

November 3, 2010

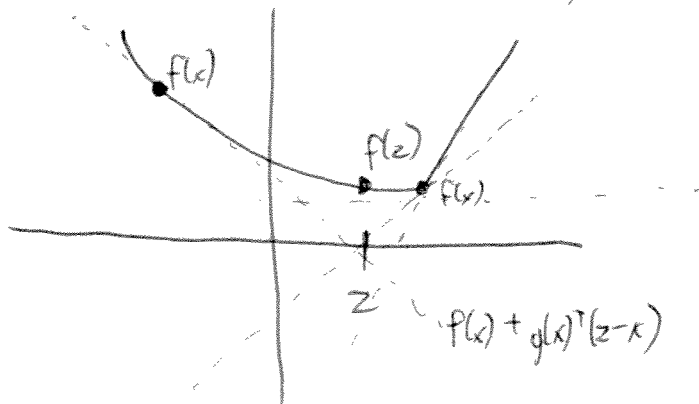
Outline:

- 1. Iteration Complexity, Assumptions
- 2. First-Order Complexity Zoo
- 3. Optimality of a stochastic method
- 4. Amplification.

1. Iteration Complexity and Assumptions

Problem: $\min_x f(x)$, where $f(x)$ is convex (not necessarily differentiable)

A vector $g(x)$ is a sub-gradient of f at x if $f(z) \geq f(x) + g(x)^T(z-x), \forall z$



$\partial f(x)$: set of sub-gradients at x .
 $\partial f(x)$ is always non-empty, if f is differentiable at x then $\partial f(x) = \{ \nabla f(x) \}$

We are given a first-order oracle.

Deterministic Oracle

Stochastic Oracle

On iteration k , algorithm receives:

- objective $f(x^k)$
 - sub-gradient $g(x^k) \in \partial f(x^k)$
 - noisy objective $F(x^k) = f(x^k) + w^k$
 - noisy gradient $G(x^k) = g(x^k) + s^k$
- where $E[w^k] = 0, E[s^k] = 0$

Deterministic

Stochastic

(2)

In terms of ϵ , how many iterations before:

$$\min_K f(x^{(K)}) - f(x^*) \leq \epsilon \quad ; \quad \min_K E[f(x^{(K)})] - f(x^*) \leq \epsilon$$

For example, we might have $K = O(1/\epsilon^2)$.

We need some assumptions to get this type of bound, such as $f(x^*) > -\infty$.

A1 (Bounded sub-gradient): There exists an M such that

$$M \geq \sup_x \|g(x)\|_2 \quad ; \quad M^2 \geq \sup_x E[\|G(x)\|_2^2]$$

only needs to hold on a compact set.

In some cases, we get better rates using quadratic bounds.

Eg. Assume f is twice-differentiable and for all x , $c \leq \text{eigs}(\nabla^2 f(x)) \leq L$, for $c > 0$.

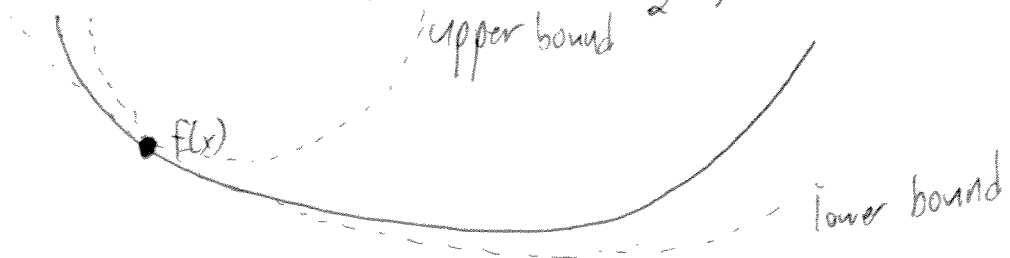
By Taylor expansion:
 $\forall x, y: f(y) = f(x) + (y-x)^T \nabla f(x) + \frac{1}{2} (y-x)^T \nabla^2 f(z) (y-x)$, for some z .

