

CPSC 340: Machine Learning and Data Mining

Sparse Matrix Factorization

Fall 2016

Admin

- **Midterms:**
 - Midterms can be viewed during office hours.
- **Assignment 4:**
 - Due Monday.
- **Office hours:**
 - Tuesday 2pm office hours moved to ICICS 104.
 - Extra office hours Thursdays from 4:30-5:30 in ICICS X836.
- **Assignment 5:**
 - Out on the weekend.

Last Time: PCA with Orthogonal/Sequential Basis

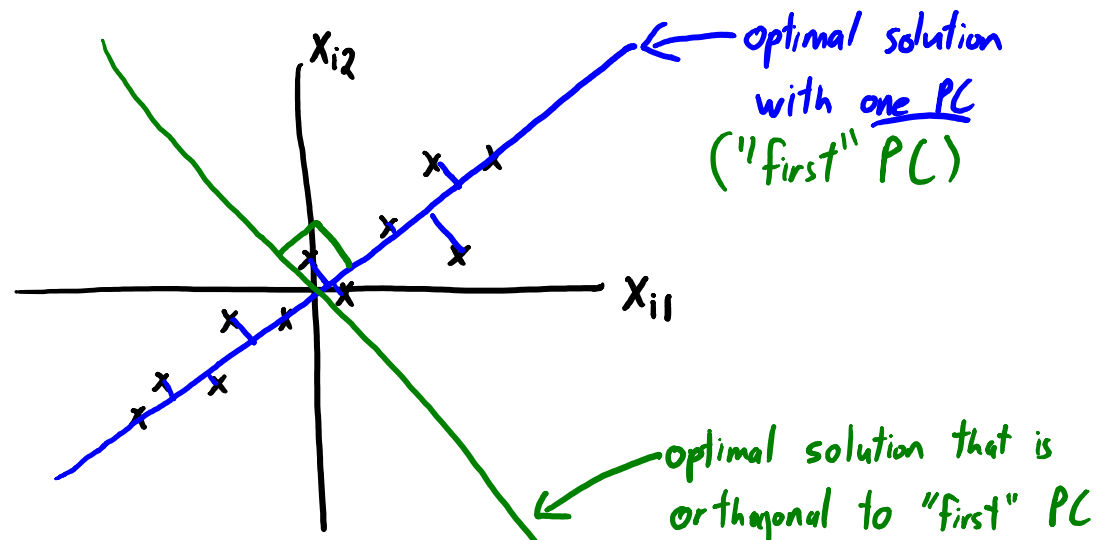
- When $k = 1$, PCA has a **scaling problem**.
- When $k > 1$, have **scaling, orthogonality, rotation, label switching**.

– Standard fix: use **normalized orthogonal rows** w_c of 'W'.

$$w_c^T w_c = 1 \quad \text{and} \quad w_c^T w_{c'} = 0 \quad \text{for } c \neq c'$$

– And **fit the rows in order**:

- First row “explains the most variance” or “reduces error the most”.



Last Time: Learning a Basis for Faces

- We discussed three ways to learn a basis z_i for faces:
 - **K-means** (vector quantization).
 - Replace face by the **average face in a cluster**.
 - **Can't distinguish between people** in the same cluster (only 'k' possible faces).

$$X_i = z_{i1} * w_1 + z_{i2} * w_2 + z_{i3} * w_3 + z_{i4} * w_4 + z_{i5} * w_5 + z_{i6} * w_6 + \dots$$

Last Time: Learning a Basis for Faces

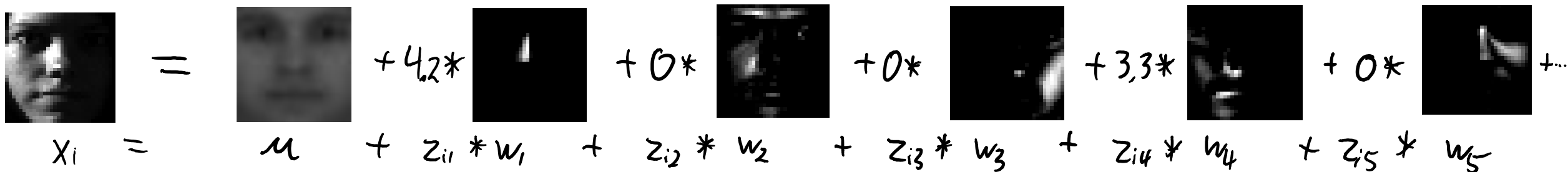
- We discussed three ways to learn a basis z_i for faces:
 - **K-means** (vector quantization).
 - **PCA** (orthogonal basis).
 - Global average plus **linear combination of “eigenfaces”**.
 - Can generate an **infinite number of faces** when changing the z_i .
 - But “eigenfaces” are **not intuitive** ingredients for faces.

$$X_i = \mu + z_{i1} * w_1 + z_{i2} * w_2 + z_{i3} * w_3 + z_{i4} * w_4 + z_{i5} * w_5 + \dots$$

862 *
+1960 *
-488 *
-201 *
-615 *

Last Time: Learning a Basis for Faces

- We discussed three ways to learn a basis z_i for faces:
 - **K-means** (vector quantization).
 - **PCA** (orthogonal basis).
 - **NMF (non-negative matrix factorization)**:
 - Instead of requiring orthogonality requires **non-negativity**.
 - No “ordering” among parts.
 - The z_i are **sparse** so each face only uses a subset of the **sparse “parts”**.


$$X_i = \mu + z_{i1} * w_1 + z_{i2} * w_2 + z_{i3} * w_3 + z_{i4} * w_4 + z_{i5} * w_5 + \dots$$

Warm-up to NMF: Non-Negative Least Squares

- Consider our usual **least squares** problem:

$$f(w) = \frac{1}{2} \sum_{i=1}^n (w^T x_i - y_i)^2$$

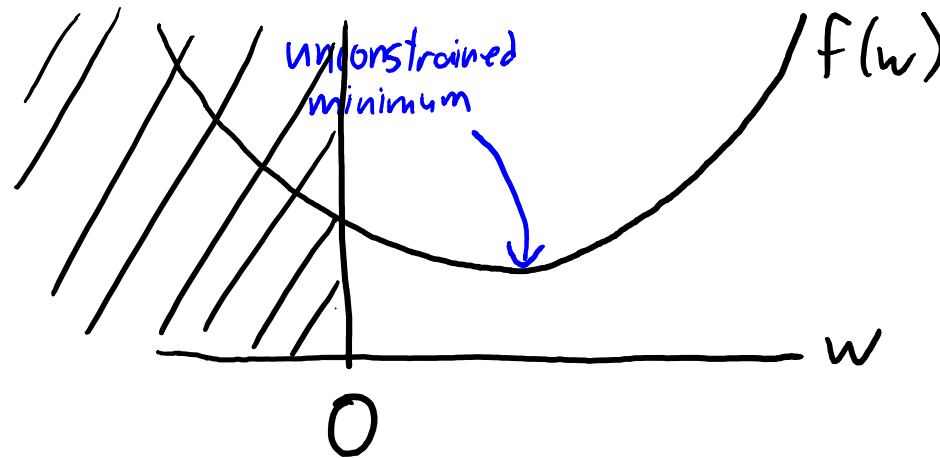
- But assume **y_i and elements of x_i are non-negative**:
 - Could be sizes ('height', 'milk', 'km') or counts ('vicodin', 'likes', 'retweets').
- Assume we want elements of ' **w** ' to be **non-negative**, too:
 - **No physical interpretation to negative weights.**
 - If x_{ij} is amount of product you produce, what does $w_j < 0$ mean?
- **Non-negativity tends to generate sparse solutions.**

