

# Stat 535 C - Statistical Computing & Monte Carlo Methods

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## 1.1– Outline

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- Importance Sampling.
- Normalized Importance Sampling.
- Importance Sampling versus Rejection Sampling.

## 2.1– Summary of Last Lecture

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- Let  $\pi(x)$  be a probability density on  $\mathcal{X}$ .
- Monte Carlo approximation is given by

$$\hat{\pi}_N(x) = \frac{1}{N} \sum_{i=1}^N \delta_{X^{(i)}}(x) \text{ where } X^{(i)} \stackrel{\text{i.i.d.}}{\sim} \pi.$$

- For any  $\varphi : \mathcal{X} \rightarrow \mathbb{R}$

$$E_{\hat{\pi}_N}(\varphi(X)) = \frac{1}{N} \sum_{i=1}^N \varphi(X^{(i)}) \simeq E_{\pi}(\varphi(X))$$

and more precisely

$$E_X[E_{\hat{\pi}_N}(\varphi(X))] = E_{\pi}(\varphi(X)) \text{ and } \text{var}_X(E_{\hat{\pi}_N}(\varphi(X))) = \frac{\text{var}_{\pi}(\varphi(X))}{N}.$$

## 2.1– Summary of Last Lecture

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- Direct methods feasible for standard distributions: inverse method, composition, etc.
- In case where  $\pi \propto \pi^*$  does not admit any standard form, we can use a *proposal* distribution  $q$  on  $\mathsf{X}$  where  $q \propto q^*$ .
- We need  $q$  to ‘dominate’  $\pi$ ; i.e.

$$C = \sup_{x \in \mathsf{X}} \frac{\pi^*(x)}{q^*(x)} < +\infty.$$

## 2.2– Accept Reject - Illustration

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Consider  $C' \geq C$ . Then the accept/reject procedure proceeds as follows:

### Accept/Reject procedure

1. Sample  $Y \sim q$  and  $U \sim \mathcal{U}(0, 1)$ .
2. If  $U < \frac{\pi^*(Y)}{C'q^*(Y)}$  then return  $Y$ ; otherwise return to step 1.

## 2.2– Accept Reject - Illustration

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- This is a simple generic algorithm but it requires coming up with a bound  $C$ .
- Its performance typically degrades exponentially fast with the dimension of  $X$ .
- It seems you are wasting some information by rejecting samples.
- You need to wait a random time to obtain some samples from  $\pi$ .
- Is it possible to “recycle” these samples?

## 3.1– Importance Sampling

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- Consider again the target distribution  $\pi$  and the proposal distribution  $q$ . We only require

$$\pi(x) > 0 \Rightarrow q(x) > 0.$$

- In this case, the Importance Sampling (IS) identity is

$$E_{\pi}(\varphi(X)) = \int_{\mathcal{X}} \varphi(x)\pi(x)dx = \int_{\mathcal{X}} \varphi(x) \frac{\pi(x)}{q(x)} q(x)dx = E_q(w(X)\varphi(X))$$

where the so-called Importance Weight is given by

$$w(x) = \frac{\pi(x)}{q(x)}$$

- This is a simple yet very flexible identity.

## 3.1– Importance Sampling

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- Monte Carlo approximation of  $q$  is

$$\hat{q}_N(x) = \frac{1}{N} \sum_{i=1}^N \delta_{X^{(i)}}(x) \text{ where } X^{(i)} \stackrel{\text{i.i.d.}}{\sim} q.$$

- It follows that an estimate of  $E_\pi(\varphi(X)) = E_q(w(X)\varphi(X))$  is

$$E_{\hat{q}_N}(w(X)\varphi(X)) = \frac{1}{N} \sum_{i=1}^N w(X^{(i)})\varphi(X^{(i)})$$

- It corresponds to the following approximation

$$\hat{\pi}_N(x) = \frac{1}{N} \sum_{i=1}^N w(X^{(i)})\delta_{X^{(i)}}(x)$$



## 3.1– Importance Sampling

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- We have

$$E_X [E_{\hat{q}_N} (w(X)\varphi(X))] = E_\pi (\varphi(X))$$

and

$$\text{var}_X (E_{\hat{q}_N} (\varphi(X))) = \frac{\text{var}_q (w(X)\varphi(X))}{N} = \frac{E_\pi (w(X)\varphi^2(X)) - E_\pi^2 (\varphi(X))}{N}$$

