

Introduction to Artificial Intelligence (AI)

Computer Science cpsc502, Lecture 7

Oct, 4, 2011

Today Oct 4

Finish R&R systems in deterministic environments

- Logics
 - Reasoning with individuals and relations
 - Full Propositional Logics and First-Order Logics
- **Start R&R systems in Stochastic environments**
 - Bayesian Networks Representation



R&Rsys we'll cover in this course

Environment

Deterministic

Stochastic

Problem

Constraint Satisfaction

Vars + Constraints

Arc Consistency SLS

Search

Static

Query

Logics

Propositional
First Order

Search

Belief Nets

Var. Elimination

Approx. Inference

Temporal. Inference

Sequential

Planning

STRIPS

*actions
precs
effects*

Search

Decision Nets

Var. Elimination

Markov Processes

Value Iteration

Representation

Reasoning
Technique

Logics: Big Picture

First Order Logic

$$\forall X \exists Y p(X, Y) \Leftrightarrow \neg q(Y)$$

$$p(a_1, a_2)$$
$$\neg q(a_5)$$

Propositional Logic

$$\neg (p \vee q) \rightarrow (r \wedge s \wedge t),$$

p, r

Datalog

$$p(X) \leftarrow q(X) \wedge r(X, Y)$$

$$r(X, Y) \leftarrow s(Y)$$

$$s(a_1), q(a_2)$$

PDCL

$$p \leftarrow s \wedge t$$

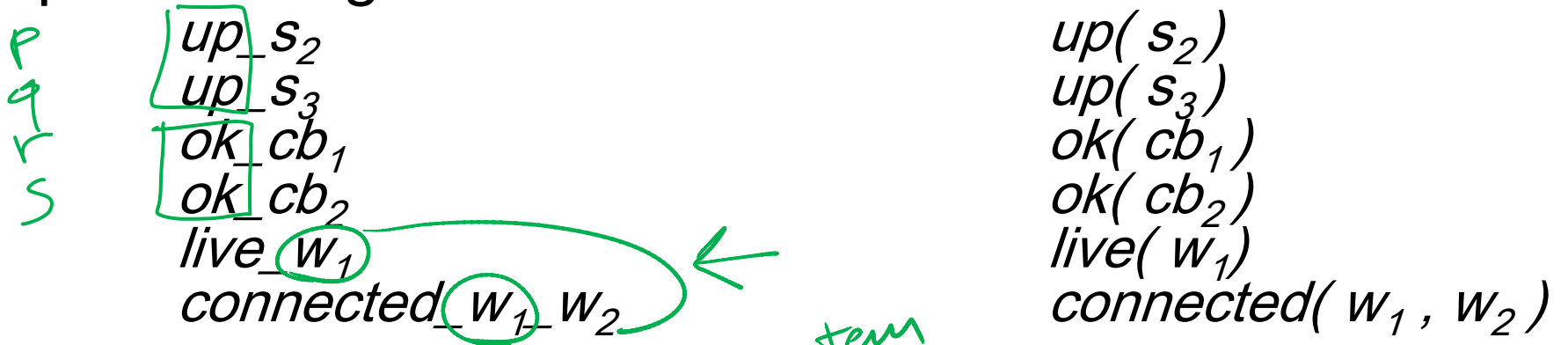
$$r \leftarrow s \wedge q \wedge p$$

p, r

Representation and Reasoning in Complex domains

- In complex domains expressing knowledge with **propositions** can be quite limiting

- It is often **natural** to consider **individuals** and their **properties**



There is no notion that

up_s_2
 up_s_3

up are about the same property

the system can reason about

$live_w_1$
 $connected_w_1_w_2$

w1 are about the same individual

What do we gain....

By breaking propositions into relations applied to individuals?

- Express **knowledge** that holds for set of individuals (by introducing **variables**)

$$\mathit{live}(W) \leftarrow \mathit{connected_to}(W, W1) \wedge \mathit{live}(W1) \wedge \mathit{wire}(W) \wedge \mathit{wire}(W1).$$

- We can ask **generic queries** (i.e., containing **variables**)

$$? \mathit{connected_to}(W, w_1)$$

Datalog: a relational rule language

It expands the syntax of PDCL....

A **variable** is a symbol starting with an upper case letter

X Y

A **constant** is a symbol starting with lower-case letter or a sequence of digits.

alan w1

A **term** is either a variable or a constant.

A **predicate symbol** is a symbol starting with lower-case letter.

in part-of live

Datalog Syntax (cont')

so it includes propositions

An **atom** is a symbol of the form p or $p(t_1 \dots t_n)$ where p is a predicate symbol and t_i are terms

sunny

in(alan, X)

A **definite clause** is either an atom (a fact) or of the form:

$$h \leftarrow b_1 \wedge \dots \wedge b_m$$

where h and the b_i are atoms (Read this as "h if b.")

$$\text{in}(X, Y) \leftarrow \text{in}(X, Z) \wedge \text{part_of}(Z, Y)$$

A **knowledge base** is a set of definite clauses

Datalog: Top Down Proof

Extension of TD for PDCL.

How do you deal with variables?

Example:

KB {
in(alan, r123).
part_of(r123, cs_building).
in(X, Y) <- part_of(Z, Y) & in(X, Z).

Query: in(alan, cs_building).

yes <- in(alan, cs_building).

yes ← part-of(Z, cs bldg) ∧ in(alan, Z)

Datalog: queries with variables

`in(alan, r123).`

`part_of(r123, cs_building).`

`in(X, Y) <- in(X, Z). & part_of(Z, Y)`

Query: `in(alan, X1).`

`Yes(X1) <- in(alan, X1).`

one answer
yes(r123)

`yes(x1) <- in(alan, z) & part_of(z, x1)`

.....

.....
`yes(cs_building)`

Logics: Big Picture

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p, r

Datalog

$$p(X) \leftarrow q(X) \wedge r(X, Y)$$

$$r(X, Y) \leftarrow s(Y)$$

$$s(a_1), q(a_2)$$

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$$p \leftarrow s \wedge t$$

$$r \leftarrow s \wedge q \wedge p$$

p, r

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Full Propositional Logics

DEFs.