Sparsity and Non-Negative Least Squares

- Consider 1D non-negative least squares objective:

$$f(w) = \frac{1}{2} \sum_{i=1}^n (w x_i - y_i)^2 \quad \text{with } w > 0$$

- Plotting the (constrained) objective function:



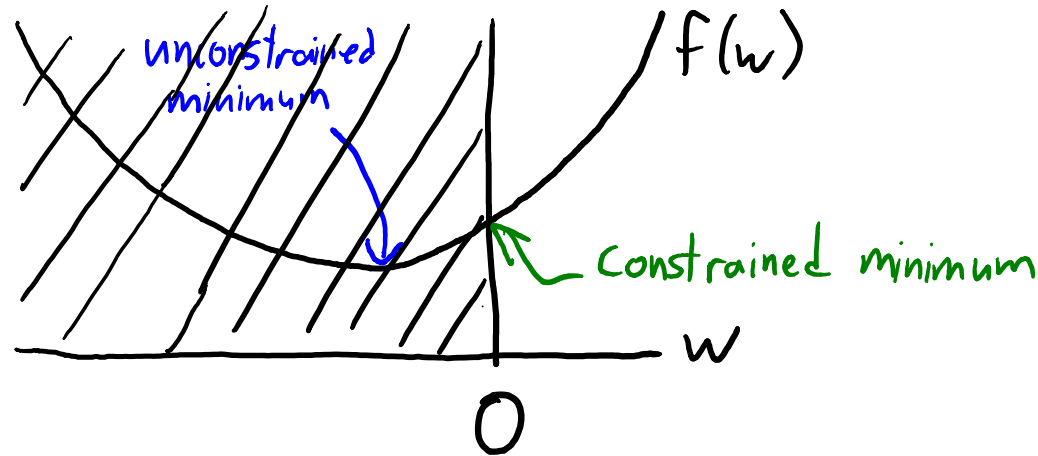
- In this case, non-negative solution is least squares solution.

Sparsity and Non-Negative Least Squares

- Consider 1D non-negative least squares objective:

$$f(w) = \frac{1}{2} \sum_{i=1}^n (w x_i - y_i)^2 \quad \text{with } w > 0$$

- Plotting the (constrained) objective function:



- In this case, **non-negative solution is $w = 0$.**

Sparsity and Non-Negativity

- So **non-negativity leads to sparsity**.
 - Also **regularizes**: w_j are smaller since can't "cancel" out negative values.
- How can we minimize $f(w)$ with **non-negative constraints**?
 - **Naive approach**: solve least squares problem, set negative w_j to 0.

$$\text{Compute } w = (X^T X)^{-1} (X^T y)$$

$$\text{Set } w_j = \max\{0, w_j\}$$

- This is correct when $d = 1$.
- **Can be worse than setting $w = 0$** when $d \geq 2$.

Sparsity and Non-Negativity

- So **non-negativity leads to sparsity**.
 - Also **regularizes**: w_j are smaller since can't “cancel” out negative values.
- How can we minimize $f(w)$ with **non-negative constraints**?
 - A correct approach is **projected gradient** algorithm:

- Run a **gradient descent** iteration:

$$w^{t+1/2} = w^t - \alpha^t \nabla f(w^t)$$

- **After each step, set negative values to 0.**

$$w_j^{t+1} = \max\{0, w_j^{t+1/2}\}$$

- Repeat.

Sparsity and Non-Negativity

- Similar to L1-regularization, **non-negativity leads to sparsity**.
 - Also **regularizes**: w_j are smaller since can't “cancel” out negative values.
- How can we minimize $f(w)$ with **non-negative constraints**?
 - Correct approach is “**projected**” gradient descent:

$$w^{t+1/2} = w^t - \alpha^t \nabla f(w^t)$$

$$w_j^{t+1} = \max\{0, w_j^{t+1/2}\}$$

– **Similar properties to gradient descent**:

- Guaranteed decrease of ‘f’ if α_t is small enough.
- Reaches local minimum under weak assumptions (global minimum for convex ‘f’).
- Generalizations allow things like **L1-regularization** instead of non-negativity.

(findMinL1.m)

Projected-Gradient for NMF

- Back to the **non-negative matrix factorization (NMF)** objective:

$$f(W, Z) = \sum_{i=1}^n \sum_{j=1}^d (w_j^T z_i - x_{ij})^2 \quad \text{with } w_{cj} \geq 0 \text{ and } z_{ij} \geq 0$$

– Different ways to use **projected gradient**:

- Alternate between projected gradient steps on 'W' and on 'Z'.
- Or run projected gradient on both at once.
- Or sample a random 'i' and 'j' and do **stochastic projected gradient**.

$$\text{Set } z_i^{t+1} = z_i^t - \alpha^t \nabla_{z_i} f(W, Z) \text{ and } w_j^{t+1} = w_j^t - \alpha^t \nabla_{w_j} f(W, Z) \text{ for selected } i \text{ and } j$$

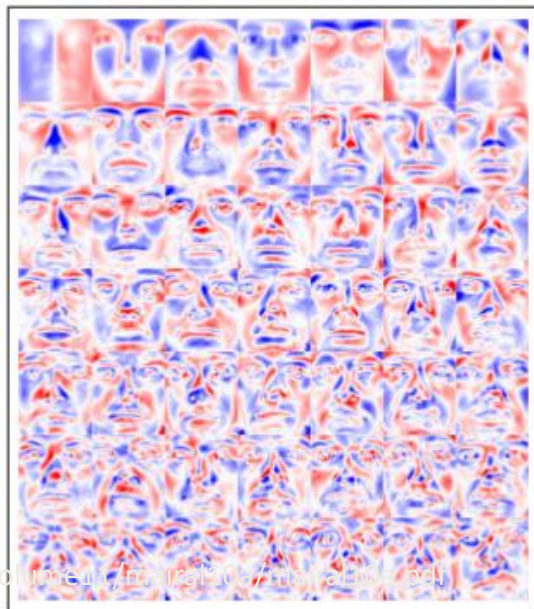
– **Non-convex** and (unlike PCA) is sensitive to initialization.

- Hard to find the global optimum.
- Typically use **random initialization**.

