# **Local Search**

### Computer Science cpsc322, Lecture 14

### (Textbook Chpt 4.8)

February, 4, 2009



## **Lecture Overview**

- Recap CSP (solving CSPs systematically)
- Local search
- Greedy Descent / Hill Climbing: Problems

# Systematically solving CSPs: Summary

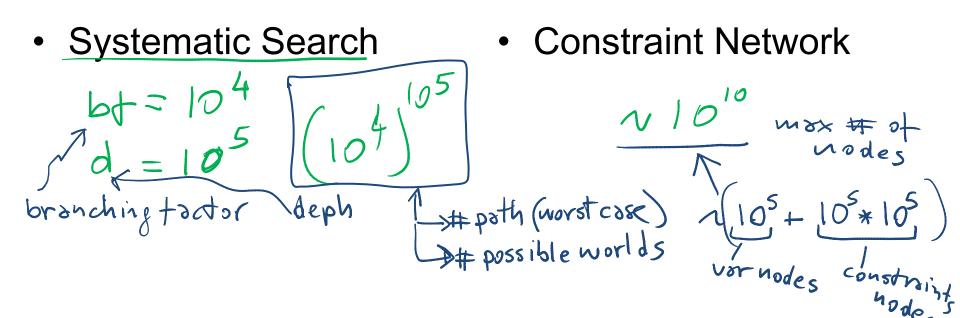
- Build Constraint Network
- Apply Arc Consistency
  - One domain is empty  $\rightarrow$  no solution
- $\rightarrow$  Each domain has a single value  $\rightarrow$  unque solution
  - Some domains have more than one value →
    may or may most be a solution
  - Apply Depth-First Search with Pruning
  - Split the problem in a number of disjoint cases
    - Apply Arc Consistency to each case

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# Local Search motivation: Scale

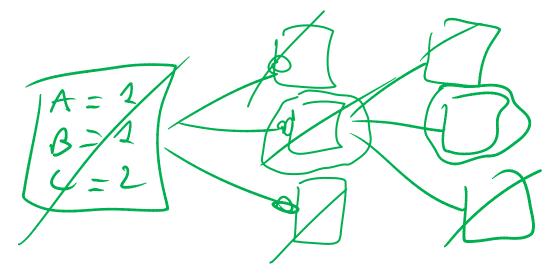
- Many CSPs (scheduling, DNA computing, more later) are simply too big for systematic approaches
- If you have  $10^5$  vars with dom(var<sub>i</sub>) =  $10^4$



but if solutions are densely distributed......

## Local Search: General Method

- Start from a possible world
- Generate some neighbors ( "similar" possible worlds)
- Move from the current node to a neighbor, selected according to a particular strategy
  - Example: A,B,C same domain {1,2,3}

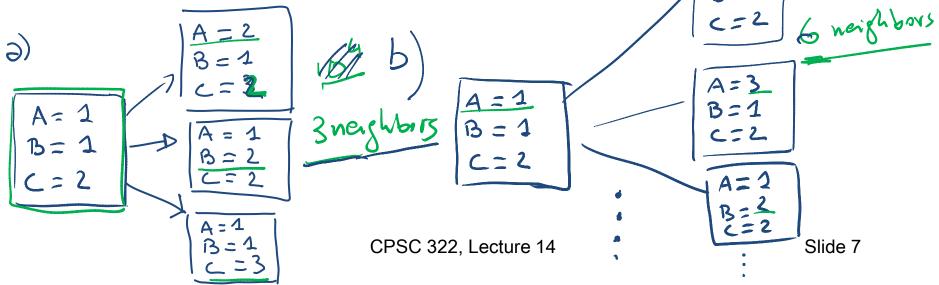


## Local Search: Selecting Neighbors

How do we determine the neighbors?

- Usually this is simple: some small incremental change to the variable assignment
  - a) assignments that differ in one variable's value, by a value difference of (+1 dor un state)
  - b) assignments that differ in one variable's value
  - c) assignments that differ in two variables' values, etc.