- In practice, it is recommended to ensure

$$E_\pi (w(X)) = \int \frac{\pi^2(x)}{q(x)} dx < \infty.$$

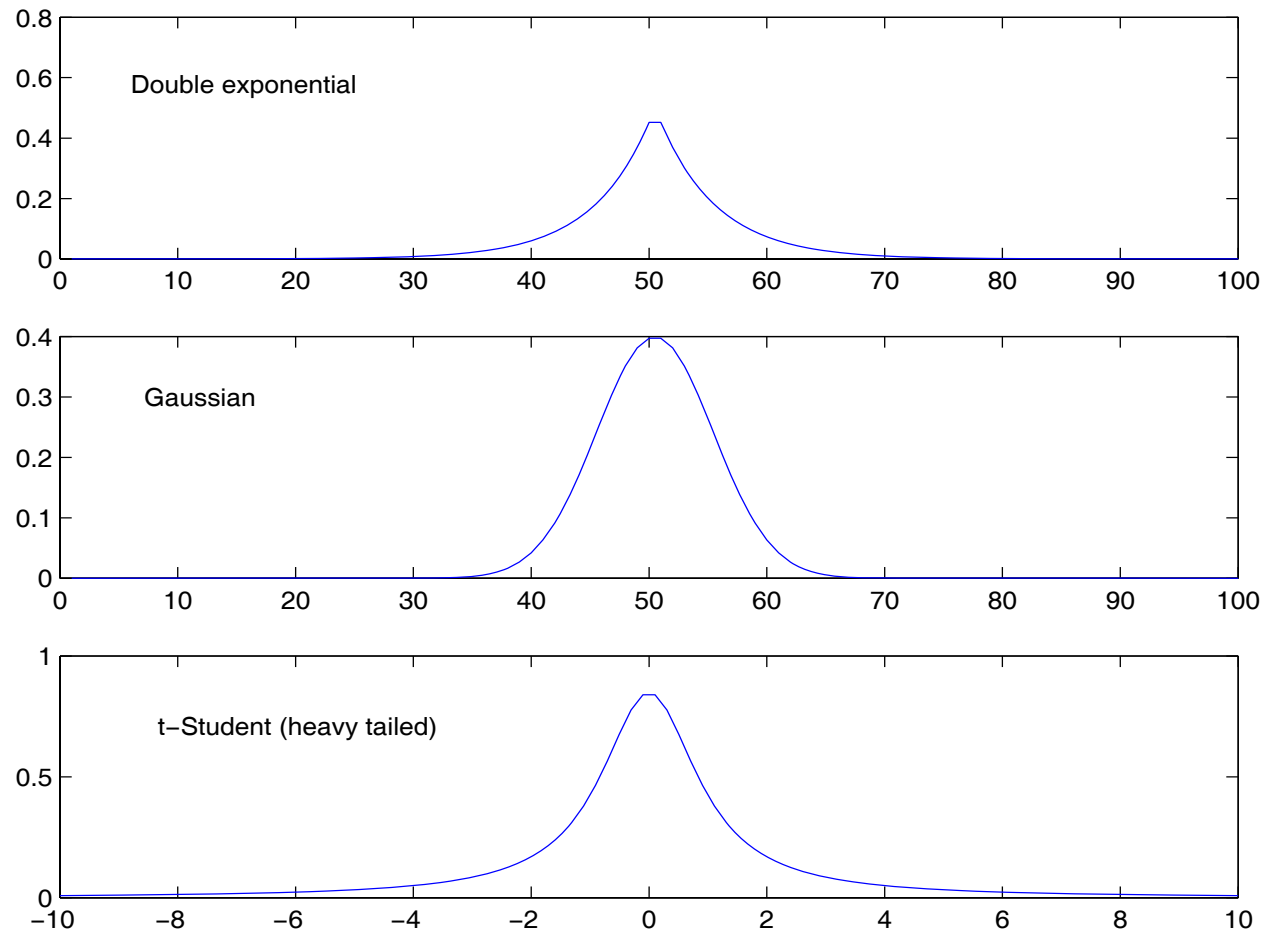
- Even if it is not necessary, it is actually even better to ensure that

