

# Approximate decoding: ICM, block methods, alpha-beta swap & alpha-expansion

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Sense & Understand: Challenges

Sense & Understand

While Movable obstacles avoidance- is well accomplished by incrementally expanding existing ADAS sensing, the problem of **autonomous driving Path determination** requires a quantum leap:

- Lane marks not visible, yet human driver knows what to do
- Lanes split/merges/beginning/ending creates ambiguities
- Critical on-road markings that are not lanes: Traffic Islands, arrows.
- Structural path delimiters: barriers, cones, curbs, guardrails, barrels.



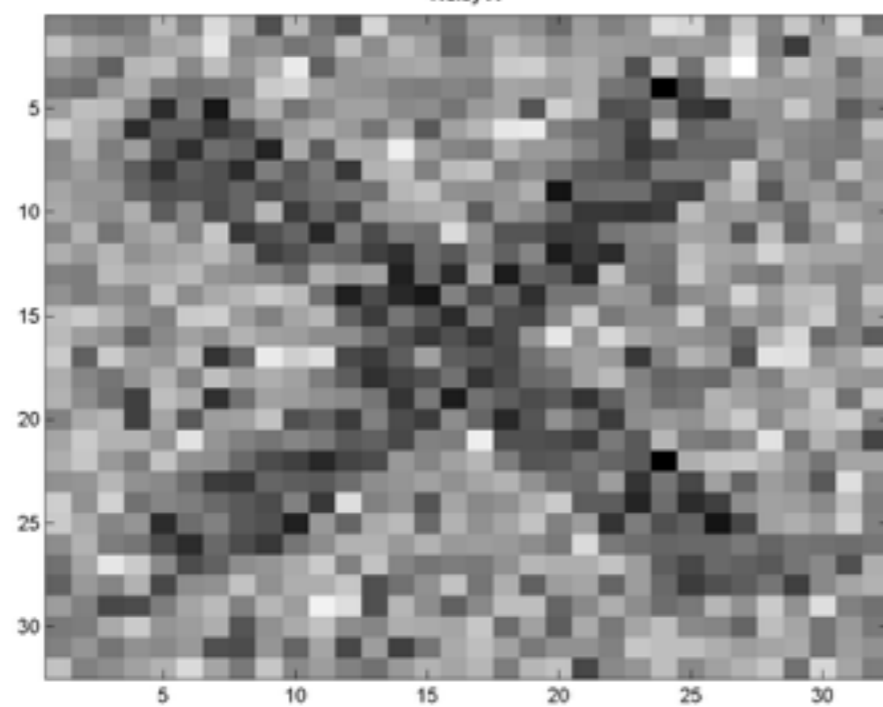
<https://www.youtube.com/watch?v=kp3ik5f3-2c&t=18m36s>

# Outline

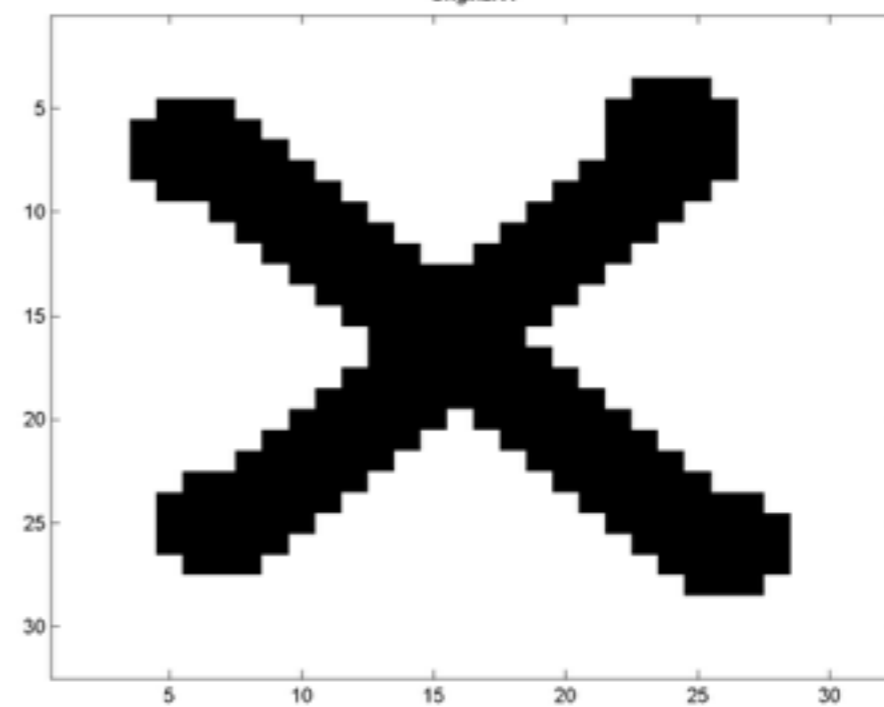
- Motivation
- Approximate decoding
- ICM: Iterated conditional modes
- Block methods
- Alpha-beta swap & alpha-expansion

