



Mixed Strategies and Nash Equilibrium

Game Theory Course: Jackson, Leyton-Brown & Shoham

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Mixed Strategies

- It would be a pretty bad idea to play any deterministic strategy in matching pennies
- Idea: confuse the opponent by playing randomly
- Define a strategy s_i for agent i as any probability distribution over the actions A_i .
 - pure strategy: only one action is played with positive probability
 - mixed strategy: more than one action is played with positive probability
 - these actions are called the support of the mixed strategy
- Let the set of all strategies for i be S_i
- Let the set of all strategy profiles be $S = S_1 \times \ldots \times S_n$.



Utility under Mixed Strategies



- What is your payoff if all the players follow mixed strategy profile s ∈ S?
 - We can't just read this number from the game matrix anymore: we won't always end up in the same cell

Utility under Mixed Strategies



- What is your payoff if all the players follow mixed strategy profile s ∈ S?
 - We can't just read this number from the game matrix anymore: we won't always end up in the same cell
- Instead, use the idea of expected utility from decision theory:

$$u_i(s) = \sum_{a \in A} u_i(a) Pr(a|s)$$
$$Pr(a|s) = \prod_{j \in N} s_j(a_j)$$

Best Response and Nash Equilibrium

Our definitions of best response and Nash equilibrium generalize from actions to strategies.

Definition (Best response)

 $\overline{s_i^* \in BR(s_{-i})} \text{ iff } \forall s_i \in S_i, \ u_i(s_i^*, s_{-i}) \ge u_i(s_i, s_{-i})$

Definition (Nash equilibrium)

 $s = \langle s_1, \dots, s_n
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Definition (Nash equilibrium)

 $s = \langle s_1, \ldots, s_n \rangle$ is a Nash equilibrium iff $\forall i, s_i \in BR(s_{-i})$

Theorem (Nash, 1950)

Every finite game has a Nash equilibrium.







- It's hard in general to compute Nash equilibria, but it's easy when you can guess the support
- For BoS, let's look for an equilibrium where all actions are part of the support





- Let player 2 play B with p, F with 1 p.
- If player 1 best-responds with a mixed strategy, player 2 must make him indifferent between F and B (why?)





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- If player 1 best-responds with a mixed strategy, player 2 must make him indifferent between F and B (why?)

$$u_1(B) = u_1(F)$$

 $2p + 0(1-p) = 0p + 1(1-p)$
 $p = \frac{1}{3}$





- Likewise, player I must randomize to make player 2 indifferent.
 - Why is player I willing to randomize?





- Likewise, player I must randomize to make player 2 indifferent.
 - Why is player I willing to randomize?
- Let player I play B with q, F with 1-q.

$$u_2(B) = u_2(F)$$

$$q + 0(1-q) = 0q + 2(1-q)$$

$$q = \frac{2}{3}$$
hus the mixed strategies $(\frac{2}{3}, \frac{1}{3})$, $(\frac{1}{3}, \frac{2}{3})$ are a Nash equilibrium.

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Interpreting Mixed Strategy Equilibria

What does it mean to play a mixed strategy? Different interpretations:

- Randomize to confuse your opponent
 - consider the matching pennies example
- Randomize when uncertain about the other's action
 - consider battle of the sexes
- Mixed strategies are a concise description of what might happen in repeated play: count of pure strategies in the limit
- Mixed strategies describe population dynamics: 2 agents chosen from a population, all having deterministic strategies. MS gives the probability of getting each PS.



Example - Soccer Penalty Kicks



Kicker/Goalie	Left	Right
Left	0, 1	1, 0
Right	1, 0	0, 1

Example - Soccer Penalty Kicks



Kicker/Goalie	Left	Right
Left	0, 1	1, 0
Right	.75, .25	0, 1





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Hardness beyond $2\times 2~{\rm games}$ $_{\rm Algorithms}$



Two example algorithms for finding NE

- LCP (Linear Complementarity) formulation
 - [Lemke-Howson '64]
- Support Enumeration Method
 - [Porter et al. '04]

The Lemke-Howson Algorithm

CPSC 532L

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The Lemke-Howson Algorithm

Lecture Overview





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The Lemke-Howson Algorithm

Linear Programming

A linear program is defined by:

- a set of real-valued variables
- a linear objective function
 - a weighted sum of the variables
- a set of linear constraints
 - the requirement that a weighted sum of the variables must be greater than or equal to some constant

Linear Programming

Given n variables and m constraints, variables x and constants w, a and b:

maximize
$$\sum_{i=1}^{n} w_i x_i$$

subject to $\sum_{i=1}^{n} a_{ij} x_i \leq b_j$ $\forall j = 1 \dots m$

- These problems can be solved in polynomial time using interior point methods.
 - Interestingly, the (worst-case exponential) simplex method is often faster in practice.

