# SEMI-AUTOMATIC IMPLEMENTATION OF NETWORK PROTOCOLS

by

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### SEMI-AUTOMATIC IMPLEMENTATION OF NETWORK PROTOCOLS

By

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1-2

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### Abstract

A compiler which achieves automatic implementation of network protocols by transforming specifications written in FDT into C programs is presented. A brief introduction to the the fundamentals of FDT, a standard language developed by ISO/TC97/SC 16/WG 1 Subgroup B for specifying network protocols, is given. We then present an overview of the compiler and discuss the problem of *PASCAL* to C translation. Transformation of a FDTspecification into code is explained and illustrated by two implementation examples. The first example illustrates the implementation strategy by tracing the processing of a simple protocol. The second example demonstrates the validity of using automatically generated implementations by showing how a communication path was established between two hosts using code generated for the alternating bit protocol.

Son Lawry

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# Table of Contents

| Abstract   | ii  |
|--|-----|
| Acknowledgement  | iii |
| Table of Contents  | iv  |
| Table of Figures   | vi  |
| Chapter 1: Introduction                                    | 1   |
| 1.1 Motivations and Objectives                             | 1   |
| 1.2 Previous Research and Thesis Contribution              | 2   |
| 1.3 Thesis Outline   | 3   |
| Chapter 2: FDT—A Formal Description Technique of Protocols | 4   |
| 2.1 Overview   | 4   |
| 2.2 Module   | 5   |
| 2.3 Channel  | 5   |
| 2.4 Process  | 6   |
| 2.5 Refinement   | 8   |
| Chapter 3: The FDT Compiler                                | 10  |
| 3.1 The Compiler   | 10  |
| 3.2 Pascal to C Translation                                | 10  |
| Chapter 4: Translating FDT Specifications into C Code      | 13  |
| 4.1 Overview   | 13  |
| 4.2 Data Structure   | 14  |
| 4.3 Initialization Routines                                | 15  |

| 4.4 Transition Routines                           | 17 |
|---|----|
| Chapter 5: Illustrative Implementation Examples   | 19 |
| 5.1 Example 1—The Hot Potato Protocol             | 19 |
| 5.1.1 Implementation Code                         | 23 |
| 5.1.2 Execution Description                       | 30 |
| 5.1.3 Transition Processing                       | 34 |
| 5.2 Example 2—The Alternating Bit Protocol        | 34 |
| Chapter 6: Conclusion                             | 37 |
| 6.1 Thesis Summary                                | 37 |
| 6.2 Future Work                                   | 38 |
| References  | 39 |
| Appendix I: FDT Grammar                           | 41 |
| Appendix II: Utility Routine Listings             | 49 |
| Appendix III: Listdefs.h                          | 63 |
| Appendix IV: Alternating Bit Specification        | 64 |
| Appendix VI: Utility Routines for Alternating Bit | 73 |
| Appendix VI: Alternating Bit Implementation Code  | 81 |
| Appendix VII: Running the Compiler                | 92 |

# Table of Figures

| Figure 1: Example Module Specification                               |  |
|--|--|
| Figure 2: Example Channel Specification 6                            |  |
| Figure 3: Example Process Specification                              |  |
| Figure 4: Example Refinement Specification                           |  |
| Figure 5: Illustration of Hot Potato Protocol Machines 20            |  |
| Figure 6: FDT Specification of Hot Potato Protocol                   |  |
| Figure 7: FDT Specification of Player Process                        |  |
| Figure 8: Implementation Code for Hot Potato Protocol 25             |  |
| Figure 9: Initialization Routine for hot_ref 26                      |  |
| Figure 10: Initialization Routine for team_ref 27                    |  |
| Figure 11: Initialization Routine for player_process                 |  |
| Figure 12: Transition Routine for player_process                     |  |
| Figure 13: Representation Data Structures for Hot Potato Protocol 31 |  |

### Chapter 1

### Introduction

#### 1.1 Motivations and Objectives

Network protocols have historically been specified in large informal documents prepared by the protocol designer. This imprecise method of specifying such a complex entity was potentially a source of problems when it came time to implement the protocol, particularly when done by someone other than its designer. The document might contain ambiguities or contradictions or it may simply be too vague. All of these inadequacies can impose implementation decisions which may or may not be compatible with decisions made for other implementations of the same protocol. Another problem of an informal specification is that it excludes the possibility of processing the protocol specification to automatically generate an implementation.

In an effort to provide more precise specification techniques, various models for protocols have been proposed [Boch 80]. The two most useful of which have been finite state machine and Petri net models. In a finite state machine model the entities in the protocol (e.g. sender, receiver) are each described as state machines. In a Petri net model the entire protocol is described in terms of a Petri net.

A practical formalism of the finite state machine model has been developed in the form of a PASCAL like language called Formal Description Technique (FDT) [ISO 84]. In addition to providing unambiguous specifications, the programming language nature of FDTmakes it particularly amenable to processing and the automatic generation of implementations directly from their specifications. Developing such an automatic implementation capability would remove the errors introduced by manual interpretation and implementation. Furthermore, it would allow the widespread installation of the protocol on differing machines and operating systems, subject to the availability of a translation tool (compiler) for each environment.

The motivation for this thesis is the production of such a translation tool. A tool which would correctly implement a protocol specification written in FDT and be as portable as possible. Achieving this goal would let installers working in different environments use the same implementation tool, thereby enhancing the compatibility of their installations and providing absolute portability of protocols at the FDT source code level.

A way of approaching this goal is to use a portable high level language as both the implementation and target languages of the compiler. At present, one of the most portable languages is C [Kern 78]. Consequently, the ultimate objective of this thesis is the production of a *FDT* compiler written in C which also uses C as its target language.

#### **1.2 Previous Research and Thesis Contribution**

There have been various attempts to produce compilers which process protocol specifications. Blummer and Tenney [Blum 81] describe one for an early version of *FDT*. Hansson [Hansson 84] describes the design of an "an integrated design environment" which provides a number of tools to aid the protocol designer and which automatically produces an implementation.

George Gerber, at the University of Montreal, has implemented a compiler in DEC PASCAL on a VAX-11 running VMS and which uses DEC PASCAL as its target language [Gerber 83]. Initial attempts by the author to port this compiler to Berkeley UNIX 4.2 BSD were unsuccessful however due to incompatibilities between Berkeley PASCAL and DEC PASCAL. While it is possible to manually alter the FDT compiler's source code to con-

2

form to Berkeley *PASCAL*, such efforts are for naught since it would still produce relatively non-portable *DEC PASCAL* code which again would require manual processing before it could be compiled.

This lack of success in porting the compiler underscores the need for a more portable tool. By using C as both the implementation and target language of an FDT compiler, it will be as portable as is presently possible.

### 1.3 Thesis Outline

Chapter 2 of the thesis gives an overview of the FDT language, Chapter 3 gives a short description of the compiler implemented and a discussion of *PASCAL* to *C* translation, Chapter 4 describes the technique used to produce an implementation from a FDTspecification, Chapter 5 presents two implementation examples which illustrate the techniques described in Chapter 4, and finally, Chapter 6 concludes the success of the implementation and offers suggestions for further enhancements.

### Chapter 2

### FDT-A Formal Description Technique of Protocols

#### 2.1 Overvlew

FDT (Formal Description Technique) is a language developed by Bochmann and ISO/TC97/SC16/WG1 subgroup B [ISO 84] for specifying network protocols that is based on the PASCAL programming language [Jensen 74]. The underlying model used in the FDT approach is one of communicating finite state automatons called protocol machines which exchange signals with each other and with their system environment. Except for intercommunication, the protocol machines are totally independent and operating in parallel.

FDT is really the melding of a state machine formalism and a PASCAL engine. This powerful combination allows the construction of extended state transition models. Such models use the variables of a programming language to augment the memory capabilities of a state machine. The net result is a powerful machine with a vastly smaller state space than would normally be possible.

In FDT the behaviour of a protocol machine can be specified in two ways. Either directly by a corresponding state machine described by a list of state transitions and associated actions or indirectly, by specifying a subsystem of interconnected protocol machines. The subsystem would have appropriate connections between internal interaction points and those of the enclosing machine being defined. Note that internal protocol machines are no different from any other and may themselves be specified as a composition of other state machines.

The non-procedural (i.e. non-PASCAL) part of the language is concerned with the

definition of the protocol machines and their interconnections. Four concepts are embodied in the language and are combined to produce a specification. A module corresponds to a type of protocol machine. A channel represents a communication path between two protocol machines (modules). A process is a declaration of a finite state machine. And a refinement is specification of protocol machine instances and their interconnection.

#### 2.2 Module

Conceptually, each module type specified in a FDT specification represents one particular type of protocol machine. The actual behavior of which will be specified directly by a *process* or indirectly by a *refinement*.

As it is used in the language a *module* is a precise specification of the types (i.e. channel types) of interaction points belonging to a protocol machine. A *FDT* module specification is simply a list of interaction points. Each of which is given an identifier and a channel type in a manner analogous to a variable declaration.

The example shown in Figure 1 declares a module called *team*. This module has two interaction points called *tossin* and *tossout*, both are of channel type *toss*. The interaction point *tossin* plays the role of "catcher" and *tossout* plays the role of "thrower".

#### MODULE team;

toesin : toss(catcher);

tossout: toss(thrower);

end leam;

Figure 1. Example Module Specification

#### 2.3 Channel

In the model a channel is a communication path existing between two protocol

machines.

In a FDT specification, a channel is a precise description of the signals that may be sent via a particular interaction point by the protocol machines on either side. A FDT channel specification gives names to the roles played by the protocol machines (modules) on each side of the interaction point (e.g. provider/user, inputer/outputer etc.) which serve to distinguish one side from the other, and lists the signals, with any optional data fields, that can be sent by each.

In Figure 2 below is an example channel declaration for a channel type called *toss*. This channel type distinguishes the two sides of the interaction point as *thrower* and *catcher*. Where the "thrower" side is allowed to send the message *potato*, which has two integer data fields, and the "catcher" side is allowed to send the message *thanks*.

CHANNEL toss (thrower, catcher);

by thrower: potato (thrower\_team, thrower\_num : integer);

by catcher: thanks; end toss; Figure 2. Example Channel Specification

#### 2.4 Process

A process defines an (extended) state machine and is the atomic specification of the behavior of a protocol machine.

A FDT process specification is a list of the transitions of a state machine, a declaration of the queueing status of each interaction point declared in the associated module, local variable declarations for the extended state model and declaration of initial values for those variables. The queueing status of an interaction point states whether the signals sent via it are queued or not before being accepted by a protocol machine. When signals are not queued they are processed immediately upon arrival by the receiver (*rendez-vous*), even if this means suspending the processing of the sender.

Each transition listed in a process consists of two parts, an enabling condition and an operation. An enabling condition is a specification of:

- the present state (FROM clause)
- an input signal (WHEN clause)
- an enabling predicate (PROVIDED clause)
- a transition priority (PRIORITY clause)

Note that not all of the above need be present for every transition. In particular, if the input signal specification (WHEN clause) is absent the transition is *spontaneous*. There is also another clause, the ANY clause, which is to be used only in spontaneous transitions for selecting "random" values.

The operation portion of each transition consists of an optional specification of the next machine state (TO clause) and the action to be performed, usually a small fragment of a PASCAL program.

Figure 3 below contains a sample process declaration. It defines a process called player\_process for the module type player. The process has two integer parameters *leam\_num* and player\_num which are used to pass values to be stored as part of the state information of the state machine. The first statement declares that the two interaction points *left* and *right*, of the module player are to queue their signals. The next two statements declare local variables and give them initial values. The rest of the process is a list of three transition specifications. The first of which will occur whenever a potato signal is received via the *left*  interaction point, the second when a *thankyou* signal is received via the right interaction point, and the third occurs spontaneously.

