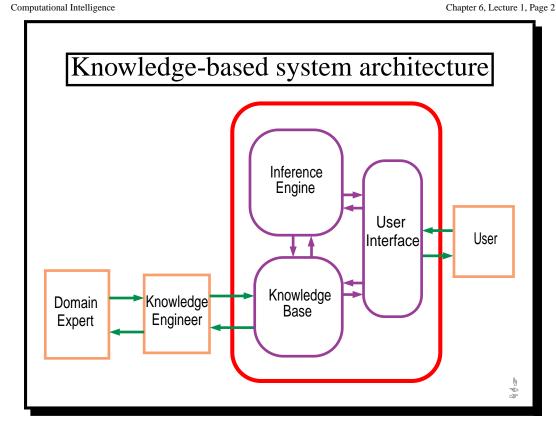


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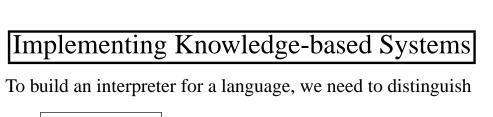
# Roles for people in a KBS

- Software engineers build the inference engine and user interface.
- Knowledge engineers design, build, and debug the knowledge base in consultation with domain experts.
- Domain experts know about the domain, but nothing about particular cases or how the system works.
- Users have problems for the system, know about particular cases, but not about how the system works or the domain.

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- Base language the language of the RRS being implemented.
- Metalanguage the language used to implement the system.

They could even be the same language!

# Implementing the base language

Let's use the definite clause language as the base language and the metalanguage.

- We need to represent the base-level constructs in the metalanguage.
- We represent base-level terms, atoms, and bodies as meta-level terms.
- We represent base-level clauses as meta-level facts.
- In the non-ground representation base-level variables are represented as meta-level variables.

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# Representing the base level constructs

- Base-level atom  $p(t_1, \ldots, t_n)$  is represented as the meta-level term  $p(t_1, \ldots, t_n)$ .
- Meta-level term  $oand(e_1, e_2)$  denotes the conjunction of base-level bodies  $e_1$  and  $e_2$ .
- Meta-level constant *true* denotes the object-level empty body.
- The meta-level atom *clause*(*h*, *b*) is true if "*h* if *b*" is a clause in the base-level knowledge base.

#### Example representation

The base-level clauses

connected\_to( $l_1, w_0$ ).

connected\_to( $w_0, w_1$ )  $\leftarrow up(s_2)$ .

 $lit(L) \leftarrow light(L) \land ok(L) \land live(L).$ 

can be represented as the meta-level facts

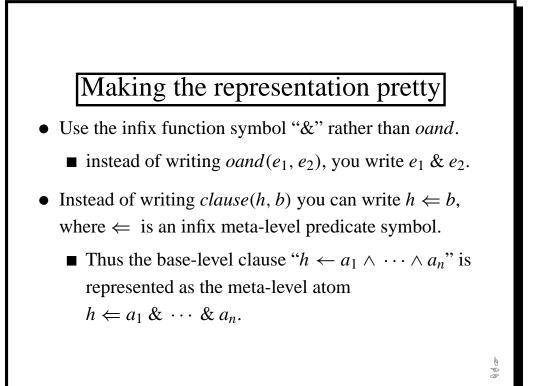
 $clause(connected\_to(l_1, w_0), true).$  $clause(connected\_to(w_0, w_1), up(s_2)).$ 

clause(lit(L), oand(light(L), oand(ok(L), live(L)))).

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#### Example representation

The base-level clauses

connected\_to( $l_1, w_0$ ). connected\_to( $w_0, w_1$ )  $\leftarrow up(s_2)$ .

