

# CPSC 340 Tutorial

## Assignment 5 part 2

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Questions 3 to 5

# Multi-Dimensional Scaling (MDS)

The function *example\_MDS* loads the animals dataset and then shows (i) the raw data, (ii) the data projected onto the first two principal components, and (iii) the result of applying gradient descent to minimize the following multi-dimensional scaling (MDS) objective (starting from the PCA solution):

$$X \in \mathbb{R}^{n \times d} \quad \operatorname{argmin}_{Z \in \mathbb{R}^{n \times k}} \frac{1}{2} \sum_{i=1}^n \sum_{j=i+1}^n (\|x_i - x_j\| - \|z_i - z_j\|)^2. \quad (1)$$

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$x_i \in \mathbb{R}^d$                        $z_i \in \mathbb{R}^k$

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- Recall: principal component analysis (PCA) projects d-dimensional data points to a hyperplane orthogonal to the directions of maximal variance.

$$X \in \mathbb{R}^{n \times d}$$

$$SVD(X) = U, \Sigma, V^T$$

$$x_i \in \mathbb{R}^d$$

$$W = V_{(1:d, 1:k)}^T \xrightarrow{\text{Eigenvectors of (directional vectors)}} X^T X$$

$$z_i \in \mathbb{R}^k$$

Covariance matrix

$$Z = XW^T$$

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- Recall: principal component analysis (PCA) projects d-dimensional data points to a hyperplane orthogonal to the directions of maximal variance
- PCA preserves **covariance** between the data points

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- MDS projects data points to a space where similar data points are clustered together
- MDS preserves distances between points

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Optimizing for  $\mathbf{Z}$

$$\operatorname{argmin}_{\mathbf{Z} \in \mathbb{R}^{n \times k}} \frac{1}{2} \sum_{i=1}^n \sum_{j=i+1}^n (\|x_i - x_j\| - \|z_i - z_j\|)^2$$

Original distances but in d-dimensional space

Derives k-dimensional data points such that the original distances are preserved

- MDS preserves distances between points

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Original distances but in d-dimensional space

Derives k-dimensional data points such that the original distances are preserved

- We want  $\|x_i - x_j\| \approx \|z_i - z_j\| \quad \forall i, j$
- where, for example,

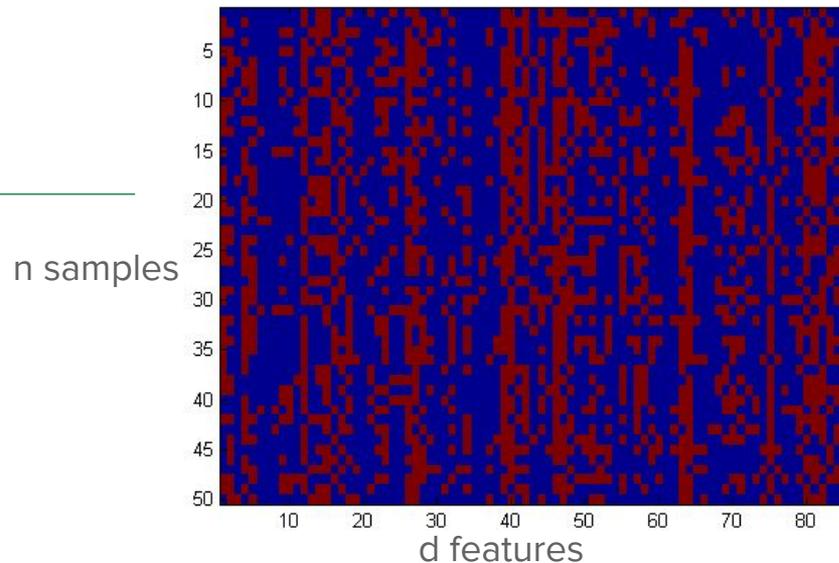
$$x_i \in R^{50} \quad z_i \in R^2$$

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1 load animals.mat
2 [n,d] = size(X);
3
4 % Figure 1 shows raw data
5 figure(1);
6 imagesc(X);
7
8 % Figure 2 shows PCA visualization
9 figure(2);clf;
10 [U,S,V] = svd(X);
11 W = V(:,1:2)';
12 Z = X*W';
13 figure(2);
14 plot(Z(:,1),Z(:,2),'.');
15 hold on;
16 for i = 1:n
17     text(Z(i,1),Z(i,2),animals(i,:));
18 end
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20 % Figure 3 shows MDS visualization
21 z = visualizeMDS(X,2,animals);
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exampleMDS.m file

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Figure 1 - Displays matrix X