PROCESS player\_process(team\_num, player\_num : integer) FOR player; QUEUED left, right; (\* queuing status \*) VAR (\* local variable declarations \*) the\_team, the\_player : integer; INITIALIZE (\* local variable initiallization \*) begin the\_team := team\_num; the\_player := player\_num; end; TRANS (\* potato message on left \*) WHEN left.potato begin writeln('Player ', the\_player,' of team ', the\_team,' caught a potato from player ', thrower\_num, ' of team ', thrower\_team); OUT right.potato(the\_team,the\_player); OUT left.thcnks; end; TRANS (\* thanks message on right \*) WHEN right.thanks begin writeln('Player ', the\_player,' of team ', the\_team,' got a thankyou'); end; TRANS (\* spontaneous \*) provided (*lthe\_player = 1*) and (*the\_team = 1*)) begin OUT right.potato(the\_team,the\_player); end; end player\_process;

Figure 3. Example Process Specification

### 2.5 Refinement

The concept of a refinement is an indirect specification of the behaviour of one protocol machine in terms of the combined behaviour of a set of other protocol machines.

A FDT refinement specification specifies the internal structure of a protocol machine.

This includes the declaration of new, internal, channel and module types as well as processes

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and other refinements. Internal refinements, in turn, can have their own internal declarations. The internal structure is defined by three sets of declarations; one for the protocol machine instances (i.e. a module and a process or a refinement), one for protocol machine interconnection (*CONNECT*) and one for the connections between internal interaction points and those of the enclosing machine being defined (*REPLACE*).

In the sample refinement shown in figure 4, one sees the internal declaration of a state machine's interaction points (the module player) and transitions (the process player\_process). Instances of this machine, P1 and P2, are declared and then interconnected with the statement P1.right to P2.left. The refinement's REPLACE section establishes equivalence (a connection) between the interaction points tossin and tossout declared in its associated module team and the internal interaction points P1.left and P2.right.

### REFINEMENT team\_ref(team\_num : integer) FOR team; MODULE player;

left : toss(catcher);

right: loss(thrower); end player;

PROCESS player\_process(team\_num, player\_num : integer) FOR player; (\* declaration omited see figure 3 \*) end player\_process;

(\* instances \*)

P1: player with player\_process(team\_num, 1); P2: player with player\_process(team\_num, 2);

CONNECT

P1.right to P2.left;

REPLACE

tossin by P1.left; tossout by P2.right; end team\_ref;

Figure 4. Example Refinement Specification

### Chapter 3

10

### The FDT Compiler

#### 3.1 The Compiler

The FDT compiler was developed on a VAX-11/750 running Berkeley UNIX 4.2 BSD. The implementation language used was C. Certain sections of the compiler were produced by program generators. The lexical analysis module was generated by the *LEX* [Lesk 75] utility and the parser was generated by the *YACC* [John 75] LALR parser generator utility. Both are standardly available in UNIX environments.

Not including the automatically generated code, the compiler consists of some 8000 lines of C and approximately 200 modules. It is structured much like all compilers, having the standard lexical analysis, parser and symbol table modules. Processing uses no intermediate forms and is completed in one pass of the source specification.

The following section discusses one of the main jobs of the compiler, the translation of PASCAL to C.

### 3.2 Pascal to C Translation

One of the primary issues addressed during the implementation of the compiler was the problem of translating programs and statements written in PASCAL to their equivalent representations in C. Translation between the two languages is almost straight textual substitution, they being very similar in nature having almost identical control constructs and data types. However, enough differences remain to impose limitations on the ease with which the process can be performed.

10

Generally, generating a C program from a given *PASCAL* program does not require sophisticated processing. *Begin/end* pairs are replaced by pairs of braces (i.e. { }) and data types like *reals* translate to *floats*. All of the control constructs of *PASCAL* have direct equivalents in C, and some even have the same names (e.g. FOR, WHILE etc.). While it is tempting to think that a text editor is more suited to the job than a powerful compiler. The language differences however preclude this possibility.

For example, the two languages have different formats for specifying I/O. PASCAL adopts a style similar to that of FORTRAN or PL/1, while C uses its own considerably different format. Direct translation between the two is difficult but not impossible, but certainly beyond the power of even a sophisticated text substitution system. A simple solution to the problem is to produce one C output statement (i.e. *printf*) for each field in the PASCAL format list.

PASCAL has a different mechanism from C for specifying a return value for a function. PASCAL uses an assignment to the function identifier and C uses a return statement. A solution to this problem is to declare a variable in the corresponding C function to hold the return value and then return it with a return statement.

The main difference between the two languages and the hardest one to overcome is their different approaches to defining the scope of identifiers. *PASCAL* views identifier scope as a variable gradation between being global to the entire program and local to a particular routine. C on the other hand, has only two levels of identifier scope (within one source file), external (global) and internal (local). *PASCAL* for instance allows function and procedure definitions to be nested while C does not. Implementing a scheme for automatically translating between the two views is not easy.

Two solutions to the problem are to use multiple output files for the generated C code or make all identifiers external and systematically rename them to avoid conflicts. Both will

11

work but, particularly in the former case, would be somewhat cumbersome to implement.

The solution adopted by this *FDT* compiler is to simply ignore the problem since the types of programs likely to be processed are unlikely to require extensive use of *PASCAL*'s scoping rules. This approach does have implications for the user as it prohibits the use of shared identifiers and global data references but should not be too much of a problem.

All in all, the problem of translating programs from PASCAL to C is not too difficult provided some restrictions on the types of programs processed can be imposed.

### Chapter 4

### Translating FDT Specifications into C Code

#### 4.1 Overview

Generating a high level language program that implements a protocol specified in FDT is not a difficult task. The declarative part of FDT which specifies the protocol machines, their interconnection and the signals they pass, translates into simple conditional expressions, calls to predefined routines and structure (record) declarations. The *PASCAL* parts of the specification translate directly, requiring relatively little extra processing.

The implementation strategy adopted is the same one used successfully by Gerber in his FDT compiler [Gerber 83]. This approach produces two sets of routines from a FDT specification. One set, the *transition routines*, implements the transition processing of the protocol machines, and the other, the *initialization routines*, is responsible for constructing a data structure that represents the machines and their interconnections.

The transition routines are simply a series of conditional expressions and program blocks. The expressions evaluate the enabling conditions of state transitions and the program blocks implement the associated operations.

The initialization routines use a couple of predefined utilities to construct small parts of the data structure which are then joined to produce the complete representation.

The binding force between these two groups of routines is a couple of prewritten driver routines which use the initialization routines to create the necessary data structure and then the transition routines to process the transitions of the protocol machines. The driver routines are an initialization routine (system\_init) and a transition scheduler (schedule) which directs the processing of signals.

#### **4.2 Data Structure**

The data structure used to represent the protocol machines and their interconnections consists of a set of linked records. In all, four record structures are used, to store state information (process block), to represent an interaction point (channel block), to represent a signal and its data fields (signal block) and finally, to store index information for aggregate (array) interaction points (index block). When linked appropriately, records of these four types can represent arbitrarily complex FDT structures in a simple manner.

The representation of one protocol machine instance, and the storing of its state information, is performed by one instance of the process block record type. This record structure has fields for the major state variable (if there is one) and any local variables. It also stores the identifier of, and a pointer to, the instance's transition routine.

Process block records also contain links to other process block records and to a list of channel block records representing the protocol machine's interaction points.

Each interaction point of a protocol machine instance is represented by a channel block record. Actually a channel block record only represents half of an interaction point, the other half being represented by another channel block record belonging to the protocol machine on the other side of the interaction point. The channel blocks representing the interaction ponts of a particular machine instance are joined together to form a linked list attached to the process block of that instance.

Each channel block record stores two numbers to identify it, the first is the number of the interaction point and the second is the index of the channel block record for an aggregate interaction point. In addition, each record also contains pointers to the channel and process blocks on the other side of the communication path. These pointers constitute the actual connection between two protocol machines.

The queue of signals which can exist at an interaction point is represented by a list of signal block records attached to a channel block record.

Signal block record instances represent messages sent by a protocol machines. They contain fields to store an identifying number and optional transmitted data. Instances are not produced by the initialization routines but come from the execution of *OUT* statements in transition routines.

Finally, those channel records belonging to aggregate interaction points store their index specified in the *FDT* source via a list of index block records. The index number stored in the channel record is the ordinal of the interaction point in a row-major ordering of the array. Index block records simply contain a single number that is the value of one dimension of an array. These values are required by the enabling conditions of transitions to identify, and possibly test, the identity of an interaction point receiving a signal.

#### **4.3 Initialization Routines**

The set of initialization routines contains two types, those that generate a representation of a machine instance (i.e. a process block and its channel list) and those that combine the machine representations into larger structures. Each process specification in the *FDT* source produces one routine belonging to the first group, and each refinement specification produces one belonging to the second. Both groups make use of a series of prewritten utilities to perform their functions.

The process initialization routines are quite simple. Their only responsibility is to construct the part of the data structure needed to represent one machine instance. They merely allocate a process block record, attach a list of channel block records, perform any initialization specified in the *FDT* source, and then add the process block record to a linked list. The refinement initialization routines are a bit more complex as they must create a complete representation of the structures defined within them. Their task is simplified somewhat by the use of initialization routines from both groups to construct the machine instance representations. Their main job then becomes the combining of these small sections into one larger one representing the internal structure.

The operations performed by a refinement initialization routine can be divided into four phases, three of which correspond to the instance, connection and replacement sections of a FDT refinement and the fourth to what could be termed a "clean up" phase.

The instance section of a refinement defines the number and type of protocol machines in the internal structure. Each instance specification causes a call to the appropriate process or refinement routine to be generated, this call will simply add another machine instance on to a linked list.

The connection section of a refinement specifies which interaction points of the protocol machine instances are joined together. Each interconnection generates one call to a prewritten utility called *connect\_ports* which does the actual pointer manipulation to form the connection.

The replacement section of a refinement specifies which internal interaction points are to be used for the external interaction points of the protocol machine being defined. The corresponding code in the refinement initialization routine first generates what is termed a "refinement header", consisting of a process block record and a channel block record list, and which represents the external protocol machine and its interaction points. The list of process block records produced by the instance and connection phases and which is now termed the "refinement body" is linked to the refinement header. Each replacement specification in the FDT source generates a call to a prewritten utility  $replace_ports$  which makes connections between the channel block records in the refinement header and those in the refinement body.

The refinement header is really a place holder whose purpose is to mimic a process block and channel list produced by a process initialization routine. This uniformity in representation allows protocol machine instances from both process and refinement initialization routines to appear to be identical in the process block record list processed by the connection and replacement phases of a refinement initialization routine. This allows a consistent numbering scheme to be employed when specifying interconnections. The prewritten utilities *connect\_ports* and *replace\_ports* are smart enough to recognize connections to refinement headers and will make the actual connections to internal channel block records in the refinement bodies attached to the headers.

The fourth phase of a refinement routine, the "clean up" phase, is where the refinement headers holding the place of a protocol machine representation in the refinement body are removed and replaced by their refinement bodies. This task is performed by the prewritten utility *clean\_up*.

#### **4.4 Transition Routines**

The actual implementation of a specified protocol, as opposed to simply creating a data structure, is achieved by a section of the generated code known as the transition routines. These routines, together with the prewritten transition scheduler, completely embody the behaviour of the model described in the FDT source.

The transition scheduler calls a transition routine whenever it decides that some processing should occur. The transition routine receives from the scheduler a process block record and possibly channel and signal block records. The process block record contains the state information of the machine instance needed to correctly process the state transitions. If the transition routine does receive channel and signal block records then the associated proto-

17

col machine has received a signal at an interaction point (the one represented by the channel block record), if the signal does not cause a transition it is simply requeued. If the routine does not receive the records then the scheduler has decided that a spontaneous transition should be attempted by the transition routine.

For their part the transition routines consist of a series of if statments, each of which corresponds to one transition in the FDT source. The boolean expression in the statement evaluates the truth value of the enabling condition and the body contains the associated action.