Literal: an atom or a negation of an atom $P \quad \neg q \quad r$

Clause: is a disjunction of literals $p \vee \neg r \vee q$

Conjunctive Normal Form (CNF): a conjunction of clauses

INFERENCE: $KB \stackrel{?}{\models} \alpha$ \leftarrow formula $(P) \wedge (q \vee \neg r) \wedge (\neg q \vee p)$

- Convert all formulas in KB and $\neg \alpha$ in CNF
- Apply **Resolution Procedure** (at each step combine two clauses containing complementary literals into a new one) $p \vee q \quad r \vee \neg q \rightarrow p \vee r$

Termination

- No new clause can be added $KB \not\models \alpha$
- Two clause resolve into an empty clause $KB \models \alpha$

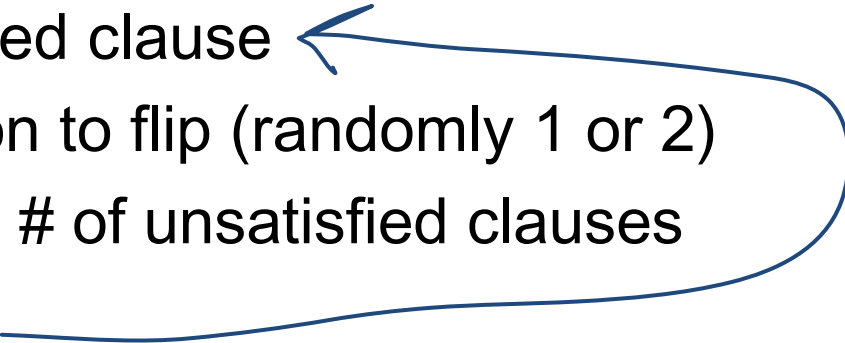
Propositional Logics: Satisfiability (SAT problem)

Does a set of formulas have a model? Is there an interpretation in which all the formulas are true?

(Stochastic) Local Search Algorithms can be used for this task!

Evaluation Function: number of unsatisfied clauses

WalkSat: One of the simplest and most effective algorithms:
Start from a randomly generated interpretation

- Pick an unsatisfied clause
 - Pick a proposition to flip (randomly 1 or 2)
 1. To minimize # of unsatisfied clauses
 2. Randomly
- 

Full First-Order Logics (FOLs)

We have **constant symbols**, **predicate symbols** and **function symbols**

So **interpretations** are much more complex (but the same basic idea – one possible configuration of the world)

constant symbols => individuals, entities

predicate symbols => relations

function symbols => functions

INFERENCE:

- **Semidecidable:** algorithms exists that says yes for every entailed formulas, but no algorithm exists that also says no for every non-entailed sentence
- **Resolution Procedure** can be generalized to FOL

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	<p>Arc Consistency</p> <p>SLS</p> <p><i>Vars + Constraints</i></p> <p>Search</p>	
	<p>Logics</p> <p>→ Propositional</p> <p>→ First Order</p> <p>→</p> <p>Search</p>	<p>Belief Nets</p> <p>Var. Elimination</p> <p>Approx. Inference</p> <p>Temporal. Inference</p>
	<p><u>STRIPS</u></p> <p>actions precs effects</p> <p>Search</p>	<p>Decision Nets</p> <p>Var. Elimination</p> <p>Markov Processes</p> <p>Value Iteration</p>

influence diagrams

Intro to Probability (Motivation)

- Will it rain in 10 days? Was it raining 98 days ago?
- Right now, how many people are in this building (DMP)? At UBC? Yesterday?
- AI agents (and humans ☹️) are not omniscient (*know everything*)
they are ignorant
- And the problem is not only predicting the future or “remembering” the past
also current state

Intro to Probability (Key points)

- Are agents all ignorant/uncertain to the same degree? ^{NO}
it is subjective
- Should an agent act only when it is certain about relevant knowledge?
- (not acting usually has implications) ←
- So agents need to represent and reason about their ignorance/ uncertainty

Probability as a formal measure of uncertainty/ignorance

- Belief in a proposition f (e.g., *it is snowing outside, there are 321 people in this bldg*) can be measured in terms of a number between 0 and 1 – this is the probability of f
 - The probability f is 0 means that f is believed to be **definitely false**
 - The probability f is 1 means that f is believed to be **definitely true**
 - Using 0 and 1 is purely a convention.

Random Variables

- A **random variable** is a **variable** like the ones we have seen in **CSP** and **Planning**, but the agent can be **uncertain about its value**.
- As usual
 - The **domain** of a random variable X , written $dom(X)$, is the set of values X can take
 - values are mutually exclusive and exhaustive

Examples (Boolean and discrete)

outside Raining
T F

#-of-people-in-DMP
[0-10⁴]

Random Variables (cont')

- A tuple of random variables $\langle X_1, \dots, X_n \rangle$ is a **complex random variable** with domain..

$$\text{dom}(X_1) \times \dots \times \text{dom}(X_n)$$

- **Assignment** $X=x$ means X has value x

$$\text{outside Raining} = T$$

- A **proposition** is a Boolean formula made from assignments of values to variables

Examples

$$\text{outside Raining} = T \quad \overset{\text{OR}}{\vee} \quad \# \text{people-rm} = 47$$

AND

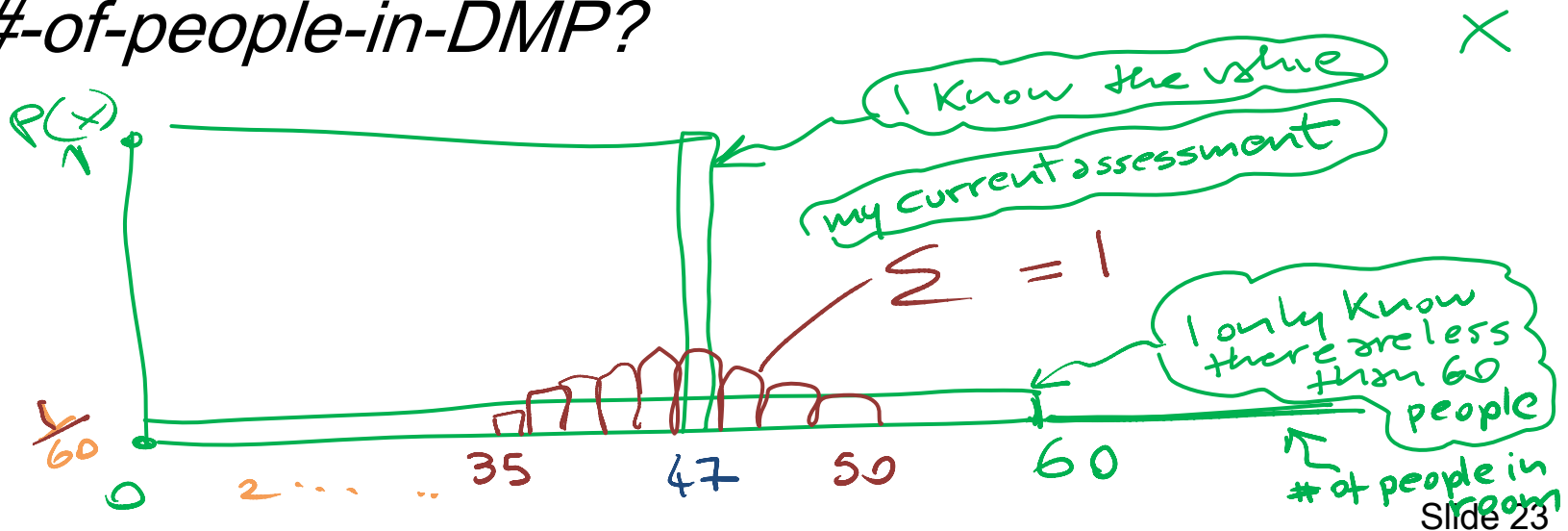
Probability Distributions

- A probability distribution P on a random variable X is a function $dom(X) \rightarrow [0,1]$ such that $x \rightarrow P(X=x)$

$$dom(cavity) = [T, F]$$

cavity? $\begin{matrix} \nearrow T \rightarrow .2 & P(cavity=T) \\ \searrow F \rightarrow .8 & P(cavity=F) \end{matrix}$

#-of-people-in-DMP?