X consists of values 0 and 1

blue is 0; red is 1

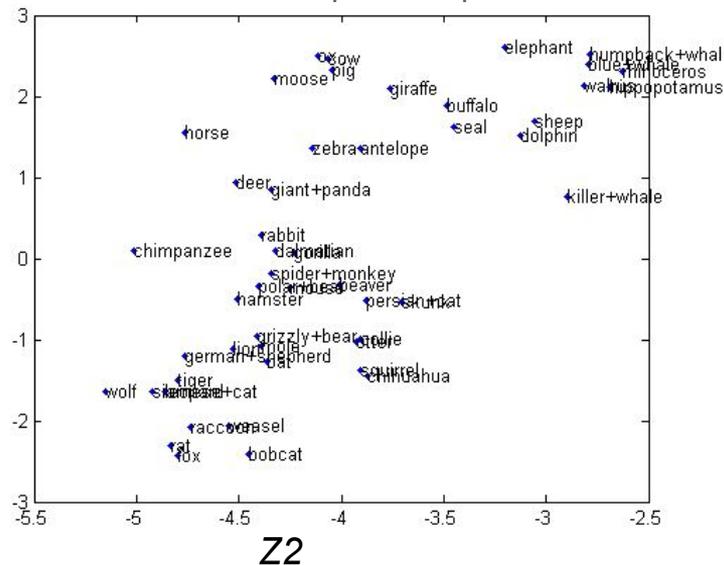
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Z1

Figure 2 - Displays the projection of X onto the first two Principal components



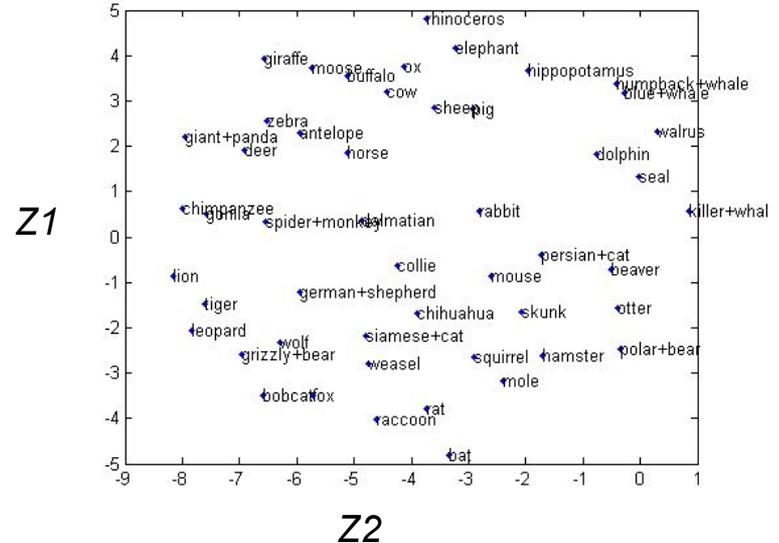
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Figure 3 - Displays the datasets in terms of the two latent features obtained from MDS



$$X(i) = [Z_{i1}, Z_{i2}]$$

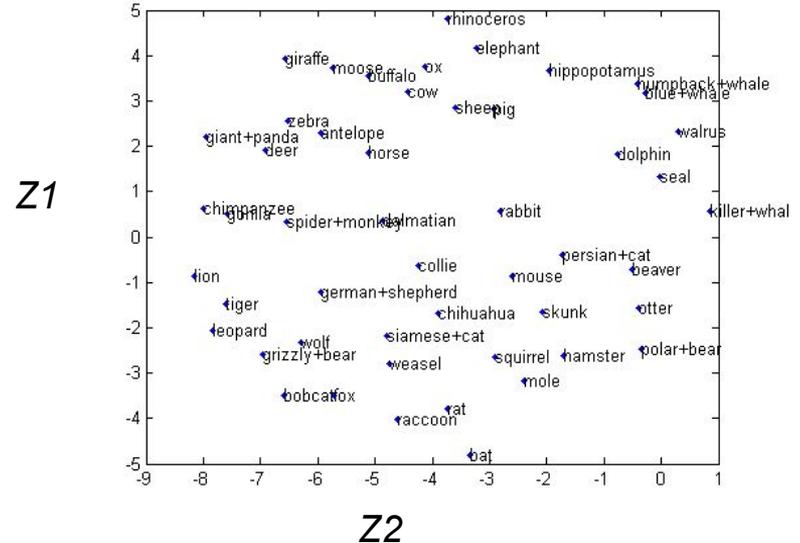
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$$X(i) = [Z_{i1}, Z_{i2}]$$

```
function [Z] = visualizeMDS(X,k,names)

[n,d] = size(X);

% Compute all distances
D = X.^2*ones(d,n) + ones(n,d)*(X').^2 - 2*X*X';
D = sqrt(abs(D));

% Initialize low-dimensional representation with PCA
[U,S,V] = svd(X);
W = V(:,1:k)';
Z = X*W';

Z(:) = findMin(@stress,Z(:),500,0,D,names);

end
```

