

CPSC 340: Machine Learning and Data Mining

Linear Least Squares

Fall 2016

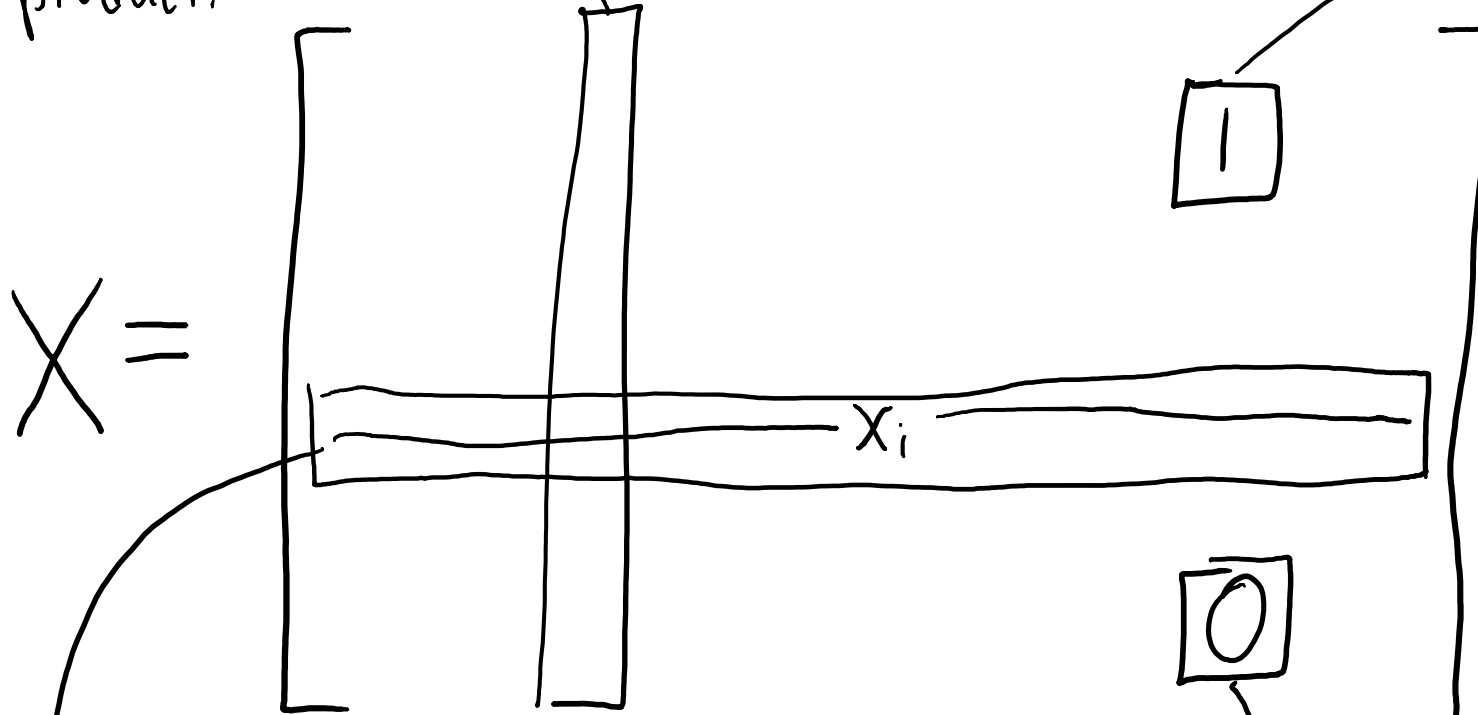
Admin

- **Assignment 2** is due Friday:
 - You should already be started!
 - 1 late day to hand it in on Wednesday, 2 for Friday, 3 for next Monday.
- We **will have tutorials** on Tuesday/Wednesday of next week:
 - Focusing on multivariate calculus in matrix notation.
- **Tutorial room change**: T1D (Monday @5pm) moved to DMP 101.

User-Product Matrix

Column gives all users that bought product.

$X_{ij} = 1$ means user 'i' bought item 'j'!

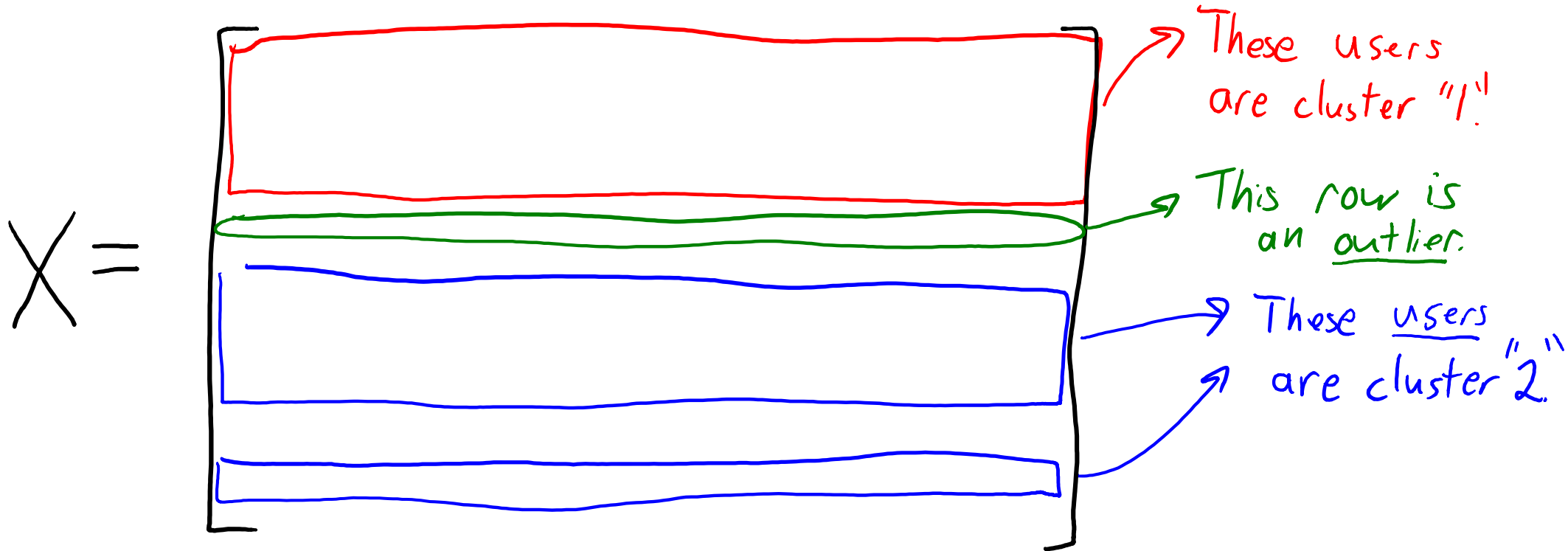


$X_{ij} = 0$ means user 'i' did not buy item 'j'!

Row x_i gives all items bought by user 'i'. By convention, x_i is a $d \times 1$ column vector.

