

Uncertainty: Wrap up & Decision Theory: Intro

Alan Mackworth

UBC CS 322 - Decision Theory 1

March 25, 2013

Textbook §6.4.1 & §9.2

Announcements (1)

- Teaching Evaluations are online
 - You should have received a message about them
 - Secure, confidential, mobile access
- **Your feedback is important!**
 - Allows us to assess and improve the course material
 - I use it to assess and improve my teaching methods
 - The department as a whole uses it to shape the curriculum
 - Teaching evaluation results are important for instructors
 - Appointment, reappointment, tenure, promotion and merit, salary
 - UBC takes them very seriously (now)
 - Evaluations close at 11:59PM on April 9, 2013.
 - Before exam, but instructors can't see results until *after* we submit grades
 - Please do it!
- Take a few minutes and visit <https://eval.olt.ubc.ca/science>


Announcements (2)

- Assignment 4 due Wednesday, April 3rd, 1pm
- Final exam
 - Thursday, April 18th, 8:30am – 11am in PHRM 1101
 - Same general format as midterm (~60% short questions)
 - *List of short questions is now on Connect*
 - *Practice final is now available in Connect*
 - More emphasis on material after midterm
 - How to study?
 - Practice exercises, assignments, short questions, lecture notes, text, problems in text, learning goals ...
 - Use TA and my office hours (extra office hours TBA if needed)
 - Review sessions: last class plus more TBA if needed
 - *Submit topics you want reviewed in response to message on Connect*

Hints for Assignment 4

- Question 4 (Bayesian networks)
 - “correctly represent the situation described above” means “do not make any independence assumptions that aren’t true”
 - “(Hint: remember that Bayes nets do not necessarily encode causality.”
 - Another hint:
 - Step 1: identify the causal network
 - Step 2: for each network, check if it entails (conditional or marginal) independencies the causal network does not entail. If so, it’s incorrect
 - Failing to entail some (or all) independencies does not make a network incorrect (only computationally suboptimal)

Lecture Overview

- 
- Variable elimination: recap and some more details
 - Variable elimination: pruning irrelevant variables
 - Summary of Reasoning under Uncertainty
 - Decision Theory
 - Intro
 - Time-permitting: Single-Stage Decision Problems

Recap: Factors and Operations on them

- A factor is a function from a tuple of random variables to the real numbers \mathbb{R}
- Operation 1: assigning a variable in a factor
 - E.g., assign $X=t$

Factor of Y,X,Z

X	Y	Z	$f_1(X,Y,Z)$
t	t	t	0.1
t	t	f	0.9
t	f	t	0.2
t	f	f	0.8
f	t	t	0.4
f	t	f	0.6
f	f	t	0.3
f	f	f	0.7

$$f_1(X,Y,Z)_{X=t} = f_2(Y,Z)$$



Y	Z	$f_2(Y,Z)$
t	t	0.1
t	f	0.9
f	t	0.2
f	f	0.8

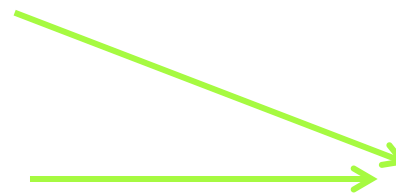
Factor of Y,Z

Recap: Factors and Operations on Them

- A factor is a function from a tuple of random variables to the real numbers \mathbb{R}
- Operation 1: assigning a variable in a factor
 - $f_2(Y,Z) = f_1(X,Y,Z)_{X=t}$
- Operation 2: marginalize out a variable from a factor

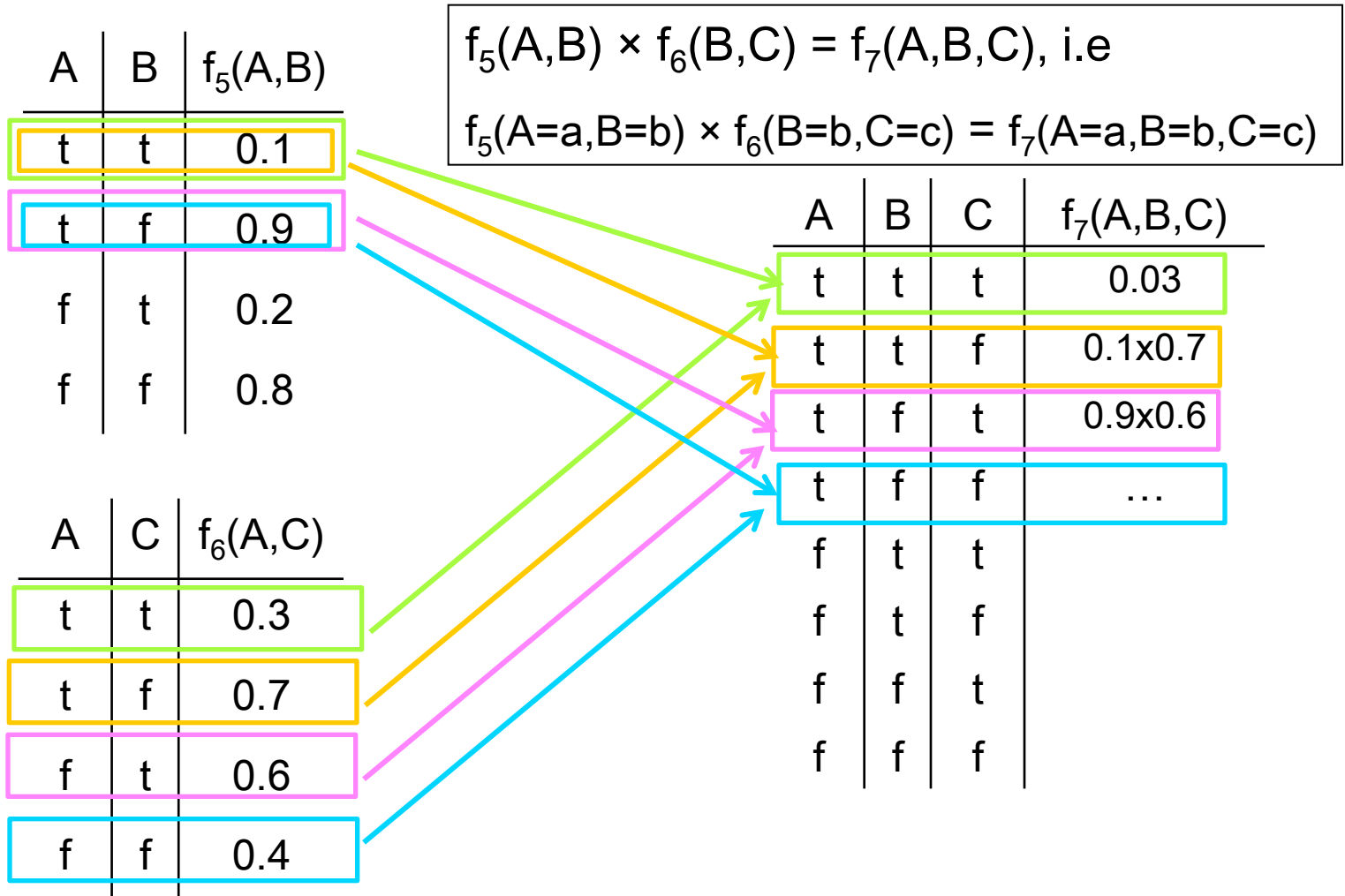
B	A	C	$f_3(A,B,C)$
t	t	t	0.03
t	t	f	0.07
f	t	t	0.54
f	t	f	0.36
t	f	t	0.06
t	f	f	0.14
f	f	t	0.48
f	f	f	0.32

$$\sum_B f_3(A,B,C) = f_4(A,C)$$



A	C	$f_4(A,C)$
t	t	0.57
t	f	0.43
f	t	0.54
f	f	0.46

Recap: Operation 3: multiplying factors



Recap: Factors and Operations on Them

- A factor is a function from a tuple of random variables to the real numbers \mathbb{R}
- Operation 1: assigning a variable in a factor
 - E.g., $f_2(Y,Z) = f_1(X,Y,Z)_{X=t}$
- Operation 2: marginalize out a variable from a factor
 - E.g., $f_4(A,C) = \sum_B f_3(A,B,C)$
- Operation 3: multiply two factors
 - E.g. $f_7(A,B,C) = f_5(A,B) \times f_6(B,C)$
 - That means, $f_7(A=a,B=b,C=c) = f_5(A=a,B=b) \times f_6(B=b,C=c)$
- If we assign variable $A=a$ in factor $f_7(A,B)$, what is the correct form for the resulting factor?