$$\sup_{x \in \mathcal{X}} w(x) < \infty.$$

## 3.2– Example

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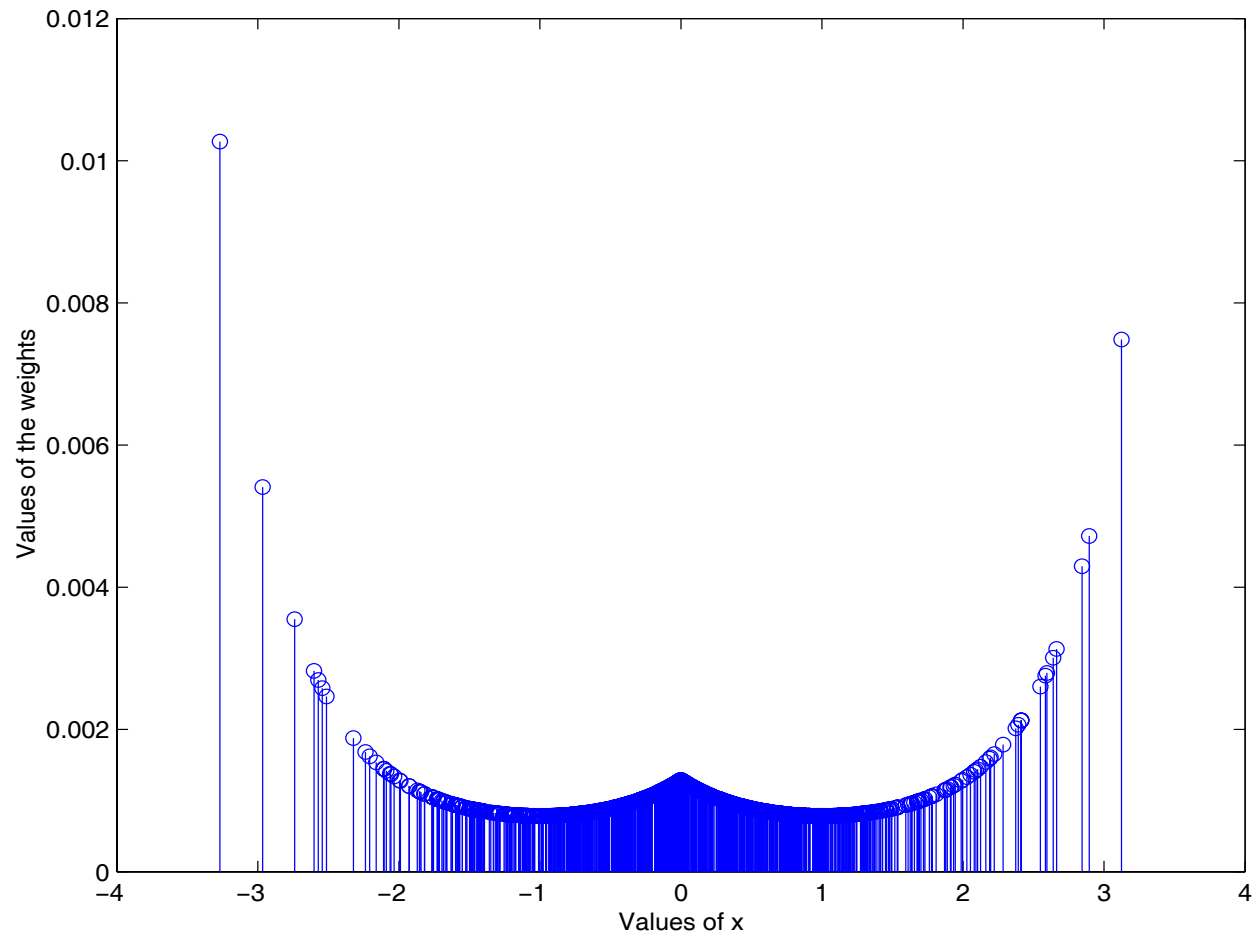
Target double exponential distributions and two IS distributions



