(L \mid G)$$

$$P(G, S \mid I) = \frac{\sum_{d,l} P(D, I, G, S, L)}{\sum_{d,g,s,l} P(D, I, G, S, L)} =$$



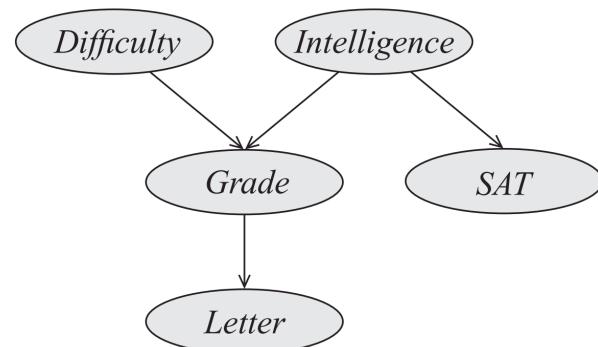
# Local CIs from factorization; example

$$S \perp G \mid I$$

given

$$P(D, I, G, S, L) = P(D)P(I)P(G \mid D, I)P(S \mid I)P(L \mid G)$$

$$P(G, S \mid I) = \frac{\sum_{d,l} P(D, I, G, S, L)}{\sum_{d,g,s,l} P(D, I, G, S, L)} = \frac{\sum_{d,l} P(D)P(I)P(G|D,I)P(S|I)P(L|G)}{\sum_{d,g,s,l} P(D)P(I)P(G|D,I)P(S|I)P(L|G)} =$$



# Local CIs from factorization; example

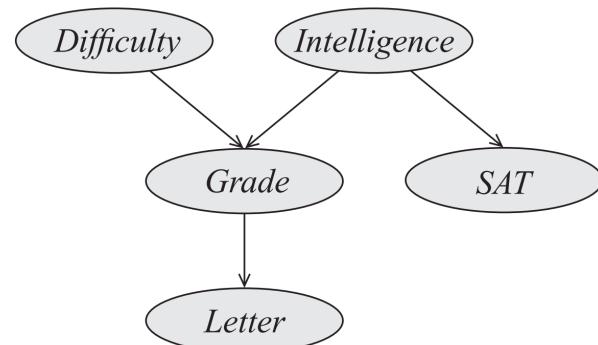
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$$\frac{P(I)P(S|I)\sum_{d,l} P(D)P(G|D,I)P(L|G)}{P(I)\sum_{d,g,s,l} P(D)P(G|D,I)P(S|I)P(L|G)} =$$



# Local CIs from factorization; example

$$S \perp G \mid I$$

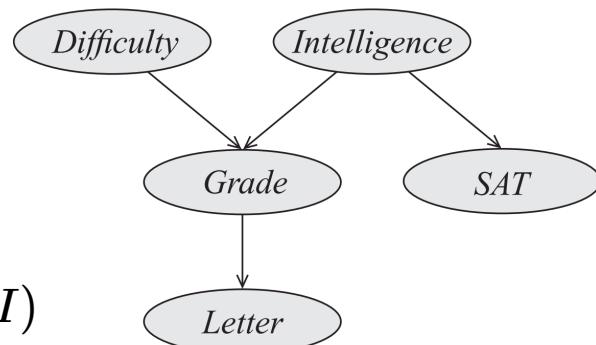
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$$P(D, I, G, S, L) = P(D)P(I)P(G \mid D, I)P(S \mid I)P(L \mid G)$$

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$$\frac{P(I)P(S|I)\sum_{d,l} P(D)P(G|D,I)P(L|G)}{P(I)\sum_{d,g,s,l} P(D)P(G|D,I)P(S|I)P(L|G)} =$$

$$\frac{P(S|I)\sum_{d,l} P(D)P(G|D,I)P(L|G)}{1} = P(S \mid I)P(G \mid I)$$



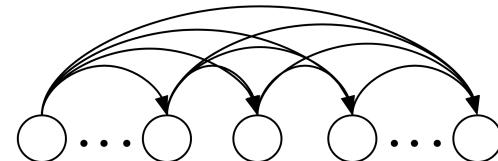
# Factorization from local CIs

from **local CIs**  $\mathcal{I}_\ell(\mathcal{G}) = \{X_i \perp NonDesc_{X_i} \mid Pa_{X_i} \mid i\}$

find a topological ordering (*parents before children*):  $X_{i_1}, \dots, X_{i_n}$

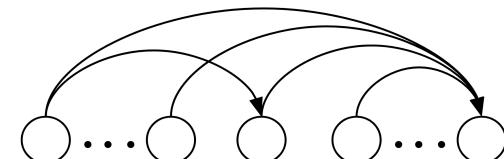
use the chain rule

$$P(\mathbf{X}) = P(X_{i_1}) \prod_{j=2}^n P(X_{i_j} \mid X_{i_1}, \dots, X_{i_{j-1}})$$



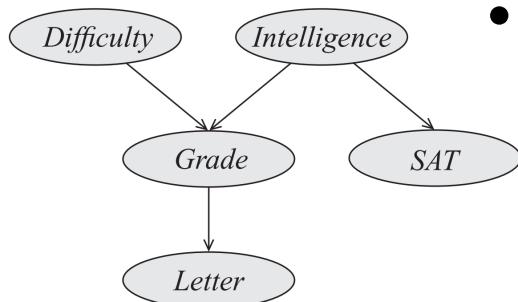
simplify using local CIs

$$P(\mathbf{X}) = P(X_{i_1}) \prod_{j=2}^n P(X_{i_j} \mid Pa_{X_{i_j}})$$



# Factorization from local CIs; example

- local CIs  $\mathcal{I}_\ell(\mathcal{G}) = \{ (D \perp I, S), (I \perp D), (G \perp S \mid I), (S \perp G, L, D \mid I), (L \perp D, I, S \mid G) \}$



- a topological ordering: D, I, G, L, S

- use the chain rule

$$P(D, I, G, S, L) = P(D)P(I \mid D)P(G \mid D, I)P(L \mid D, I, G)P(S \mid D, I, G, L)$$

- simplify using  $\mathcal{I}_\ell(\mathcal{G})$

$$P(D, I, G, S, L) = P(D)P(I)P(G \mid D, I)P(L \mid G)P(S \mid I)$$

# Factorization $\Leftrightarrow$ local CIs

$$P(\mathbf{X}) = \prod_i P(X_i \mid Pa_{X_i}^{\mathcal{G}}) \Leftrightarrow \mathcal{I}_{\ell}(\mathcal{G}) \text{ holds in } P$$

---

P factorizes according to  $\mathcal{G}$

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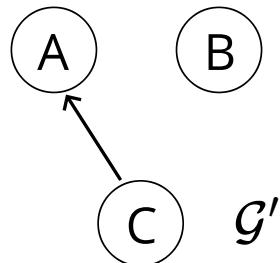
$$\mathcal{I}_\ell(\mathcal{G}) \subseteq \mathcal{I}(P)$$

$\mathcal{G}$  is an **I-map** for P

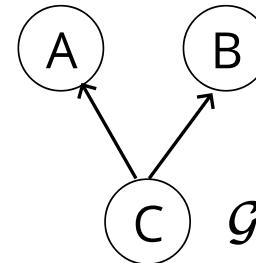
it does not mislead us  
about independencies in P

# Independence map (I-map); example

the term is used for both **graphs** and **distributions**.

