CPSC 322 Introduction to Artificial Intelligence

October 6, 2004

Things to look for



Midterm exam is being marked

Solutions posted later this week

Your results available next week



Highlights from a couple of weeks ago

We're moving forward under some assumptions:

Whatever intelligence is, it results from some kind of computation and it's platform independent. It's not unique to brains.

Symbol manipulation is a type of computation that is sufficient to give rise to intelligent behavior.

Any symbol manipulation can be carried out on a Turing machine (and, by the way, computers are TMs).

But keep in mind that these assumptions may be wrong.

Search

A physical symbol system exercises its intelligence in problem solving by search -- that is, by generating and progressively modifying symbol structures until it produces a solution structure.

Allen Newell and Herbert A. Simon, "Computer Science as Empirical Inquiry: Symbols and Search"

Search

In order to cope, an organism must either armor itself (like a tree or a clam) and "hope for the best," or else develop methods for getting out of harm's way and into the better neighborhoods of the vicinity. If you follow this later course, you are confronted with the primordial problem that every agent must continually solve: Now what do I do?

Daniel C. Dennett, "Consciousness Explained"

The Cracker Barrel





2 8 3 1 _ 4 7 6 5

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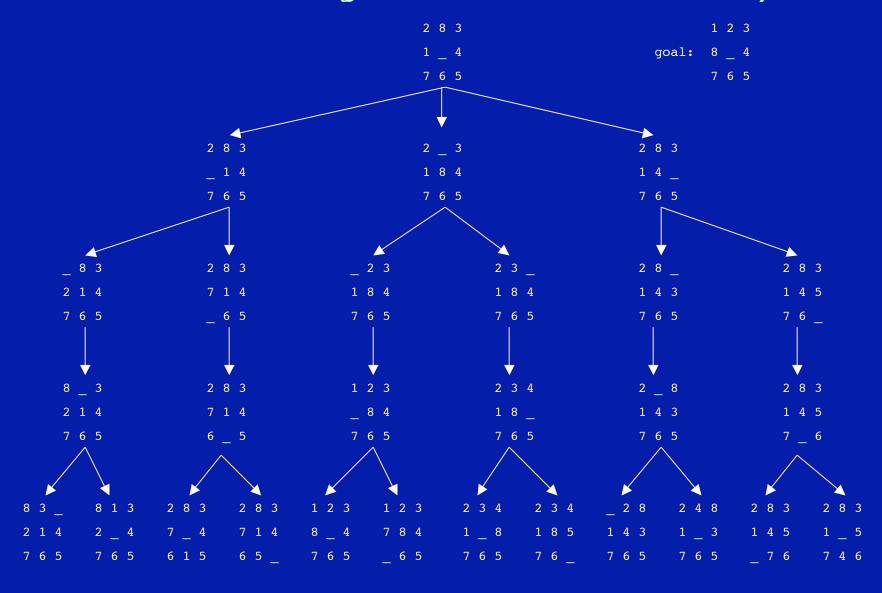
2 8 3 1 _ 4 7 6 5

What do I do now?

You're Al students, so the obvious answer is search! More specifically, graph search:

Many (why not all?) problem-solving tasks can be mapped onto the problem of finding a path in a graph

8-Tile Puzzle (just a little bit of it)

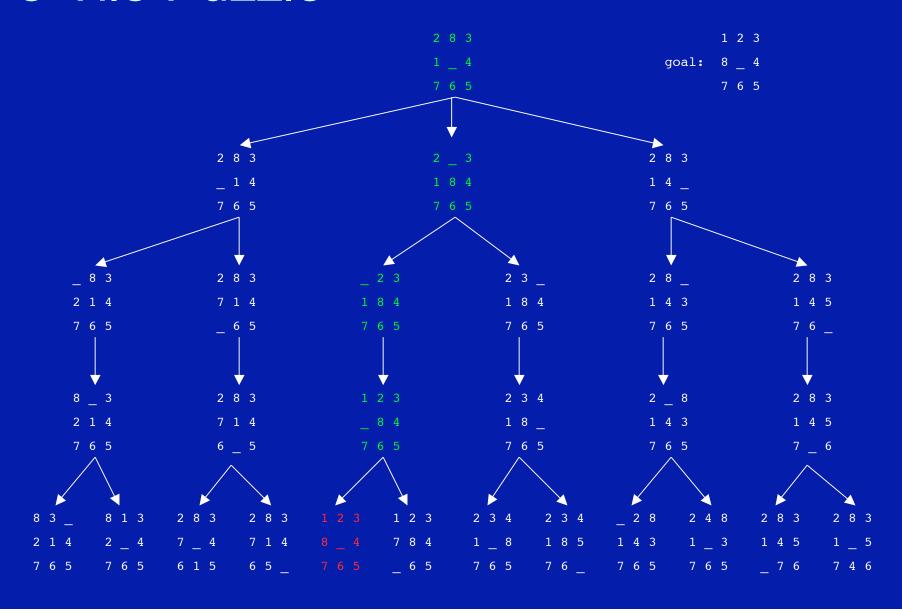


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- nodes represent partial solutions
- arcs represent transformations from one partial solution to another
- try to find path along arcs from a start node to a goal node



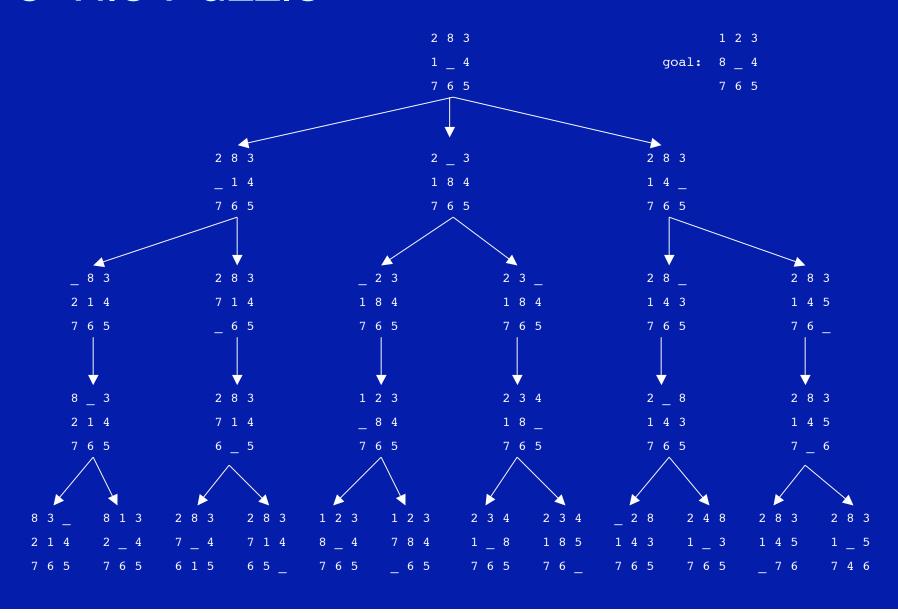
How do I do this graph search stuff?

