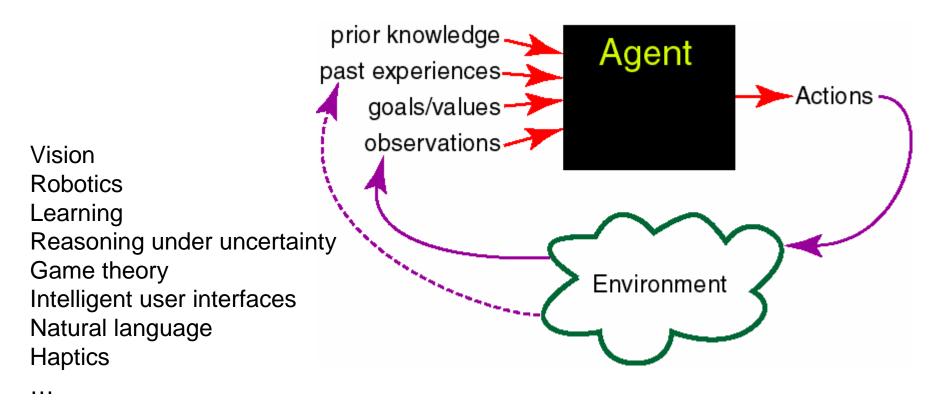


Welcome to LCI! The Laboratory for Computational Intelligence

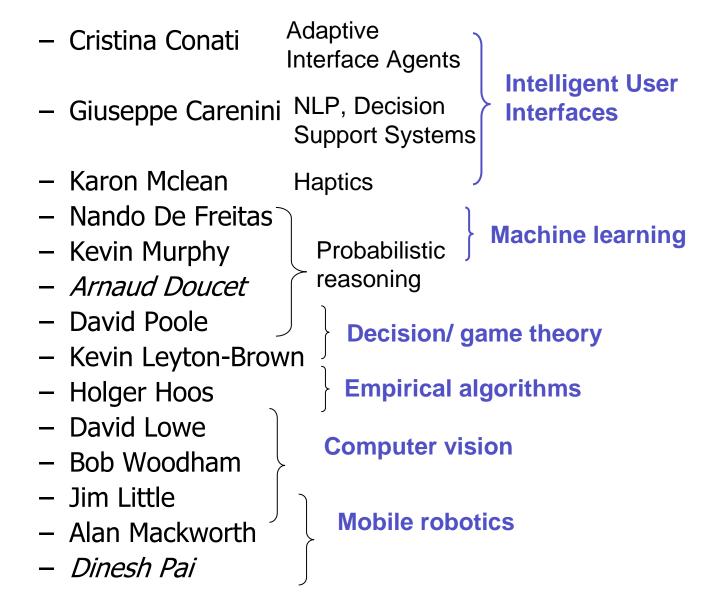


AI as Study and Design of Intelligent Agents

- An *intelligent agent* is such that
 - Its *actions* are *appropriate* for its goals, given the current environment
 - It is *flexible* to changing environments and goals
 - It *learns* from experience



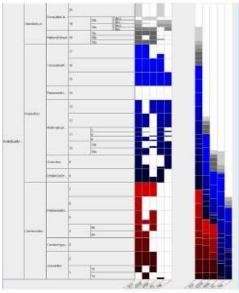
14 faculty members

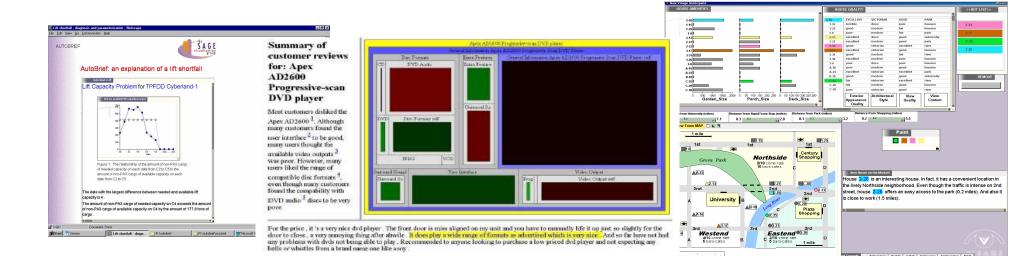


Giuseppe Carenini

- Intersection of computational linguistics, HCI and decision theory
- Generation of understandable and convincing multimedia presentations
 - explanations, arguments, reports, summaries and narratives tailored to the interaction context
 - combine natural language and information graphics
 - provide interactive means for enabling users to further explore the information presented.