Clustering User-Product Matrix

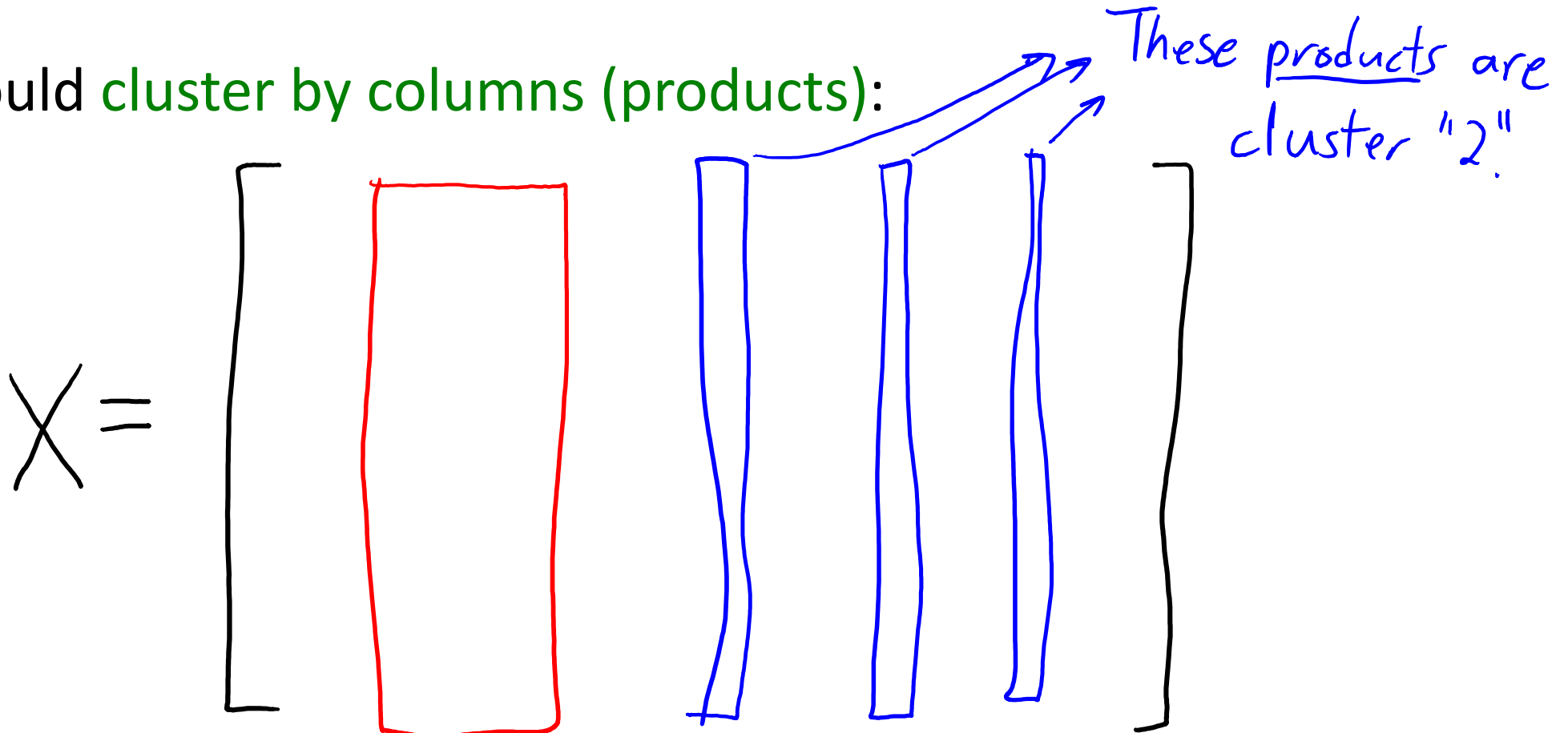
- Normally think of clustering by rows (users):



- We also find outliers by rows.

Clustering User-Product Matrix

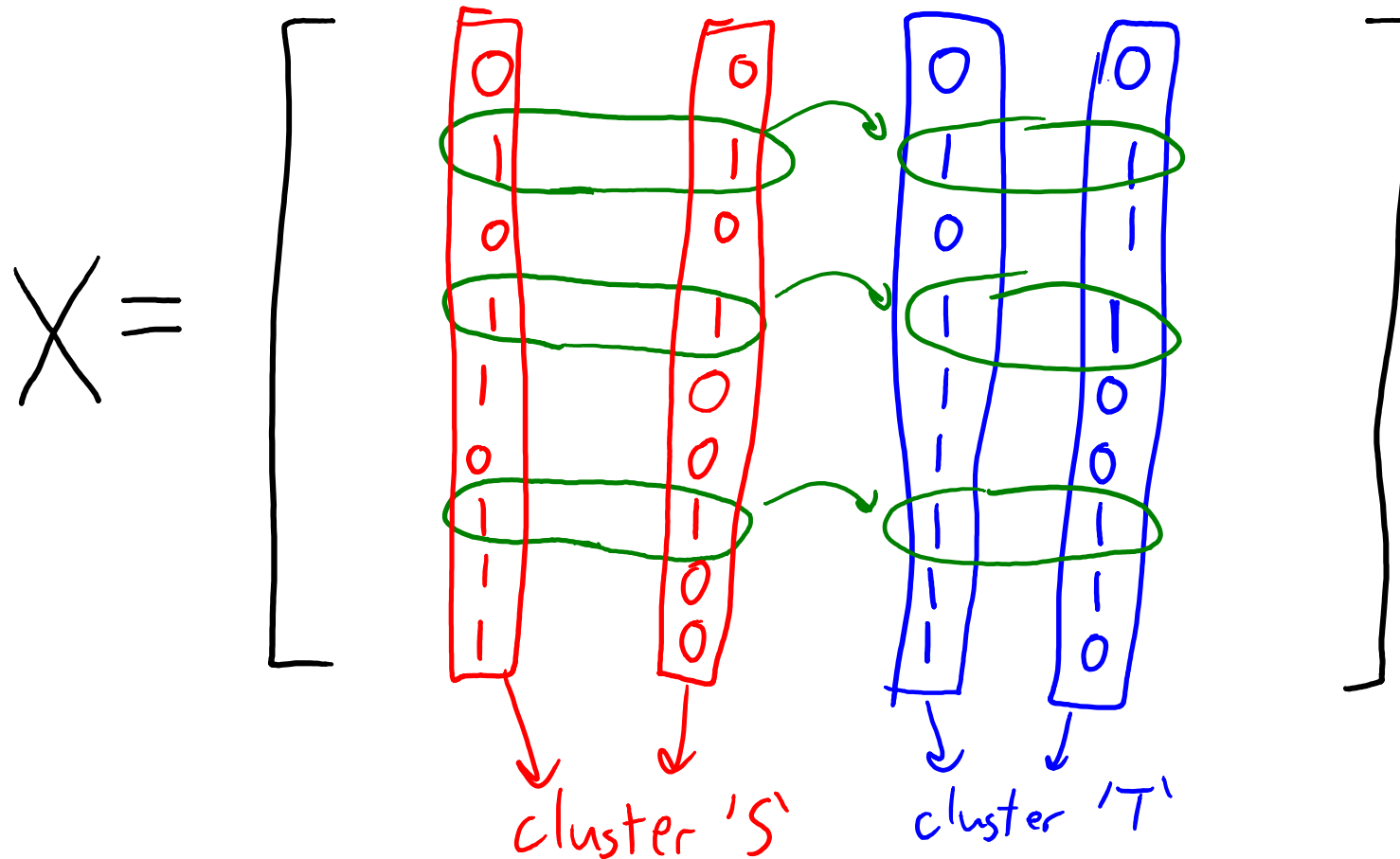
- We could **cluster by columns (products)**:



- Apply clustering to X^T .

Association Rules

- Association rules ($S \Rightarrow T$): all '1' in cluster S \Rightarrow all '1' in cluster T.



Amazon Product Recommendation

- Amazon product recommendation works by columns:

– Conceptually, you take the user-product matrix:

$$X = \begin{bmatrix} \text{①} \end{bmatrix} \rightarrow \text{user 'i' bought item 'j'}$$

– And transpose it to make a product-user matrix:

$$X^T = \begin{bmatrix} \text{①} \end{bmatrix} \rightarrow \text{product 'i' was bought by user 'j'}$$

- Find similar products as nearest neighbours among products.
- Cosine similarity used as “distance”.

End of Part 2: Key Concepts

- We focused on 3 unsupervised learning tasks:
 - Clustering.
 - K-means algorithm (and using it for vector quantization).
 - Density-based clustering (and region-based pruning for finding close points).
 - Hierarchical clustering (and agglomerative algorithm for constructing trees).
 - Outlier Detection.
 - Surveyed common approaches (and said that problem is ill-defined).
 - Association rules.
 - A priori algorithm (for finding rules with high support and confidence).
 - Amazon product recommendation (for huge datasets).