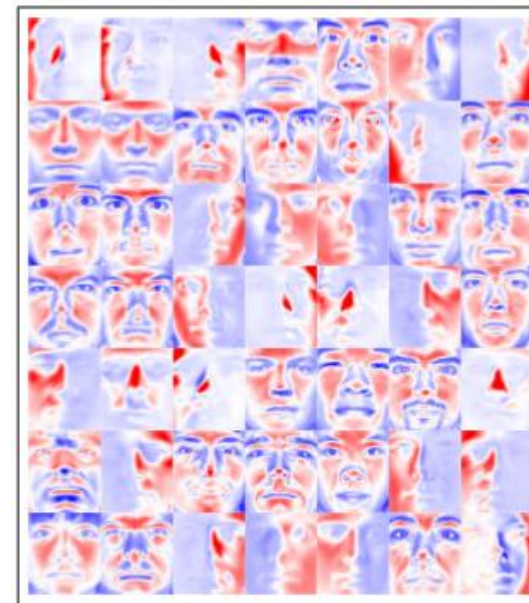
(keep other values of W and Z fixed)

Regularized Matrix Factorization

- For many PCA applications, ordering orthogonal PCs makes sense.
 - Latent factors are independent of each other.
 - We definitely want this for visualization.
- In other cases, ordering orthogonal PCs doesn't make sense.
 - We might not expect a natural "ordering".



Usual
orthogonal
eigen faces



PCA with
non-orthogonal
basis.

Regularized Matrix Factorization

- More recently people have considered **L2-regularized PCA**:

$$f(W, Z) = \frac{1}{2} \|ZW - X\|_F^2 + \frac{\lambda_1}{2} \|W\|_F^2 + \frac{\lambda_2}{2} \|Z\|_F^2 \rightarrow \sum_{c=1}^k \sum_{j=1}^d w_{cj}^2$$

- Replaces normalization/orthogonality/sequential-fitting.
 - But requires **regularization parameters** λ_1 and λ_2 .
- **Need to regularize W and Z** because of scaling problem:
 - Regularizing only 'W' won't work: you could make 'Z' big to compensate.
 - You could alternately constrain one and regularize the other:

$$f(W) = \frac{1}{2} \|ZW - X\|_F^2 + \frac{\lambda}{2} \|Z\|_F^2 \quad \text{with } \|w_c\| \leq 1 \quad \text{for all 'c'}$$

Sparse Matrix Factorization

- Instead of non-negativity, we could use L1-regularization:

$$f(W, Z) = \frac{1}{2} \|ZW - X\|_F^2 + \frac{\lambda_1}{2} \sum_{i=1}^n \|z_i\|_1 + \frac{\lambda_2}{2} \sum_{j=1}^d \|w_j\|_1$$

- Called **sparse coding** (L1 on 'Z') or **sparse dictionary learning** (L1 on 'W').
- **Disadvantage of using L1-regularization** over non-negativity:
 - Sparsity controlled by λ_1 and λ_2 so you need to set these.
- **Advantage of using L1-regularization:**
 - Negative coefficients usually make sense.
 - Sparsity controlled by λ_1 and λ_2 , so you can control amount of sparsity.

Sparse Matrix Factorization

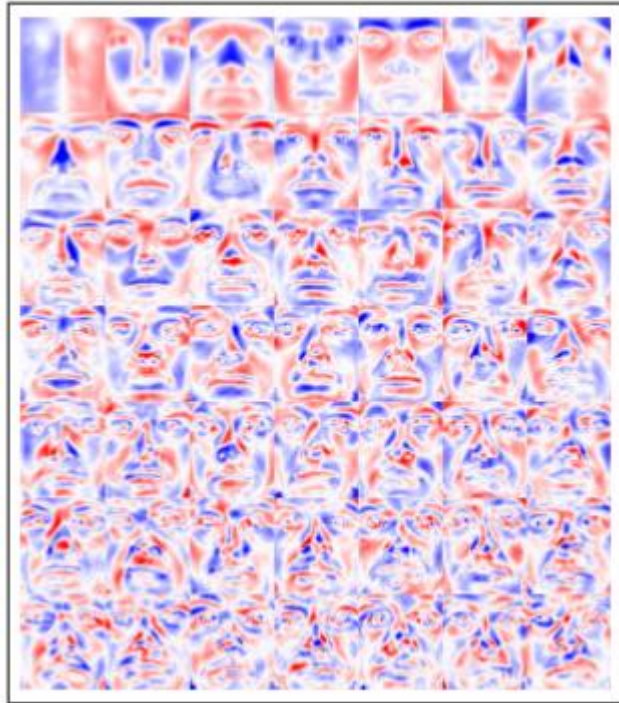
- Instead of non-negativity, we could use L1-regularization:

$$f(W, Z) = \frac{1}{2} \|ZW - X\|_F^2 + \frac{\lambda_1}{2} \sum_{i=1}^n \|z_i\|_1 + \frac{\lambda_2}{2} \sum_{j=1}^d \|w_j\|_1$$

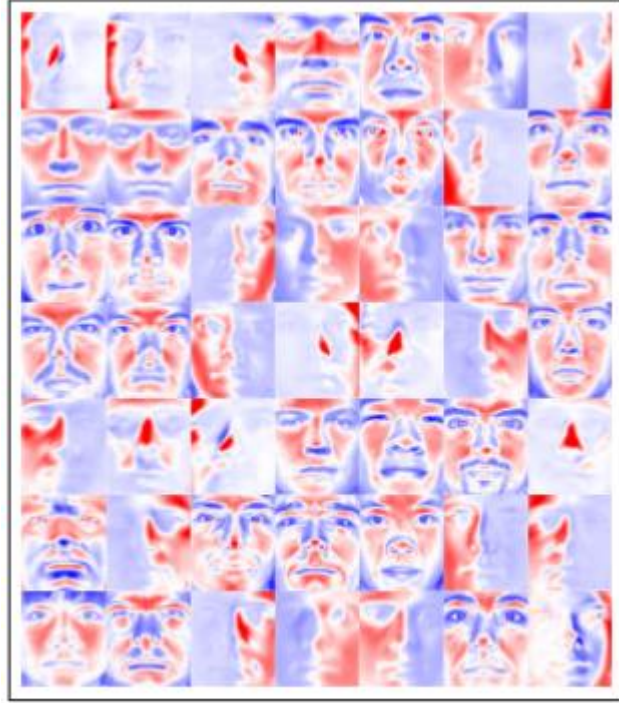
- Called **sparse coding** (L1 on 'Z') or **sparse dictionary learning** (L1 on 'W').
- Many variations exist:
 - Mixing L2-regularization and L1-regularization or making one a constraint.
 - **K-SVD** constrains each z_i to have at most 'k' non-zeroes:
 - K-means is special case where $k = 1$.
 - PCA is special case where $k = d$.