~~$$f(y) \leq f(x) + (y-x)^T \nabla f(x) + \frac{L}{2} \|y-x\|_2^2$$~~

Then (by spectral decomp):

(A) $f(y) \leq f(x) + (y-x)^T \nabla f(x) + \frac{L}{2} \|y-x\|_2^2$

(B) $f(y) \geq f(x) + (y-x)^T \nabla f(x) + \frac{c}{2} \|y-x\|_2^2$



We can get (A) and (B) under weaker assumptions:

(3)

(A) Gradient of differentiable f is Lipschitz-continuous if

$$\|\nabla f(x) - \nabla f(y)\| \leq L \|x - y\|.$$

Implies (A). Weak assumption (given differentiability) on a compact set.

(B) A function is strongly convex if $f(x) - \frac{\epsilon}{2} \|x\|_2^2$ is convex.

(Strongly convex \Rightarrow strictly convex \Rightarrow convex)

Implies (B) for differentiable functions, but differentiability is not required for strong convexity.

2. First-Order Complexity Zoo

We assume f is convex, there exists x^* , and bounded sub-gradients

Translation from error on iteration k to number of iterations:

$$O\left(\frac{1}{\sqrt{k}}\right) \Rightarrow O\left(\frac{1}{\epsilon^2}\right)$$

$$O\left(\frac{\log k}{k}\right) \Rightarrow O\left(\frac{1}{\epsilon}\right)$$

$$O\left(\frac{1}{k}\right) \Rightarrow O\left(\frac{1}{\epsilon}\right)$$

$$O\left(\frac{1}{k^2}\right) \Rightarrow O\left(\frac{1}{\epsilon}\right)$$

$$\frac{1}{\exp(O(k))} \Rightarrow O\left(\log\left(\frac{1}{\epsilon}\right)\right)$$

<u>Assumptions/Method</u>	<u>Deterministic</u>	<u>Stochastic</u>
none/sub-gradient	$O(1/\epsilon^2)$	$O(1/\epsilon^2)$
Lipschitz/gradient	$O(1/\epsilon)$	$O(1/\epsilon^2)$
smoothed to Lipschitz/Nesterov	$O(1/\epsilon)$	$O(1/\epsilon^2)$
strongly/sub-gradient	$\tilde{O}(1/\epsilon)$	$\tilde{O}(1/\epsilon)$
strongly/epoch averaging	$O(1/\epsilon)$	$O(1/\epsilon)$
Lipschitz/Nesterov	$O(1/\sqrt{\epsilon})$	$O(1/\epsilon^2)$
Lipschitz + strongly/gradient	$O(\log(1/\epsilon))$	$O(1/\epsilon)$
Lipschitz + strongly + "steps convex" / Barzilai-Borwein	$O(\log(1/\epsilon))$	N/A

we prove this one in next section

Notes:

- Lipschitz does not help in stochastic case
- Without Lipschitz, no difference between deterministic and stochastic (so we use stochastic)
- Polyak-Ruppert averaging does not give better rates, but can achieve the same rates with a more robust strategy.
- Many of these results are tight, no "first-order" method can do better by more than a constant.
- There is a second-order complexity zoo with faster rates like $O(1/\sqrt{\epsilon})$ for Lipschitz-Hessian and $O(\log \log(1/\epsilon))$ for Lipschitz and strongly convex

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(5)

- We can re-write (sub-)gradient method as:

$$\textcircled{*} \quad x^{k+1} \leftarrow \underset{x}{\operatorname{argmin}} \quad f(x^k) + (x - x^k)^T g(x^k) + \underbrace{\alpha^k \frac{1}{2} \|x - x^k\|_2^2}_{D(x, x^k)}$$

- Mirror Descent: replace $D(x, x^k)$ with another Bregman distance, get similar rates.
 (e.g. if x is a probability and use Kullback-Leibler divergence, get convergence rates for exponentiated gradient variants)
- Composite Objectives / Proximal-Splitting: add extra ^{convex} term $r(x)$ to $\textcircled{*}$ and solve, get the convergence rate of $f(x)$ even if $r(x)$ doesn't satisfy the same assumptions.
 (e.g. if $r(x) = \lambda \|x\|_1$, get convergence rates for iterative soft-thresholding variants)
- No results for MCMC, Kiefer-Wolfowitz, or other biased stochastic methods.

3. Optimality of a stochastic method (following Nemirovsky ~~et al.~~ et al., 2009)

Problem: $\min_x f(x)$, given first-order stochastic oracle.