Supervised Learning Round 2: Regression

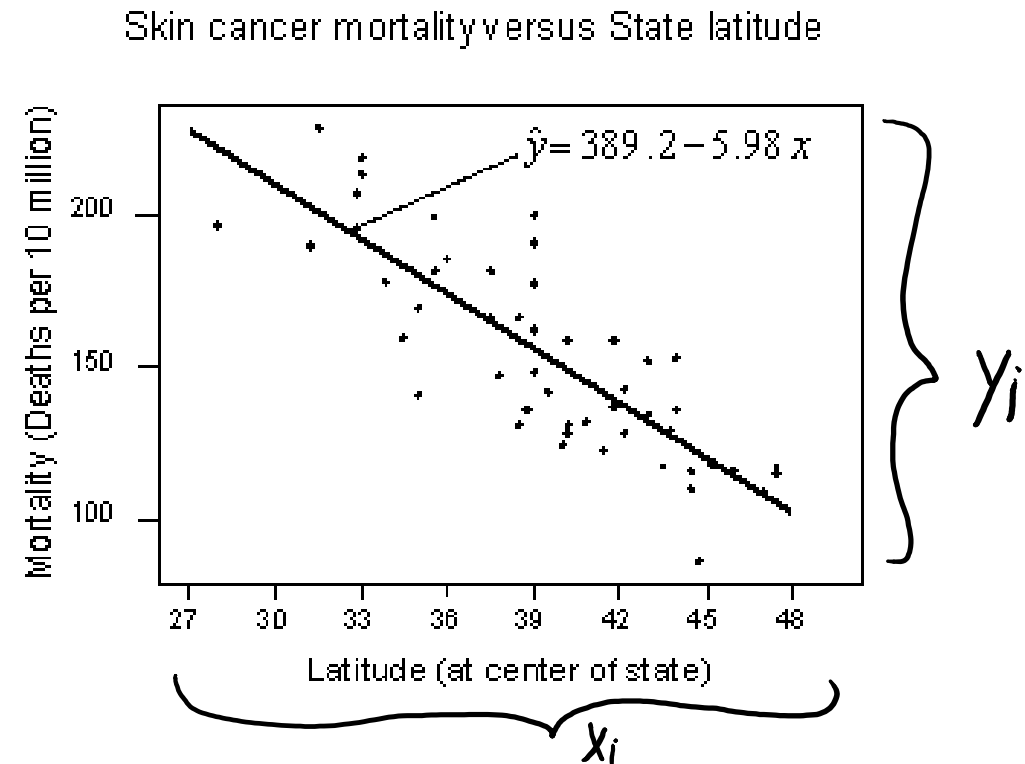
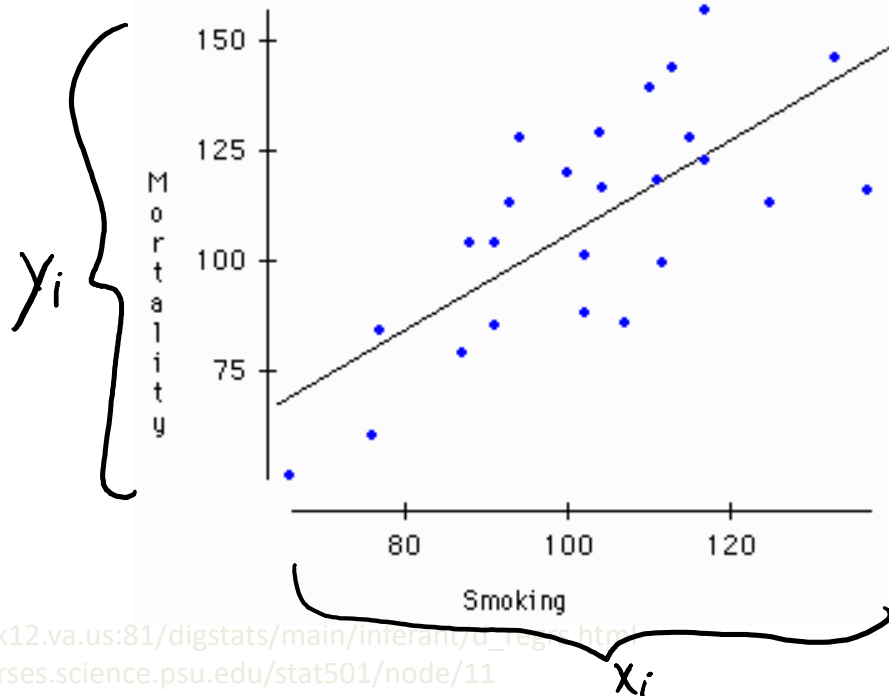
- We're going to revisit supervised learning:

$$X = \begin{bmatrix} \\ \\ \end{bmatrix} \quad y = \begin{bmatrix} \\ \\ \end{bmatrix}$$

- Previously, we considered classification:
 - We assumed y_i was discrete: $y_i = \text{'spam'}$ or $y_i = \text{'not spam'}$.
- Now we're going to consider regression:
 - We allow y_i to be numerical: $y_i = 10.34\text{cm}$.

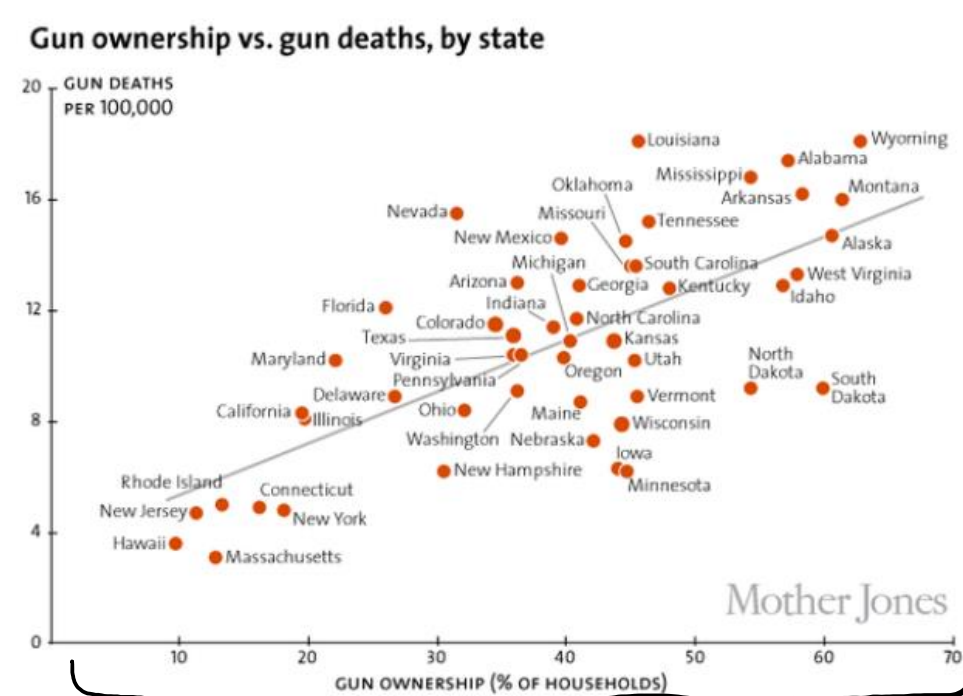
Example: Dependent vs. Explanatory Variables

- We want to discover relationship between numerical variables:
 - Does number of lung cancer deaths change with number of cigarettes?
 - Does number of skin cancer deaths change with latitude?



Example: Dependent vs. Explanatory Variables

- We want to discover relationship between numerical variables:
 - Does number of lung cancer deaths change with number of cigarettes?
 - Does number of skin cancer deaths change with latitude?
 - Does number of gun deaths change with gun ownership?



y_i

x_i

Handling Numerical Labels

- One way to handle numerical y_i : **discretize**.
 - E.g., for ‘age’ could we use {‘age ≤ 20 ’, ‘ $20 < \text{age} \leq 30$ ’, ‘age > 30 ’}.
 - Now we can apply methods for classification to do regression.
 - But **coarse discretization loses resolution**.
 - And **fine discretization requires lots of data**.
- We could make regression versions of classification methods:
 - Next time: regression trees, generative models, non-parametric models.
- Today: one of oldest, but still most popular/important methods:
 - **Linear regression based on squared error**.
 - Very interpretable and the building block for more-complex methods.

