## **Decision Theory**

- Shall I bring the umbrella today?
- I am looking for a house to buy. Shall I buy this one?
- Am I going to smoke the next cigarette?
- The court has to decide whether the defendant is guilty or not.
- Is this email spam or not?

We make decisions under uncertainty all the time!!

Decision Matrix

	Rain	No rain
Umbrella	Dry clothes	Dry clothes
	Heavy Backpack	Heavy Backpack
	True Positive	False Positive
No umbrella	Soaked clothes	Dry clothes
	Light Backpack	Light backpack
	False Negative	True Negative

How do we make decisions?

Given our belief, we take a possible action.

In this example the set of possible actions is {umbrella, no umbrella}. If we feel that P(rain) > P(no rain), we decide to bring an umbrella.

In this case our decision rule is based on a prior belief. To make better decision rules we should use information from the data as well. **SPAM Filters**. We have two actions:  $\alpha_1$  for keep the mail and  $\alpha_2$  for delete as SPAM. There are two classes  $C_1$ : normal mail and  $C_2$ : SPAM

True Positive  $\Rightarrow$  Correct Detection

False Negative  $\Rightarrow$  Missed Detection

False Positive  $\Rightarrow$  False Alarm

True Negative  $\Rightarrow$  Correct Rejection

In a classification problem, the action is: Given the input  $\mathbf{x}$ , assign observation to a class  $C_i$ . A **decision rule**  $\alpha(x)$  is the action taken after observing x.

The **loss function**, denoted by  $\lambda$ , tells how costly each action is.

 $\lambda(\alpha_i|C_j)$  is the loss incurred for taking action  $\alpha_i$  if the true class is  $C_j$  .

An important loss function is zero-one-loss (0-1)

 $\lambda(\alpha_i|C_j) = 0$  if i = j, and 1 if  $i \neq j$ 

The expected loss or the **conditional risk** of taking action  $\alpha_i$ , after observing **x**, is

$$R(\alpha_i | \mathbf{x}) = \sum_{j=1}^{c} \lambda(\alpha_i | C_j) P(C_j | \mathbf{x})$$

The total expected loss, also called overall risk, is

$$R(\alpha) = \int R(\alpha(\mathbf{x})|\mathbf{x}))p(\mathbf{x})d\mathbf{x}$$

We would like to find a decision rule  $\alpha(x)$  that minimizes the overall risk (the minimum expected loss  $R(\alpha_i | \mathbf{x})$ ).

This is **Bayes decision rule**. The overall risk  $R(\alpha)$  for Bayes decision rule is called **Bayes risk**. This is the smallest possible overall risk.

## Two Category Classification

The possible classes are  $C_1$  and  $C_2$  (or spam and not spam). The action  $\alpha_1$  corresponds to deciding if the true class is  $C_1$  and  $\alpha_2$  corresponds to deciding that the true class is  $C_2$ .

$$R(\alpha_1|x) = \lambda_{11}P(C_1|\mathbf{x}) + \lambda_{12}P(C_2|\mathbf{x})$$
$$R(\alpha_2|x) = \lambda_{21}P(C_1|\mathbf{x}) + \lambda_{22}P(C_2|\mathbf{x})$$

What is Bayes decision rule?

Decide that the true class is  $C_1$  if  $R(\alpha_1|x) < R(\alpha_2|x)$  and  $C_2$  otherwise.



Here we assume that  $\lambda_{21} > \lambda_{11}$ , this is reasonable since the loss is greater when making a mistake.

In general we should pick the most probable case:

If  $P(C_1|\mathbf{x}) > P(C_2|\mathbf{x})$  pick  $C_1$ 

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If P(C_2|\mathbf{x}) > P(C_1|\mathbf{x}) pick C_2
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