Matrix Factorization with L1-Regularization

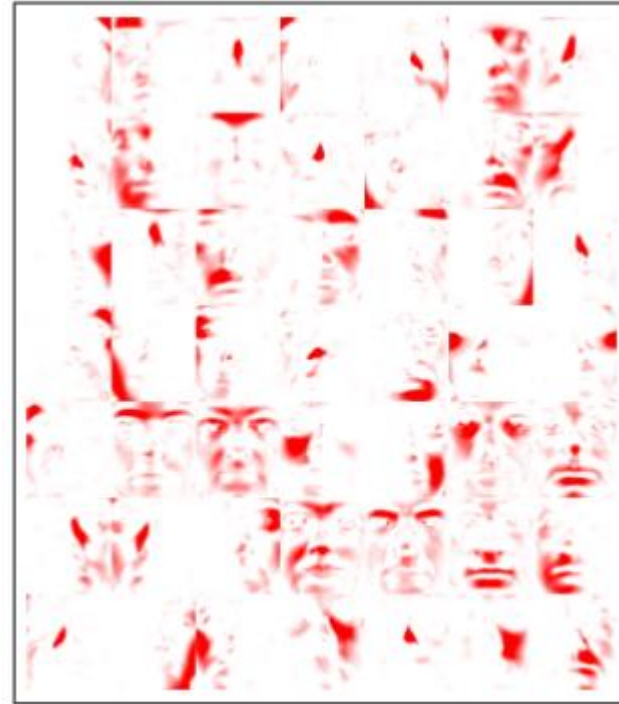
blue: negative
red: positive



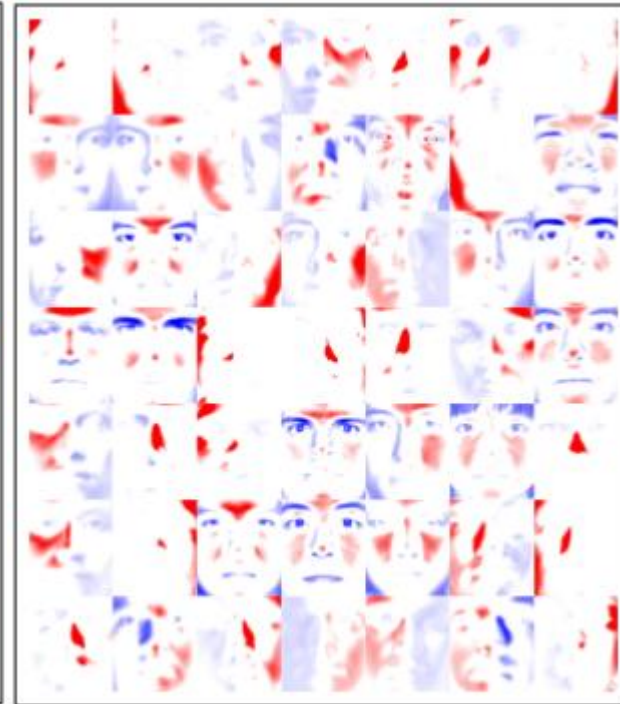
(a) PCA



(e) Dictionary Learning



(c) NMF



(d) SPCA, $\tau = 30\%$

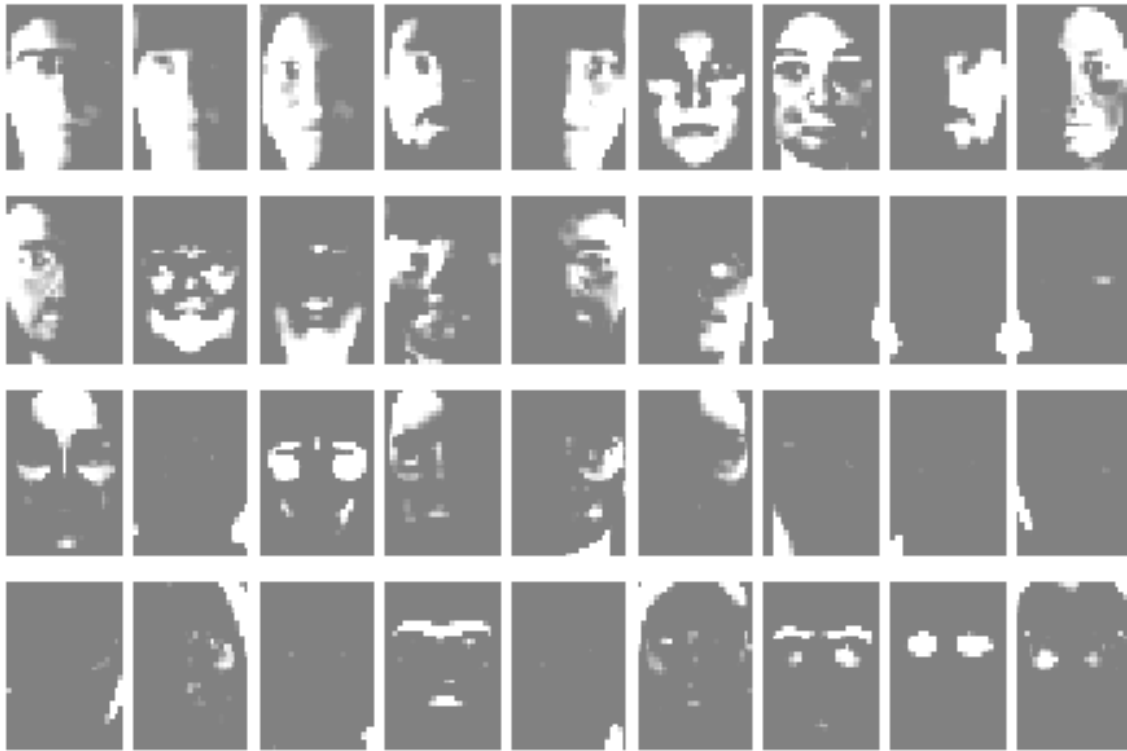
PCA without orthogonality

sparsity due to non-negativity

sparsity due to L_1 -regularization

Recent Work: Structured Sparsity

- “**Structured sparsity**” considers dependencies in sparsity patterns.



NMF

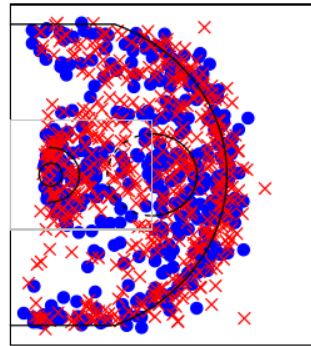


Sparse PCA with "structured" sparsity

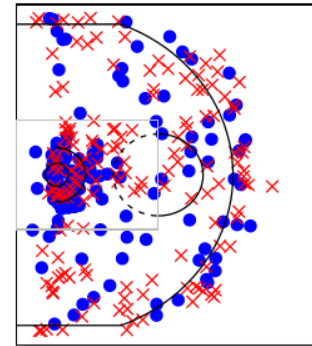
Application: Sports Analytics

- NBA shot charts:

Stephen Curry (940 shots)

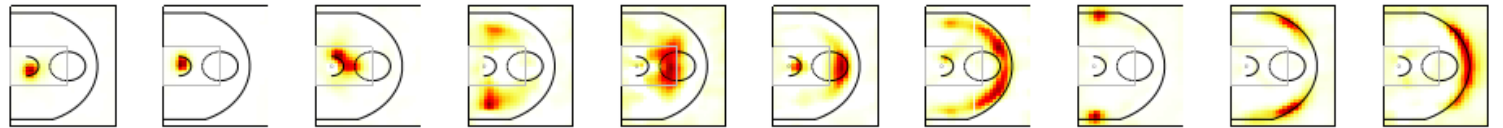


LeBron James (315 shots)



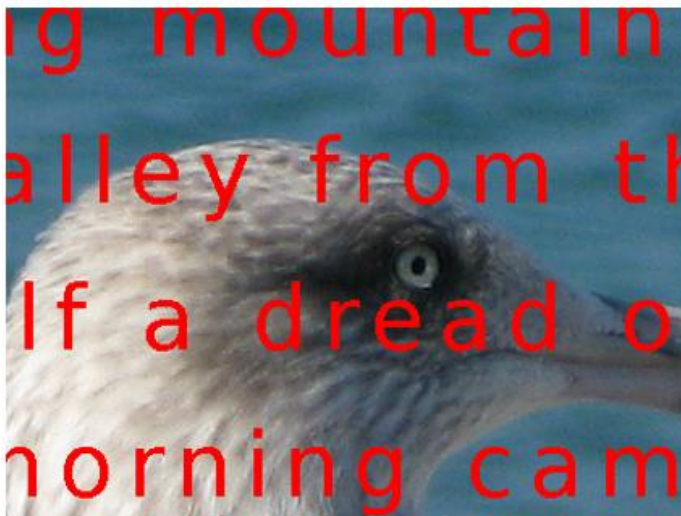
- NMF (using “KL divergence” loss with $k=10$ and smoothed data).