 $lit(L) \leftarrow light(L) \land ok(L) \land live(L).$ 

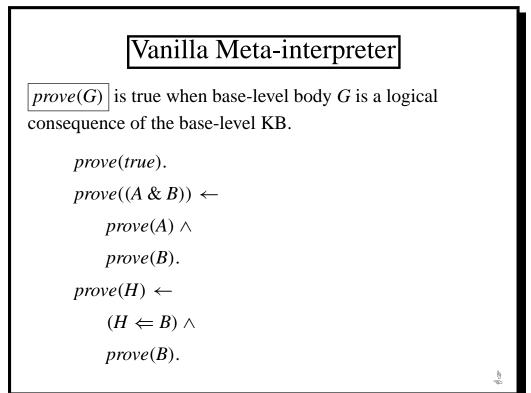
can be represented as the meta-level facts

 $connected\_to(l_1, w_0) \Leftarrow true.$   $connected\_to(w_0, w_1) \Leftarrow up(s_2).$  $lit(L) \Leftarrow light(L) \& ok(L) \& live(L).$ 

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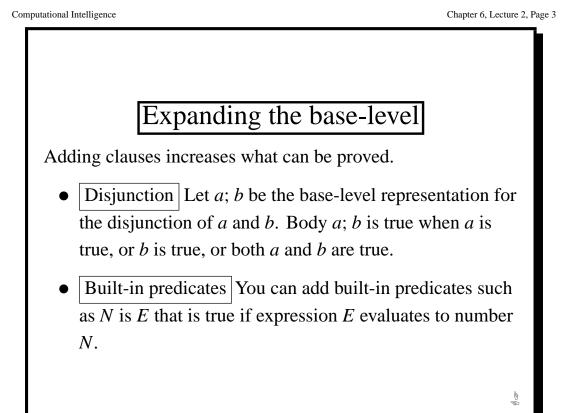
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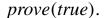


### Example base-level KB

 $live(W) \Leftarrow$   $connected\_to(W, W_1) \&$   $live(W_1).$   $live(outside) \Leftarrow true.$   $connected\_to(w_6, w_5) \Leftarrow ok(cb_2).$   $connected\_to(w_5, outside) \Leftarrow true.$   $ok(cb_2) \Leftarrow true.$   $?prove(live(w_6)).$ 



#### Expanded meta-interpreter

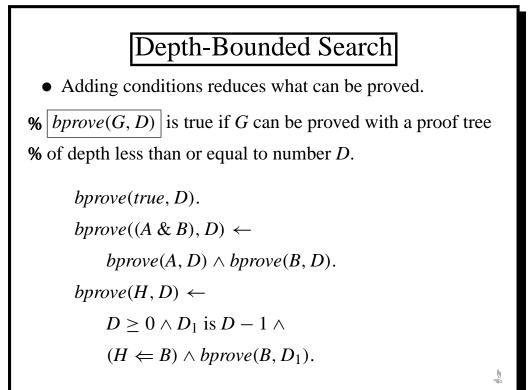


 $prove((A \& B)) \leftarrow$   $prove(A) \land prove(B).$   $prove((A; B)) \leftarrow prove(A).$   $prove((A; B)) \leftarrow prove(B).$   $prove((N \text{ is } E)) \leftarrow$  N is E.  $prove(H) \leftarrow$   $(H \leftarrow B) \land prove(B).$ 

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# Delaying Goals

Some goals, rather than being proved, can be collected in a list.

- To delay subgoals with variables, in the hope that subsequent calls will ground the variables.
- To delay assumptions, so that you can collect assumptions that are needed to prove a goal.
- To create new rules that leave out intermediate steps.
- To reduce a set of goals to primitive predicates.

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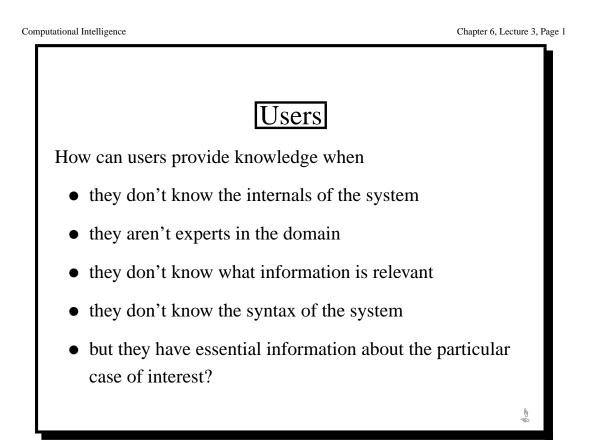
#### Delaying Meta-interpreter

%  $dprove(G, D_0, D_1)$  is true if  $D_0$  is an ending of list of % delayable atoms  $D_1$  and  $KB \wedge (D_1 - D_0) \models G$ .