Computes the distances between each pair of samples  $D(i,j) = \|x_i - x_j\|^2$

Initializes Z using PCA

MDS

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23 Z = reshape(Z,[n k]);
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25 f = 0;
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28     for j = i+1:n
29         % Objective Function
30         Dz = norm(Z(i,:)-Z(j,:));
31         s = D(i,j) - Dz;
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$$f(Z) = \frac{1}{2} \sum_{i=1}^n \sum_{j=i+1}^n (\|x_i - x_j\| - \|z_i - z_j\|)^2$$

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MDS gradient w.r.t  $z_i$  and  $z_j$

$$s = \sum_{i=1}^n \sum_{j=i+1}^n (\|x_i - x_j\| - \|z_i - z_j\|)$$

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Derivative

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MDS function value

$$f(Z) = \frac{1}{2} \sum_{i=1}^n \sum_{j=i+1}^n (\|x_i - x_j\| - \|z_i - z_j\|)^2$$

MDS gradient w.r.t  $z_i$  and  $z_j$

$$s = \sum_{i=1}^n \sum_{j=i+1}^n (\|x_i - x_j\| - \|z_i - z_j\|)$$

$$s_{ij} = \|x_i - x_j\| - \|z_i - z_j\| = \sqrt{(x_i - x_j)^2} - \sqrt{(z_i - z_j)^2}$$

$$f(Z) = \sum_{i=1}^n \sum_{j=i+1}^n \left(\frac{1}{2} s_{ij}^2\right)$$

Derivative

$$\frac{\partial f_{ij}}{\partial z_i} = \frac{\partial f_{ij}}{\partial s_{ij}} \frac{\partial s_{ij}}{\partial z_i}$$

$$\frac{\partial f_{ij}}{\partial s_{ij}} = \frac{\partial(\frac{1}{2} s_{ij}^2)}{\partial s_{ij}} = s_{ij}$$