Motivation

Noisy X



Original X







Photography by Dina Boyer: <https://flic.kr/p/n9kdpQ>

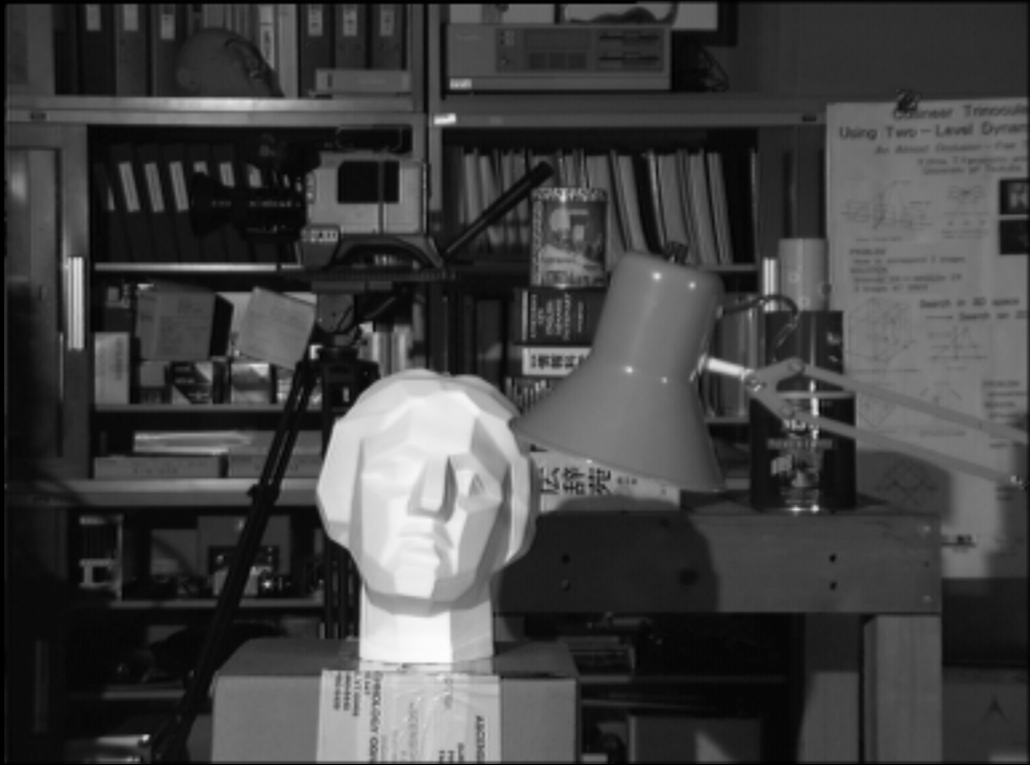


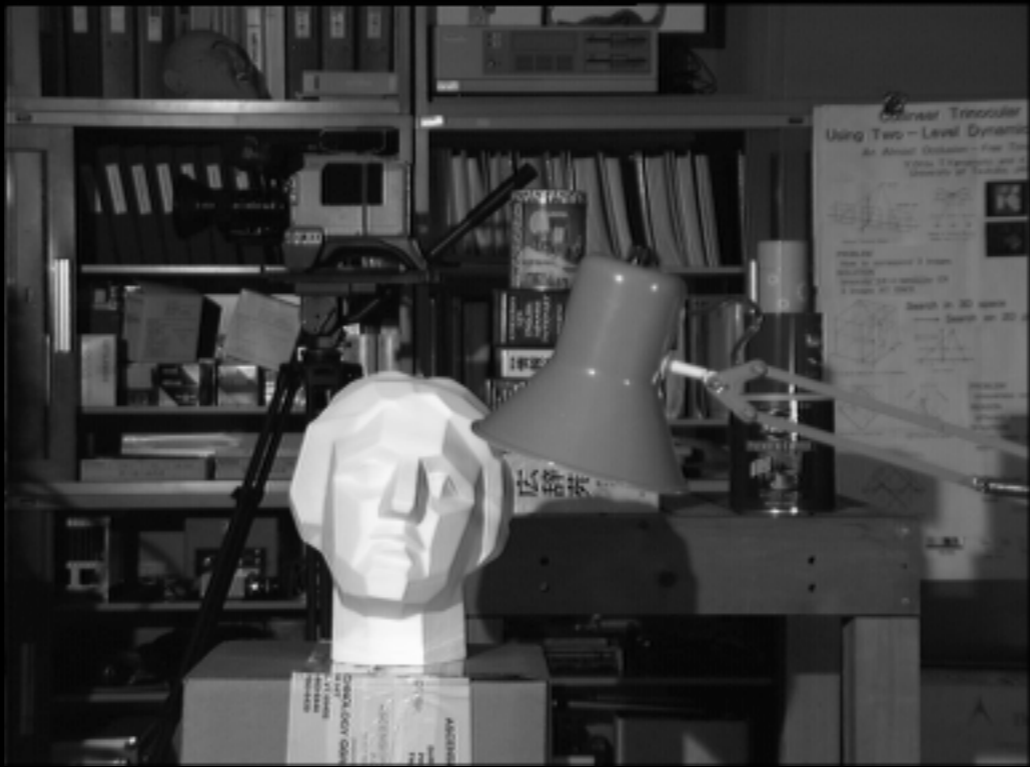
- mountain
- rock
- sea
- sky
- sun

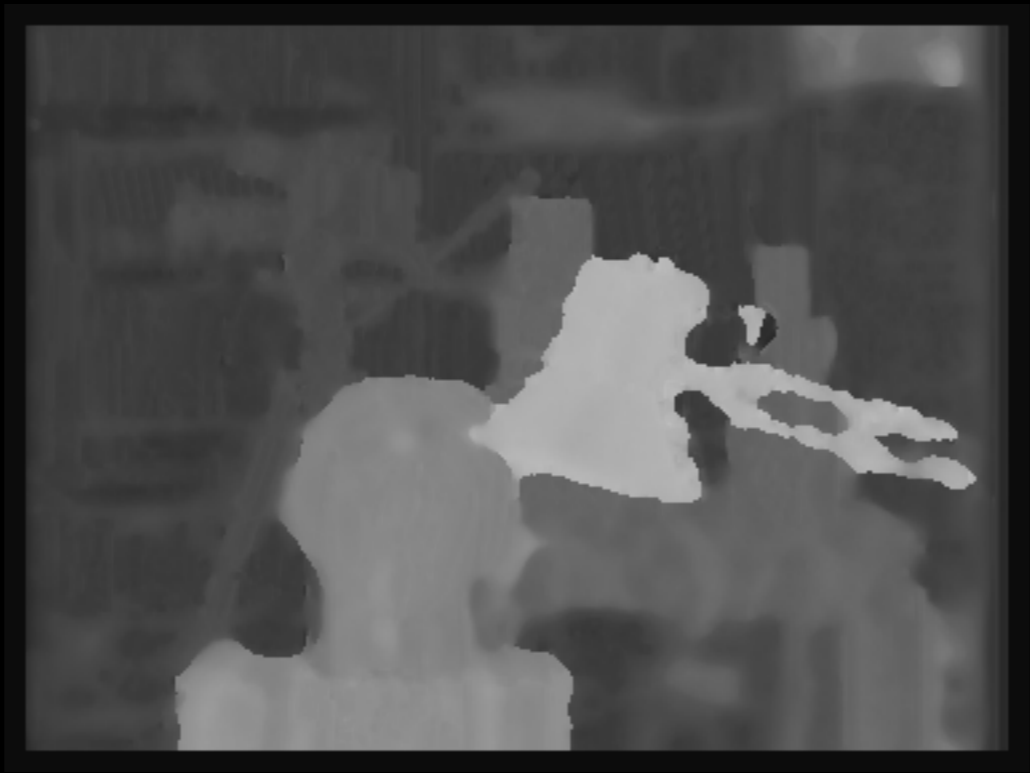


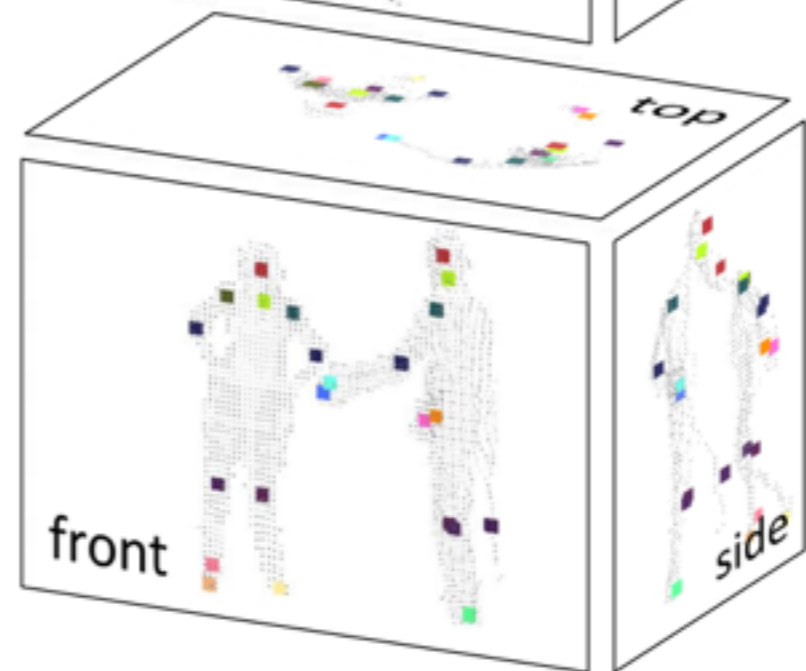
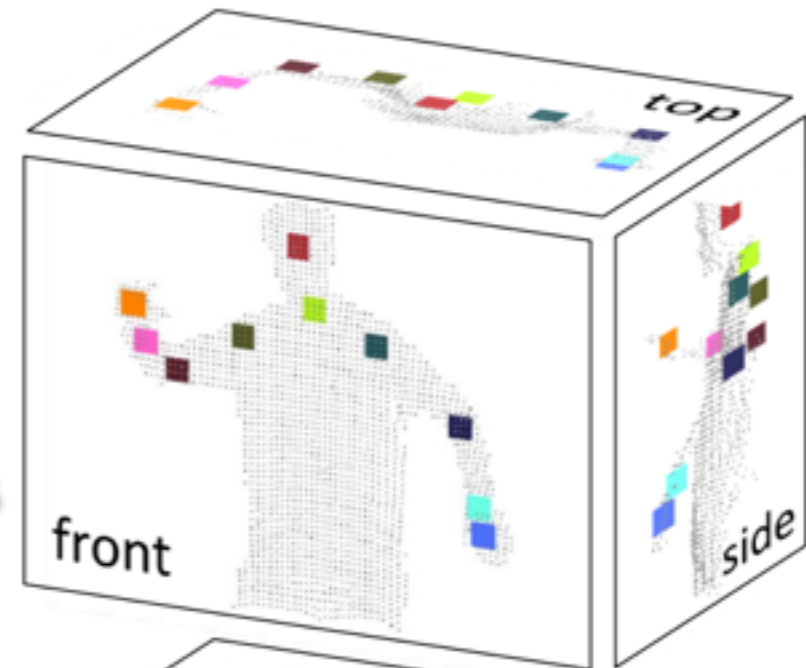
- mountain
- plant
- sky
- tree











depth image



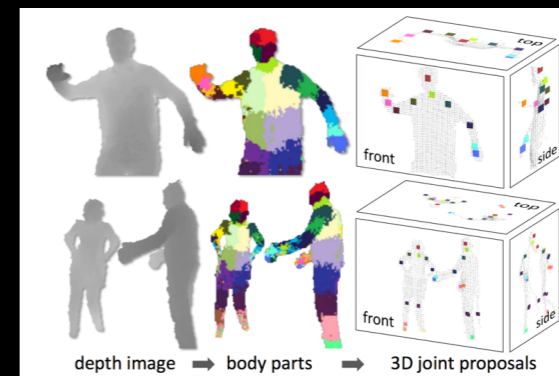
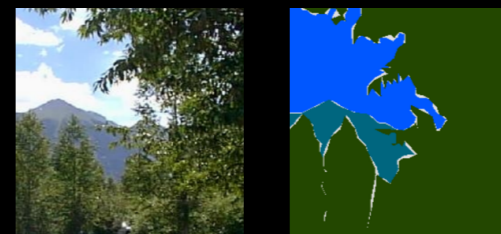
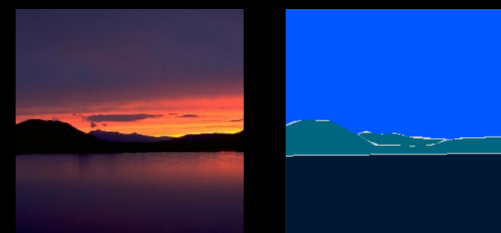
body parts



3D joint proposals

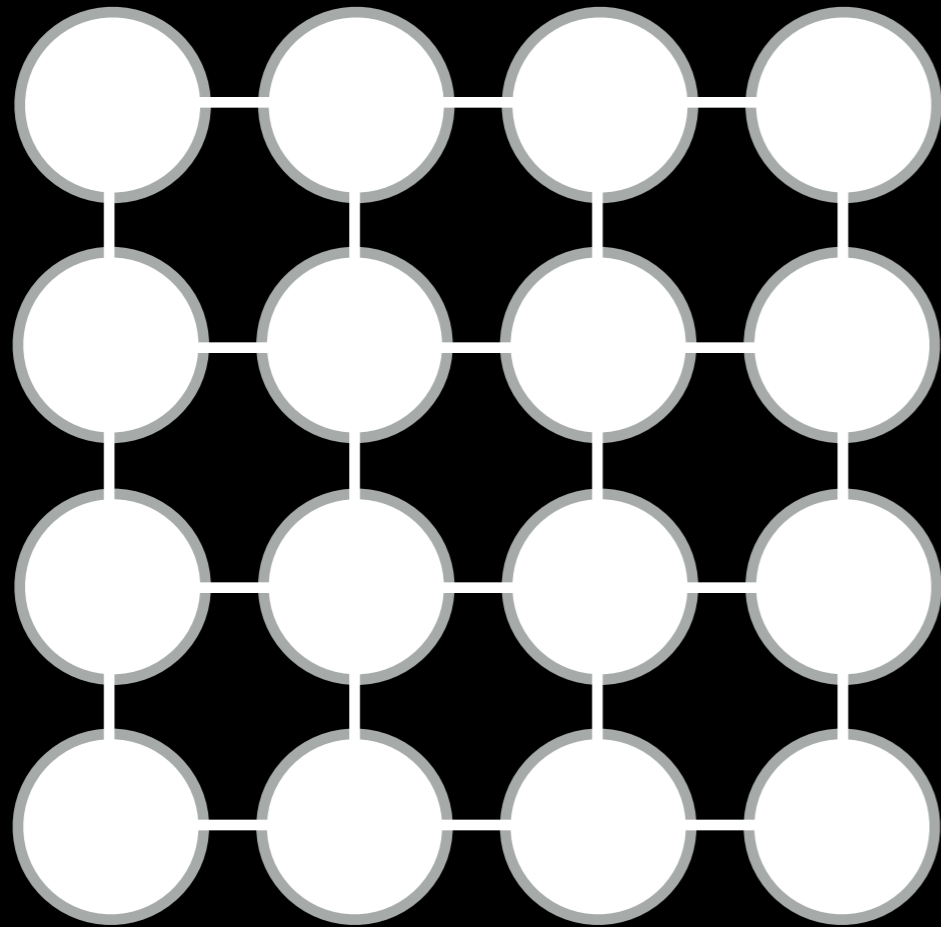
# Motivation

- We often have more than 2 states for each node
- Often the states are not directly comparable
- Exact decoding is NP-hard — but we still want real-time predictions