## 3.2– Example

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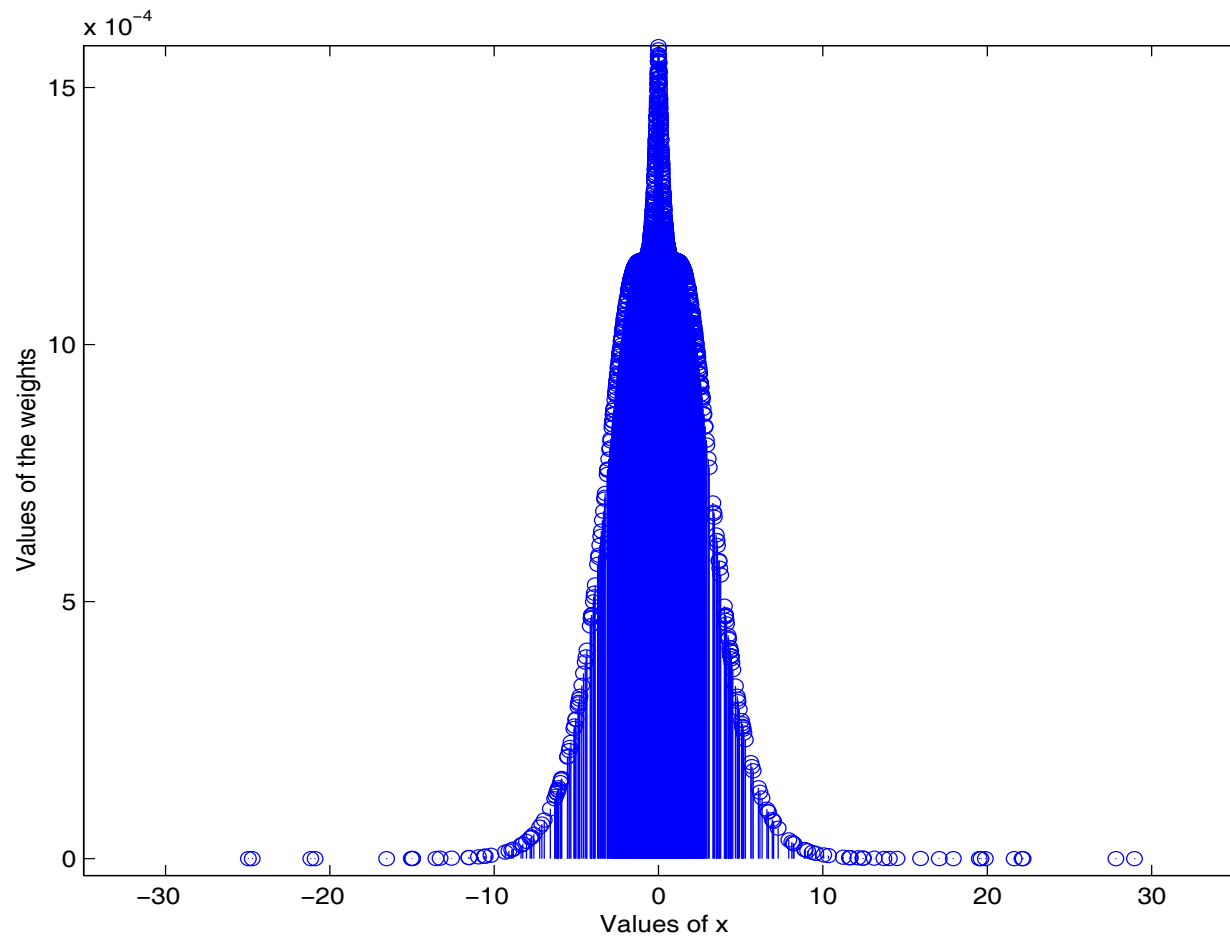
IS approximation obtained using a Gaussian IS distribution



## 3.2– Example

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IS approximation obtained using a Student-t IS distribution



