Mechanism Design

Lecture 13

Mechanism Design

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Lecture Overview



- 2 Social Choice Functions

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Recap	Social Choice Functions	Fun Game	Mechanism Design
Notation			

- N is the set of agents
- O is a finite set of outcomes with $|O|\geq 3$
- L is the set of all possible strict preference orderings over O.
 - for ease of exposition we switch to strict orderings
 - we will end up showing that desirable SWFs cannot be found even if preferences are restricted to strict orderings
- [≻] is an element of the set Lⁿ (a preference ordering for every agent; the input to our social welfare function)
- \succ_W is the preference ordering selected by the social welfare function W.
 - When the input to W is ambiguous we write it in the subscript; thus, the social order selected by W given the input $[\succ']$ is denoted as $\succ_{W([\succ'])}$.

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Pareto Efficiency

Definition (Pareto Efficiency (PE))

W is Pareto efficient if for any $o_1, o_2 \in O$, $\forall i \ o_1 \succ_i o_2$ implies that $o_1 \succ_W o_2$.

• when all agents agree on the ordering of two outcomes, the social welfare function must select that ordering.

Independence of Irrelevant Alternatives

Definition (Independence of Irrelevant Alternatives (IIA))

W is independent of irrelevant alternatives if, for any $o_1, o_2 \in O$ and any two preference profiles $[\succ'], [\succ''] \in L^n$, $\forall i \ (o_1 \succ'_i o_2)$ if and only if $o_1 \succ''_i o_2$) implies that $(o_1 \succ_{W([\succ'])} o_2)$ if and only if $o_1 \succ_{W([\succ''])} o_2$).

• the selected ordering between two outcomes should depend only on the relative orderings they are given by the agents.

Nondictatorship

Definition (Non-dictatorship)

W does not have a dictator if $\neg \exists i \forall o_1, o_2(o_1 \succ_i o_2 \Rightarrow o_1 \succ_W o_2)$.

- there does not exist a single agent whose preferences always determine the social ordering.
- We say that W is dictatorial if it fails to satisfy this property.

Arrow's Theorem

Theorem (Arrow, 1951)

Any social welfare function W that is Pareto efficient and independent of irrelevant alternatives is dictatorial.

We will assume that W is both PE and IIA, and show that W must be dictatorial. Our assumption that $|O| \ge 3$ is necessary for this proof. The argument proceeds in four steps.

Lecture Overview



2 Social Choice Functions



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Social Choice Functions

- Maybe Arrow's theorem held because we required a whole preference ordering.
- Idea: social choice functions might be easier to find
- We'll need to redefine our criteria for the social choice function setting; PE and IIA discussed the ordering

Weak Pareto Efficiency

Definition (Weak Pareto Efficiency)

A social choice function C is weakly Pareto efficient if, for any preference profile $[\succ] \in L^n$, if there exist a pair of outcomes o_1 and o_2 such that $\forall i \in N$, $o_1 \succ_i o_2$, then $C([\succ]) \neq o_2$.

• A dominated outcome can't be chosen.

Monotonicity

Definition (Monotonicity)

C is monotonic if, for any $o \in O$ and any preference profile $[\succ] \in L^n$ with $C([\succ]) = o$, then for any other preference profile $[\succ']$ with the property that $\forall i \in N, \forall o' \in O, o \succ'_i o'$ if $o \succ_i o'$, it must be that $C([\succ']) = o$.

• an outcome *o* must remain the winner whenever the support for it is increased relative to a preference profile under which *o* was already winning

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Non-dictatorship

Definition (Non-dictatorship)

C is non-dictatorial if there does not exist an agent j such that C always selects the top choice in j's preference ordering.

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The bad news

Theorem (Muller-Satterthwaite, 1977)

Any social choice function that is weakly Pareto efficient and monotonic is dictatorial.

- Perhaps contrary to intuition, social choice functions are no simpler than social welfare functions after all.
- The proof repeatedly "probes" a social choice function to determine the relative social ordering between given pairs of outcomes.
- Because the function must be defined for all inputs, we can use this technique to construct a full social welfare ordering.

But... Isn't Plurality Monotonic?

Plurality satisfies weak PE and ND, so it must not be monotonic.

Consider the following preferences:

3 agents: $a \succ b \succ c$ 2 agents: $b \succ c \succ a$ 2 agents: $c \succ b \succ a$

Plurality chooses a.

But... Isn't Plurality Monotonic?