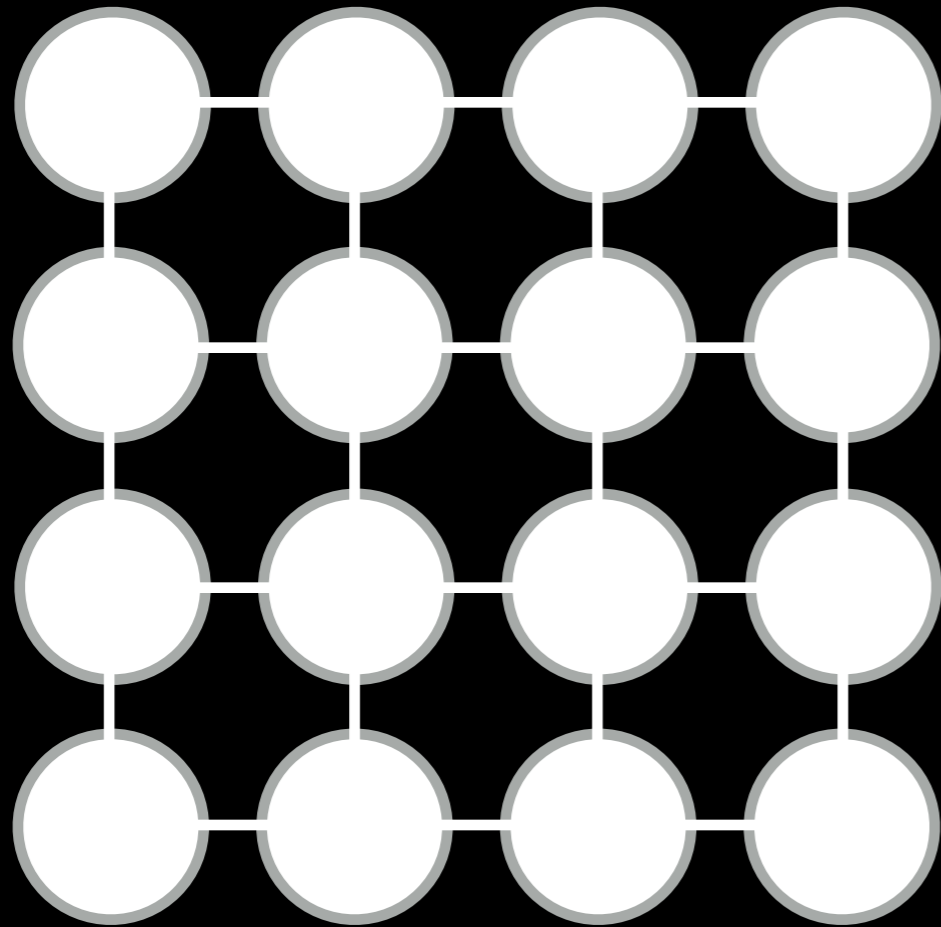
# ICM: Iterated Conditional Modes

- Until convergence

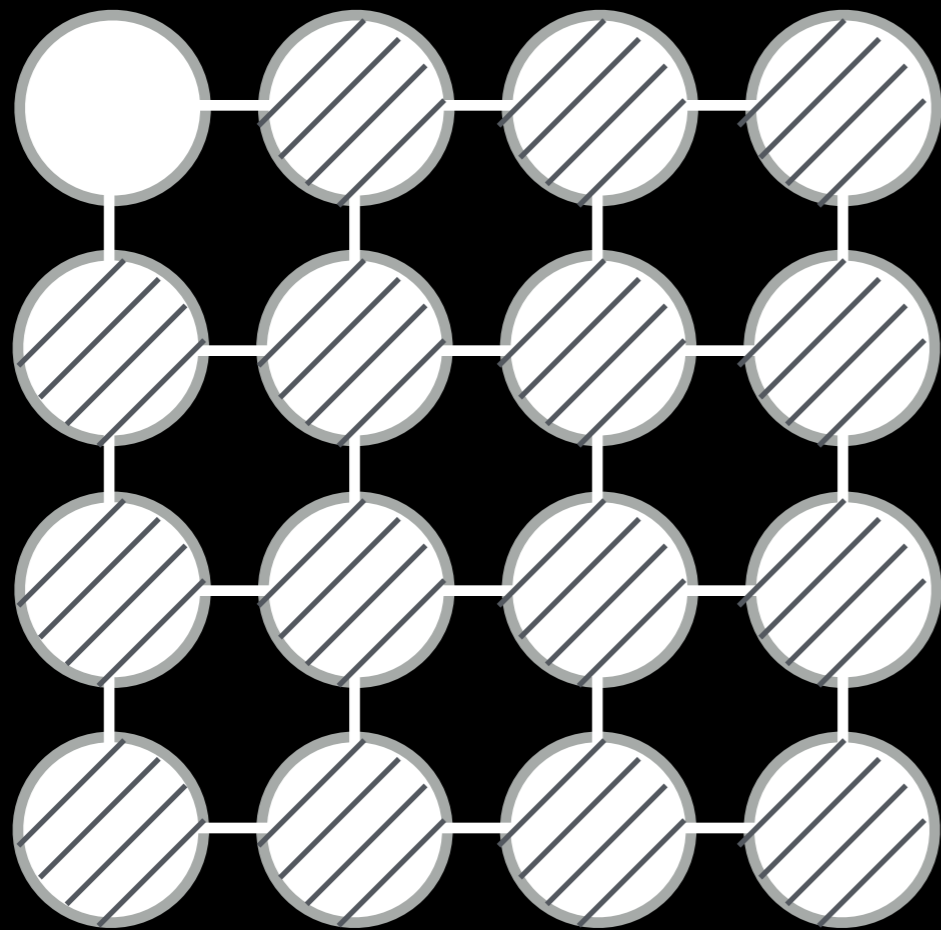


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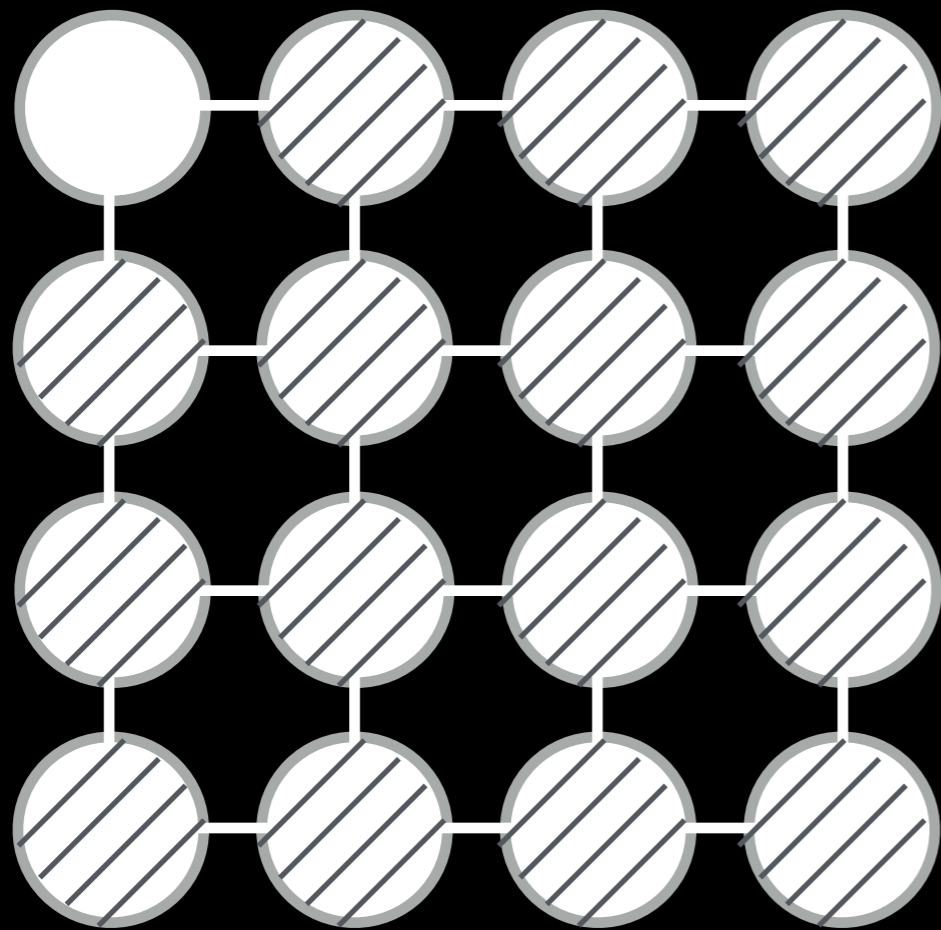
- For  $x_i \in \mathbf{X}$



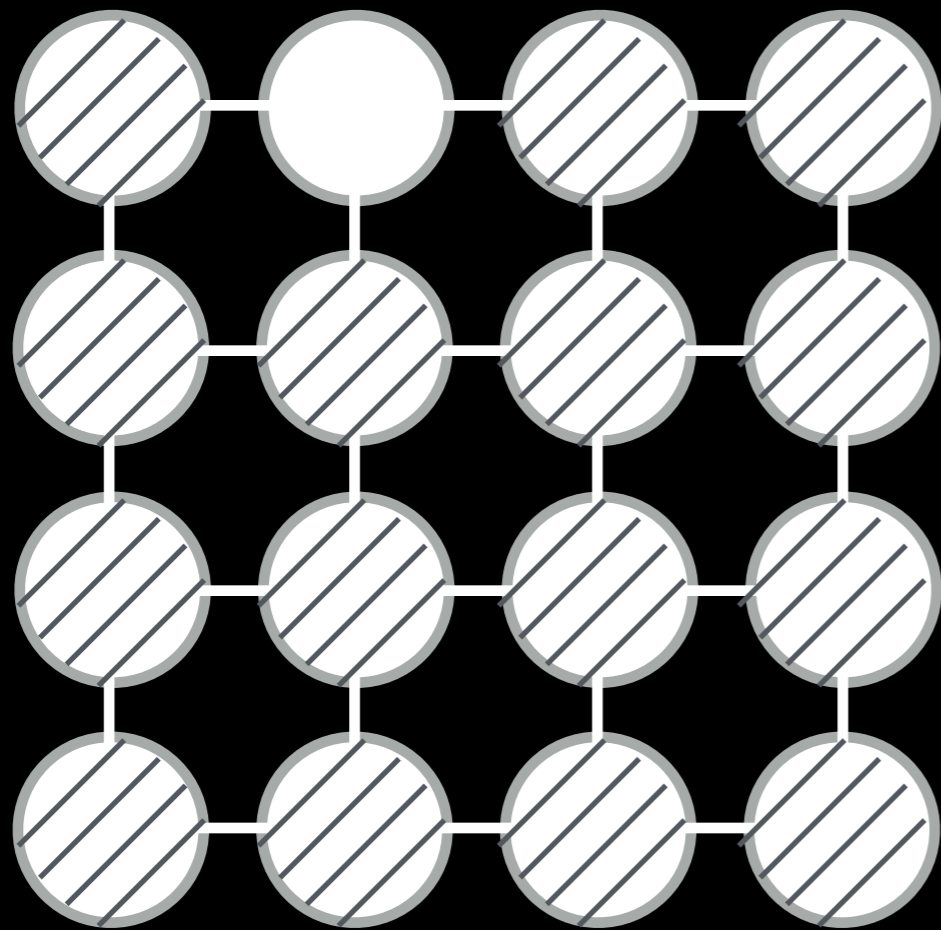




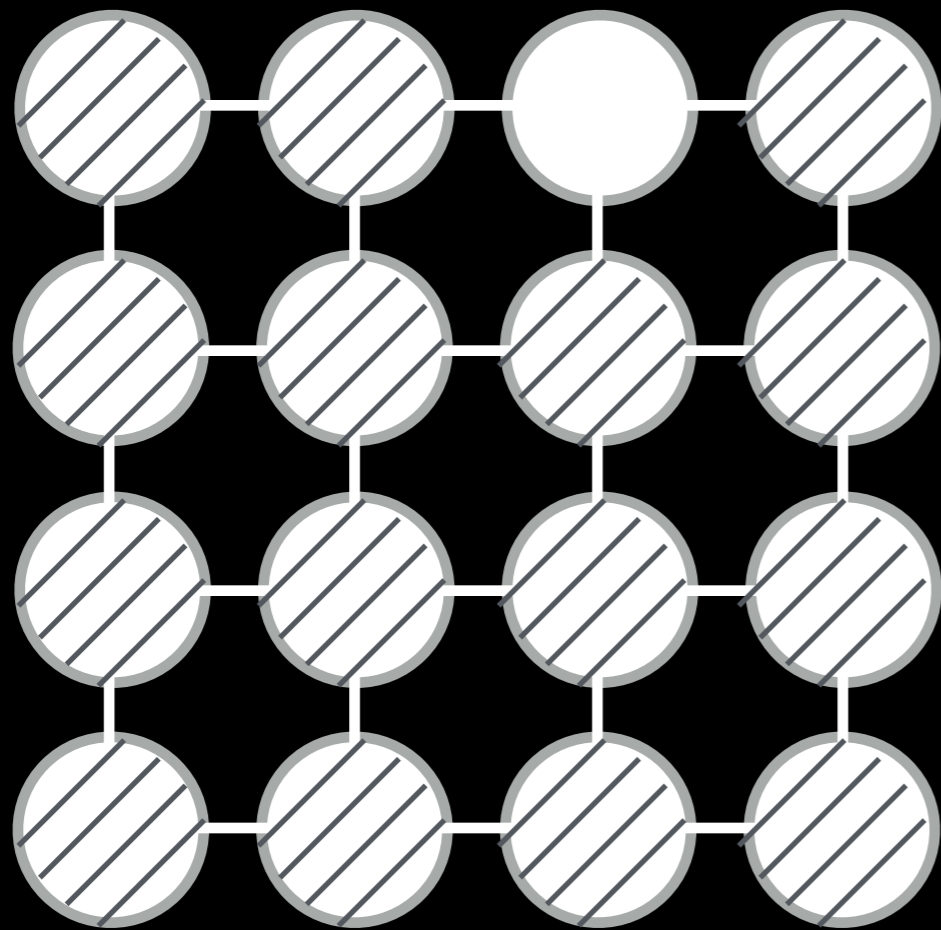
- Until convergence
  - For  $x_i \in \mathbf{X}$ 
    - Assume that all other nodes  $x_j \in \mathbf{X}, j \neq i$  are fixed



