

Unsupervised Learning

What is it?

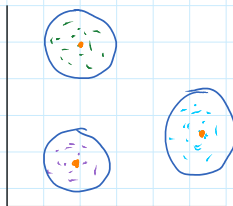
- no labels
- discover patterns in data / structures
- clustering

Just a bunch of vectors, what to do with them?

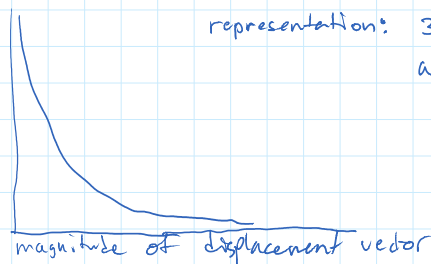
What are our Goals?

- understand data
- sanity check
- remove uninformative part of data (dimensionality reduction) (compression)
- learning features (and feature selection)
- visualization

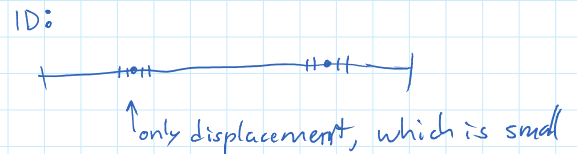
clustering



k-means: adds points to clusters



representation: 3 centers, assignment (lossy compression)



- new points are likely in the cluster

Principle Component Analysis (PCA)

- dimensionality reduction method

approximate data set in some dimension m , $m < d$

PCA is a linear model

$$v_n = W x_n$$

$$v \in \mathbb{R}^m$$

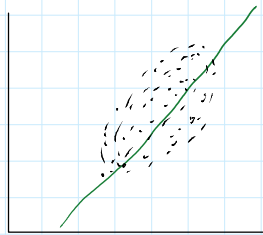
$$W \in \mathbb{R}^{m \times d}$$

$$x \in \mathbb{R}^d$$

new dimensionality
original dimensionality

X : whole data set $\mathbb{R}^{d \times N}$

amount of data



← one dimensional subspace (project)

approximate representation

"maximize variance"
of projected values

- equivalent to small L_2 error / fitting

$M=1$ (for now)

$$u \in \mathbb{R}^d$$

← learning u

$$u^T u = 1$$

variance of projected data:

$$= \frac{1}{N} \sum_{n=1}^N (u^T x_n)^2 \quad (\text{sum of squares})$$

$$= u^T S u, \quad \text{where } S \text{ is covariance matrix } X X^T$$

$$\max_u \quad u^T S u + \lambda (1 - u^T u)$$

Lagrange multiplier: ie, $1 = u^T u$

$$S u - \lambda u = 0$$

$$S u = \lambda u$$

(eigenvector of covariance matrix of the data)

- but which eigenvector?

variance is now:

$$u^T S u = u^T \lambda u = \lambda u^T u = \lambda$$

- pick biggest eigenvalue

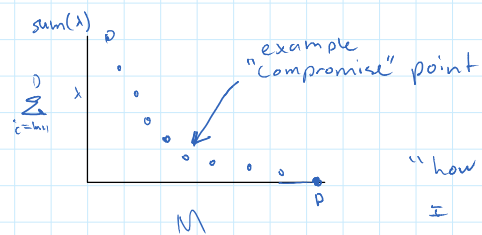
$m > 1$? repeat with remaining variance

Singular Value Decomposition (SVD)

$$X = U \Sigma V^T$$

eigenvalues in Σ , pick biggest
another way of doing eigenvalue decomposition

How to pick m ?



"how much of the variance am I throwing away?"

Probabilistic PCA - generative, higher dimension

$$X_n = W z_n + \varepsilon$$

← noise
← latent space

$$z_n \in \mathbb{R}^m, x_n \in \mathbb{R}^D, W \in \mathbb{R}^{D \times m}$$

$$z_n \sim N(0, \mathbf{I}) \quad \text{iid}$$

$$\varepsilon \sim N(0, \sigma^2 \mathbf{I}) \quad \text{iid} \quad (\text{isotropic noise})$$

$$p(x | z) \sim N(Wz, \sigma^2 \mathbf{I})$$

$$p(x) \sim N(\mu, C)$$

$$\mu = E[x] = E[Wz + \varepsilon] = 0$$

$$C = \text{cov}[x] = E[(Wz + \varepsilon)(Wz + \varepsilon)^T]$$

$$= E[Wz z^T W^T] + E[\varepsilon \varepsilon^T]$$

$$= W W^T + \sigma^2 \mathbf{I}$$

MLE is PCA

W only appears as $W W^T$

$$\tilde{W} = W R \quad \leftarrow \text{orthogonal}$$

$$\tilde{W} \tilde{W}^T = W R R^T W^T = W W^T$$

could be considered undesirable, any orthogonal transformation on W gives the same model

Cocktail Party Problem

microphones listening to sum of S voices
decompose signal to S sources

Blind Source Separation

treat as i.i.d. data

$$Z = \begin{bmatrix} \text{person 1} \\ \text{person 2} \\ \vdots \end{bmatrix}$$

infer distances, disambiguate people

observed
↓

$$X = WZ$$

$t =$ # time samples

$n_s =$ # of speakers

$n_m =$ # of microphones

unknowns: $n_s n_m + t n_s$

equations: $t n_m$

if $t n_m >$ # unknowns,
we can hopefully solve it

PCA: disaster! Z means S people

PCA could be multiplied by some orthogonal matrix

the problem has a "correct answer"

Independent Component Analysis (ICA)

- linear model (like PCA)
- NOT Gaussian prior on Z
- $p(z) = \prod_{n=1}^M p(z_n)$

Factor Analysis

- like probabilistic PCA, but: instead of variance $\sigma^2 I$ variance, each element can have its own.