### Model-Based Algorithm Configuration

#### Guest lecture in CPSC 536H - Empirical Algorithmics

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#### Most algorithms have parameters

- Decisions that are left open during algorithm design
  - numerical parameters (e.g., real-valued thresholds)
  - categorical parameters (e.g., which heuristic to use)

### **Motivation 1: Algorithm Configuration**

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### Automated Approaches for Parameter Optimization

- Eliminate most tedious part of algorithm design and end use
- Can generate custom algorithms for different problem types
- Save development time & improve performance

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Use model for algorithm configuration

1. Predictive Models of Algorithm Performance

2. Sequential Model-Based Optimization

3. Summary

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### Models of algorithm performance: basics

Data: algorithm performance in previous algorithm runs

- Parameter settings  $oldsymbol{ heta}_1,\ldots,oldsymbol{ heta}_n$ ,  $oldsymbol{ heta}_i\in oldsymbol{\Theta}$
- ▶ Observed algorithm performances  $y_1, \ldots, y_n, y_i \in \mathbb{R}$
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#### Performance prediction for new algorithm run

- Given a new configuration  $\theta_{i+1}$
- Predict performance as  $f(\theta_{i+1})$

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Typical types of models used

- Linear regression
- Gaussian process (GP) regression
- Regression trees
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### Requirements in the context of algorithm configuration

- Handle many data points
- Handle mixed continuous/discrete parameters
- Quantify uncertainty of predictions

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### E.g. expected improvement

- $\mathbb{E}_{cost(\theta)}[max(0, cost(incumbent) cost(\theta))]$
- Closed form expression for Gaussian predictive distribution
- ► Also for Gaussian predictive distribution in log space



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- Repeat 1-3 until time is up





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#### repeat

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return  $\theta_{inc}$ 

### Sequential Model-Based Optimization: roots

### Experimental design literature in statistics

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  - Popularized the approach
- Sequential Kriging Optimization [Huang et al., 2006]
  - Also allowed noise

# **Sequential Model-Based Optimization:** adaptation for optimizing algorithms

#### Sequential Parameter Optimization (SPO)

[Bartz-Beielstein et al., '05-present]

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- Studied SPO components
- How many runs to perform for each heta
  - "Intensification mechanism" inspired by FocusedILS

 $\rightarrow$  : SPO<sup>+</sup>

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- More robust completely automated tool [Hutter et al, GECCO-09]
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 $\rightarrow$  : SPO<sup>+</sup>

- ► Time-Bounded SPO [Hutter et al, LION-10]
  - Reduced computational overheads due to the model
  - Removed need for costly initial design

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- Include instance features in the model
- Predict marginal performance across the training instances

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- Predict marginal performance across the training instances
- → ActiveConfigurator 1.0

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Optimizing algorithms for single instances

- Outperforms FocusedILS in most cases
- Is more robust than FocusedILS
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### Optimizing algorithms for single instances

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- Is more robust than FocusedILS
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### Optimizing algorithms for multiple instances

- Performed somewhat better than FocusedILS
- But need to perform more comparisons

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- Capping (as in ParamILS)
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  - Tricky to exploit in learning

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  - Tricky for learning: if *i*-th run capped  $\rightarrow y_i$  is only lower bound
- Conditional parameters
  - Tricky to exploit in learning
- Use of model for
  - Active selection of instances
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### Model-free vs model-based

Advantages of model-free approach

- Conceptual simplicity
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- Simple to integrate conditional parameters
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- Implementation robustness (less things can break)
- Advantages of model-based approach
  - Can interpolate & extrapolate
  - Can handle continuous parameters
  - Enable future, more sophisticated techniques
    - Active selection of most informative instance
    - Active selection of cutoff time
    - Per-instance approaches

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# Summary

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### Existing Extensions

- Handle noise better: intensification mechanism
- Keep computational overhead at bay
- Outperform ParamILS for single instances