Joint Probability Distributions $P(\langle X_1, \dots, X_n \rangle)$

- Probability distribution over the variable Cartesian product of multiple random variables
 - Think of a joint distribution over n variables as an n -dimensional table
 - Each entry, indexed by $X_1 = x_1, \dots, X_n = x_n$ corresponds to $P(X_1 = x_1 \wedge \dots \wedge X_n = x_n)$
 - The sum of entries across the whole table is 1

	<i>toothache</i>		\neg <i>toothache</i>	
	<i>catch</i>	\neg <i>catch</i>	<i>catch</i>	\neg <i>catch</i>
<i>cavity</i>	.108	.012	.072	.008
\neg <i>cavity</i>	.016	.064	.144	.576

<i>cavity</i>	<i>toothache</i>	<i>catch</i>	$\mu(w)$
T	T	T	.108
T	T	F	.012
T	F	T	.072
T	F	F	.008
F	T	T	.016
F	T	F	.064
F	F	T	.144
F	F	F	.576

for n Boolean vars

24

entries

Joint Prob. Distribution (JPD): Example2

3 binary random variables: $P(H,S,F)$

H=true *H=false*

- **H** $\text{dom}(H)=\{h, \neg h\}$ has heart disease, does not have...
- **S** $\text{dom}(S)=\{s, \neg s\}$ smokes, does not smoke
- **F** $\text{dom}(F)=\{f, \neg f\}$ high fat diet, low fat diet

		f		\neg f	
		s	\neg s	s	\neg s
\rightarrow h	.015	.007	.005	.003	
\rightarrow \neg h	.21	.51	.07	.18	

2³-1 *2^k-1* $\sum 1$

Marginalization

$P(H, S, F)$

	<u>f</u>	
	s	\neg s
h	.015	.007
\neg h	.21	.51

	<u>\negf</u>	
	s	\neg s
h	.005	.003
\neg h	.07	.18

$$P(H, S) = \sum_{x \in \text{dom}(F)} P(H, S, F = x)$$

$P(H, S)?$ \rightarrow

	s	\neg s	
h	.02	.01	.03
\neg h	.28	.69	.97
$P(S)$.3	.7	

$P(H)$

Conditional Probability

$P(H,S)$	s	\neg s	$P(H)$
h	.02	.01	.03
\neg h	.28	.69	.97
$P(S)$.30	.70	

$$P(S | H) = \frac{P(S, H)}{P(H)}$$

$$P(s | \neg h) = \frac{P(s, \neg h)}{P(\neg h)}$$

Two probability distributions for S

$P(S H)$	s	\neg s	
h	.666	.333	$\sum 1$
\neg h	.29	.71	$\sum 1$

$P(H|S)$
do this as an exercise

Recap Conditional Probability (cont.)

$$P(S|H) = \frac{P(S, H)}{P(H)}$$

$$P(S|H, F)$$

$$P(X_1 \dots X_n | Y_1 \dots Y_k)$$

binary

- It is not a probability distributions but.....

set of
prob. distrib.

- One for each configuration of the conditioning var(s)

if conditioned
by k binary vars,

set 2^k prob. distributions

Chain Rule

$$\underline{P(H, S, F)} = P(H) * P(S|H) * P(F|H, S)$$
$$\downarrow$$
$$\cancel{P(H)} * \frac{P(S, H)}{\cancel{P(H)}} * \frac{P(F, H, S)}{\cancel{P(H, S)}}$$

Bayes Theorem

$$P(S | H) = \frac{P(S, H)}{P(H)}$$

$$P(H | S) = \frac{P(S, H)}{P(S)}$$

Substitute

↓ rewrite

$$P(H | S) P(S) = \underline{P(S, H)}$$

$$P(S | H) = \frac{P(H | S) P(S)}{P(H)}$$

Do you always need to revise your beliefs?

NO when your knowledge of **Y**'s value doesn't affect your belief in the value of **X**

DEF. Random variable **X** is **marginal independent** of random variable **Y** if, for all $x_i \in \text{dom}(X)$, $y_k \in \text{dom}(Y)$,

$$P(X= x_i \mid Y= y_k) = P(X= x_i)$$

Marginal Independence: Example

X and Y are independent iff: $P(X) = P(X|Y) = \frac{P(X, Y)}{P(Y)}$

$P(X|Y) = P(X)$ or $P(Y|X) = P(Y)$ or $P(X, Y) = P(X) P(Y)$

That is new evidence Y (or X) does not affect current belief in X (or Y)

Ex: $P(\text{Toothache}, \text{Catch}, \text{Cavity}, \text{Weather})$
 $= P(\text{Toothache}, \text{Catch}, \text{Cavity}) P(\text{weather})$

4 possible values: Sunny, Cloudy, Rainy, Snowy

JPD requiring 32 entries is reduced to two smaller ones (8 and 4)

Joint prob. distribution

Conditional Independence

With marg. Independence, for n independent random vars, $O(2^n) \rightarrow O(n)$

$$P(x_1, \dots, x_n) = P(x_1) \times \dots \times P(x_n)$$

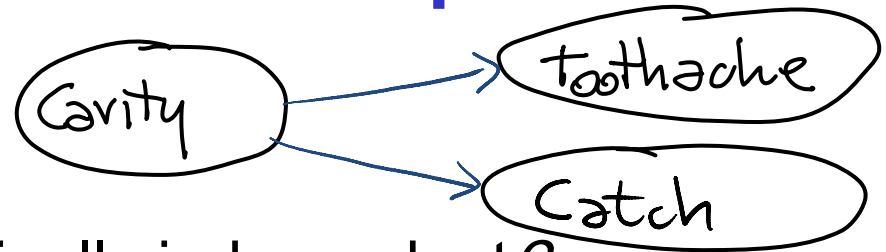
Absolute independence is powerful **but** when you model a **particular domain**, it is **rare**

Dentistry is a large field with hundreds of variables, few of which are independent (e.g., *Cavity*, *Heart-disease*).

What to do?

Look for weaker form of independence

$P(\textit{Toothache}, \textit{Cavity}, \textit{Catch})$



Are *Toothache* and *Catch* marginally independent?

$$P(\downarrow \mid \downarrow) = P(\textit{Toothache}) ?$$

BUT If I have a cavity, does the probability that the probe catches depend on whether I have a toothache?

$$(1) P(\textit{catch} \mid \textit{toothache}, \textit{cavity}) = P(\textit{catch} \mid \textit{cavity})$$

What if I haven't got a cavity?

$$(2) P(\textit{catch} \mid \textit{toothache}, \neg \textit{cavity}) = P(\textit{catch} \mid \neg \textit{cavity})$$

STOP HERE 04/10/11

- Each is directly caused by the cavity, but neither has a direct effect on the other

Conditional independence

In general, *Catch* is conditionally independent of *Toothache* given *Cavity*.