### Chapter 5

### **Illustrative Implementation Examples**

This chapter presents two protocols and describes their implementation. The first protocol is a simple one invented to illustrate the implementation process. The second is the alternating bit protocol.

#### 5.1 Example 1—The Hot Potato Protocol

The simple protocol described below is an excellent vehicle for illustrating the implementation process used by the compiler. This protocol models a system of two "teams" of two "players" which continuously pass a message (a hot potato) around in a circle. Its specification contains a good sampling of the features of contained in *FDT*. In addition to the standard specification of channels, modules, processes and refinements, it contains composite protocol machine definitions and argument passing to processes and refinements.

The actions of each "player" in the protocol are identical and specified by one process. When a player receives a "potato" message from the player on his left he prints a message identifying himself and the player who sent the message. He then sends a "thankyou" message to that player and a new potato message to the player on his right.

The teams are organized identically and specified by a single refinement. The players are conceptually side-by-side, with the right of one being connected to the left of the other.

The teams are joined by connecting the two remaining sides of the players on one team to their opposite numbers on the other. Figure 5 shows the interconnection of the protocol machines involved.

As part of his local state information each player stores two numbers, one identifies his

team and the other is his player number within the team.

The complete FDT specification for the protocol is shown in Figures 6 and 7 below.



Figure 5. Illustration of Hot Potato Protocol Machines

MODULE hot\_potato; end hot\_potato;

REFINEMENT hot\_ref FOR hot\_potato;

CHANNEL toss (thrower, catcher); by thrower: polato (thrower\_team, thrower\_num : integer); by catcher: thanks; end toss;

MODULE team; tossin : toss(catcher); tossout: toss(thrower); end team;

REFINEMENT team\_ref(team\_num : integer) FOR team;

MODULE player; left : toss(catcher); right: toss(thrower); end player;

PROCESS player\_process(team\_num, player\_num : integer) FOR player; (\* see Figure 7 for definition \*) end player\_process;

P1: player with player\_process(team\_num, 1); P2: player with player\_process(team\_num, 2);

CONNECT P1.right to P2.left;

REPLACE tossin by P1.left; tossout by P2.right; end team\_ref;

T1: team with team\_ref(1); T2: team with team\_ref(2);

CONNECT T1.tossout to T2.tossin; T2.tossout to T1.tossin;

end hot\_ref;

Figure 6. FDT Specification of Hot Potato Protocol

```
PROCESS player_process(team_num, player_num : integer)
                            FOR player;
      QUEUED left, right; (* queuing status *)
      VAR (* local variable declarations *)
       the_team, the_player : integer;
     INITIALIZE (* local variable initiallization *)
       begin
        the_team := team_num;
        the_player := player_num;
       end;
      TRANS (* potato message on left *)
       WHEN left.potato begin
         writeln('Player ',the_player,' of team ',
             the_team,' caught a potato from player ',
             thrower_num, ' of team ', thrower_team);
         OUT right.potato(the_team, the_player);
         OUT left.thanks;
       end;
      TRANS
                (* thanks message on right *)
       WHEN right.thanks begin
         writeln('Player ', the_player,' of team ',
            the_team,' got a thankyou');
           end;
```

TRANS (\* spontaneous \*) provided ((the\_player = 1) and (the\_team = 1)) begin OUT right.potato(the\_team, the\_player); end;

end player\_process;

#### Figure 7. FDT Specification of Player Process

The overall structure of the system is contained by the top level refinement hot\_ref which is specified for the empty, top level, module hot\_potato. This refinement, directly or indirectly, contains all of the other declarations. The system structure is defined by the instance and connection specifications at the end of hot\_ref. The refinement *team\_ref* is similar to *hot\_ref* except that it also has a replace specification which defines which interaction points, internal to *team\_ref*, are to be used for the interaction points *tossin* and *tossout* of the refinement's module *team*. Note that *hot\_ref* does not have a replace specification as its module *hot\_potato* does not define any interaction points.

In the instance specifications, both refinements pass arguments to the refinement or process used. In *hot\_ref* one number identifying the team of the instance is given to the refinement *team\_ref*, which passes it and a player number to the process *player\_process* in its instance specification. *Player\_process* stores the numbers it receives as part of the local state information of each machine instance.

The actions of the players in the protocol are specified by *player\_process*. It declares that the two interaction points, *left* and *right*, of its module *player* are to queue their signals, that the protocol machine has two local variables, *the\_team* and *the\_player*, and that they are to be initiallized to the values of the two parameters passed.

The first transition of *player\_process* occurs whenever a potato message arrives via the left interaction point. It prints a message and transmits two more messages.

The second transition occurs whenever a *thanks* message arrives via the right interaction point of the protocol machine, it also prints a message.

The third transition will only occur for player one of team one when the transition scheduler detects that there are no messages enqueued and awaiting processing. For this protocol that only occurs a the start of processing.

#### 5.1.1 Implementation Code

The implementation code produced by the compiler is placed into one output file. The

first entries in this file are a series of "#include's" whose purpose is to direct the C compiler to include files like the C standard input/output library (stdio.h). The next entries are the signal and process block declarations and then various initiallization, transition and user defined procedures which are in no particular order. The finally entry of the file is another "#include" which directs the C compiler to include (compile) the prewritten utility routines.

The output file generated for the example in Figures 6 and 7 is shown in Figure 8. The bodies of the procedures have been deleted for brevity and are show individually in later Figures.

```
#include <stdio.h>
#include < strings.h>
#include "listdefs.h"
struct signal_block {
      int signal id;
      struct signal_block #next;
      union { struct { struct {
                  int thrower_team, thrower_num;
                 } potato;
           } 1088;
      } lvars;
};
struct process_block {
      struct process_block *next;
      char p_ident[MAX_IDENT_LENGTH+1];
      struct channel_block *chan_list;
      struct process_block *refinement;
     int (*proc_ptr)();
      union { struct {
                 int the_team, the_player;
           } s_player_process;
     } luars;
};
struct process_block *iohot_ref(p_block)
struct process_block *ioteam_ref(p_block, team_num)
struct process_block *ioplayer_process(process_list, team_num,
                                     player_num)
player_process()
#include "fdtutil.c"
```

#### Figure 8. Implementation Code for Hot Potato Protocol

The signal block declaration contains two fields, thrower\_team and thrower\_num, which store the data values of a potato message. If there had been other channel declarations, at any level of nesting containing messages with data fields, they to would have appeared in the declaration.

The process\_block declaration has similar fields for the storage of variables for a proto-

col machine instance. It also contains the identifier and a procedure pointer to the transition routine associated with the process\_block instance.

The initiallization and transition routines follow the two structure declarations. They use the same identifiers as their associated refinement or process in the the FDT source, with the exception that the initiallization routines also have a "io" prefix. This prefix is necessary to distinguish between the two routines, one initiallization and one transition, generated for each process specification.

The initiallization routine generated for the refinement *hot\_ref* is *iohot\_ref* and is shown in Figure 9. This procedure is called by the system initiallization utility to generate the entire representation data structure.

```
struct process_block *iohot_ref(p_block)
```

connect\_ports(process\_list, 2, 2, 0, 1, 1, 0); connect\_ports(process\_list, 1, 2, 0, 2, 1, 0);

p\_block = add\_refinement\_header(p\_block, process\_list);
p\_block->refinement = clean\_up(p\_block->refinement);

return(p\_block);

Figure 9. Initiallization Routine for hot\_ref

The initiallization routine generated for the refinement *team\_ref* is shown in Figure 10. It is slightly more complex than iohot\_ref as it must also add channel blocks to its refinement
header (add\_channel\_block) and establish connections between them and internal interaction points (replace\_ports).

The calls to connect\_ports in Figures 9 and 10 contain a cryptic set of numbers as arguments to the routine. These numbers describe which two channel blocks are to be interconnected to form the interaction point. For example, the set of three numbers 2, 2, 0, tells connect\_ports to look in the channel list of the second process block in the process list for a channel block containing the two numbers 2 and 0. Calls to replace\_ports contain similar sets of numbers except that the process block number for the first channel block is not required because the channel list is know to be in the refinement header and so is omitted. Note that the numbering of the process blocks in the list is the reverse of their creation since the initiallization routines place them at the front of the process block list.

process\_list = NULL; process\_list=ioplayer\_process(process\_list, team\_num, 1); process\_list=ioplayer\_process(process\_list, team\_num, 2);

connect\_ports(procces\_list, 2, 2, 0, 1, 1, 0);

replace\_port(p\_block, 1, 0, 2, 1, 0); replace\_port(p\_block, 2, 0, 1, 2, 0);

 $p_block > refinement = clean_up(p_block > refinement);$ 

return(p\_block);

}

Figure 10. Initialization Routine for team ref

The two declarations of  $ioplayer_process$  in Figures 9 and 10 is not an error, simply a harmless idiosyncrasy of the compiler which was left in to ease the implementation of the compiler. The C compiler will not complain about multiple function definitions so long as they are consistent.

The initiallization routine generated for the process player\_process is shown in Figure 11 and the transition routine in figure 12.

p\_block->lvars.s\_player\_process.the\_team = team\_num;

return(p\_block);
}

Figure 11. Initiallization Routine for player\_process

player\_process(p\_block, channel, signal) struct process block \*p block; struct channel block \*channel; struct signal block \*signal; { struct signal\_block \*s\_ptr;

if ((channel != NULL)) if ((channel->c\_id == 1) & (signal->signal\_id == 0)) {{ printf("Player "); printf("%d",p\_block->lvars.s\_player\_process.the\_player); printf(" of team "); printf("%d",p\_block->lvars.s\_player\_process.the\_team); printf(" caught a potato from player "); printf("%d", signal->lvars.toss.potato.thrower\_num); printf(" of team "); printf("%d", signal->lvars.toss.potato.thrower\_team); printf("0);

s\_ptr = ALLOCATE(signal\_block); s\_ptr->signal\_id = 0; s ptr->lvars.toss.potato.thrower\_team = p\_block->lvars.s\_player\_process.the\_team;

s ptr->lvars.loss.potato.thrower\_num = p\_block->lvars.s\_player\_process.the\_player;

out(p\_block-> chan\_list, s\_ptr, 2, 0);

s\_ptr = ALLOCATE(signal\_block); s\_ptr->signal\_id = 1; out(p\_block-> chan\_list, s\_ptr, 1, 0); } goto dispose; }}

if ((channel != NULL))if ((channel->c id == 2) && (signal->signal\_id == 1)) {{{ printf("Player"); printf("%d",p\_block->lvars.s\_player\_process.the\_player); printf(" of learn "); printf("%d",p\_block->lvars.s\_player\_process.the\_team); printf(" got a thankyou"); printf("0); } goto dispose; }}

if (channel != NULL) { requeue(channel, signal); signal = NULL;}

if (((((p\_block->lvars.s\_player\_process.the\_player == 1)) && ((p\_block->lvars.s\_player\_process.the\_team == 1))))) {{ s\_ptr = ALLOCATE(signal\_block); s\_ptr->signal\_id = 0; s\_ptr->lvars.toss.potato.thrower\_team = p\_block->lvars.s\_player\_process.the\_team; s\_ptr->lvars.toss.potato.thrower\_num = p\_block->lvars.s\_player\_process.the\_player; out(p\_block->chan\_list, s\_ptr, 2, 0); } goto dispose; } dispose: free(signal);

}



#### 5.1.2 Execution Description

The creation of the data structure that represents the interconnected protocol machines that implement the *hot\_potato* protocol is initiated by a call to the initiallization routine *iohot\_ref* by the prewritten utility *system\_init*. The subsequent sequence of calls to the other initiallization routines and the construction of the data structure are described below.

The first operation performed by *iohot\_ref* is to call the routine *ioteam\_ref*, which, in turn, calls the initiallization routine *ioplayer\_process* twice to create two protocol machine instances. The structure returned by one of these calls is shown in part (a) of Figure 13.