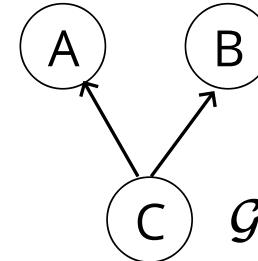
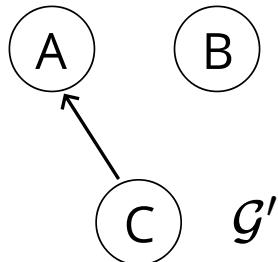


$$P(A, B, C) = P(C)P(A | C)P(B) \quad \Rightarrow \quad P(A, B, C) = P(C)P(A | C)P(B | C)$$



# Independence map (I-map); example

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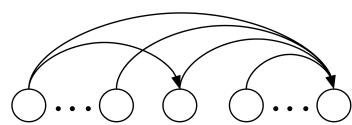
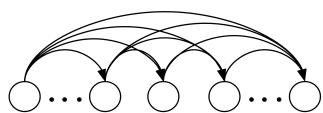


$$P(A, B, C) = P(C)P(A | C)P(B) \quad \Rightarrow \quad P(A, B, C) = P(C)P(A | C)P(B | C)$$

- easy to check  $\mathcal{I}_\ell(\mathcal{G}) \subseteq \mathcal{I}_\ell(\mathcal{G}')$
- factorization of  $P$  over  $\mathcal{G}' \Rightarrow \mathcal{I}_\ell(\mathcal{G}') \subseteq \mathcal{I}(P)$ 
  - both  $\mathcal{G}, \mathcal{G}'$  are I-maps for  $P$

# Summary so far

- simplification of the chain rule  $P(\mathbf{X}) = \prod_i P(X_i \mid Pa_{X_i})$



- Bayes-net represented using a DAG
- naive Bayes
- **local** conditional independencies  $\mathcal{I} = \{X_i \perp NonDesc_{X_i} \mid Pa_{X_i} \mid i\}$ 
  - hold in a Bayes-net
  - imply a Bayes-net

## **Global CIs from the graph**

for any subset of vars  $\mathbf{X}$ ,  $\mathbf{Y}$  and  $\mathbf{Z}$ , we can ask  $\mathbf{X} \perp \mathbf{Y} \mid \mathbf{Z}$ ?

**global CI:** the set of all such CIs

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**global CI:** the set of all such CIs

factorized form of  $P \Rightarrow$  **global** CIs  $\mathcal{I}_\ell(\mathcal{G}) \subseteq \mathcal{I}(\mathcal{G}) \subseteq \mathcal{I}(P)$

## Global CIs from the graph

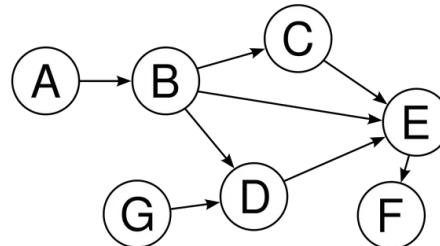
for any subset of vars  $\mathbf{X}$ ,  $\mathbf{Y}$  and  $\mathbf{Z}$ , we can ask  $\mathbf{X} \perp \mathbf{Y} \mid \mathbf{Z}$ ?

**global CI:** the set of all such CIs

factorized form of  $P \Rightarrow$  **global** CIs  $\mathcal{I}_\ell(\mathcal{G}) \subseteq \mathcal{I}(\mathcal{G}) \subseteq \mathcal{I}(P)$

Example:

$$C \perp D \mid B, F \quad ?$$

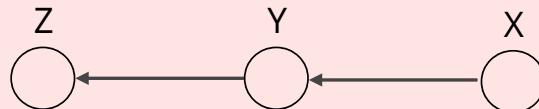


**algorithm:** directed separation (**D-separation**)

# Three canonical settings

for three random variables

1. causal / evidence trail



$$P(X, Y, Z) = P(X)P(Y|X)P(Z | Y)$$

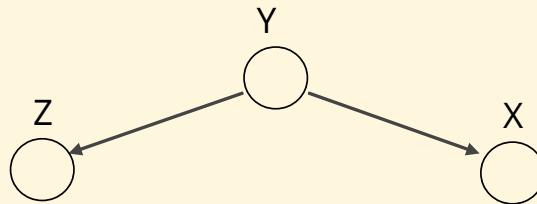
~~marginal independence~~:  $P(X, Z) \neq P(X)P(Z)$

conditional Independence:

$$P(Z | X, Y) = \frac{P(X, Y, Z)}{P(X, Y)} = \frac{P(X)P(Y|X)P(Z|Y)}{P(X)P(Y|X)} = P(Z | Y)$$

# Three canonical settings

2. common cause



$$P(X, Y, Z) = P(Y)P(X | Y)P(Z | Y)$$

~~marginal independence:~~  $P(X, Z) \neq P(X)P(Z)$

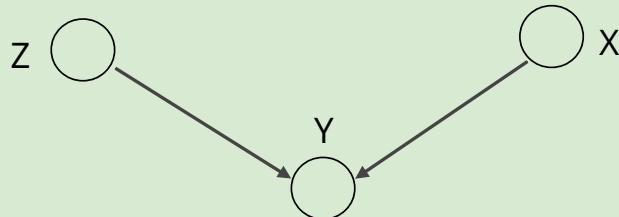
conditional independence:

$$P(X, Z | Y) = \frac{P(X, Y, Z)}{P(Y)} = P(X | Y)P(Z | Y)$$

# Three canonical settings

3. common effect

a.k.a. *collider, v-structure*



$$P(X, Y, Z) = P(X)P(Z)P(Y | X, Z)$$

marginal independence:

$$P(X, Z) = \sum_Y P(X, Y, Z) = P(X)P(Z) \sum_Y P(Y | X, Z) = P(X)P(Z)$$

~~conditional independence:~~

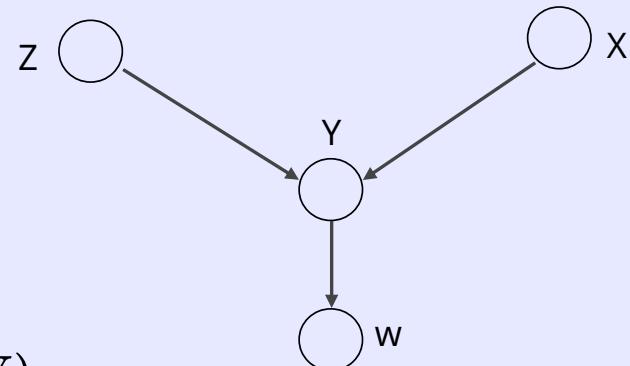
$$P(X, Z | Y) = \frac{P(X, Y, Z)}{P(Y)} \neq P(X | Y)P(Z | Y)$$