$f(A)$

$f(B)$

$f(A,B)$

A number

Recap: Factors and Operations on Them

- A factor is a function from a tuple of random variables to the real numbers \mathbb{R}
- Operation 1: assigning a variable in a factor
 - E.g., $f_2(Y,Z) = f_1(X,Y,Z)_{X=t}$
- Operation 2: marginalize out a variable from a factor
 - E.g., $f_4(A,C) = \sum_B f_3(A,B,C)$
- Operation 3: multiply two factors
 - E.g. $f_7(A,B,C) = f_5(A,B) \times f_6(B,C)$
 - That means, $f_7(A=a,B=b,C=c) = f_5(A=a,B=b) \times f_6(B=b,C=c)$
- If we assign variable $A=a$ in factor $f_7(A,B)$, what is the correct form for the resulting factor?
 - $f(B)$.
When we assign variable A we remove it from the factor's domain

Recap: Factors and Operations on Them

- A factor is a function from a tuple of random variables to the real numbers \mathbb{R}
- Operation 1: assigning a variable in a factor
 - E.g., $f_2(Y,Z) = f_1(X,Y,Z)_{X=t}$
- Operation 2: marginalize out a variable from a factor
 - E.g., $f_4(A,C) = \sum_B f_3(A,B,C)$
- Operation 3: multiply two factors
 - E.g. $f_7(A,B,C) = f_5(A,B) \times f_6(B,C)$
 - That means, $f_7(A=a,B=b,C=c) = f_5(A=a,B=b) \times f_6(B=b,C=c)$
- If we marginalize variable A out from factor $f_7(A,B)$, what is the correct form for the resulting factor?

$f(A)$

$f(B)$

$f(A,B)$

A number

Recap: Factors and Operations on Them

- A factor is a function from a tuple of random variables to the real numbers \mathbb{R}
- Operation 1: assigning a variable in a factor
 - E.g., $f_2(Y,Z) = f_1(X,Y,Z)_{X=t}$
- Operation 2: marginalize out a variable from a factor
 - E.g., $f_4(A,C) = \sum_B f_3(A,B,C)$
- Operation 3: multiply two factors
 - E.g. $f_7(A,B,C) = f_5(A,B) \times f_6(B,C)$
 - That means, $f_7(A=a,B=b,C=c) = f_5(A=a,B=b) \times f_6(B=b,C=c)$
- If we assign variable $A=a$ in factor $f_7(A,B)$, what is the correct form for the resulting factor?
 - $f(B)$.
When we marginalize out variable A we remove it from the factor's domain

Recap: Factors and Operations on Them

- A factor is a function from a tuple of random variables to the real numbers \mathbb{R}
- Operation 1: assigning a variable in a factor
 - E.g., $f_2(Y,Z) = f_1(X,Y,Z)_{X=t}$
- Operation 2: marginalize out a variable from a factor
 - E.g., $f_4(A,C) = \sum_B f_3(A,B,C)$
- Operation 3: multiply two factors
 - E.g. $f_7(A,B,C) = f_5(A,B) \times f_6(B,C)$
 - That means, $f_7(A=a,B=b,C=c) = f_5(A=a,B=b) \times f_6(B=b,C=c)$
- If we multiply factors $f_4(X,Y)$ and $f_6(Z,Y)$, what is the correct form for the resulting factor?

$f(X,Z)$

$f(X)$

$f(X,Y)$

$f(X,Y,Z)$

Recap: Factors and Operations on Them

- A factor is a function from a tuple of random variables to the real numbers \mathbb{R}
- Operation 1: assigning a variable in a factor
 - E.g., $f_2(Y,Z) = f_1(X,Y,Z)_{X=t}$
- Operation 2: marginalize out a variable from a factor
 - E.g., $f_4(A,C) = \sum_B f_3(A,B,C)$
- Operation 3: multiply two factors
 - E.g. $f_7(A,B,C) = f_5(A,B) \times f_6(B,C)$
 - That means, $f_7(A=a,B=b,C=c) = f_5(A=a,B=b) \times f_6(B=b,C=c)$
- If we multiply factors $f_4(X,Y)$ and $f_6(Z,Y)$, what is the correct form for the resulting factor?
 - $f(X,Y,Z)$
 - When multiplying factors, the resulting factor's domain is the union of the multiplicands' domains

Recap: Factors and Operations on Them

- A factor is a function from a tuple of random variables to the real numbers \mathbb{R}
- Operation 1: assigning a variable in a factor
 - E.g., $f_2(Y,Z) = f_1(X,Y,Z)_{X=t}$
- Operation 2: marginalize out a variable from a factor
 - E.g., $f_4(A,C) = \sum_B f_3(A,B,C)$
- Operation 3: multiply two factors
 - E.g. $f_7(A,B,C) = f_5(A,B) \times f_6(B,C)$
 - That means, $f_7(A=a,B=b,C=c) = f_5(A=a,B=b) \times f_6(B=b,C=c)$
- What is the correct form for $\sum_B f_5(A,B) \times f_6(B,C)$
 - As usual, product before sum: $\sum_B (f_5(A,B) \times f_6(B,C))$

$f(A,B,C)$

$f(B)$

$f(A,C)$


$f(B,C)$

Recap: Factors and Operations on Them

- A factor is a function from a tuple of random variables to the real numbers \mathbb{R}
- Operation 1: assigning a variable in a factor
 - E.g., $f_2(Y,Z) = f_1(X,Y,Z)_{X=t}$
- Operation 2: marginalize out a variable from a factor
 - E.g., $f_4(A,C) = \sum_B f_3(A,B,C)$
- Operation 3: multiply two factors
 - E.g. $f_7(A,B,C) = f_5(A,B) \times f_6(B,C)$
 - That means, $f_7(A=a,B=b,C=c) = f_5(A=a,B=b) \times f_6(B=b,C=c)$
- What is the correct form for $\sum_B f_5(A,B) \times f_6(B,C)$
 - As usual, product before sum: $\sum_B (f_5(A,B) \times f_6(B,C))$
 - Result of multiplication: $f(A,B,C)$. Then marginalize out B: $f'(A,C)$

Recap: Factors and Operations on Them

- A factor is a function from a tuple of random variables to the real numbers \mathbb{R}
- Operation 1: assigning a variable in a factor
 - E.g., $f_2(Y,Z) = f_1(X,Y,Z)_{X=t}$
- Operation 2: marginalize out a variable from a factor
 - E.g., $f_4(A,C) = \sum_B f_3(A,B,C)$
- Operation 3: multiply two factors
 - E.g. $f_7(A,B,C) = f_5(A,B) \times f_6(B,C)$
 - That means, $f_7(A=a,B=b,C=c) = f_5(A=a,B=b) \times f_6(B=b,C=c)$
- Operation 4: normalize the factor
 - Divide each entry by the sum of the entries. The result will sum to 1.