Interaction points of the two instances. The resulting structure is a refinement body and is shown in part (b) of Figure 13.

Next, *ioleam\_ref* creates a refinement header (add\_refinement\_header), attaches the refinement body and calls *replace\_ports* to make interconnections between the header and the body. Its job is then completed by calling the prewritten utility *clean\_up* which in this case has no work to do and then returning. The complete structure returned by *ioleam\_ref* is shown in part (c) of Figure 13.

Iohot\_ref now receives control and proceeds to call ioteam\_ref a second time to generate another machine representation. That structure is shown in part (d) of Figure 13.

With the construction of the two instances now complete *iohot\_ref* calls *connect\_ports* to interconnect them. *Connect\_ports* will detect that it is making connections between refinement headers and will connect to the appropriate channel blocks in their refinement bodies instead.

*lohot\_ref* then creates a refinement header (without channel blocks) for the refinement body (i.e. the two structures returned by *ioteam\_ref*).





(b)



Figure 13. Representation Data Structures for Hot Potato Protocol



Figure 13. Representation Data Structures for Hot Potato Protocol (continued)



Figure 13. Representation Data Structures for Hot Potato Protocol (continued)

#### **5.1.3 Transition Processing**

When the initiallization routines have completed their task and built the representation data structure the transition scheduler receives control.

The scheduler distributes enqueued messages and spontaneous transitions in a round robin manner.

The identities of the spontaneous routines are hand coded into the scheduler by the user (not everything is automatic!). The user enters a series of string comparisons between the identifier stored in the process\_block instances and the identifiers of the spontaneous transition routines. These tests are OR'ed together and become the boolean expression of an *if* statement that decides whether to call the transition routine to attempt a spontaneous transition.

In this example, when the scheduler first receives control it tests for the existence of enqueued signals. Discovering that none exist it proceeds to search the process block list for a process block that contains a transition routine identifier matching one of those known (hand coded) to contain a spontaneous transition. The first block tested just happens to contain (like the others) such an identifier (*player\_process*) so the scheduler calls that routine. Once a signal does get enqueued by the spontaneous transition of the protocol machine of player one, team one, the scheduler stops searching for a spontaneous transition and goes about the job of dispatching signals.

#### 5.2 Example 2—The Alternating Bit Protocol

The second example is an implementation of the alternating bit protocol which serves to illustrate the ability of the compiler to implement a real protocol. The specification of the protocol is taken from the ISO working document [ISO 84] and is shown in Appendix IV.

The specification contains one, top level, refinement *ab\_ref*, and five module types *ab\_pc*, *Alternating\_Bit*, *timer*, *network* and *user*. It also has four different channel types and various messages.

The specification models the typical situation of a protocol machine on a particular level of abstraction. It has the alternating bit protocol machine and a system entity (timer) on one level, as well as entities on the levels above (user) and below (network).

This specification was used to create a communication path between two separate hosts. This required the modification of the system initialization routine system\_init, the system scheduler schedule and the the two signal transmission routines get\_signal and out. A time out facility was also implemented. Code for these routines is given in Appendix V.

The system initialization routine was modified to allow it to establish a network connection between the two hosts being used. The actual communication path was created using a set of locally developed network primitives which allow easy access to a local area network (ETHERNET).

The system scheduler was modified so that it tested the result of a call to get\_signal before it called the destination routine.

Get\_signal was modified to detect when it was at the particular channel through which signals from the network are to arrive. When at the designated channel it called a nonblocking network *receive* primitive in attempt to get a signal from the other host.

The routine *out* was modified to detect the transmission of a signal over the channel designated to carry traffic to the other host. Instead of queueing the signal it places it in a buffer and calls a network *send* primitive.

The time out facility was provided by a pair of C routines which schedule and test timers. These two routines are quite simple. The time out scheduler, schedule\_timeout, adds the timer duration to the present time and stores the value. The routine timer\_expired checks to see if the system time is later than the stored time and returns the appropriate truth value.

The implementation code generated for this example can be found in Appendix VI.

## Chapter 6

## Conclusion

### 6.1 Thesis Summary

The development of formal models for protocol specification has opened the door to the possibility of automatically generating protocol implementations directly from their specification. The wide spread availability of implementation tools will allow protocol implementors to produce compatible protocol implementations with ease. The compiler developed demonstrates the feasibility of producing such a tool. It generates virtually all of the code needed to implement a protocol (the only thing it does not produce are some simple declarations and tests in two utility routines). And both it and its output code are written in highly portable *C*. Despite of its large size, 8000 lines, it runs very quickly, processing the two examples in negligible time (less than a second).

The restrictions placed on the structure of the *PASCAL* programs accepted by the compiler, namely the elimination of nested routines and global references, could be a factor when more complex protocols are to be processed. However, at present the restrictions do not appear to be too severe.

The success of the venture can be measured by contrasting automatic and manual protocol implementation techniques. The compiler produces consistently well structured and easy to understand code. The quality of manually generated code varies considerably. Compiler generated code is easy to maintain and modify, a change in the input specification is all that is required. On the other hand, manually produced code requires a great deal of effort and expense to maintain. Perhaps the greatest difference between the two implementation methods is the respective confidence given to their generated implementations. Code produced by a compiler can generally be assumed to be a correct representation of the specification, whereas manually produced code cannot.

#### **6.2** Enhancements

Further testing of the compiler on real-life protocols such as the ISO transport protocol is desirable. Such a test would further demonstrate the usefulness of using such tools and perhaps spawn the development of production versions of the compiler.

Enhancements to the compiler itself can also be made. The processing of the scope of transition enabling condition clauses is currently handled clumsily and as a result the usefulness of some of the shorthand clause specifications is restricted. *PASCAL* set types, were not implemented as they were not considered to be important enough to warrant the effort. The FDT DELAY clause which implements timer functions was not implemented as timers can be simulated with system calls. Adding the DELAY clause would enhance the compatibility of the compiler with the ISO standard.

A major enhancement to the system would be the implementation of protocol machines as separate processes running under control of the host's operating system. This approach would be a closer representation of the model of independent protocol machines then the current one.

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# Appendix I

# FDT Grammar

specification -> seqsect

seqsect -> section ";" seqsect | /\* empty \*/

section -> channel | module | process | refinemt

channel -> constd typed "channel" IDENT

"(" rolelist ")" ";" byclause "end" IDENT

rolelist -> IDENT seqident

seqident -> "," rolelist | /\* empty \*/

byclause -> "by" rolelist ":" signal byclause | /\* empty \*/

signal -> IDENT signalpara ";" signal | /\* empty \*/

signalpara -> "(" paradef ")" | /\* empty \*/

seqparadef -> ";" paradef | /\* empty \*/

paradef -> rolelist ":" basictype seqparadef

module -> "module" IDENT ";" portlist "end" IDENT

portlist -> rolelist ":" array IDENT "(" IDENT ")"

";" portlist | /\* empty \*/

---

array -> "array" "{" indextype sequed at "}" "of"

| /\* empty \*/

indextype -> simpletype

seqindext -> "," indextype seqindext | /\* empty \*/

refinemt -> "refinement" IDENT signalpara "for" IDENT ";" refbody "end" IDENT

refbody -> sequect instance connect replace | /\* empty \*/

instance -> rolelist ":" IDENT "with" IDENT actualpar ";" seqinst

seqinst -> instance | /\* empty \*/

connect -> "connect" intconn | /\* empty \*/

intconn -> mport "to" mport ";" segintconn

seqintconn -> intconn | /\* empty \*/

replace -> "replace" extconn | /\* empty \*/

extconn -> port "by" mport ";" seqextconn

seqextconn -> extconn | /\* empty \*/

port -> IDENT optindex

optindex -> "{" constant listconst "}" | /\* empty \*/

mport -> IDENT "." port

-> "process" IDENT signalpara "for" IDENT ";" process procbody "end" IDENT

qchannel -> "queued" rolelist ";" | /\* empty \*/

procbody -> qchannel constd typed pvard procfuned init trans

| /\* empty \*/

-> "var" procvar | /\* empty \*/ pvard

-> IDENT ":" "(" rolelist ")" ";" sequardecl | vardecl procvar

-> IDENT | /\* empty \*/ stateset

-> "initialize" stateset "begin" initstatmt init seqstatmt "end" ";" | /\* empty \*/

initstatmt -> plainstatmt

trans -> "trans" sequence opttrans

opttrans -> trans | /\* empty \*/

seqclause -> clause seqclause | opttag block ";" seqtrans

-> "any" paradef "do" | "when" IDENT vparam "." IDENT clause | "from" rolelist | "to" nextmstate | "provided" expression | "priority" idorint

-> seqclause | /\* empty \*/

seqtrans

-> IDENT ":" | /\* empty \*/ opttag

-> "{" rolelist "}" | /\* empty \*/ vparam

listvariable -> "," variable | /\* empty \*/

nextmstate -> IDENT | "same"

idorint -> IDENT | INTEGER

block -> labeld constd typed vard procfuncd "begin"
 statmt seqstatmt "end"

labeld -> "label" INTEGER sequences ";" | /\* empty \*/

seqinteger -> "," INTEGER seqinteger | /\* empty \*/

constd -> "const" defconst | /\* empty \*/

defconst -> IDENT "=" constant ";" seqdefconst

seqdefconst-> defconst | /\* empty \*/

constant -> optsign numconst | STRING

optsign -> SIGN | /\* empty \*/

numconst -> INTEGER | REAL | IDENT

typed -> "type" deftype | /\* empty \*/

deftype -> IDENT "=" type ";" seqdeftype

seqdeftype -> deftype | /\* empty \*/

type -> simpletype | optpack typstruct | """ IDENT -

| "^" "boolean" | "^" "char" | "^" "integer" | "^" "real" simpletype -> "(" rolelist ")" | SIGN numconst ".." constant | INTEGER ".." constant | IDENT optconst | "boolean" | "char" | "integer" | "real"

optconst -> ".." constant | /\* empty \*/

optpack -> "packed" | /\* empty \*/

typstruct -> "array" "{" simpletype seqsimplet "}" "of" type

| "record" field "end"

seqsimplet -> "," simpletype seqsimplet | /\* empty \*/

field -> fixedpart seqfield

| "case" IDENT typselect "of" variant

fixedpart -> rolelist ":" type | /\* empty \*/

seqfield -> '';" field | /\* empty \*/

typselect -> ":" basictype | /\* empty \*/

variant -> constant listconst ":" "(" field ")" sequariant

| /\* empty \*/

sequariant -> ";" variant | /\* empty \*/

listconst -> "," constant listconst | /\* empty \*/

vard -> "var" vardecl | /\* empty \*/

vardecl -> rolelist ":" type ";" sequardecl

seqvardecl -> vardecl | /\* empty \*/

procfuncd -> procefuncd pfheader ";" pfbody ";" | /\* empty \*/

pfheader -> "procedure" IDENT lpara | "predicate" IDENT lpara | "function" IDENT lpara ":" basictype

pfbody -> block | "extern" | "forward" | "primitive"

```
lpara -> "(" spara seqspara ")" | /* empty */
```

seqspara -> ";" spara seqspara | /\* empty \*/

spara -> rolelist ":" basictype

| "var" rolelist ":" basictype

factor -> REAL | STRING | "nil" | INTEGER | "{" seqsetint "}" | "(" expression ")"

| "not" factor | IDENT seqfactid

seqfactid -> lseqvaria | "(" index ")"

index -> expression sequidex

seqindex -> "," index | /\* empty \*/

lseqvaria -> "{" index "}" lseqvaria | "." IDENT lseqvaria | """ lseqvaria | /\* empty \*/

seqsetint -> setint lseqset | /\* empty \*/

lseqset -> "," setint lseqset | /\* empty \*/

setint -> expression seqxpset

seqxpset -> ".." expression | /\* empty \*/

### term -> term OPERMULT factor | factor

simplexp -> simplexp OPERADD term | optsign term

expression -> simplexp OPEREL simplexp | simplexp

statmt -> INTEGER ":" plainstatmt | plainstatmt

plainstatmt -> IDENT appendix

| "out" IDENT sequindice "." IDENT actualpar

| "goto" INTEGER

| "begin" statmt seqstatmt "end"