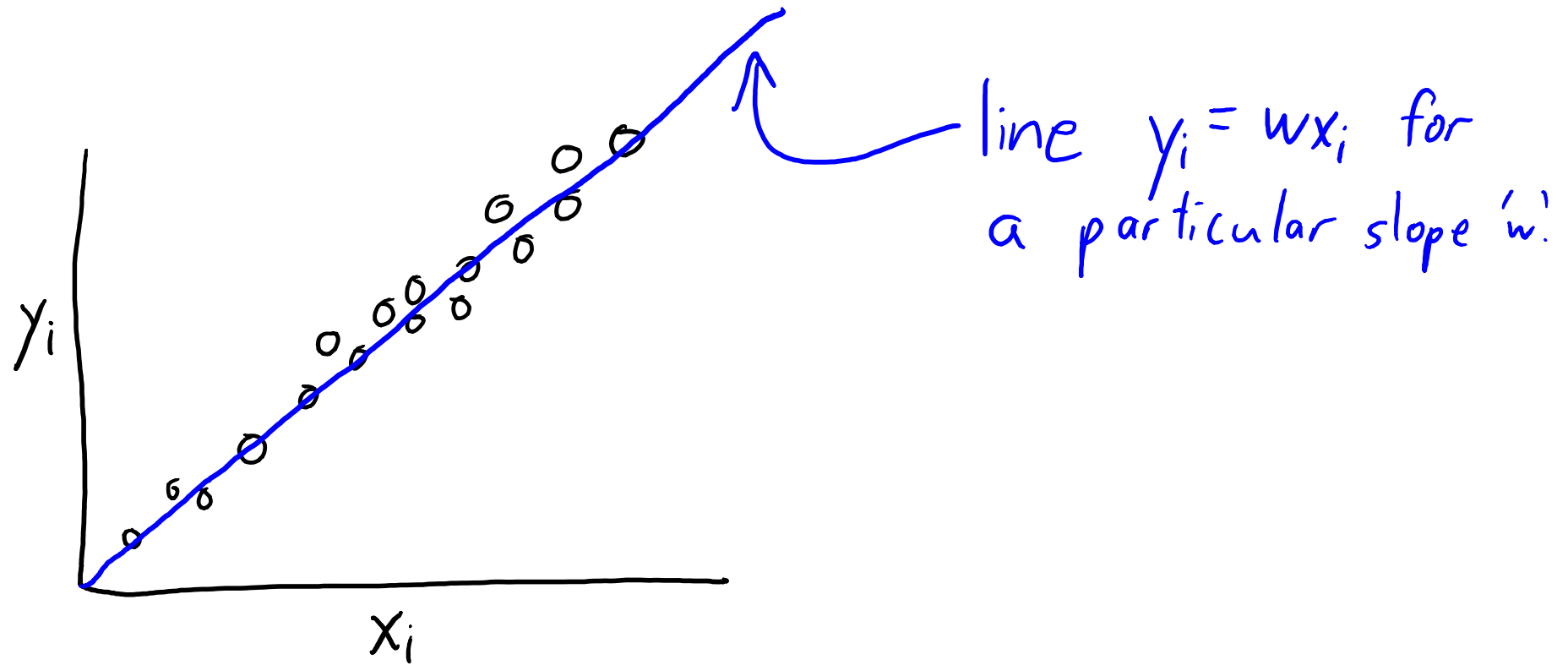
Linear Regression in 1 Dimension

- Assume we only have 1 feature ($d = 1$):
 - E.g., x_i is number of cigarettes and y_i is number of lung cancer deaths.
- **Linear regression** models y_i is a linear function of x_i :

$$y_i = w x_i$$

- The parameter 'w' is the **weight** or **regression coefficient** of x_i .
- As x_i changes, slope 'w' affects the rate that y_i increases/decreases:
 - Positive 'w': y_i increase as x_i increases.
 - Negative 'w': y_i decreases as x_i increases.

Linear Regression in 1 Dimension



Least Squares Objective

- Our **linear model** is given by:

$$y_i = w x_i$$

- So we make **predictions** for a new example by using:

$$\hat{y}_i = w \hat{x}_i$$

- But we **can't use the same error** as before:

- Even if data comes from a linear model but has noise,
we can have $\hat{y}_i \neq y_i$ for all training examples 'i' for the "best" model

Least Squares Objective

- We need a way to evaluate **numerical error**.
- Classic way to set slope 'w' is minimizing **sum of squared errors**:

$$f(w) = \sum_{i=1}^n (w x_i - y_i)^2$$

Annotations for the equation:

- Blue arrow from y_i to "True value of y_i "
- Blue arrow from $w x_i$ to "Our prediction of y_i "
- Green bracket under $(w x_i - y_i)$ with arrow to "Difference between prediction and true value for example 'i'"

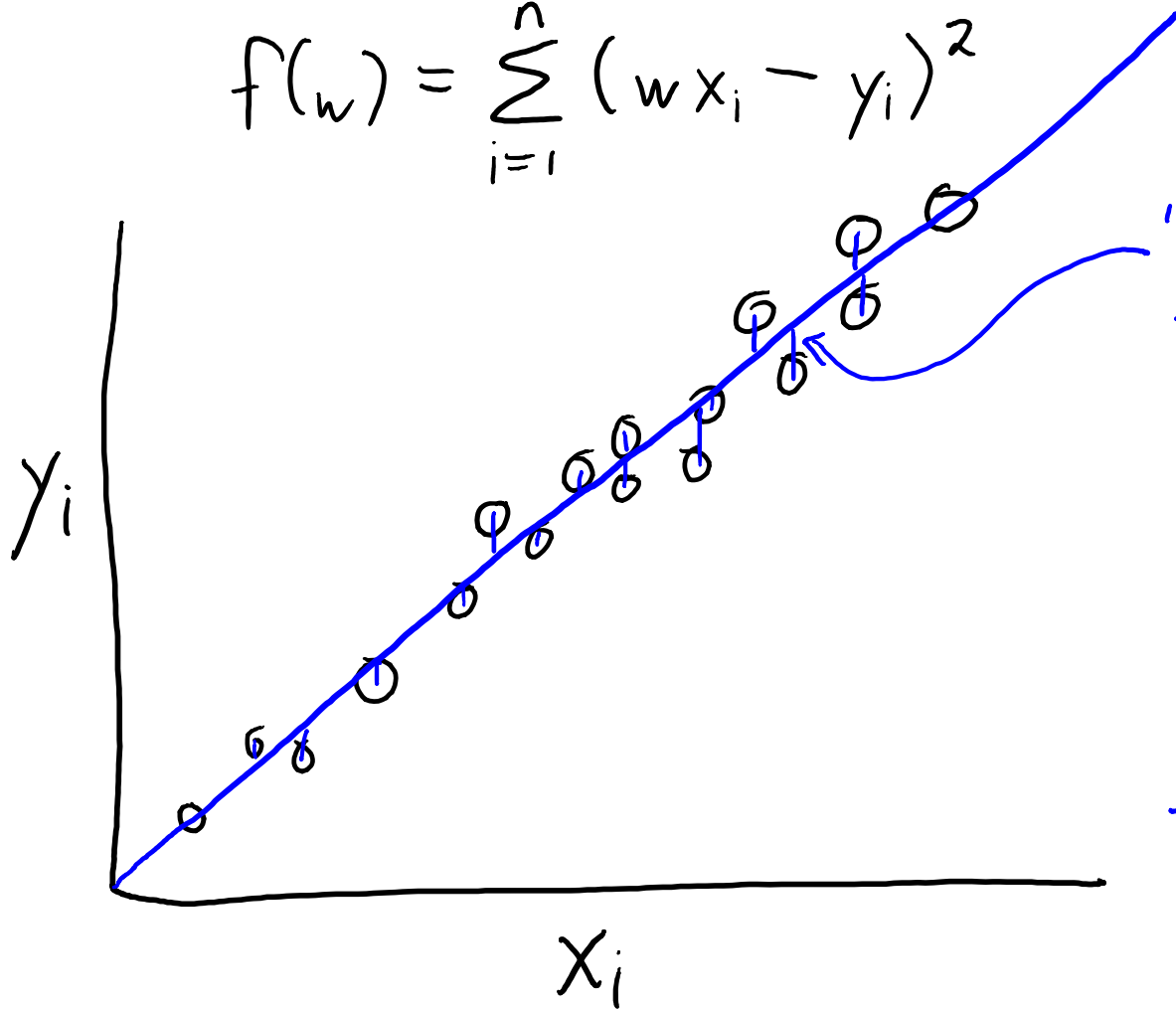
Sum up the squared differences over all training examples.

- There are some justifications for this choice.
 - Assuming errors are Gaussian or using 'central limit theorem'.
- But usually, it is done because **it is easy to compute**.