A	$f_8(A)$		A	$f_9(A)$
t	0.4		t	$0.4/(0.4+0.1) = 0.8$
f	0.1		f	$0.1/(0.4+0.1) = 0.2$

Recap: General Inference in Bayesian Networks

Given

- A Bayesian Network BN, and
- Observations of a subset of its variables E : $E=e$
- A subset of its variables Y that is queried

Compute the conditional probability $P(Y=y|E=e)$

Definition of conditional probability

Marginalization over Y :
 $P(E=e) = \sum_{y' \in \text{dom}(Y)} P(E=e, Y=y')$

$$P(Y = y | E = e) = \frac{P(Y = y, E = e)}{P(E = e)} = \frac{P(Y = y, E = e)}{\sum_{y' \in \text{dom}(Y)} P(Y = y', E = e)}$$

All we need to compute is the joint probability of the query variable(s) and the evidence!

Recap: Key Idea of Variable Elimination

- To sum out a variable Z from a product $f_1 \times \dots \times f_k$ of factors:
 - Partition the factors into
 - those that don't contain Z say $f_1 \times \dots \times f_i$
 - those that contain Z say $f_{i+1} \times \dots \times f_k$

- We know:

$$\sum_Z f_1 \times \dots \times f_k = f_1 \times \dots \times f_i \times \left(\sum_Z f_{i+1} \times \dots \times f_k \right)$$

New factor! Let's call it f'

- We thus have $\sum_Z f_1 \times \dots \times f_k = f_1 \times \dots \times f_i \times f'$
- Store f' explicitly, and discard $f_{i+1} \dots f_k$
- Now we've summed out Z

Recap: Variable Elimination (VE) in BNs

- The joint probability distribution of a Bayesian network is $P(X_1, \dots, X_n) = \prod_{i=1}^n P(X_i | \text{pa}(X_i))$
 - We make a factor f_i for each conditional probability table $P(X_i | \text{pa}(X_i))$
 - So we have $P(X_1, \dots, X_n) = \prod_{i=1}^n f_i$
- The **variable elimination algorithm** computes $P(Y | E_1=e_1, \dots, E_j=e_j)$ as follows:
 - **Assign** $E_1=e_1, \dots, E_j=e_j$
 - **Sum out** all non-query variables Z_1, \dots, Z_k , one at a time
 - To sum out Z_i :
 - Multiply factors containing it Z_i
 - Then marginalize out Z_i from the product
 - The order in which we sum out variables is called our **elimination ordering**
 - **Normalize** the final factor $f(Y)$.
 - The resulting factor is exactly $P(Y | E_1=e_1, \dots, E_j=e_j)$

VE_BN Algorithm

```
1: Procedure VE_BN(Vs,Ps,O,Q)
2:   Inputs
3:     Vs: set of variables
4:     Ps: set of factors representing the conditional probabilities
5:     O: set of observations of values on some of the variables
6:     Q: a query variable
7:   Output
8:     posterior distribution on Q
9:   Local
10:    Fs: a set of factors
11:     $F_s \leftarrow P_s$ 
12:    for each  $X \in V_s - \{Q\}$  using some elimination ordering do
13:      if (X is observed) then
14:        for each  $F \in F_s$  that involves X do
15:          set X in F to its observed value in O
16:          project F onto remaining variables
17:        else
18:           $R_s \leftarrow \{F \in F_s: F \text{ involves } X\}$ 
19:          let T be the product of the factors in  $R_s$ 
20:           $N \leftarrow \sum_X T$ 
21:           $F_s \leftarrow F_s \setminus R_s \cup \{N\}$ 
22:        let T be the product of the factors in  $R_s$ 
23:         $N \leftarrow \sum_Q T$ 
24:    return T/N
```

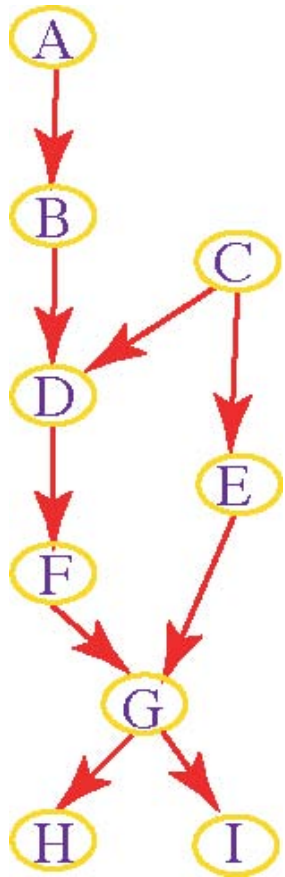
Figure 6.8: Variable elimination for belief networks (P&M, Section 6.4.1, p. 254)

Recap: VE example: compute $P(G|H=h_1)$

Step 1: construct a factor for each cond. probability

$P(G,H) =$

$$\sum_{A,B,C,D,E,F,I} f_0(A) f_1(B,A) f_2(C) f_3(D,B,C) f_4(E,C) f_5(F,D) f_6(G,F,E) f_7(H,G) f_8(I,G)$$

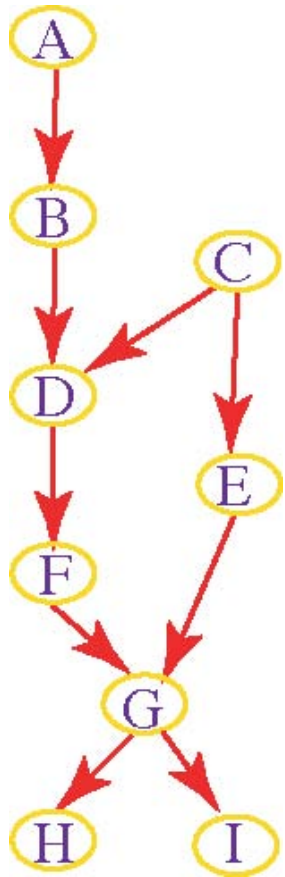


Recap: VE example: compute $P(G|H=h_1)$

Step 2: assign observed variables their observed value

$$P(G,H) =$$

$$\sum_{A,B,C,D,E,F,I} f_0(A) f_1(B,A) f_2(C) f_3(D,B,C) f_4(E,C) f_5(F,D) f_6(G,F,E) f_7(H,G) f_8(I,G)$$



Assigning the variable $H=h_1$:

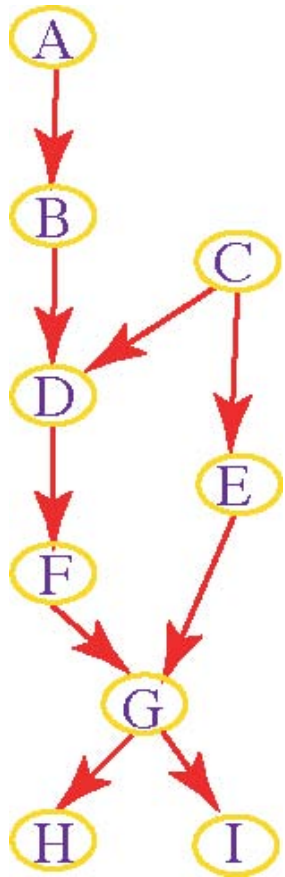
$$f_9(G) = f_7(H,G)_{H=h_1}$$

$$P(G,H=h_1) = \sum_{A,B,C,D,E,F,I} f_0(A) f_1(B,A) f_2(C) f_3(D,B,C) f_4(E,C) f_5(F,D) f_6(G,F,E) f_9(G) f_8(I,G)$$

