

The Immerman-Szelepcsnyi Theorem

Relating NL and co-NL

NL and co-NL

Quick review: See if you can remember

- Definition of co-NP
- A complete problem for co-NP
- A problem in $NP \cap co-NP$

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Can you suggest the following?

- Definition of co-NL
- A complete problem for co-NL
- A problem in $NL \cap co-NL$

NL and co-NL

- It's widely conjectured that $NP \neq co-NP$
- In contrast, $NL = co-NL$!
(Proved independently by Immerman and Szelepcsnyi in 1987)

Immerman-Szelepcsnyi Theorem

- Recall that PATH is complete for NL:
$$\text{PATH} = \{ (G,x,y) \mid y \text{ is reachable from } x \text{ in } G \}$$
- Let NoPATH =
$$\{ (G,x,y) \mid y \text{ is } \textit{not} \text{ reachable from } x \text{ in } G \}$$
- NoPATH is complete for co-NL
- Immerman-Szelepcsnyi: NoPATH is in NL
- Corollary: NL = co-NL

NoPATH = $\{(G,x,y) \mid x \not\Rightarrow y \text{ in } G\}$ is in NL

Notation: for an instance (G,x,y) of NoPATH

- Let the nodes of G be $1, 2, \dots, n$
- Let C_i denote the set of nodes of G that are reachable from x via a path of length at most i
- y is reachable from x if and only if y is in C_{n-1}

NoPATH = $\{(G,x,y) \mid x \not\Rightarrow y \text{ in } G\}$ is in NL

We'll build up to the proof by developing nondeterministic algorithms for several handy checks

- Check0(v,j): is v in C_j?
- Nondeterministic algorithm correctness: Some algorithm execution returns true if the answer is yes, and there is no such execution if the answer is no

NoPATH = $\{(G,x,y) \mid x \not\Rightarrow y \text{ in } G\}$ is in NL

Check0(v,j): is v in C_j ? (v is a node of G, $1 \leq j \leq n-1$)

If $v = x$ Return true

Else

$p = x$

 For $k = 1$ to j

 Nondeterministically choose a node p'

 If ((p,p') is not in G) Return false

 If ($p' = v$) Return true

$p = p'$

 Return false

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We'll build up to the proof by developing nondeterministic algorithms for several handy checks

- Check0(v, j): is v in C_j ?
- Check1(v, j, c_j): is v is *not* in C_j , given that $c_j = |C_j|$?

NoPATH = $\{(G,x,y) \mid x \not\Rightarrow y \text{ in } G\}$ is in NL

Check1(v, j, c_j): is v is *not* in C_j , given that $c_j = |C_j|$?

Idea: find c_j nodes that *are* in C_j , and make sure none is v

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Idea: find c_j nodes that *are* in C_j, and make sure none is v

count = 0 //the number of nodes found in C_j so far

For k = 1 to n

 If (k ≠ v)

 If Check0(k,j) // k is in C_j

 count = count + 1

 If (count = c_j) Return true

Return false

NoPATH = $\{(G,x,y) \mid x \not\Rightarrow y \text{ in } G\}$ is in NL

Check1(v, j, c_j): is v is *not* in C_j , given that $c_j = |C_j|$?

Correctness:

- If v is not in C_j , there is an accepting execution, where on each iteration of the For loop when k is in C_j , Check0(k,j) returns true. In this case, count is incremented exactly c_j times.
- If v is in C_j then there is no accepting execution: count can be incremented at most c_j-1 times and so the algorithm returns false.

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We'll build up to the proof by developing nondeterministic algorithms for several handy checks

- Check0(v, j): is v in C_j ?
- Check1(v, j, c_j): is v is not in C_j given $c_j = |C_j|$?
- Check2(v, j, c_{j-1}): is v is not in C_j given $c_{j-1} = |C_{j-1}|$?
 - Try modifying Check1

NoPATH = $\{(G,x,y) \mid x \not\Rightarrow y \text{ in } G\}$ is in NL

Check2(v, j, c_{j-1}): is v is not in C_j given $c_{j-1} = |C_{j-1}|$?

Idea: find c_{j-1} nodes in C_{j-1} , and make sure there is no edge to v from any of these

NoPATH = $\{(G,x,y) \mid x \not\Rightarrow y \text{ in } G\}$ is in NL

Check2(v, j, c_{j-1}): is v is not in C_j given $c_{j-1} = |C_{j-1}|$?

Idea: find c_{j-1} nodes in C_{j-1} , and make sure there is no edge to v from any of these

count = 0 //the number of nodes found in C_{j-1} so far

For $k = 1$ to n

 If ($k \neq v$)

 If Check0($k, j-1$) // k is in C_{j-1}

 count = count + 1

 If (k, v) is in G , Return false

 If (count = c_{j-1}) Return true

 Return false

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We'll build up to the proof by developing nondeterministic algorithms for several handy checks

- Check0(v, j): is v in C_j ?
- Check1(v, j, c_j): is v is not in C_j given $c_j = |C_j|$?
- Check2(v, j, c_{j-1}): is v is not in C_j given $c_{j-1} = |C_{j-1}|$?
- Check3(j, c_j, c_{j-1}): is $c_j = |C_j|$ given $c_{j-1} = |C_{j-1}|$?

NoPATH = $\{(G, x, y) \mid x \not\Rightarrow y \text{ in } G\}$ is in NL

Check3(j, c_j , c_{j-1}): is $c_j = |C_j|$ given $c_{j-1} = |C_{j-1}|$?

count = 0 //the number of nodes found in C_j so far

For k = 1 to n

 If Check0(k, j)

 count = count + 1

 Else If not Check2(k, j, c_{j-1})

 Return false

 If (count = c_j) Return true

Return false

NoPATH = $\{(G,x,y) \mid x \not\Rightarrow y \text{ in } G\}$ is in NL

Check3(j, c_j, c_{j-1}): is c_j = |C_j| given c_{j-1} = |C_{j-1}|?