### 3.3– Optimal IS Distribution

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- For a given test function, one can minimize the IS variance using

$$q^{\text{opt}}(x) = \frac{|\varphi(x)| \pi(x)}{\int_{\mathcal{X}} |\varphi(x)| \pi(x) dx}$$

*Proof:*

$$\text{var}_q(w(X)\varphi(X)) = \int q(x) \frac{\pi^2(x)}{q^2(x)} \varphi^2(x) dx - \left( \int \pi(x) \varphi(x) dx \right)^2$$

and

$$\int q(x) \frac{\pi^2(x)}{q^2(x)} \varphi^2(x) dx \geq \left( \int q(x) \frac{\pi(x) |\varphi(x)|}{q(x)} dx \right)^2 = \left( \int \pi(x) |\varphi(x)| dx \right)^2.$$

This lower bound is attained for  $q^{\text{opt}}(x)$ .

## 3.4– Normalized Importance Sampling

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- In most if not all applications we are interested in, standard IS cannot be used as the importance weights  $w(x) = \pi(x)/q(x)$  cannot be evaluated in closed-form. In practice, we typically only know  $\pi(x) \propto \pi^*(x)$  and  $q(x) \propto q^*(x)$ .
- Normalized IS identity is based on

$$\pi(x) = \frac{\pi^*(x)}{\int \pi^*(x) dx} = \frac{w^*(x) q^*(x)}{\int w^*(x) q^*(x) dx} = \frac{w^*(x) q(x)}{\int w^*(x) q(x) dx}$$

where

$$w^*(x) = \frac{\pi^*(x)}{q^*(x)}.$$

## 3.4– Normalized Importance Sampling

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- For any test function  $\varphi$ , we can also write

$$E_{\pi}(\varphi(X)) = \frac{E_q(w^*(X)\varphi(X))}{E_q(w^*(X))} = \frac{E_q(w(X)\varphi(X))}{E_q(w(X))}.$$

- Given a Monte Carlo approximation of  $q$ ;  $\hat{q}_N(x) = \frac{1}{N} \sum_{i=1}^N \delta_{X^{(i)}}(x)$  then

$$\hat{\pi}_N(x) = \sum_{i=1}^N W^{(i)} \delta_{X^{(i)}}(x) \text{ where } W^{(i)} = \frac{w^*(X^{(i)})}{\sum_{j=1}^N w^*(X^{(j)})},$$

$$E_{\hat{\pi}_N}(\varphi(X)) = \sum_{i=1}^N W^{(i)} \varphi(X^{(i)}).$$

- The estimates are a ratio of estimates.

## 3.4– Normalized Importance Sampling

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- Contrary to standard IS, this estimate is biased but asymptotically unbiased by the LLN it is asymptotically consistent.
  
- Derivation of the asymptotic bias and variance based on the delta method.



### 3.5– Proof using the Delta Method

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- Assume you have  $Z = g(A, B)$  with  $E(A) = \mu_A$  and  $E(B) = \mu_B$  then a two-dimensional Taylor series gives around  $\mu = (\mu_A, \mu_B)$

$$Z \simeq g(\mu) + (A - \mu_A) \frac{\partial g}{\partial a}(\mu) + (B - \mu_B) \frac{\partial g}{\partial b}(\mu).$$

It follows that

$$E(Z) \simeq g(\mu),$$

$$\text{Var}(Z) \simeq \sigma_A^2 \frac{\partial g}{\partial a}(\mu) + \sigma_B^2 \frac{\partial g}{\partial b}(\mu) + 2 \frac{\partial g}{\partial a}(\mu) \frac{\partial g}{\partial b}(\mu) \sigma_{A,B}.$$

- In our case

$$Z = E_{\hat{\pi}_N}(\varphi(X)) = \frac{E_{q_N}(w^*(X) \varphi(X))}{E_{q_N}(w^*(X))} = \frac{A}{B}$$