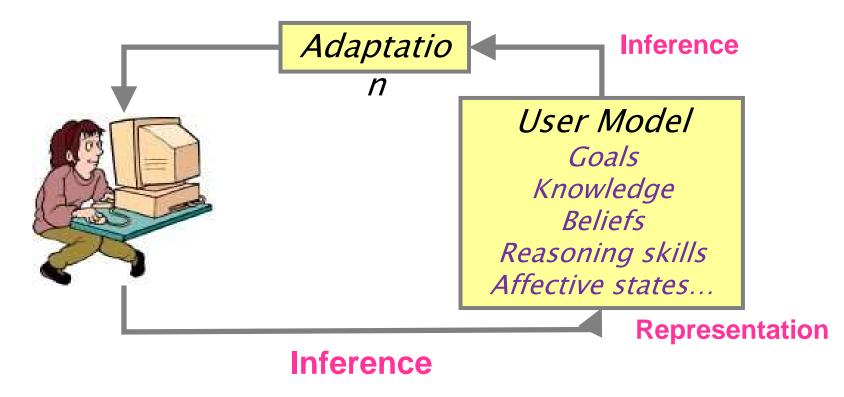
C

Cristina Conati

Intelligent User Interfaces



- integrate research in AI, HCI and Cognitive Science to devise interactive systems that can *autonomously adapt* to their users' needs
- How to *infer, represent* and *reason about* non-trivial user features relevant to intelligently adapt to the user's needs



C

Arnaud Doucet

- Simulation-Based Methods
 - Bayesian statistics
 - Decision under uncertainty
 - Optimization of structured stochastic systems
- Applications
 - Classification and regression in complex models
 - Bioinformatics, computational genetics, tracking

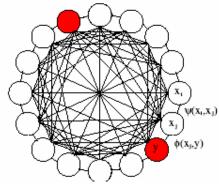
$$\pi_{\theta} (x_{n}, Y_{n}) = \left[\int \int \alpha_{\theta} (x_{n-1:n}, Y_{n}) q_{\theta} (x_{n} | Y_{n}, x_{n-1}) p_{\theta} (x_{n-1} | Y_{1:n-1}) dx_{n-1:n} \right]^{-1} \times \left\{ \int \nabla \alpha_{\theta} (x_{n-1:n}, Y_{n}) q_{\theta} (x_{n} | Y_{n}, x_{n-1}) p_{\theta} (x_{n-1} | Y_{1:n-1}) dx_{n-1} + \int \alpha_{\theta} (x_{n-1:n}, Y_{n}) \nabla q_{\theta} (x_{n} | Y_{n}, x_{n-1}) p_{\theta} (x_{n-1} | Y_{1:n-1}) dx_{n-1} + \int \alpha_{\theta} (x_{n-1:n}, Y_{n}) q_{\theta} (x_{n} | Y_{n}, x_{n-1}) \nabla p_{\theta} (x_{n-1} | Y_{1:n-1}) dx_{n-1} \right\}$$

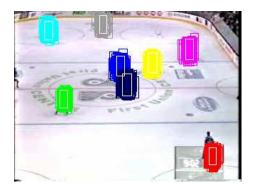


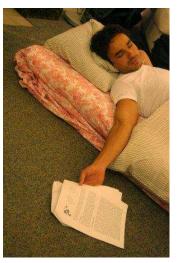


Nando de Freitas

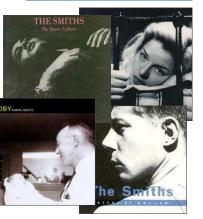




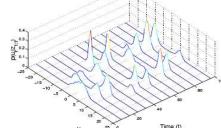






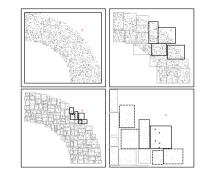


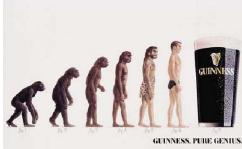
- Active learning, optimal control, decision making under uncertainty, performing the right experiment, asking the right questions, marrying the right person.
- Particle filtering, Monte Carlo and N-Body simulation.
- Learning in large distributed systems: factor graphs, random fields, brains.
- Learning relations, object identity and the number of objects in probabilistic first order logic systems.
- ... Mars rovers, multimedia search engines, music, animation, tracking, object recognition, games, sensor networks and robotics.









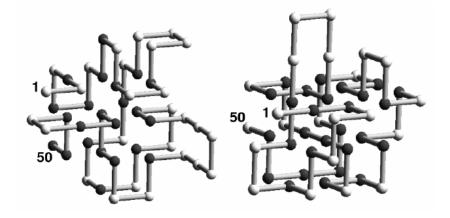




Holger Hoos



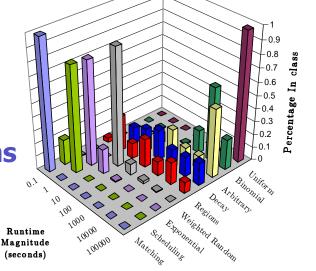
- Hard combinatorial problems from AI and Bioinformatics
- Design and characterisation of stochastic local search algorithms for such problems
- Human-centred information management
- Computer music



