## **Representational Dimensions**

### Computer Science cpsc322, Lecture 2 (Textbook Chpt1)

January, 7, 2009

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CPSC 322, Lecture 2

Slide 1

# Announcement (1) : Need to talk at the end of lecture (missing prereqs for 322)

#### **Announcement (2): Industry Panel**

- Date: Thursday, Jan 15, 5:30-7:30
- Time: 5:30 6:30 pm : Panel Discussion

6:30 – 7:30 pm : Networking Session

- Place: DMP 110 : Panel Discussion
- X-wing Student Lounge : Networking Session
- Theme: How to Prepare Yourself to be Leaders in IT Speakers:
- *David Fracchia*, VP Technology, Radical Entertainment *David Hunter*, VP Operations and Academic Research Centre, SAP *Gail Murphy*, COO, Tasktop Technologies, Prof., UBC CS Dept. *Sheri Plewes*, VP Planning & Engineering, Translink *Tim Richards*, Manager, IS Operations, TELUS

#### Food and beverages will be provided!

#### **Lecture Overview**

- Recap from last lecture
- Representation and Reasoning
- An Overview of This Course
- Further Dimensions of Representational Complexity

#### **Course Essentials**

- Course web-page : CHECK IT OFTEN!
- Textbook: Available on WebCT (wait to print all Chps... they may change a little!)
  - We will cover at least Chapters: 1, 3, 4, 5, 6, 8, 9
- WebCT: used for textbook, discussion board....
- Alspace : online tools for learning Artificial Intelligence
  <u>http://aispace.org/</u>
- Lecture slides...
- Midterm exam, Wed, Mar 4 (1.5 hours, regular room)

#### Agents acting in an environment



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### What do we need to represent?

 The environment /world : What different configurations (states / possible worlds) can the world be in, and how do we denote them?

Chessboard, Info about a patient, Robot Location

- How the world works (we will focus on)
  - Constraints: *sum of current into a node = 0*
  - Causal: what are the causes and the effects of brain disorders?
  - Actions preconditions and effects: <u>when can</u> / press this button? What happens if I press it?

#### Corresponding Reasoning Tasks / Problems

- Constraint Satisfaction Find state that satisfies set of constraints. E.g., What is a feasible schedule for final exams?
- Inference Is a given proposition true/likely given
  what is known? E.g., Does this patient suffers from viral hepatitis?

Planning – Find sequence of actions to reach a
 goal state. E.g., Navigate through and environment
 to reach a particular location

#### **Representation and Reasoning System**

- A (**representation**) **language** in which the environment and how it works can be described
- Computational (reasoning) procedures to compute a solution to a problem in that environment (an answer, a sequence of actions)

But the choice of an appropriate R&R system depends on a key property of the environment and of the agent's knowledge

#### **Deterministic vs. Stochastic Domains**

- Is the environment **deterministic** or **stochastic**?
- Is the agent's knowledge certain or uncertain?
  - A. Does the agent knows for sure what the effects of its actions are?
  - B. Can the agent fully observe the current state of the world?



#### **Deterministic vs. Stochastic Domains**

- Historically, AI has been divided into two camps: those who prefer representations based on **logic** and those who prefer **probability**.
- A few years ago, CPSC 322 covered logic, while CPSC 422 introduced probability
- now we introduce both representational families in 322, and 422 goes into more depth
- this should give you a better idea of what's included in AI
  - Note: Some of the most exciting current research in Al is actually building bridges between these camps. CPSC 322, Lecture 2 Slide 12

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#### Modules we'll cover in this course: R&Rsys



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#### **Dimensions of Representational Complexity**

#### We've already discussed:

- Reasoning tasks (Static vs. Sequential)
- Deterministic versus stochastic domains
- Some other important dimensions of complexity:
- Explicit state or propositions or relations
- Flat or hierarchical
- Knowledge given versus knowledge learned from experience
- Goals versus complex preferences
- Single-agent vs. multi-agent

#### Explicit State or propositions

How do we model the environment? efficiency

- You can enumerate the states of the world.
- A state can be described in terms of features
  - Often it is more natural to describe states in terms of assignments of values to variables (features).
  - 30 binary features (also called propositions) can one possible state { 5,+35,30,110} represent  $2^{30}$  = 1,073,741,824 states.

cloudy Mars Explorer Example Weather  $5 \leq$ 

Temperature [-40-+43] Ioneritude LOCX 0° 359 LOCY 0° 179° CPSC 322, Lecture 2

Z \* 81 \* 360 \* 180

### **Explicit State or propositions or relations**

- Features can be described in terms of objects and relationships.
- There is a proposition for each relationship on each "possible" tuple of individuals.

University Example 1 relationship Registred(S,C)  $\rightarrow$  (S1C1) (S2C3) positions 12 states $12 \text{ sta$ 

 Textbook example: One binary relation and 10 individuals can represents 10<sup>2</sup>=100 propositions and 2<sup>100</sup> states! CPSC 322, Lecture 2 Slide 18

#### **Flat or hierarchical**

- Is it useful to model the whole world at the same level of abstraction?
- You can model the world at one level of abstraction: flat
- You can model the world at multiple levels of abstraction: hierarchical
- Example: Planning a trip from here to a resort in Cancun, Mexico get to simplet Jly to Exam get cob get cob con cob toxe cob CPSC 322, Lecture 2 Slide 19

## Knowledge given vs. knowledge learned from experience

The agent is provided with a model of the world once and far all

- The agent can learn how the world works based
  on experience
  - in this case, the agent often still does start out with some prior knowledge
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#### Goals versus complex preferences

An agent may have a goal that it wants to achieve

- e.g., there is some state or set of states of the world that the agent wants to be in (room-1)
- e.g., there is some proposition or set of propositions that the agent wants to make true tolde-dem T/F door-open T/F

An agent may have complex preferences  $\int \mathcal{O} - \mathcal{I} \setminus$ 

 e.g., there is some preference function that describes how happy the agent is in each state of the world; the agent's task is to put the world into a state which makes it as happy (sp 2mins
 (sp 2mins)
 The sooner I get one the better
 Cappuccino better than Espresso
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### Single-agent vs. Multiagent domains

- Does the environment include other agents?
- Everything we've said so far presumes that there is only one agent in the environment.
- If there are other agents whose actions affect us, it can be useful to explicitly model their goals and beliefs rather than considering them to be part of the environment
- Other Agents can be: <u>cooperative</u>, <u>competitive</u>, or <u>a bit</u> of both

#### **Dimensions of Representational Complexity** in CPSC322

- Reasoning tasks (Constraint Satisfaction / Logic&Probabilistic Inference / Planning)
- Deterministic versus stochastic domains
- Some other important dimensions of complexity:
- Explicit state or propositions or relations minute
- Flat or hierarchical
- Knowledge given versus knowledge learned from experience 540 Goals versus complex preferences
- Single-agent vs. multi-agent gracourse

#### **Next class**

- Assignment 0 due: submit electronically and you can't use late days
- Come to class ready to discuss the two examples of fielded Al agents you found
- I'll show some pictures of cool applications in that class
- Read carefully Section 1.6 on textbook: "Example Applications"
  - The Tutoring System
  - The trading agent

- The autonomous delivery robot
- The diagnostic assistant



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