Recap: VE example: compute $P(G|H=h_1)$

Step 4: sum out non- query variables (one at a time)

$$P(G, H=h_1) = \sum_{A,B,C,D,E,F,I} f_0(A) f_1(B,A) f_2(C) f_3(D,B,C) f_4(E,C) f_5(F,D) f_6(G,F,E) f_9(G) f_8(I,G)$$

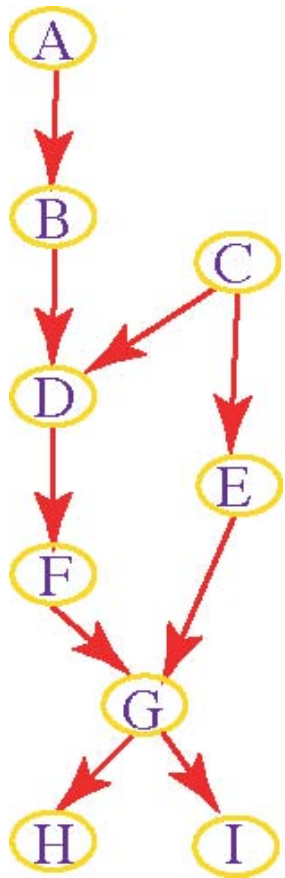


Elimination ordering: A, C, E, I, B, D, F

Recap: VE example: compute $P(G|H=h_1)$

Step 4: sum out non- query variables (one at a time)

$$\begin{aligned} P(G, H=h_1) &= \sum_{A,B,C,D,E,F,I} \underbrace{f_0(A) f_1(B,A)}_{\text{red line}} f_2(C) f_3(D,B,C) f_4(E,C) f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) \\ &= \sum_{B,C,D,E,F,I} f_2(C) f_3(D,B,C) f_4(E,C) f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) \overset{\text{red arrow}}{f_{10}(B)} \end{aligned}$$



Summing out variable A :

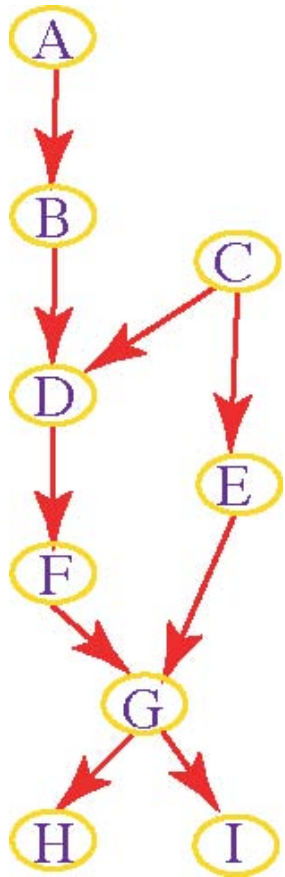
$$\sum_A f_0(A) f_1(B,A) = f_{10}(B)$$

Elimination ordering: A, C, E, I, B, D, F

Recap: VE example: compute $P(G|H=h_1)$

Step 4: sum out non- query variables (one at a time)

$$\begin{aligned} P(G, H=h_1) &= \sum_{A,B,C,D,E,F,I} f_0(A) f_1(B,A) f_2(C) f_3(D,B,C) f_4(E,C) f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) \\ &= \sum_{B,C,D,E,F,I} \underline{f_2(C) f_3(D,B,C) f_4(E,C)} f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) \\ &= \sum_{B,D,E,F,I} f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) \rightarrow f_{11}(B,D,E) \end{aligned}$$



Summing out variable C :

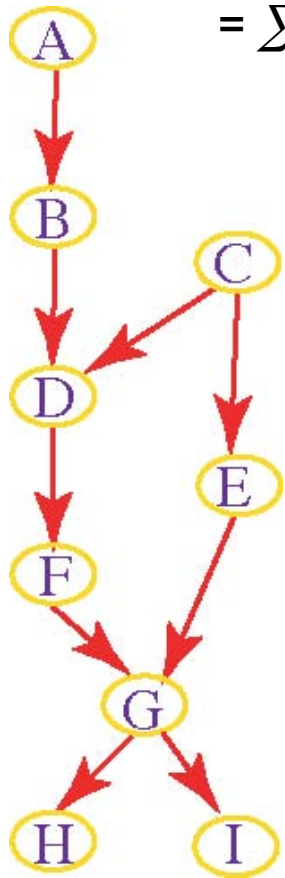
$$\sum_C f_2(C) f_3(D,B,C) f_4(E,C) = f_{11}(B,D,E)$$

Elimination ordering: A, C, E, I, B, D, F

Recap: VE example: compute $P(G|H=h_1)$

Step 4: sum out non- query variables (one at a time)

$$\begin{aligned} P(G, H=h_1) &= \sum_{A,B,C,D,E,F,I} f_0(A) f_1(B,A) f_2(C) f_3(D,B,C) f_4(E,C) f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) \\ &= \sum_{B,C,D,E,F,I} f_2(C) f_3(D,B,C) f_4(E,C) f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) \\ &= \sum_{B,D,E,F,I} f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) f_{11}(B,D,E) \\ &= \sum_{B,D,F,I} f_5(F, D) f_9(G) f_8(I,G) f_{10}(B) f_{12}(G,F,B,D) \end{aligned}$$



Summing out variable E :

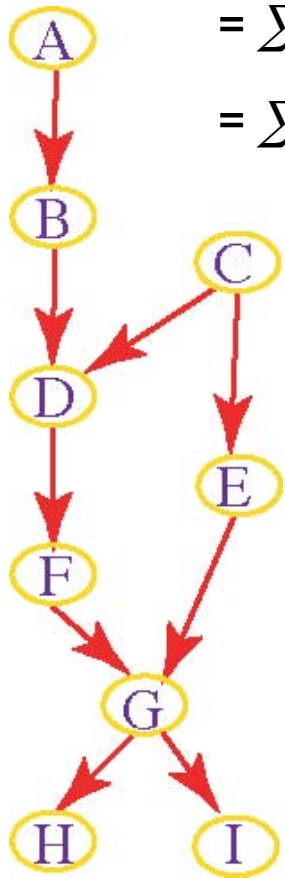
$$\sum_E f_6(G,F,E) f_{11}(B,D,E) = f_{12}(G,F,B,D)$$

Elimination ordering: A, C, E, I, B, D, F

Recap: VE example: compute $P(G|H=h_1)$

Step 4: sum out non- query variables (one at a time)

$$\begin{aligned}
 P(G, H=h_1) &= \sum_{A,B,C,D,E,F,I} f_0(A) f_1(B,A) f_2(C) f_3(D,B,C) f_4(E,C) f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) \\
 &= \sum_{B,C,D,E,F,I} f_2(C) f_3(D,B,C) f_4(E,C) f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) \\
 &= \sum_{B,D,E,F,I} f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) f_{11}(B,D,E) \\
 &= \sum_{B,D,F,I} f_5(F, D) f_9(G) f_8(I,G) f_{10}(B) f_{12}(G,F,B,D) \\
 &= \sum_{B,D,F} f_5(F, D) f_9(G) f_{10}(B) f_{12}(G,F,B,D) f_{13}(G)
 \end{aligned}$$