Least Squares Objective

- Classic way to set slope 'w' is minimizing **sum of squared errors**:

$$f(w) = \sum_{i=1}^n (wx_i - y_i)^2$$



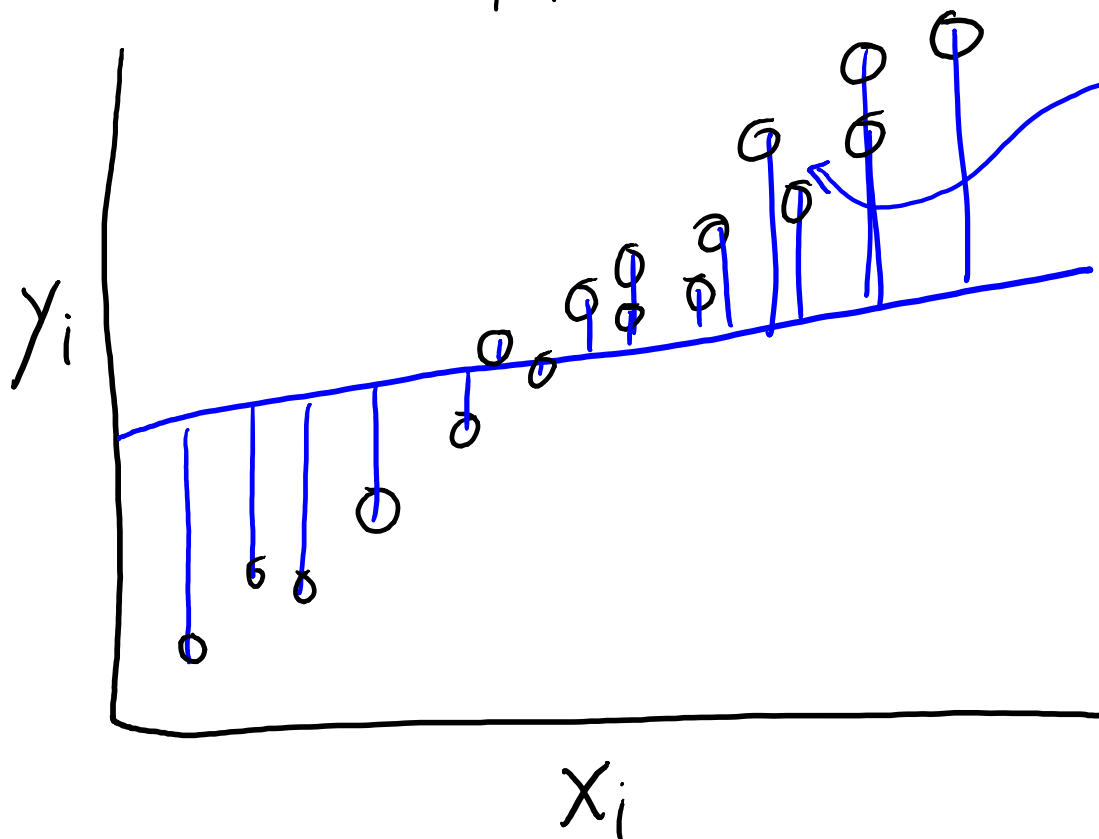
"Error" is the sum of the squared values of these vertical distances between the line ($w x_i$) and the targets (y_i)

↓
If this error is small, then our predictions are close to the targets.

Least Squares Objective

- Classic way to set slope 'w' is minimizing **sum of squared errors**:

$$f(w) = \sum_{i=1}^n (wx_i - y_i)^2$$

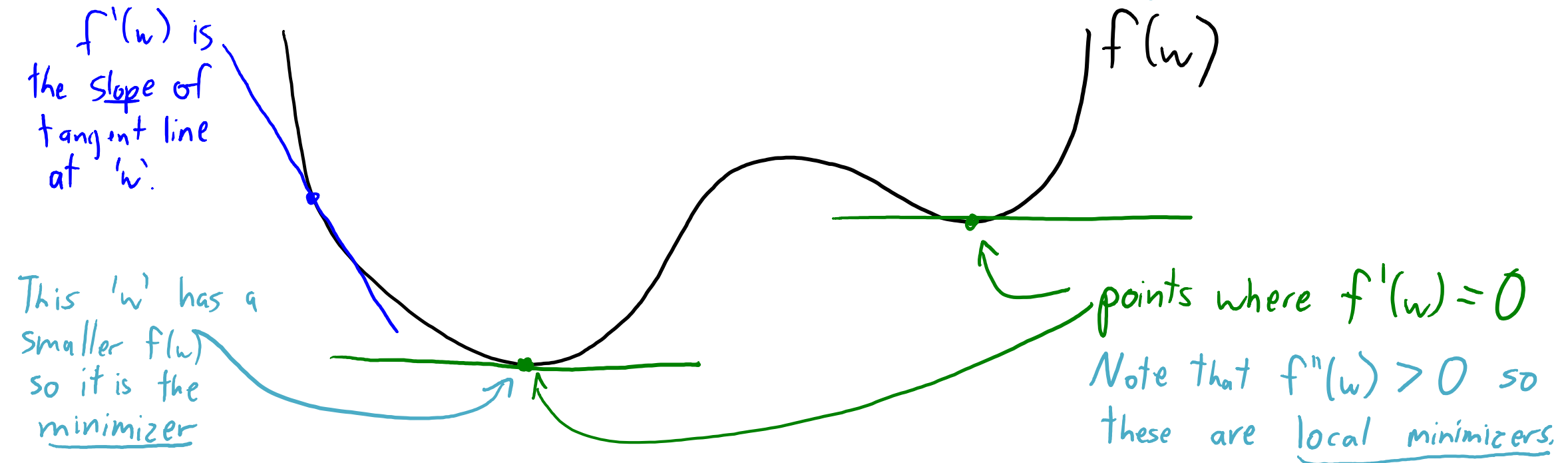


"Error" is the sum of the squared values of these vertical distances between the line ($w x_i$) and the targets (y_i)

↓
If this error is **large**, then our predictions are **far from** the targets.

Minimizing a Differential Function

- Math 101 approach to minimizing a differentiable function 'f':
 1. Take the derivative of 'f'.
 2. Find points 'w' where the derivative $f'(w)$ is equal to 0.
 3. Choose the smallest one (but check that $f''(w)$ is positive).



Finding Least Squares Solution

- Finding 'w' that minimizes **sum of squared errors**:

$$\frac{d}{dx} \left(\frac{1}{2} a x^2 \right) = a x$$

$$f(w) = \frac{1}{2} \sum_{i=1}^n (w x_i - y_i)^2 = \frac{1}{2} (w x_1 - y_1)^2 + \frac{1}{2} (w x_2 - y_2)^2 + \dots + \frac{1}{2} (w x_n - y_n)^2$$

$$f'(w) = \sum_{i=1}^n (w x_i - y_i) x_i = (w x_1 - y_1) x_1 + (w x_2 - y_2) x_2 + \dots + (w x_n - y_n) x_n$$

$$\text{Set } f'(w) = 0: \sum_{i=1}^n (w x_i - y_i) x_i = 0$$

$$\text{or } \sum_{i=1}^n [w x_i^2 - y_i x_i] = 0$$

$$\text{or } \sum_{i=1}^n w x_i^2 = \sum_{i=1}^n y_i x_i$$

$$\text{or } w \sum_{i=1}^n x_i^2 = \sum_{i=1}^n y_i x_i$$

$$\text{so } w = \frac{\sum_{i=1}^n y_i x_i}{\sum_{i=1}^n x_i^2}$$

Is this a minimizer?

$$f''(w) = \sum_{i=1}^n x_i^2$$

Since (anything)² is non-negative, $f''(w) \geq 0$.

If at least one $x_i \neq 0$ then $f''(w) > 0$ and this is a minimizer.