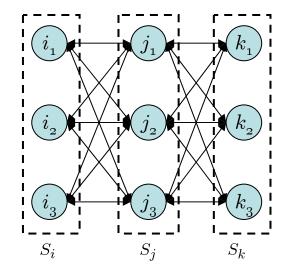


Kevin Leyton-Brown

- Research goals:
 - theoretical problems in multiagent systems
 - understanding empirical properties of algorithms



- Research areas:
 - Computational Game Theory
 - Auction Theory, Mechanism Design
 - Trading Agents
 - Bounded Rationality
 - Empirical Hardness Models

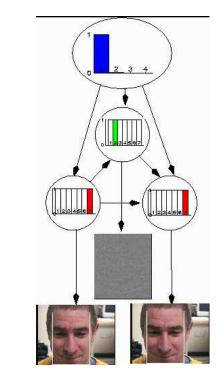






Jim Little

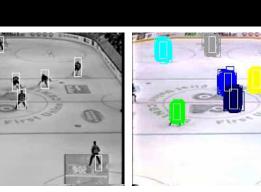
Cognitive vision Action recognition Visual tracking Mobile robotics











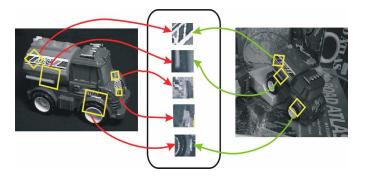


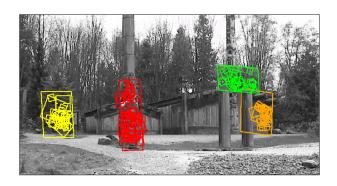


David Lowe

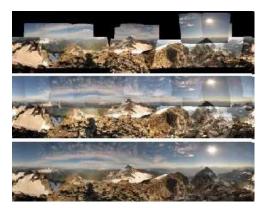
Object recognition Invariant image features (SIFT) Panorama stitching, augmented reality Recognition in large image databases







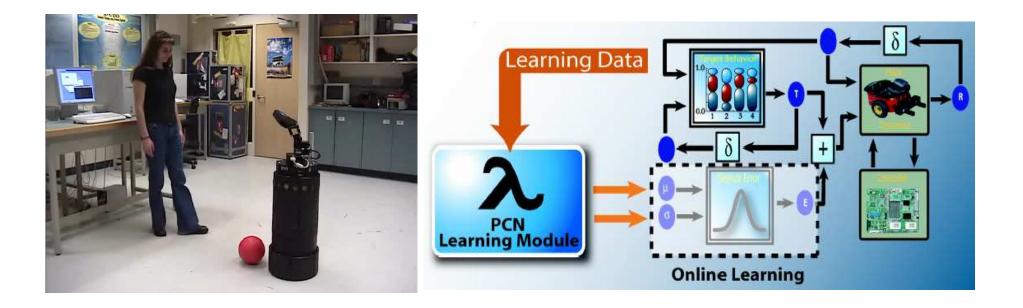






Alan Mackworth

- Constraint-based agents: models, languages and systems
- Computational vision and robotics
- Multiagent systems including soccer-playing robots
- Specification, modeling and verification of hybrid dynamical systems





Karon Maclean robotics / haptic interfaces



physical user interfaces:

talking to computers through your hands defining perceptual spaces \rightarrow language

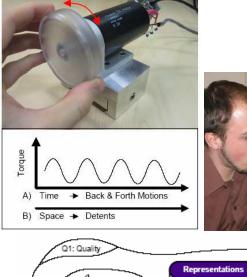
haptic force feedback

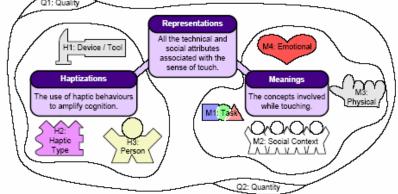
novel devices embedding interfaces in the world: *cars, homes, portables* expressive control - art & streaming media

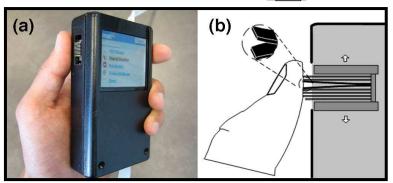
transparent multisensory interfaces

non-conscious interfaces

haptic guidance: sharing control w/ intelligent systems





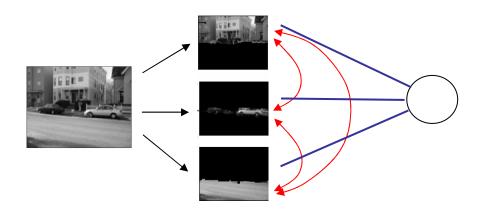


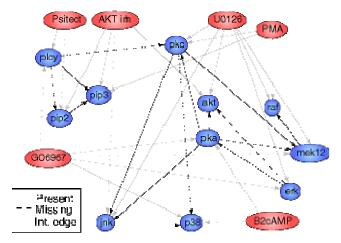
Kevin Murphy

- Machine learning
 - Probabilistic graphical models
 - Algorithms for Bayesian statistics $p(\theta|D) = \frac{p(D|\theta)p(\theta)}{p(D)}$
- Applications