# Three canonical settings

3. common effect

~~conditional~~ Independence:

$$P(X, Z | W) \neq P(X | W)P(Z | W)$$

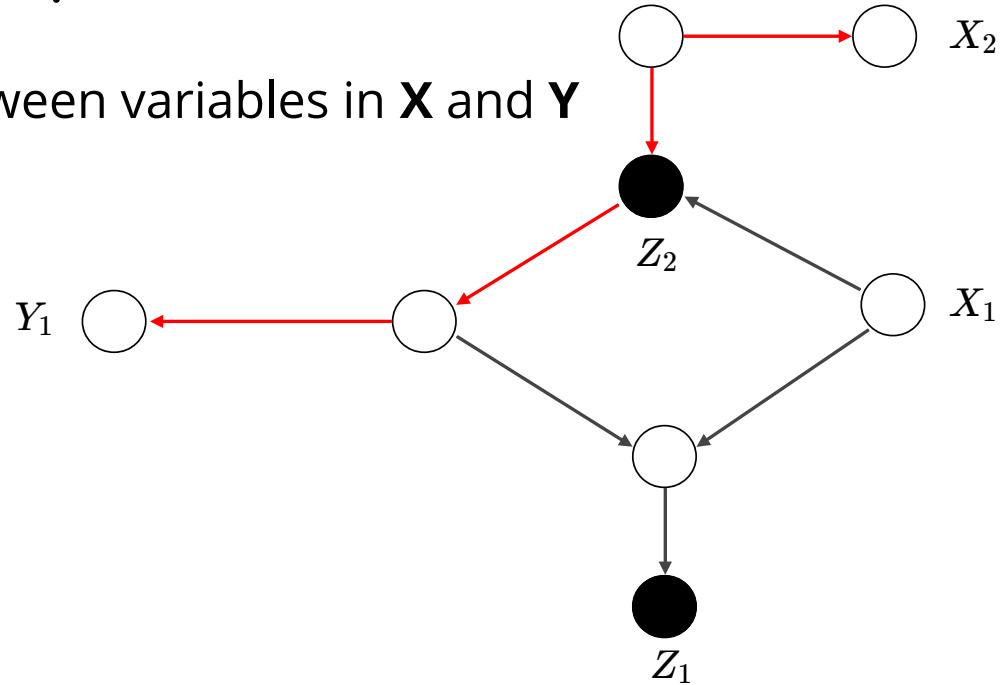


even observing a descendant of Y makes X, Z dependent

# Putting the three cases together

$$X_1, X_2 \perp Y_1 \mid Z_1, Z_2 \quad ?$$

consider all paths between variables in **X** and **Y**

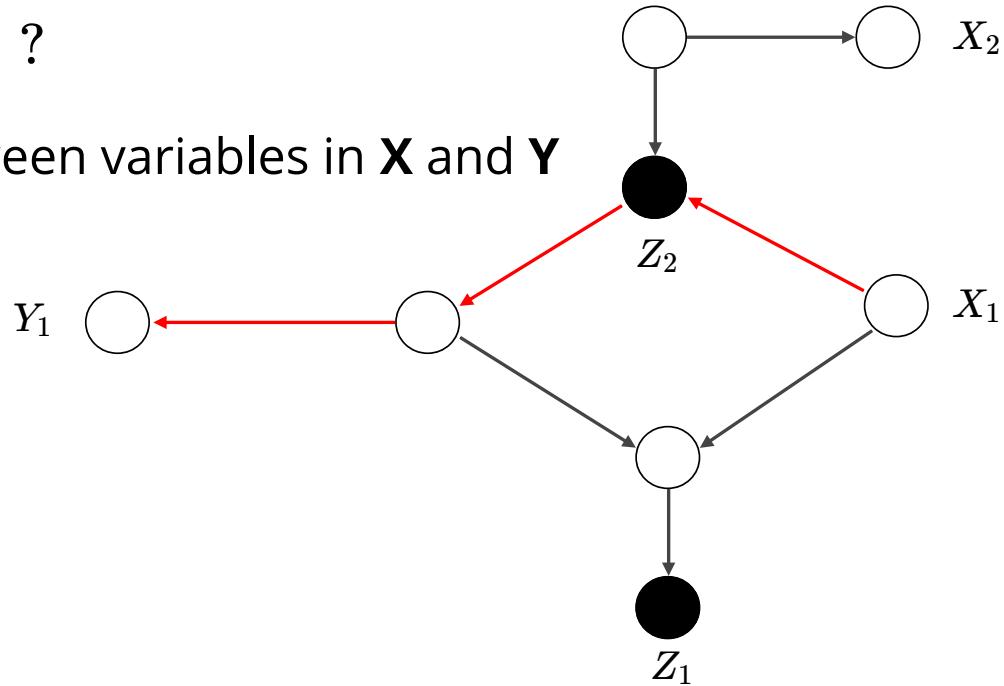


## Putting the three cases together

$$X_1, X_2 \perp Y_1 \mid Z_1, Z_2 \quad ?$$

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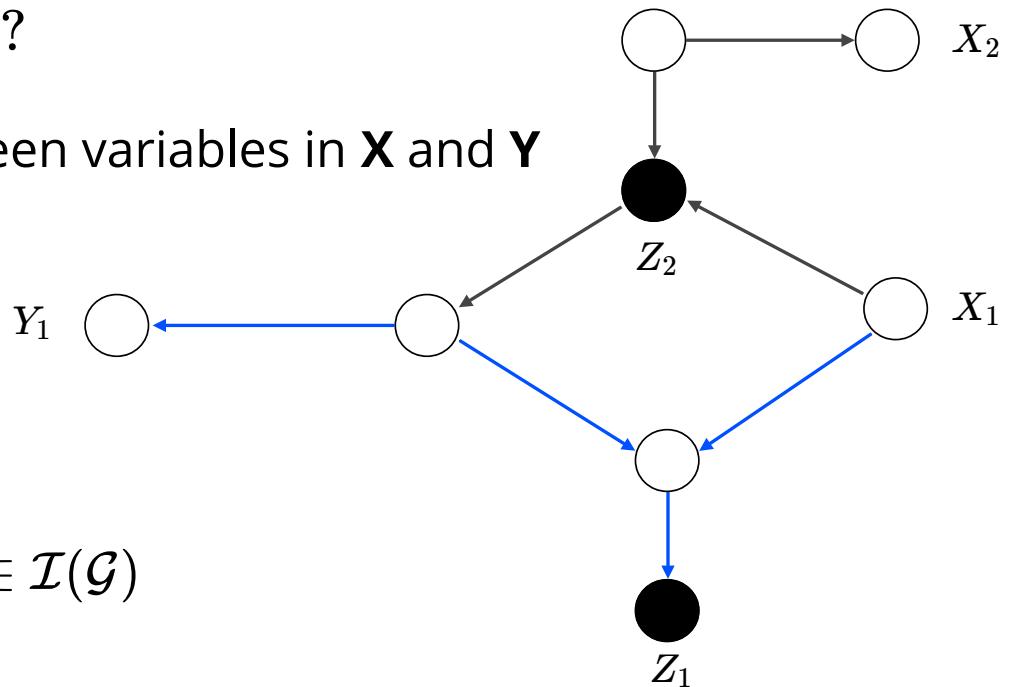
so far **X**  $\perp$  **Y**  $\mid$  **Z**