Motivation: Combining Explanatory Variables

- Smoking is **not the only contributor** to lung cancer.
 - For example, environmental factors like exposure to asbestos.
- How can we model the **combined effect** of smoking and asbestos?
- A simple way is with a **2-dimensional linear function**:

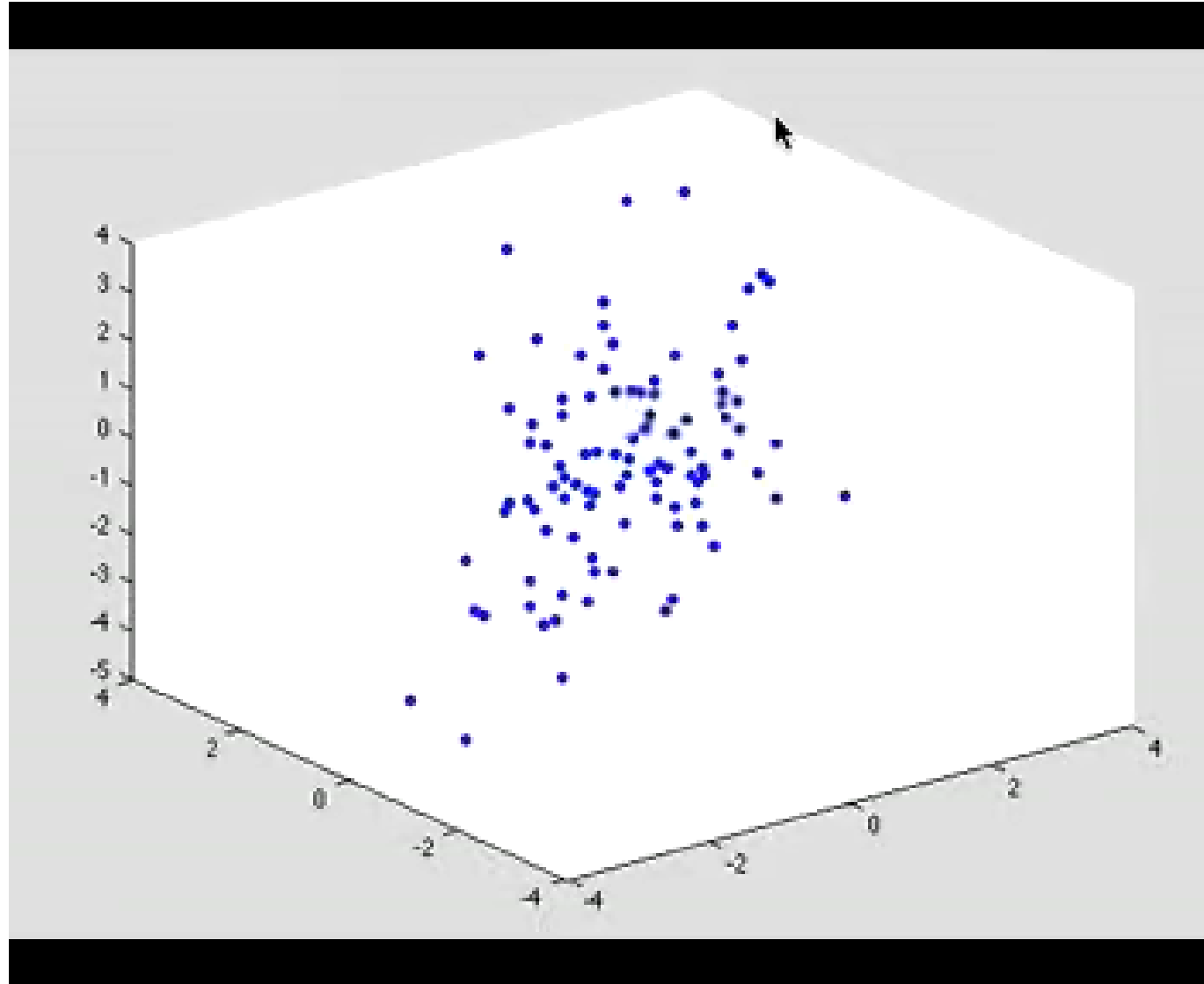
$$y_i = w_1 x_{i1} + w_2 x_{i2}$$

Handwritten annotations:

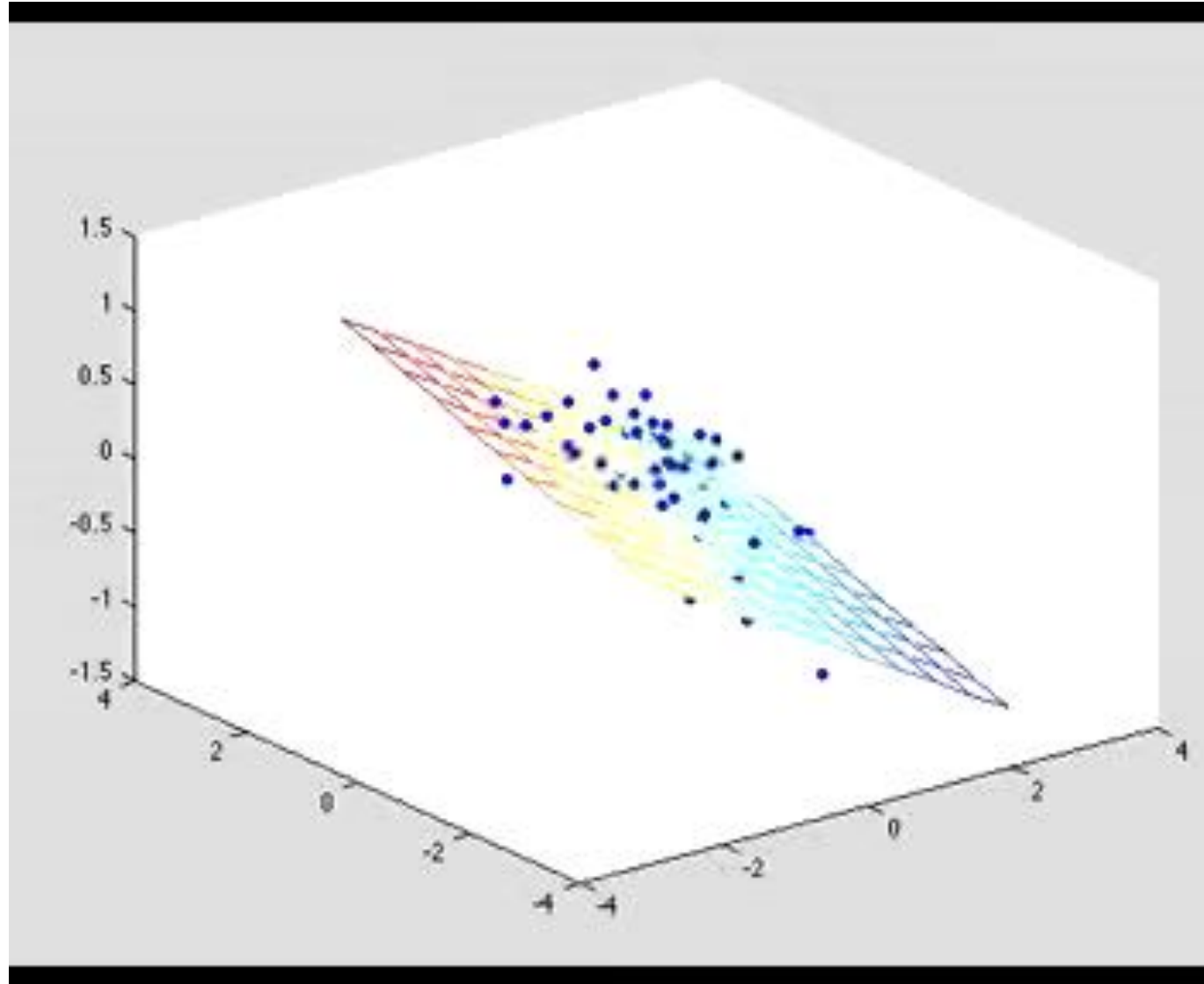
- w_1 : "weight" of feature 1
- x_{i1} : Value of feature 1 in example 'i'
- w_2 : "weight" on feature 2.
- x_{i2} : Value of feature 2 in example 'i'

- We have a weight w_1 for feature '1' and w_2 for feature '2'.