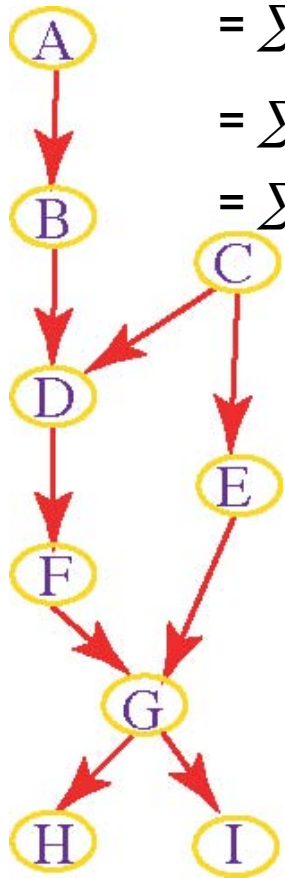


Elimination ordering: A, C, E, I, B, D, F

Recap: VE example: compute $P(G|H=h_1)$

Step 4: sum out non- query variables (one at a time)

$$\begin{aligned}
 P(G,H=h_1) &= \sum_{A,B,C,D,E,F,I} f_0(A) f_1(B,A) f_2(C) f_3(D,B,C) f_4(E,C) f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) \\
 &= \sum_{B,C,D,E,F,I} f_2(C) f_3(D,B,C) f_4(E,C) f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) \\
 &= \sum_{B,D,E,F,I} f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) f_{11}(B,D,E) \\
 &= \sum_{B,D,F,I} f_5(F, D) f_9(G) f_8(I,G) f_{10}(B) f_{12}(G,F,B,D) \\
 &= \sum_{B,D,F} f_5(F, D) f_9(G) f_{10}(B) f_{12}(G,F,B,D) f_{13}(G) \\
 &= \sum_{D,F} f_5(F, D) f_9(G) f_{11}(G,F) f_{12}(G) f_{14}(G,F,D)
 \end{aligned}$$

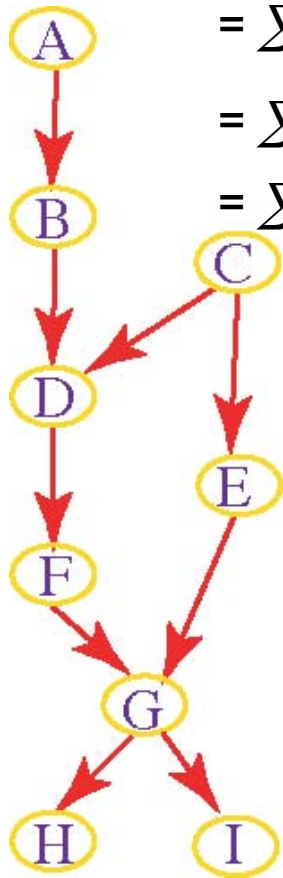


Elimination ordering: A, C, E, I, **B**, D, F

Recap: VE example: compute $P(G|H=h_1)$

Step 4: sum out non- query variables (one at a time)

$$\begin{aligned}
 P(G, H=h_1) &= \sum_{A,B,C,D,E,F,I} f_0(A) f_1(B,A) f_2(C) f_3(D,B,C) f_4(E,C) f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) \\
 &= \sum_{B,C,D,E,F,I} f_2(C) f_3(D,B,C) f_4(E,C) f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) \\
 &= \sum_{B,D,E,F,I} f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) f_{11}(B,D,E) \\
 &= \sum_{B,D,F,I} f_5(F, D) f_9(G) f_8(I,G) f_{10}(B) f_{12}(G,F,B,D) \\
 &= \sum_{B,D,F} f_5(F, D) f_9(G) f_{10}(B) f_{12}(G,F,B,D) f_{13}(G) \\
 &= \sum_{D,F} f_5(F, D) f_9(G) f_{11}(G,F) f_{12}(G) f_{14}(G,F,D) \\
 &= \sum_F f_9(G) f_{11}(G,F) f_{12}(G) f_{15}(G,F)
 \end{aligned}$$

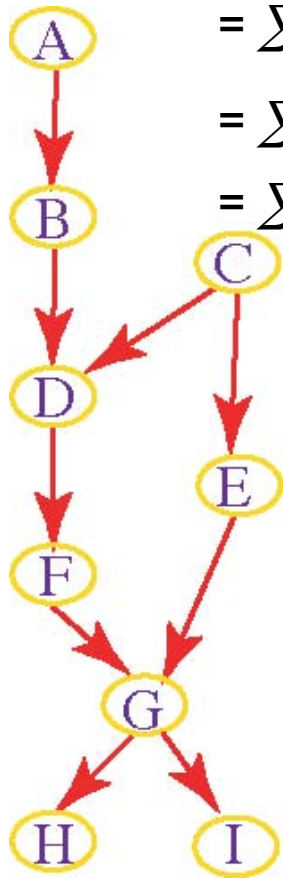


Elimination ordering: A, C, E, I, B, **D**, F

Recap: VE example: compute $P(G|H=h_1)$

Step 4: sum out non- query variables (one at a time)

$$\begin{aligned}
 P(G, H=h_1) &= \sum_{A,B,C,D,E,F,I} f_0(A) f_1(B,A) f_2(C) f_3(D,B,C) f_4(E,C) f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) \\
 &= \sum_{B,C,D,E,F,I} f_2(C) f_3(D,B,C) f_4(E,C) f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) \\
 &= \sum_{B,D,E,F,I} f_5(F, D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) f_{11}(B,D,E) \\
 &= \sum_{B,D,F,I} f_5(F, D) f_9(G) f_8(I,G) f_{10}(B) f_{12}(G,F,B,D) \\
 &= \sum_{B,D,F} f_5(F, D) f_9(G) f_{10}(B) f_{12}(G,F,B,D) f_{13}(G) \\
 &= \sum_{D,F} f_5(F, D) f_9(G) f_{11}(G,F) f_{12}(G) f_{14}(G,F,D) \\
 &= \sum_F f_9(G) f_{11}(G,F) f_{12}(G) f_{15}(G,F) \\
 &= f_9(G) f_{12}(G) f_{16}(G)
 \end{aligned}$$

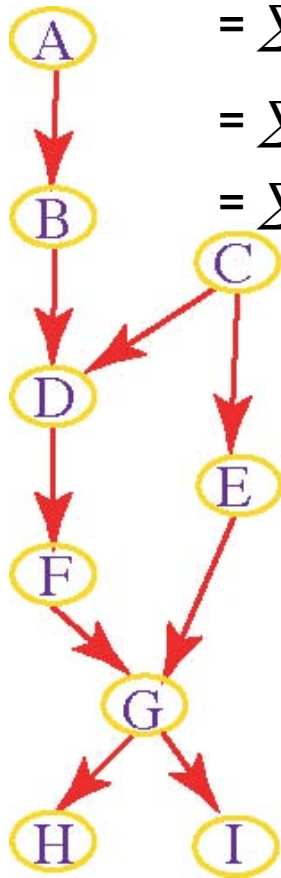


Elimination ordering: A, C, E, I, B, D, **F**

Recap: VE example: compute $P(G|H=h_1)$

Step 5: multiply the remaining factors

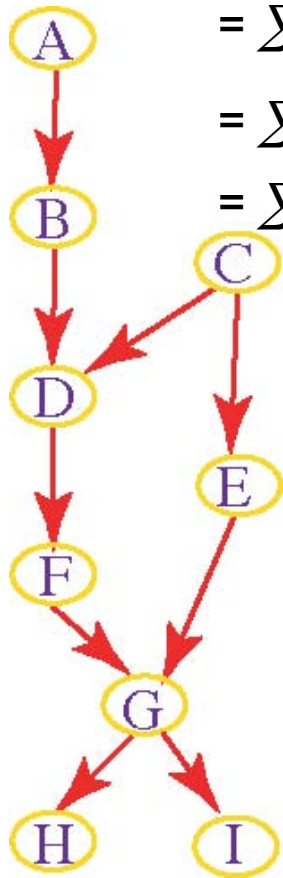
$$\begin{aligned}
 P(G, H=h_1) &= \sum_{A,B,C,D,E,F,I} f_0(A) f_1(B,A) f_2(C) f_3(D,B,C) f_4(E,C) f_5(F,D) f_6(G,F,E) f_9(G) f_8(I,G) \\
 &= \sum_{B,C,D,E,F,I} f_2(C) f_3(D,B,C) f_4(E,C) f_5(F,D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) \\
 &= \sum_{B,D,E,F,I} f_5(F,D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) f_{11}(B,D,E) \\
 &= \sum_{B,D,F,I} f_5(F,D) f_9(G) f_8(I,G) f_{10}(B) f_{12}(G,F,B,D) \\
 &= \sum_{B,D,F} f_5(F,D) f_9(G) f_{10}(B) f_{12}(G,F,B,D) f_{13}(G) \\
 &= \sum_{D,F} f_5(F,D) f_9(G) f_{11}(G,F) f_{12}(G) f_{14}(G,F,D) \\
 &= \sum_F f_9(G) f_{11}(G,F) f_{12}(G) f_{15}(G,F) \\
 &= f_9(G) f_{12}(G) f_{16}(G) \\
 &= f_{17}(G)
 \end{aligned}$$



