CPSC 314, Written Homework 1: Transformations

Out: Mon 22 Jan 2007 Due: Fri 2 Feb 2007 3pm Value: 3% of final grade Total Points: 100

1. (18 pts) The point coordinate P can be expressed as P = 1*i + 2*j, where i and j are basis vectors of unit length along the x and y axes, respectively. Describe the point P in terms of the 3 other coordinate systems given below.



- 2. (5 pts) Write down the 4x4 matrix for rotating an object counterclockwise by 270 degrees around the Y axis.
- 3. (5 pts) Write down the 4x4 matrix for shearing an object by 2 in y and 3 in Z.
- 4. (10 pts) Decompose this matrix M into two matrices A and B such that p' = Mp = ABp. Write down A and B.

Γ	1	0	0	3
	0	2	0	2
	0	0	1	1
	0	0	0	1

- 5. (5 pts) Describe in words what M does, interpreting it as an operation in local coordinates that changes the coordinate frame. Be specific about the order of operations.
- 6. (5 pts) Describe in words what M above does, interpreting it as an operation in a fixed global coordinate system coordinates that moves the object. Be specific about the order of operations.
- 7. (5 pts) Give the OpenGL commands required to encode M. You may assume the matrix stack has been initialized with glldentity().
- 8. (6 pts) Homogenize the point (8,15,9,5).
- 9. (15 pts) Given a triangle T with vertices a = (1, 1, 1, 1), b = (2, 2, 1, 1), c = (0, 0, -1, 1) and the transformation S = (1, 1, 1, 1), b = (2, 2, 1, 1), c = (0, 0, -1, 1)

2.828	0	.707	1
0	5	0	0
707	1	.707	0
0	0	0	1

Compute the vertices of T after applying transformation S to it.

10. (10 pts) Compute the normal of T before and after applying transformation S to it.

11. (16 pts) Give the 4x4 matrices that result from the OpenGL commands at the four lines A, B, C, and D below.

```
glLoadIdentity();
glRotate(90, 0,0,1);
A
glTranslate(2,3,0);
B
glPushMatrix();
glTranslate(1,1,0);
glScale(1,.5,1);
C
glPopMatrix();
glScale(2,1,1);
D
```