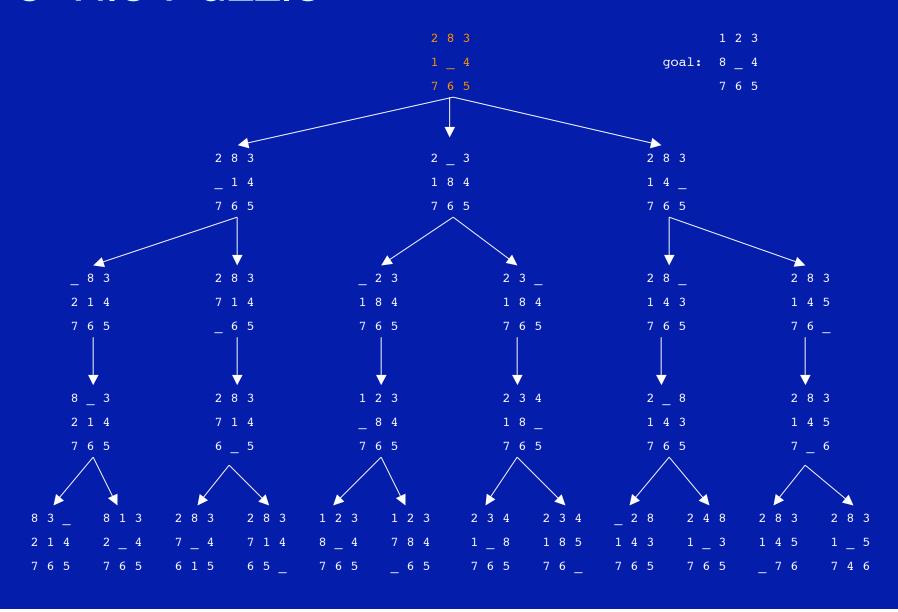
Given a set of start nodes, a set of goal nodes, and a graph:

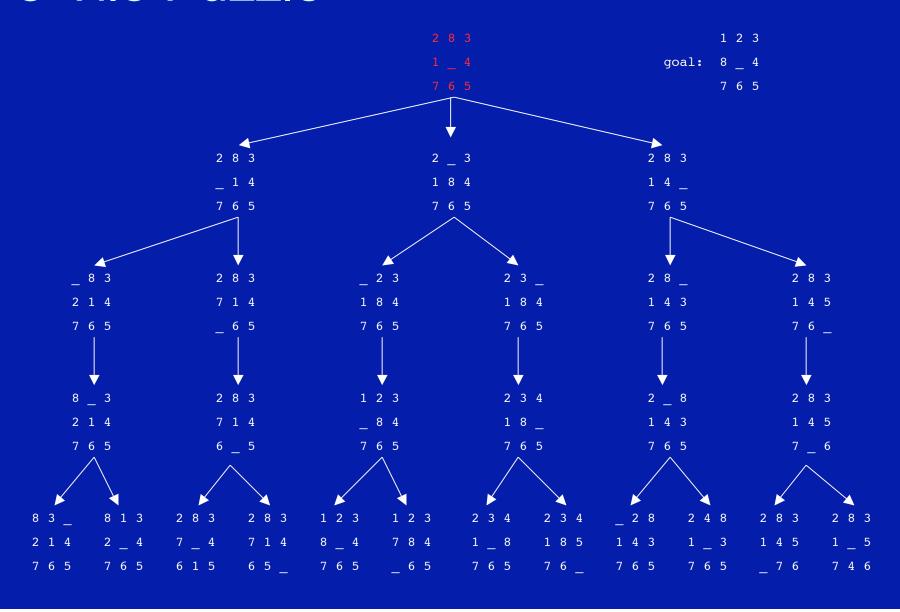
make a "list" of the start nodes - let's call it the "frontier"

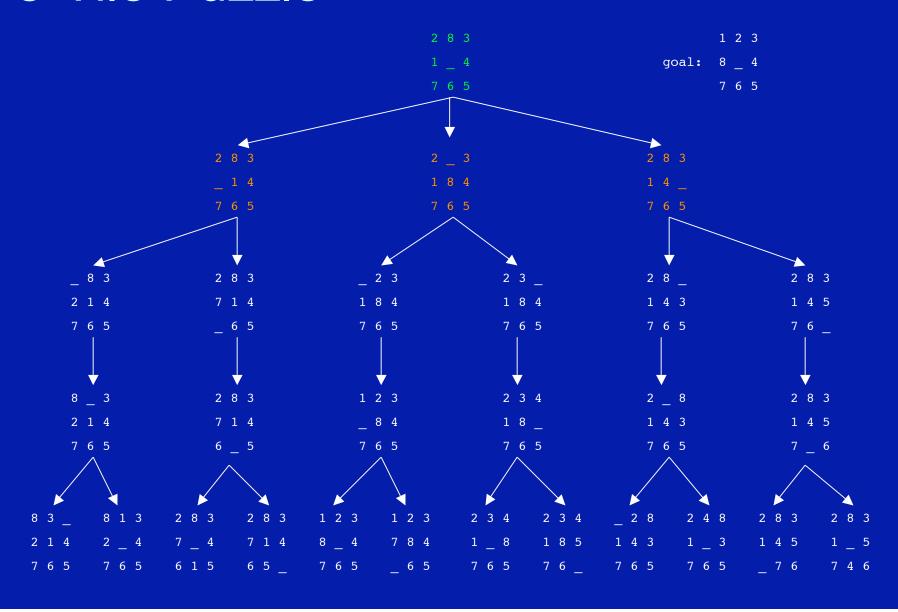
repeat

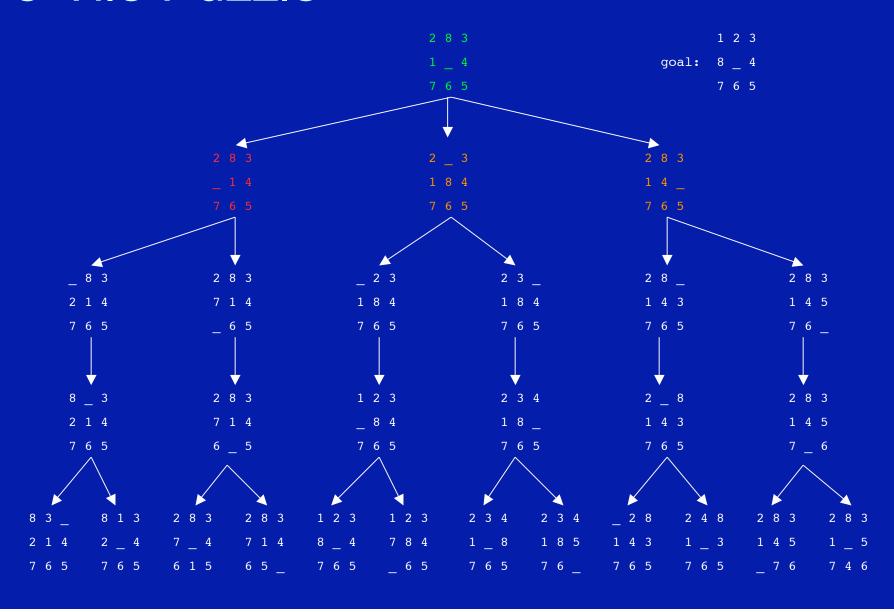
if no nodes on the frontier then terminate with failure choose one node from the frontier and remove it if the chosen node matches the goal node then terminate with success else put next nodes (neighbours) on frontier end repeat