## 3.6– Asymptotic Variance

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- We have

$$\frac{\partial g}{\partial a}(\mu) \frac{\partial g}{\partial b}(\mu) = -\frac{\mu_A}{\mu_B^3}, \quad \frac{\partial g^2}{\partial a}(\mu) = \frac{1}{\mu_B^2}, \quad \frac{\partial g^2}{\partial b}(\mu) = \frac{\mu_A^2}{\mu_B^4},$$

$$\mu_A = E_q(w^*(X) \varphi(X)), \quad \mu_B = E_q(w^*(X)),$$

$$\sigma_A^2 = \frac{\text{var}_q(w^*(X) \varphi(X))}{N}, \quad \sigma_B^2 = \frac{\text{var}_q(w^*(X))}{N}$$

$$\sigma_{A,B} = \frac{E_q\left(w^*(X)^2 \varphi(X)\right) - \mu_A \cdot \mu_B}{N}.$$

## 3.6– Asymptotic Variance

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- It follows that

$$\begin{aligned} \text{Var} (E_{\hat{\pi}_N} (\varphi (X))) &\simeq \sigma_A^2 \frac{\partial g^2}{\partial a} (\mu) + \sigma_B^2 \frac{\partial g^2}{\partial b} (\mu) + 2 \frac{\partial g}{\partial a} (\mu) \frac{\partial g}{\partial b} (\mu) \sigma_{A,B} \\ &= \frac{\sigma_A^2}{\mu_B^2} + \frac{\sigma_B^2 \mu_A^2}{\mu_B^4} - 2 \frac{\mu_A \sigma_{A,B}}{\mu_B^3} \end{aligned}$$

- Asymptotically, we have a central limit theorem

$$\sqrt{N} (E_{\hat{\pi}_N} (\varphi (X)) - E_{\pi} (\varphi (X))) \Rightarrow \mathcal{N} (0, \sigma_{IS}^2 (\varphi))$$

where

$$\sigma_{IS}^2 (\varphi) = \int \frac{\pi^2 (x)}{q (x)} (\varphi (x) - E_{\pi} (\varphi))^2 dx$$

## 3.6– Asymptotic Variance

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- In practice, it is now necessary but highly recommended to select the proposal  $q$  such that

$$\sup_{x \in \mathcal{X}} w(x) < \infty \text{ or equivalently } \sup_{x \in \mathcal{X}} w^*(x) < \infty.$$

- There is some empirical evidence that Normalized IS performs better than standard IS in numerous cases.

## 3.7– Asymptotic Bias

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- Using a second order Taylor expansion

$$\begin{aligned} Z &\simeq g(\mu) + (A - \mu_A) \frac{\partial g}{\partial a}(\mu) + (B - \mu_B) \frac{\partial g}{\partial b}(\mu) \\ &\quad + \frac{1}{2} (A - \mu_A)^2 \frac{\partial^2 g}{\partial a^2}(\mu) + \frac{1}{2} (B - \mu_B)^2 \frac{\partial^2 g}{\partial b^2}(\mu) + (A - \mu_A)(B - \mu_B) \frac{\partial^2 g}{\partial a \partial b}(\mu) \end{aligned}$$

gives

$$E(E_{\hat{\pi}_N}(\varphi(X))) \simeq g(\mu) + \frac{1}{2} \sigma_A^2 \frac{\partial^2 g}{\partial a^2}(\mu) + \frac{1}{2} \sigma_B^2 \frac{\partial^2 g}{\partial b^2}(\mu) + \sigma_{A,B} \frac{\partial^2 g}{\partial a \partial b}(\mu).$$

- It follows that asymptotically we have

$$N(E_{\hat{\pi}_N}(\varphi(X)) - E_{\pi}(\varphi(X))) \rightarrow - \int \frac{\pi^2(x)}{q(x)} (\varphi(x) - E_{\pi}(\varphi)) dx.$$

- We have  $Bias^2$  of order  $1/N^2$  and Variance of order  $1/N$ .