Least Squares in 2-Dimensions



Least Squares in 2-Dimensions



Least Squares in d-Dimensions

- If we have 'd' features, the **d-dimensional linear model** is:

$$y_i = w_1 x_{i1} + w_2 x_{i2} + w_3 x_{i3} + \dots + w_d x_{id}$$

- We can re-write this in **summation notation**:

$$y_i = \sum_{j=1}^d w_j x_{ij}$$

- We can also re-write this in **vector notation**:

$$y_i = \underbrace{w^T x_i}_{\substack{\text{"inner product"} \\ \text{between vectors}}} = \underbrace{[w_1 \ w_2 \ \dots \ w_d]}_{w^T} \underbrace{\begin{bmatrix} x_{i1} \\ x_{i2} \\ \vdots \\ x_{id} \end{bmatrix}}_{x_i} = \sum_{j=1}^d w_j x_{ij}$$

Weird Notation Alert

- In this course, all **vectors are assumed to be column-vectors**:

$$w = \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_d \end{bmatrix} \quad y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} \quad x_i = \begin{bmatrix} x_{i1} \\ x_{i2} \\ \vdots \\ x_{id} \end{bmatrix}$$

- So **$w^T x_i$ is a scalar**: $w^T x_i = [w_1 \quad w_2 \quad \dots \quad w_d] \begin{bmatrix} x_{i1} \\ x_{i2} \\ \vdots \\ x_{id} \end{bmatrix} = w_1 x_{i1} + w_2 x_{i2} + \dots + w_d x_{id} = \sum_{j=1}^d w_j x_{ij}$

- But our notation is weird: assume row 'i' of 'X' is elements of x_i .

– So **rows of 'X' are actually transpose of column-vector x_i** :

$$X = \begin{bmatrix} \text{---} & x_1^T & \text{---} \\ \text{---} & x_2^T & \text{---} \\ & \vdots & \\ \text{---} & x_n^T & \text{---} \end{bmatrix}$$

Least Squares in d-Dimensions

- The **linear least squares** model in d-dimensions minimizes:

$$f(w) = \frac{1}{2} \sum_{i=1}^n (w^T x_i - y_i)^2$$

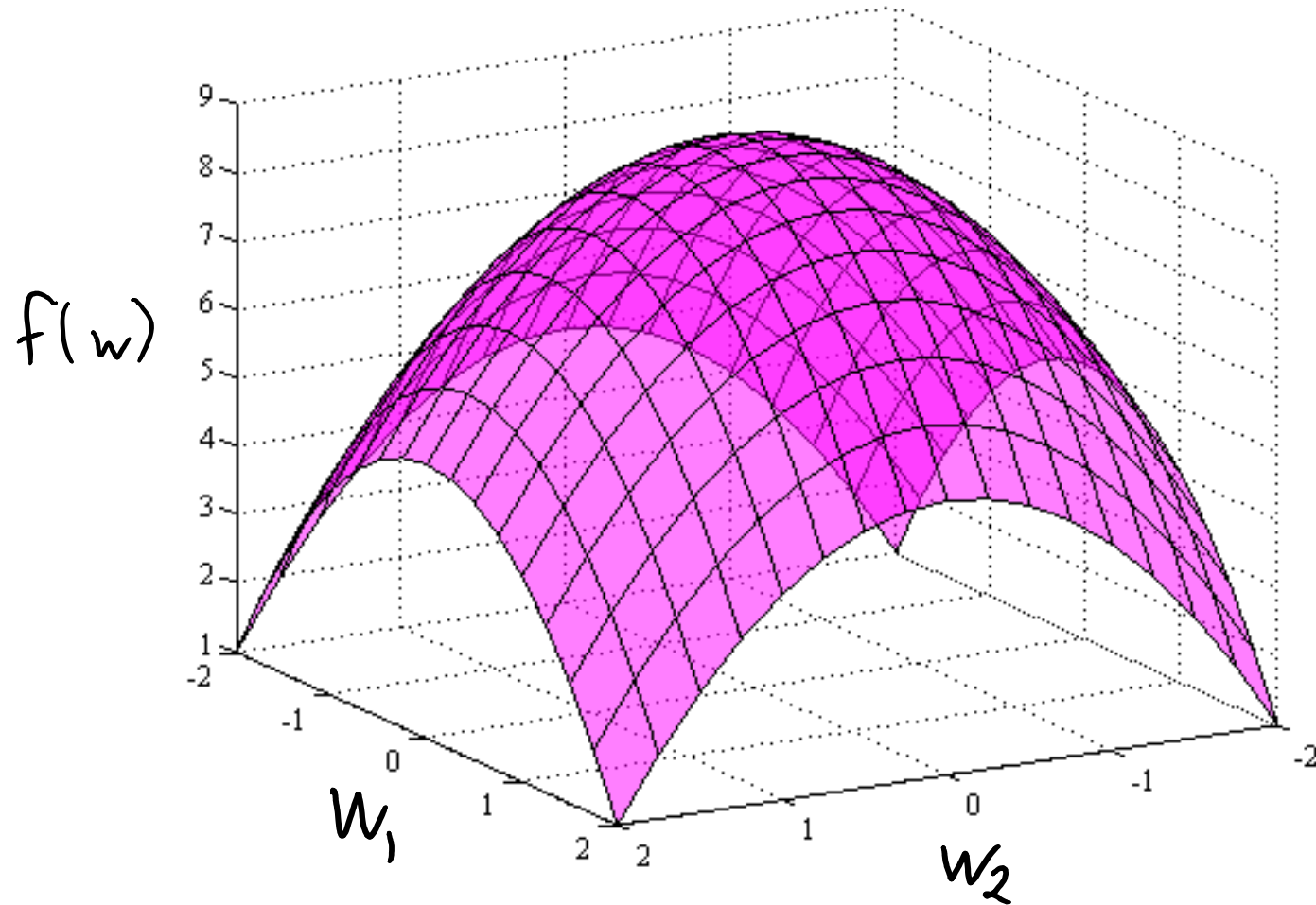
'w' is now a vector

*prediction is inner product of 'w' and 'x_i'
(linear combination of features)*

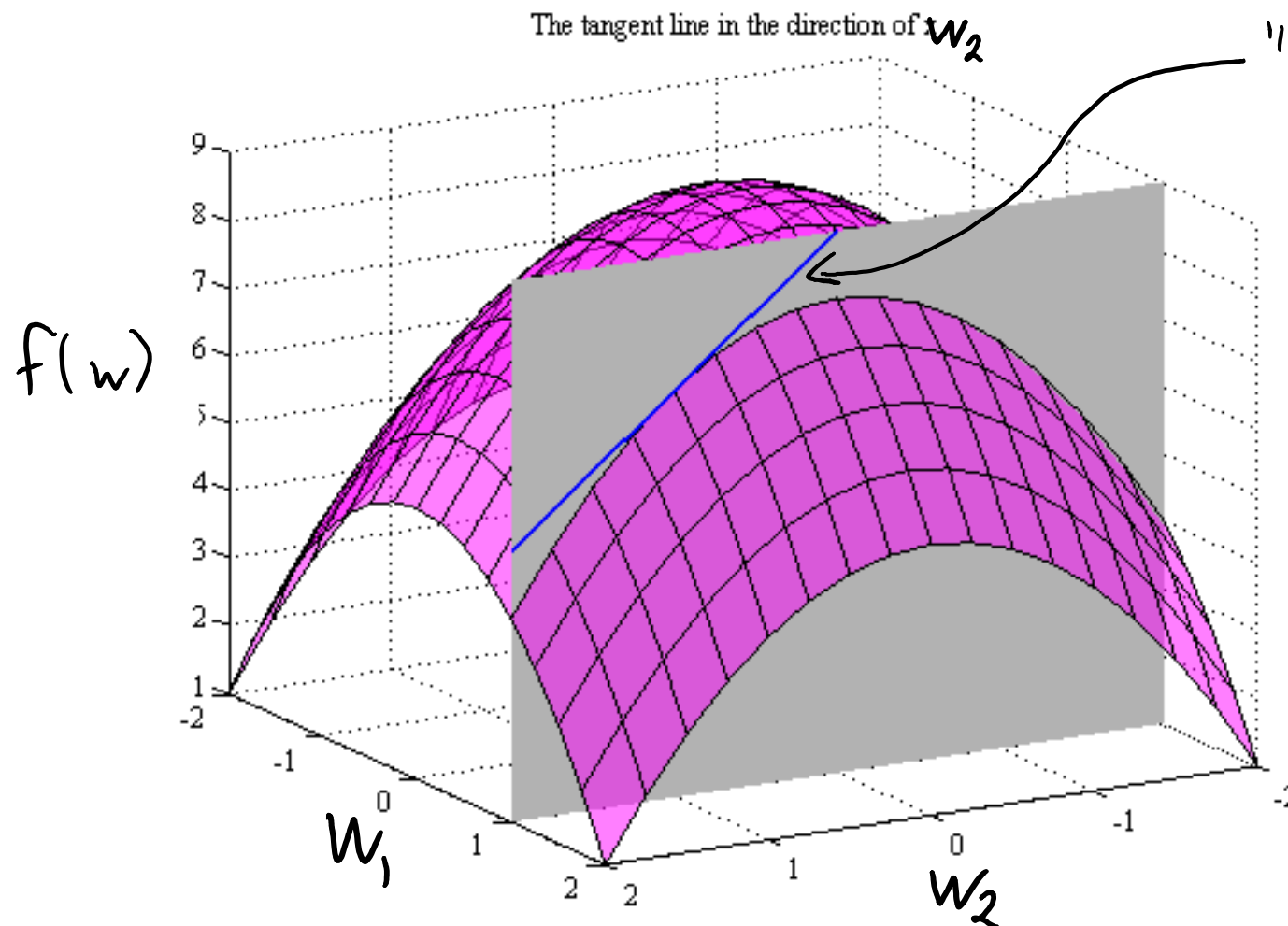
"Error" is still the sum of squared differences between "true" y_i and our "prediction" $w^T x_i$

