

Notes

- ◆ Please read Enright et al., “Animation and rendering of complex water surfaces”, SIGGRAPH’02

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Level Set Distortion

- ◆ Assuming even no numerical diffusion problems in level set advection (e.g. well-resolved on grid), level sets still have problems
- ◆ Initially equal to signed distance
- ◆ After non-rigid motion, stop being signed distance
 - E.g. points near interface will end up deep underwater, and vice versa

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Fixing Distortion

- ◆ Remember it’s only zero isocontour we care about - free to change values away from interface
- ◆ Can reinitialize to signed distance (“redistance”)
 - Without moving interface, change values to be the signed distance to the interface

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Reinitialization

- ◆ Idea: we have a distorted ϕ , $|\nabla\phi|\neq 1$
- ∪ Want to return to $|\nabla\phi|=1$ without disturbing the location of the interface
- ∪ If we’re not too far from $|\nabla\phi|=1$, makes sense to use an iterative method
 - We can even think of each iteration as a pseudo-time step
 - Information should flow outward from interface
 - Advection in direction $\text{sign}(\phi)n$ and with rate of change $\text{sign}(\phi)$:

$$\phi_t + \left(\text{sign}(\phi) \frac{\nabla\phi}{|\nabla\phi|} \right) \cdot \nabla\phi = \text{sign}(\phi)$$

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Reinitialization cont’d

- ◆ Simplifying this we get:
$$\phi_t + \text{sign}(\phi)(|\nabla\phi| - 1) = 0$$
- ◆ This is another Hamilton-Jacobi equation...
 - If we want $|\nabla\phi|=1$ to very high order accuracy, can use high-order HJ methods

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Discretization

- ◆ When we discretize (e.g. with semi-Lagrangian) we’ll end up interpolating with values on either side of interface
- ◆ Limit the possibility for weird stuff to happen, like ϕ changing sign
- ∪ So instead of $\text{sign}(\phi)$, use $S(\phi_0)$
 - Can never flip sign
 - Sign function smeared out to be smooth:

$$S(\phi_0) = \frac{\phi_0}{\sqrt{\phi_0^2 + |\nabla\phi_0|^2 (\Delta x)^2}}$$

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Aside: initialization

- ◆ This works well if we're already close to signed distance
- ◆ What if we start from scratch at $t=0$?
 - For very simple geometry, may construct ϕ analytically
 - More generally, need to numerically approximate
- ◆ One solution - if we can at least get inside/outside on the grid, can run reinitialization equation from there (1st order accurate)

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Problems

- ◆ Reinitialization will unfortunately slightly move the interface (less than a grid cell)
- ◆ Errors look like, as usual, extra diffusion or smoothing
 - In addition to the errors we're making in advection...

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Fast methods

- ◆ Problem with reinitialization from scratch - to get full field, need to take $O(n)$ steps, each costs $O(n^3)$
- ◆ Can speed up with local level set method
 - Only care about signed distance near interface, so only compute those $O(n^2)$ values in $O(1)$ steps
 - Gives optimal $O(n^2)$ complexity (but the constant might be big!)
- ◆ If we really want full grid, but fast:
 - Fast Marching Method $O(n^3 \log n)$ (Tsitsiklis, Sethian)
 - Fast Sweeping Method $O(n^3)$ (Zhao)
 - Other more geometric ideas (e.g. Tsai, Mauch)
- ◆ Nice property: more careful about not letting the interface move

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Velocity extrapolation

- ◆ We can exploit level set to extrapolate velocity field outside water
 - Not a big deal for pressure solve - can directly handle extrapolation there
 - But a big deal for advection - with semi-Lagrangian method might be skipping over, say, 5 grid cells
 - So might want velocity 5 grid cells outside of water
- ◆ Simply take the velocity at an exterior grid point to be interpolated velocity at closest point on interface
 - Alternatively, propagate outward to solve $\nabla u \cdot \nabla \phi = 0$ similar to redistancing methods

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Particle-Level Set

- ◆ Last time - mentioned marker particles (MAC) method great for rough surfaces
- ◆ But if we want surface tension (which is strongest for rough flows!) or smooth water surfaces, we need a better technique
- ◆ Hybrid method: particle-level set
 - [Fedkiw and Foster], [Enright et al.]
 - Level set gives great smooth surface - excellent for getting mean curvature
 - Particles correct for level set mass (non-)conservation through excessive numerical diffusion

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Level set advancement

- ◆ Put marker particles with values of ϕ attached in a band near the surface
 - We're also storing ϕ on the grid, so we don't need particles deep in the water
 - For better results, also put particles with $\phi > 0$ ("air" particles) on the other side
- ∪ After doing a step on the grid and moving ϕ , also move particles with (extrapolated) velocity field
- ∪ Then correct the grid ϕ with the particle ϕ
- ∪ Then adjust the particle ϕ from the grid ϕ