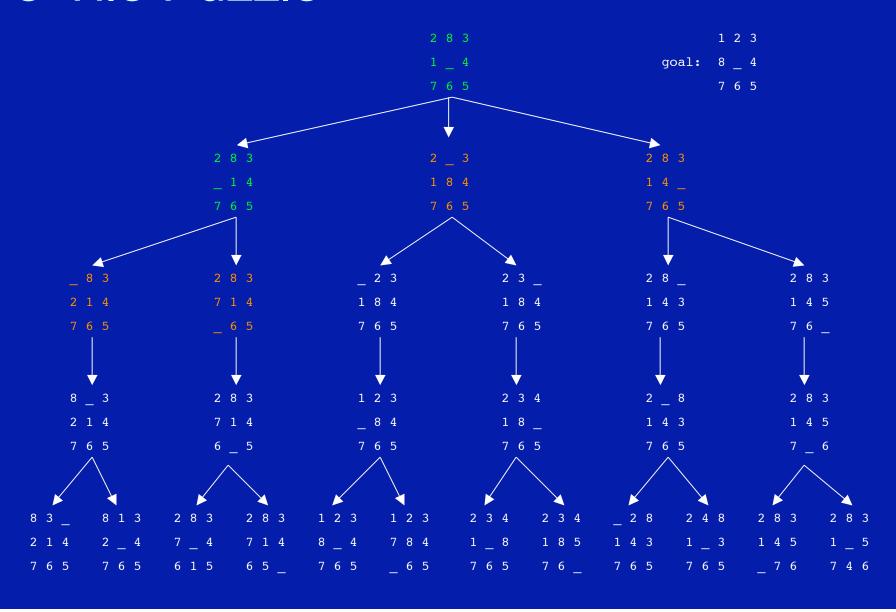


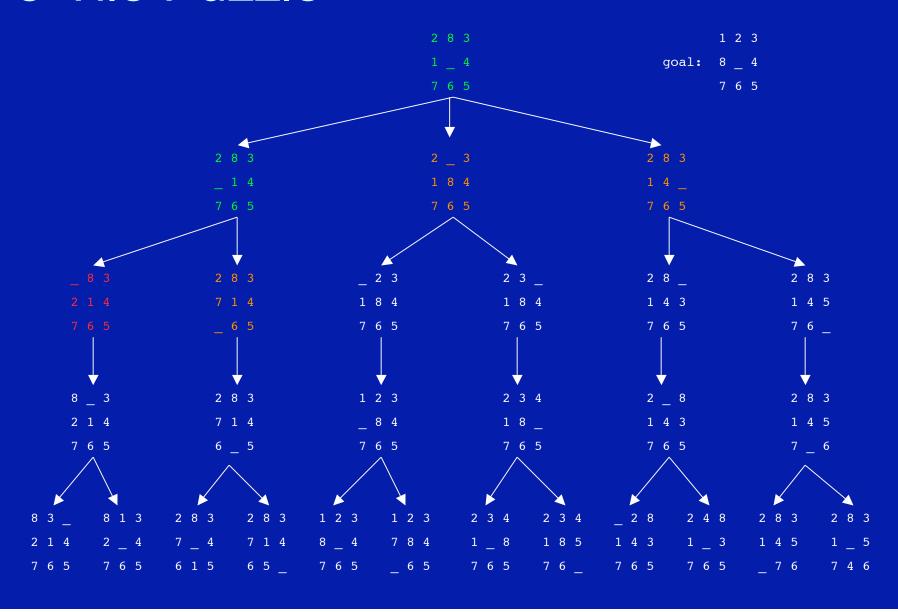


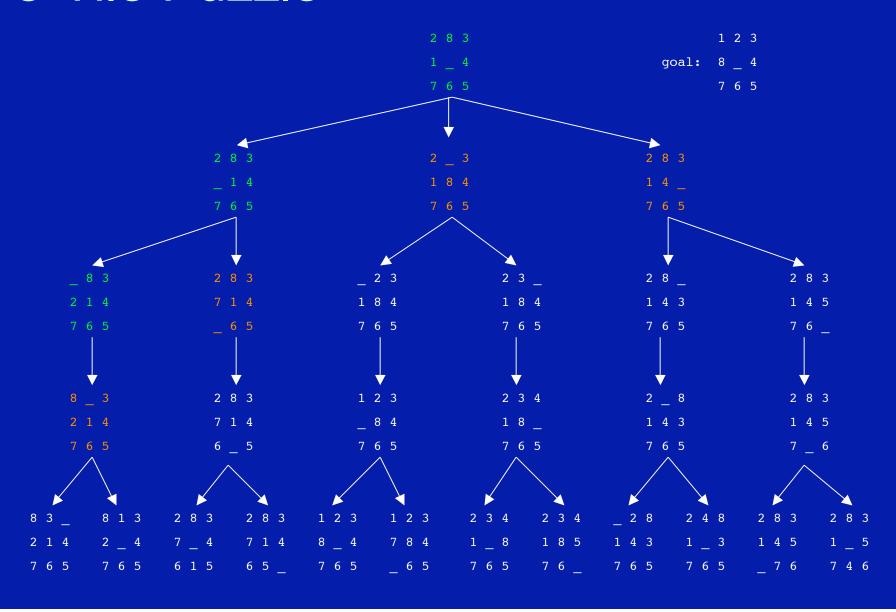


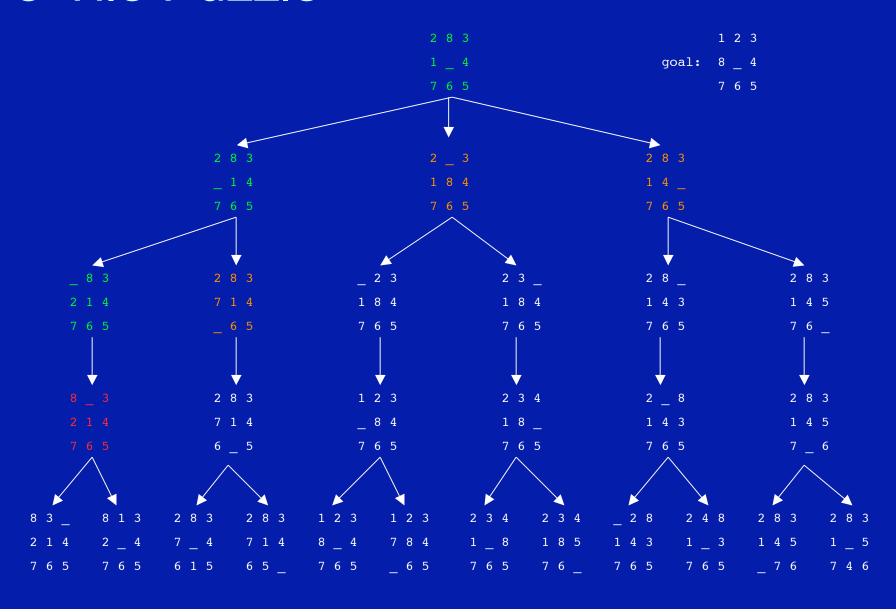


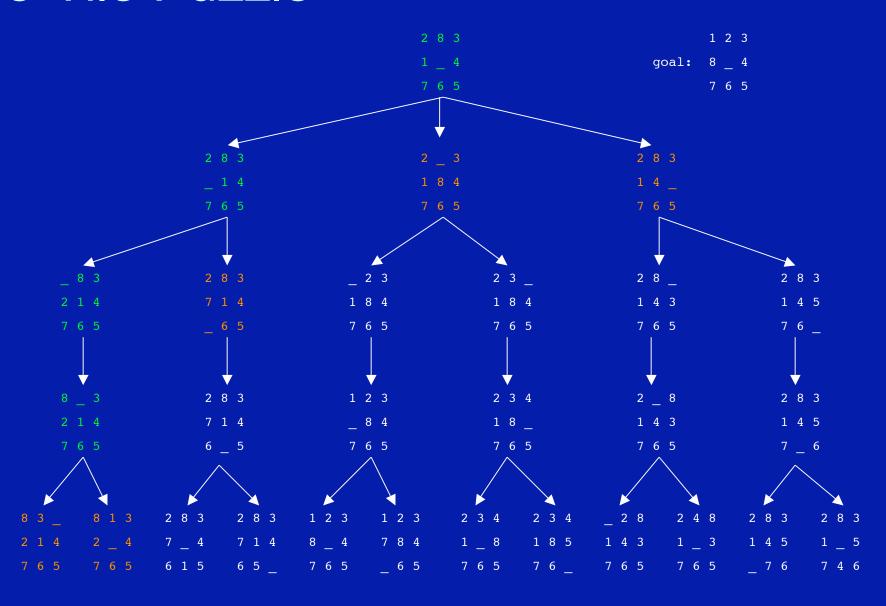


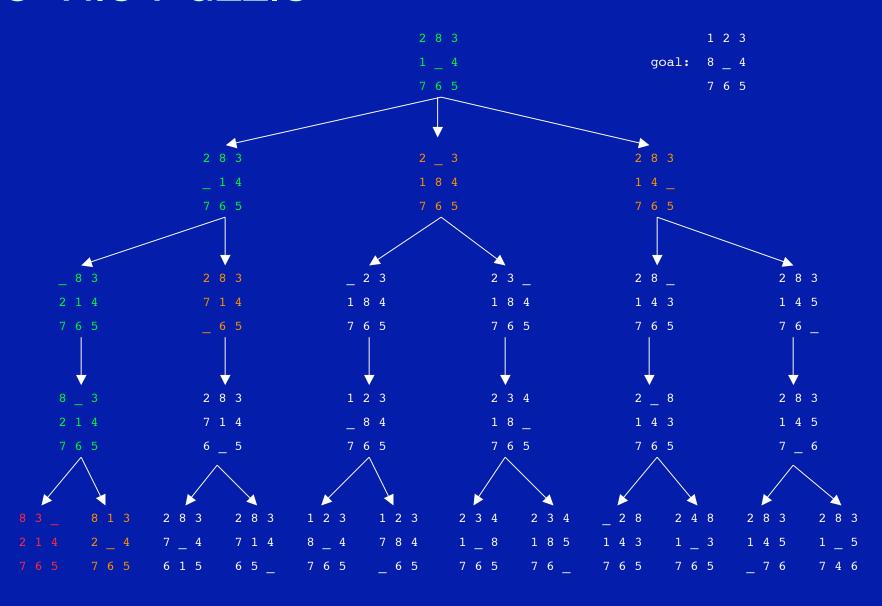