- How do we find the **best vector** 'w'?
 - Set the derivative of each variable ("**partial derivative**") to 0?

Partial Derivatives



Partial Derivatives



"Partial" derivative of 'f' with respect to w_2 is the derivative with respect to w when all other variables are held fixed.

Denoted by $\frac{\partial}{\partial w_2}$ for variable w_2

Least Squares in d-Dimensions

- The **linear least squares** model in d-dimensions minimizes:

$$f(w) = \frac{1}{2} \sum_{i=1}^n (w^T x_i - y_i)^2$$

$$\begin{aligned} w^T x_i &= w_1 x_{i1} + w_2 x_{i2} + \dots + w_d x_{id} \\ \frac{d}{dw_1} [w^T x_i] &= x_{i1} + 0 + \dots + 0 \\ &= x_{i1} \end{aligned}$$

- Computing the **partial derivative**:

$$\begin{aligned} \frac{\partial}{\partial w_1} \left[\frac{1}{2} \sum_{i=1}^n (w^T x_i - y_i)^2 \right] &= \frac{1}{2} \sum_{i=1}^n \frac{\partial}{\partial w_1} \left[(w^T x_i - y_i)^2 \right] \\ &= \frac{1}{2} \sum_{i=1}^n 2 (w^T x_i - y_i) \frac{\partial}{\partial w_1} [w^T x_i] \end{aligned}$$

Problem: I can't just set to 0 and solve because it depends on w_2, w_3, \dots, w_d

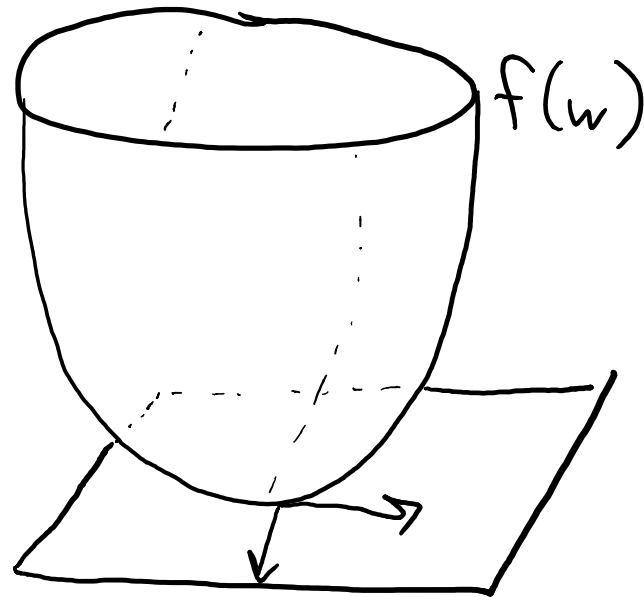
$$= \sum_{i=1}^n (w^T x_i - y_i) x_{i1}$$

What is the derivative of $w^T x_i$ with respect to w_1 ?

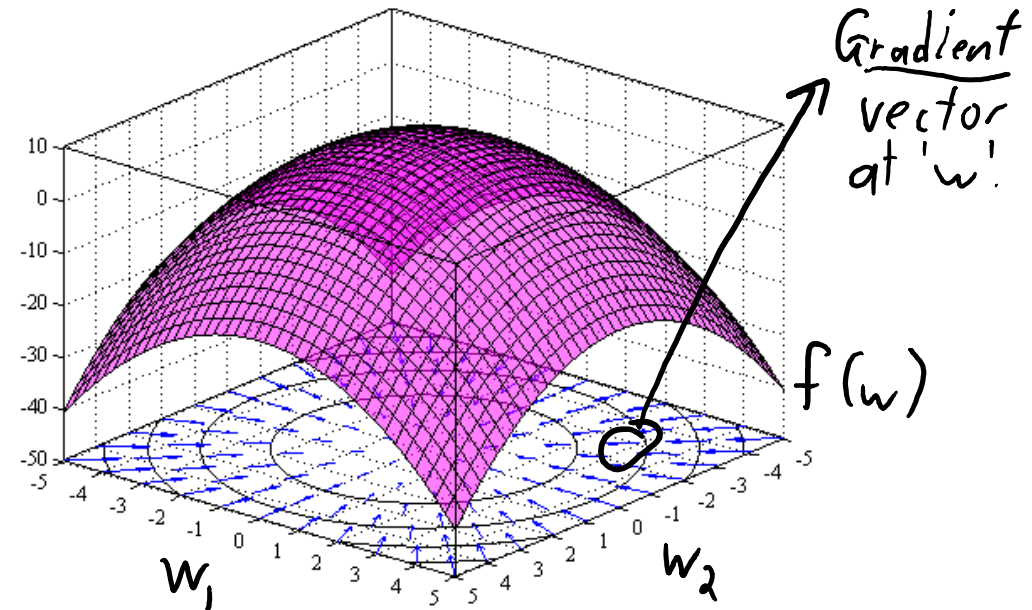
Gradient and Critical Points in d-Dimensions

- Generalizing “set the derivative to 0 and solve” in d-dimensions:
 - Find ‘w’ where the **gradient** vector **equals the zero vector**.
- **Gradient** is vector with partial derivative ‘j’ in position ‘j’:

$$\nabla f(w) = \begin{bmatrix} 2f \\ 2w_1 \\ 2f \\ 2w_2 \\ \vdots \\ 2f \\ 2w_d \end{bmatrix}$$



Tangent slope is 0 in every direction at minimizer.



Gradient and Critical Points in d-Dimensions

- Generalizing “set the derivative to 0 and solve” in d-dimensions:
 - Find ‘w’ where the **gradient** vector **equals the zero vector**.
- **Gradient** is vector with partial derivative ‘j’ in position ‘j’:

$$\nabla f(w) = \begin{bmatrix} \frac{\partial f}{\partial w_1} \\ \frac{\partial f}{\partial w_2} \\ \vdots \\ \frac{\partial f}{\partial w_d} \end{bmatrix}$$

For linear least squares:

$$\nabla f(w) = \begin{bmatrix} \sum_{i=1}^n (w^T x_i - y_i) x_{i1} \\ \sum_{i=1}^n (w^T x_i - y_i) x_{i2} \\ \vdots \\ \sum_{i=1}^n (w^T x_i - y_i) x_{id} \end{bmatrix}$$

Claims for linear least square:

1. Finding a ‘w’ where $\nabla f(w) = 0$ can be done by solving a system of linear equations.
2. All ‘w’ where $\nabla f(w) = 0$ are minimizers.

Summary

- **Regression** considers the case of a numerical y_i .
- **Least squares** is a classic method for fitting linear models.
 - With 1 feature, it has a simple closed-form solution.
- **Gradient** is vector containing partial derivatives of all variables.
- **Linear system of equations** gives least squares with 'd' features.

- Next time: *non-linear* regression.