① $P(\text{Catch} / \text{Toothache}, \text{Cavity}) = P(\text{Catch} / \text{Cavity})$

Equivalent statements:

② $P(\text{Toothache} / \text{Catch}, \text{Cavity}) = P(\text{Toothache} / \text{Cavity})$

③ $P(\text{Toothache}, \text{Catch} / \text{Cavity}) = \frac{P(\text{Toothache} / \text{Cavity}) P(\text{Catch} / \text{Cavity})}{P(\text{Cavity})}$

$$P(x, y | z) = P(x | z) P(y | z)$$

Proof of equivalent statements

①

if

$$P(X|YZ) = P(X|Z) \Rightarrow$$

$$\Rightarrow \textcircled{A} \frac{P(X, Y, Z)}{P(Y, Z)} = \frac{P(X, Z)}{P(Z)} \Rightarrow \textcircled{2}$$

$$\Rightarrow \frac{P(X, Y, Z)}{P(X, Z)} = \frac{P(Y, Z)}{P(Z)} \Rightarrow P(Y|X, Z) = P(Y|Z)$$

$$\begin{aligned} \textcircled{3} P(X, Y|Z) &= \frac{P(X, Y, Z)}{P(Z)} \stackrel{\text{from A}}{\Rightarrow} \frac{P(Y, Z) P(X, Z)}{P(Z)} \cdot \frac{1}{P(Z)} \\ &= \frac{P(Y, Z)}{P(Z)} \cdot \frac{P(X, Z)}{P(Z)} = P(Y|Z) \cdot P(X|Z) \end{aligned}$$

Conditional Independence: Formal Def.

Sometimes, two variables might not be marginally independent. However, they *become* independent after we observe some third variable

DEF. Random variable \mathbf{X} is **conditionally independent** of random variable \mathbf{Y} given random variable \mathbf{Z} if, for all $x_i \in \text{dom}(X)$, $y_k \in \text{dom}(Y)$, $z_m \in \text{dom}(Z)$

$$P(X = x_i \mid Y = y_k, Z = z_m) = P(X = x_i \mid Z = z_m)$$

That is, knowledge of \mathbf{Y} 's value doesn't affect your belief in the value of \mathbf{X} , given a value of \mathbf{Z}

Conditional independence: Use

Write out full joint distribution using **chain rule**:

$$\begin{aligned} & \mathbf{P(Cavity, Catch, Toothache)} \\ &= \mathbf{P(Toothache \mid Catch, Cavity) P(Catch \mid Cavity) P(Cavity)} \\ &= \mathbf{P(Toothache \mid Cavity) P(Catch \mid Cavity) P(Cavity)} \end{aligned}$$

Handwritten annotations: A blue box encloses the first two lines. A blue arrow points from the first line to the second. A blue bracket under the second line is labeled '2'. A blue arrow points from the second line to the expression $2^3 - 1 = 7$. A blue arrow points from the third line to the expression $2 + 2 + 1 = 5$. A blue arrow points from the first term of the second line to the expression $2^3 - 1 = 7$. A blue arrow points from the second term of the second line to the expression 2 . A blue arrow points from the third term of the second line to the expression 1 .

how many probabilities? $2^3 - 1 = 7$

$$2 + 2 + 1 = 5$$

The use of conditional independence often **reduces the size** of the representation of the joint distribution from **exponential in n** to **linear in n** . n is the number of vars

Conditional independence is our **most basic** and **robust** form of **knowledge** about **uncertain environments**.

Key points Recap

- We model the environment as a set of random vars

$$X_1 \dots X_n \quad \text{JPD} \quad P(X_1 \dots X_n)$$

- Why the joint is not an adequate representation ?

“Representation, reasoning and learning” are
“exponential” in the number of variables

Solution: Exploit marginal & conditional independence

$$P(x|Y) = P(x) \quad P(x|YZ) = P(x|Z)$$

But how does independence allow us to simplify the joint?

CHAIN RULE!

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Belief Nets: Burglary Example

There might be a **burglar** in my house

B

The **anti-burglar alarm** in my house may go off

A

I have an agreement with two of my neighbors, **John** and **Mary**, that they **call** me if they hear the alarm go off when I am at work

M

J

Minor earthquakes may occur and sometimes they set off the alarm.

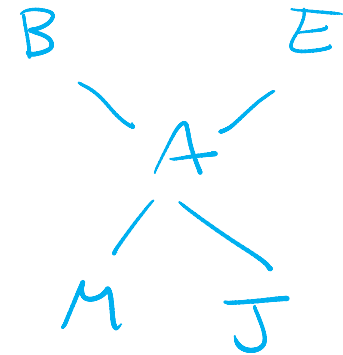
E

Variables: B A M J E $n = 5$

Joint has $2^5 - 1$ entries/probs $2^n - 1$

Belief Nets: Simplify the joint

- Typically order vars to reflect causal knowledge (i.e., causes *before* effects)
 - A burglar (B) can set the alarm (A) off
 - An earthquake (E) can set the alarm (A) off
 - The alarm can cause Mary to call (M)
 - The alarm can cause John to call (J)



$$P(B, E, A, M, J)$$

- Apply Chain Rule *marginal indep.*

$$\underbrace{P(B)} \quad \underbrace{P(E|B)} \quad \underbrace{P(A|B,E)} \quad \underbrace{P(M|A,E)} \quad \underbrace{P(J|A,E)}$$

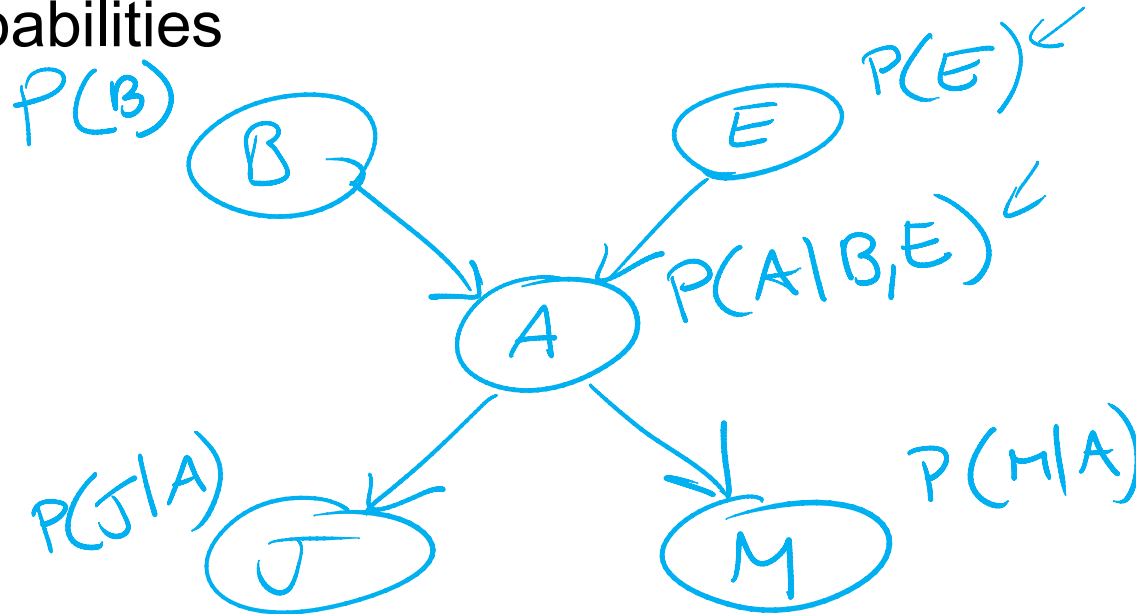
conditional indep.

