



Lecture 2: The Singular Value Decomposition



Nando de Freitas

www.cs.ubc.ca/~nando/340-2009/

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Outline

The Singular Value Decomposition (SVD) is a matrix factorization that has many applications, including:

- Information retrieval,
- Least-squares problems,
- Image processing,
- Dimensionality reduction.

Eigenvalue decomposition

Let $\mathbf{A} \in \mathbb{R}^{m \times m}$. If we put the eigenvalues of \mathbf{A} into a diagonal matrix $\mathbf{\Lambda}$ and gather the eigenvectors into a matrix \mathbf{X} , then the eigenvalue decomposition of \mathbf{A} is given by

$$\mathbf{A} = \mathbf{X}\mathbf{\Lambda}\mathbf{X}^{-1}.$$

But what if \mathbf{A} is not a square matrix? Then the SVD comes to the rescue.

EXAM Exercise, if $A \in \mathbb{R}^{m \times m}$, Symmetric
show that $A = X\mathbf{\Lambda}X^T$

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Formal definition of the SVD

Given $\mathbf{A} \in \mathbb{R}^{m \times n}$, the SVD of \mathbf{A} is a factorization of the form

$$\mathbf{A} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T$$

m x n m x n n x n n x n

where \mathbf{u} are the left **singular vectors**, σ are the **singular values** and \mathbf{v} are the right singular vectors.

$\mathbf{\Sigma} \in \mathbb{R}^{n \times n}$ is diagonal with positive entries (singular values in the diagonal).

$\mathbf{U} \in \mathbb{R}^{m \times n}$ with orthonormal columns.

$\mathbf{V} \in \mathbb{R}^{n \times n}$ with orthonormal columns.

($\Rightarrow \mathbf{V}$ is orthogonal so $\mathbf{V}^{-1} = \mathbf{V}^T$)

$$\mathbf{U}^T \mathbf{U} = \mathbf{I}$$

$$\begin{cases} \mathbf{V}^T \mathbf{V} = \mathbf{I} \\ \mathbf{V} \mathbf{V}^T = \mathbf{I} \end{cases}$$

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Formal definition of the SVD

The equations relating the right singular values $\{\mathbf{v}_j\}$ and the left singular vectors $\{\mathbf{u}_j\}$ are

$$\mathbf{A}\mathbf{v}_j = \sigma_j\mathbf{u}_j \quad j = 1, 2, \dots, n$$

$$\mathbf{A}\mathbf{V} = \mathbf{U}\mathbf{\Sigma}$$

$$\mathbf{A} \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 & \dots & \mathbf{v}_n \end{bmatrix} = \begin{bmatrix} \mathbf{u}_1 & \mathbf{u}_2 & \dots & \mathbf{u}_n \end{bmatrix} \begin{bmatrix} \sigma_1 & & & 0 \\ & \sigma_2 & & \\ & & \dots & \\ 0 & & & \sigma_n \end{bmatrix}$$

$v_i \in \mathbb{R}^n$ $u_i \in \mathbb{R}^m$

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SVD properties

1. There is no assumption that $m \geq n$ or that \mathbf{A} has full rank.
2. All diagonal elements of $\mathbf{\Sigma}$ are non-negative and in non-increasing order:

$$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_p \geq 0$$

where $p = \min(m, n)$

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SVD properties

Theorem 3 Every matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$ has singular value decomposition $\mathbf{A} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^T$

Furthermore, the singular values $\{\sigma_j\}$ are uniquely determined.

If \mathbf{A} is square and $\sigma_i \neq \sigma_j$ for all $i \neq j$, the left singular vectors $\{\mathbf{u}_j\}$ and the right singular vectors $\{\mathbf{v}_j\}$ are uniquely determined to within a factor of ± 1 .

SVD in terms of eigenvalues

$$(\mathbf{A}^T \mathbf{A})^T = \mathbf{A}^T \mathbf{A} = \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^T$$


Theorem 4 The nonzero singular values of \mathbf{A} are the (positive) square roots of the nonzero eigenvalues of $\mathbf{A}^T \mathbf{A}$ or $\mathbf{A} \mathbf{A}^T$ (these matrices have the same nonzero eigenvalues).



$$\begin{aligned} \textcircled{1} \quad \mathbf{A}^T \mathbf{A} &= (\mathbf{U} \mathbf{\Sigma} \mathbf{V}^T)^T \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T \\ &= \mathbf{V} \mathbf{\Sigma} \mathbf{U}^T (\mathbf{U} \mathbf{\Sigma} \mathbf{V}^T) \end{aligned}$$

$$\boxed{\mathbf{A}^T \mathbf{A} = \mathbf{V} \mathbf{\Sigma}^2 \mathbf{V}^T}$$

$$\begin{aligned} \mathbf{Q} &= \mathbf{V} \\ \mathbf{\Sigma}^2 &= \mathbf{\Lambda} \end{aligned}$$

 ② $AA^T = U\Sigma V^T V\Sigma U^T = U\Sigma^2 U^T$

③ $A = U\Sigma V^T \Rightarrow AV = U\Sigma$
 $AV\Sigma^{-1} = U$


① $\Sigma^2 = \Lambda, A^T A = V\Sigma^2 V^T, Q = V$

Let $A = \begin{bmatrix} 1 & 2 & 3 \end{bmatrix}$, what is U, Σ, V

Matrix norms

Theorem 5 $\|A\|_2 = \sigma_1$, where $\|A\|_2 = \max_{x \neq 0} \frac{\|Ax\|}{\|x\|} =$

$\max_{\|x\| \leq 1} \|Ax\|$.