Recap: VE example: compute $P(G|H=h_1)$

Step 6: normalize

$$\begin{aligned}
 P(G, H=h_1) &= \sum_{A,B,C,D,E,F,I} f_0(A) f_1(B,A) f_2(C) f_3(D,B,C) f_4(E,C) f_5(F,D) f_6(G,F,E) f_9(G) f_8(I,G) \\
 &= \sum_{B,C,D,E,F,I} f_2(C) f_3(D,B,C) f_4(E,C) f_5(F,D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) \\
 &= \sum_{B,D,E,F,I} f_5(F,D) f_6(G,F,E) f_9(G) f_8(I,G) f_{10}(B) f_{11}(B,D,E) \\
 &= \sum_{B,D,F,I} f_5(F,D) f_9(G) f_8(I,G) f_{10}(B) f_{12}(G,F,B,D) \\
 &= \sum_{B,D,F} f_5(F,D) f_9(G) f_{10}(B) f_{12}(G,F,B,D) f_{13}(G) \\
 &= \sum_{D,F} f_5(F,D) f_9(G) f_{11}(G,F) f_{12}(G) f_{14}(G,F,D) \\
 &= \sum_F f_9(G) f_{11}(G,F) f_{12}(G) f_{15}(G,F) \\
 &= f_9(G) f_{12}(G) f_{16}(G) \\
 &= f_{17}(G)
 \end{aligned}$$



$$P(G = g \mid H = h_1) = \frac{f_{17}(g)}{\sum_{g' \in \text{dom}(G)} f_{17}(g')}$$

Aispace: Belief and Decision Networks Applet

- <http://aispace.org/bayes/> implements VE_BN.
- Try some of the sample problems.
- Provide some evidence (symptoms) and query some of the causes.
- Observe how the posterior probability of the causes changes from the prior as you add more evidence.
- Switch from Brief mode to Verbose mode to see the factors generated.
- Experiment with different elimination orderings.

Complexity of Variable Elimination (VE)

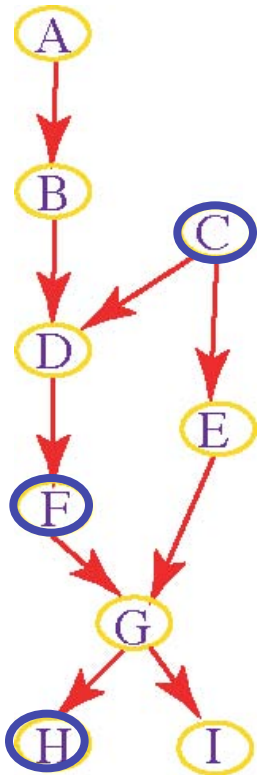
- A factor over n binary variables has to store 2^n numbers
 - The initial factors are typically quite small (variables typically only have few parents in Bayesian networks)
 - But variable elimination constructs larger factors by multiplying factors together
- The complexity of VE is exponential in the maximum number of variables in any factor during its execution
 - This number is called the **treewidth of a graph** (along an ordering)
 - Elimination ordering influences treewidth
- Finding the best ordering is NP-complete
 - I.e., the ordering that generates the minimum treewidth
 - Heuristics work well in practice (e.g. least connected variables first)
 - Even with best ordering, inference is sometimes infeasible
 - In those cases, we need approximate inference. See CS422 & CS540

Lecture Overview

- Variable elimination: recap and some more details
- ➔ Variable elimination: pruning irrelevant variables
- Summary of Reasoning under Uncertainty
- Decision Theory
 - Intro
 - Time-permitting: Single-Stage Decision Problems

VE and conditional independence

- So far, we haven't use conditional independence!
 - Before running VE, we can prune all variables Z that are conditionally independent of the query Y given evidence E : $Z \perp\!\!\!\perp Y \mid E$

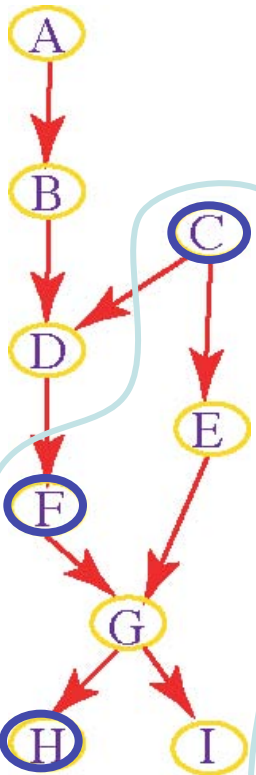


- Example: which variables can we prune for the query $P(G=g \mid C=c_1, F=f_1, H=h_1)$?



VE and conditional independence

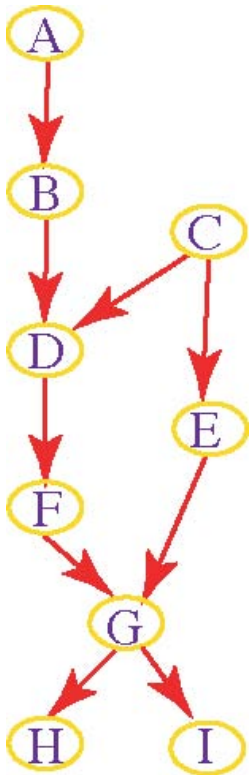
- So far, we haven't use conditional independence!
 - Before running VE, we can prune all variables Z that are conditionally independent of the query Y given evidence E : $Z \perp\!\!\!\perp Y \mid E$



- Example: which variables can we prune for the query $P(G=g \mid C=c_1, F=f_1, H=h_1)$?
 - A, B, and D. Both paths are blocked
 - F is observed node in chain structure
 - C is an observed common parent
 - Thus, we only need to consider this subnetwork

One last trick

- We can also prune unobserved leaf nodes
 - And we can do so recursively

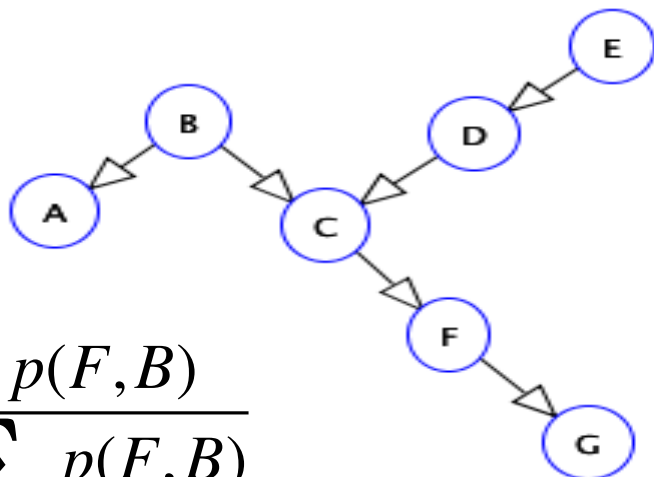


E.g., which nodes can we prune if the query is $P(A)$?