$$\begin{split} dprove(true, D, D). \\ dprove((A \& B), D_1, D_3) \leftarrow \\ dprove(A, D_1, D_2) \wedge dprove(B, D_2, D_3). \\ dprove(G, D, [G|D]) \leftarrow delay(G). \\ dprove(H, D_1, D_2) \leftarrow \\ (H \Leftarrow B) \wedge dprove(B, D_1, D_2). \end{split}$$

### Example base-level KB

```
live(W) \Leftarrow
connected\_to(W, W_1) \&
live(W_1).
live(outside) \Leftarrow true.
connected\_to(w_6, w_5) \Leftarrow ok(cb_2).
connected\_to(w_5, outside) \Leftarrow ok(outside\_connection).
delay(ok(X)).
?dprove(live(w_6), [], D).
```



# Querying the User

- The system can determine what information is relevant and ask the user for the particular information.
- A top-down derivation can determine what information is relevant. There are three types of goals:
  - Goals for which the user isn't expected to know the answer, so the system never asks.
  - Goals for which the user should know the answer, and for which they have not already provided an answer.
  - Goals for which the user has already provided an answer.

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#### Yes/No questions

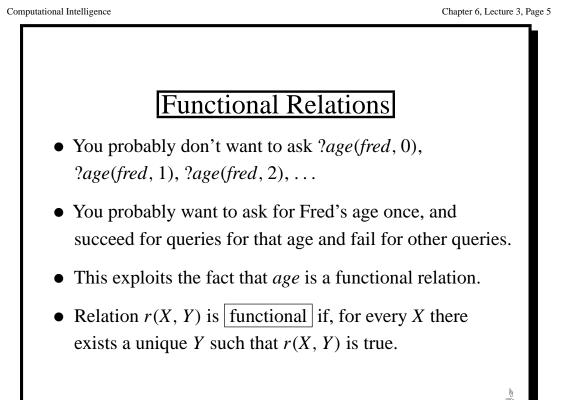
- The simplest form of a question is a ground query.
- Ground queries require an answer of "yes" or "no".
- The user is only asked a question if
  - the question is askable, and
  - the user hasn't previously answered the question.
- When the user has answered a question, the answer needs to be recorded.

#### Ask-the-user meta-interpreter

% *aprove*(G) is true if G is a logical consequence of the% base-level KB and yes/no answers provided by the user.

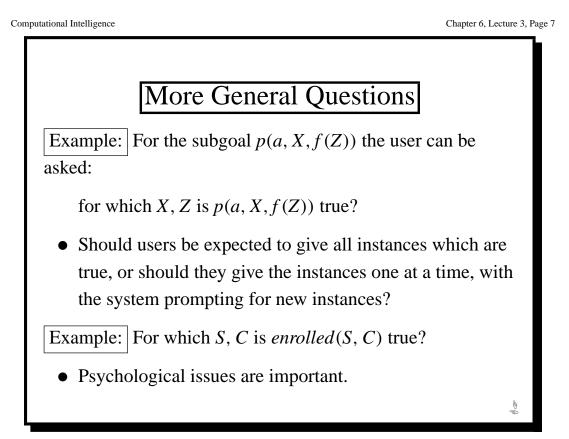
aprove(true).  $aprove((A \& B)) \leftarrow aprove(A) \land aprove(B).$   $aprove(H) \leftarrow askable(H) \land answered(H, yes).$   $aprove(H) \leftarrow$   $askable(H) \land unanswered(H) \land ask(H, Ans) \land$   $record(answered(H, Ans)) \land Ans = yes.$   $aprove(H) \leftarrow (H \Leftarrow B) \land aprove(B).$ 

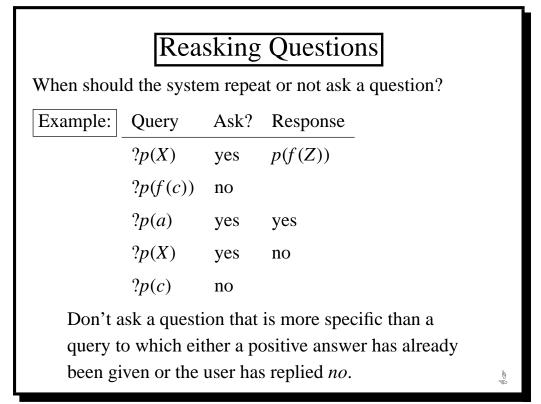
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#### Getting information from a user

- The user may not know the vocabulary that is expected by the knowledge engineer.
- Either:
  - The system designer provides a menu of items from which the user has to select the best fit.
  - The user can provide free-form answers. The system needs a large dictionary to map the responses into the internal forms expected by the system.