- Simplify according to marginal & conditional independence

Belief Nets: Structure + Probs

$$\rightarrow P(B) * P(E) * \underline{P(A|B,E)} * \underline{P(M|A)} * P(J|A)$$

- Express remaining dependencies as a network
 - Each var is a node
 - For each var, the conditioning vars are its parents
 - Associate to each node corresponding conditional probabilities



- Directed Acyclic Graph (DAG)

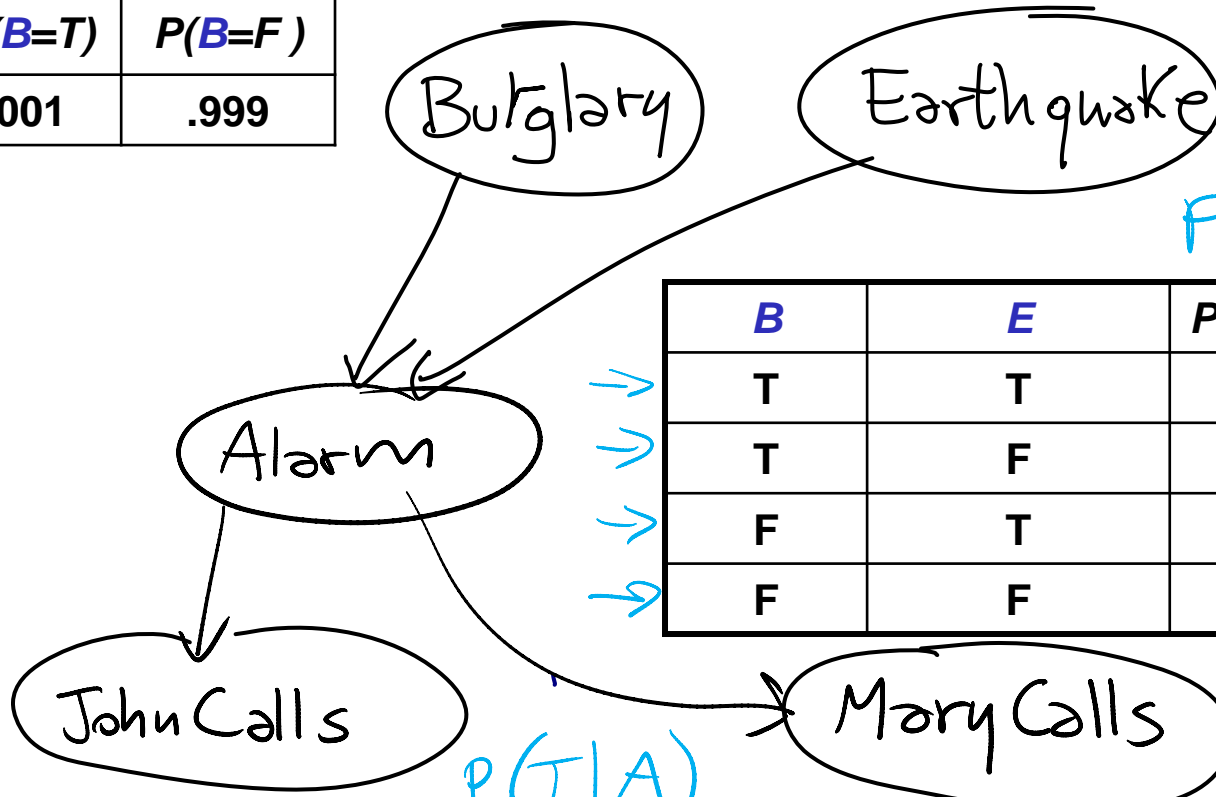
$P(B) \leftarrow$

Burglary: complete BN

$P(E) \leftarrow$

$P(B=T)$	$P(B=F)$
.001	.999

$P(E=T)$	$P(E=F)$
.002	.998



$P(A|B,E)$

B	E	$P(A=T B,E)$	$P(A=F B,E)$
T	T	.95	.05
T	F	.94	.06
F	T	.29	.71
F	F	.001	.999

$P(J|A)$

A	$P(J=T A)$	$P(J=F A)$
T	.90	.10
F	.05	.95

$P(M|A)$

A	$P(M=T A)$	$P(M=F A)$
T	.70	.30
F	.01	.99

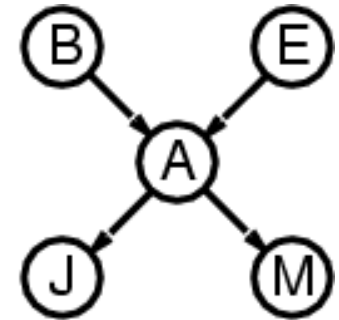
call for any other reasons

Burglary Example: Bnets inference

Our BN can answer any probabilistic query that can be answered by processing the joint!

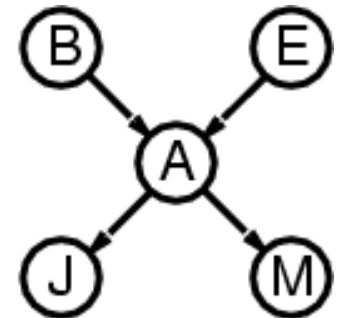
(Ex1) I'm at work,

- • neighbor John calls to say my alarm is ringing,
- • neighbor Mary doesn't call.
- • No news of any earthquakes.
- Is there a burglar?



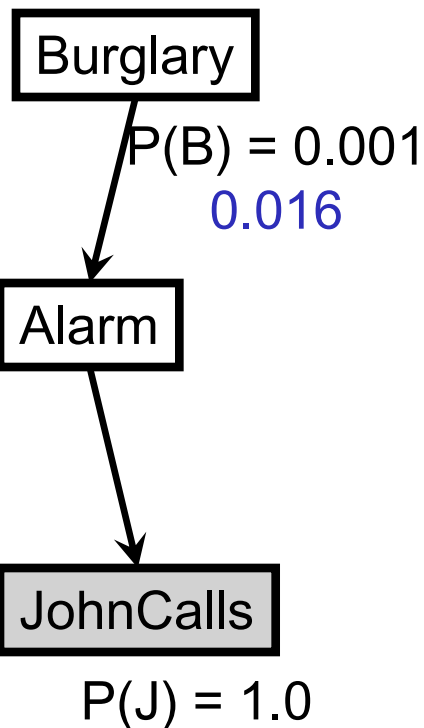
(Ex2) I'm at work,

- Receive message that neighbor John called ,
- News of minor earthquakes.
- Is there a burglar?