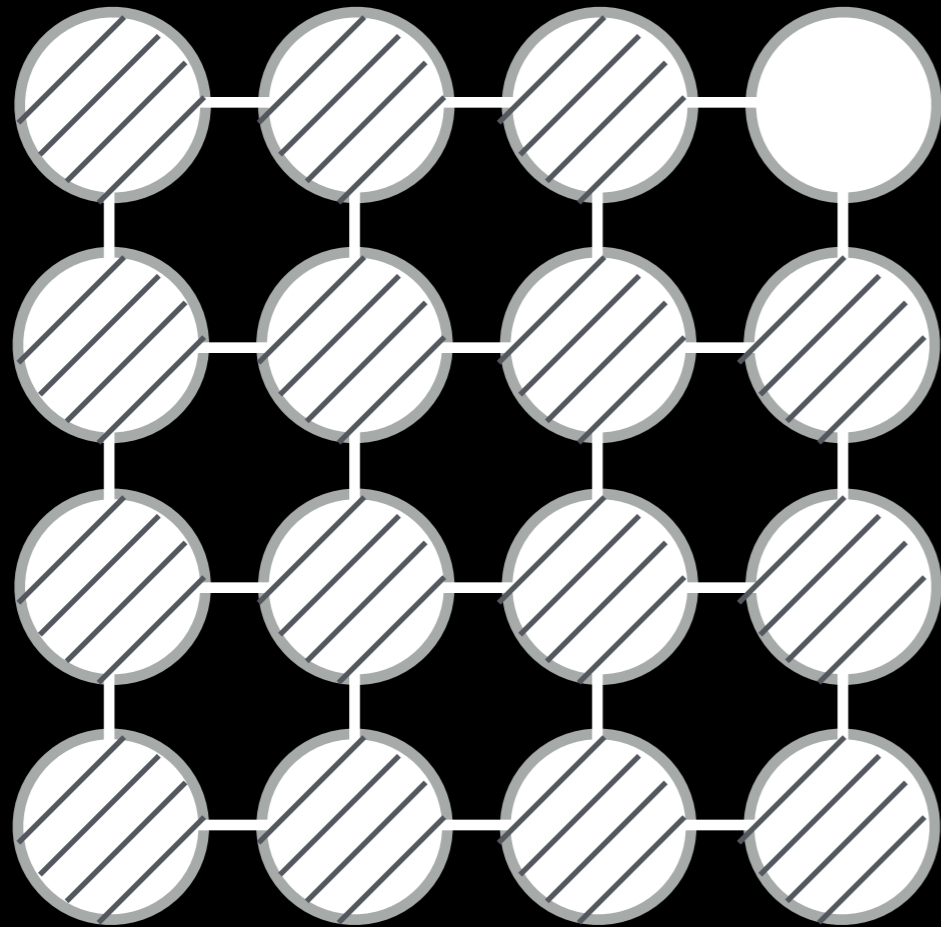
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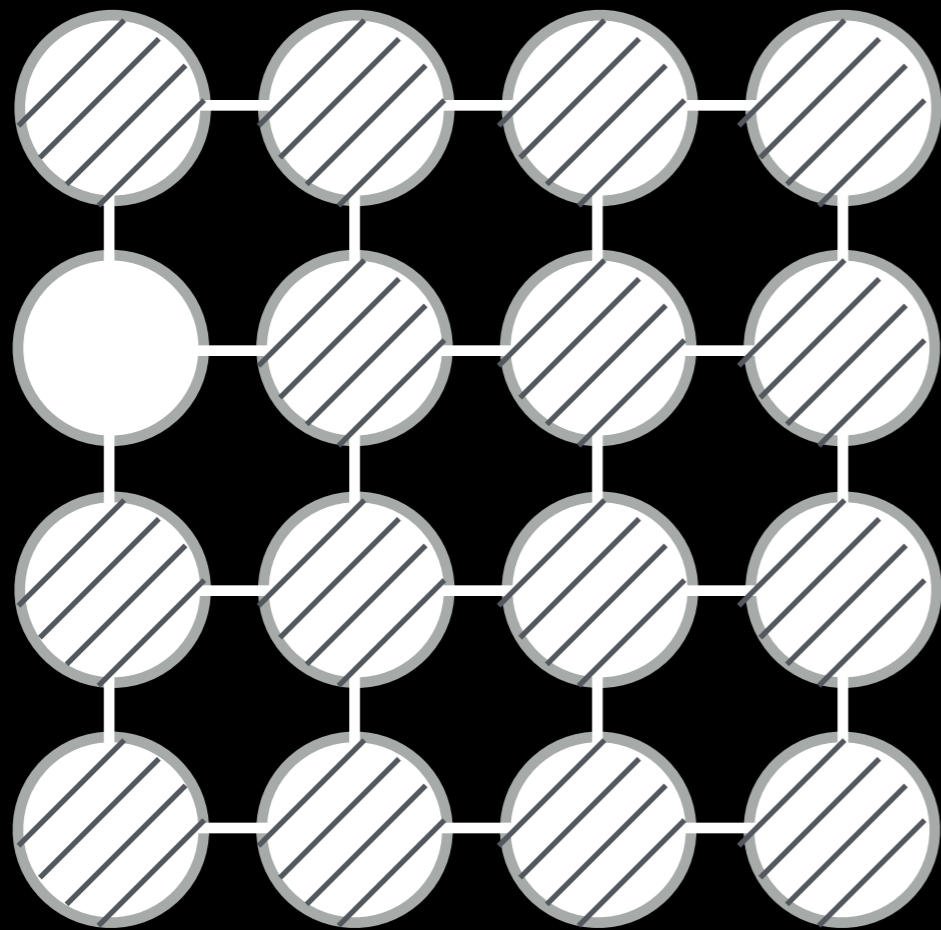
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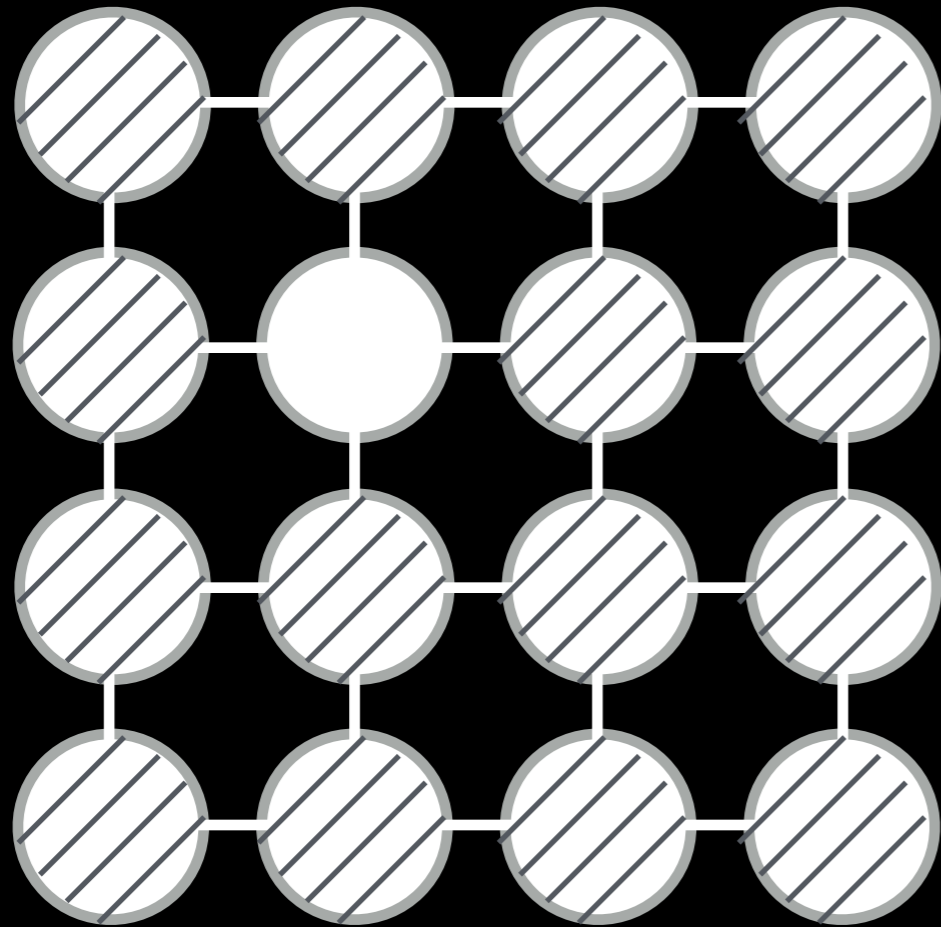
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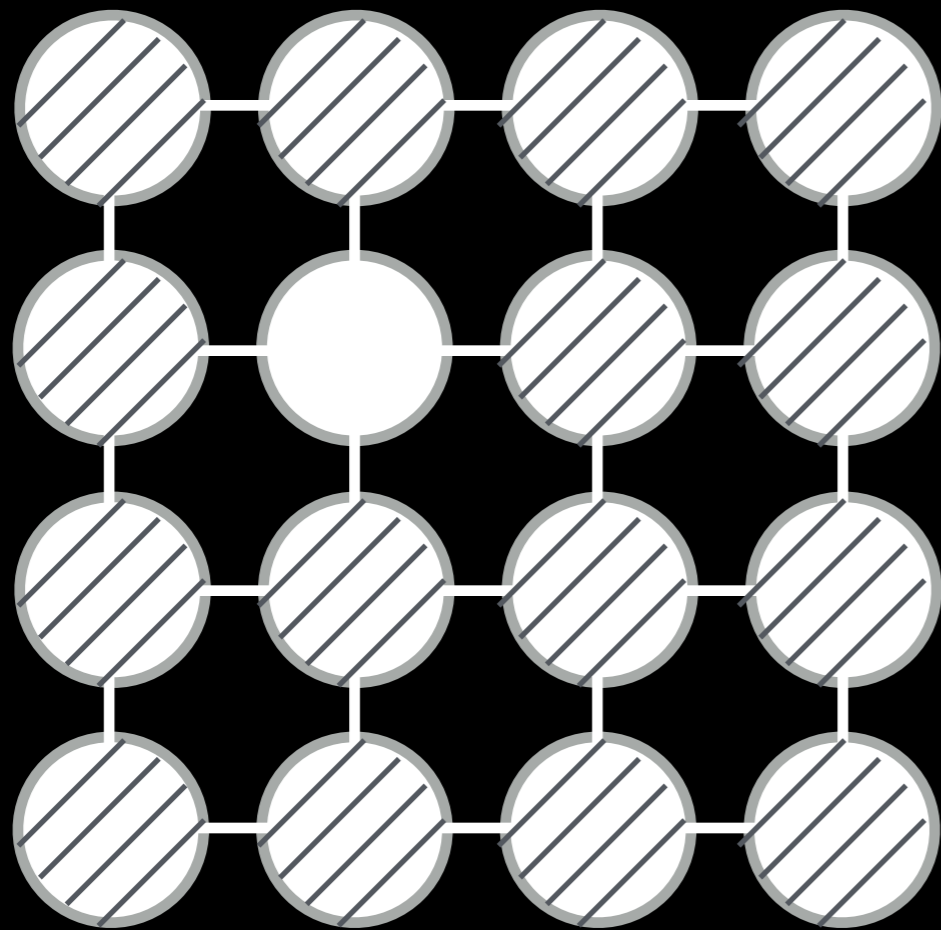
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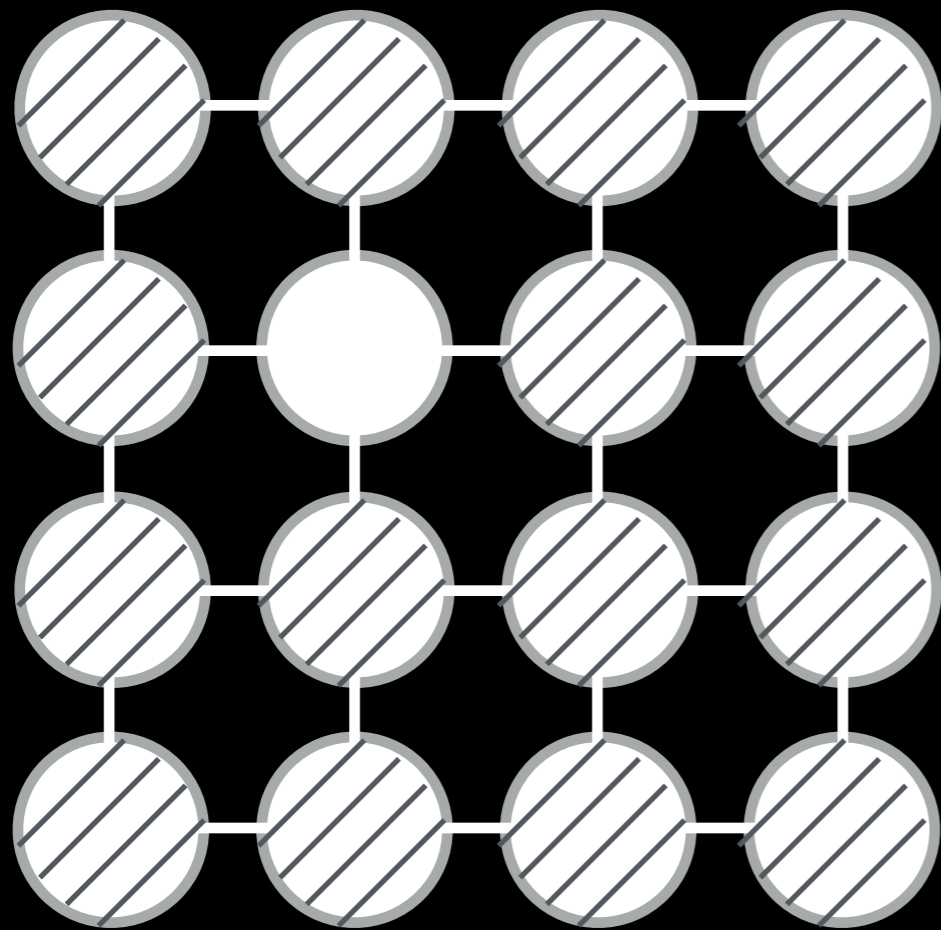
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...and so on