## 3.8– Optimal Importance Sampling

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- For a given test function, one can minimize the normalized IS asymptotic variance using

$$q^{\text{opt}}(x) = \frac{|\varphi(x) - E_{\pi(\varphi)}| \pi(x)}{\int_{\mathcal{X}} |\varphi(x) - E_{\pi(\varphi)}| \pi(x) dx}$$

*Proof:*

$$\begin{aligned} \int q(x) \frac{\pi^2(x)}{q^2(x)} (\varphi(x) - E_{\pi(\varphi)})^2 dx &\geq \left( \int q(x) \frac{\pi(x) |\varphi(x) - E_{\pi(\varphi)}|}{q(x)} dx \right)^2 \\ &= \left( \int \pi(x) |\varphi(x) - E_{\pi(\varphi)}| dx \right)^2 \end{aligned}$$

and this lower bound is attained for  $q^{\text{opt}}(x)$ .

- This result is practically useless because it requires knowing  $E_{\pi(\varphi)}$  but it suggests approximations.

### 3.9– In practice...

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- In statistics, we are usually not interested in a specific  $\varphi$  but in several functions and we prefer having  $q(x)$  as close as possible to  $\pi(x)$ .
- For flat functions, one can approximate the variance by

$$\text{var}(E_{\hat{\pi}_N}(\varphi(X))) \simeq (1 + \text{var}_q(w(X))) \frac{\text{var}(E_{\pi}(\varphi(X)))}{N}.$$

- Simple interpretation: The  $N$  weighted samples are approximately equivalent to  $M$  unweighted samples from  $\pi$  where

$$M = \frac{N}{1 + \text{var}_q(w(X))} \leq N.$$

### 3.9– In practice...

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- However, we are often interested in estimating the ratio of normalizing constants

$$\frac{\int \pi^*(x) dx}{\int q^*(x) dx} = \int w^*(x) q(x) dx = E_q[w^*(X)].$$

using

$$E_{q_N}[w^*(X)] = \frac{1}{N} \sum_{i=1}^N w^*(X^{(i)})$$

which is unbiased and has variance

$$\text{var}[E_{q_N}[w^*(X)]] = \frac{\text{var}_q(w^*(X))}{N}.$$



## 3.10– Open Question

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- Clearly if you have  $q(x) = \pi(x)$  then

$$\text{var} [E_{q_N} [w^*(X)]] = 0$$

- However if  $q(x) \neq \pi(x)$  then the estimate is simply

$$E_{q_N} [w^*(X)] = \frac{\int \pi^*(x) dx}{\int q^*(x) dx}.$$

- **Open Question:** How could you come up with a good estimate of  $\int \pi^*(x) dx$  based on samples of  $\pi$ .

## 3.11– Application to Bayesian Inference

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- Consider a Bayesian model: prior  $\pi(\theta)$  and likelihood  $f(x|\theta)$ .
- The posterior distribution is given by

$$\pi(\theta|x) = \frac{\pi(\theta) f(x|\theta)}{\int_{\Theta} \pi(\theta) f(x|\theta) d\theta} \propto \pi^*(\theta|x) \text{ where } \pi^*(\theta|x) = \pi(\theta) f(x|\theta).$$

- We can use the prior distribution as a candidate distribution  $q(\theta) = q^*(\theta) = \pi(\theta)$ .
- We also get an estimate of the marginal likelihood

$$\int_{\Theta} \pi(\theta) f(x|\theta) d\theta.$$

## 3.11– Application to Bayesian Inference

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- IS is more powerful than you think.
- Assume you have say to compute the importance weight

$$w(\theta^{(i)}) \propto \int f(x, z | \theta) dz;$$

i.e. the likelihood is very complex and might not admit a closed-form expression.

- You do NOT need to compute  $w(\theta^{(i)})$  exactly, an unbiased estimate of it is sufficient.

### 3.12– Importance sampling does not work well in high-dimension

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- Consider the case where  $\mathcal{X} = \mathbb{R}^n$

$$\pi(\theta) = \frac{1}{(2\pi)^{n/2}} \exp\left(-\frac{\sum_{i=1}^n \theta_i^2}{2}\right)$$

and

$$q_\sigma(\theta) = \frac{1}{(2\pi\sigma^2)^{n/2}} \exp\left(-\frac{\sum_{i=1}^n \theta_i^2}{2\sigma^2}\right)$$