$$\frac{\partial s_{ij}}{\partial z_i} = \frac{\partial(\sqrt{(x_i - x_j)^2} - \sqrt{(z_i - z_j)^2})}{\partial z_i} = -\frac{z_i - z_j}{\sqrt{(z_i - z_j)^2}}$$

```

18 function [f,g] = stress(Z,D,names)
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## Question 3.1: *visualizeSammon*

Make new function *visualizeSammon* that implements gradient descent for MDS Sammon mapping objective,

Sammon's mapping objective function

$$\operatorname{argmin}_{Z \in \mathbb{R}^{n \times k}} \frac{1}{2} \sum_{i=1}^n \sum_{j=i+1}^n \frac{(\|x_i - x_j\| - \|z_i - z_j\|)^2}{\|x_i - x_j\|}.$$

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Recall:  $D(i, j) = \|x_i - x_j\|$

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Make changes here

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$s_{ij} = ?$

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$$s_{ij} = ?$$

MDS gradient function

$$f(Z) = \frac{1}{2} \sum_{i=1}^n \sum_{j=i+1}^n (\|x_i - x_j\| - \|z_i - z_j\|)^2$$

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$s_{ij} = ?$

$$\frac{\partial f}{\partial z_i} = \frac{\partial f}{\partial s} \frac{\partial s}{\partial z_i} = ?$$

Make changes here

MDS gradient function

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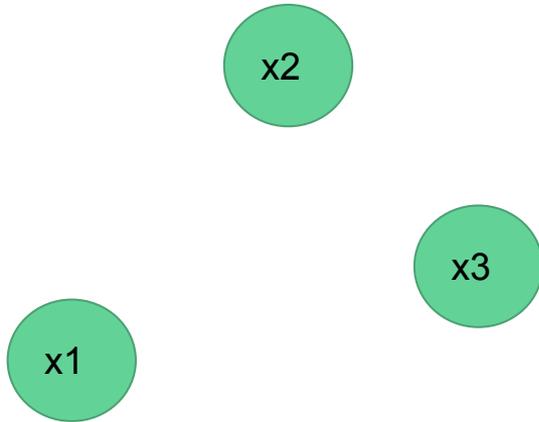
## Question 3.2: ISOMAP

This suggests that ISOMAP may give a better visualization. Make a new function *visualizeISOMAP* that computes the approximate geodesic distance (shortest path through a graph where the edges are only between  $k$ -nearest neighbours, and the edge weights are the distances between these neighbours) between each pair of points, and then fits a standard MDS model (1) using gradient descent. [Hand in your code and the plot of the result when using the 3-nearest neighbours.](#)

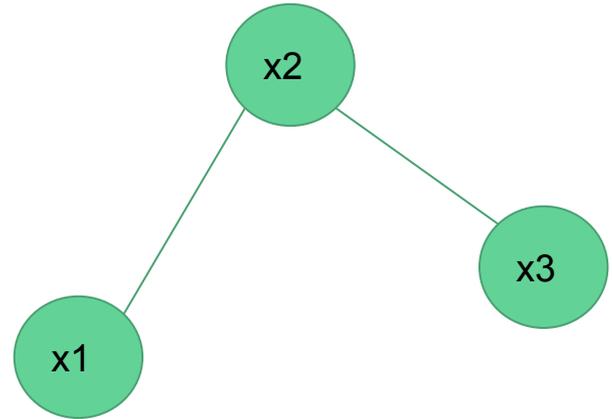
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Multi-dimensional scaling

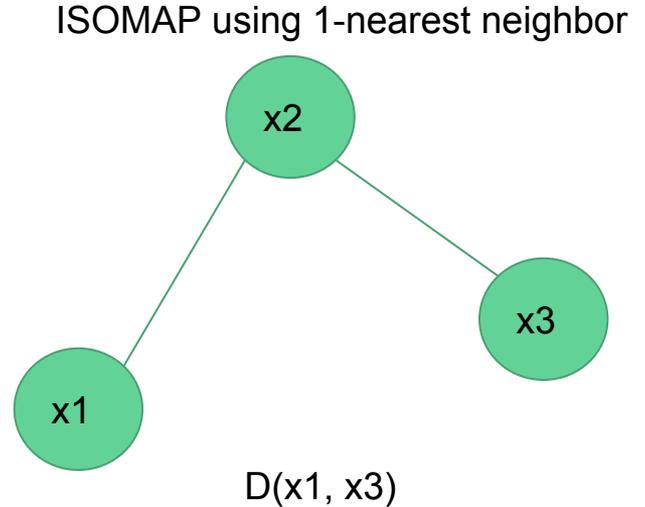
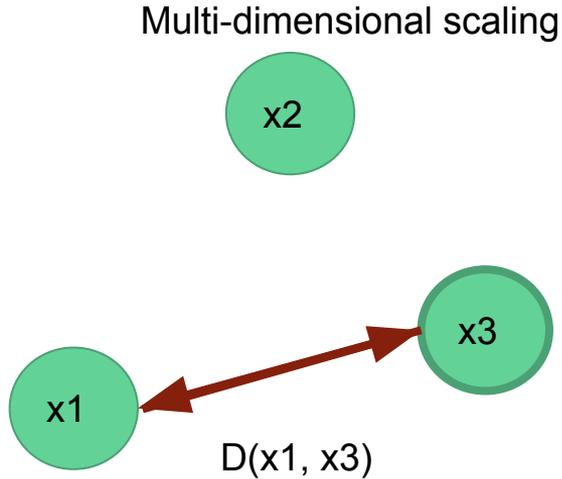


ISOMAP using 1-nearest neighbor



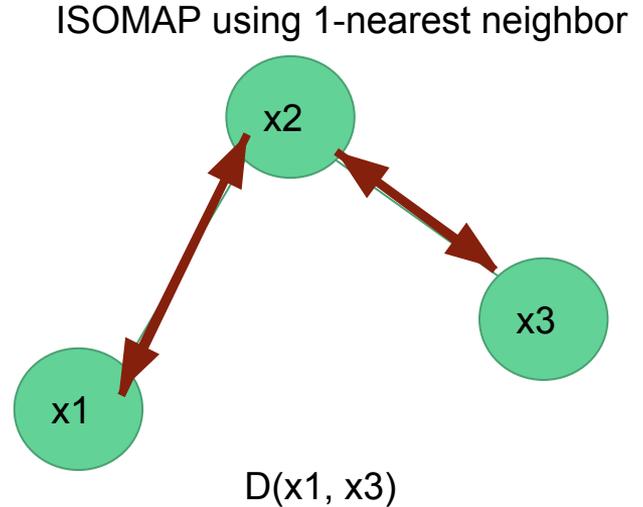
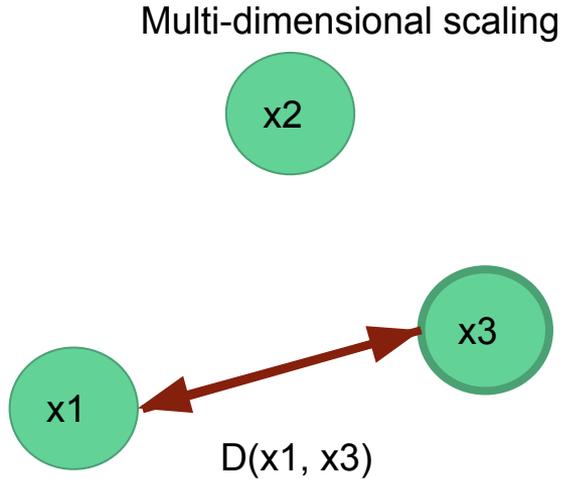
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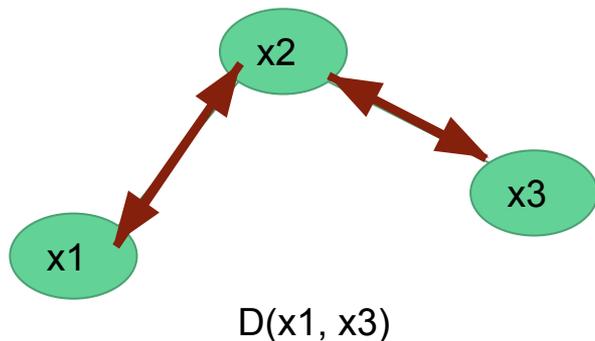
- If  $x$  is  $d$ -dimensional,
  - then ISOMAP with  $n$ -nearest neighbor is MDS
  - Otherwise the only difference is in the distance function

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ISOMAP: Make changes here

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2
3 [n,d] = size(X);
4
5 % Compute all distances
6 D = X.^2*ones(d,n) + ones(n,d)*(X').^2 - 2*X*X';
7 D = sqrt(abs(D));
8
9 % Initialize low-dimensional representation with PCA
10 [U,S,V] = svd(X);
11 W = V(:,1:k)';
12 Z = X*W';
13
14 Z(:) = findMin(@stress,Z(:),500,0,D, names);
```