- Until convergence
- For  $x_i \in \mathbf{X}$ 
  - Assume that all other nodes  $x_j \in \mathbf{X}, j \neq i$  are fixed
  - Solve for  $x_i$



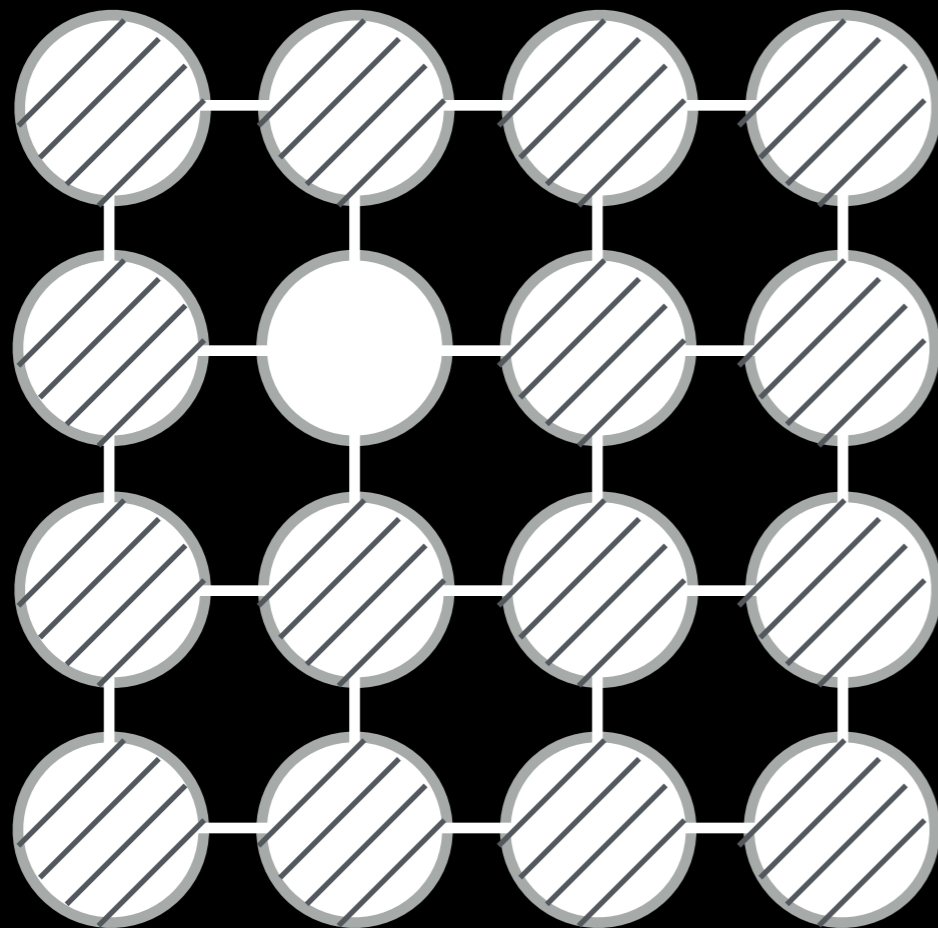


...and so on

- Until convergence

- For  $x_i \in \mathbf{X}$  iterated

- Assume that all other nodes  $x_j \in \mathbf{X}, j \neq i$  are fixed
- Solve for  $x_i$



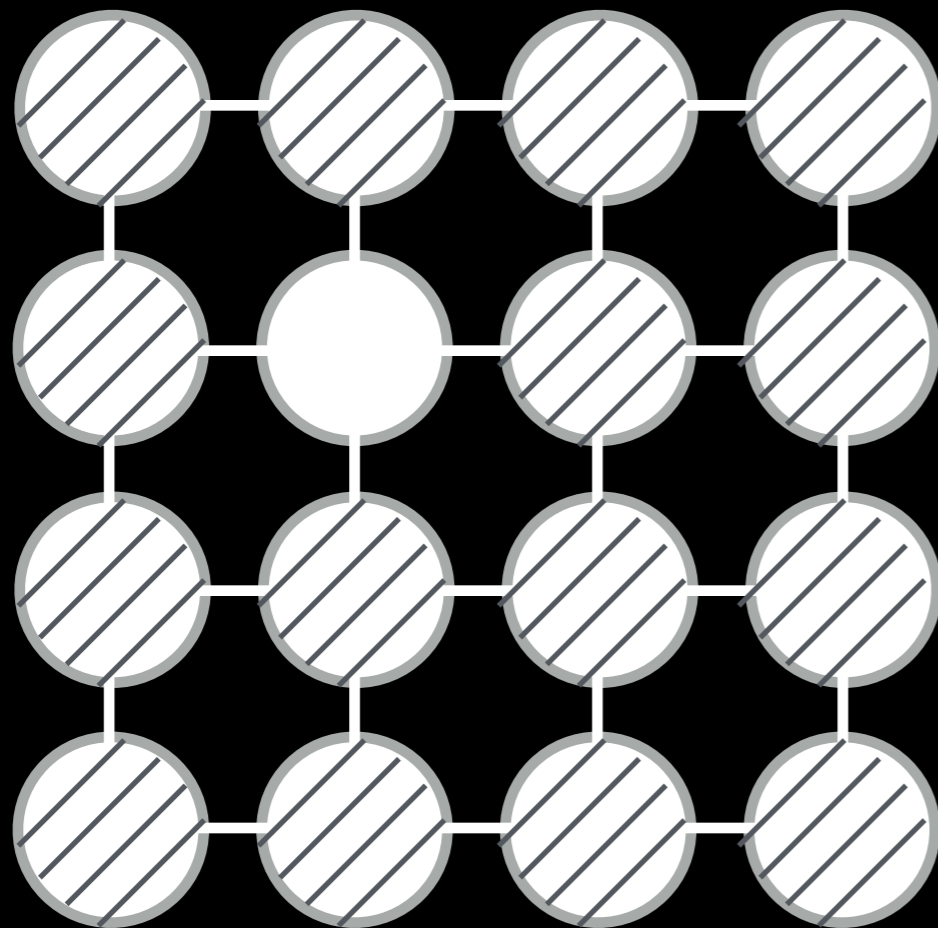
...and so on

- Until convergence

- For  $x_i \in \mathbf{X}$  iterated

- Assume that all other nodes  $x_j \in \mathbf{X}, j \neq i$  are fixed conditional

- Solve for  $x_i$



...and so on

- Until convergence

- For  $x_i \in \mathbf{X}$  iterated

- Assume that all other nodes  $x_j \in \mathbf{X}, j \neq i$  are fixed conditional


- Solve for  $x_i$  modes

# Pros and cons of ICM

- Pros
  - Super fast
  - Super easy to implement
- Cons
  - Greedy — will get stuck on local minima
  - In practice, local minima will not be very good

# Improving ICM

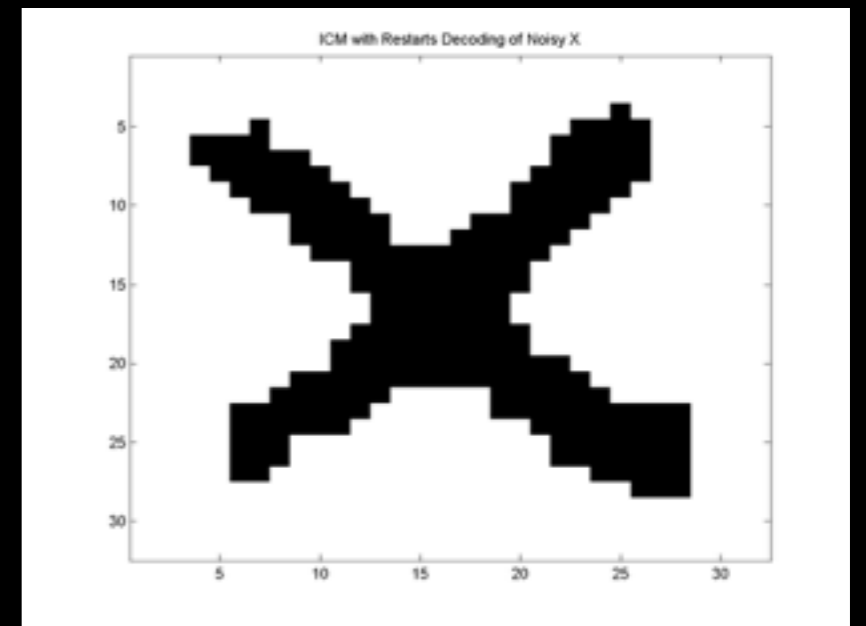
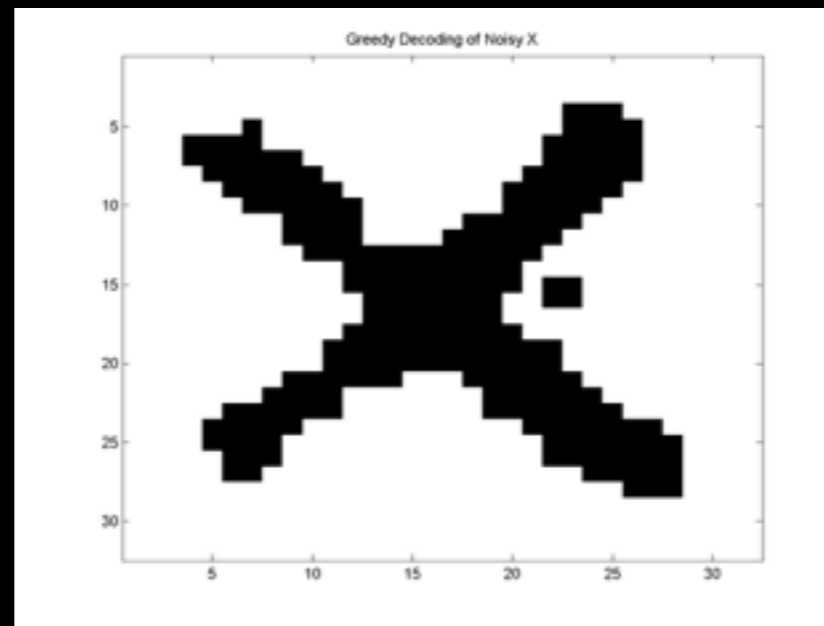
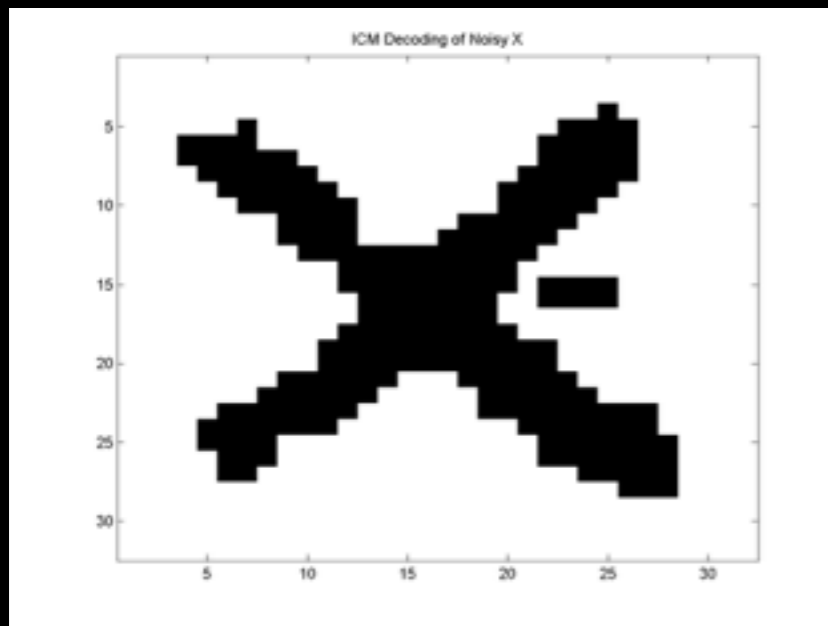
Guaranteed to find global minimum if done enough times

