Tutorial 2

CPSC 340: Machine Learning and Data Mining

Fall 2017



- Decision Stump
- Decision Tree



Decision Stump

- Decision stump: simple decision tree with 1 splitting rule based on 1 feature.
- Binary example:



- Assigns a label to each leaf based on the most frequent label.
- How to find the best splitting rule?
 - score the rules
 - intuitive score: classification accuracy.

• X: A matrix

- each row corresponds to a city
 - first column corresponds to longitude
 - second column corresponds to latitude
- y: class label
 - 1 for blue states, 2 for red states.
- Given new city Xtest
 - predict label ytest

exampledecisionStump.jl

```
example_decisionStump.jl
    using JLD
   X = load("citiesSmall.jld","X")
   y = load("citiesSmall.jld","y")
    (n.d) = size(X)
   ### Majority Predictor Model ###
14 include("majorityPredictor.il")
  model = majorityPredictor(X,y)
18 vhat = model.predict(X)
19 trainError = sum(vhat .!= v)/n
20 @printf("Error with majority predictor: %.2f\n".trainError):
    ### Decision Stump Moodel #######
27 include("decisionStump.il")
28 model = decisionStumpEquality(X,y)
31 vhat = model.predict(X)
32 trainError = sum(yhat .!= y)/n
   @printf("Error with equality-rule decision stump: %.2f\n".trainError);
  include("plot2Dclassifier.jl")
   plot2Dclassifier(X,y,model)
```

decisionStump.jl

decisionStump.il 1 include("misc.il") # Includes "mode" function type StumpModel baseSplit # Set this to one stump doesn't split function decisionStumpEquality(X,y) (n,d) = size(X) $X = round_{1}(X)$ $y_mode = mode(y)$ minError = sum(y .!= y_mode); splitVariable = []; solitValue = []: splitYes = y_mode; splitNo = []; what = zeros(n) for val in unique(X[:,j]) ves = X[:.i] .== val v ves = mode(v[ves]) y_no = mode(y[.!yes]) 83 end

decisionStump.il

vhat[ves] = v ves vhat[.!ves] = v no

trainError = sum(vhat .!= v)

if trainError < minError minError = trainError splitVariable = i splitValue = val splitNo = y_no end function split(Xhat) Xhat = round.(Xhat) if isempty(splitVariable) return fill(true,t) return (Xhat[:,splitVariable] .== splitValue) function predict(Xhat) (t,d) = size(Xhat) yes = split(Xhat)

yhat = fill(splitNo,t)

yhat[yes] = splitYes

return yhat

return StumpModel(predict,split,isempty(splitNo))

- Decision stumps have only 1 rule based on only 1 feature.
 - Very limited class of models: usually not very accurate for most tasks.
- Decision trees allow sequences of splits based on multiple features.
 - Very general class of models: can get very high accuracy.
 - However, it's computationally infeasible to find the best decision tree.
- Most common decision tree learning algorithm in practice:
 - Greedy recursive splitting.

exampleDecisionTree.jl and decisionTree.jl

	example_decisionTree.jl		decisionTree.jl
1		1	include("decisionStump.jl")
2	using JLD		
3	<pre>X = load("citiesSmall.jld","X")</pre>		<pre>function decisionTree(X,y,depth)</pre>
4	<pre>y = load("citiesSmall.jld","y")</pre>		
5	n = size(X, 1)		
6			
7			(n,d) = size(X)
8	include("decisionTree.jl")		
9	depth = 2		# Learn a decision stump
10	model = decisionTree(X,y,depth)		<pre>splitModel = decisionStump(X,y)</pre>
11			
12	# Evaluate training error		if depth <= 1 splitModel.baseSplit
13	yhat = model.predict(X)		# Base cases where we stop splitting:
14	trainerror = sum(ynat .!= y)/n		# - this stump gets us to the max depth
15	eprintt("Error with depth-%d decision tree: %.3T(n",depth,trainError)		# - this stump doesn't split the data
10			return splithodet
17	# Plot classifier		else
10	nictude(ptotzbctassifier.jt)		were enlightedel enlight/Y)
20	protzberassilier(x,y,modec)	20	yes = spirinder.spirith)
20			# Perusively fit a decision tree to each solit
			vesModel = decisionTree(X[ves:1].v[ves].denth=1)
			noModel = decisionTree(X[.]ves.:].v[.]ves].denth-1)
			# Make a predict function
			function predict(Xhat)
			<pre>(t,d) = size(Xhat)</pre>
			yhat = zeros(t)
			<pre>yes = splitModel.split(Xhat)</pre>
			<pre>yhat[yes] = yesModel.predict(Xhat[yes,:])</pre>
			<pre>yhat[.!yes] = noModel.predict(Xhat[.!yes,:])</pre>
			return yhat
			end
			return GenericModel(predict)
			end
			end
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Rewriting a decision tree using if/else statements

• Decision tree:



Rewriting a decision tree using if/else statements

• Decision tree:



• If-else statement:

```
if X(i,98) ==1
    if X(i,6) ==1
        return 2
    else
        return 1
    end
else
        if X(i,89)==1
        return 2
    else
        return 4
end
end
```

Training, Testing, and Validation Set

- Given training data, we would like to learn a model to minimize error on the testing data
- How do we decide decision tree depth?
- We care about test error.
- But we can't look at test data.
- So what do we do?????

Training, Testing, and Validation Set

- Given training data, we would like to learn a model to minimize error on the testing data
- How do we decide decision tree depth?
- We care about test error.
- But we can't look at test data.
- So what do we do?????
- One answer: Use part of your train data to approximate test error.
- Split training objects into training set and validation set:
 - Train model on the training data.
 - Test model on the validation data.

Cross-Validation

- Isn't it wasteful to only use part of your data?
- k-fold cross-validation:
 - Train on k-1 folds of the data, validate on the other fold.
 - Repeat this k times with different splits, and average the score.



Figure 1: Adapted from Wikipedia.

• Note: if examples are ordered, split should be random.

- Modify the code below to compute the 2-fold cross-validation scores on the training data alone.
- Find the depth that would be chosen by cross-validation.

```
% Load X and y variable
load newsgroups.mat
[N,D] = size(X);
T = length(ytest);
depth = 5;
model = .decisionTree(X,y,depth);
yhat = model.predictFunc(model,X);
errorTrain = sum(yhat ~= y)/N;
yhat = model.predictFunc(model,Xtest);
errorTest = sum(yhat ~= ytest)/T;
```

Solution: 2-Fold Cross Validation

```
% Load X and v variable
  load newsgroups.mat
  [N,D] = size(X);
 Xtest = X (floor(N/2) + 1 : N , : );
 ytest= y (floor(N/2) +1 : N) ;
 X = X (1:floor(N/2), :);
 v = v (1: floor(N/2));
 mindepth = -1 ; minError = Inf;
- for depth =1 :15
     errorTrain = 0: errorTest = 0:
      for i =1:2
         [N,D] = size(X);
         T = length(vtest);
         model = decisionTree(X,v,depth);
         vhat = model.predictFunc(model,X);
         errorTrain = errorTrain +sum(yhat ~= y)/N;
         yhat = model.predictFunc(model,Xtest);
         errorTest = errorTest + sum(yhat ~= ytest)/T;
          [X, Xtest]=mvSwap(Xtest, X);
          [v,vtest] = mvSwap(vtest,v) ;
      end
     disp(errorTest/2 ) ;
      if errorTest/2 < minError
         minError= errorTest/2:
         mindepth = depth;
      end
  end
 disp(minError); disp(mindepth);
```