Lecture Overview







$$\begin{split} \sum_{a_2 \in A_2} u_1(a_1, a_2) \cdot s_2(a_2) + r_1(a_1) &= U_1^* & \forall a_1 \in A_1 \\ \sum_{a_1 \in A_1} u_2(a_1, a_2) \cdot s_1(a_1) + r_2(a_2) &= U_2^* & \forall a_2 \in A_2 \\ \sum_{a_i \in A_i} s_i(a_i) &= 1 & \forall i \in N \\ s_i(a_i) &\geq 0 & \forall i \in N, a_i \in A_i \\ r_i(a_i) &\geq 0 & \forall i \in N, a_i \in A_i \\ r_i(a_i) \cdot s_i(a_i) &= 0 & \forall i \in N, a_i \in A_i \end{split}$$

• We can write down a set of constraints that a two player strategy profile satisfies if and only if it is a Nash equilibrium.

Two-player equilibrium constraints

$$\begin{split} \sum_{a_2 \in A_2} u_1(a_1, a_2) \cdot s_2(a_2) + r_1(a_1) &= U_1^* & \forall a_1 \in A_1 \\ \sum_{a_1 \in A_1} u_2(a_1, a_2) \cdot s_1(a_1) + r_2(a_2) &= U_2^* & \forall a_2 \in A_2 \\ \sum_{a_i \in A_i} s_i(a_i) &= 1 & \forall i \in N \\ s_i(a_i) &\geq 0 & \forall i \in N, a_i \in A_i \\ r_i(a_i) &\geq 0 & \forall i \in N, a_i \in A_i \\ r_i(a_i) \cdot s_i(a_i) &= 0 & \forall i \in N, a_i \in A_i \\ \forall i \in N,$$

- $s_i(a_i)$ is the probability that *i* plays a_i .
- $r_i(a_i)$ is a "slack" variable.
- Each $u_i(a_i, a_{-i})$ is a constant.

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$$\begin{split} \sum_{a_2 \in A_2} u_1(a_1, a_2) \cdot s_2(a_2) + r_1(a_1) &= U_1^* & \forall a_1 \in A_1 \\ \sum_{a_1 \in A_1} u_2(a_1, a_2) \cdot s_1(a_1) + r_2(a_2) &= U_2^* & \forall a_2 \in A_2 \\ \sum_{a_i \in A_i} s_i(a_i) &= 1 & \forall i \in N \\ \sum_{a_i \in A_i} s_i(a_i) &\geq 0 & \forall i \in N, a_i \in A_i \\ r_i(a_i) &\geq 0 & \forall i \in N, a_i \in A_i \\ r_i(a_i) \cdot s_i(a_i) &= 0 & \forall i \in N, a_i \in A_i \end{split}$$

• s_1 and s_2 are valid probability distributions.

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- Slack variables $r_i(a_i)$ are non-negative.
- U_1^* is weakly greater than the EU of any of player 1's actions, given $s_2 \dots$

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Two-player equilibrium constraints

$$\sum_{a_{2} \in A_{2}} u_{1}(a_{1}, a_{2}) \cdot s_{2}(a_{2}) + r_{1}(a_{1}) = U_{1}^{*} \qquad \forall a_{1} \in A_{1}$$

$$\sum_{a_{1} \in A_{1}} u_{2}(a_{1}, a_{2}) \cdot s_{1}(a_{1}) + r_{2}(a_{2}) = U_{2}^{*} \qquad \forall a_{2} \in A_{2}$$

$$\sum_{a_{i} \in A_{i}} s_{i}(a_{i}) = 1 \qquad \forall i \in N$$

$$s_{i}(a_{i}) \geq 0 \qquad \forall i \in N, a_{i} \in A_{i}$$

$$r_{i}(a_{i}) \geq 0 \qquad \forall i \in N, a_{i} \in A_{i}$$

$$r_{i}(a_{i}) \cdot s_{i}(a_{i}) = 0 \qquad \forall i \in N, a_{i} \in A_{i}$$

- Slack variables $r_i(a_i)$ are non-negative.
- U_1^* is weakly greater than the EU of any of player 1's actions, given $s_2 \dots$
- and exactly equal to the EU of every action in the support. = 990