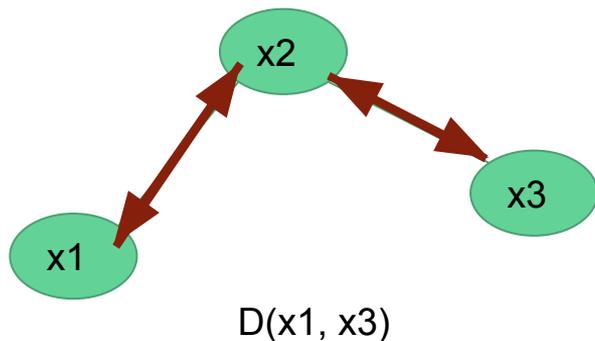
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#### ISOMAP:

- 1) Find  $k$ -nearest neighbors  
The ' $k$ ' points that are closest to each data point (see KNN)

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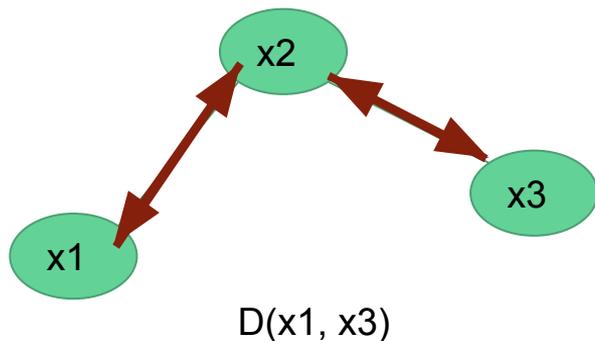
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### ISOMAP:

- 2) Create  $n \times n$  zero matrix  $G$   
 (the adjacency graph)  
 s.t.

$$G(i, j) = \begin{cases} D(i, j) & \text{if } j \in \text{neighbors}(i) \\ 0 & \text{otherwise} \end{cases}$$