"if" expression "then" statmt else

| "case" expression "of" case seqcase otherw "end"

| "repeat" statmt seqstatmt "until" expression

| "while" expression "do" statmt

| "for" IDENT ":=" expression

direction expression "do" statmt

| "write" iolist | "writeln" lniolist

| /\* empty \*/

actualpar -> "(" index ")" | /\* empty \*/

newmstate -> IDENT | "same"

seqstatmt -> ";" statmt seqstatmt | /\* empty \*/

else -> "else" statmt | /\* empty \*/

seqcase -> ";" case seqcase | /\* empty \*/

case -> constant listconst ":" statmt | /\* empty \*/

- otherw -> "otherwise" statmt seqstatmt | /\* empty \*/
- lniolist -> iolist | /\* empty \*/
- iolist -> ''(" ioexp '')"
- ioexp -> ioident seqioident
- sequoident -> "," ioexp | /\* empty \*/
- ioident -> expression ioextra
- ioextra -> ":" simplexp | /\* empty \*/
- direction -> "to" | "downto"
- variable -> IDENT lsequaria listuariable
- appendix -> actualpar | lseqvaria ":=" expression
- seqindice -> "{" index "}" seqindice | /\* empty \*/

basictype -> IDENT | "boolean" | "char"

| "integer" | "real"

# APPENDIX II

# Utility Routine Listings

int signal\_pending;

/\*-----\*/

process\_block \*add\_process\_block(process\_list,proc\_ptr,identifier) struct /\* This function allocates a new process block, initializes it, and places it at the head of the process list passed to it. The pointer to the process\_list is returned. \*/ \*process\_list; struct process\_block (\*proc\_ptr)(); int \*identifier; char { process block \*ptr, \*temp\_ptr; struct = ALLOCATE( process\_block); ptr ptr->next = process\_list; ptr->proc\_ptr = proc\_ptr; strcpy(ptr->p\_ident,identifier); ptr->chan\_list = NULL; ptr->refinement =NULL; return(ptr); } \*/

struct channel\_block \*add\_channel\_block(channel\_list,c\_ptr,queued\_flag,

## number, index)

```
/*
This function allocates a new channel block, initializes it, and places
it at the end of the channel list passed to it. It returns the channel
list.
```

```
*/
```

```
struct channel_block
                               *channel_list, *(*c_ptr);
  int
                               queued_flag,number,index;
    {
               channel_block
     struct
                                    *ptr, *temp_ptr;
     /* make a new channel block */
                  = ALLOCATE( channel_block);
     ptr
                  = NULL;
     ptr->next
     ptr->c_id
                  = number;
                             = index;
     ptr->index_num
     ptr->signal_list = NULL;
                       = queued_flag;
     ptr->queued
     ptr->target_proc =
                               NULL;
     ptr->target_channel=
                               NULL;
     ptr->index_list = NULL;
     *c_ptr = ptr;
     if (channel_list != NULL)
        /* find the end of the channel list */
       for (temp_ptr = channel_list; temp_ptr->next != NULL;
               temp_ptr = temp_ptr->next);
        temp_ptr->next =
                               ptr;
       return(channel_list);
       }
     else
       return(ptr);
     }
                                                     */
struct
          channel_block #find_channel(channel_list,id,index)
/*
```

This function returns a pointer to the first channel block with the passed id in the channel list.

\*/

```
struct channel_block
                                  *channel_list;
   int
                                  id, index;
     {
                 channel block
      struct
                                       *ptr;
      /* find the block */
      for (ptr = channel_list; (ptr->c_id != id)||(ptr->index_num != index);
              ptr = ptr->next);
      return(ptr);
     }
struct
           process_block
                            *add_refinement_header(process_list,ref_body)
/*
 This function allocates a "refinement" type process header and places
 it at the head of the process list. The ref_body (also a process list)
 is then attached to the refinement header.
*/
   struct process block
                            *process_list, *ref_body;
     {
      struct
                process_block
                                *ptr,*add_process_block();
                 = add_process_block(process_list,NULL,"refinement");
      ptr
      ptr->refinement= ref_body;
      return(ptr);
     }
                                                        */
connect_ports(process_list, instance_num1, channel_num1, index1,
                   instance_num2, channel_num2, index2)
/*
 This routine interconnects the specified channels.
*/
  struct process_block
                            *process_list;
                            instance_num1, instance_num2,
  int
                      channel_num1, channel_num2,
```

| struct p  | rocess_block | <pre>*find_process(), *p_ptr1, *p_ptr2;</pre>            |
|-----------|--------------|--|
| struct cl | hannel_block | *find_channel(), *c_ptr1, *c_ptr2;                       |
| p_ptr1    | =            | find_process(process_list,instance_num1);                |
| p_ptr2    | =            | find_process(process_list,instance_num2);                |
| c_ptr1    | =            | find_channel(p_ptr1->chan_list,channel_num1,<br>index1); |
| c_ptr2    |              | find_channel(p_ptr2->chan_list,channel_num2,<br>index2); |

```
/*
```

{

If the channel blocks are already connected to another channel block then they must be in the header of a refinement so take their targets as the channel blocks to connect to. \*/

| n ntal |  |
|--------|--|
| p_puri |  |

| 1 | $= (c_ptrl -> target_proc == NULL)$ |  |  |  |  |
|---|-------------------------------------|--|--|--|--|
|   | ? p_ptrl                            |  |  |  |  |
|   | : c_ptrl->target_proc;              |  |  |  |  |
|   |                                     |  |  |  |  |

| p_ptr2 | $= (c_ptr2 - target_proc == NULL)$ |
|--------|------------------------------------|
|        | ? p_ptr2                           |
|        | : c_ptr2->target_proc;             |

- c\_ptr1 = (c\_ptr1->target\_channel == NULL) ? c\_ptr1 : c\_ptr1->target\_channel;
- c\_ptr2 = (c\_ptr2->target\_channel == NULL) ? c\_ptr2 : c\_ptr2->target\_channel;

/\* make the connection \*/

c\_ptr1->target\_proc = p\_ptr2; c\_ptr1->target\_channel = c\_ptr2; c\_ptr2->target\_proc = p\_ptr1; c\_ptr2->target\_channel = c\_ptr1; }

-\*/

struct process\_block \*find\_process(process\_list, number) 1\* This function returns a pointer to the number'th element of the process list. \*/ struct process\_block \*process\_list; int number; { int i; for (i = 1; i < number; i++)process\_list = process\_list->next; return(process\_list); } \*/ replace\_port(ref\_ptr, port\_num, port\_index, instance, channel\_num, index) /\* This routine connects a port (channel) in a refinement header to a port in the refinement body. \*/ struct process\_block \*ref\_ptr; int port\_num, port\_index, instance, channel\_num, index; { \*p ptr,\*find process(); process block struct channel\_block \*c\_ptr1,\*c\_ptr2,\*find\_channel(); struct find\_process(ref\_ptr->refinement, instance); p\_ptr c\_ptr1 find\_channel(ref\_ptr->chan\_list, = port\_num,port\_index); find\_channel(p\_ptr->chan\_list,channel\_num,index); c\_ptr2 = = (c\_ptr2->target\_proc == NULL) p\_ptr ? p\_ptr : c\_ptr2->target\_proc; = (c\_ptr2->target\_channel == NULL) c\_ptr2 ? c\_ptr2 : c\_ptr2->target\_channel;

```
c_ptr1->target_proc = p_ptr;
c_ptr1->target_channel = c_ptr2;
c_ptr2->target_proc = ref_ptr;
c_ptr2->target_channel = c_ptr1;
}
```

/\*-----\*/

struct process\_block \*clean\_up(process\_list)
/\*
This function removes the refinement header in a process list. It
returns a process list which is a concatenation of the refinement

```
returns a process list which is a concatenation of the refinement
bodies
*/
```

```
struct process_block
                          *process_list;
  {
             process_block
                                *ptr1, *ptr2, *remove_header();
   struct
   if (process_list == NULL)
    {
      return(NULL);
    }
   else
    {
      ptr1
             = process_list->next;
             = process_list;
      ptr2
      if (strcmp(process_list->p_ident,"refinement") == 0)
       {
                        = remove_header(process_list);
        process_list
        for (ptr2 = process_list; ptr2->next != NULL;
                ptr2 = ptr2 > next);
        ptr2->next
                        = ptr1;
       }
      while (ptr1 != NULL)
        if (strcmp(ptr1->p_ident,"refinement") == 0)
```

{

```
ptrl = ptrl->next;
              ptr2->next = remove_header(ptr2->next);
              while (ptr2->next != NULL)
                {
                 ptr2 = ptr2 - next;
                }
              ptr2->next = ptr1;
             }
           else
             {
              ptr2
                     = ptr1;
              ptr1
                         ptr1->next;
                     ----
          }
         return(process_list);
       }
     }
                                                      */
struct
          process_block
                         *remove_header(ref_ptr)
/*
 This function removes the refinement header and its channel list and
 returns a pointer to the refinement body.
*/
  struct process_block
                              *ref_ptr;
     {
                process_block
     struct
                                   *p_ptr;
                channel_block
     struct
                                   *c_ptr1, *c_ptr2;
     /* remove the channel list */
     for (c_ptr1 = ref_ptr->chan_list; c_ptr1 != NULL;
             c_ptr2 = c_ptr1, c_ptr1 = c_ptr1->next)
       {
        free(c_ptr2);
       }
     /* remove the process block */
                     = ref_ptr->refinement;
     p_ptr
     free(ref_ptr);
     return(p_ptr);
     }
```

```
out(channel_list,signal,chan_num,index)
/*
 This routine dispatches a signal on the indicated channel.
*/
  struct channel_block
                            *channel_list;
   struct signal_block * signal;
   int
                            chan_num, index;
     {
                int signal_pending;
      extern
                channel_block *channel, *find_channel();
      struct
      channel = find_channel(channel_list,chan_num,index);
      if (channel->target_channel->queued)
         signal_pending++;
         signal->next = channel->target_channel->signal_list;
         channel->target_channel->signal_list = signal;
      else /* rendez-vous */
         (*(channel->target_proc->proc_ptr))(channel->target_proc,
                channel, signal);
        }
     }
                                                         .*/
                            *system_init()
struct
           process_block
/*
 This routine causes the generation of the data structure and then checks
 for dangling channel connections.
*/
  {
```

struct process\_block \*ptr, \*process\_list, \*remove\_header();

struct channel\_block \*c\_ptr;

struct process\_block \*iohot\_ref();

process\_list = remove\_header(iohot\_ref(NULL));

/\* join the ends of the process list into a loop \*/

for (ptr = process\_list; ptr->next != NULL; ptr = ptr->next);

ptr->next = process\_list;

return(process\_list);

}

/\*\_\_\_\_\_\*/

schedule(process\_list) /\* This is the main driving routine. \*/

struct process\_block \*process\_list;

```
{
extern int signal_pending;
```

| struct | channel_block | <pre>*c_ptr;</pre>                |
|--------|---------------|-----------------------------------|
| struct | signal_block  | <pre>*s_ptr, *get_signal();</pre> |
| struct | process_block | *p_ptr, *p_ptr2;                  |

```
p_ptr2 = process_list;
p_ptr = process_list;
```

c\_ptr = p\_ptr->chan\_list;

signal\_pending = 0;

```
while (TRUE)
{
    if (signal_pending > 0)
      {
      s_ptr = get_signal(&c_ptr, &p_ptr);
    }
}
```

signal\_pending--;