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Consider the following preferences:

3 agents: $a \succ b \succ c$ 2 agents: $b \succ c \succ a$ 2 agents: $c \succ b \succ a$

Plurality chooses a.

Increase support for a by moving c to the bottom:

3 agents: $a \succ b \succ c$ 2 agents: $b \succ c \succ a$ 2 agents: $b \succ a \succ c$

Now plurality chooses b.

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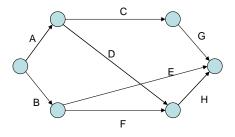
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Mechanism Design

Selfish Routing



- 8 people play as agents A H; the others act as mediators.
- Agents' utility functions: $u_i = payment cost if your edge is chosen; 0 otherwise.$
- Mediators: find me a path from source to sink, at the lowest cost you can.
- Agents: agree to be paid whatever you like; claim whatever you like; however, you can't show your paper to anyone.

Lecture Overview



2 Social Choice Functions







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Bayesian Game Setting

- Extend the social choice setting to a new setting where agents can't be relied upon to disclose their preferences honestly.
- Start with a set of agents in a Bayesian game setting (but no actions).

Definition (Bayesian game setting)

A Bayesian game setting is a tuple (N, O, Θ, p, u) , where

- N is a finite set of n agents;
- O is a set of outcomes;
- $\Theta = \Theta_1 \times \cdots \times \Theta_n$ is a set of possible joint type vectors;
- p is a (common prior) probability distribution on Θ ; and
- $u = (u_1, \ldots, u_n)$, where $u_i : O \times \Theta \mapsto \mathbb{R}$ is the utility function for each player *i*.

Mechanism Design

Definition (Mechanism)

A mechanism (for a Bayesian game setting $(N,O,\Theta,p,u))$ is a pair (A,M), where

- $A = A_1 \times \cdots \times A_n$, where A_i is the set of actions available to agent $i \in N$; and
- $M: A \mapsto \Pi(O)$ maps each action profile to a distribution over outcomes.

Thus, the designer gets to specify

- the action sets for the agents (though they may be constrained by the environment)
- the mapping to outcomes, over which agents have utility
- can't change outcomes; agents' preferences or type spaces

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What we're up to

- The problem is to pick a mechanism that will cause rational agents to behave in a desired way, specifically maximizing the mechanism designer's own "utility" or objective function
 - each agent holds private information, in the Bayesian game sense
 - often, we're interested in settings where agents' action space is identical to their type space, and an action can be interpreted as a declaration of the agent's type
- Various equivalent ways of looking at this setting
 - perform an optimization problem, given that the values of (some of) the inputs are unknown
 - choose the Bayesian game out of a set of possible Bayesian games that maximizes some performance measure
 - design a game that *implements* a particular social choice function in equilibrium, given that the designer no longer knows agents' preferences and the agents might lie

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Implementation in Dominant Strategies

Definition (Implementation in dominant strategies)

Given a Bayesian game setting (N, O, Θ, p, u) , a mechanism (A, M) is an implementation in dominant strategies of a social choice function C (over N and O) if for any vector of utility functions u, the game has an equilibrium in dominant strategies, and in any such equilibrium a^* we have $M(a^*) = C(u)$.

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Implementation in Bayes-Nash equilibrium

Definition (Bayes–Nash implementation)

Given a Bayesian game setting (N, O, Θ, p, u) , a mechanism (A, M) is an implementation in Bayes–Nash equilibrium of a social choice function C (over N and O) if there exists a Bayes–Nash equilibrium of the game of incomplete information (N, A, Θ, p, u) such that for every $\theta \in \Theta$ and every action profile $a \in A$ that can arise given type profile θ in this equilibrium, we have that $M(a) = C(u(\cdot, \theta))$.

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Bayes-Nash Implementation Comments

Bayes-Nash Equilibrium Problems:

- there could be more than one equilibrium
 - which one should I expect agents to play?
- agents could miscoordinate and play none of the equilibria
- asymmetric equilibria are implausible

Refinements:

- Symmetric Bayes-Nash implementation
- *Ex-post* implementation

Implementation Comments

We can require that the desired outcome arises

- in the only equilibrium
- in every equilibrium
- in at least one equilibrium

Forms of implementation:

- Direct Implementation: agents each simultaneously send a single message to the center
- Indirect Implementation: agents may send a sequence of messages; in between, information may be (partially) revealed about the messages that were sent previously like extensive form