## Putting the three cases together

$X_1, X_2 \perp\!\!\!\perp Y_1 \mid Z_1, Z_2$  ?

consider all paths between variables in **X** and **Y**



had we **not** observed  $Z_1$

$$(X_1, X_2 \perp\!\!\!\perp Y_1 \mid Z_2) \in \mathcal{I}(\mathcal{G})$$

# D-seperation

(a.k.a. **Bayes-Ball** algorithm)

$$X \perp Y \mid Z \quad ?$$

See whether at least one ball from **X** reaches **Y**

**Z** is shaded

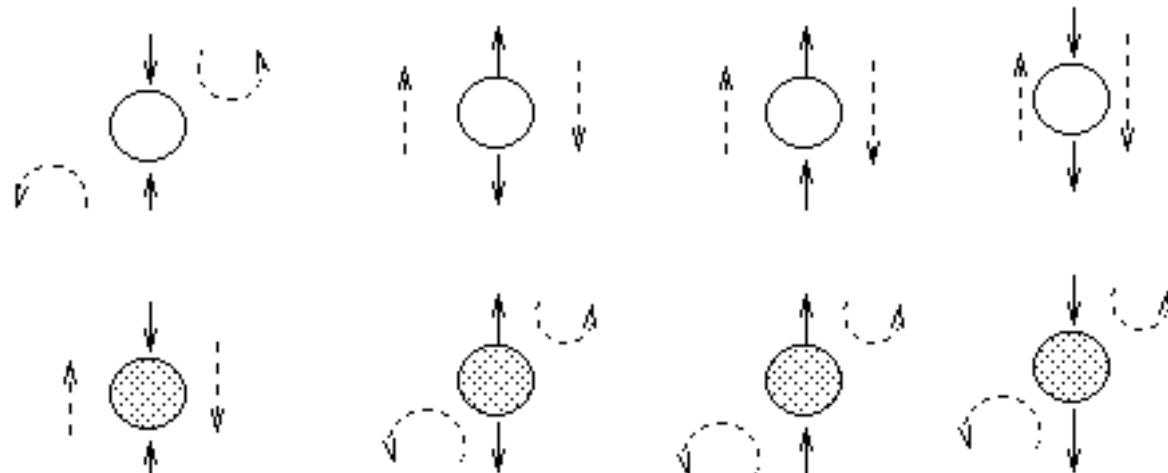


image from:<https://www.cs.ubc.ca/~murphyk/Bayes/bnintro.html>

# D-separation; algorithm

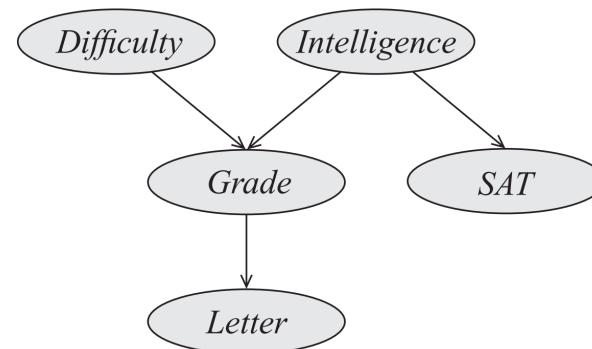
Linear time complexity

- **input:** graph G and  $X, Y, Z$
- **output:**  $X \perp Y \mid Z$  ?
- **mark** the variables in  $Z$  and all of their *ancestors* in G
- **breadth-first-search** starting from X
- stop any trail that reaches a **blocked node**
- a node in Y is reached?



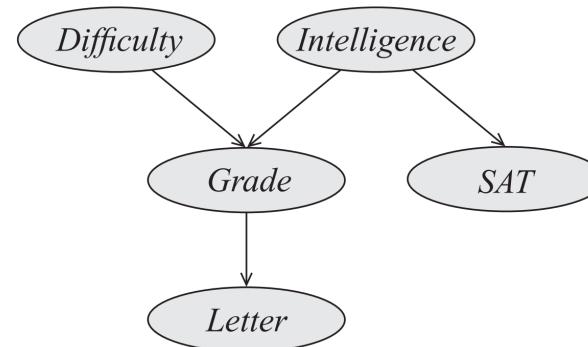
- **unmarked** middle of a collider (V-structure)
- in Z otherwise

# D-separation quiz



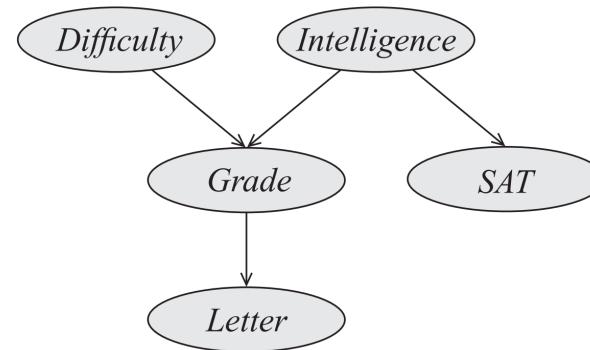
# D-separation quiz

$G \perp S \mid \emptyset?$



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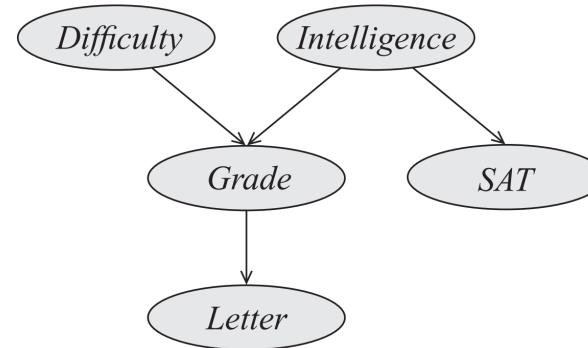


