

$$\begin{aligned}
 1. \quad P &= 4i + 4j \\
 &= -3A_i - A_j \\
 &= \frac{B_i}{4} + 3B_j \\
 &= C_i - C_j
 \end{aligned}$$

$$2. \quad \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$3. \quad \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0.2 & 0 & 0 \\ 0 & 0 & 0.5 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

4. Two possible answers:

$$\begin{aligned}
 \textcircled{1} \quad \begin{bmatrix} 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & -2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} &= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \\
 &= T_y(-2) R_z(90^\circ)
 \end{aligned}$$

local coordinate system (left to right):

1. translate 2 units along y axis in negative direction
2. rotate 90° CCW around z -axis of modified coordinate frame.

$$\begin{aligned}
 \text{OR: } \textcircled{2} \quad \begin{bmatrix} 0 & -1 & 0 & 0 \\ 1 & 0 & 0 & -2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} &= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \\
 &= R_z(90^\circ) T_x(-2)
 \end{aligned}$$

local coordinates:

1. rotate 90° CCW around z -axis
2. translate -2 units along modified x -axis.

①

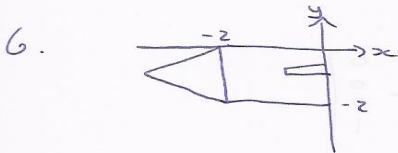
5. ① global coordinate system (right to left)

1. rotate 90° ccw around z -axis

2. translate by -2 along original y -axis.

or: ② 1. translate -2 along x -axis

2. rotate 90° ccw around original z -axis.



7. $P' = M_1 M_2 M_3 P$

$$= T(P_F) R_y(90) T(-P_F)$$

$$P_F = (4, -1, 2, 1)$$

$$M_1 = \begin{bmatrix} 1 & 0 & 0 & 4 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$M_2 = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$M_3 = \begin{bmatrix} 1 & 0 & 0 & -4 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

8. g | Translate $(4, -1, 2)$;
 g | Rotate $(90, 0, 1, 0)$;
 g | Translate $(-4, 1, -2)$;

9. $(4, 5, 3, 1)$

10. Shear by 2 in x , then 3 in y uses matrix A

$$A = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 3 & 1 \end{bmatrix}$$

Shear simultaneously uses matrix B

$$B = \begin{bmatrix} 1 & 2 \\ 3 & 1 \end{bmatrix}$$

and $A \neq B \therefore$ they are not the same operation.

②