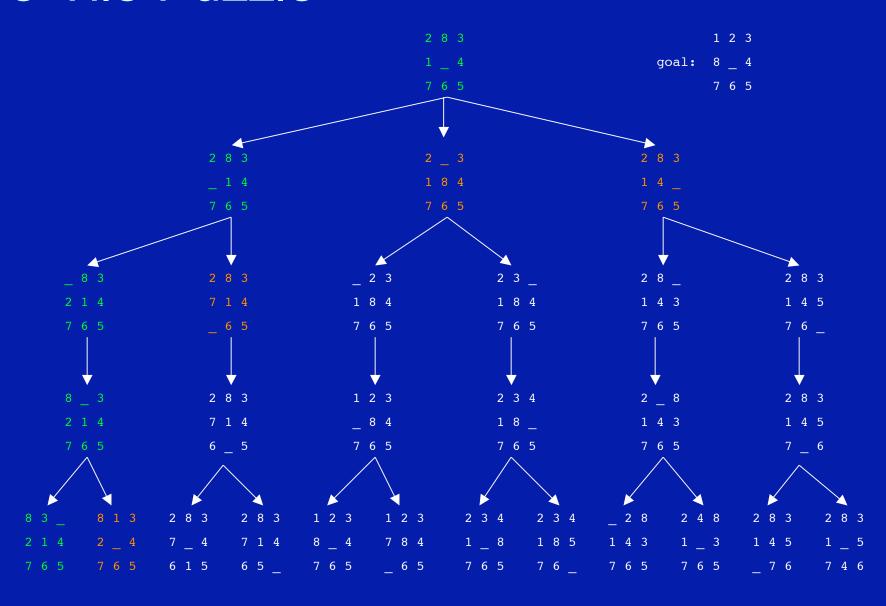


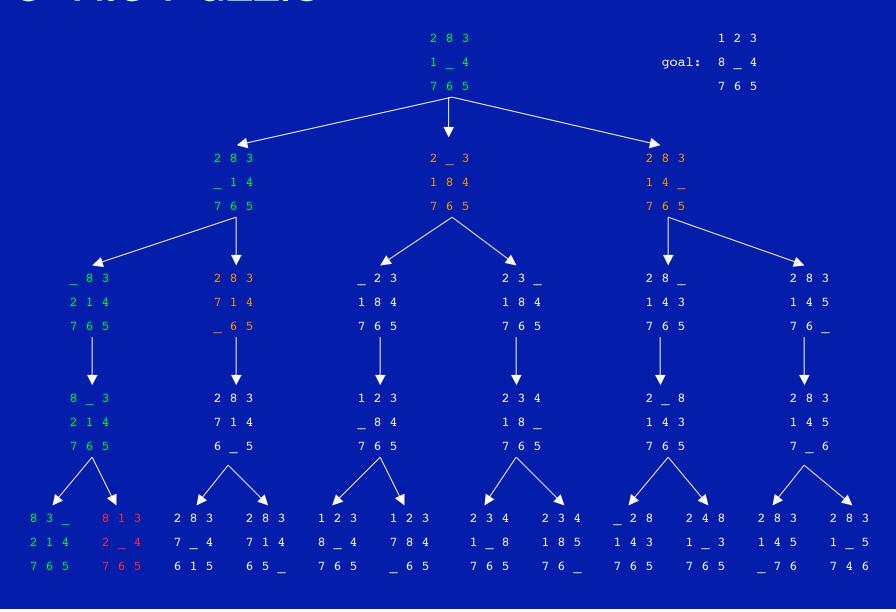


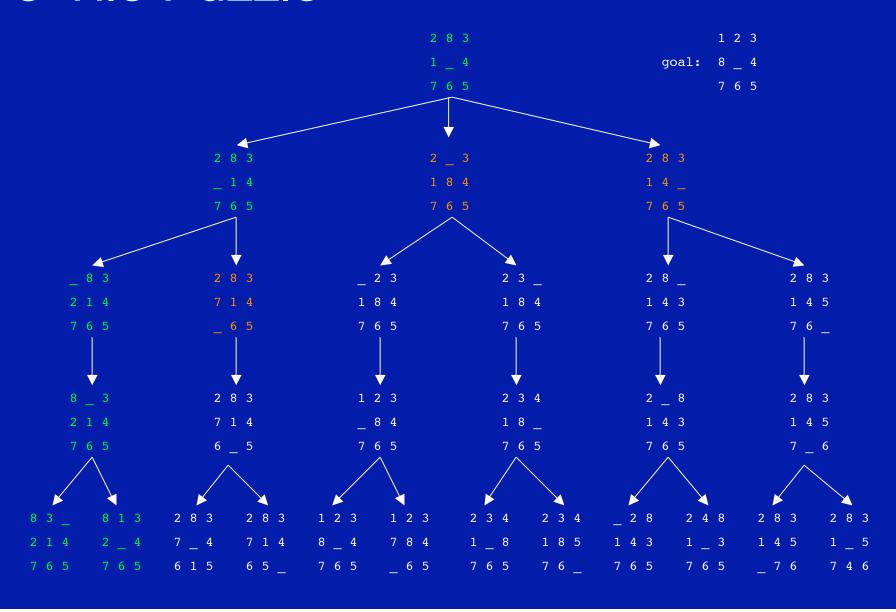


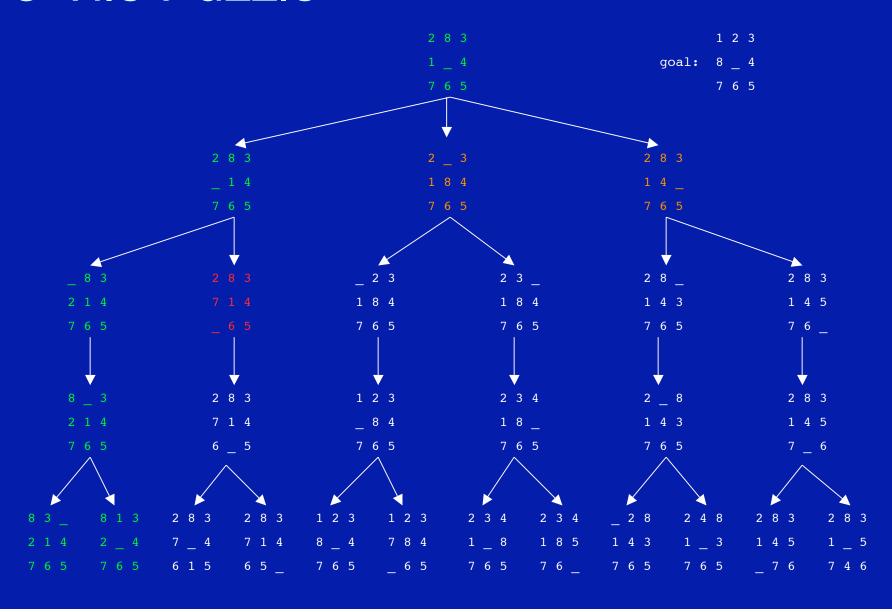


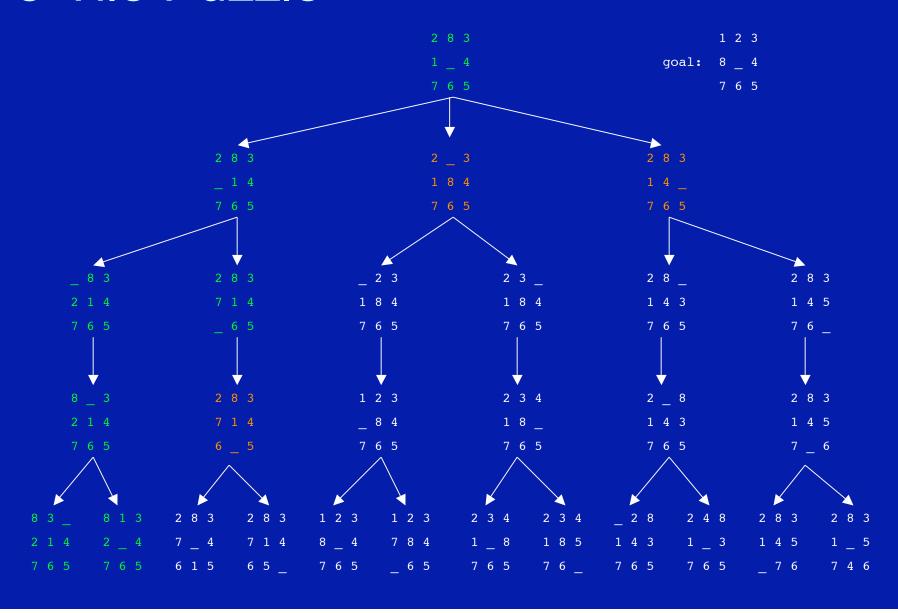


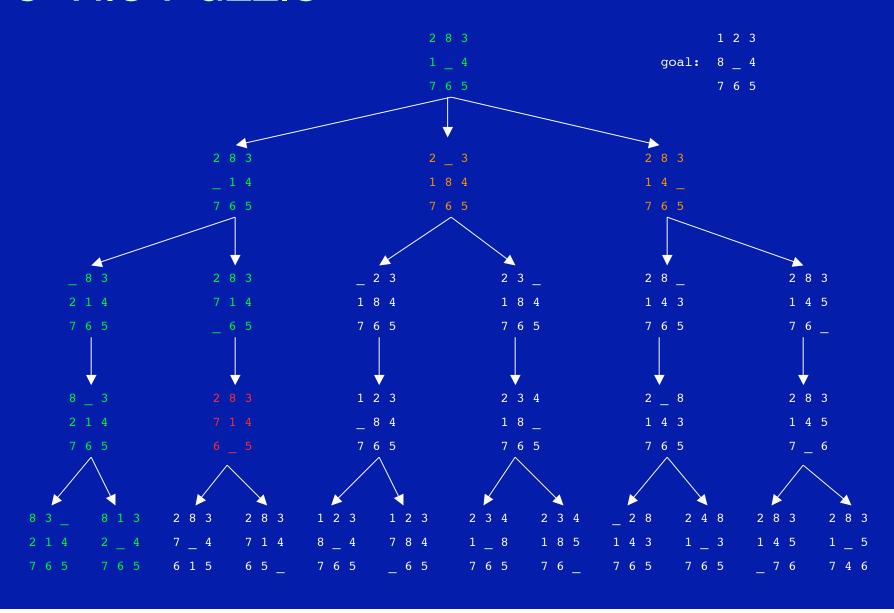