– Negative values would not make sense here.



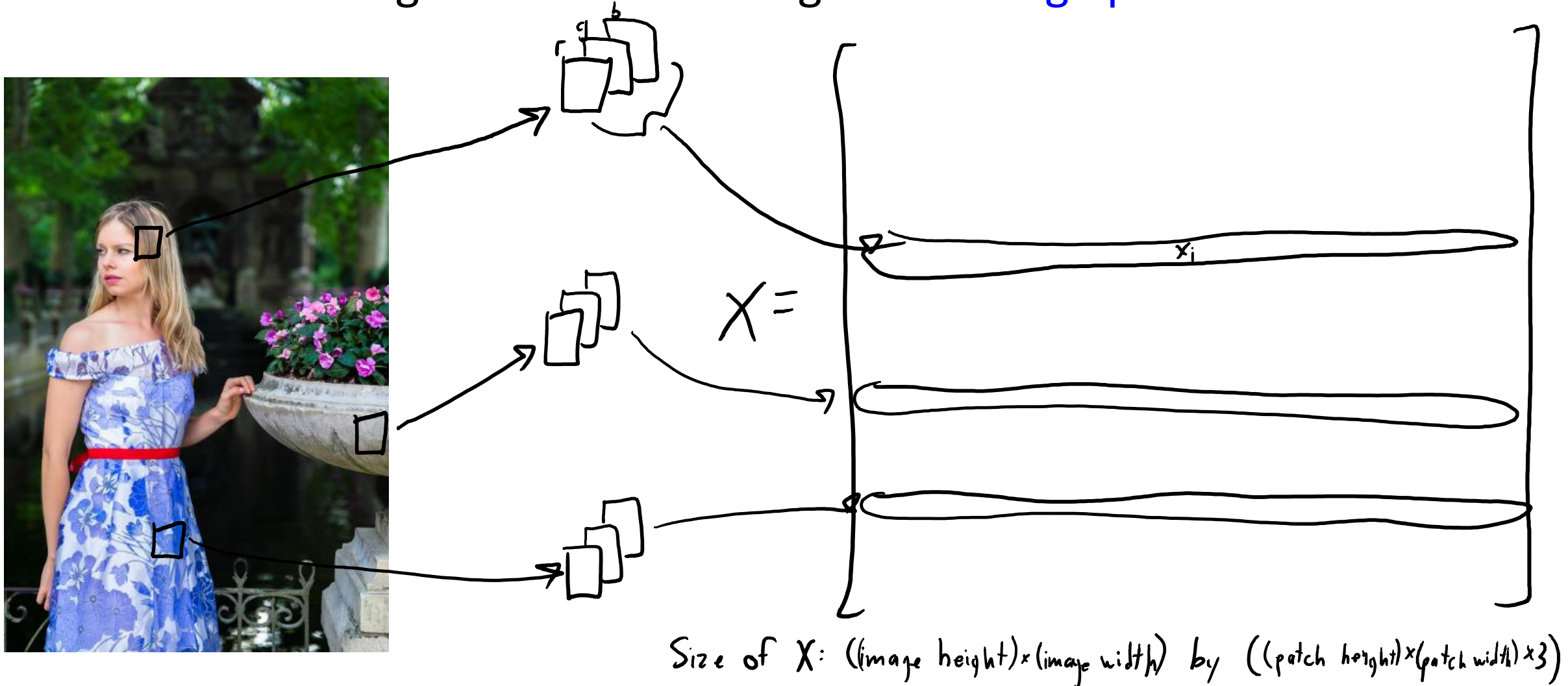
LeBron James	0.21	0.16	0.12	0.09	0.04	0.07	0.00	0.07	0.08	0.17
Brook Lopez	0.06	0.27	0.43	0.09	0.01	0.03	0.08	0.03	0.00	0.01
Tyson Chandler	0.26	0.65	0.03	0.00	0.01	0.02	0.01	0.01	0.02	0.01
Marc Gasol	0.19	0.02	0.17	0.01	0.33	0.25	0.00	0.01	0.00	0.03
Tony Parker	0.12	0.22	0.17	0.07	0.21	0.07	0.08	0.06	0.00	0.00
Kyrie Irving	0.13	0.10	0.09	0.13	0.16	0.02	0.13	0.00	0.10	0.14
Stephen Curry	0.08	0.03	0.07	0.01	0.10	0.08	0.22	0.05	0.10	0.24
James Harden	0.34	0.00	0.11	0.00	0.03	0.02	0.13	0.00	0.11	0.26
Steve Novak	0.00	0.01	0.00	0.02	0.00	0.00	0.01	0.27	0.35	0.34

Application: Image Restoration



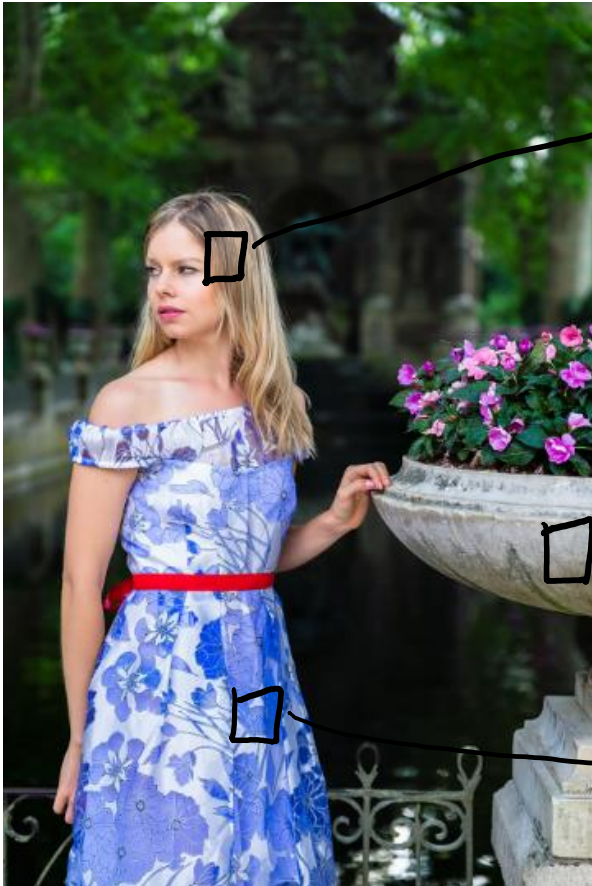
Latent-Factor Models for Image Patches

- Consider building latent-factors for general **image patches**:



Latent-Factor Models for Image Patches

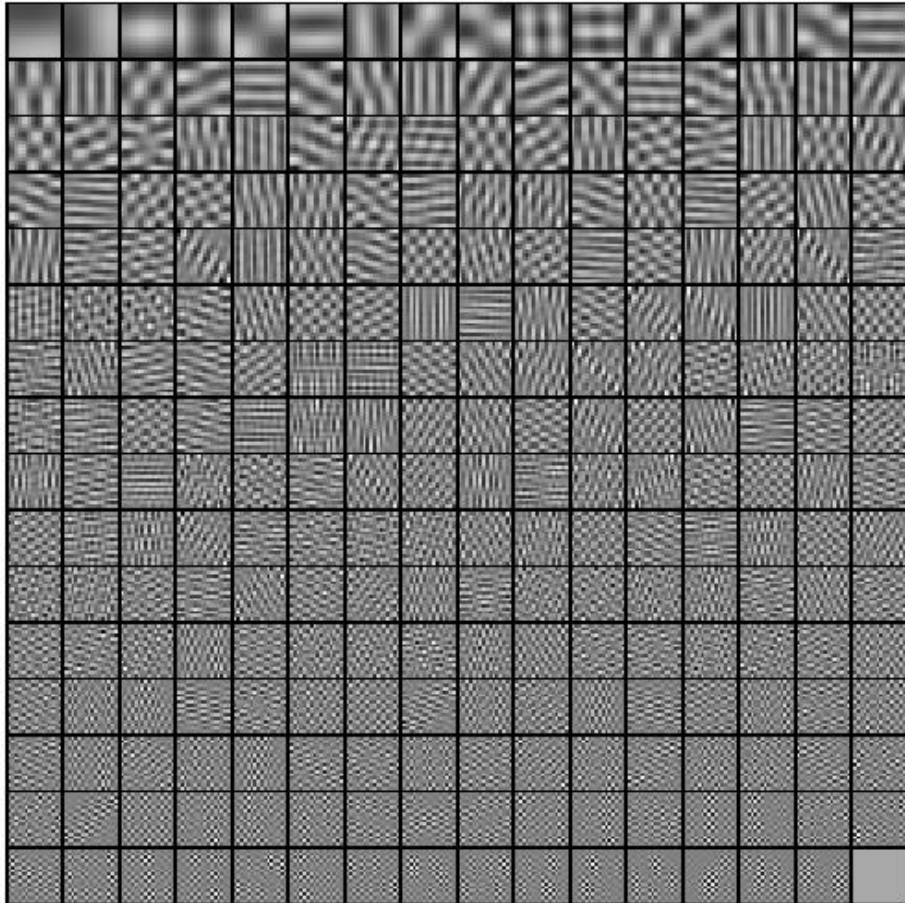
- Consider building latent-factors for general **image patches**:



Typical pre-processing:

1. Usual variable centering
2. “Whiten” patches.
(remove correlations)

Latent-Factor Models for Image Patches

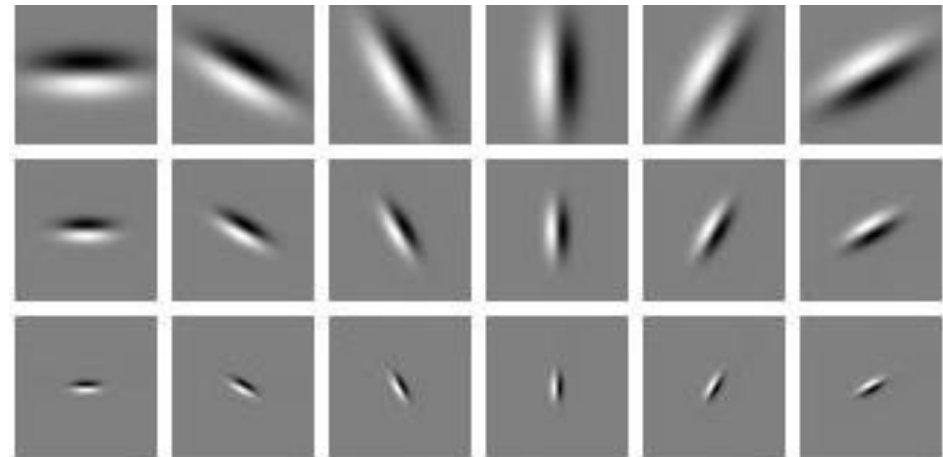


(b) Principal components.

Orthogonal bases don't seem right:

- Few PCs do almost everything.
- Most PCs do almost nothing.

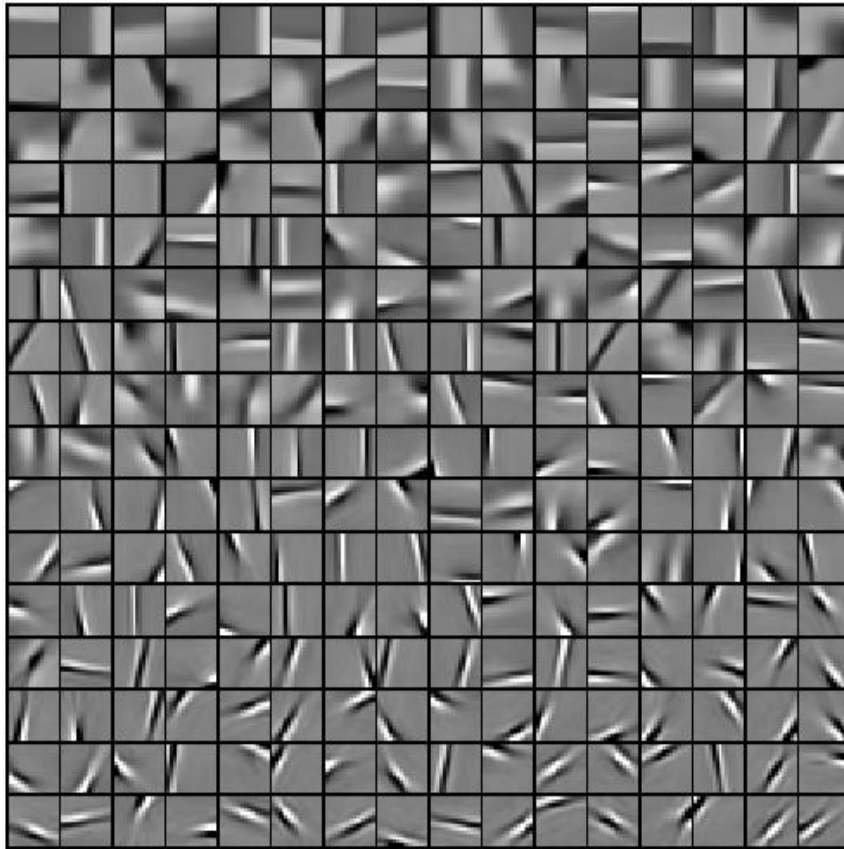
We believe “simple cells” in visual cortex use:



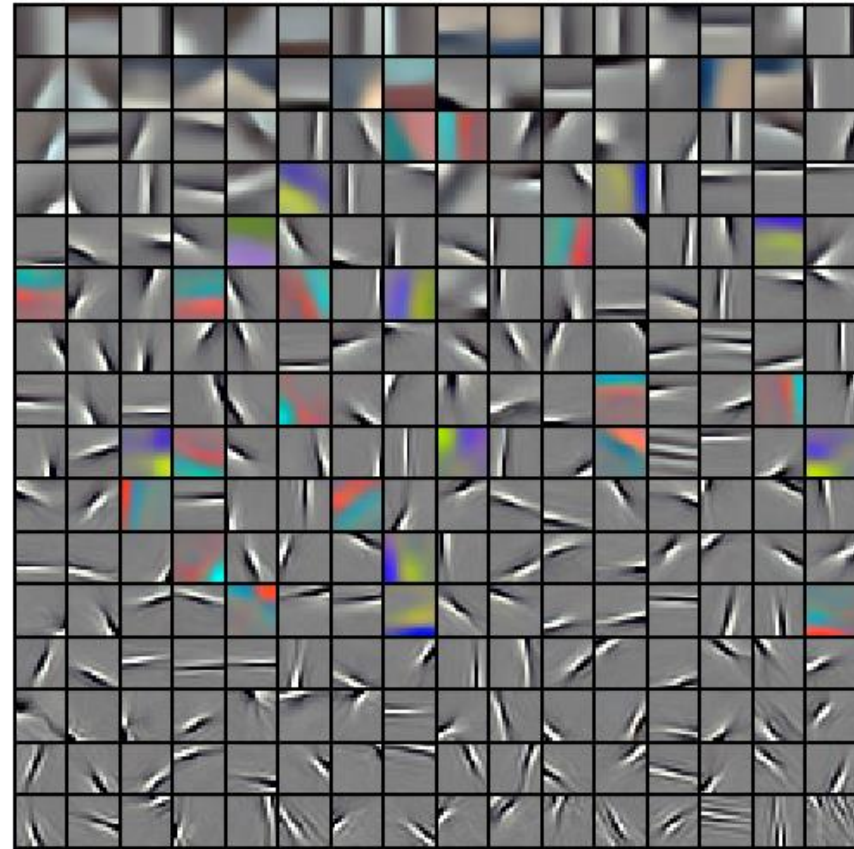
'Gabor' filters

Latent-Factor Models for Image Patches

- Results from a sparse (non-orthogonal) latent factor model:



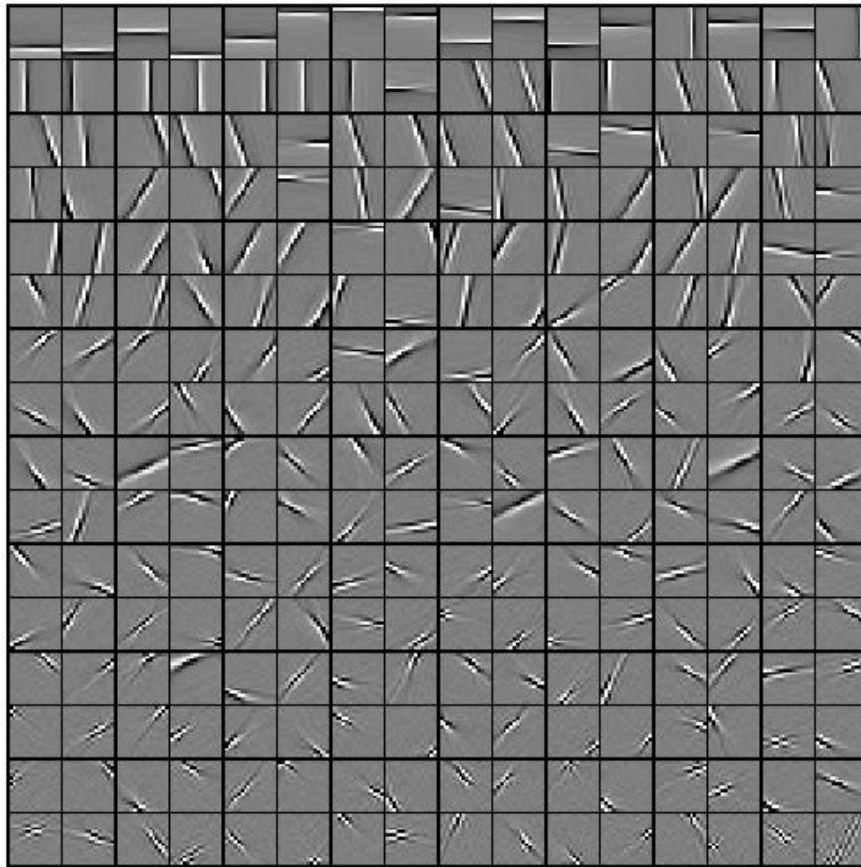
(a) With centering - gray.



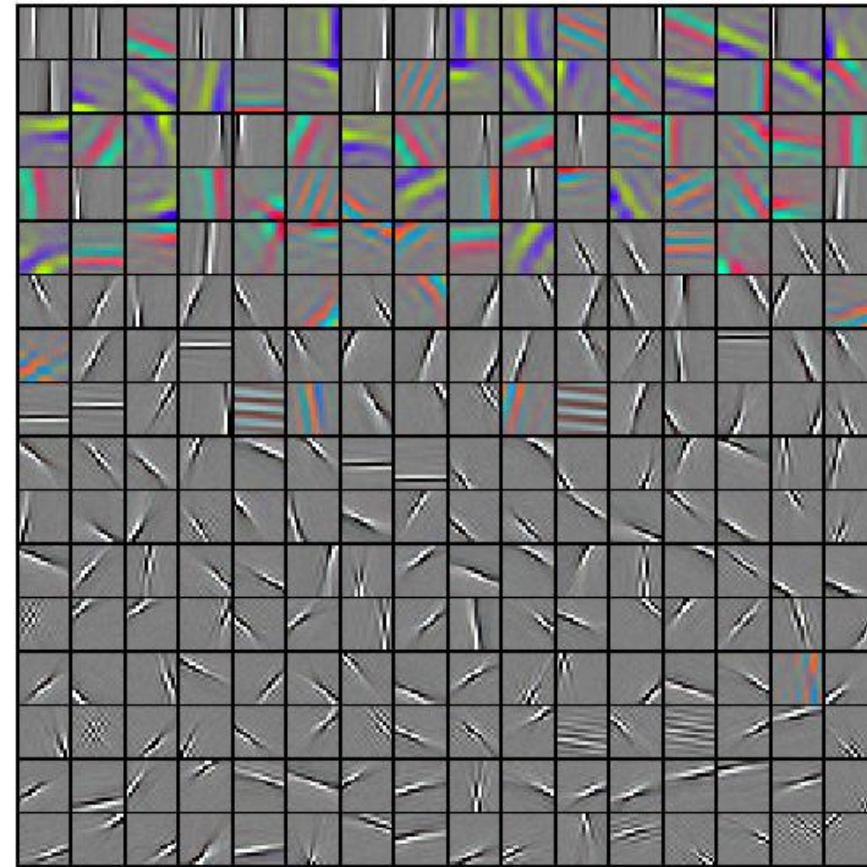
(b) With centering - RGB.