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# Delaying Asking the User

- Should the system ask the question as soon as it's encountered, or should it delay the goal until more variables are bound?
- Example consider query p(X) & q(X), where p(X) is askable.
  - If p(X) succeeds for many instances of X and q(X) succeeds for few (or no) instances of X it's better to delay asking p(X).
  - If *p*(*X*) succeeds for few instances of *X* and *q*(*X*) succeeds for many instances of *X*, don't delay.

# Explanation

- The system must be able to justify that its answer is correct, particularly when it is giving advice to a human.
- The same features can be used for explanation and for debugging the knowledge base.
- There are three main mechanisms:
  - Ask HOW a goal was derived.
  - Ask WHYNOT a goal wasn't derived.
  - Ask WHY a subgoal is being proved.

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#### How did the system prove a goal?

• If g is derived, there must be a rule instance

 $g \Leftarrow a_1 \& \ldots \& a_k.$ 

where each  $a_i$  is derived.

• If the user asks HOW *g* was derived, the system can display this rule. The user can then ask

HOW i.

to give the rule that was used to prove  $a_i$ .

• The HOW command moves down the proof tree.

# Meta-interpreter that builds a proof tree

% *hprove*(G, T) is true if G can be proved from the base-level% KB, with proof tree T.

 $\begin{array}{l} hprove(true, true).\\ hprove((A \& B), (L \& R)) \leftarrow\\ hprove(A, L) \land\\ hprove(B, R).\\ hprove(B, R).\\ hprove(H, if(H, T)) \leftarrow\\ (H \leftarrow B) \land\\ hprove(B, T). \end{array}$ 

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### Why Did the System Ask a Question?

It is useful to find out why a question was asked.

- Knowing why a question was asked will increase the user's confidence that the system is working sensibly.
- It helps the knowledge engineer optimize questions asked of the user.
- An irrelevant question can be a symptom of a deeper problem.
- The user may learn something from the system by knowing why the system is doing something.

### WHY question

• When the system asks the user a question *g*, the user can reply with

WHY

• This gives the instance of the rule

 $h \Leftarrow \cdots \& g \& \cdots$ 

that is being tried to prove *h*.

• When the user asks WHY again, it explains why *h* was proved.

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### Meta-interpreter to collect rules for why

% *wprove*(*G*, *A*) is true if *G* follows from base-level KB, and % *A* is a list of ancestor rules for *G*.

wprove(true, Anc). wprove((A & B), Anc)  $\leftarrow$ wprove(A, Anc)  $\land$ wprove(B, Anc). wprove(H, Anc)  $\leftarrow$ (H  $\Leftarrow$  B)  $\land$ wprove(B, [(H  $\Leftarrow$  B)|Anc]).

# Debugging Knowledge Bases

There are four types of nonsyntactic errors that can arise in rule-based systems:

- An incorrect answer is produced; that is, some atom that is false in the intended interpretation was derived.
- Some answer wasn't produced; that is, the proof failed when it should have succeeded, or some particular true atom wasn't derived.
- The program gets into an infinite loop.
- The system asks irrelevant questions.

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# **Debugging Incorrect Answers**

- An incorrect answer is a derived answer which is false in the intended interpretation.
- An incorrect answer means a clause in the KB is false in the intended interpretation.
- If g is false in the intended interpretation, there is a proof for g using g ⇐ a<sub>1</sub> & ... & a<sub>k</sub>. Either:
  - Some  $a_i$  is false: debug it.
  - All  $a_i$  are true. This rule is buggy.



- WHYNOT g. g fails when it should have succeeded. Either:
  - There is an atom in a rule that succeeded with the wrong answer, use HOW to debug it.
  - There is an atom in a body that failed when it should have succeeded, debug it using WHYNOT.
  - There is a rule missing for g.

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# Debugging Infinite Loops

- There is no automatic way to debug all such errors: halting problem.
- There are many errors that can be detected:
  - If a subgoal is identical to an ancestor in the proof tree, the program is looping.
  - Define a well-founded ordering that is reduced each time through a loop.