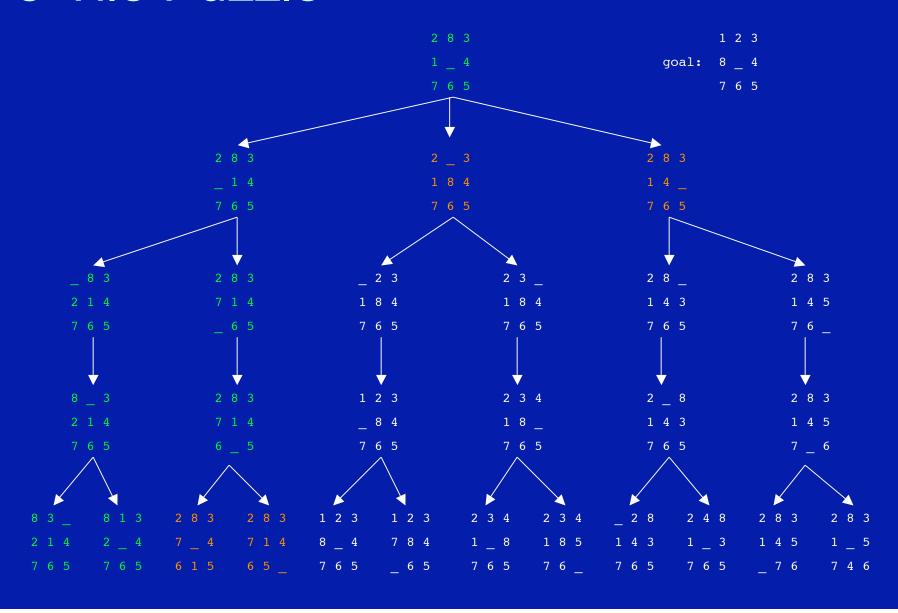


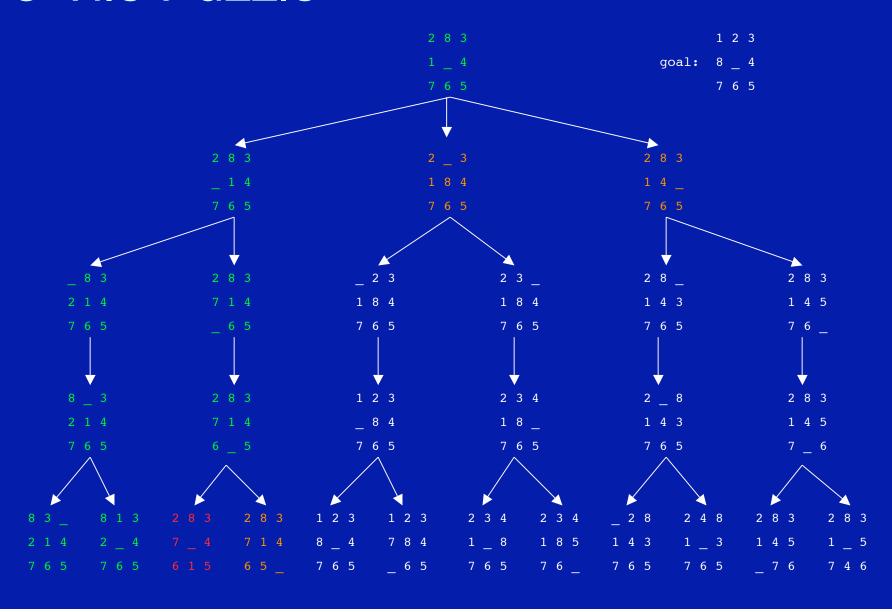


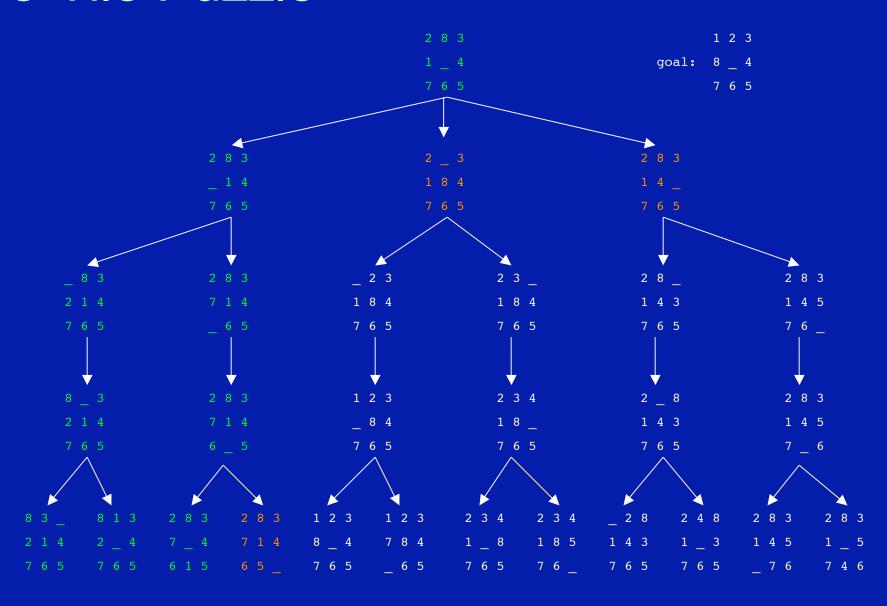


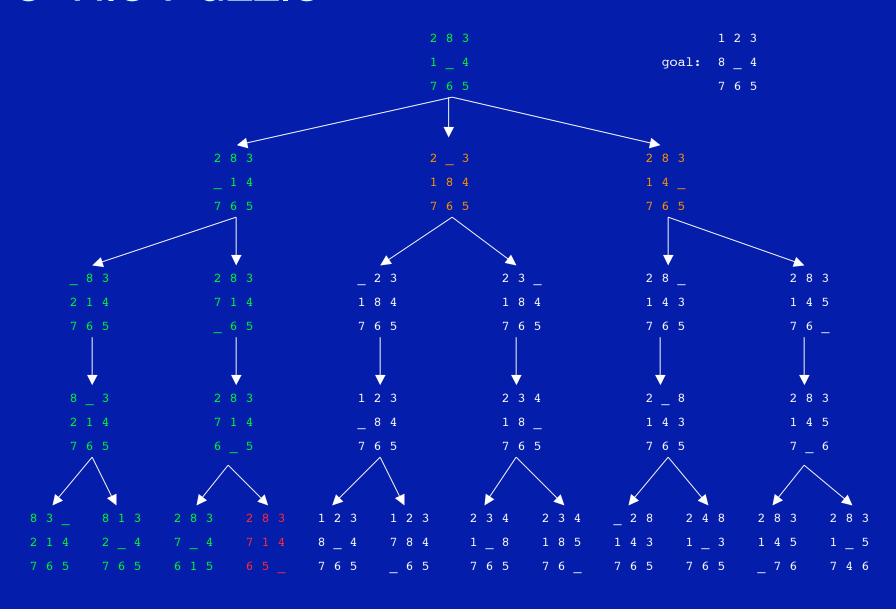


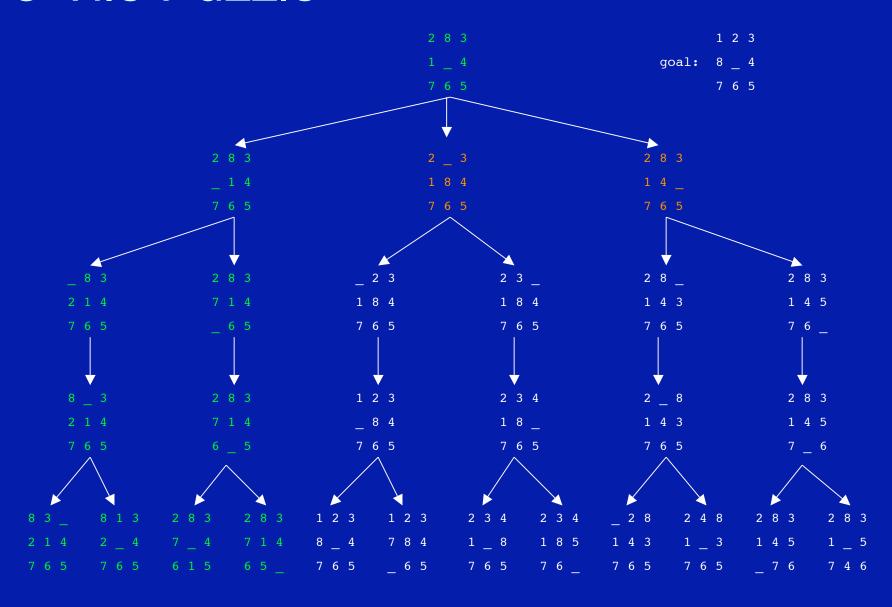


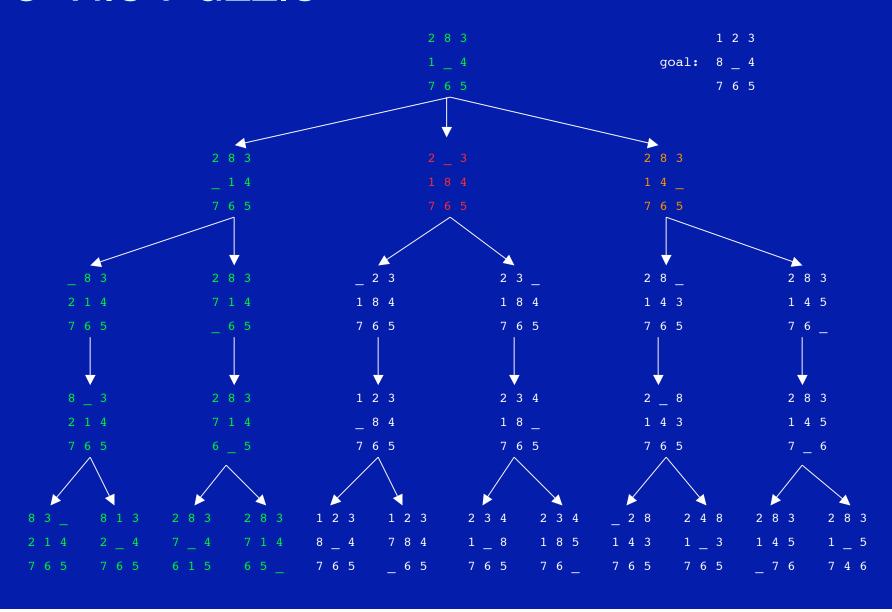


