Congestion Games

Kevin Leyton-Brown
What you’ll learn in this talk

- What is a congestion game?
  - ...and, that there are other ways of representing simultaneous-move games
- What sorts of interactions do they model?
- What good theoretical properties do they have?
- What are potential games, and how are they related to congestion games?
Definition

Each player chooses some subset from a set of resources, and the cost of each resource depends on the number of other agents who select it.
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Definition (Congestion game)

A congestion game is a tuple \((N, R, A, c)\), where

- \(N\) is a set of \(n\) agents;
- \(R\) is a set of \(r\) resources;
- \(A = A_1 \times \cdots \times A_n\), where \(A_i \subseteq 2^R \setminus \{\emptyset\}\) is the set of actions for agent \(i\);
- \(c = (c_1, \ldots, c_r)\), where \(c_k : \mathbb{N} \to \mathbb{R}\) is a cost function for resource \(k \in R\).
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Utility functions:

- Define \(# : R \times A \mapsto \mathbb{N}\) as a function that counts the number of players who took any action that involves resource \(r\) under action profile \(a\).
- For each resource \(k\), define a cost function \(c_k : \mathbb{N} \mapsto \mathbb{R}\).
- Given an action profile \(a = (a_i, a_{-i})\),
  \[
  u_i(a) = - \sum_{r \in R | r \in a_i} c_r(#(r, a)).
  \]
Motivating Example: Selfish Routing

Agents trying to choose uncongested paths in a graph.

- Each **edge** connecting two nodes is a resource
- Actions are **paths** in the graph that connect a given user’s source and target nodes
  - Stream a video in a computer network
  - Travel along a road network
- The cost function for each resource expresses the latency on each link as a function of its congestion
  - an increasing (possibly nonlinear) function
Motivating Problem: Santa Fe ("El Farol") Bar Problem

- Each of a set of people independently selects whether or not to go to the bar
- Utility for attending:
  - number of people attending, if less than or equal to 6;
  - 6 minus the number of people attending, if greater than 6
- Utility for not attending: 0
- Note: nonmonotonic cost functions
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Play the game (raising your hands)
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Play again. Change your action if you like.
Represent the Santa Fe Bar Problem as a Congestion Game

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u_i(a) = - \sum_{r \in R \mid r \in a_i} c_r(#(r, a)).\]
Why care about congestion games?

Theorem

Every congestion game has a ("pure-strategy") Nash equilibrium.

Theorem

A simple procedure (*MyopicBestResponse*) is guaranteed to find a pure-strategy Nash equilibrium of a congestion game.
Myopic Best Response

- Start with an arbitrary action profile $a$
- While there exists an agent $i$ for whom $a_i$ is not a best response to $a_{-i}$
  - $a'_i \leftarrow$ some best response by $i$ to $a_{-i}$
  - $a \leftarrow (a'_i, a_{-i})$
- Return $a$

By the definition of equilibrium, MyopicBestResponse returns a pure-strategy Nash equilibrium if it terminates.
In general games **MyopicBestResponse** can get caught in a cycle, even when a pure-strategy Nash equilibrium exists.

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<td>$D$</td>
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Can you find a cycle?
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This game has one pure-strategy Nash equilibrium, $(D, R)$. However, if we run **MyopicBestResponse** with $a = (L, U)$ the procedure will cycle forever.
A game $G = (N, A, u)$ is a **potential game** if there exists a function $P : A \mapsto \mathbb{R}$ such that, for all $i \in N$, all $a_{-i} \in A_{-i}$ and $a_i, a'_i \in A_i$, $u_i(a_i, a_{-i}) - u_i(a'_i, a_{-i}) = P(a_i, a_{-i}) - P(a'_i, a_{-i})$. 

**Theorem**

Every potential game has a pure-strategy Nash equilibrium.

**Proof.**

Let $a^* = \arg \max_{a \in A} P(a)$. Clearly for any other action profile $a'$, $P(a^*) \geq P(a')$. Thus by the definition of a potential function, for any agent $i$ who can change the action profile from $a^*$ to $a'$ by changing his own action, $u_i(a^*) \geq u_i(a')$. 

**Congestion Games**

Kevin Leyton-Brown, Slide 10
Potential Games

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Congestion Games
Every congestion game has the potential function

$$P(a) = \sum_{r \in R} \sum_{j=1}^{\#(r,a)} c_r(j)$$

- There's a proof in the book
- Main intuition: utility functions are linear combinations of cost functions, so most of the terms in this expansion cancel out when we take the difference between the potential values for two similar action profiles
- It also turns out that every potential game is a congestion game (harder to show)
The MyopicBestResponse procedure is guaranteed to find a pure-strategy Nash equilibrium of a congestion game.

Proof.

It is sufficient to show that MyopicBestResponse finds a pure-strategy Nash equilibrium of any potential game. With every step of the while loop, $P(a)$ strictly increases, because by construction $u_i(a'_i, a_{-i}) > u_i(a_i, a_{-i})$, and thus by the definition of a potential function $P(a'_i, a_{-i}) > P(a_i, a_{-i})$. Since there are only a finite number of action profiles, the algorithm must terminate.
Myopic Best Response: Analysis

MyopicBestResponse converges for CGs regardless of:

- the cost functions (e.g., they do not need to be monotonic)
- the action profile with which the algorithm is initialized
- which agent best responds (when there’s a choice)
- And even if we change best response to “better response”
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**MyopicBestResponse** converges for CGs regardless of:
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Complexity considerations:
- the problem of finding a pure Nash equilibrium in a congestion game is **PLS-complete**
  - as hard to find as any other object whose existence is guaranteed by a potential function argument
  - intuitively, as hard as finding a local minimum in a traveling salesman problem using local search
- **We thus expect MyopicBestResponse** to be **inefficient in the worst case**
Conclusions

- **Congestion games** are a compact and intuitive way of representing interactions in which agents care about the number of others who choose a given resource, and their utility decomposes additively across these resources.

- **Potential games** are a less-intuitive but analytically useful characterization equivalent to congestion games.
  - potential function: a single function that captures any player’s utility change from deviating.

- These games always have pure-strategy Nash equilibria.

- **MyopicBestResponse** always converges to a pure-strategy Nash equilibrium in congestion/potential games.

- They’re very widely studied in the literature, particularly in CS.
  - realistic model
  - pure-strategy equilibria are actually fairly rare
  - nice computational story
References


