

Lecture 19 — Mar. 31, 2009

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This lecture introduces the concept of Martingales, which will eventually be used to prove the convergence of stochastic approximation with dependent noise. Some examples of Martingales are given, and a measure-theoretic definition of conditional expectation is introduced.

19.1 Martingales

Definition 19.1. A sequence of random variables $\{S_n\}$ is a **martingale** with respect to the sequence of random variables $\{X_n\}$ if for all $n \geq 1$:

- (i) $E(|S_n|) < \infty$
- (ii) $E(S_{n+1}|X_{1:n}) = S_n$

Example 19.2. Let X_1, X_2, \dots be a sequence of independent random variables with $E(|X_k|) < \infty$, $E(X_k) = 0 \ \forall k$. Then $S_n = \sum_{i=1}^n X_i$ is a martingale with respect to the sequence $\{X_n\}$.

Proof: Property (i) is satisfied since n is a finite number, and therefore S_n is a finite sum of finite numbers which means it is also finite. To show that property (ii) is satisfied, we use induction:

$$E(S_1|X_1) = E(X_1) = 0$$

Now assume $E(S_n|X_{1:n}) = S_n$, then:

$$\begin{aligned} E(S_{n+1}|X_{1:n}) &= E(X_{n+1} + S_n|X_{1:n}) \\ &= E(X_{n+1}|X_{1:n}) + E(S_n|X_{1:n}) \\ &= E(X_{n+1}) + E(S_n|X_{1:n}) \text{ by independence} \\ &= 0 + E(S_n|X_{1:n}) \\ &= S_n \end{aligned}$$

□

Example 19.3 ([1]). Let X_0, X_1, \dots be a discrete Markov chain taking values on a countable space \mathfrak{X} with transition matrix P . Suppose $\pi : \mathfrak{X} \rightarrow \mathbb{R}$ is a bounded function that satisfies $\sum_{j \in \mathfrak{X}} P_{ij} \pi(j) = \pi(i) \forall i \in \mathfrak{X}$.

In other words, n is a time index and $X_n = i$ if the Markov chain takes the value i at time n , and π is a vector of probabilities for each value in \mathfrak{X} that X_n could take. $\pi = [\pi(1), \pi(2), \dots, \pi(i), \dots, \pi(|\mathfrak{X}|)]^T$.

$S_n = \pi(X_n)$ is a martingale with respect to the sequence $\{X_n\}$ since:

$$\begin{aligned} E(S_{n+1} | X_{1:n}) &= E(\pi(X_{n+1}) | X_{1:n}) \\ &= E(\pi(X_{n+1}) | X_n) && \text{by the Markov property} \\ &= \sum_{j \in \mathfrak{X}} P_{X_n j} \pi(j) = \pi(X_n) = S_n \end{aligned}$$

19.2 Conditional Expectation

Consider the random variables X, Z on a measurable space $(\Omega, \mathfrak{F}, P)$.

Let

$$\begin{cases} X \in \{x_1, x_2, \dots, x_n\} \\ Z \in \{z_1, z_2, \dots, z_n\} \end{cases} \quad (19.1)$$

Then the random variable $Y = E(X|Z)$ is defined as follows:

If $Z(\omega) = z_j$, then $Y(\omega) = E(X|Z = z_j) \doteq y_j = \sum_i x_i P(X = x_i | Z = z_j)$

Remark:

- The σ -algebra over Z , $\mathcal{H} = \sigma(Z)$ consists of 2^n elements.
- Y is \mathcal{H} -measurable

Hence,

$$\begin{aligned} E(Y I_{Z=z_j}) &= \int I_{Z=z_j} y_j dP(Y, Z) \\ &= P(Z = z_j) \sum_i x_i P(X = x_i | Z = z_j) \\ &= E(X I_{Z=z_j}) \end{aligned}$$

That is, if $H_j \in \mathcal{H} = \{Z = z_j\}$ then $E(Y I_{H_j}) = E(X I_{H_j})$, and since for each $H \in \mathcal{H}$, I_H is a sum of I_{H_j} 's: $E(Y I_H) = E(X I_H)$

We illustrate this with an example to make it more clear.

Example 19.4. Let $A = \{B_i : 1 \leq i \leq n\}$.

$$\begin{aligned} E(X|A) &\doteq E(XI_A) \\ &= \int \int XI_A(Z) dP(X, Z) \\ &= \int \int X \left(\sum_i I_{B_i}(Z) \right) dP(X, Z) \\ &= \sum_i E(XI_{B_i}) \end{aligned}$$

Theorem 19.5 (Kolmogorov Fundamental Theorem (1933)). *Give an random variable X on a measurable space $(\Omega, \mathfrak{F}, P)$, and a sub- σ -algebra of \mathfrak{F} , \mathcal{H} . There exists a random variable Y such that:*

- Y is \mathcal{H} -measurable
- $E(|Y|) < \infty$
- $\forall H \in \mathcal{H}, \int_H Y dP = \int_H X dP$

Bibliography

- [1] Williams, D.: Probability with Martingales. Cambridge Mathematical Textbooks. (1991)