- *Restart* with different initializations 
- Look at all the nodes, and update only the one that gives the *best improvement*

# Improving ICM

ICM with

restarts

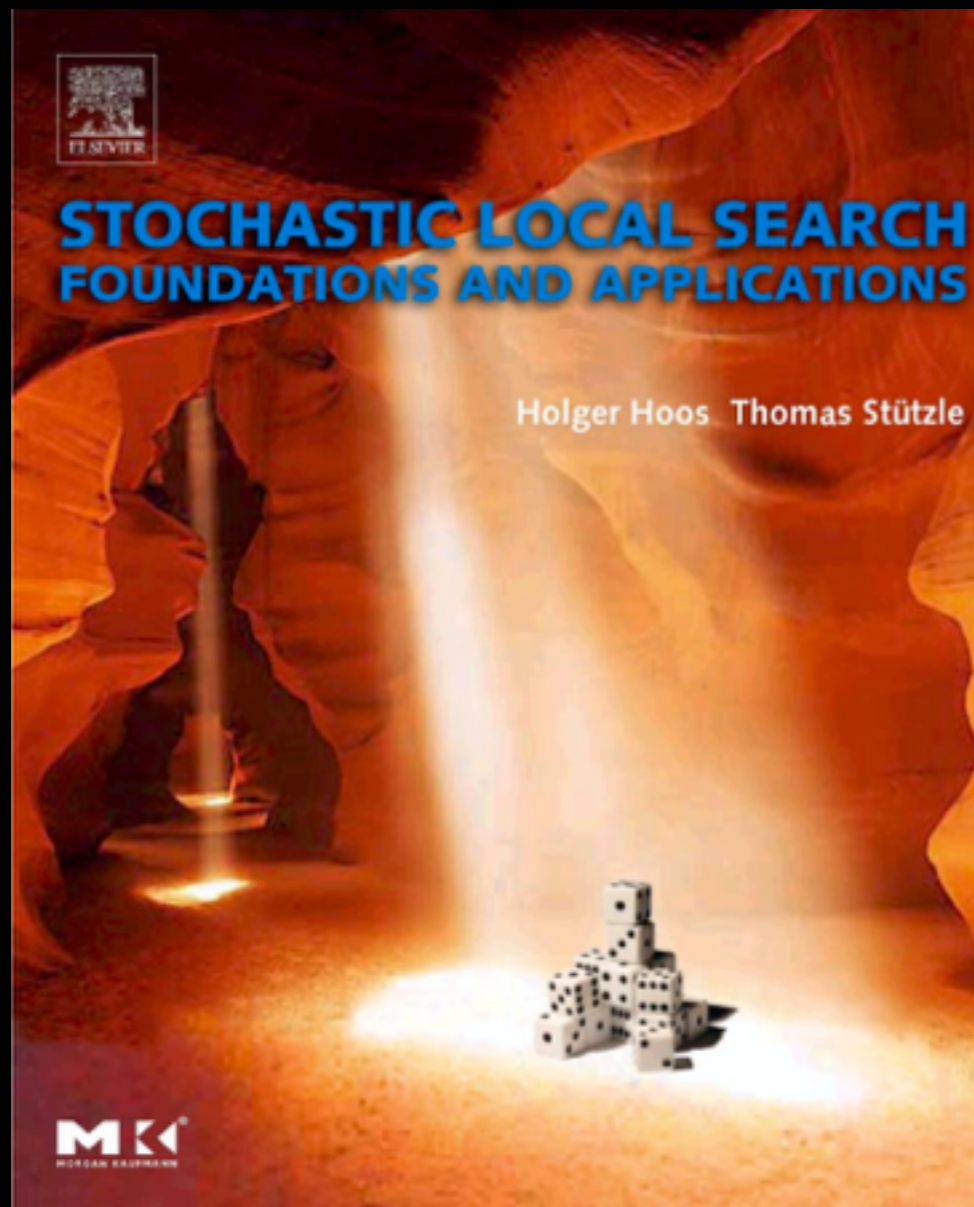


Vanilla ICM

ICM with

best improvement

# Other variants of local search




- Local search is an area of research on its own
- Usually a top performer on SAT, TSP, scheduling, and other NP-hard problems
- Read the book of my supervisor 😊

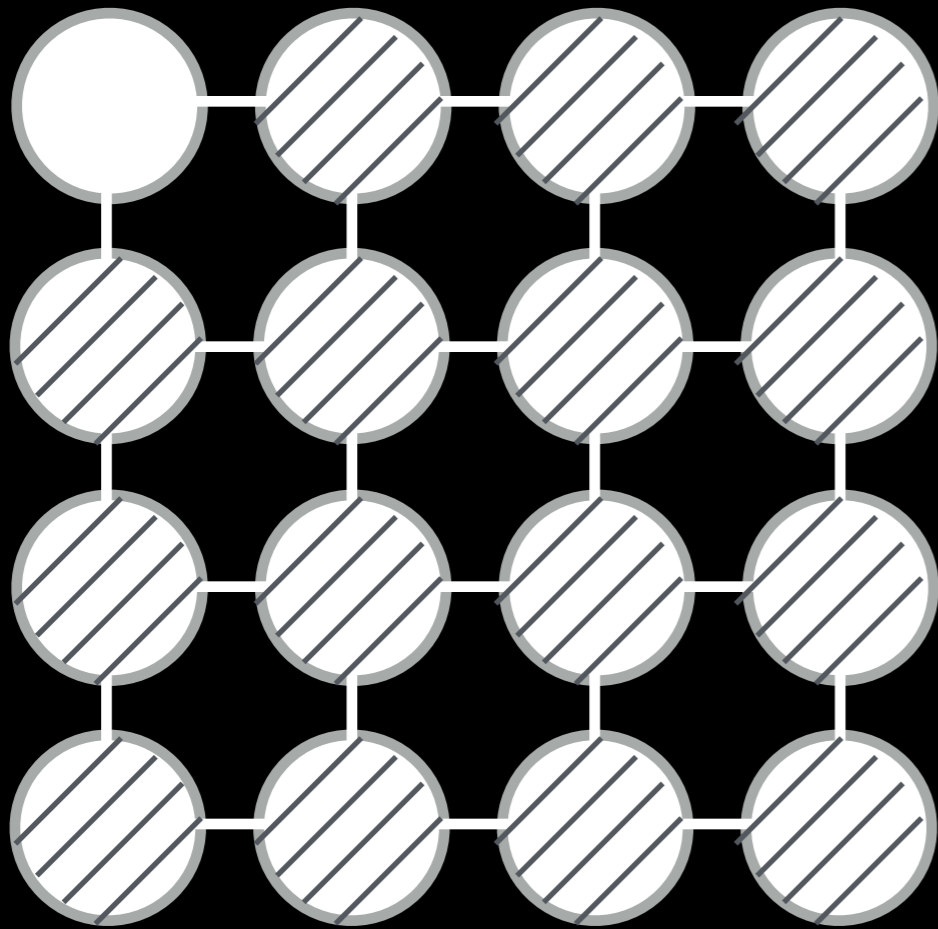
Block methods



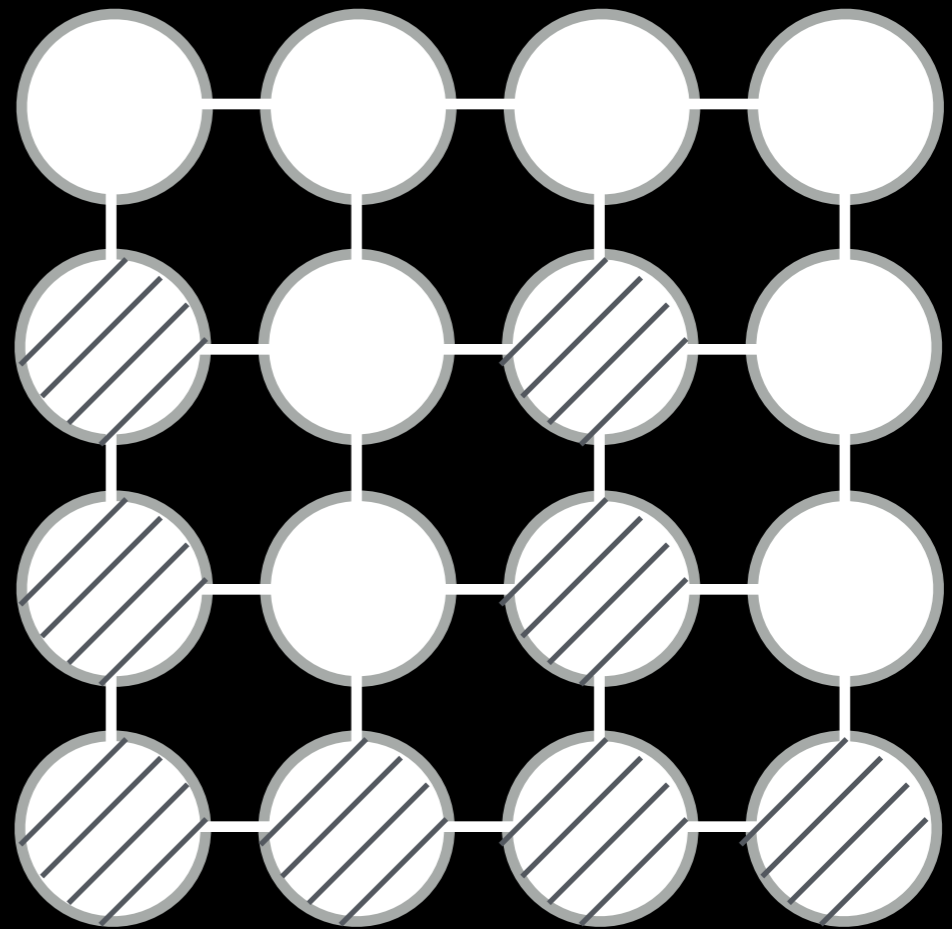
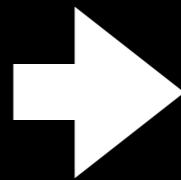
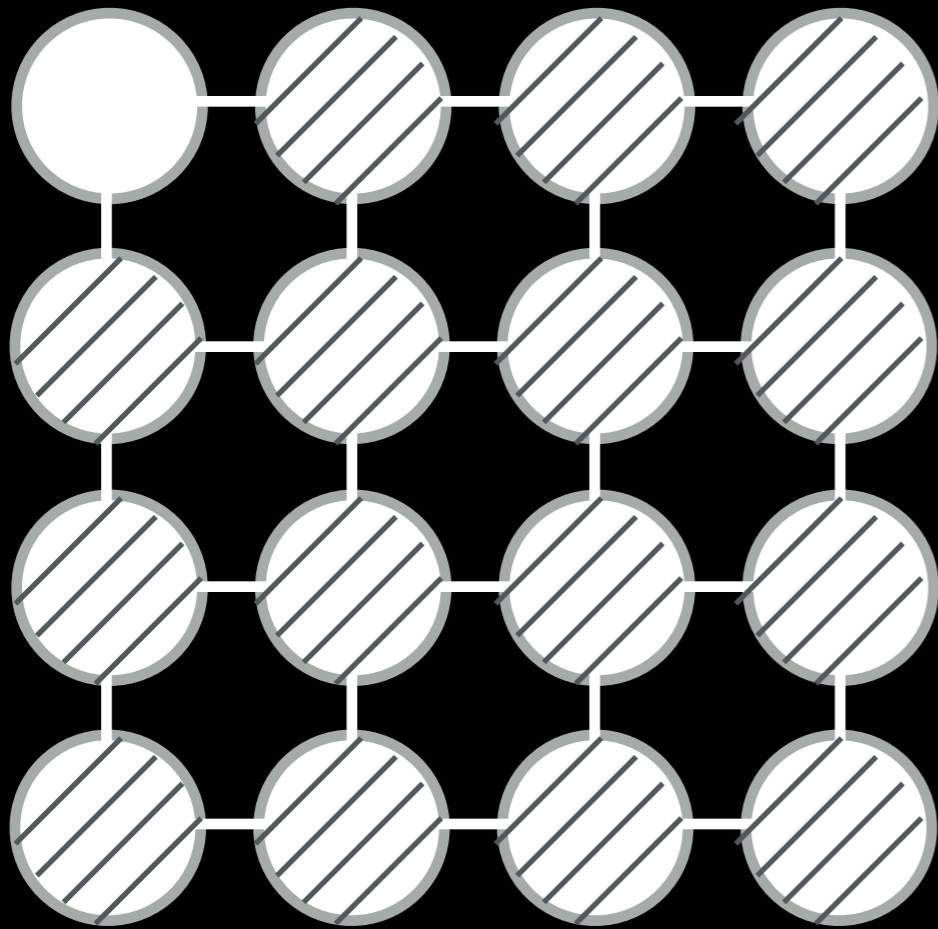
# Block ICM