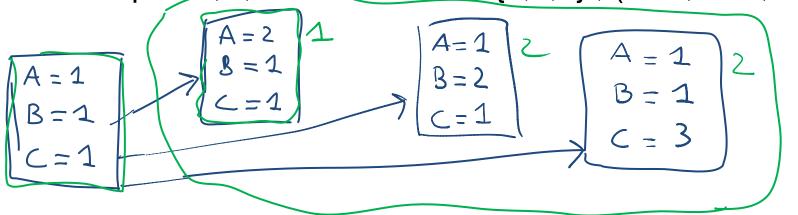




B=1

# Selecting the best neighbor

Example: A,B,C same domain {1,2,3}, (A=B, A>1, C≠3)

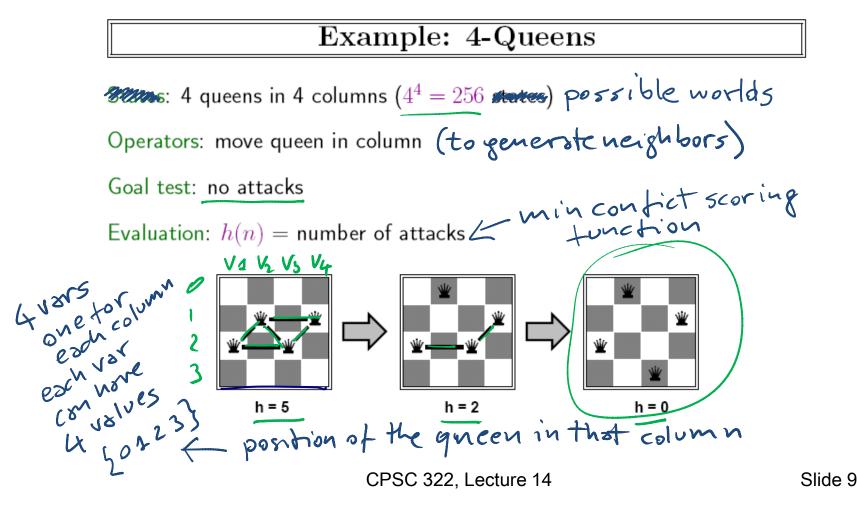


A common component of the scoring function (heuristic) => select the neighbor that results in the .....

- the min conflicts heuristics

### Example: *n*-queens

### Put <u>*n*</u> queens on an <u>*n*</u> <u>*n*</u> board with no two queens on the same row, column, or diagonal

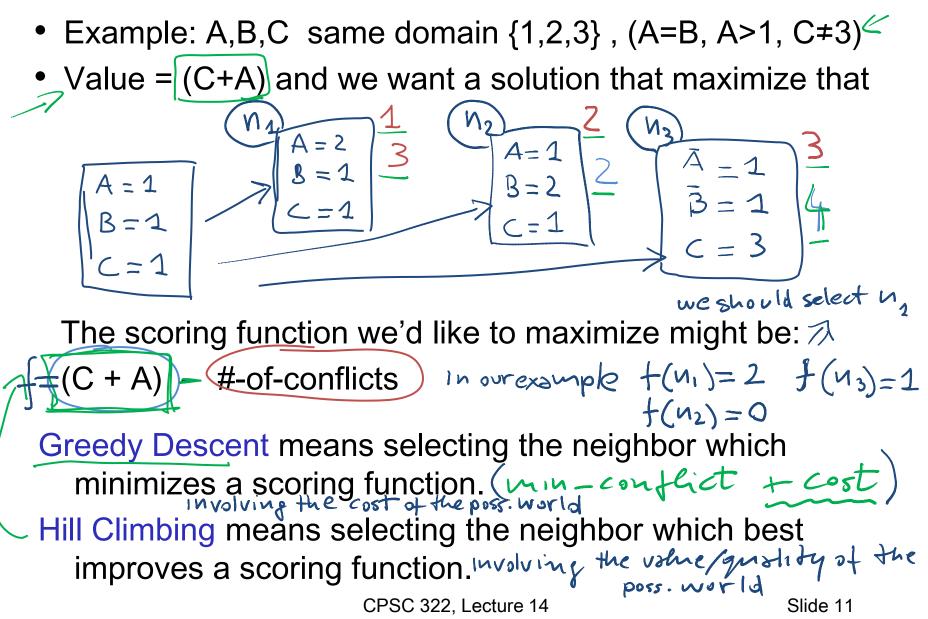


# *n*-queens, Why? *the spectral control of the OO' on local control for OO'*

Lots of research in the 90' on local search for CSP was generated by the observation that the runtime of local search on n-queens problems is independent of problem size!