# D-separation quiz

$G \perp S \mid \emptyset?$



$D \perp L \mid G?$

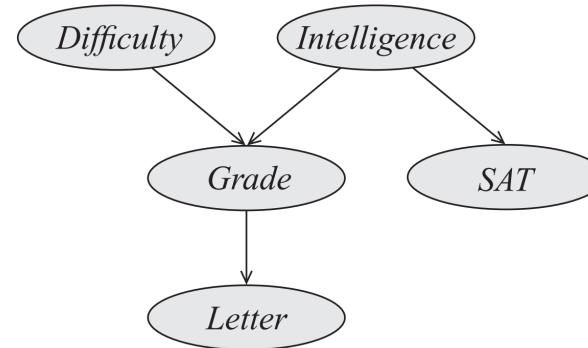


# D-separation quiz

$G \perp S \mid \emptyset?$



$D \perp L \mid G?$



# D-separation quiz

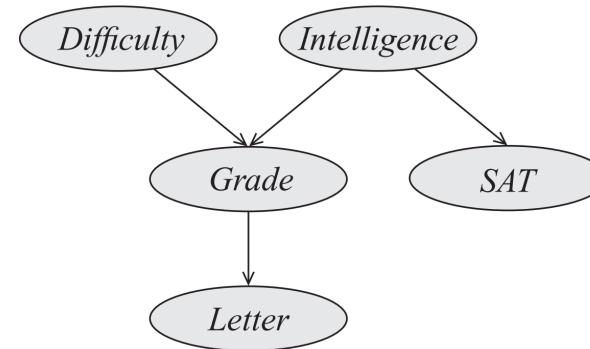
$G \perp S \mid \emptyset?$



$D \perp L \mid G?$



$D \perp I, S \mid \emptyset?$



# D-separation quiz

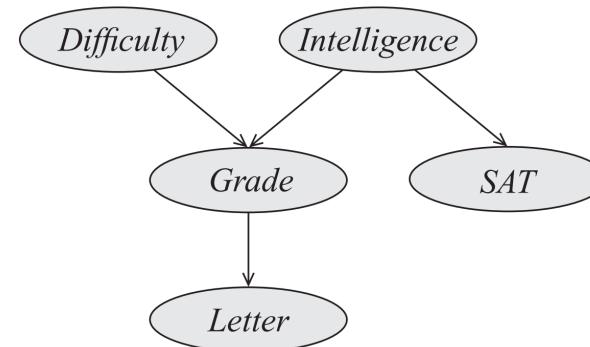
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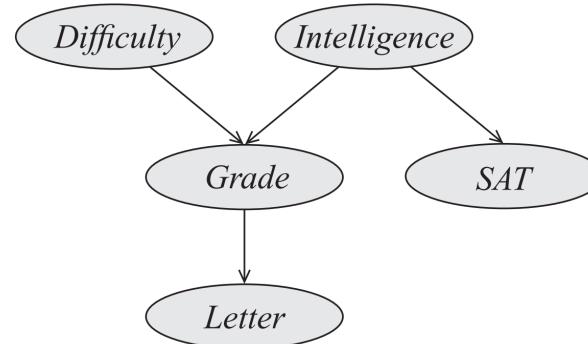
$D \perp L \mid G?$



$D \perp I, S \mid \emptyset?$



$D, L \perp S \mid I, G?$



# D-separation quiz

$G \perp S \mid \emptyset?$



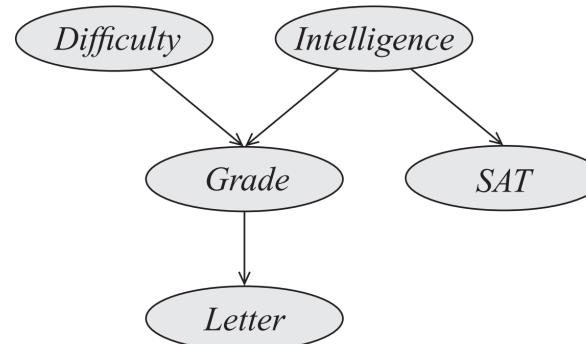
$D \perp L \mid G?$



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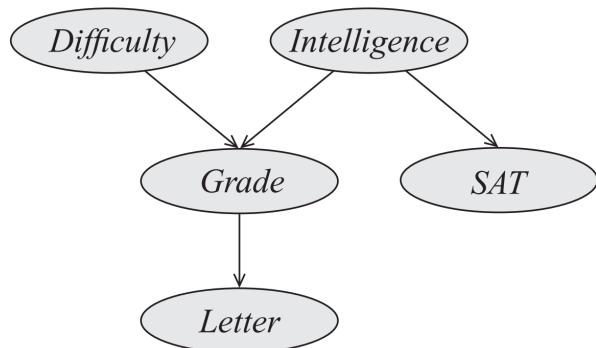


$D, L \perp S \mid I, G?$



## I-map quiz

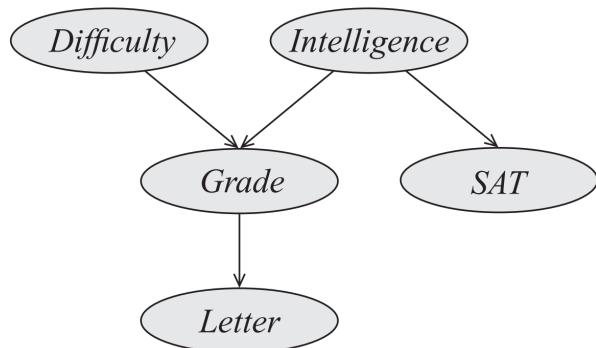
is G an I-MAP for the following distribution?



$$P(D, I, G, S, L) = P(L)P(S)P(G | D, I)P(D)P(I)$$

## I-map quiz

is G an I-MAP for the following distribution? yes!



$$P(D, I, G, S, L) = P(L)P(S)P(G | D, I)P(D)P(I)$$

# Summary so far

**graph** and **distribution** are combined:

- factorization of the **distribution**
  - according to the **graph**  $P(\mathbf{X}) = \prod_i P(X_i \mid Pa_{X_i}^{\mathcal{G}})$
- conditional independencies of the **distribution**
  - inferred from the **graph**
    - local CI:  $X_i \perp NonDescendents_{X_i} \mid Parents_{X_i}$
    - global CI: D-separation

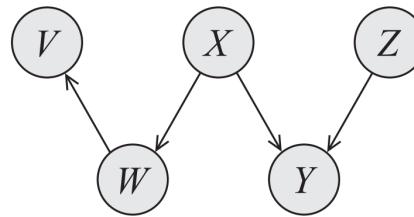
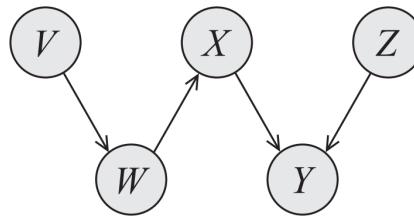
# Summary so far