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Level set correction

- ◆ Look for escaped particles
 - Any particle on the wrong side (sign differs) by more than the particle radius $l\phi$
- ∪ Rebuild $\phi < 0$ and $\phi > 0$ values from escaped particles (taking min/max's of local spheres)
- ∪ Merge rebuilt $\phi < 0$ and $\phi > 0$ by taking minimum-magnitude values
- ∪ Reinitialize new grid ϕ
- ∪ Correct again
- ∪ Adjust particle ϕ values within limits (never flip sign)

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Artificial Compressibility

- ◆ Let's make a quick detour...
- ◆ So far we've seen projection methods for enforcing divergence-free constraint
 - Means solving Poisson equation for pressure
 - Big, sparse linear system - it's slow, it's the bottleneck
 - Particularly on parallel architectures - global communication
 - Needs a weird staggered grid, or more complicated problems and fixes
- ◆ An alternative: artificial compressibility

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Revisiting incompressibility

- ◆ Real fluids are not incompressible
- ◆ We just make the idealization of incompressibility
 - Water, air are very close unless material velocity comparable to sound speed (transonic or faster)
 - Simplifies math a lot
 - Means we can ignore sound waves in numerical methods - terrible time step limit
- ◆ But we could go the other way
 - Replace real compressible physics with fake ones that still have sound speed much faster than material velocity

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Equation of state

- ◆ Turn hard constraint $\nabla \cdot \mathbf{u} = 0$ into soft constraint
 - Allow the fluid to compress a little, but add restoring force to get it back
- ◆ Real compressible flow does this, but with all sorts of complications from thermodynamics
- ◆ We'll fake it, simplify compressible flow
 - We don't care about compressibility effects and ideally won't even see them at all
- ◆ Artificial equation of state: $p = c^2 \rho$
 - ∪ [Chorin '67]

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New equations

- ◆ Need to include density again (continuity eq. = conservation of mass)

$$\rho_t + \nabla \cdot (\rho \mathbf{u}) = 0$$

$$\rho_t + \mathbf{u} \cdot \nabla \rho = -\rho \nabla \cdot \mathbf{u}$$

- ◆ And momentum equation

$$u_t + \mathbf{u} \cdot \nabla u + \frac{1}{\rho} \nabla p = g + \frac{1}{\rho} \nabla \cdot \mu (\nabla u + \nabla u^T)$$

- ◆ And the new equation of state

$$p = c^2 \rho$$

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What is c?

- ◆ Can derive acoustic wave equation
- ◆ We want to make sure that the maximum material speed (u) is much less than c
 - E.g. choose c at least $10 |u|_{\max}$
- ◆ Note that time step limit (for explicit methods) will have $\Delta t < \Delta x / c$
 - Hope is that 10+ times the number of steps is worth it for no pressure solve, easier programming, etc.

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The flies in the ointment

- ◆ To make it stable without a staggered grid, need artificial viscosity, or sophisticated conservation law methods
 - Just like shallow water
- ◆ We may have to give up a lot of space and time resolution to make it work

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Mesh Free Methods

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Particle fluids

- ◆ Particles are great for advection (hence marker particles in MAC, particle-level set, etc.)
- ◆ So get rid of the mesh - figure out how to do ∇p etc. with just the particles
- ◆ Basic qualitative behaviour of fluids: resist density changes
 - When particles get too close, add repulsion forces between them
 - When they get just a little too far, add attraction forces
 - When far, no force at all
- ◆ Damp particle interactions
 - Otherwise we see small-scale vibration ("heat")
 - Also accounts for viscosity

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Mesh-free?

- ◆ Mathematically, particle-only methods are independent of meshes
- ◆ Practically, need an acceleration structure to speed up finding neighbouring particles (to figure out forces)
- ◆ Most popular structure (for non-adaptive codes, i.e. where $h=\text{constant}$ for all particles) is... a mesh (background grid)

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SPH

- ◆ Smoothed Particle Hydrodynamics
- ◆ SPH can be interpreted as a particular way of choosing forces, so that you converge to solving Navier-Stokes
- ◆ [Lucy'77], [Gingold & Monaghan '77], [Monaghan...], [Morris, Fox, Zhu '97], ...
- ◆ Similar to FEM, we go to a finite dimensional space of functions
 - Basis functions now based on particles instead of grid elements
 - Can take derivatives etc. by differentiating the real function from the finite-dimensional space

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Kernel

- ◆ Need to define particle's influence in surrounding space (how we'll build the basis functions)
- ◆ Choose a kernel function W
 - Smoothed approximation to δ
 - $W(x)=W(|x|)$ - radially symmetric
 - Integral is 1
 - $W=0$ far enough away - when $|x|>2.5h$ for example
- ◆ Examples:
 - Truncated Gaussian
 - Splines (cubic, quartic, quintic, ...)