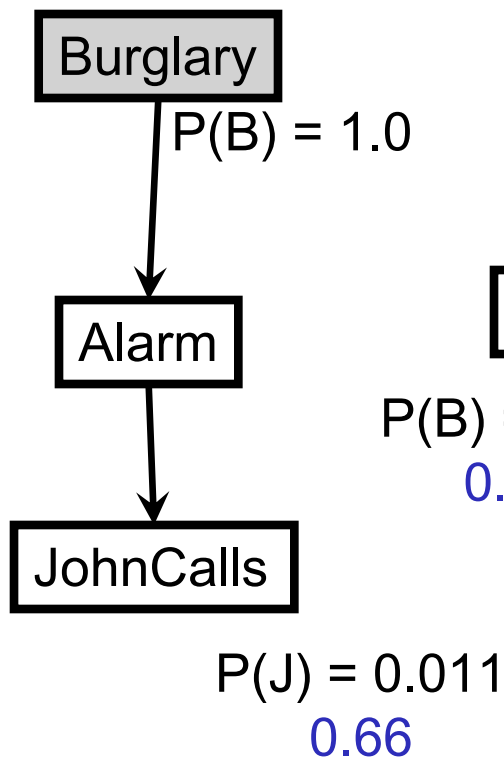


Bayesian Networks – Inference Types

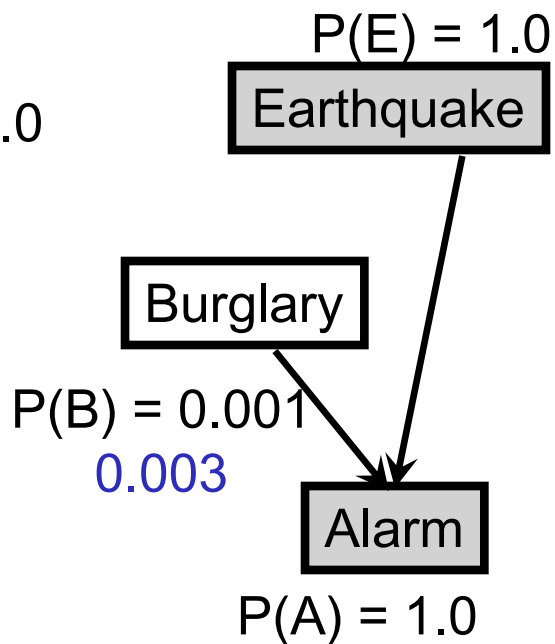
Diagnostic



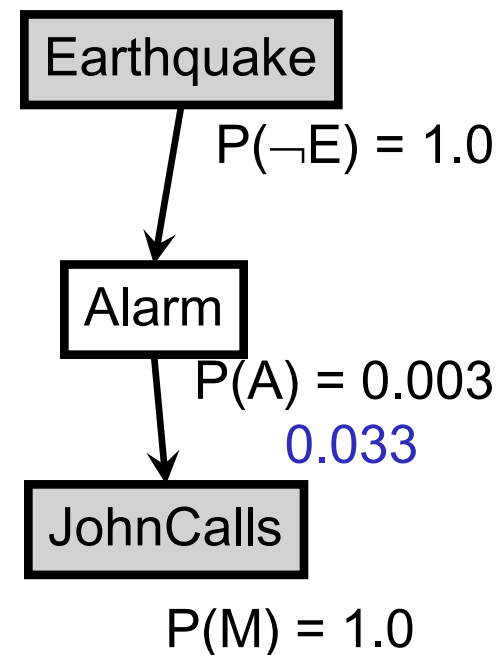
Predictive



Intercausal



Mixed



BNnets: Compactness

$P(B=T)$	$P(B=F)$
.001	.999

1

$P(E=T)$	$P(E=F)$
.002	.998

1

Burglary

Earthquake

Alarm

B	E	$P(A=T B,E)$	$P(A=F B,E)$
T	T	.95	.05
T	F	.94	.06
F	T	.29	.71
F	F	.001	.999

4

John Calls

Mary Calls

A	$P(J=T A)$	$P(J=F A)$
T	.90	.10
F	.05	.95

2

A	$P(M=T A)$	$P(M=F A)$
T	.70	.30
F	.01	.99

2

BNet

$$2 + 2 + 4 + 1 + 1 = 10$$

$$|JPD| = 2^5 - 1$$

BNets: Compactness

Conditional
Probability
Table



In General:

A **CPT** for boolean X_i with k boolean parents has 2^k rows for the combinations of parent values

Each row requires one number p_i for $X_i = \text{true}$ (the number for $X_i = \text{false}$ is just $1-p_i$)

If each on the n variable has no more than k parents, the complete network requires $O(n 2^k)$ numbers

For $k \ll n$, this is a substantial improvement,

- the numbers required grow linearly with n , vs. $O(2^n)$ for the full joint distribution