- factorization of the distribution
- local conditional independencies
- global conditional independencies

identify the same  
**family** of distributions

# Equivalence class of DAGs

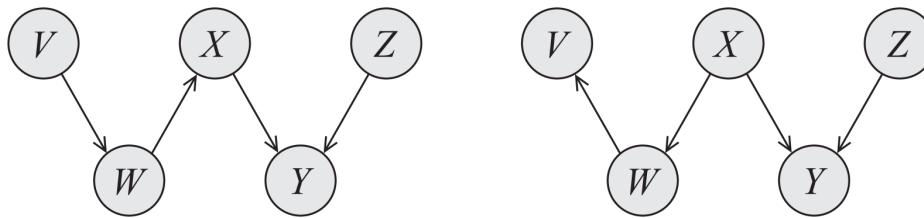
Two DAGs are **I-equivalent** if  $\mathcal{I}(\mathcal{G}) = \mathcal{I}(\mathcal{G}')$



P factorizes on both of these graphs

# Equivalence class of DAGs

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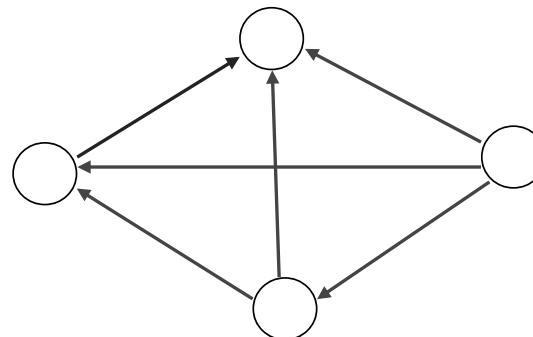
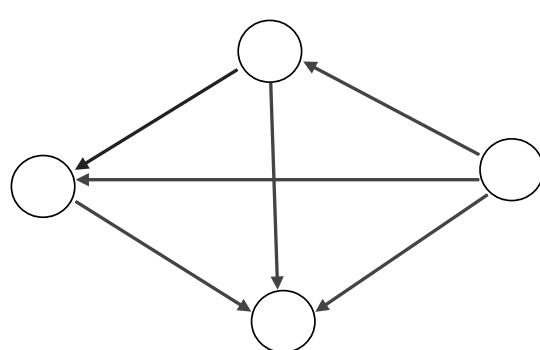
P factorizes on both of these graphs

From d-separation algorithm it is **sufficient**

- same undirected **skeleton**
- same **v-structures**

# Equivalence class of DAGs

Two DAGs are I-equivalent if  $\mathcal{I}(\mathcal{G}) = \mathcal{I}(\mathcal{G}')$

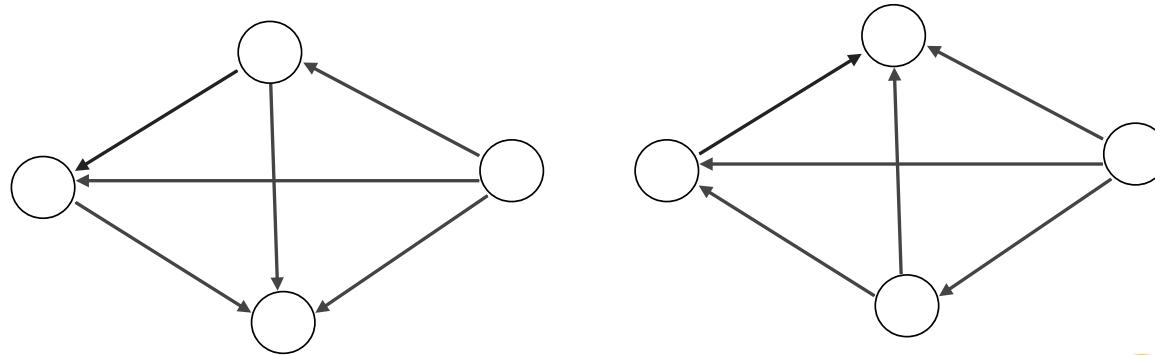


different v-structures, yet  $\mathcal{I}(\mathcal{G}) = \mathcal{I}(\mathcal{G}') = \emptyset$



# Equivalence class of DAGs

Two DAGs are I-equivalent if  $\mathcal{I}(\mathcal{G}) = \mathcal{I}(\mathcal{G}')$



different v-structures, yet  $\mathcal{I}(\mathcal{G}) = \mathcal{I}(\mathcal{G}') = \emptyset$



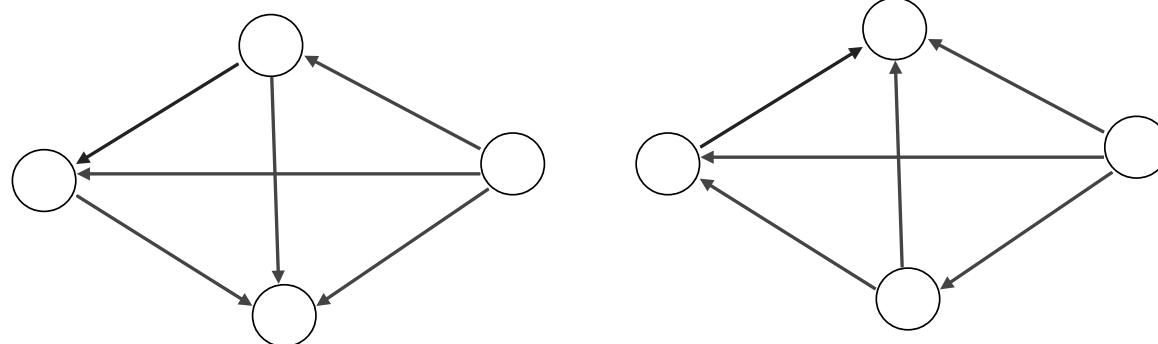
here, v-structures are irrelevant for I-equivalent because:

- parents are connected (**moral parents!**)

# Equivalence class of DAGs

Two DAGs are I-equivalent if  $\mathcal{I}(\mathcal{G}) = \mathcal{I}(\mathcal{G}')$

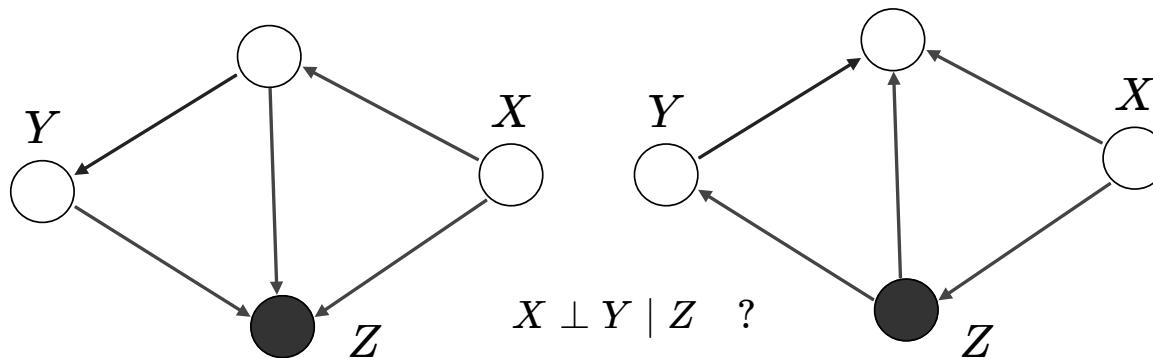
$$\mathcal{I}(\mathcal{G}) = \mathcal{I}(\mathcal{G}') \iff \begin{array}{l} \text{same undirected skeleton} \\ \text{same immoralities} \end{array}$$