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Cubic kernel

- ◆ Use $W(x) = \frac{1}{h^3} f\left(\frac{|x|}{h}\right)$ where

$$f(s) = \frac{1}{\pi} \begin{cases} 1 - \frac{3}{2}s^2 + \frac{3}{4}s^3, & 0 \leq s \leq 1 \\ \frac{1}{4}(2-s)^3, & 1 \leq s \leq 2 \\ 0, & 2 \leq s \end{cases}$$

- Note: not good for viscosity (2nd derivatives involved - not very smooth)

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Estimating quantities

- ◆ Say we want to estimate some flow variable q at a point in space x
- ◆ We'll take a mass and kernel weighted average
- ◆ Raw version: $Q(x) = \sum_j m_j q_j W(x - x_j)$
 - But this doesn't work, since sum of weights is nowhere close to 1
 - Could normalize by dividing by $\sum_j m_j W_j$ but that complicates derivatives...
 - Instead use estimate for normalization at each particle separately (some mass-weighted measure of overlap)

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Smoothed Particle Estimate

- ◆ Take the "raw" mass estimate to get density:

$$\langle \rho(x) \rangle = \sum_j m_j W(x - x_j)$$

- ◆ Evaluate this at particles, use that to approximately normalize:

$$\langle q(x) \rangle = \sum_j q_j \frac{m_j W(x - x_j)}{\rho_j}$$

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Incompressible Free Surfaces

- ◆ Actually, I lied
 - That is, regular SPH uses the previous formulation
 - For doing incompressible flow with free surface, we have a problem
 - Density drop smoothly to 0 around surface
 - This would generate huge pressure gradient, surface goes wild...
- ◆ So instead, track density for each particle as a primary variable (as well as mass!)
 - Update it with continuity equation
 - Mass stays constant however - probably equal for all particles, along with radius

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Continuity equation

- ◆ Recall the equation is

$$\rho_t + u \cdot \nabla \rho = -\rho \nabla \cdot u$$
- ◆ We'll handle advection by moving particles around
- ◆ So we need to figure out right-hand side
- ◆ Divergence of velocity for one particle is

$$\nabla \cdot v = \nabla \cdot (v_j W(x - x_j)) = v_j \cdot \nabla W_j$$
- ◆ Multiply by density, get SPH estimate:

$$\langle \rho \nabla \cdot v \rangle_i = \sum_j m_j v_j \cdot \nabla_i W_{ij}$$

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Momentum equation

- ◆ Without viscosity: $u_t + u \cdot \nabla u = -\frac{1}{\rho} \nabla p + g$
- ◆ Handle advection by moving particles
- ◆ Acceleration due to gravity is trivial
- ◆ Left with pressure gradient
- ◆ Naïve approach - just take SPH estimate as before

$$\frac{dv_i}{dt} = \left\langle -\frac{1}{\rho} \nabla p \right\rangle = -\sum_j m_j \frac{p_j}{\rho_j^2} \nabla_i W_{ij}$$

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Conservation of momentum

- ◆ Remember momentum equation really came out of $F=ma$ (but we divided by density to get acceleration)
- ◆ Previous slide - momentum is not conserved
 - Forces between two particles is not equal and opposite
- ◆ We need to symmetrize this somehow

$$\frac{dv_i}{dt} = -\sum_j m_j \left(\frac{p_i}{\rho_i^2} + \frac{p_j}{\rho_j^2} \right) \nabla_i W_{ij}$$

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SPH advection

- ◆ Simple approach: just move each particle according to its velocity
- ◆ More sophisticated: use some kind of SPH estimate of v
 - keep nearby particles moving together
 - Note: SPH estimates only accurate when particles well organized, so this is needed for complex flows
- ◆ XSPH $\frac{dx_i}{dt} = v_i + \sum_j \frac{m_j (v_j - v_i)}{\frac{1}{2}(\rho_i + \rho_j)} W_{ij}$

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Equation of state

- ◆ Some debate - maybe need a somewhat different equation of state if free-surface involved
- ◆ E.g. [Monaghan'94]

$$p = B \left(\left(\frac{\rho}{\rho_0} \right)^7 - 1 \right)$$

- ◆ For small variations, looks like gradient is the same [linearize]
 - But SPH doesn't estimate -1 exactly, so you do get different results...

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Incompressible SPH

- ◆ Can actually do a pressure solve instead of using artificial compressibility
- ◆ But if we do exact projection get the same kinds of instability as collocated grids
 - And no alternative like staggered grids available
- ◆ Instead use approximate pressure solve
 - And rely on smoothing in SPH to avoid high-frequency compression waves
 - [Cummins & Rudman '99]

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