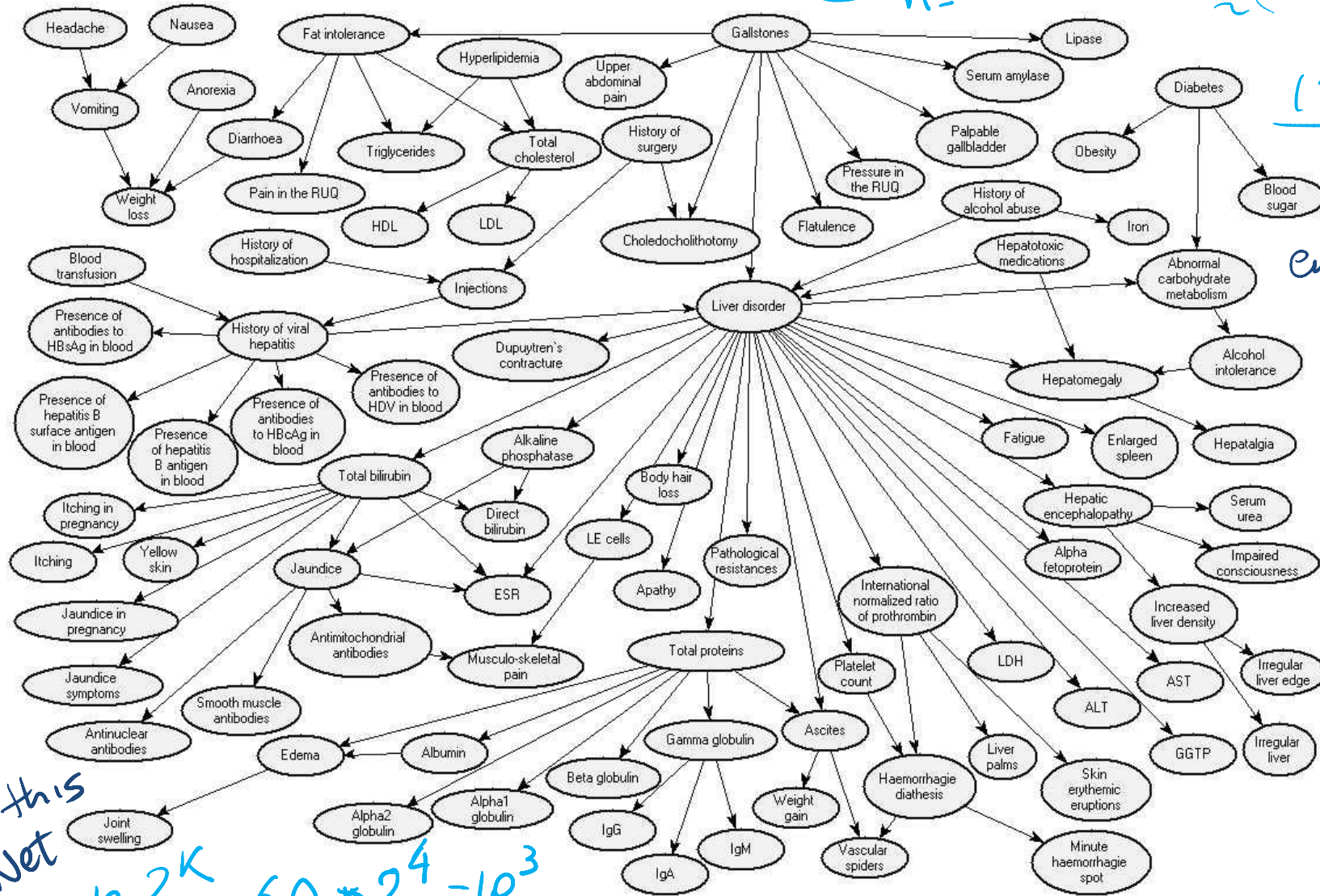
Realistic BNet: Liver Diagnosis

~60 nodes

Source: Onisko et al., 1999

JPD
 $n \approx 60 \sim 2^{60} \approx (2^{10})^6$

10^{18}
 Entries

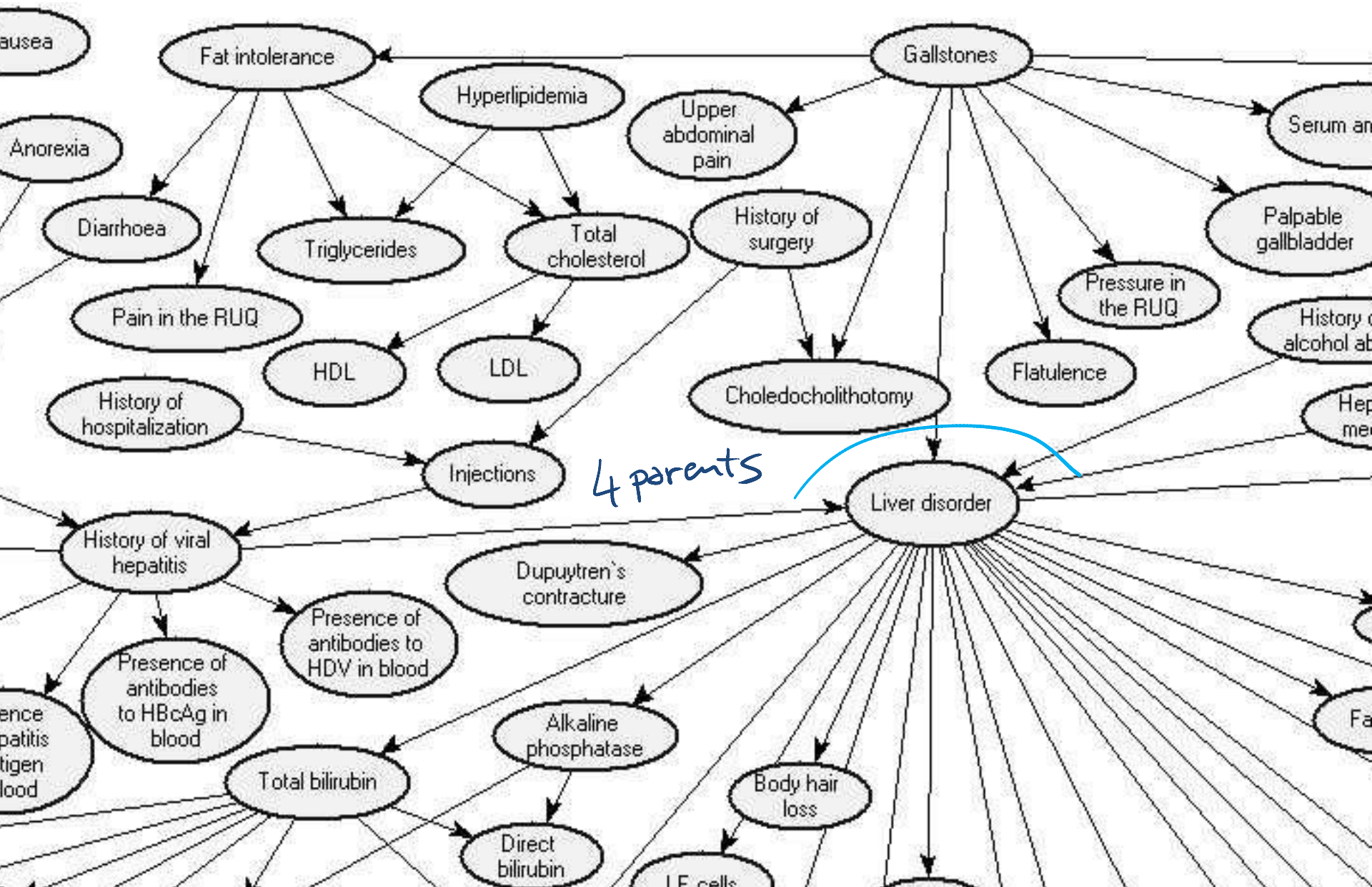


for this BNet

$n \approx 2^k$
 $60 * 2^4 = 10^3$

Realistic BNet: Liver Diagnosis

Source: Onisko et al., 1999



TODO for this Thur

Read Chp 6 of textbook up to Rejection Sampling included

Also Do exercises 6.A and 6.B

<http://www.aispace.org/exercises.shtml>

BNets: Construction General Semantics

The full joint distribution can be defined as the product of conditional distributions:

$$P(X_1, \dots, X_n) = \prod_{i=1}^n P(X_i | X_1, \dots, X_{i-1}) \text{ (chain rule)}$$