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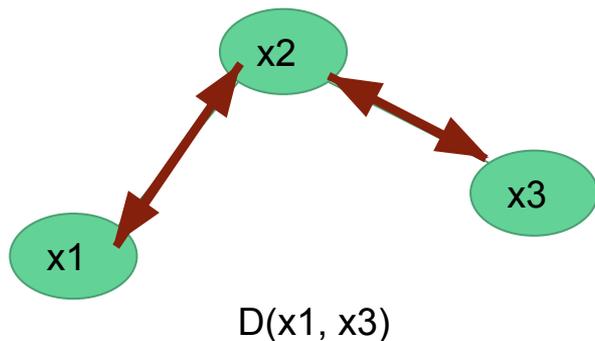
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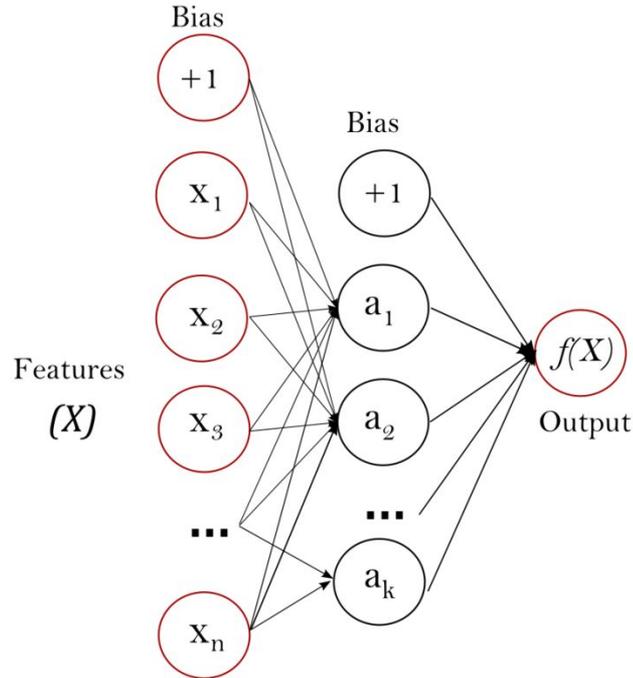
$$D(i, j) = \text{dijkstra}(G, i, j)$$

Update the distance matrix

The adjacency matrix

# Q4: Visualizing a neural net for 1D regression

the data very well. Try to improve the performance of the method by changing the structure of the network ( $nHidden$  is a vector giving the number of hidden units in each layer) and the training procedure (e.g., change the sequence of step sizes, add momentum, or use *findMin* from the previous assignment). **Hand in your plot after changing the code to have better performance, and list the changes you made.**



```

load nnetData.mat % Loads data {X,y}
[N,d] = size(X);

% Add bias
X = [ones(N,1) X];
d = d + 1;

% Choose network structure
nHidden = [3];

% Count number of parameters and initialize weights 'w'
nParams = d*nHidden(1);
for h = 2:length(nHidden)
    nParams = nParams+nHidden(h-1)*nHidden(h);
end
nParams = nParams+nHidden(end);
w = randn(nParams,1);

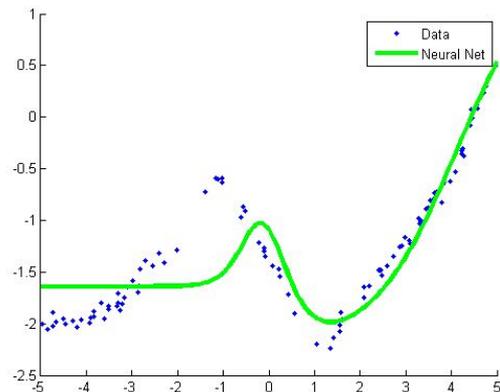
% Train with stochastic gradient
maxIter = 100000;
stepSize = 1e-4;
funObj = @(w,i)MLPregressionLoss(w,X(i,:),y(i),nHidden);
for t = 1:maxIter

    % Every few iterations, plot the data/model:
    if mod(t-1,round(maxIter/100)) == 0
        fprintf('Training iteration = %d\n',t-1);
        figure(1);clf;hold on
        Xhat = [-5:.05:5]';
        Xhat = [ones(size(Xhat,1),1) Xhat];
        yhat = MLPregressionPredict(w,Xhat,nHidden);
        plot(X(:,2),y, '.');
        h=plot(Xhat(:,2),yhat, 'g-');
        set(h, 'LineWidth', 3);
        legend({'Data', 'Neural Net'});
        drawnow;
    end

    % The actual stochastic gradient algorithm:
    i = ceil(rand*N);
    [f,g] = funObj(w,i);
    w = w - stepSize*g;
end