Given random initial state, can solve *n*-queens in almost constant time for arbitrary *n* with high probability (e.g., n = 10,000,000)

# Solutions might have different values

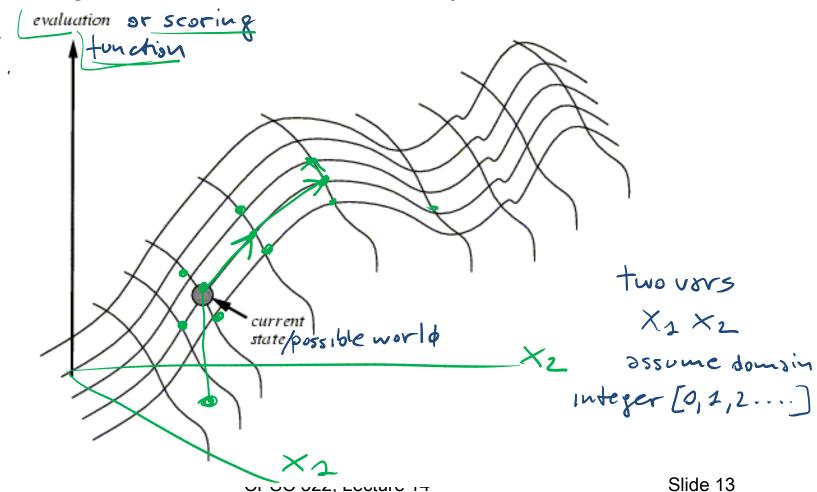


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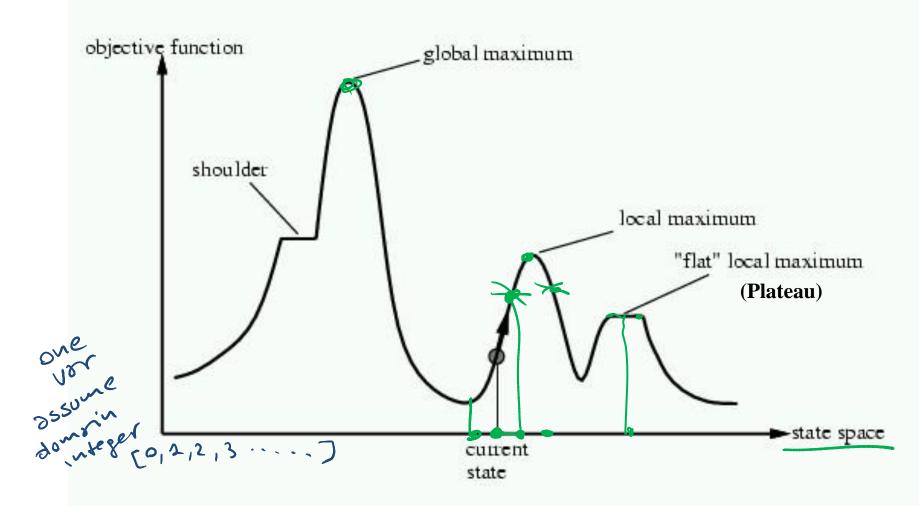
# **Hill Climbing**

NOTE: Everything that will be said for Hill Climbing is also true for Greedy Descent

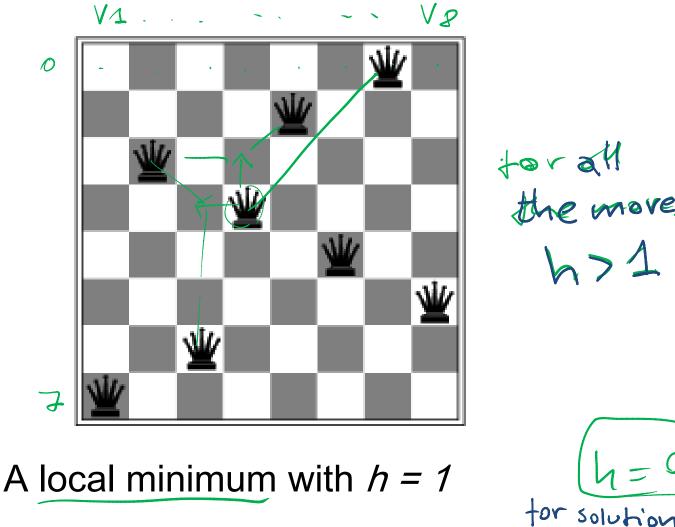


### **Problems with Hill Climbing**

#### Local Maxima. Plateau - Shoulders



### **Corresponding problem for GreedyDescent** Local minimum example: 8-queens problem



torall the moves h>1

## **Even more Problems in higher dimensions**

E.g., Ridges – sequence of local maxima not directly connected to each other From each local maximum you can only go downhill

### Learning Goals for today's class

You can:

- Implement local search for a CSP.
  - Implement different ways to generate neighbors
  - Implement scoring functions to solve a CSP by local search through either greedy descent or hill-climbing.

### **Next Class**

 How to address problems with Greedy Descent / Hill Climbing?

Stochastic Local Search (SLS)

# 322 Feedback <sup>(2)</sup> or <sup>(2)</sup>

- Lectures
- Slides
- Practice
  Exercises
- Assignments
- Alspace

- Textbook
- Course Topics /
  Objectives
- TAs
- Learning Goals