Recursively prune unobserved leaf nodes:
we can prune all nodes other than A !

Elimination of Irrelevant Variables in VE



$$p(F | B) = \frac{p(F, B)}{\sum_f p(F, B)}$$

$$p(F, B) = \sum_c \sum_d \sum_e p(B)p(F | C)p(C | B, D)p(D | E)p(E)$$

$$p(F, B) = \sum_c \sum_d p(B)p(F | C)p(C | B, D)f_1(D)$$

$$p(F, B) = \sum_c p(B)p(F | C)f_2(C, B)$$

$$p(F, B) = p(B)f_3(B, F)$$

$$p(F, B) = f_4(B, F)$$

Lecture Overview

- Variable elimination: recap and some more details
- Variable elimination: pruning irrelevant variables
- ➔ Summary of Reasoning under Uncertainty
- Decision Theory
 - Intro
 - Time-permitting: Single-Stage Decision Problems

Big picture: Reasoning Under Uncertainty

Probability Theory

— you know

Bayesian Networks &
Variable Elimination

Dynamic Bayesian
Networks

Hidden Markov Models &
Filtering

Monitoring
(e.g. credit card
fraud detection)

Bioinformatics

Motion Tracking,
Missile Tracking, etc

Natural Language
Processing

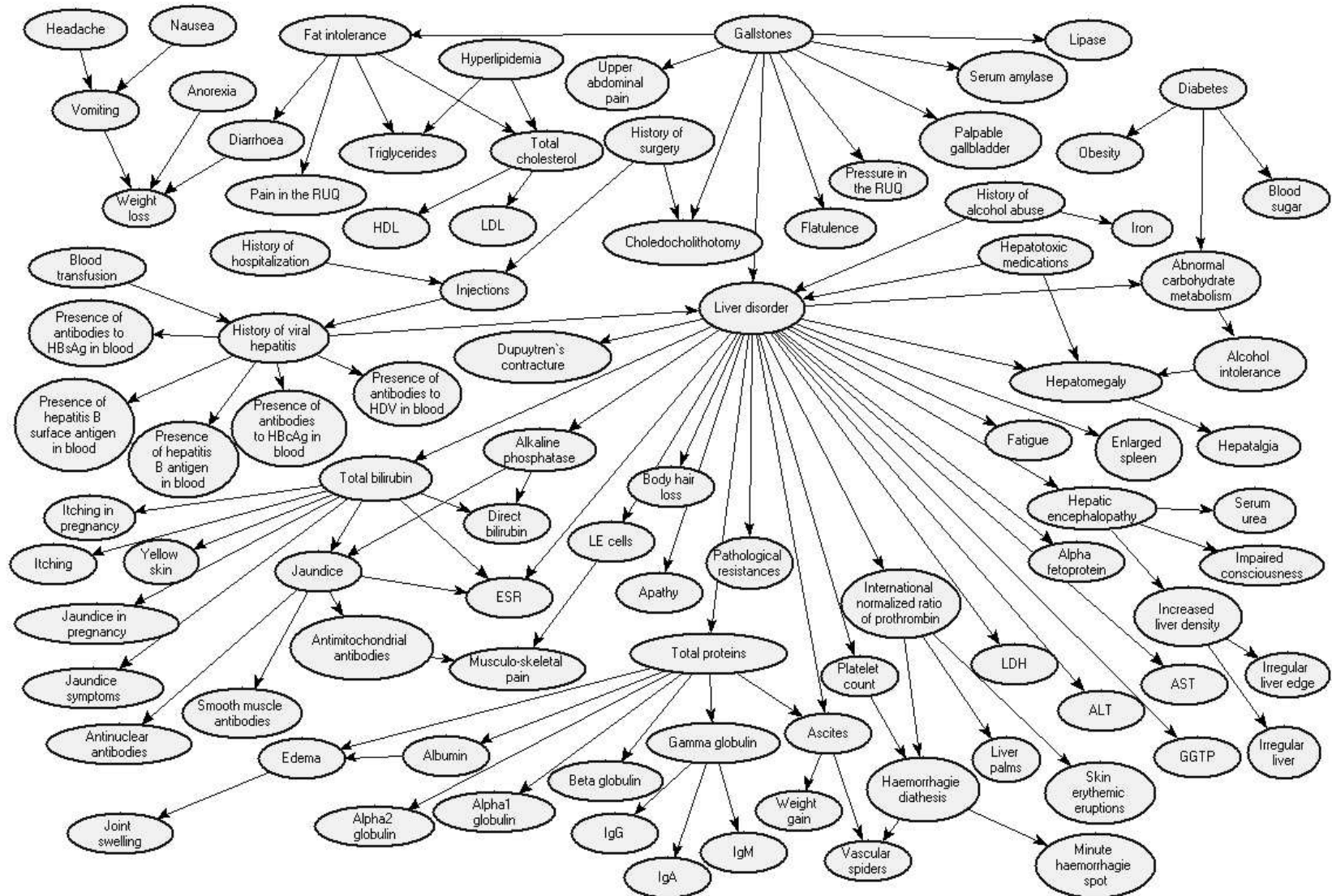
Diagnostic systems
(e.g. medicine)

Email spam filters

Some Applications

One Realistic BN: Liver Diagnosis

Source: Onisko et al., 1999



~60 nodes, max 4 parents per node

Course Overview

Course Module

Environment

Deterministic

Stochastic

Representation

Reasoning
Technique

Problem Type

Constraint
Satisfaction

Arc
Consistency
Variables + Constraints
Search

This concludes
the uncertainty
module

Static

Logic

Logics
Search
*Bayesian
Networks*
Variable
Elimination

Uncertainty

Sequential

Planning

STRIPS
Search
As CSP (using
arc consistency)
*Decision
Networks*
Variable
Elimination
Markov Processes
Value
Iteration

Decision
Theory

Course Overview

Course Module

Environment

Deterministic

Stochastic

Problem Type

Constraint Satisfaction

Arc Consistency

Variables + Constraints Search

Logic

Logics Search

Bayesian Networks

Variable Elimination

But uncertainty is also at the core of decision theory: now we're **acting** under uncertainty

Uncertainty

Sequential

Planning

STRIPS Search

As CSP (using arc consistency)

Decision Networks

Variable Elimination

Decision Theory

Markov Processes

Value Iteration

Lecture Overview

- Variable elimination: recap and some more details
- Summary of Reasoning under Uncertainty
- Decision Theory
 - Intro
 - Time-permitting: Single-Stage Decision Problems

Decisions Under Uncertainty: Intro

- Earlier in the course, we focused on decision making in deterministic domains
 - Search/CSPs: single-stage decisions
 - Planning: sequential decisions
- Now we face **stochastic domains**
 - so far we've considered how to represent and update beliefs
 - What if an agent has to make decisions under uncertainty?
- Making decisions under uncertainty is important
 - We mainly represent the world probabilistically so we can use our beliefs as the basis for making decisions