 $\|x\| = 1$ is a circle in 2d
 when $x = [x_1, x_2]$.





$$\|A\| = \max_{\|x\| \neq 0} \frac{\|Ax\|}{\|x\|} = \max_{\|x\|=1} \|Ax\|$$

$$\rightarrow \max_{\|x\| \neq 0} \frac{\|U \Sigma V^T x\|}{\|x\|} = \max_{\|x\| \neq 0} \frac{\|\Sigma V^T x\|}{\|x\|}$$

$$= \max_{\|x\| \neq 0} \frac{\|\Sigma V^T x\|}{\|V^T x\|} = \max_{\|y\| \neq 0} \frac{\|\Sigma y\|}{\|y\|}$$

$$= \max_{\|y\|=1} \|\Sigma y\| = \max_{\|y\|=1} \sqrt{(\sigma_1 y_1)^2 + (\sigma_2 y_2)^2 + \dots}$$

$$\text{Optimal } y = [1 \ 0 \ 0 \ \dots]^T = e_1$$

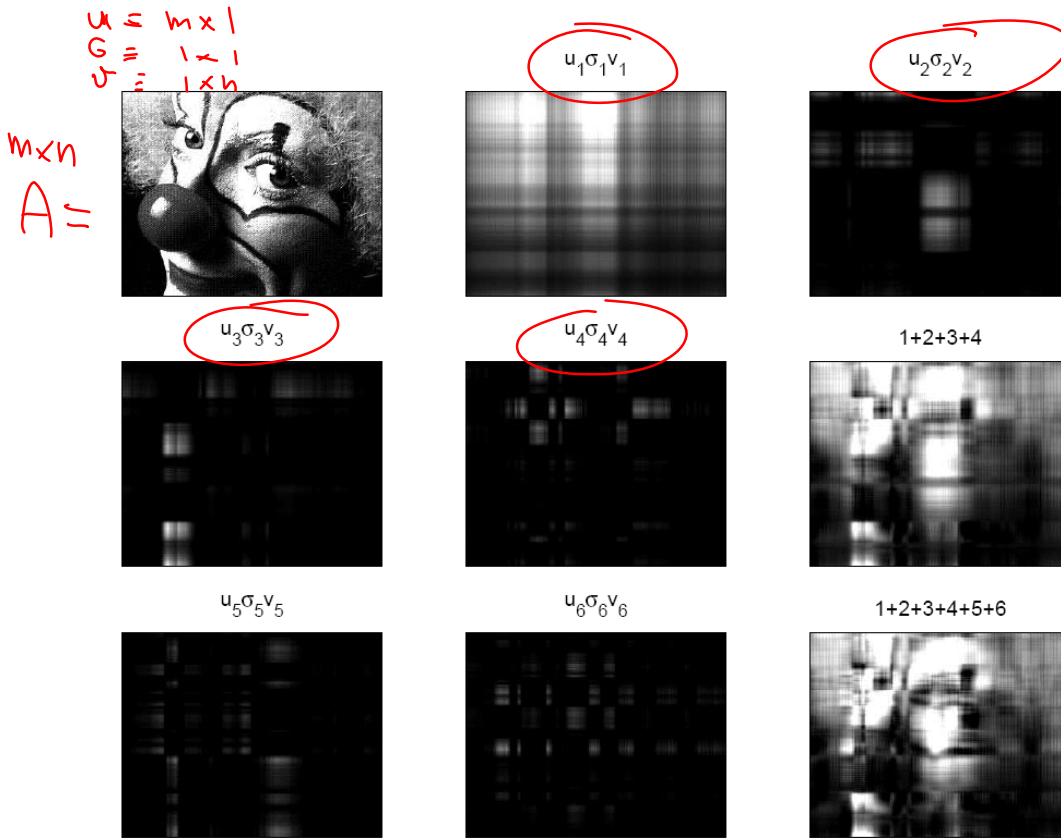
SVD in terms of rank 1 matrices

Theorem 6

$$A = \sum_{j=1}^r \sigma_j u_j v_j^T$$

where r is the rank of A .





Energy interpretation and approximation error

What is so useful about this expansion is that the ν^{th} partial sum captures as much of the “energy” of \mathbf{A} as possible by a matrix of at most rank- ν . In this case, “energy” is defined by the 2-norm.

Theorem 7 For any ν with $0 \leq \nu \leq r$ define

$$\mathbf{A}_\nu = \sum_{j=1}^{\nu} \sigma_j \mathbf{u}_j \mathbf{v}_j^T$$

If $\nu = p = \min(m, n)$, define $\sigma_{\nu+1} = 0$.

Then,

$$\|\mathbf{A} - \mathbf{A}_\nu\|_2 = \sigma_{\nu+1}$$