/\* call the transition routine \*/

(\*(p\_ptr->proc\_ptr))(p\_ptr,c\_ptr,s\_ptr);

```
/* move on to the next channel for the
start of the next search */
```

```
if (c_ptr->next != NULL)
c_ptr = c_ptr->next;
```

else

```
{
              p_ptr = p_ptr > next;
              c_ptr = p_ptr->chan_list;
              }
          }
         if ((strcmp(p_ptr2->p_ident,"player_process") == 0))
                (*(p_ptr2->proc_ptr))(p_ptr2,NULL,NULL);
         p_ptr2 = p_ptr2 > next;
       }
     }
struct
           signal_block
                           *get_signal(c_ptr,p_ptr)
/*
 This function finds a pending signal on a signal queue.
*/
  struct channel_block
                           *(*c_ptr);
  struct process_block
                           *(*p_ptr);
     {
                signal_block
                                *s_ptr, *s_ptr2;
     struct
                     found = FALSE;
     int
      for (; !found; (*p_ptr) = (*p_ptr) > next, (*c_ptr) = (*p_ptr) > chan_list)
       {
        for (; ((*c_ptr) != NULL) && (!found);
             (*c_ptr) = (*c_ptr) - next)
          {
           if ((*c_ptr)->signal_list != NULL)
             ł
              found = TRUE;
              if ((*c_ptr)->signal_list->next != NULL){
                for (s_ptr = (*c_ptr)->signal_list,
                   s_ptr2 = s_ptr->next;
                   s_ptr2->next != NULL;
                s_ptr = s_ptr2, s_ptr2 = s_ptr2->next);
                s_ptr->next = NULL;
                }
              else
               {
```

```
s_ptr2
                                         (*c_ptr)->signal_list;
                                     -
                (*c_ptr)->signal_list = NULL;
               }
              goto end;
            }
          }
       }
  end:
     return(s_ptr2);
     }
                                                      */
add_index_block (channel, index)
/*
 This routine appends an index block on to the channels index list.
*/
  struct channel_block *channel;
  int
                        index;
     {
     struct
               index_block *ptr, *ptr2;
     ptr = ALLOCATE(index_block);
     ptr->next = NULL;
     ptr->num = index;
     if (channel->index_list == NULL)
        channel->index_list = ptr;
     else{
        for (ptr2 = channel->index_list; ptr2->next != NULL;
             ptr2 = ptr2 - next);
        ptr2->next = ptr;
        }
     }
                                                      .*/
int get_index(channel, index_pos)
/*
```

This routine retrives the index value store in an index block

```
The index_pos is origin zero
*/
   struct channel_block *channel;
   int
                          index_pos;
      {
                 index_block *ptr;
      struct
      for (ptr = channel->index_list; index_pos > 0;
              ptr = ptr->next,index_pos--);
      return(ptr->num);
     }
                                                        .*/
/*.
requeue(channel, signal)
/*
 This routine puts the signal passed on to the head of the signal queue.
*/
   struct channel_block *channel;
   struct signal_block *signal;
     {
      struct
                 signal_block
                                  *ptr;
                 int signal_pending;
      extern
      signal_pending++;
      if (channel->signal_list != NULL).
        {
         for (ptr = channel->signal_list; ptr->next != NULL; ptr=ptr->next);
         ptr->next = signal;
       }
      else channel->signal_list = signal;
     }
```

return((low + ((high - low + 1) \* temp))/1);

}

.\*/
# Appendix III

## Listdefs.h

| #define N | MAX_IDENT_L     | ENGTH 30                              |
|-----------|-----------------|---------------------------------------|
| #define 7 | TRUE            | 1 .                                   |
| #define F | FALSE           | 0                                     |
| #define A | ALLOCATE(A)     | (struct A *)malloc(sizeof(struct A)); |
| struct    | channel_block   |                                       |
| struct    | channel block   | *next                                 |
| struct    | signal_block*si | gnal_list;                            |
| struct    | process_block   | *target_proc;                         |
| struct    | channel_block   | <pre>*target_channel;</pre>           |
| struct    | index_block     | *index_list;                          |
| int       |                 | queued;                               |
| int       |                 | c_id;                                 |
| int       |                 | index_num;                            |
| };        |                 |                                       |
| /*        |                 | */                                    |
| ,         |                 |                                       |

struct index\_block
{
 struct index\_block \*next;
 int num;
};

## Appdenix IV

### **Appendix IV: Alternating Bit Specification**

```
module ab_pc;
end ab_pc;
refinement ab_ref for ab_pc;
const
     retran_time
                         100; (* retranstission time *)
                    =
type
     data_type =
                    integer;
     seq_type =
                    0..1;
                    = (A_DATA,ACK);
     id_type
     timer_type = (retransmit);
     ndata_type =
          record
           id : id_type;
           data
                    : data_type;
           seq : seq_type;
          end;
     msg_type =
          record
           msgdata : data_type;
           msgseq : seq_type;
          end;
     buffer_type=
                    record
                      flag : boolean;
                      msg: msg_type;
                    end;
     int_type = integer;
                                                 -*)
```

(\* channel definitions \*)

channel U\_receive\_point(sender, receiver);

by sender: RECEIVE\_request;

by receiver: RECEIVE\_response(UData: data\_type);

end U\_receive\_point;

channel U\_send\_point(sender, receiver);

by sender: SEND\_request(UData : data\_type);

end U\_send\_point;

(\*------\*)

type

time\_struct = array[timer\_type] of record flag : boolean; secs : integer; millisecs : integer;

end;

channel S\_access\_point(User, Provider);

by User: Timer\_request(name : timer\_type; time : integer);

by Provider: Timer\_response(Name: timer\_type); end S\_access\_point;

(\*------\*)

channel N\_access\_point(User, Provider);

by User:

Data\_request(id:id\_type; data: data\_type; seq:seq\_type);

by Provider:

#### Data\_response(id:id\_type; data: data\_type; seq:seq\_type);

end N\_access\_point;

(\*-----

channel network\_channel(sender,receiver);

by sender, receiver: packet (id:id\_type; data: data\_type; seq:seq\_type);

end network\_channel;

(\*-----\*)

(\* module definitions \*)

module Alternating\_Bit;

Us : U\_send\_point(receiver); ur : U\_receive\_point(receiver); N : N\_access\_point(User); S : S\_access\_point(User);

end Alternating\_Bit;

process alternating\_process for Alternating\_Bit;

```
QUEUED Us, Ur, N, S;
```

var

| state:       | (ACK_WAIT, ESTAB); |
|--------------|--------------------|
| send_seq:    | seq_type;          |
| recv_seq:    | seq_type;          |
| send_buffer: | buffer_type;       |
| recv_buffer: | buffer_type;       |
| p,q:         | msg_type;          |

function Ack\_OK(id: id\_type; seq,send\_seq: seq\_type) : boolean; begin

Ack\_OK := (id = ACK) and (seq = send\_seq)

end;

```
initialize
begin
state := ESTAB;
send_seq := 0;
recv_seq := 0;
send_buffer.flag := FALSE;
recv_buffer.flag := FALSE;
end;
```

(\* transistions \*)

trans

```
from ESTAB (* transition 1 *)
to ACK_WAIT
when Us.SEND_request
provided not send_buffer.flag
begin
send_buffer.flag := true;
send_buffer.msg.msgdata := UData;
send_buffer.msg.msgseq := send_seq;
```

out N.DATA\_request(A\_DATA,Udata, send\_seq);

```
out S.TIMER_request(retransmit,retran_time)
end;
```

trans

```
from ESTAB, ACK_WAIT (* transition 2 *)
to SAME
when Ur.RECEIVE_request
provided recv_buffer.flag
begin
```

out Ur.RECEIVE\_response(recv\_buffer.msg.msgdata);
recv\_buffer.flag := false;
end;

trans

```
from ACK_WAIT (* transition 3 *)
to ACK_WAIT
when S.TIMER_response
provided Name = retransmit
begin
```

out N.DATA\_request(A\_DATA,send\_buffer.msg.msgdata, send\_buffer.msg.msgseq); out S.TIMER\_request(retransmit,retran\_time) end;

-

#### trans

```
from ESTAB (* transition 4 *)
to ESTAB
when S.TIMER_response
provided Name = retransmit
begin
(* do nothing: the message that cause this timer to be
sent has been acknowledged. *)
state := state
end;
```

#### trans

```
from ACK_WAIT (* transition 5 *)
to ESTAB
when N.DATA_response
provided Ack_OK(id, seq, send_seq)
begin
send_buffer.flag := false;
send_seq := (send_seq + 1) mod 2
end;
trans
from ESTAB, ACK_WAIT (* transistion 6 *)
to SAME
when N.DATA_response
provided id = A_DATA
```

```
begin
```

```
out N.DATA_request(ACK, data, seq);
```

```
if seq = recv_seq then
    begin
    recv_buffer.flag := true;
    recv_buffer.msg.msgdata:= data;
    recv_buffer.msg.msgseq := seq;
```

```
recv_seq := (recv_seq + 1) mod 2
end
```

end;

end alternating\_process;

\*------\*)

(\* timer module \*)

module timer; S : S\_access\_point(provider);

#### process timer\_process for timer;

QUEUED S;

var

```
index : timer_type;
a_timer: time_struct;
```

procedure schedule\_timeout(Var timer: time\_struct; time\_value: integer);
primitive;

predicate timer\_expired(Var timer : time\_struct);
primitive;

```
initialize
begin
for index := retransmit to retransmit do
    begin
    a_timer[index].flag := FALSE;
    a_timer[index].secs := 0;
    a_timer[index].millisecs := 0
    end
end;
```

(\* transistions \*)

trans

when S.Timer\_request (\* transistion 1 \*) begin

schedule\_timeout(a\_timer[Name], Time);

end;

```
any index:timer_type do (* transition 2 *)
provided timer_expired(a_timer[index])
```

begin
 a\_timer[index].flag := false;
 out S.Timer\_response(index)
end;

end timer\_process;

(\* network module \*)

module network;

N : N\_access\_point(Provider); send\_path : network\_channel(sender); receive\_path : network\_channel(receiver); end network;

process net\_proc for network;

QUEUED N, send\_path, receive\_path;

trans

```
when N.Data_request
begin
OUT send_path.packet(id, data, seq)
end;
```

trans

when receive\_path.packet begin OUT N.Data\_response(id, data, seq) end;

end net\_proc;

(\* user module \*)

module the\_user;

Us : U\_send\_point(sender); Ur : U\_receive\_point(sender); end the\_user;

process user\_process(number : integer) for the\_user;

#### QUEUED Us, Ur;

type

request\_type = (send, receive); message\_value\_type = 1..9;

var

user\_number : integer;

#### initialize

begin user\_number := number end;

```
trans
```

```
when Ur.RECEIVE_response
begin
writeln('User ',user_number,' received the message ',
UData);
end;
```

trans

provided request = receive begin OUT Ur.RECEIVE\_request end;

end user\_process;

(\* define some instances \*)

A1 : Alternating\_Bit with alternating\_process; A2 : Alternating\_Bit with alternating\_process;

timer1 : timer with timer\_process; timer2 : timer with timer\_process;

N1 : network with net\_proc; N2 : network with net\_proc;

U1 : the\_user with user\_process(1); U2 : the\_user with user\_process(2);

(\* and connect them together \*)

CONNECT

A1.Us to U1.Us; A1.Ur to U1.Ur; A1.N to N1.N; A1.S to timer1.S;

A2.Us to U2.Us; A2.Ur to U2.Ur; A2.N to N2.N; A2.S to timer2.S;

N1.send\_path to N2.receive\_path; N2.send\_path to N1.receive\_path;

(\* no replaces \*)

end ab\_ref;