Simplify according to marginal&conditional independence

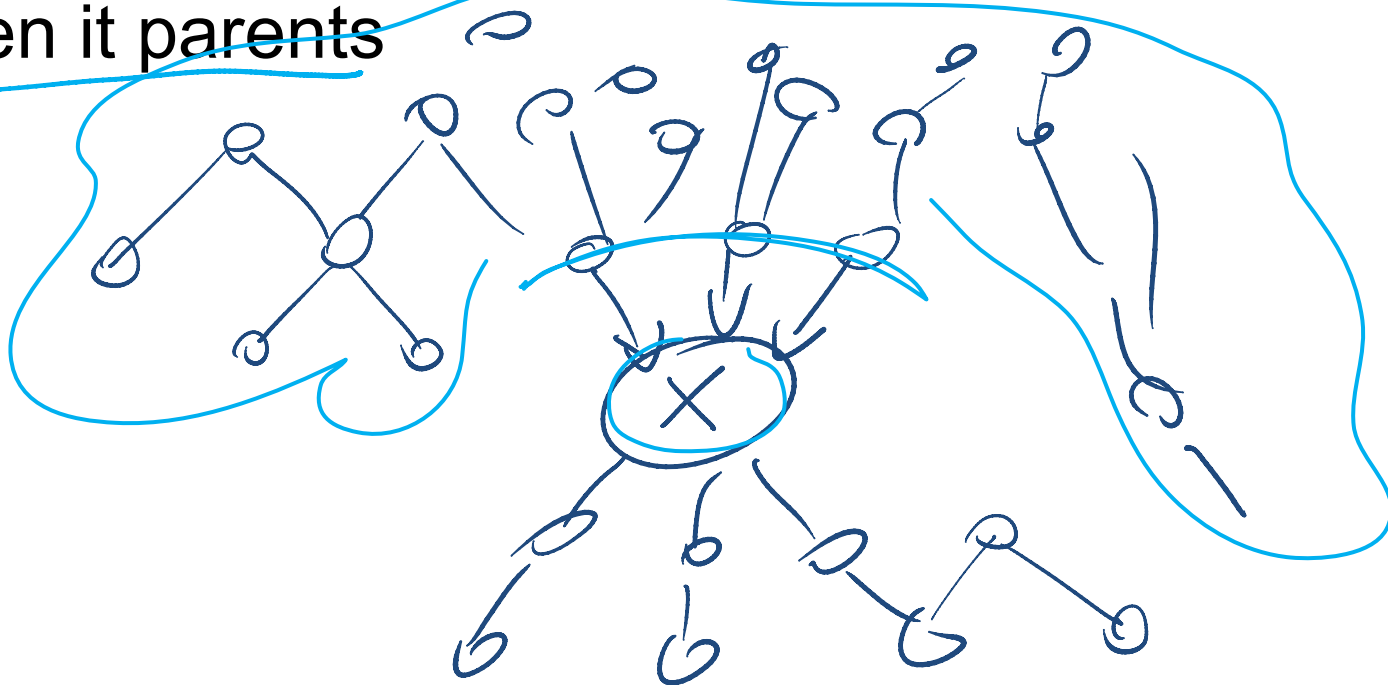
- Express remaining dependencies as a network
 - Each var is a node
 - For each var, the conditioning vars are its parents
 - Associate to each node corresponding conditional probabilities ↙

$$P(X_1, \dots, X_n) = \prod_{i=1}^n P(X_i | \text{Parents}(X_i))$$

BNets: Construction General Semantics (cont')

$$P(X_1, \dots, X_n) = \prod_{i=1}^n P(X_i | \text{Parents}(X_i))$$

- Every node is independent from its non-descendants given its parents



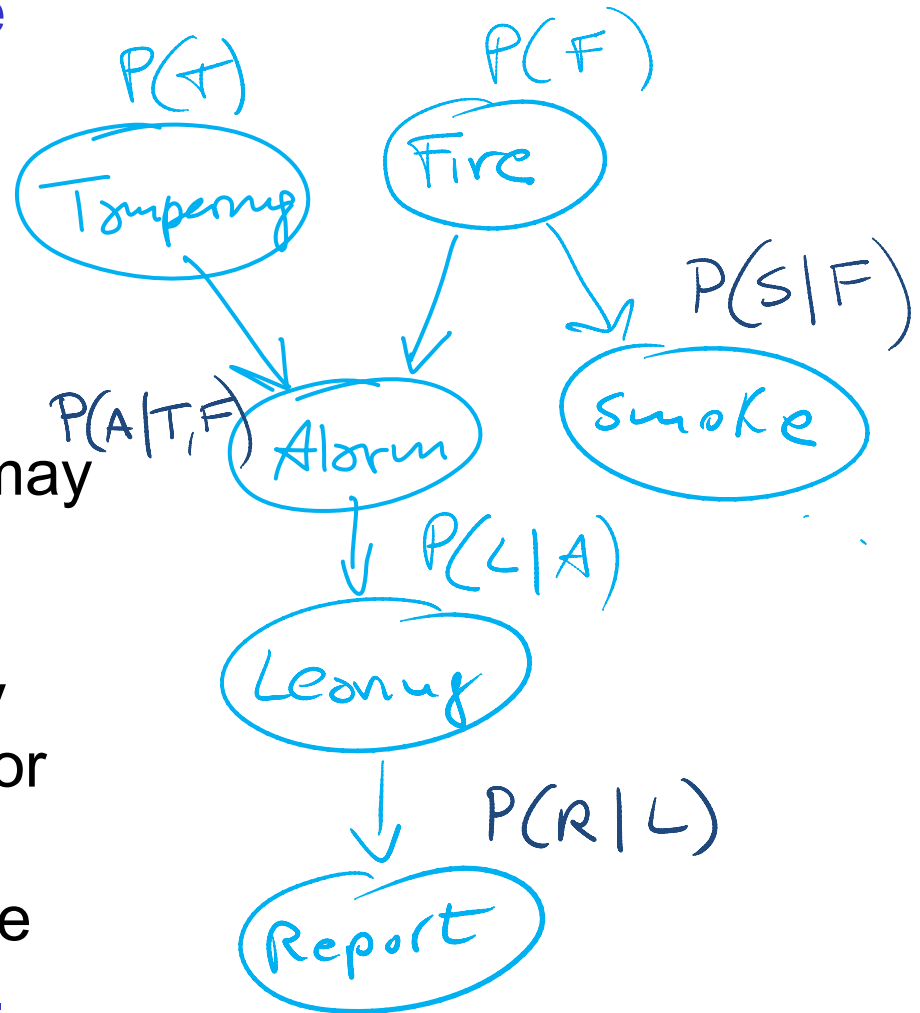
Lecture Overview

- **Belief Networks**
 - Build sample BN
 - Intro Inference, Compactness, Semantics
 - **More Examples**




Other Examples: Fire Diagnosis (textbook Ex. 6.10)

Suppose you want to diagnose whether there is a fire in a building

- you receive a noisy report about whether everyone is leaving the building.
- if everyone is leaving, this may have been caused by a fire alarm.
- if there is a fire alarm, it may have been caused by a fire or by tampering
- if there is a fire, there may be smoke raising from the bldg.



Other Examples (cont')

- Make sure you explore and understand the Fire Diagnosis example (we'll expand on it to study Decision Networks) 
- **Electrical Circuit** example (textbook ex 6.11) 
- **Patient's wheezing and coughing** example (ex. 6.14) 
- Several other examples on