# Equivalence class of DAGs

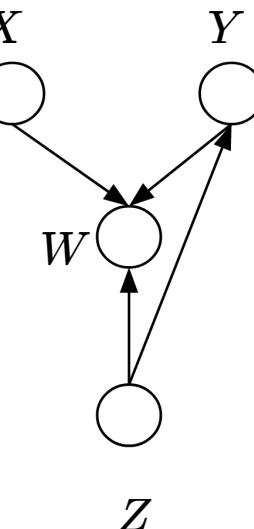
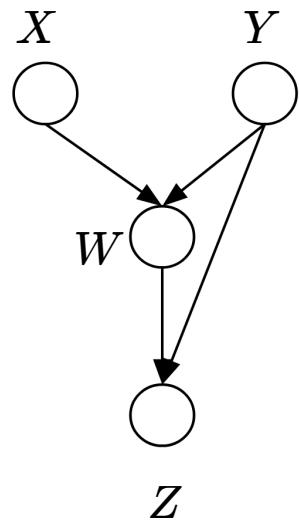
Two DAGs are I-equivalent if  $\mathcal{I}(\mathcal{G}) = \mathcal{I}(\mathcal{G}')$

$$\mathcal{I}(\mathcal{G}) = \mathcal{I}(\mathcal{G}') \iff \begin{array}{l} \text{same undirected skeleton} \\ \text{same immoralities} \end{array}$$



# I-Equivalence quiz

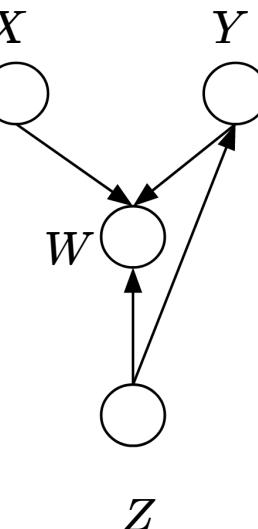
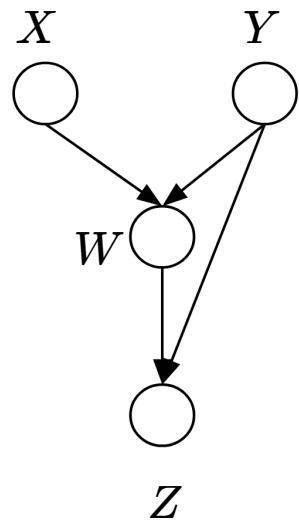
do these DAGs have the same set of CIs?



# I-Equivalence quiz

do these DAGs have the same set of CIs?

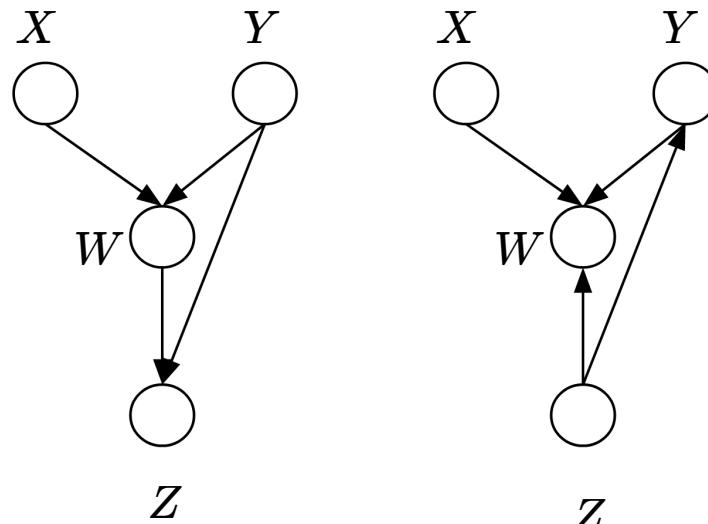
no!



# I-Equivalence quiz

do these DAGs have the same set of CIs?

no!



$$X \perp\!\!\! \perp Z \mid W$$

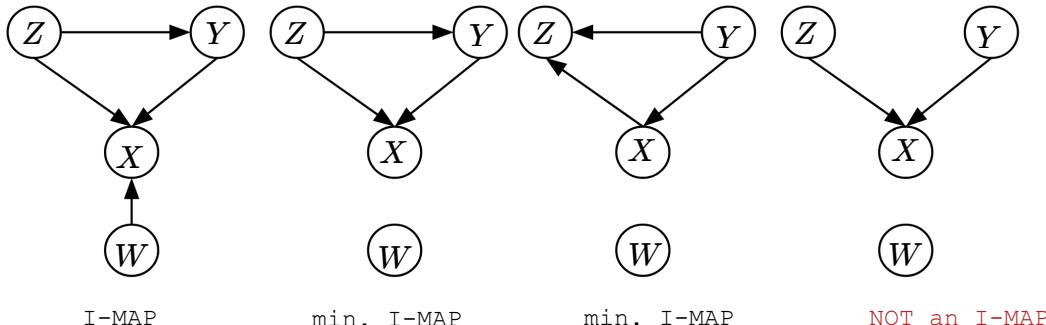
# Minimal I-map

*which graph  $G$  to use for  $P$ ?*

$G$  is **minimal I-map** for  $P$ :

- $G$  is an I-map for  $P$ :  $\mathcal{I}(G) \subseteq \mathcal{I}(P)$
- removing any edge destroys this property

**Example:**  $P(X, Y, Z, W) = P(X | Y, Z)P(W)P(Y | Z)P(Z)$

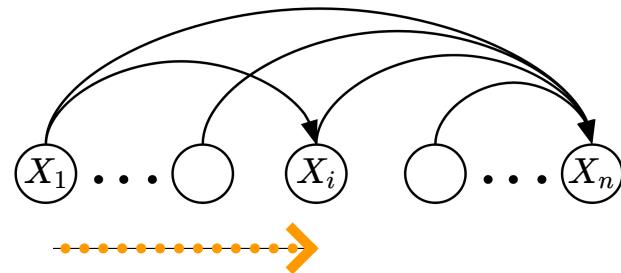


# Minimal I-map from CI

which graph  $G$  to use for  $P$ ?