### Appendix V

### Utility Routines for Alternating Bit

```
#include "inet.h"
#define ROLE 1 /* or 0 */
out(channel_list,signal,chan_num,index)
/*
 This routine dispatches a signal on the indicated channel.
*/
  struct channel_block
                           *channel_list;
  struct signal_block * signal;
                           chan_num, index;
  int
     {
                int signal_pending, in_count, out_count;
      extern
      extern NET_CONN conn;
                channel_block *channel, *find_channel();
      struct
      int
                     n;
     channel = find_channel(channel_list,chan_num,index);
      if ((channel->target_channel != NULL) &&
          (channel->target_channel->queued))
       {
        signal_pending++;
        signal->next = channel->target_channel->signal_list;
        channel->target_channel->signal_list = signal;
     else /* send it out on the network */
        buf[0] = signal->signal_id;
        buf[1] = signal->lvars.network_channel.packet.id;
        buf[2] = signal->lvars.nctwork_channel.packet.data;
```

```
buf[3] = signal->lvars.network_channel.packet.seq;
```

```
free(signal);
out_count++;
```

}

```
if ((n =N_send(&conn,buf,16)) != NET_OK)
{
    printf(">>> out : send problem %d ",n);
    exit(1);
}
```

/\*-----\*/

struct process\_block \*system\_init()
/\*
This routine causes the generation of the data structure and then checks

for dangling channel connections.

```
*/
```

{

struct process\_block \*ptr, \*process\_list, \*remove\_header();

```
struct channel_block *c_ptr;
```

int n;

/\* user included dcl \*/

struct process\_block \*ioab\_ref();

```
if (ROLE == 1) /*server*/
{
    n = N_open(&conn, "T_port1@cs", CLSTWO);
    if (n != NET_OK)
    {
        printf(">>> service : N_open error %d0,n);
        exit(1);
    }
    n = N_accept(&conn);
    if (n != NET_OK)
    {
        printf(">>> service : N_accept error %d0,n);
    }
}
```

--

```
process_list = remove_header(ioab_ref(NULL));
```

/\* join the ends of the process list into a loop \*/

for (ptr = process\_list; ptr->next != NULL; ptr = ptr->next);

ptr->next = process\_list;

return(process\_list);

}

\*\_\_\_\_\_\*/

```
schedule(process_list)
/*
This is the main driving routine.
*/
```

```
struct process_block *process_list;
```

```
{
    extern int signal_pending;
    extern int in_count, out_count;
```

```
struct channel_block *c_ptr;
struct signal_block *s_ptr, *get_signal();
struct process_block *p_ptr, *p_ptr2;
```

```
p_ptr2 = process_list;
p_ptr = process_list;
c_ptr = p_ptr->chan_list;
signal_pending = 0;
```

{

while ( (in\_count < 5) || (out\_count <5))
 /\* arbitrary stop condition \*/
{
 if ((s\_ptr = get\_signal(&c\_ptr, &p\_ptr))
 != NULL)</pre>

/\* call the transition routine \*/

/\* move on to the next channel for the start of the next search \*/

if (c\_ptr->next != NULL)
 c\_ptr = c\_ptr->next;

else { p\_ptr = p\_ptr->next; c\_ptr = p\_ptr->chan\_list; }

if ((strcmp(p\_ptr2->p\_ident,"timer\_process") == 0) || (strcmp(p\_ptr2->p\_ident,"user\_process") == 0)) (\*(p\_ptr2->proc\_ptr))(p\_ptr2,NULL,NULL);

 $p_ptr2 = p_ptr2 - next;$ 

```
}
     N_close(&conn);
     }
           signal block
                           *get_signal(c_ptr,p_ptr)
struct
/*
 This function finds a pending signal on a signal queue.
*/
  struct channel_block
                           *(*c_ptr);
  struct process_block
                           *(*p_ptr);
     {
                signal_block
                                *s_ptr, *s_ptr2;
      struct
      int
                     found = FALSE;
      int
                     n, temp;
      extern NET_CONN conn;
      extern int
                     in_count, out_count;
      static int count;
      s_ptr2 = NULL;
      for (:!found; (*p_ptr) = (*p_ptr)->next,(*c_ptr)=(*p_ptr)->chan_list,
             s_{ptr2} = NULL)
       {
        for (; (((*c_ptr) != NULL) && (!found));
             (*c_ptr)= (*c_ptr)->next)
          {
           if ((*c_ptr)->signal_list != NULL)
             ł
              found = TRUE;
              if ((*c_ptr)->signal_list->next != NULL){
                for (s_ptr = (*c_ptr)->signal_list,
                   s_ptr2 = s_ptr->next;
                  s_ptr2->next != NULL;
                s_ptr = s_ptr2, s_ptr2 = s_ptr2 > next;
```

```
s_ptr = s_ptr2, s_ptr2 = s_ptr2>next),
s_ptr->next = NULL;
}
else
{
    s_ptr2 = (*c_ptr)->signal_list;
    (*c_ptr)->signal_list = NULL;
```

```
}
              goto end;
             }
           if ((strcmp((*p_ptr)->p_ident,"net_proc") == 0) &&
                  ((*c_ptr)->c_id == 3))
               {
               if ((n = N_receive(\&conn, buf, buffsize)) \le 0)
                {if (n < 0)}
                  {
                   printf(" read error %d0,n);
                   exit(1);
                   }
                }
               else
                  ł
                   s_ptr2 = ALLOCATE(signal_block);
                   s_ptr2->signal_id = buf[0];
                   s_ptr2->lvars.network_channel.packet.id = buf[1];
                   s_ptr2->lvars.network_channel.packet.data = buf[2];
                   s_ptr2->lvars.network_channel.packet.seq = buf[3];
                   in_count++;
                   goto end;
                  }
               s_ptr2 = NULL;
               goto end;
              }
          }
        }
  end:
     return(s_ptr2);
     }
1*-
                                                        */
#include <sys/types.h>
#include <sys/timeb.h>
#include "listdefs.h"
           time_struct
struct
 {
  int
              flag;
```

schedule\_timeout(timer,time\_value)
/\*

This routine places in the timer passed the value of present time + "time\_value" which will be tested later by "timer\_expired". The units of time\_value are milliseconds.

```
*/
```

struct time\_struct \*timer; int time\_value; { struct timeb \*tp;

ftime(tp);

timer->flag = TRUE;

timer->secs = tp->time;

timer->millisecs= tp->millitm;

```
if ((time_value = time_value + tp->millitm) >= 1000)
{
    timer->secs++;
    timer->millisecs = time_value - 1000;
}
```

/\*-----\*/

int timer\_expired(timer) /\*

This predicate returns TRUE if the timer passed has expired and cancels it if it has

\*/

struct time\_struct \*timer;

{ struct timeb \*tp;

ftime(tp);

```
if ((timer->flag == TRUE) &&
(timer->secs < tp->time) &&
(timer->millisecs < tp->millitm))
```

```
return(TRUE);
```

else return(FALSE);

```
}
```

\*/

```
cancel_timer(timer)
/*
This routine cancels the timer passed
*/
struct time_struct *timer;
{
   timer->flag = FALSE;
}
```

### Appendix VI

## Alternating Bit Implementation Code

#include <stdio.h> #include <strings.h> #include "listdefs.h" /\* type code \*/ typedef int data\_type; typedef int seq\_type; typedef int id\_type; typedef int timer\_type; typedef struct { id\_type id; data\_type data; seq\_type seq; } ndata\_type; typedef struct { data\_type msgdata; seq\_type msgseq; } msg\_type; typedef struct { int flag; msg\_type msg; buffer\_type; typedef int int\_type; typedef struct { int flag; int secs; int millisecs; } time\_struct[1]; typedef int request\_type; typedef int message\_value\_type; -----\*/ /\*----

/\* signal block dcl \*/

---

```
struct signal_block {
     int signal_id;
     struct signal_block *next;
     union {
           struct {
                 struct {____
                      data_type udata;
                 }
                 receive_response;
           }
           u_receive_point;
           struct {
                struct {
                      data_type udata;
                 }
                 send_request;
           }
           u_send_point;
           struct {
                struct {
                      timer_type name;
                      int time;
                 }
                 timer_request;
                 struct {
                      timer_type name;
                 }
                 timer_response;
           }
           s_access_point;
           struct {
                 struct {
                      id_type id;
                      data_type data;
                      seq_type seq;
                 }
                 data_request;
                 struct {
                      id_type id;
                      data_type data;
                      seq_type seq;
                 }
                 data_response;
           }
           n_access_point;
           struct {
                 struct {
                      id_type id;
                      data_type data;
                      seq_type seq;
                 }
                 packet;
           }
           network_channel;
```

```
lvars;
};
                                   */
/* process dcl code */
struct process_block {
     struct process_block *next;
     char p_ident[MAX_IDENT_LENGTH+1];
     struct channel_block *chan_list;
     struct process_block *refinement;
     int (*proc_ptr)();
     union {
           struct {
                 int state;
                 seq_type send_seq;
                 seq_type recv_seq;
                 buffer_type send_buffer;
                 buffer_type recv_buffer;
                 msg_type p, q;
           }
           s_alternating_process;
           struct {
                 timer_type index;
                 time_struct a_timer;
           }
           s_timer_process;
           struct {
                 int user_number;
                 int count;
           s_user_process;
     }
     lvars;
};
/* procedure code */
struct process_block *ioab_ref(p_block) struct process_block *p_block;
{
     struct process_block *ioalternating_process();
     struct process_block *iotimer_process();
     struct process_block *ionet_proc();
     struct process_block *iouser_process();
     struct channel_block *add_channel_block(), *c_ptr;
     struct process_block *add_refinement_header(), *clean_up(),
                     *process_list;
     process_list = NULL;
     process_list = ioalternating_process(process_list);
     process_list = iotimer_process(process_list);
```

83

```
process_list = ionet_proc(process_list);
process_list = iouser_process(process_list,1);
connect_ports(process_list,4, 1, 0, 1, 1, 0);
connect_ports(process_list,4, 2, 0, 1, 2, 0);
connect_ports(process_list,4, 3, 0, 2, 1, 0);
connect_ports(process_list,4, 4, 0, 3, 1, 0);
p_block = add_refinement_header(p_block,process_list);
p_block->refinement = clean_up(p_block->refinement);
return(p_block);
```

```
}
```

{

/\*-----\*/

struct process\_block \*ioalternating\_process(process\_list)

struct process\_block \*process\_list;

struct process\_block \*p\_block, \*add\_process\_block(); extern int alternating process(); struct channel\_block \*add\_channel\_block(), \*c\_ptr; p\_block = add\_process\_block(process\_list, alternating\_process, "alternating\_process"); p\_block->chan\_list = add\_channel\_block(p\_block->chan\_list, &c\_ptr,TRUE,1,0); p\_block->chan\_list = add\_channel\_block(p\_block->chan\_list, &c\_ptr,TRUE,2,0); p\_block->chan\_list = add\_channel\_block(p\_block->chan\_list, &c\_ptr,TRUE,3,0); p\_block->chan\_list = add\_channel\_block(p\_block->chan\_list, &c\_ptr,TRUE,4,0); p\_block->lvars.s\_alternating\_process.state == 1; p\_block->lvars.s\_alternating\_process.send\_seq = 0; p\_block->lvars.s\_alternating\_process.recv\_seq = 0; p\_block->lvars.s\_alternating\_process.send\_buffer.flag = 0; p\_block->lvars.s\_alternating\_process.recv\_buffer.flag = 0; return(p\_block);

