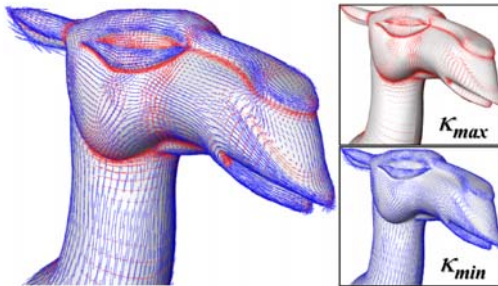


## Differential Geometry & Discrete Operators



## Curves

- Tangent vector to curve  $C(t)=(x(t),y(t))$  is

$$T = C'(t) = \frac{dC(t)}{dt} = [x'(t), y'(t)]$$

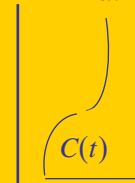
- Unit length tangent vector

$$\vec{T} = \vec{C}(t) = \frac{[x'(t), y'(t)]}{\sqrt{x'(t)^2 + y'(t)^2}}$$

- Curvature

$$k(t) = \frac{x'(t)y''(t) - y'(t)x''(t)}{(x'(t)^2 + y'(t)^2)^{3/2}}$$

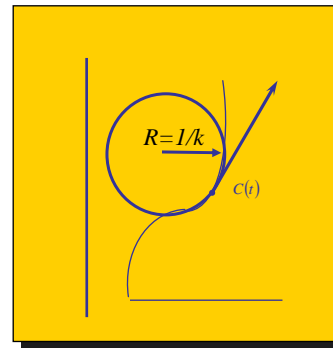
$$T = \frac{dC(t)}{dt}$$





## Curvature (Curves)

- Curvature is **independent** of parameterization
  - $C(t)$ ,  $C(t+5)$ ,  $C(2t)$  have same curvature (at corresponding locations)
- Corresponds to radius of osculating circle  $R=1/k$
- Measure curve bending



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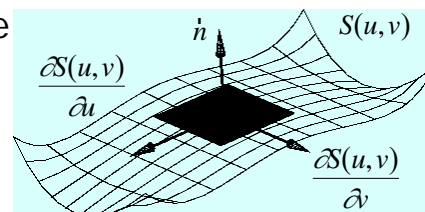
## Surfaces

- Tangent plane to surface  $S(u,v)$  is spanned by two partials of  $S$ :

$$\frac{\partial S(u,v)}{\partial u} \quad \frac{\partial S(u,v)}{\partial v}$$

- **Normal** to surface

$$\vec{n} = \frac{\partial S}{\partial u} \times \frac{\partial S}{\partial v}$$



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- perpendicular to tangent plane
- Any vector in tangent plane is tangential to  $S(u,v)$



## Curvature

- **Normal curvature** of surface is defined for each tangential direction
- **Principal curvatures**  $k_{min}$  &  $k_{max}$ : maximum and minimum of normal curvature
  - Correspond to two **orthogonal** tangent directions
    - Principal directions
  - Not necessarily partial derivative directions
  - Independent of parameterization



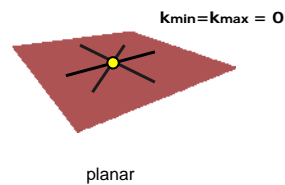
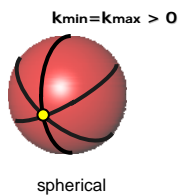
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## 3D Curvature

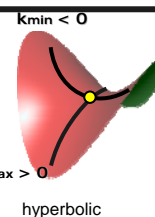
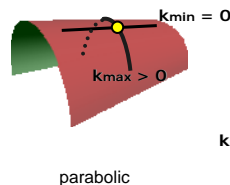
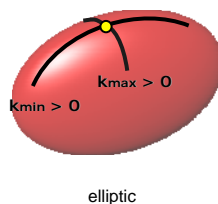
### Isotropic