Assume: strongly convex, Lipschitz gradient, bounded sub-gradient

Algorithm: $\alpha^k \leftarrow \frac{\Theta}{k}$, for some $\Theta > \frac{1}{2c}$

$$x^{k+1} \leftarrow x^k - \alpha^k G(x^k)$$

This simple algorithm has the 'optimal' expected error of $E = O(1/k)$

Outline of proof:

1. Express distance from x^{k+1} to x^* in terms of x^k .
2. Use bounded subgradient and strong convexity to bound expectation.
3. Use induction to get rate of convergence.
4. Use Lipschitz to bound function value.

Notation: $D^k = \frac{1}{2} \|x^k - x^*\|_2^2$, $d^k = E[D^k]$

$$\begin{aligned}
 1. D^{k+1} &= \frac{1}{2} \|x^{k+1} - x^*\|_2^2 = \frac{1}{2} \|(x^k - \alpha^k G(x^k)) - x^*\|_2^2 \\
 &= \frac{1}{2} \|(x^k - x^*) - \alpha^k G(x^k)\|_2^2 \\
 &= \frac{1}{2} \|x^k - x^*\|_2^2 - \alpha^k (x^k - x^*)^T G(x^k) + \frac{1}{2} (\alpha^k)^2 \|G(x^k)\|_2^2
 \end{aligned}$$

$$\begin{aligned}
 2. \text{Bound expected value} & \begin{cases} \text{by definition} \\ \text{by definition} \end{cases} \\
 d^{k+1} \leq d^k & - \alpha^k E[(x^k - x^*)^T \nabla f(x^k)] + \frac{1}{2} (\alpha^k)^2 M^2 \\
 & = E[(x^k - x^*)^T (\nabla f(x^k) - \nabla f(x^*))] \\
 & \geq c E[\|x^k - x^*\|_2^2] \text{ (by strong convexity)} \\
 & = 2cd^k
 \end{aligned}$$

Annotations for the derivation above:
 - $E[(x^k - x^*)^T \nabla f(x^k)] = 0$ (by tower property, linearity of expectation, definition of $G(x^k)$, differentiability of f)
 - $\frac{1}{2} (\alpha^k)^2 M^2$ (by bounded sub-gradient)

Use this and definition of α^k :

$$d_{k+1} \leq d_k - \frac{\theta}{k} (2cd^k) + \frac{1}{2} \frac{\theta^2}{k^2} M^2$$

3. "By induction": $d_k \leq \frac{B}{k}$, for $B = \max\{d_1, \frac{1}{2} \frac{\theta^2 M^2}{(2c\theta - 1)}\}$

Implies convergence in parameter values is $O(1/\sqrt{k})$, similar to asymptotic normality arguments.

7

4. By Lipschitz: $f(x) \leq f(x^*) + \frac{L}{2} \|x^* - x\|_2^2, \forall x$ (since $\nabla f(x^*) = 0$),
So:

$$f(x^k) - f(x^*) \leq \frac{L}{2} \|x^* - x^k\|_2^2$$

take expectation \downarrow by definition \downarrow

~~$$f(x^k) - f(x^*) \leq \frac{L}{2} \|x^* - x^k\|_2^2$$~~

$$E[f(x^k) - f(x^*)] \leq L d^k \leq \frac{L\beta}{K} \quad \square \text{ QED}$$

4. Amplification

- On a given run, the method may do worse than its expectation.
- Can we make sure it doesn't do "too badly"?
- $f(x^k) - f(x^*)$ is a non-negative random variable, use Markov's inequality to bound probability of deviation from expectation.

Recall: $P(X \geq a) \leq \frac{E[X]}{a}$, ~~$P(X \geq a) \leq \frac{E[X]}{a}$~~

Take $a = 2E[X]$ to get:

$$P\{f(x^k) - f(x^*) \geq 2E[f(x^k) - f(x^*)]\} \leq 1/2$$

If we run it twice: $P\{\dots\} \leq 1/4$

thrice: $P\{\dots\} \leq 1/8$

$\log(1/\delta)$ times: $P\{\dots\} \leq \delta$

- We need $k \log(1/\delta)$ iterations to be within a constant of the bound with probability $1 - \delta$.

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