}

/\*\_\_\_\_\_\*/

alternating\_process(p\_block,channel,signal)

```
p_block->lvars.s_alternating_process.send_buffer.msg.msgdata =
            signal->lvars.u_send_point.send_request.udata;
     p_block->lvars.s_alternating_process.send_buffer.msg.msgseq =
            p_block->lvars.s_alternating_process.send_seq;
     s_ptr = ALLOCATE(signal_block);
     s_ptr->signal_id = 5;
     s_ptr->lvars.n_access_point.data_request.id = 0;
     s_ptr->lvars.n_access_point.data_request.data ==
            signal->lvars.u_send_point.send_request.udata;
     s_ptr->lvars.n_access_point.data_request.seg =
            p_block->lvars.s_alternating_process.send_seq;
     out(p_block->chan_list,s_ptr,3,0);
     s ptr = ALLOCATE(signal_block);
     s_ptr->signal_id = 3;
     s ptr->lvars.s_access_point.timer_request.name = 0;
     s_ptr->lvars.s_access_point.timer_request.time = 100;
     out(p_block->chan_list,s_ptr,4,0);
     ł
   goto dispose;
if ((channel != NULL) &&
  ((p_block->lvars.s_alternating_process.state == 1)
   (p_block->lvars.s_alternating_process.state == 0)))
  if ((channel->c_id == 2) && (signal->signal_id == 0)) {
     if (p_block->lvars.s_alternating_process.recv_buffer.flag){
     {
     s_ptr = ALLOCATE(signal_block);
     s_ptr->signal_id = 1;
     s_ptr->lvars.u_receive_point.receive_response.udata =
      p_block->lvars.s_alternating_process.recv_buffer.msg.msgdata;
     out(p_block->chan_list,s_ptr,2,0);
     p_block->lvars.s_alternating_process.recv_buffer.flag = 0;
     goto dispose;
  }
if ((channel != NULL) &&
  ((p_block -> lvars.s_alternating_process.state == 0)))
 if ((channel->c_id == 4) && (signal->signal_id == 4)) {
     if ((signal->lvars.s_access_point.timer_response.name == 0)){
     p_block->lvars.s_alternating_process.state = 0;
     {
     s_ptr = ALLOCATE(signal_block);
     s_ptr->signal_id = 5;
     s_ptr->lvars.n_access_point.data_request.id = 0;
     s_ptr->lvars.n_access_point.data_request.data =
      p_block->lvars.s_alternating_process.send_buffer.msg.msgdata;
     s_ptr->lvars.n_access_point.data_request.seq =
      p_block->lvars.s_alternating_process.send_buffer.msg.msgseq;
     out(p_block->chan_list,s_ptr,3,0);
     s_ptr = ALLOCATE(signal_block);
```

```
s_ptr->signal_id = 3;
```

85

```
s_ptr->lvars.s_access_point.timer_request.name = 0;
     s_ptr->lvars.s_access_point.timer_request.time = 100;
     out(p_block->chan_list,s_ptr,4,0);
     goto dispose;
if ((channel != NULL) &&
   ((p_block->lvars.s_alternating_process.state == 1)))
 if ((channel->c_id == 4) && (signal->signal_id == 4)) {
     if ((signal->lvars.s_access_point.timer_response.name == 0)){
       p_block->lvars.s_alternating_process.state = 1;
     p_block->lvars.s_alternating_process.state ==
           p_block->lvars.s_alternating_process.state;
     goto dispose;
if ((channel != NULL) &&
   ((p_block->lvars.s_alternating_process.state == 0)))
 if ((channel->c_id == 3) && (signal->signal_id == 6)) {
     if (ack_ok(signal->lvars.n_access_point.data_response.id,
        signal->lvars.n_access_point.data_response.seq,
        p_block->lvars.s_alternating_process.send_seq)){
     p_block->lvars.s_alternating_process.state = 1;
     p_block->lvars.s_alternating_process.send_buffer.flag = 0;
     p_block->lvars.s_alternating_process.send_seq =
      (((p_block->lvars.s_alternating_process.send_seq + 1)) % 2);
     goto dispose;
if ((channel != NULL) &&
   ((p_block->lvars.s_alternating_process.state == 1) ||
   (p_block->lvars.s_alternating_process.state == 0)))
 if ((channel->c_id == 3) && (signal->signal_id == 6)) {
   if ((signal->lvars.n_access_point.data_response.id == 0)){
     s_ptr = ALLOCATE(signal_block);
     s_ptr->signal_id = 5;
     s_ptr->lvars.n_access_point.data_request.id = 1;
     s_ptr->lvars.n_access_point.data_request.data =
            signal->lvars.n_access_point.data_response.data;
     s_ptr->lvars.n_access_point.data_request.seq =
            signal->lvars.n access point.data response.seq;
     out(p_block->chan_list,s_ptr,3,0);
     if((signal->lvars.n_access_point.data_response.seq ===
       p_block->lvars.s_alternating_process.recv_seq)) {
     ł
     p_block->lvars.s_alternating_process.recv_buffer.flag = 1;
     p_block->lvars.s_alternating_process.recv_buffer.msg.msgdata =
```

```
signal->lvars.n_access_point.data_response.data;
           p_block->lvars.s_alternating_process.recv_buffer.msg.msgseq =
                 signal->lvars.n_access_point.data_response.seq;
           p_block->lvars.s_alternating_process.recv_seq =
            (((p_block->lvars.s_alternating_process.recv_seq + 1)) % 2);
            3
      goto dispose;
     if (channel != NULL) {
           requeue(channel,signal);
           signal=NULL;
      }
dispose:
     free(signal);
                   -*/
int ack_ok(id,seq,send_seq)id_type id;
seq_type seq, send_seq;
{
     int rtv_ack_ok;
     ł
           rtv_ack_ok = (((id == 1)) \&\& ((seq == send_seq)));
     return(rtv_ack_ok);
}
                   -*/
struct process_block *iotimer_process(process_list)
struct process_block *process_list;
{
struct process_block *p_block, *add_process_block();
extern int timer_process();
struct channel_block *add_channel_block(), *c_ptr;
p_block = add_process_block(process_list,timer_process,"timer_process");
p_block->chan_list = add_channel_block(p_block->chan_list,&c_ptr,TRUE,1,0);
for (p_block->lvars.s_timer_process.index = 0;
     p_block->lvars.s_timer_process.index++ <= 0;){
{
p_block->lvars.s_timer_process.a_timer[
 p_block->lvars.s_timer_process.index].flag = 0;
p_block->lvars.s_timer_process.a_timer
 p_block->lvars.s_timer_process.index].secs = 0;
p_block->lvars.s_timer_process.a_timer[
 p_block->lvars.s_timer_process.index].millisecs = 0;
```

87

```
return(p_block);
}
```

}

-----\*/

```
timer_process(p_block,channel,signal)
struct process block *p block;
struct channel_block *channel;
struct signal_block *signal;
{
     struct signal_block *s_ptr;
     if ((channel != NULL))
      if ((channel->c_id == 1) && (signal->signal_id == 3)) {
      schedule_timeout(&p_block->lvars.s_timer_process.a_timer]
           signal->lvars.s_access_point.timer_request.name],
           signal->lvars.s_access_point.timer_request.time);
      }
     goto dispose;
           }
     if (channel != NULL) {
           requeue(channel, signal);
           signal=NULL;
     }
     timer_type index;
     index = random_select(0,0);
     if (timer_expired(&p_block->lvars.s_timer_process.a_timer[index])) {
      {
       p_block->lvars.s_timer_process.a_timer[index].flag = 0;
       s_ptr = ALLOCATE(signal_block);
       s_ptr->signal_id == 4;
       s_ptr->lvars.s_access_point.timer_response.name = index;
       out(p_block->chan_list,s_ptr,1,0);
      }
     goto dispose;
dispose:
     free(signal);
struct process_block *ionet_proc(process_list)
struct process_block *process_list;
```

```
{
struct process_block *p_block, *add_process_block();
extern int net_proc();
struct channel_block *add_channel_block(), *c_ptr;
p_block = add_process_block(process_list,net_proc,"net_proc");
p_block->chan_list = add_channel_block(p_block->chan_list,&c_ptr,TRUE,1,0);
p_block->chan_list = add_channel_block(p_block->chan_list,&c_ptr,FALSE,2,0);
p_block->chan_list = add_channel_block(p_block->chan_list,&c_ptr,TRUE,3,0);
return(p_block);
ł
                   _*/
net_proc(p_block,channel,signal)
struct process_block *p_block;
struct channel_block *channel;
struct signal_block *signal;
struct signal_block *s_ptr;
if ((channel != NULL))
 if ((channel->c_id == 1) && (signal->signal_id == 5)) {
  s_ptr = ALLOCATE(signal_block);
  s_ptr->signal_id = 7;
  s_ptr->lvars.network_channel.packet.id =
      signal->lvars.n_access_point.data_request.id;
  s_ptr->lvars.network_channel.packet.data ==
      signal->lvars.n_access_point.data_request.data;
  s_ptr->lvars.network_channel.packet.seg =
      signal->lvars.n_access_point.data_request.seq;
  out(p_block->chan_list,s_ptr,2,0);
goto dispose;
if ((channel != NULL) )
 if ((channel->c_id == 3) && (signal->signal_id == 7)) {
 s_ptr = ALLOCATE(signal_block);
 s_ptr->signal_id = 6;
 s_ptr->lvars.n_access_point.data_response.id = signal->lvars.network_channel.packet.id;
 s_ptr->lvars.n_access_point.data_response.data = signal->lvars.network_channel.packet.data;
 s_ptr->lvars.n_access_point.data_response.seq = signal->lvars.network_channel.packet.seq;
 out(p_block->chan_list,s_ptr,1,0);
 }
goto dispose;
ł
if (channel != NULL) {
     requeue(channel, signal);
```

```
signal=NULL;
```

dispose:

}

free(signal);

/\*-----\*/

struct process\_block #iouser\_process(process\_list,number)

```
struct process_block *process_list;
int number;
{
 struct process_block *p_block, *add_process_block();
extern int user_process();
struct channel_block *add_channel_block(), *c_ptr;
p_block = add_process_block(process_list,user_process,"user_process");
p_block->chan_list = add_channel_block(p_block->chan_list,&c_ptr,TRUE,1,0);
p_block->chan_list = add_channel_block(p_block->chan_list,&c_ptr,TRUE,1,0);
p_block->chan_list = add_channel_block(p_block->chan_list,&c_ptr,TRUE,2,0);
p_block->lvars.s_user_process.user_number = number;
p_block->lvars.s_user_process.count = 0;
return(p_block);
}
```

```
/*-----*/
```

```
user_process(p_block,channel,signal)
struct process_block *p_block;
struct channel_block *channel;
struct signal_block *signal;
{
struct signal_block *s_ptr;
if ((channel != NULL) )
 if ((channel->c_id == 2) && (signal->signal_id == 1)) {
 printf("User ");
 printf("%d",p_block->lvars.s_user_process.user_number);
 printf(" received the message ");
 printf("%d",signal->lvars.u_receive_point.receive_response.udata);
 printf("0);
goto dispose;
if (channel != NULL) {
     requeue(channel, signal);
     signal=NULL;
}
request_type request;
```

```
message_value_type message;
request = random_select(0,1);
message = random_select(1,9);
if ((request == 1)) {
      ł
      s_ptr = ALLOCATE(signal_block);
      s_ptr->signal_id = 0;
      out(p_block->chan_list,s_ptr,2,0);
goto dispose;
{
request_type request;
message_value_type message;
request = random_select(0,1);
message = random_select(1,9);
if ((((request == 0)) \&\&
   ((p_block->lvars.s_user_process.count < 5)))) {
  {
 printf("User ");
 printf("%d",p_block->lvars.s_user_process.user_number);
 printf(" sent the message ");
 printf("%d",message);
 printf("0);
 p_block->lvars.s_user_process.count =
      (p_block->lvars.s_user_process.count + 1);
 s_ptr = ALLOCATE(signal_block);
 s_ptr->signal_id = 2;
 s_ptr->lvars.u_send_point.send_request.udata = message;
 out(p_block->chan_list,s_ptr,1,0);
 }
goto dispose;
dispose:
     free(signal);
}
```

/\*----\*/

#include "fdtutil.c"

## Appendix VII

### **Running The Compiler**

To run the compiler is simple. Simply enter:

#### - fdt <inputfile >fdt.c

The outputfile fdt.c will contain the generated C code which is compiled and linked with the utility routines with the following command:

#### - make

This runs the make command which knows how to "make" programs, see the manual for further details.