Equal in all directions

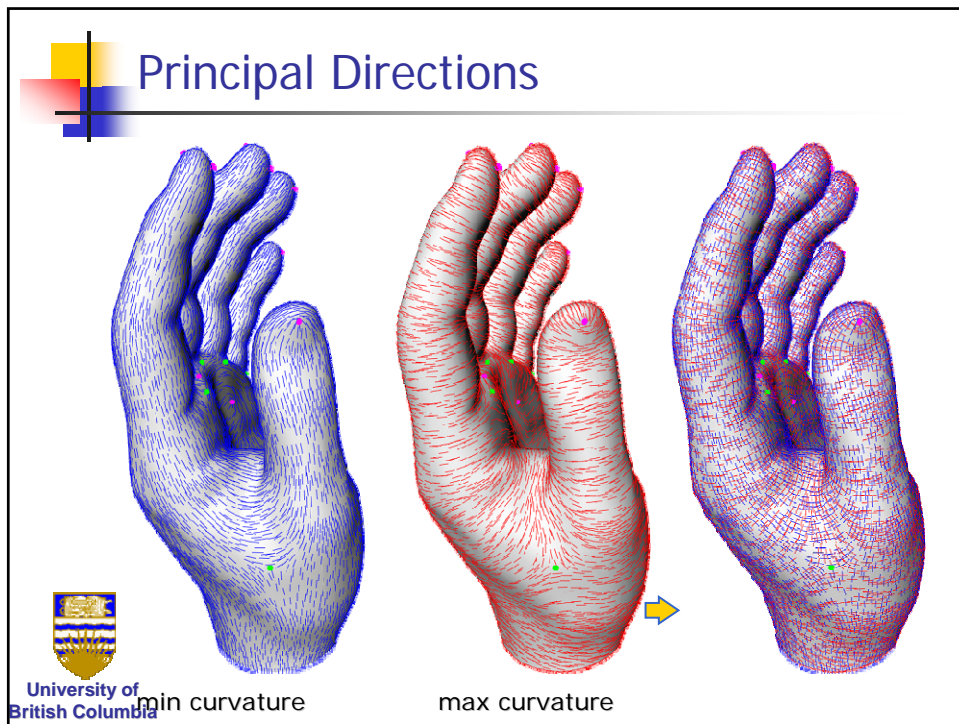


### Anisotropic

2 distinct principal directions



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## Curvature

- Typical measures:
  - Gaussian** curvature
 
$$K = k_{\min} k_{\max}$$
  - Mean** curvature
 
$$H = \frac{k_{\min} + k_{\max}}{2}$$

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## Curvature on Mesh

- Approximate curvature of (unknown) underlying surface
  - Continuous approximation
    - Approximate the surface & compute continuous differential measures
  - Discrete approximation
    - Approximate differential measures for mesh



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## Normal Estimation

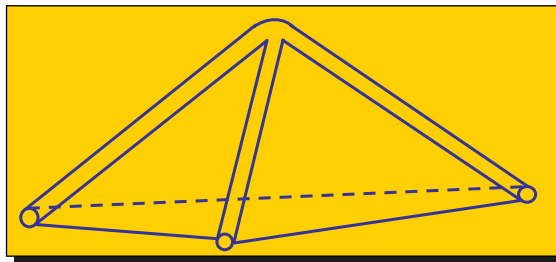
- Need surface normal to construct approximate surface
  - Defined for each face
  - Solution 1: average face normals
    - Does not reflect face "influence"
  - Solution 2: weighed average of face normals
    - Weights:
      - Face areas
      - Angles at vertex
- What happens at creases?



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## Curvature Estimate: Polyhedral Curvature

- Treat mesh as polyhedron with rounded corners with infinitesimally small radius
- Derive discrete properties from integrals across vertex *region*
  - Convention – associate half of each edge & 1/3 of triangle with vertex

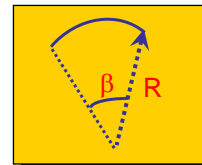


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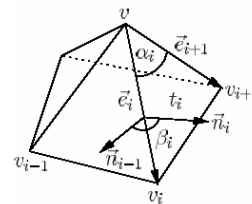
## Mean Curvature

- Integral of curvature on circular arc
  - $\beta$  - central angle

$$\int k = \frac{1}{R} \text{arclength} = \frac{1}{R} \frac{\beta}{2\pi} 2\pi R = \beta$$



- On cylindrical parts  $H = k_{max}/2$  ( $k_{min}=0$ )
- On planar faces  $H=0$



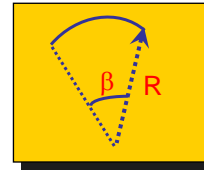
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## Mean Curvature

