

Approximate Bayesian Computation

Alireza Shafaei - April 2016



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$$\mathcal{P}(\mathcal{D}) = \int_{\Theta} \mathcal{P}(\mathcal{D}|\theta)\pi(\theta) d\theta$$



The Problem - A Review

- Previously we looked at the general problem of handling **high-dimensional integrals** and **unnormalized probability** functions.

$$\mathcal{P}(x) = \frac{1}{Z} p^*(x)$$



The Problem - A Review

- Rejection Sampling

- Given $p^*(x), q(x), M$ s.t. $\frac{p^*(x)}{q(x)} \leq M \forall x.$
- $x \sim q(x)$
- Accept x with probability

$$\frac{p^*(x)}{M \cdot q(x)}$$



The Problem - A Review

- Importance Sampling

$$\int_x f(x)p(x) dx$$



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$$\int_x f(x)p(x) dx = \frac{\int_x f(x)p^*(x) dx}{\int_x p^*(x) dx} = \frac{\int_x f(x)\frac{p^*(x)}{q(x)}q(x) dx}{\int_x \frac{p^*(x)}{q(x)}q(x) dx}$$



The Problem - A Review

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$$\int_x f(x)p(x) dx = \frac{\int_x f(x)p^*(x) dx}{\int_x p^*(x) dx} = \frac{\int_x f(x) \frac{p^*(x)}{q(x)} q(x) dx}{\int_x \frac{p^*(x)}{q(x)} q(x) dx}$$

$$\int_x f(x)p(x) dx \approx \frac{\sum_{l=1}^L f(x_l) \frac{p^*(x_l)}{q(x_l)}}{\sum_{l=1}^L \frac{p^*(x_l)}{q(x_l)}}$$



The Problem - A Review

- Markov chain Monte Carlo



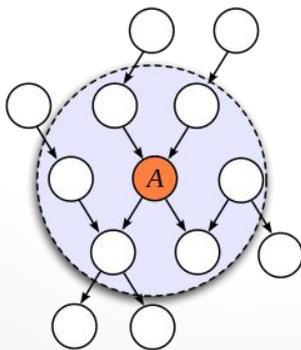
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- Markov chain Monte Carlo
- Use a transition $q(\theta^{t+1} | \theta^t)$ to move in the space.



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 - Reversible Jump MCMC (non-parametric)



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- What if we can't calculate $\mathcal{P}(\mathcal{D}|\theta)$?



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- Given a parameter θ you can simulate the execution.



The Problem

- Apparently applies to a lot of problems in biology.
- Given a parameter θ you can simulate the execution.
- $\mathcal{P}(\mathcal{D}|\theta)$ Could be intractable or simply no mathematical derivation of it exists.



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1. Draw $\theta \sim \pi(\theta)$



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3. Accept if $\rho(\mathcal{D}, \tilde{\mathcal{D}}) < \epsilon$



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- $\epsilon \rightarrow \infty \Rightarrow \theta \sim \pi(\theta)$
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Discussion

- Randomly sampling θ from the prior each time is ‘too wasteful’.
 - We want to explore the space to accept more often.



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 - We want to explore the space to accept more often.
 - Sampling from the prior does not incorporate current observations.
- How do we choose $\rho(\cdot, \cdot)$, $\mathcal{S}(\cdot)$, ϵ ?



Approximate MCMC

1. Propose $\theta' \sim Q(\theta'|\theta)$



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Approximate MCMC

1. Propose $\theta' \sim Q(\theta'|\theta)$
2. Simulate $\tilde{\mathcal{D}} \sim \mathcal{P}(\cdot|\theta')$
3. If $\rho(\mathcal{S}(\mathcal{D}), \mathcal{S}(\tilde{\mathcal{D}})) < \epsilon$
 - a. Accept θ' with probability

$$\min\left(1, \frac{\pi(\theta')Q(\theta|\theta')}{\pi(\theta)Q(\theta'|\theta)}\right)$$



Approximate Gibbs

- Let's assume $\theta = (\theta_1, \theta_2)$
 - $\mathcal{P}(\theta_1 | \mathcal{D}, \theta_2)$ is known.
 - $\mathcal{P}(\theta_2 | \mathcal{D}, \theta_1)$ is unknown.



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1. $\theta_1^{t+1} \sim \mathcal{P}(\theta_1 | \mathcal{D}, \theta_2)$



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 2. $\theta_2^* \sim \pi(\theta_2)$



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1. $\theta_1^{t+1} \sim \mathcal{P}(\theta_1 | \mathcal{D}, \theta_2)$
 2. $\theta_2^* \sim \pi(\theta_2)$
 - $\tilde{\mathcal{D}} \sim \mathcal{P}(\cdot | \theta_1^{t+1}, \theta_2^*)$



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 - $\mathcal{P}(\theta_1 | \mathcal{D}, \theta_2)$ is known.
 - $\mathcal{P}(\theta_2 | \mathcal{D}, \theta_1)$ is unknown.
- 1. $\theta_1^{t+1} \sim \mathcal{P}(\theta_1 | \mathcal{D}, \theta_2)$
- 2. $\theta_2^* \sim \pi(\theta_2)$
 - $\tilde{\mathcal{D}} \sim \mathcal{P}(\cdot | \theta_1^{t+1}, \theta_2^*)$
 - $\rho(\mathcal{S}(\mathcal{D}), \mathcal{S}(\tilde{\mathcal{D}})) < \epsilon \Rightarrow \theta_2^{t+1} = \theta_2^*$
 - else go to 2.



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Pros

- Likelihood is not needed.
- Easy to implement and parallelize.

Cons

- Lot's of tuning.
- For complex problems, sampling from the prior is frustrating because it does not incorporate the evidence.
- How good is our approximation?



Thank you!



References

1. Wilkinson, Richard, and Simon Tavaré. "Approximate Bayesian Computation: a simulation based approach to inference."
2. https://en.wikipedia.org/wiki/Gibbs_sampling
3. Barber, David. Bayesian reasoning and machine learning. Cambridge University Press, 2012.
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