- In ICM we updated one node at a time
- Simple extension: update more than one node at a time
- In fact, we now have a toolbox to do exact decoding in large graphs  as long as they have a nice graph structure

# Block ICM

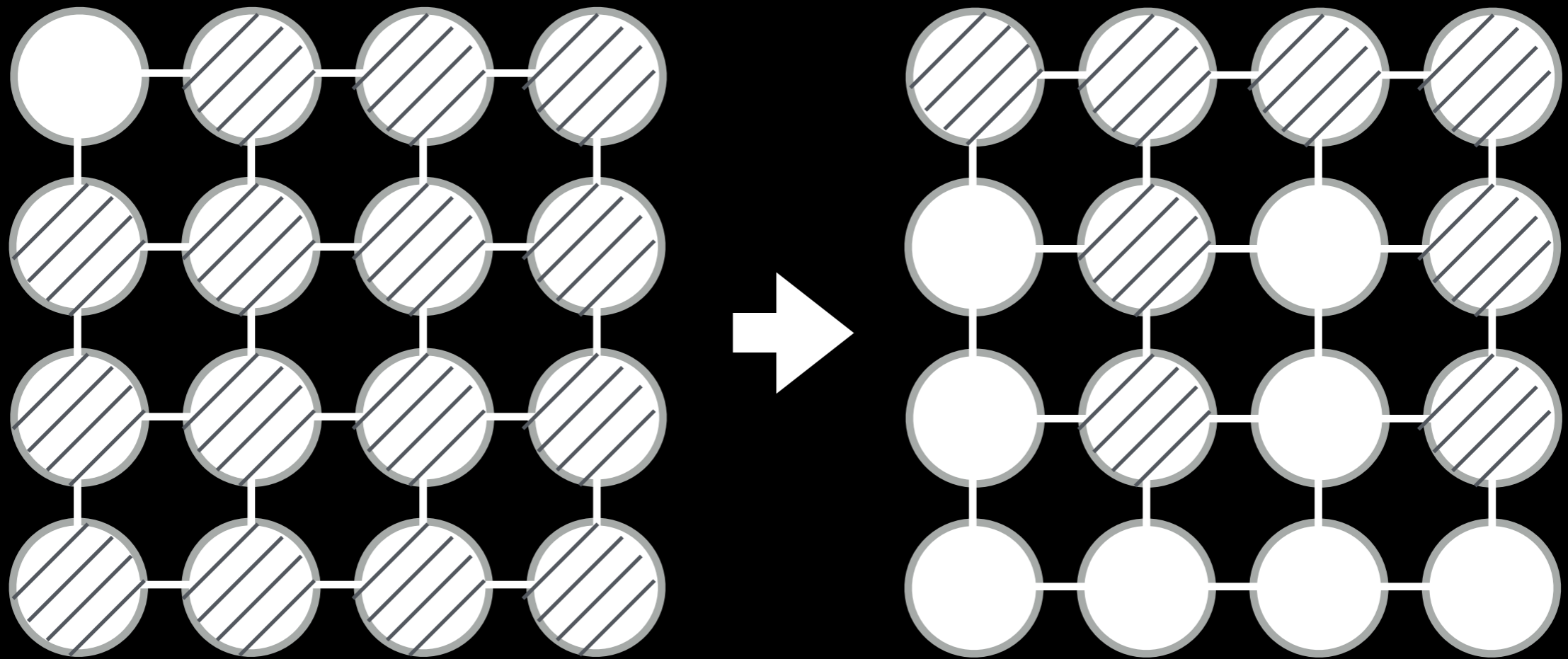


# Block ICM



*decode optimally*

# Block ICM



*decode optimally too*

# Other block methods

- Many methods have this 1-variable,  $>1$ -variables generalization

*Mark will cover this next Monday* ↘

- **Inference:** mean field updates the marginal of 1 variable at a time — we can update the marginals of  $>1$  variables at a time

- **Sampling:** Gibbs sampling samples 1 variable at a time — we can sample a block of  $>1$  variables at a time ↙

*Jason will cover this tomorrow*

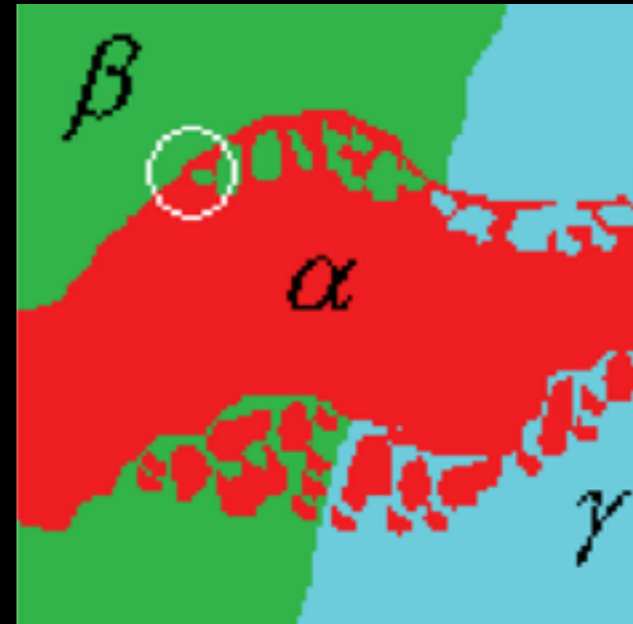
# Alpha-beta swap & alpha-expansion

# An overview

original  
labelling



ICM



alpha-beta  
swap

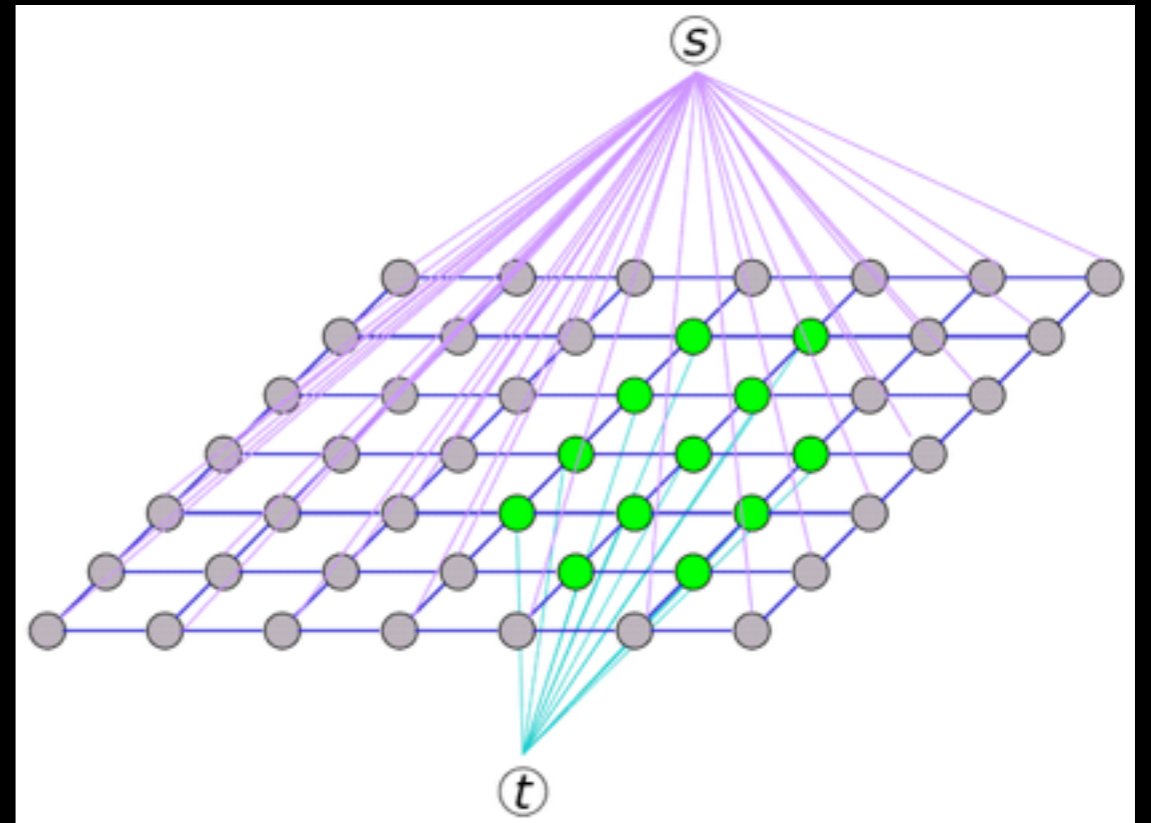


alpha-  
expansion



# Remember graph cuts

- Assume a binary label set (e.g. black and white)
- Connect nodes to “source” and “sink”
- If the submodular property is satisfied ( $\theta_{01} + \theta_{10} > \theta_{00} + \theta_{11}$ ) then we can decode this exactly solving a max-flow problem
- Problem: most images are not binary