input:  $\mathcal{I}(P)$  or an oracle; an ordering  $X_1, \dots, X_n$

output: a minimal I-map  $G$



for  $i=1 \dots n$

- find minimal  $\mathbf{U} \subseteq \{X_1, \dots, X_{i-1}\}$  s.t.  $(X_i \perp X_1, \dots, X_{i-1} - \mathbf{U} \mid \mathbf{U})$
- set  $Pa_{X_i} \leftarrow \mathbf{U}$

$$\overline{X_i \perp NonDesc_{X_i} \mid Pa_{X_i}}$$

# Minimal I-map from CI

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*different orderings give different graphs*

## Minimal I-map from CI

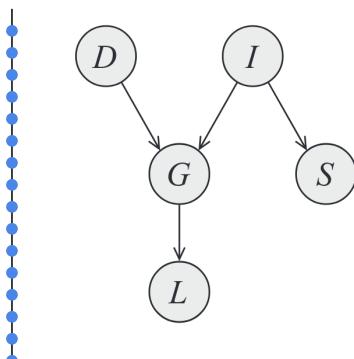
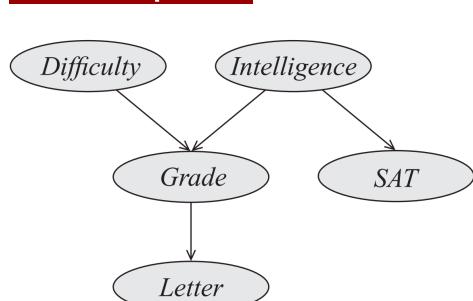
which graph  $G$  to use for  $P$ ?

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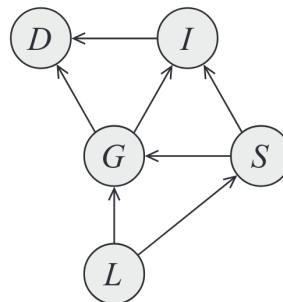
## output: a minimal I-map G

## Example:

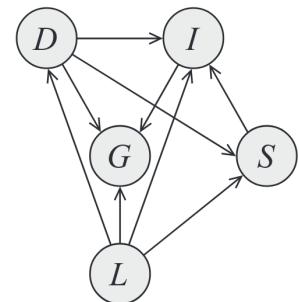
*different orderings give different graphs*



D,I,S,G,L



L,S,G,I,D

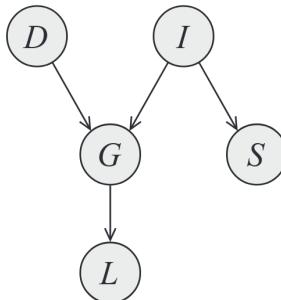
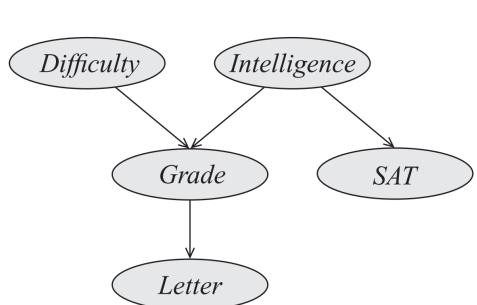


L,D,S,I,G

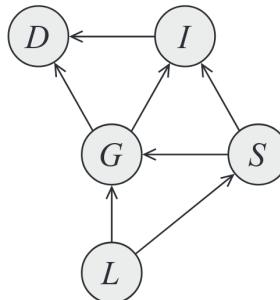
(a topological ordering)

# Perfect MAP (P-MAP)

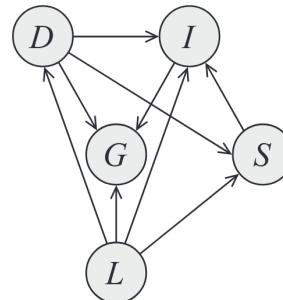
which graph  $G$  to use for  $P$ ?



D,I,S,G,L



L,S,G,I,D



L,D,S,I,G

all the graphs above are minimal I-MAPS

$$\mathcal{I}(G) \subseteq \mathcal{I}(P)$$

**Perfect MAP:**  $\mathcal{I}(G) = \mathcal{I}(P)$

# Perfect map (**P-map**)

*which graph  $G$  to use for  $P$ ?*

Perfect MAP:  $\mathcal{I}(\mathcal{G})=\mathcal{I}(P)$

$P$  may not have a P-map in the form of BN

# Perfect map (P-map)

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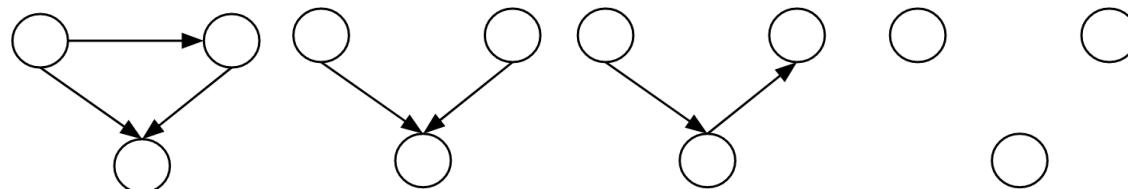
Perfect MAP:  $\mathcal{I}(\mathcal{G}) = \mathcal{I}(P)$

P may not have a P-map in the form of BN

Example:

$$P(x, y, z) = \begin{cases} 1/12, & \text{if } x \otimes y \otimes z = 0 \\ 1/6, & \text{if } x \otimes y \otimes z = 1 \end{cases}$$

- |(  $(X \perp Y), (Y \perp Z), (X \perp Z) \in \mathcal{I}(P)$  )
- |(  $(X \perp Y \mid Z), (Y \perp Z \mid Z), (X \perp Z \mid Y) \notin \mathcal{I}(P)$  )



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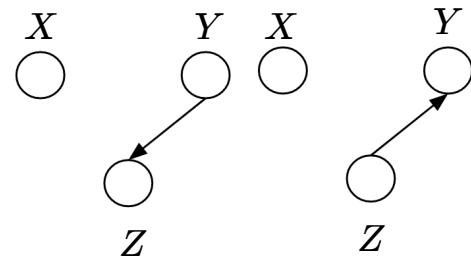
$P$  may not have a P-map in the form of a BN

if  $P$  has a P-map: **is it unique?**

unique up to I-equivalence

**Example:**

$$\mathcal{I}(P) = \{(X \perp Y, Z \mid \emptyset), (X \perp Y \mid Z), (X \perp Z \mid Y)\}$$



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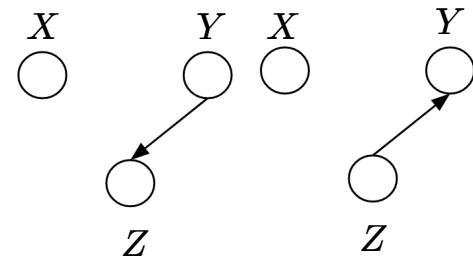
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How to find P-MAPs? discussed in learning BNs

# Summary

- factorization of the dist.
- local CIs
- global CIs

identify the same  
family of distributions



*can be represented using an equivalent class of graphs:*

- alternative factorization
- different local CIs
- same global CIs