- We have for any  $\sigma > 1$

$$w_\sigma(\theta) = \frac{\pi(\theta)}{q_\sigma(\theta)} = \sigma^n \exp\left(-\sum_{i=1}^n \frac{\theta_i^2}{2} \left(1 - \frac{1}{\sigma^2}\right)\right) \leq \sigma^n \text{ for any } \theta$$

and

$$\text{var}_{q_\sigma}\left(\frac{\pi(\theta)}{q_\sigma(\theta)}\right) = \sigma^n \sigma'^n - 1 \text{ with } \sigma'^2 = \frac{\sigma^2}{\sigma^2 - 1/2} > 1$$

- Despite having a very good proposal then the variance of the weights increases exponentially fast with the dimension of the problem.

### 3.13– Rejection Sampling versus Importance Sampling

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- Given  $N$  samples from  $q$ , we estimate  $E_\pi(\varphi(X))$  through IS

$$\widehat{E}_\pi^{IS}(\varphi(X)) = \frac{\sum_{i=1}^N w^*(X^{(i)}) \varphi(X^{(i)})}{\sum_{i=1}^N w^*(X^{(i)})}$$

or we “filter” the samples through rejection and propose instead

$$\widehat{E}_\pi^{RS}(\varphi(X)) = \frac{1}{K} \sum_{k=1}^K \varphi(X^{(i_k)})$$

where  $K$  is a random variable.

- We want to know which strategy performs the best.

### 3.14– Rejection Sampling is a special case of Importance Sampling

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- Define the artificial target  $\bar{\pi}(x, y)$  on  $\mathcal{X} \times [0, 1]$  as

$$\bar{\pi}(x, y) = \begin{cases} \frac{Cq^*(x)}{\int \pi^*(x)dx}, & \text{for } x \in \mathcal{X}, y \in \left[0, \frac{\pi^*(x)}{Cq^*(x)}\right] \\ 0 & \text{otherwise} \end{cases}$$

then

$$\int \bar{\pi}(x, y) dy = \int_0^{\frac{\pi^*(x)}{Cq^*(x)}} \frac{Cq^*(x)}{\int \pi^*(x) dx} dy = \pi(x).$$

- Now let us consider the proposal distribution

$$q(x, y) = q(x) U_{[0,1]}(y) \text{ for } (x, y) \in \mathcal{X} \times [0, 1].$$

## 3.14– Rejection Sampling is a special case of Importance Sampling

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- Then rejection sampling is nothing but IS on  $\mathcal{X} \times [0, 1]$  where

$$w(x, y) = \frac{\bar{\pi}(x, y)}{q(x) U_{[0,1]}(y)} = \begin{cases} \frac{C \int q^*(x) dx}{\int \pi^*(x) dx} & \text{for } Y^{(i)} \in \left[0, \frac{\pi^*(X^{(i)})}{Cq^*(X^{(i)})}\right] \\ 0, & \text{otherwise.} \end{cases}$$

- We have

$$\hat{E}_{\pi}^{RS}(\varphi(X)) = \frac{1}{K} \sum_{k=1}^K \varphi(X^{(i_k)}) = \frac{\sum_{i=1}^N w(X^{(i)}, Y^{(i)}) \varphi(X^{(i)})}{\sum_{i=1}^N w(X^{(i)}, Y^{(i)})}.$$

- Compared to standard IS, RS performs IS on an enlarged space.

## 3.14– Rejection Sampling is a special case of Importance Sampling

- The variance of the importance weights from RS is higher than for standard IS:

$$\text{var}_q [w(X, Y)] \geq \text{var}_q [w(X)].$$

More precisely, we have

$$\begin{aligned} \text{var} [w(X, Y)] &= \text{var} [E [w(X, Y) | X]] + E [\text{var} [w(X, Y) | X]] \\ &= \text{var} [w(X)] + E [\text{var} [w(X, Y) | X]]. \end{aligned}$$

- To compute integrals, Rejection sampling is inefficient and you should simply use IS.



## 3.15– Discussion

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- Like Rejection, IS is useful for small non-standard distributions but collapses for most “interesting” problems.
- In both cases, the problem is to be able to design “clever” proposal distributions.
- Towards the end of this course, we will present advanced dynamic method to address this problem.