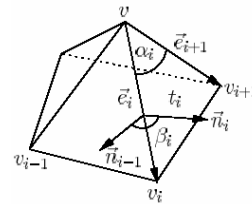
- For entire vertex region

$$\int H = \sum_i \beta_i / 2 \|e_i\| / 2 = \frac{1}{4} \sum_i \beta_i \|e_i\|$$



- Mean curvature at vertex ( $A_i$  triangle area)

$$H = \frac{3}{4 \sum A_i} \sum_i \beta_i \|e_i\|$$



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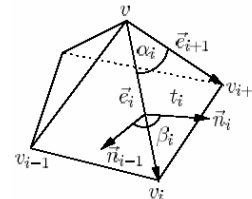
## Gaussian Curvature

- Use Gauss-Bonnet Theorem

$$\int_T K = 2\pi - \sum_i \gamma_i - \int_{\partial T} k_{\partial T} = 2\pi - \sum_i \gamma_i$$

- sum of exterior (jump) angles of polygon around  $v$  = sum of face angles at  $v$*
- Curvature at vertex

$$K = \frac{3(2\pi - \sum_i \alpha_i)}{\sum_i A_i}$$



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- Note (Gauss-Bonnet for closed surfaces) – Integral Gaussian curvature  $\approx \pi$  genus

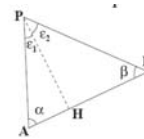


## Mean Curvature – Another View

- Mean Curvature Flow  $K(x) = kn \approx \frac{\nabla A}{A}$

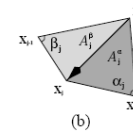
- Area gradient (per triangle):

$$\nabla A = \frac{1}{2} ((\cot \beta) \mathbf{AP} + (\cot \alpha) \mathbf{BP})$$



- Integrate (sum) on all triangles

$$\iint_{\mathcal{A}} \mathbf{K}(\mathbf{x}) dA = \frac{1}{2} \sum_{j \in N_1(i)} (\cot \alpha_{ij} + \cot \beta_{ij}) (\mathbf{x}_i - \mathbf{x}_j)$$

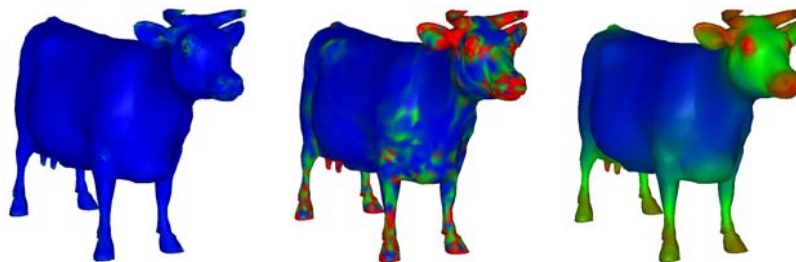


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- To get K (and normal) divide by “control” area



## Curvature – Practicalities Example: Gaussian



- Approximation always results in some noise
- Solution
  - Truncate extreme values
    - Can come for instance from division by very small area
  - Smooth
    - More later

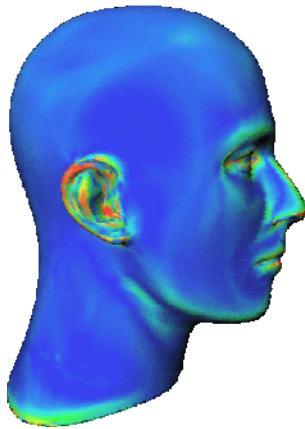


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## Examples: Mean Curvature



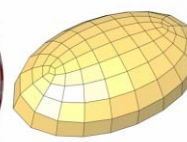
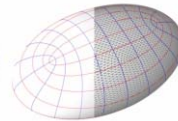
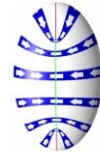
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## Some Applications



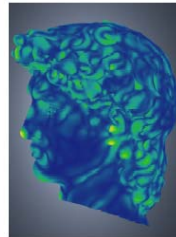
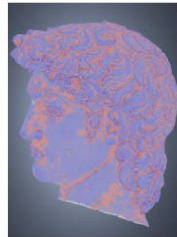
Ridges and Valleys



Remeshing



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Viewpoint  
selection