```

## Original performance



```

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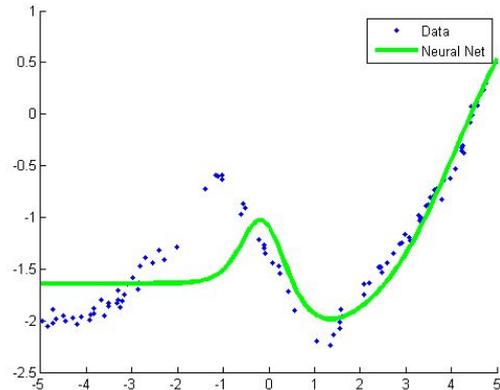
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        figure(1);clf;hold on
        Xhat = [-5:.05:5]';
        Xhat = [ones(size(Xhat,1),1) Xhat];
        yhat = MLPregressionPredict(w,Xhat,nHidden);
        plot(X(:,2),y, '.');
        h=plot(Xhat(:,2),yhat, 'g-');
        set(h, 'LineWidth', 3);
        legend({'Data', 'Neural Net'});
        drawnow;
    end

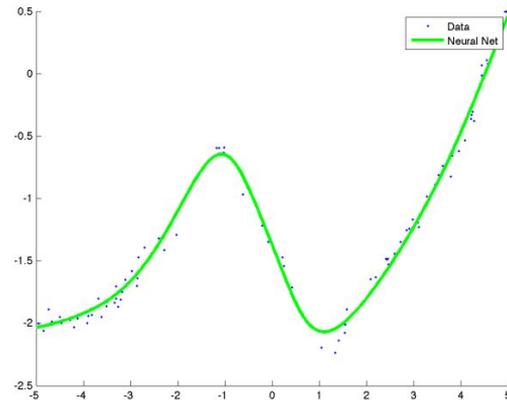
    % The actual stochastic gradient algorithm:
    i = ceil(rand*N);
    [f,g] = funObj(w,i);
    w = w - stepSize*g;
end

```

## Original performance



## Target performance



```

load nnetData.mat % Loads data {X,y}
[N,d] = size(X);

% Add bias
X = [ones(N,1) X];
d = d + 1;

% Choose network structure
nHidden = [3];

% Count number of parameters and initialize weights 'w'
nParams = d*nHidden(1);
for h = 2:length(nHidden)
    nParams = nParams+nHidden(h-1)*nHidden(h);
end
nParams = nParams+nHidden(end);
w = randn(nParams,1);

% Train with stochastic gradient
maxIter = 100000;
stepSize = 1e-4;
funObj = @(w,i)MLPRegressionLoss(w,X(i,:),y(i),nHidden);
for t = 1:maxIter

    % Every few iterations, plot the data/model:
    if mod(t-1,round(maxIter/100)) == 0
        fprintf('Training iteration = %d\n',t-1);
        figure(1);clf;hold on
        Xhat = [-5:.05:5]';
        Xhat = [ones(size(Xhat,1),1) Xhat];
        yhat = MLPRegressionPredict(w,Xhat,nHidden);
        plot(X(:,2),y, '.');
        h=plot(Xhat(:,2),yhat, 'g-');
        set(h, 'LineWidth', 3);
        legend({'Data', 'Neural Net'});
        drawnow;
    end

    % The actual stochastic gradient algorithm:
    i = ceil(rand*N);
    [f,g] = funObj(w,i);
    w = w - stepSize*g;
end

```

## Improve the performance of your neural network

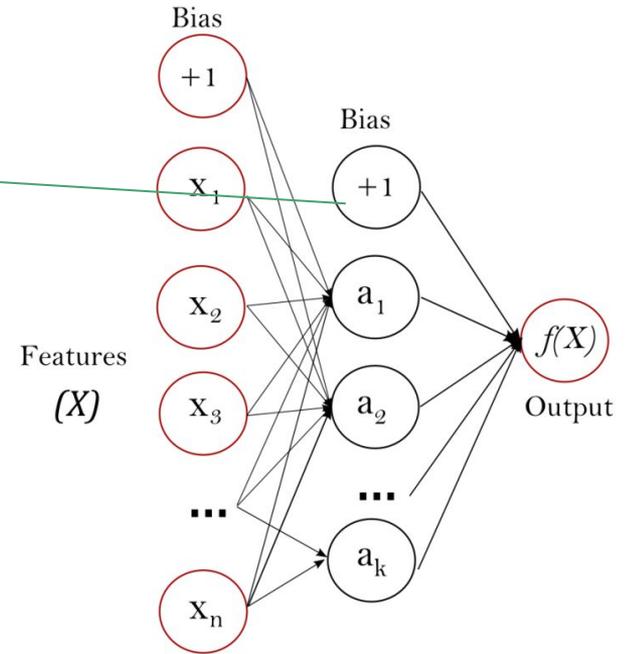
Number of hidden neurons

nParams: the total number of variables

The size of the step to take when updating 'w'