Latent-Factor Models for Image Patches

- Results from a “sparse” (non-orthogonal) latent-factor model:



(c) With whitening - gray.

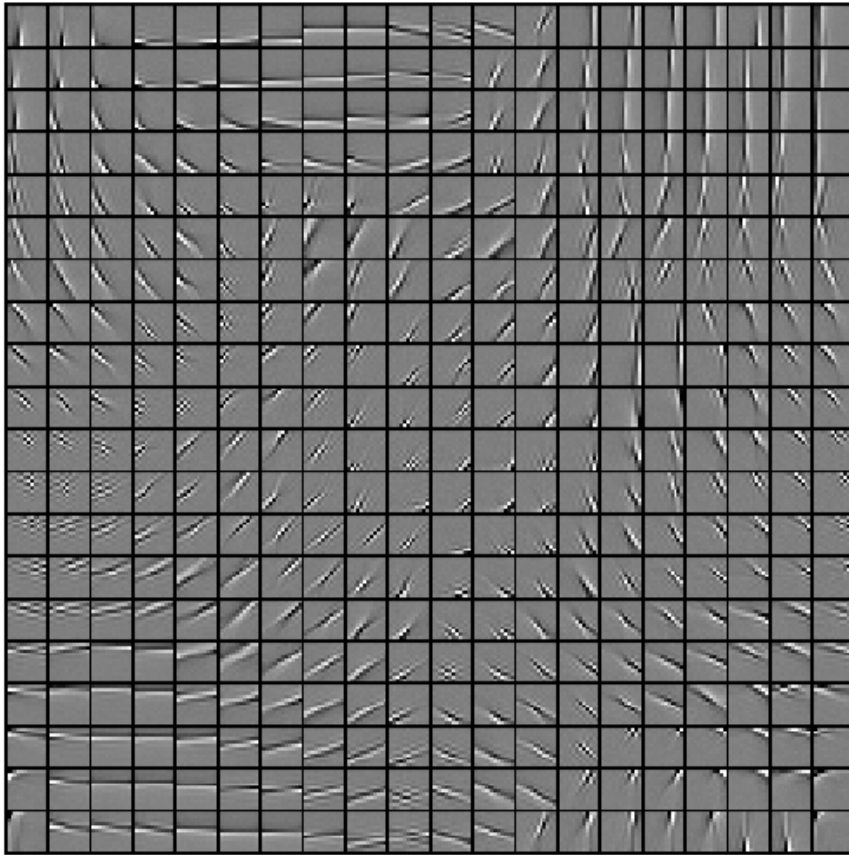


(d) With whitening - RGB.

colour opponency

Recent Work: Structured Sparsity

- Basis learned with a variant of “structured sparsity”:



Similar to "cortical columns"
theory in visual cortex.

(b) With 4×4 neighborhood.

Beyond Squared Error

- Our (unregularized) objective for **latent-factor models** (LFM):

$$f(W, Z) = \sum_{i=1}^n \sum_{j=1}^d (w_j^T z_i - x_{ij})^2$$

- As before, there are **squared error alternatives**.
- We can get a LFM for **binary** x_{ij} using the **logistic loss**:

$$f(W, Z) = \sum_{i=1}^n \sum_{j=1}^d \log(1 + \exp(-x_{ij} w_j^T z_i))$$

Robust PCA

- Robust PCA methods use the **absolute error**:

$$f(W, Z) = \sum_{i=1}^n \sum_{j=1}^d |w_j^T z_i - x_{ij}|$$

- Will be **robust to outliers** in the matrix 'X'.
- Encourages "residuals" r_{ij} to be exactly zero.
 - Non-zero r_{ij} are where the "outliers" are.

x_{ij}

$w_j^T z_i$

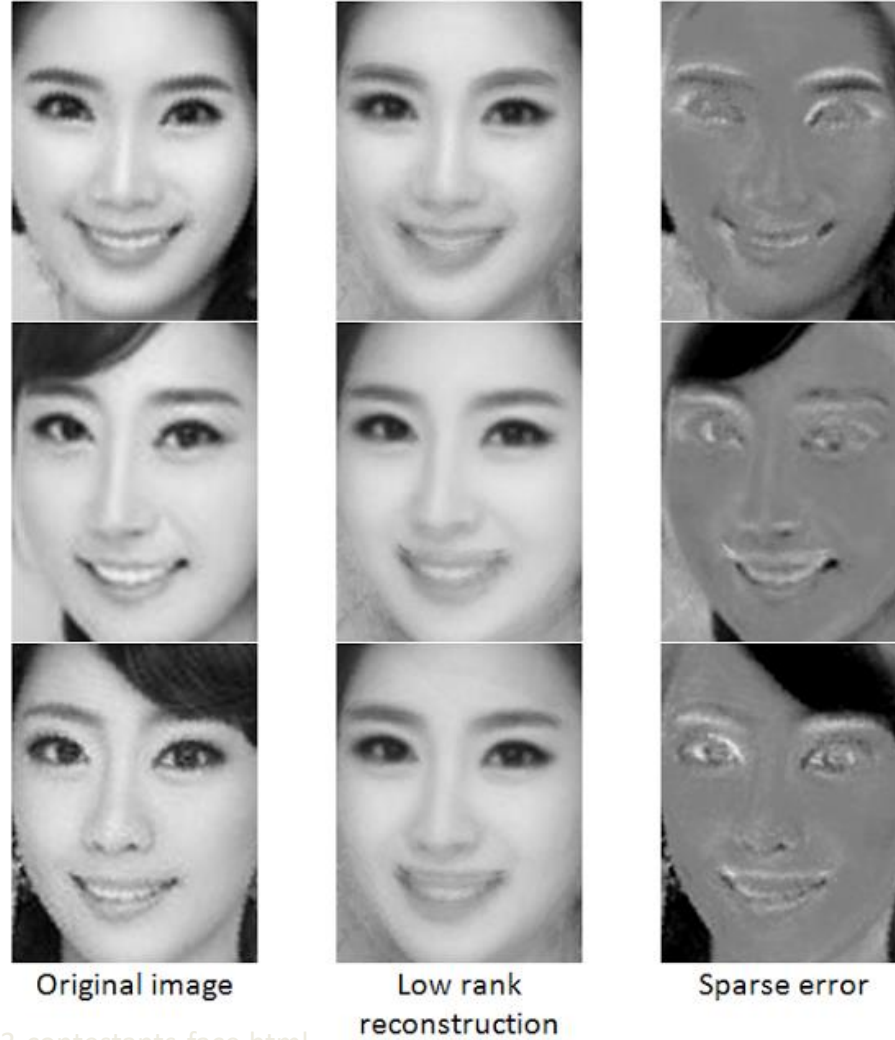
r_{ij}

Applying robust PCA
to video frames



Robust PCA

- Miss Korea contestants and robust PCA:



Summary

- **Non-negativity** constraints lead to sparse solution.
- **Projected gradient** adds constraints to gradient descent.
- **Non-orthogonal LFM**s make sense in many applications.
- **L1-regularization** leads to other sparse LFMs.
- **Robust PCA** allows identifying certain types of outliers.
- Next time: predicting which movies you are going to like.