Correctness:

- If c_j = |C_j| there is an accepting execution, when exactly c_j of the Check0(v,j) tests return true and the remaining tests to Check2(v, j, c_{j-1}) also return true. On this execution, the for loop terminates and count = c_j
- If c_j ≠ |C_j| either one of the Check2 tests returns false or at the end, count ≠ c_j

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- Check0(v, j): is v in C_j ?
- Check1(v, j, c_j): is v is not in C_j given $c_j = |C_j|$?
- Check2(v, j, c_{j-1}): is v is not in C_j given $c_{j-1} = |C_{j-1}|$?
- Check3(j, c_j, c_{j-1}): is $c_j = |C_j|$ given $c_{j-1} = |C_{j-1}|$?

Let's use these checks to build an algorithm for NoPATH.

NoPATH = $\{(G,x,y) \mid x \not\Rightarrow y \text{ in } G\}$ is in NL

NoPATH(G,x,y)

$c[0] = 1$ //only one node is reachable in 0 steps from x

For $i = 1$ to $n-1$ // calculate c_i

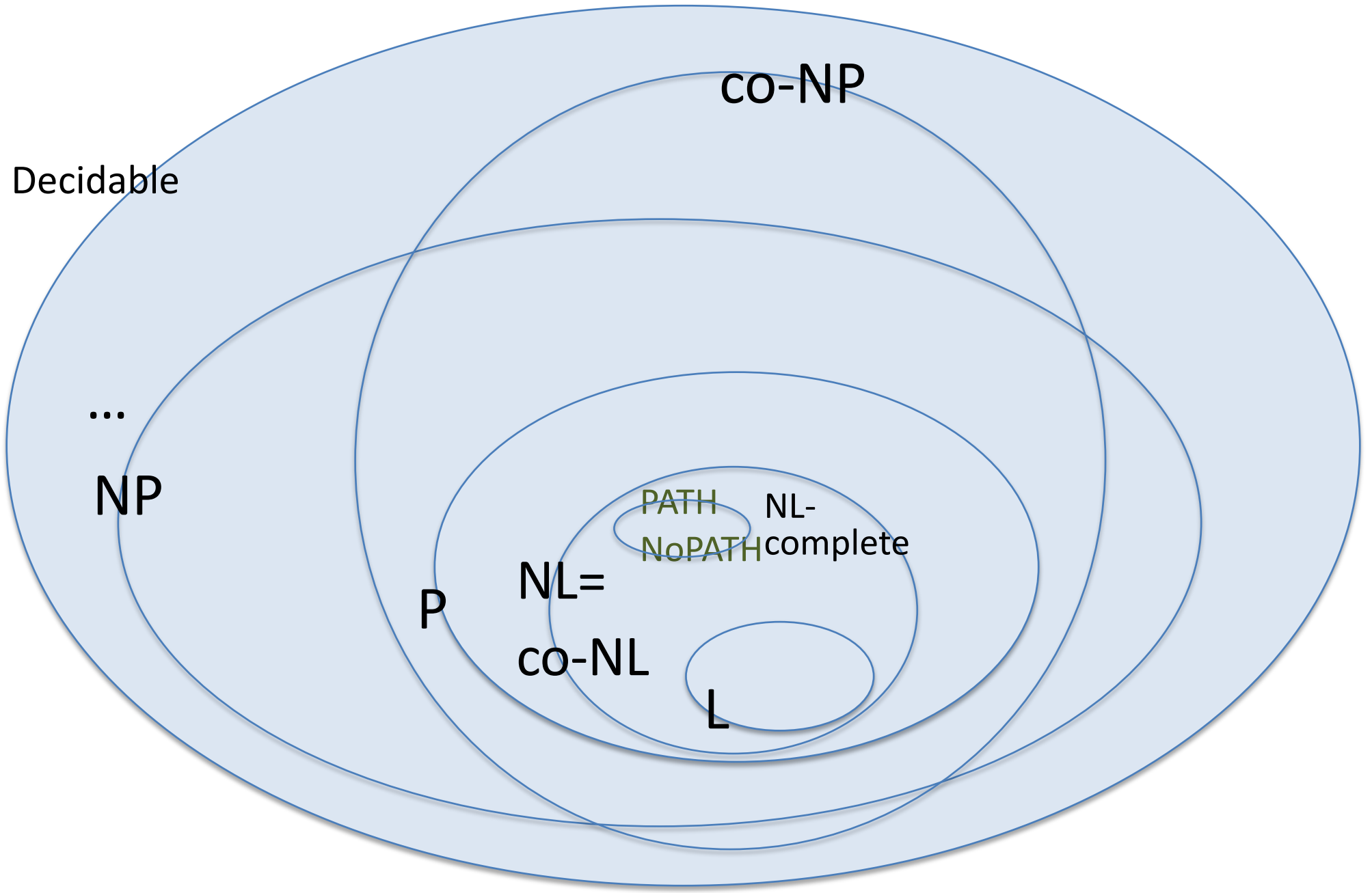
$c_i = 1$

While (not Check3(i, c_i , c_{i-1})) and ($c_i < n$)

$c_i = c_i + 1$

If Check1(y,n-1, c_{n-1}) Return true

Return false



co-NP

Decidable

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NP

PATH NL-
NoPATHcomplete

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NL=

co-NL

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Next Class

- Introduction to Randomized Complexity Classes
- Reading: Arora-Barak 7.1-7.3