CO

- Visual object detection and scene understanding
- Computational biology, network discovery







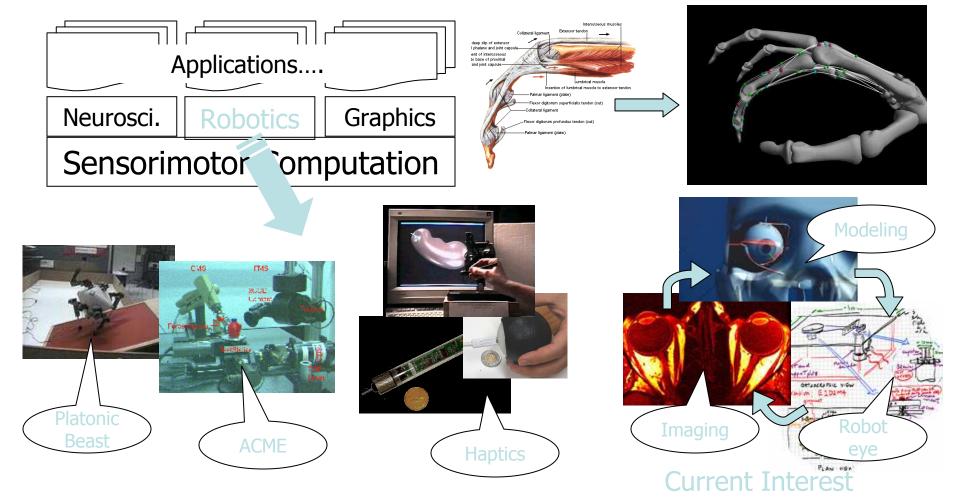




Dinesh K. Pai



• Research: Sensorimotor Computation

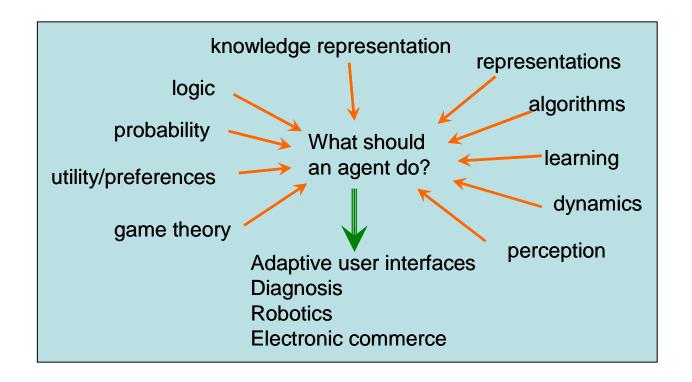




David Poole



"What should an agent do based on its prior knowledge, what it observes about the world, and its values or goals?"



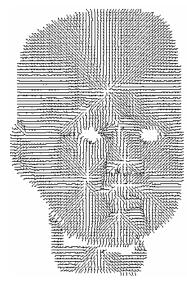
Robert J. Woodham

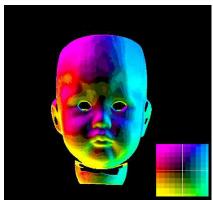
- Focus: Computer interpretation of 3D shape and visual motion
- Objective: To understand how the measurement of visual motion can support high-level interpretation tasks related to object identity, non-visual physical properties and, for an object that is an intelligent agent, to actions and intentions.
- Strategy: Link the interpretation of motion and 3D shape *as early as possible* in visual processing.

Research interests

- Image databases and content-based image retrieval
- Remote sensing and geographic information systems (GIS)
- Connections to biological vision, especially colour vision







Some Research Groups in LCI

- Adaptive Interfaces, Natural Language Processing, Haptics
- Machine Learning, Game Theory and Multi-Agent Systems
- Computational Vision, Robotics and Constraintbased Systems



Some LCI Grad Courses

- Image Understanding and Computer Vision
- Machine Learning
- Multi-agent Systems and Game Theory
- Artificial Intelligence
- Computational Linguistics
- Optimal Decision Making and Control
- Bayesian Inference and Monte Carlo Simulation
- Intelligent User Interfaces
- Sensory-motor computation

Join LCI: the world's best AI lab!



C

- Great projects
- Great people
- Sense of scientific adventure
- Support for the risky and new
- Good infrastructure
- Fun!