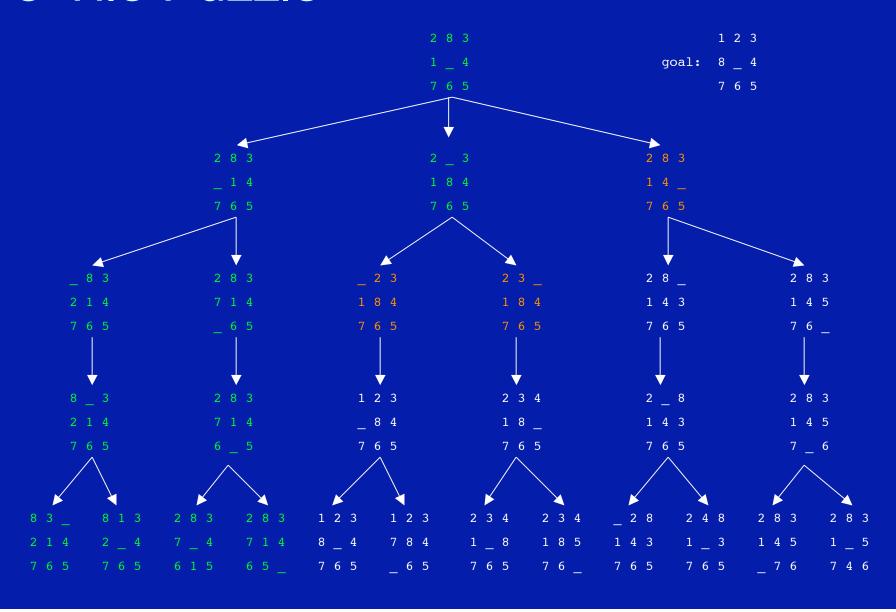


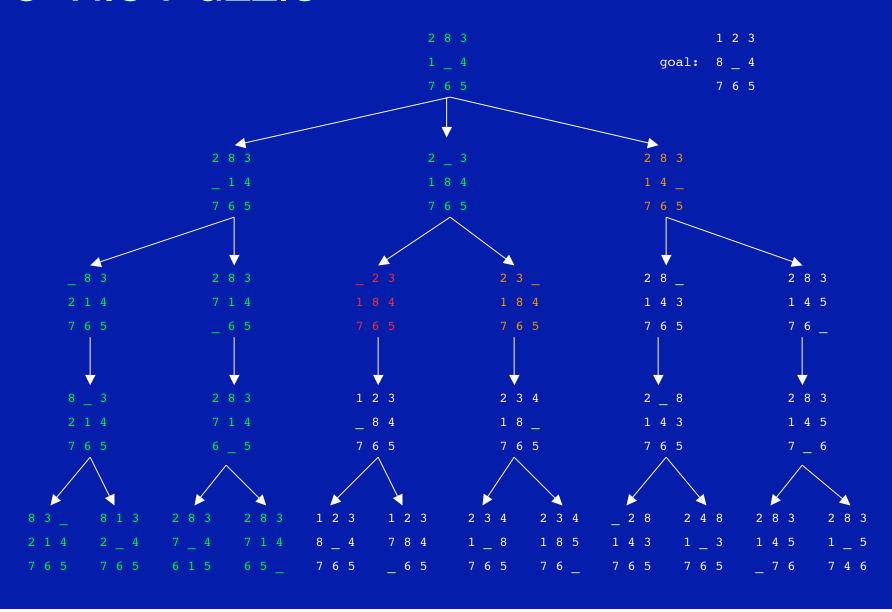


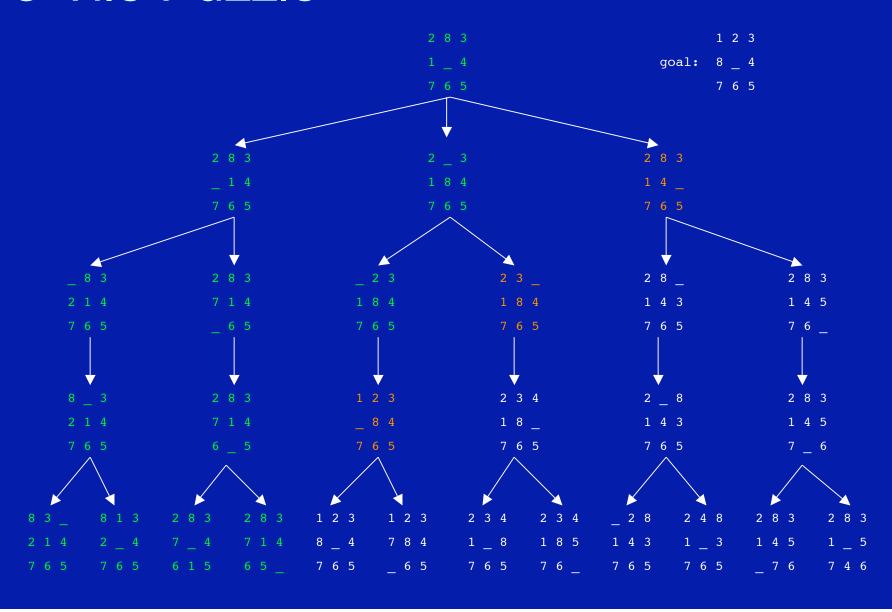


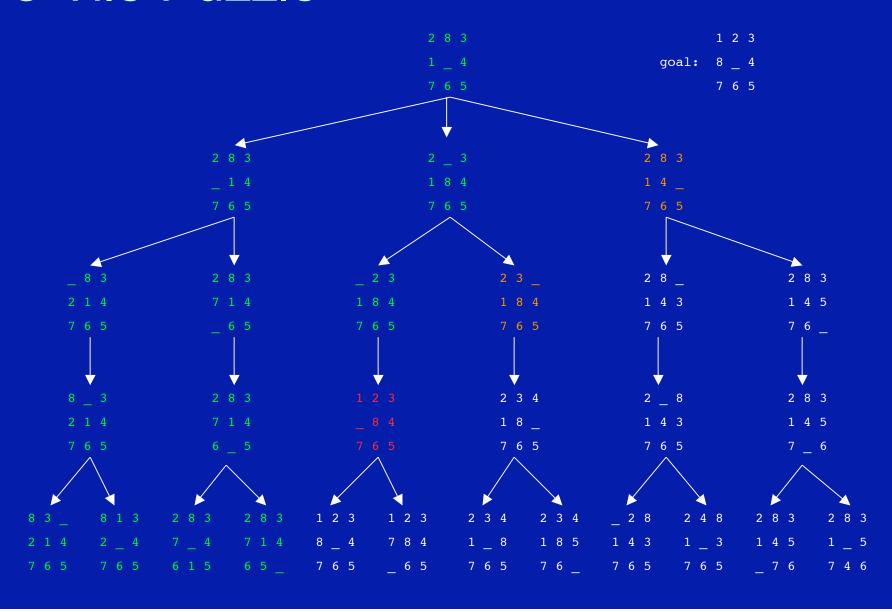


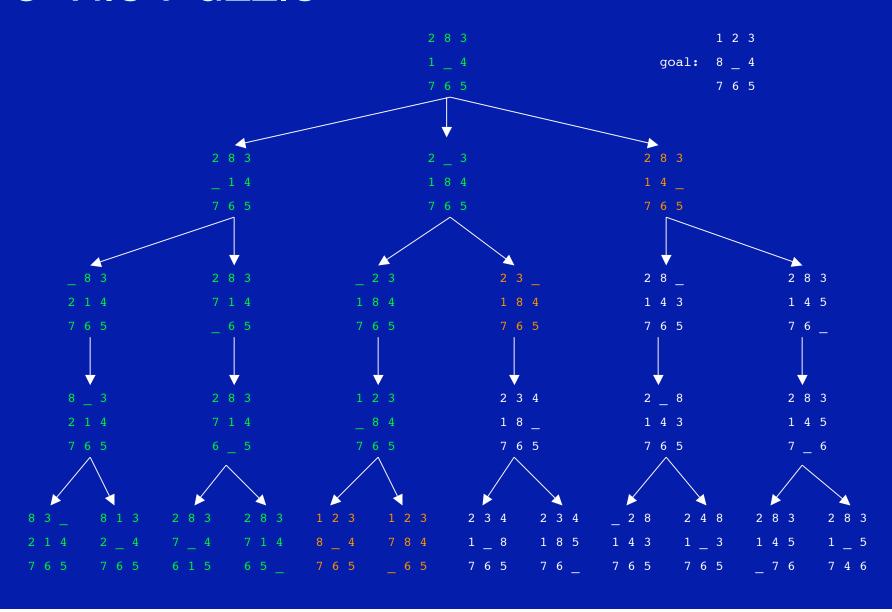


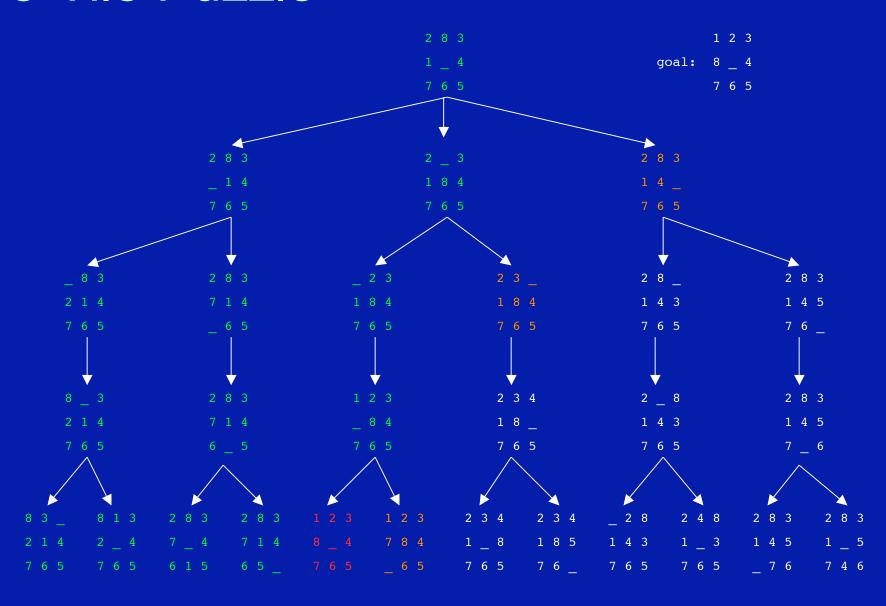












So many things to consider

Is graph search feasible on really big problems?

8-tile puzzle: 9! nodes = 362,880

4.2 days if enter 1 every second

15-tile puzzle: 15! nodes = 1,307,674,368,000

41,466 years...

chess: 10^{120} nodes = a lot!

roughly 10⁷⁹ atoms in universe

you do the math

So many things to consider

Is graph search feasible on really big problems?

Is there an alternative to graph search?

How does the way I choose nodes from the frontier change the search?

Can I use additional information to reduce the amount of search?