Notes

 In assignment 1, problem 2: smoothness = number of times differentiable

The Symmetric Eigenproblem

- Assume A is symmetric and real
- Find orthogonal matrix V and diagonal matrix D s.t. AV=VD
 - Diagonal entries of D are the eigenvalues, corresponding columns of V are the eigenvectors
- ♦ Also put: A=VDV^T or V^TAV=D
- There are a few strategies
 - More if you only care about a few eigenpairs, not the complete set...
- Also: finding eigenvalues of an nxn matrix is equivalent to solving a degree n polynomial
 - No "analytic" solution in general for n≥5
 - Thus general algorithms are iterative

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The Jacobi Algorithm

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- One of the oldest numerical methods, but still of interest
- ◆ Start with initial guess at V (e.g. V=I), set A=V^TAV
- ◆ For k=1, 2, ...
 - If A is close enough to diagonal (Frobenius norm of off-diagonal tiny relative to A) stop
 - Find a Givens rotation Q that solves a 2x2 subproblem
 Either zeroing max off-diagonal entry, or sweeping in order
 - V=VQ, A=Q^TAQ
 - $\nabla = \nabla Q$, $A = Q \cdot AQ$
- Typically O(log n) sweeps, O(n²) rotations each
- Quadratic convergence in the limit
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The Power Method

- Start with some random vector v, llvll₂=1
- Iterate v=(Av)/IIAvII
- What happens? How fast?

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Shift and Invert (Rayleigh Iteration)

- \blacklozenge Say we know the eigenvalue we want is approximately λ_{k}
- $_{\upsilon}$ The matrix (A- $\lambda_{k}I)^{-1}$ has the same eigenvectors as A $_{1}$
- υ But the eigenvalues are $\mu = \frac{1}{\lambda \lambda_k}$
- υ Use this in the power method instead
- υ Even better, update guess at eigenvalue each iteration: $λ_{k+1} = v_{k+1}^T A v_{k+1}$
- Θ Gives cubic convergence! (triples the number of significant digits each iteration when converging)
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Maximality and Orthogonality

 Unit eigenvectors v₁ of the maximum magnitude eigenvalue satisfy

$$Av_1\|_2 = \max_{\|u\|=1} \|Au\|_2$$

• Unit eigenvectors v_k of the k'th eigenvalue satisfy $\|Av_k\|_2 = \max \|Au\|_2$

$$\|2 \qquad \|u\| = 1 \\ u^T v_i = 0, i < k$$

Can pick them off one by one, or....

Orthogonal iteration

- Solve for lots (or all) of eigenvectors simultaneously
- Start with initial guess V
- ◆ For k=1, 2, ...
 - Z=AV
 - VR=Z (QR decomposition: orthogonalize W)
- Easy, but slow (linear convergence, nearby eigenvalues slow things down a lot)

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Rayleigh-Ritz

- Before going further with full problem, take a look at intermediate problem: find a subset of the eigenpairs
 E.g. largest k, smallest k
- Orthogonal estimate V (nxk) of eigenvectors
- Simple Rayleigh estimate of eigenvalues:
 diag(V^TAV)
- Rayleigh-Ritz approach:
 - Solve kxk eigenproblem V^TAV
 - Use those eigenvalues (Ritz values) and the associated orthogonal combinations of columns of V
 - Note: another instance of "assume solution lies in span of a few basis vectors, solve reduced dimension problem" (542g-term1-2006)

Solving the Full Problem

- Orthogonal iteration works, but it's slow
- First speed-up: make A tridiagonal
 - Sequence of symmetric Householder reflections
 - Then Z=AV runs in O(n²) instead of O(n³)
- Other ingredients:
 - Shifting: if we shift A by an exact eigenvalue, A-\I, we get an exact eigenvector out of QR (improves on linear convergence)
 - Division: once an offdiagonal is almost zero, problem separates into decoupled blocks

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