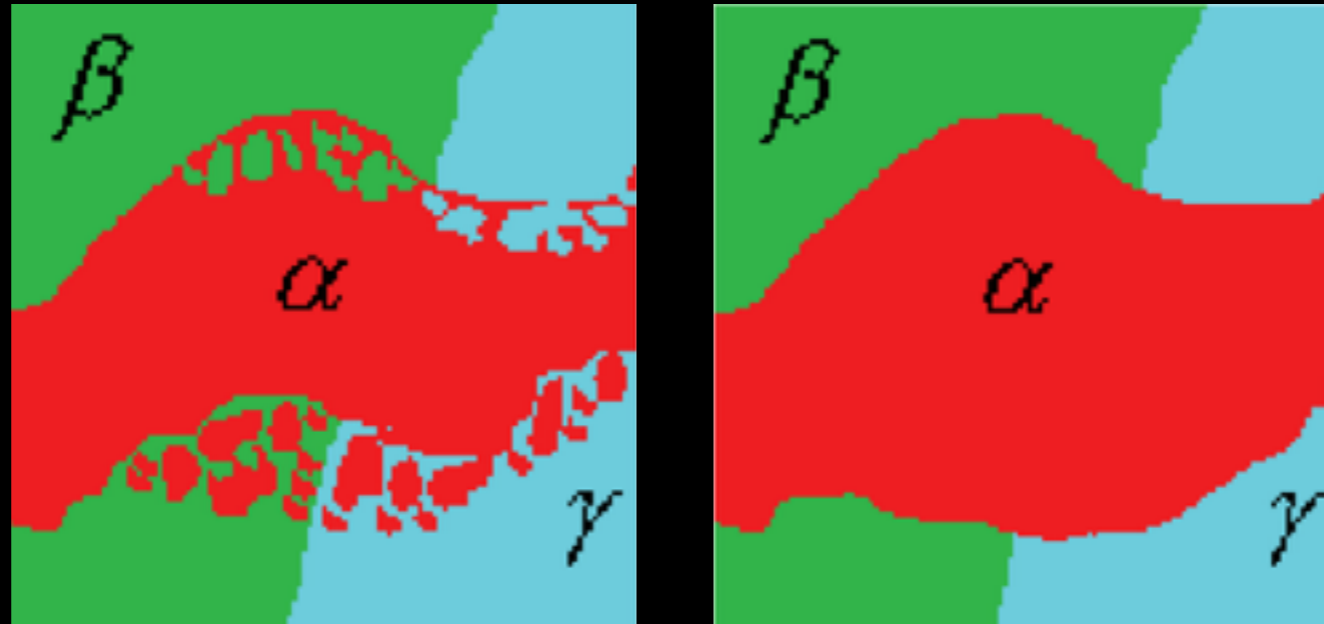


# Alpha-beta swap



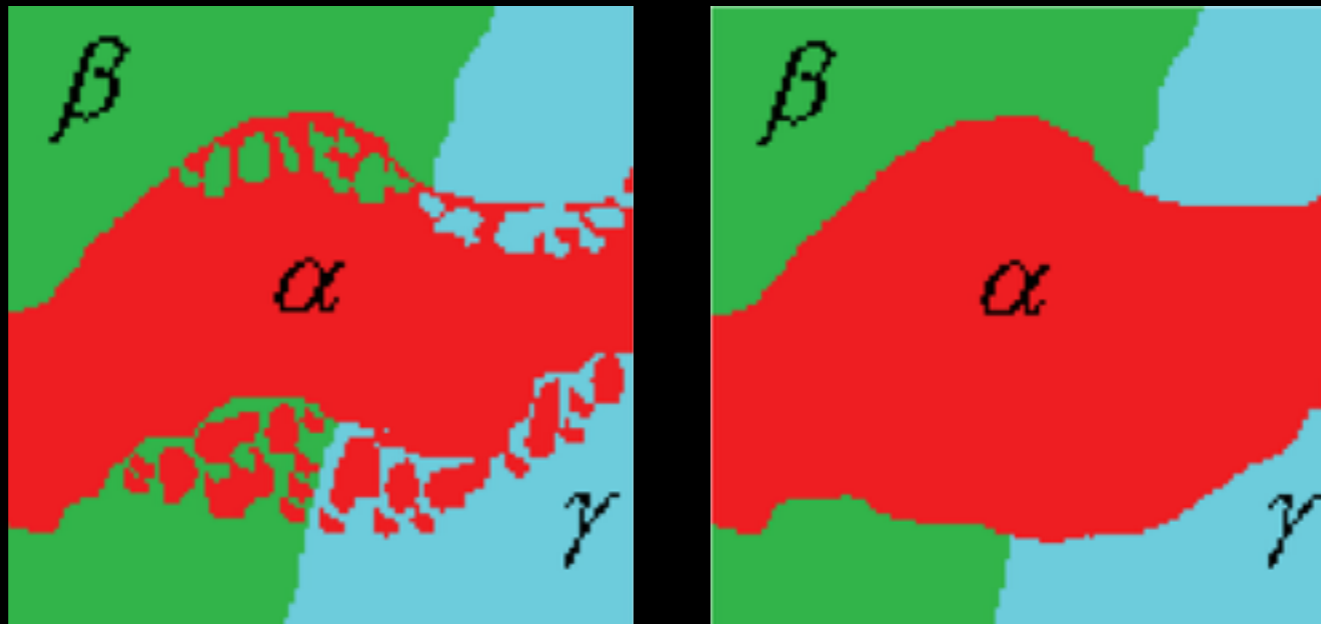
- All pixels not labelled alpha or beta stay fixed
- Do a graph cut on alpha and beta
- Some alpha nodes become beta and vice-versa

# Alpha-expansion



- All pixels not alpha may change to alpha
- Some pixels become alpha

# Alpha-expansion



- The required constraints are stronger than those for beta-swap:  $\theta(\alpha, \alpha) + \theta(\beta, \gamma) < \theta(\alpha, \gamma) + \theta(\beta, \alpha)$  for any alpha, beta and gamma triplet

# Performance on the Tsukuba image

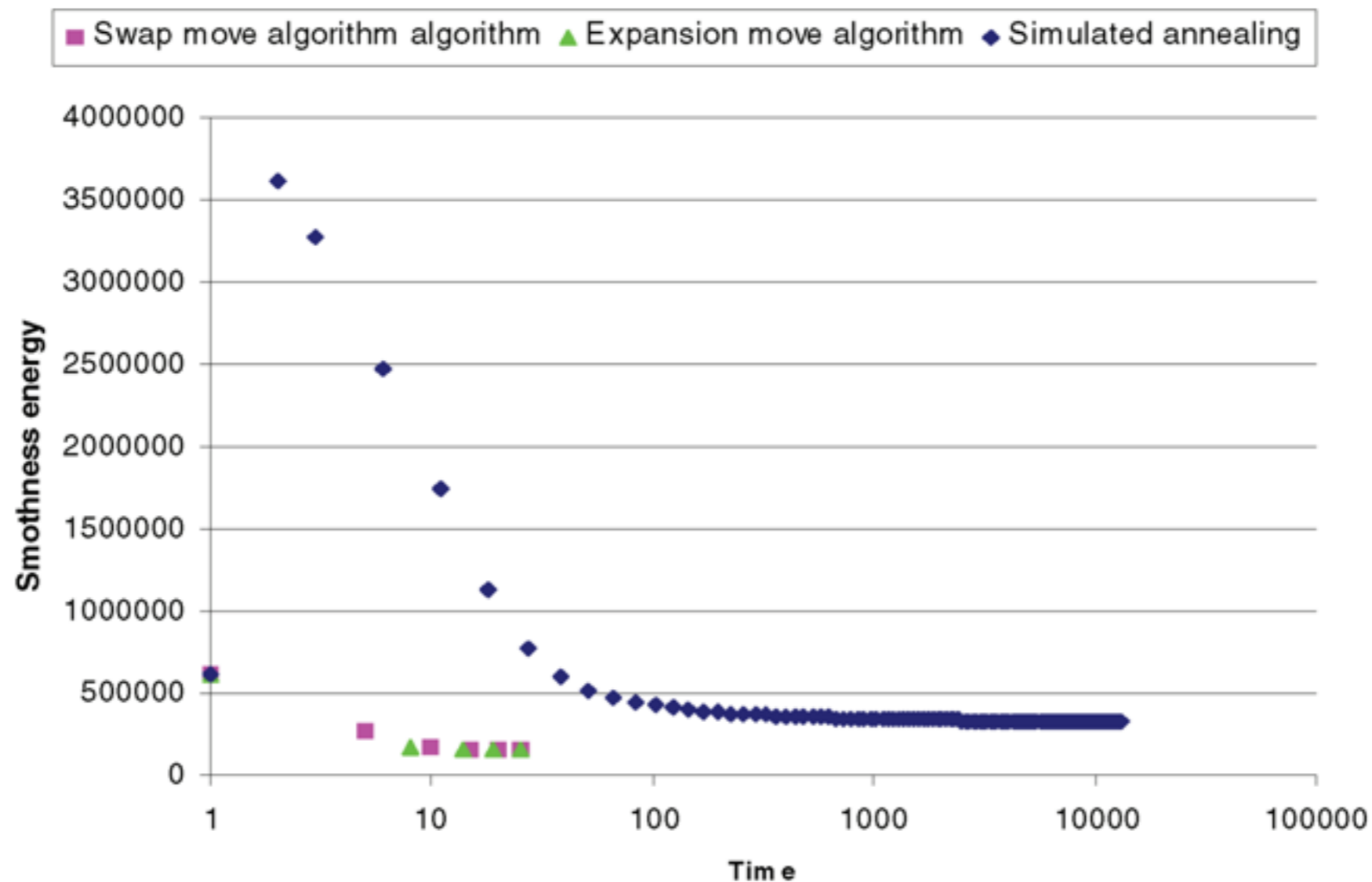
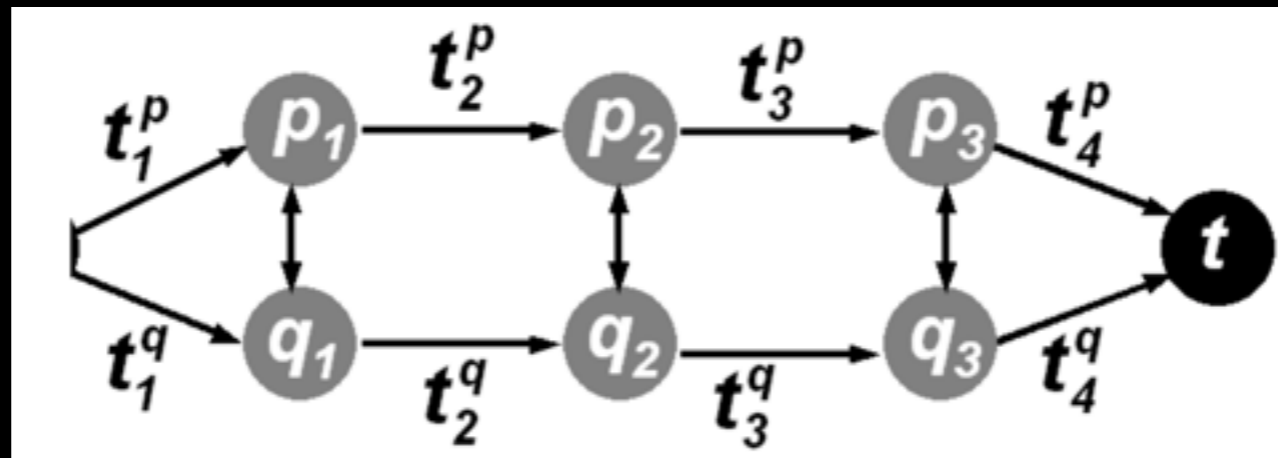


Fig. 11. Energy versus time (in seconds) of expansion, swap, and simulated annealing algorithms for the problem in Fig. 10a. The starting energy is the same for all algorithms.

# Exact multi-label optimization

- There is *one* case when multi-label optimization is possible
- We have to assume that the energy is

$$E(f) = \sum_{p \in \mathcal{P}} D_p f_p + \sum_{(p,q) \in \mathcal{N}} \lambda_{pq} |f_p - f_q|$$



- If the minimum cut severs edge  $t^p_i$ , assign label  $i$  to  $p$

# Cool applications

- Graphcut textures (SIGGRAPH 03): <https://www.youtube.com/watch?v=Ya6BshBH6G4>
- Grabcut demo (SIGGRAPH 04) using OpenCV: <https://youtu.be/kAwxLTDDAwU?t=19s>