t: the epoch number

i: the index of the next sample 'x' to be chosen  
g: the gradient of that sample with respect to 'w'



```

load nnetData.mat % Loads data {X,y}
[N,d] = size(X);

% Add bias
X = [ones(N,1) X];
d = d + 1;

% Choose network structure
nHidden = [3];

% Count number of parameters and initialize weights 'w'
nParams = d*nHidden(1);
for h = 2:length(nHidden)
    nParams = nParams+nHidden(h-1)*nHidden(h);
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nParams = nParams+nHidden(end);
w = randn(nParams,1);

% Train with stochastic gradient
maxIter = 100000;
stepSize = 1e-4;
funObj = @(w,i)MLPrepgressionLoss(w,X(i,:),y(i),nHidden);
for t = 1:maxIter

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        plot(X(:,2),y, '.');
        h=plot(Xhat(:,2),yhat, 'g-');
        set(h, 'LineWidth', 3);
        legend({'Data', 'Neural Net'});
        drawnow;
    end

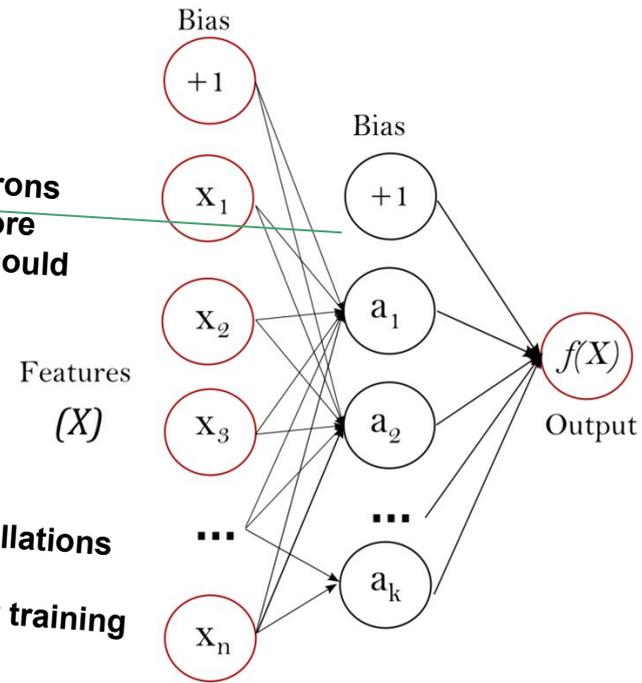
    % The actual stochastic gradient algorithm:
    i = ceil(rand*N);
    [f,g] = funObj(w,i);
    w = w - stepSize*g;
end

```

## Improve the performance of your neural network

Adjust the number of hidden neurons  
(the more hidden neurons, the more powerful your model will be, but could cause overfitting)

- Adjust the step size
- Large step size can cause oscillations in your function value
- Small step size can cause slow training



```

load nnetData.mat % Loads data {X,y}
[N,d] = size(X);

% Add bias
X = [ones(N,1) X];
d = d + 1;

% Choose network structure
nHidden = [3];

% Count number of parameters and initialize weights 'w'
nParams = d*nHidden(1);
for h = 2:length(nHidden)
    nParams = nParams+nHidden(h-1)*nHidden(h);
end
nParams = nParams+nHidden(end);
w = randn(nParams,1);

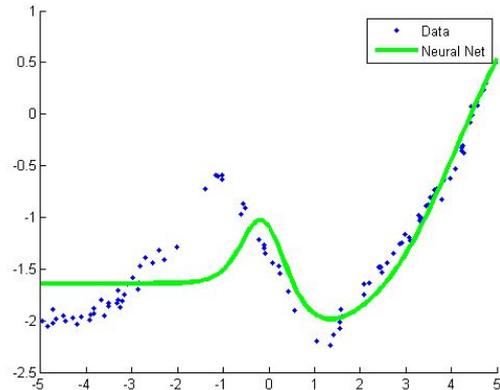
% Train with stochastic gradient
maxIter = 100000;
stepSize = 1e-4;
funObj = @(w,i)MLPregressionLoss(w,X(i,:),y(i),nHidden);
for t = 1:maxIter

% Every few iterations, plot the data/model:
if mod(t-1,round(maxIter/100)) == 0
    fprintf('Training iteration = %d\n',t-1);
    figure(1);clf;hold on
    Xhat = [-5:.05:5]';
    Xhat = [ones(size(Xhat,1),1) Xhat];
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    plot(X(:,2),y, '.');
    h=plot(Xhat(:,2),yhat, 'g-');
    set(h, 'LineWidth', 3);
    legend({'Data', 'Neural Net'});
    drawnow;
end

% The actual stochastic gradient algorithm:
i = ceil(rand*N);
[f,g] = funObj(w,i);
w = w - stepSize*g;
end

```

## Original performance



## Target performance