$$\begin{split} \sum_{a_2 \in A_2} u_1(a_1, a_2) \cdot s_2(a_2) + r_1(a_1) &= U_1^* & \forall a_1 \in A_1 \\ \sum_{a_1 \in A_1} u_2(a_1, a_2) \cdot s_1(a_1) + r_2(a_2) &= U_2^* & \forall a_2 \in A_2 \\ \sum_{a_i \in A_i} s_i(a_i) &= 1 & \forall i \in N \\ s_i(a_i) &\geq 0 & \forall i \in N, a_i \in A_i \\ r_i(a_i) &\geq 0 & \forall i \in N, a_i \in A_i \\ r_i(a_i) \cdot s_i(a_i) &= 0 & \forall i \in N, a_i \in A_i \end{split}$$

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- So we're done! Or are we?
- This requirement changes the problem from a linear program to a linear complementarity program.
- \bullet Unfortunately, there is no general algorithm for solving LCPs_ one

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It uses a concept of labels on mixed strategies.

Mixed strategy labels

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Definition (Labels)

Every possible mixed strategy s_i is given a set of labels $L(s_i) \subseteq A_1 \cup A_2$. The strategy s_i has the following labels:

• Every action $a_i \in A_i$ satisfying $s_i(a_i) = 0$, and

• Every action $a_{-i} \in A_{-i}$ such that $a_{-i} \in BR_{-i}(s_i)$.

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- Every action $a_{-i} \in A_{-i}$ such that $a_{-i} \in BR_{-i}(s_i)$.

A pair of strategies (s_1, s_2) is a Nash equilibrium iff it is completely labelled: $L(s_1) \cup L(s_2) = A_1 \cup A_2$.

Searching for a completely labelled pair

- The Lemke-Howson algorithm can be understood as searching the two spaces of labelled strategies for a fully-labelled pair.
- When the game is nondegenerate*, there are no strategies with more labels than an agent has actions.
- So a completely labelled pair of strategies must consist of a pair that has no labels in common.



Pivoting

• The LCP formulation allows us to define a pivot operation, which is able to take a labelled strategy and return a new one that differs in exactly one label.

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- Basic strategy:
 - **(**) Start at the completely-labelled "synthetic equilibrium" (0, 0).
 - 2 Pivot to a new s_1 ; its new label must duplicate a label of s_2 .

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 - 8 Repeat:
 - Pivot to a new strategy to remove the duplicated label (the "leaving" label).
 - 2 If the new label (the "entering" label) is a duplicate, continue.
 - 3 Otherwise, the "missing" label must have been found. Halt.

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- Only works on 2-player games. (why?)
- Guaranteed to find at least one equilibrium.
- Not guaranteed to find all equilibria.
- May require exponentially many pivots.
- Quite fast in practice.

The basic idea behind SEM

- If you "guess" the right support, finding an equilibrium only requires solving a system of polynomial inequalities.
- In practice, tools like MINOS [Murtagh, Saunders, 2010] solve these systems quickly.
- To find one (or all) Nash equilibra, just enumerate supports.

Hardness beyond 2×2 games

Support Enumeration Method: Porter et al. 2004

• Step 1: Finding a NE with a specific support

$$\begin{split} \sum_{a_{-1}\in\sigma_{-i}} p(a_{-i})u_i(a_i,a_{-i}) &= v_i \qquad \forall i \in \{1,2\}, a_i \in \sigma_i \\ \sum_{a_{-1}\in\sigma_{-i}} p(a_{-i})u_i(a_i,a_{-i}) &\leq v_i \qquad \forall i \in \{1,2\}, a_i \notin \sigma_i \\ p_i(a_i) &\geq 0 \qquad \forall i \in \{1,2\}, a_i \in \sigma_i \\ p_i(a_i) &= 0 \qquad \forall i \in \{1,2\}, a_i \notin \sigma_i \\ \sum_{a_i\in\sigma_i} p_i(a_i) &= 1 \qquad \forall i \in \{1,2\} \end{split}$$



Background	SEM for AGGs	Results
The ideas that mak	e SEM fast	



- (1) The size of the tree
- (2) Dominance
- (3) Test Given Support (TGS)

SEM for AGGs

Thompson, Leung, Leyton-Brown

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