# HOMEWORK 4 SOLUTIONS, MATH 340, FALL 2015 

JOEL FRIEDMAN

Copyright: Copyright Joel Friedman 2015. Not to be copied, used, or revised without explicit written permission from the copyright owner.
(1) (a)

$$
\begin{array}{rllll}
x_{3} & = & 2+\epsilon_{1} & -x_{1} & \\
x_{4} & =3+\epsilon_{2} & & -x_{2} \\
x_{5} & = & 5+\epsilon_{3} & -x_{1} & -x_{2} \\
\hline z & = & & 2 x_{1} & +x_{2}
\end{array}
$$

$x_{2}$ enters and $x_{4}$ leaves.

$$
\begin{array}{rrrrr}
x_{3} & = & 2+\epsilon_{1} & -x_{1} & \\
x_{2} & = & 3+\epsilon_{2} & & -x_{4} \\
x_{5} & = & 2-\epsilon_{2}+\epsilon_{3} & -x_{1} & +x_{4} \\
\hline z & = & 3+\epsilon_{2} & +2 x_{1} & -x_{4}
\end{array}
$$

$x_{1}$ enters; since $2+\epsilon_{1}>2-\epsilon_{2}+\epsilon_{3}$ (we'd have a tie if the $\epsilon_{i}$ 's weren't there), $x_{5}$ leaves:

$$
\begin{array}{rlrrr}
x_{3} & = & \epsilon_{1}+\epsilon_{2}-\epsilon_{3} & +x_{5} & -x_{4} \\
x_{2} & = & 3+\epsilon_{2} & & -x_{4} \\
x_{1} & = & 2-\epsilon_{2}+\epsilon_{3} & -x_{5} & +x_{4} \\
\hline z & = & 7-\epsilon_{2}+2 \epsilon_{3} & -2 x_{5} & +x_{4}
\end{array}
$$

Now $x_{4}$ enters and $x_{3}$ leaves (this would be a degenerate pivot if not for the $\epsilon_{i}{ }^{\text {'s }}$ ).

$$
\begin{array}{lrrrl}
x_{4} & = & \epsilon_{1}+\epsilon_{2}-\epsilon_{3} & +x_{5} & -x_{3} \\
x_{2} & = & 3-\epsilon_{1}+\epsilon_{3} & -x_{5} & +x_{3} \\
x_{1} & = & 2+\epsilon_{1} & & -x_{3} \\
\hline z & = & 7+\epsilon_{1}+\epsilon_{3} & -x_{5} & -x_{3}
\end{array}
$$

This dictionary is final, and so the optimal solution is $x_{1}=2, x_{2}=3$. A picture is given Figure 1.
(b) The dictionaries look the same, with $\epsilon_{1}$ and $\epsilon_{3}$ interchanged. So the first dictionary is

$$
\begin{array}{rlll}
x_{3} & =2+\epsilon_{3} & -x_{1} & \\
x_{4} & =3+\epsilon_{2} & & -x_{2} \\
x_{5} & =5+\epsilon_{1} & -x_{1} & -x_{2} \\
\hline z & = & & 2 x_{1}
\end{array}+x_{2}
$$

[^0]

Figure 1. Drawing for the first simplex method


Figure 2. Drawing for the second simplex method, i.e., $\epsilon_{1}$ and $\epsilon_{3}$ interchanged
and the first pivot is $x_{2}$ enters, $x_{4}$ leaves, as before. But on the second pivot $x_{1}$ enters and $x_{3}$ leaves, since the the second dictionary looks like:

$$
\begin{array}{rrrrr}
x_{3} & = & 2+\epsilon_{3} & -x_{1} & \\
x_{2} & = & 3+\epsilon_{2} & & -x_{4} \\
x_{5} & = & 2-\epsilon_{2}+\epsilon_{1} & -x_{1} & +x_{4} \\
\hline z & = & 3+\epsilon_{2} & +2 x_{1} & -x_{4}
\end{array}
$$

and $2+\epsilon_{3}<2-\epsilon_{2}+\epsilon_{1}$. Thus we get to the final dictionary

$$
\begin{array}{rrrrr}
x_{5} & = & -\epsilon_{3}-\epsilon_{2}+\epsilon_{1} & +x_{3} & +x_{4} \\
x_{2} & = & 3+\epsilon_{2} & & -x_{4} \\
x_{1} & = & 2+\epsilon_{3} & -x_{3} & \\
\hline z & = & 7+2 \epsilon_{3}+\epsilon_{2} & -2 x_{3} & -x_{4}
\end{array}
$$

A picture is give in Figure 2.
(c) Note that this final dictionary is different, with different basic variables! Also, we took one fewer pivots this new way.
Note also that this shows there is more than one final dictionary here. For the future, this means that there is more than one optimal solution for the dual problem; this is due to the three lines coinciding at the optimal solution for the primal LP.
When we perturb a degenerate problem, we can expect more than one geometry to emerge depending on the perturbation. The perturbed problems and the $\epsilon_{i}$ 's are guides to which pivots to take, so different geometries give rise to different sequences of dictionaries.
There are many other comments one could make along these lines (this is not a threat).
(2) Here we are going to assume, for simplicity that $a, b>0$ in optimality (we can always at $A+B t_{i}$ to each $y_{i}$ where $A, B$ are large positive numbers to achieve this). The linear program is to minimize $M_{1}+\ldots+M_{n}$ subject to

$$
-M_{1} \leq y_{1}-a-b t_{1} \leq M_{1}, \quad-M_{2} \leq y_{2}-a-b t_{2} \leq M_{2}, \quad \cdots .
$$

We therefore have $n+2$ decision variables, and $2 n$ slack variables. When some $M_{i}=0$, we have that both corresponding slack variables are zero; when some $M_{i}>0$, only (and exactly) one slack variable is zero. Since $a, b>0$ in optimality, and $n+2$ variables are non-basic, there must be (at least) two of the $M_{i}$ that are zero in the final dictionary. Hence we can say that there is always a solution, $a, b$, for which $y=a+b t$ goes through (at least) two of the data points.

Department of Computer Science, University of British Columbia, Vancouver, BC V6T 1Z4, CANADA, and Department of Mathematics, University of British Columbia, Vancouver, BC V6T 1Z2, CANADA.

E-mail address: jf@cs.ubc.ca or jf@math.ubc.ca
URL: http://www.math.ubc.ca/~jf


[^0]:    Research supported in part by an NSERC grant.