Decisions Under Uncertainty: Intro

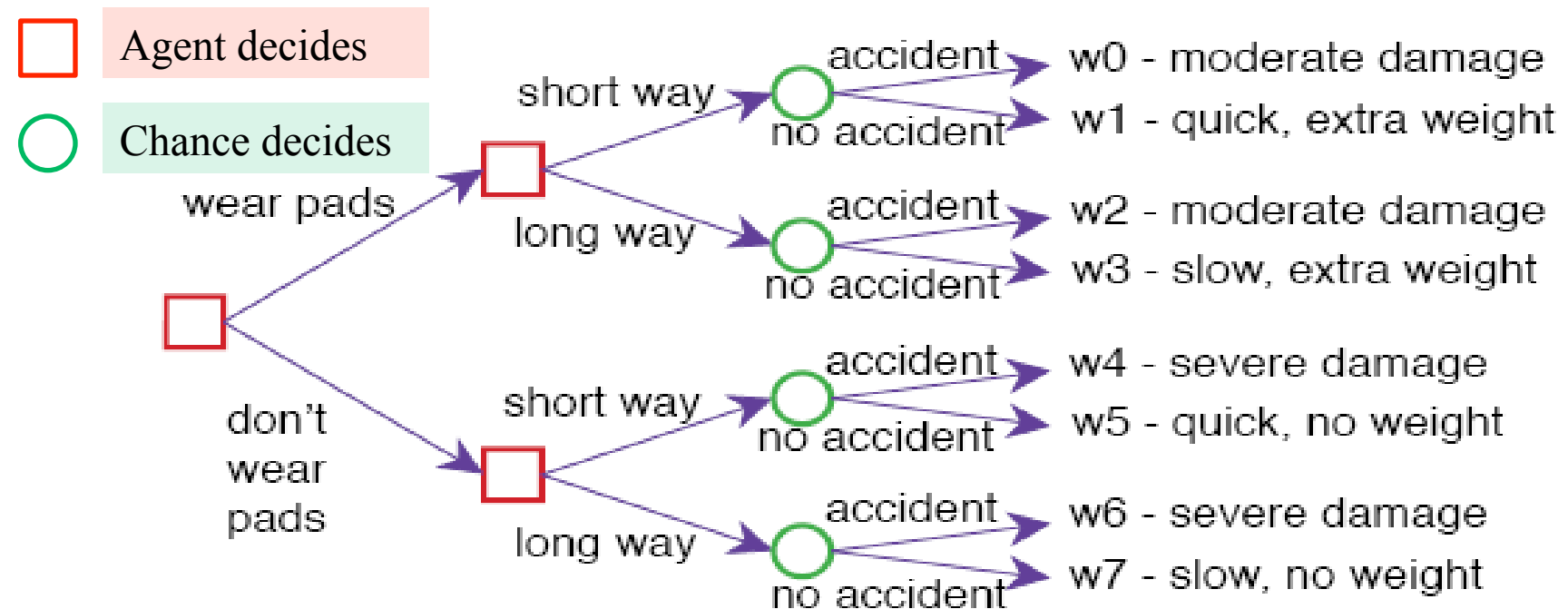
- An agent's decision will depend on
 - What actions are available
 - What beliefs the agent has
 - Which goals the agent has
- Differences between deterministic and stochastic setting
 - Obvious difference in representation: need to represent our uncertain **beliefs**
 - Now we'll speak about representing **actions** and **goals**
 - Actions will be pretty straightforward: **decision variables**
 - Goals will be interesting: we'll move from all-or-nothing goals to a richer notion: rating **how happy the agent is** in different situations.
 - Putting these together, we'll extend Bayesian Networks to make a new representation called **Decision Networks**

Lecture Overview

- Variable elimination: recap and some more details
- Variable elimination: pruning irrelevant variables
- Summary of Reasoning under Uncertainty
- Decision Theory
 - Intro
 - – Time-permitting: Single-Stage Decision Problems

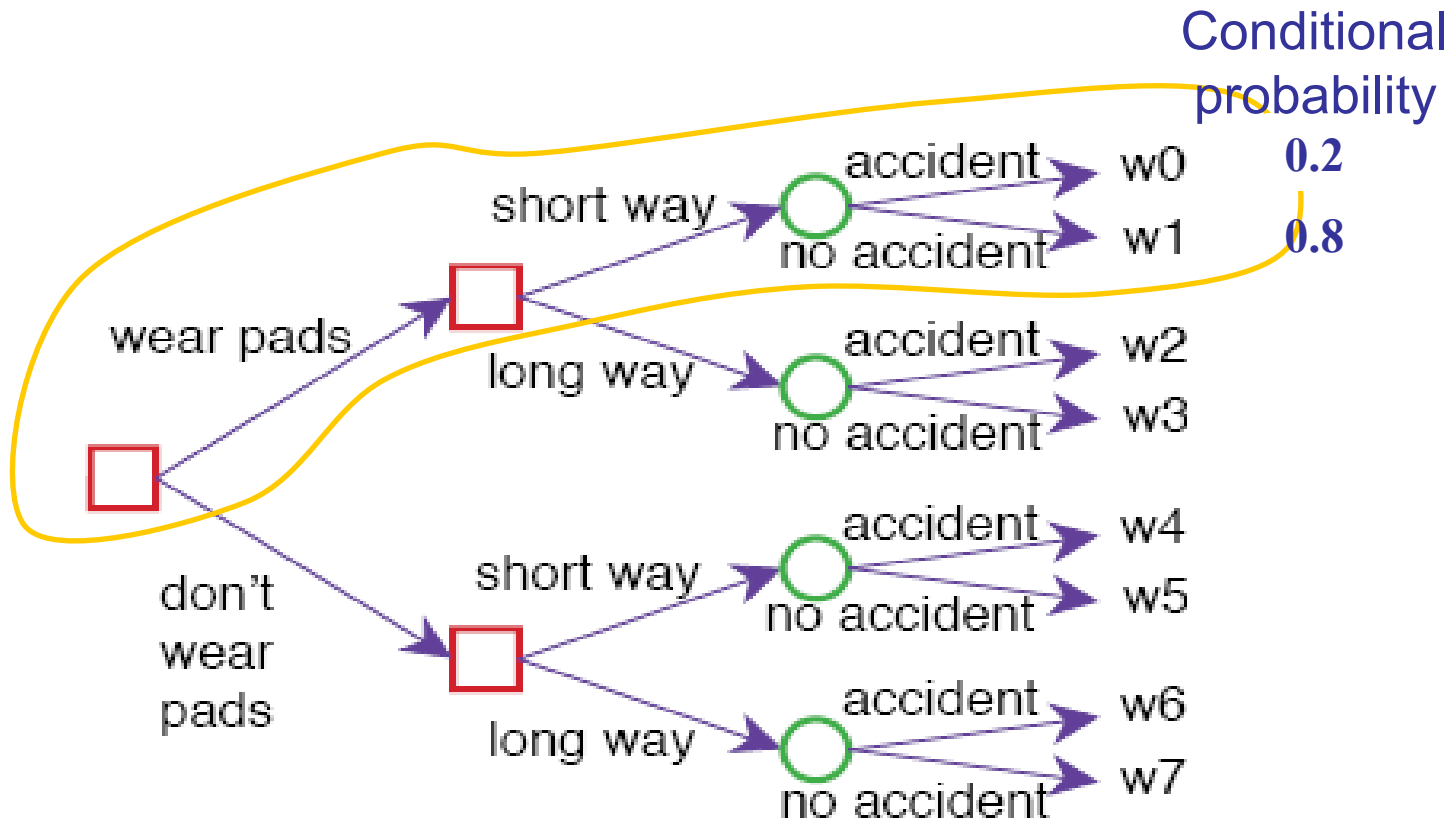
Delivery Robot Example

- Decision variable 1: the robot can choose to wear pads
 - Yes: protection against accidents, but extra weight
 - No: fast, but no protection
- Decision variable 2: the robot can choose the way
 - Short way: quick, but higher chance of accident
 - Long way: safe, but slow
- Random variable: is there an accident?



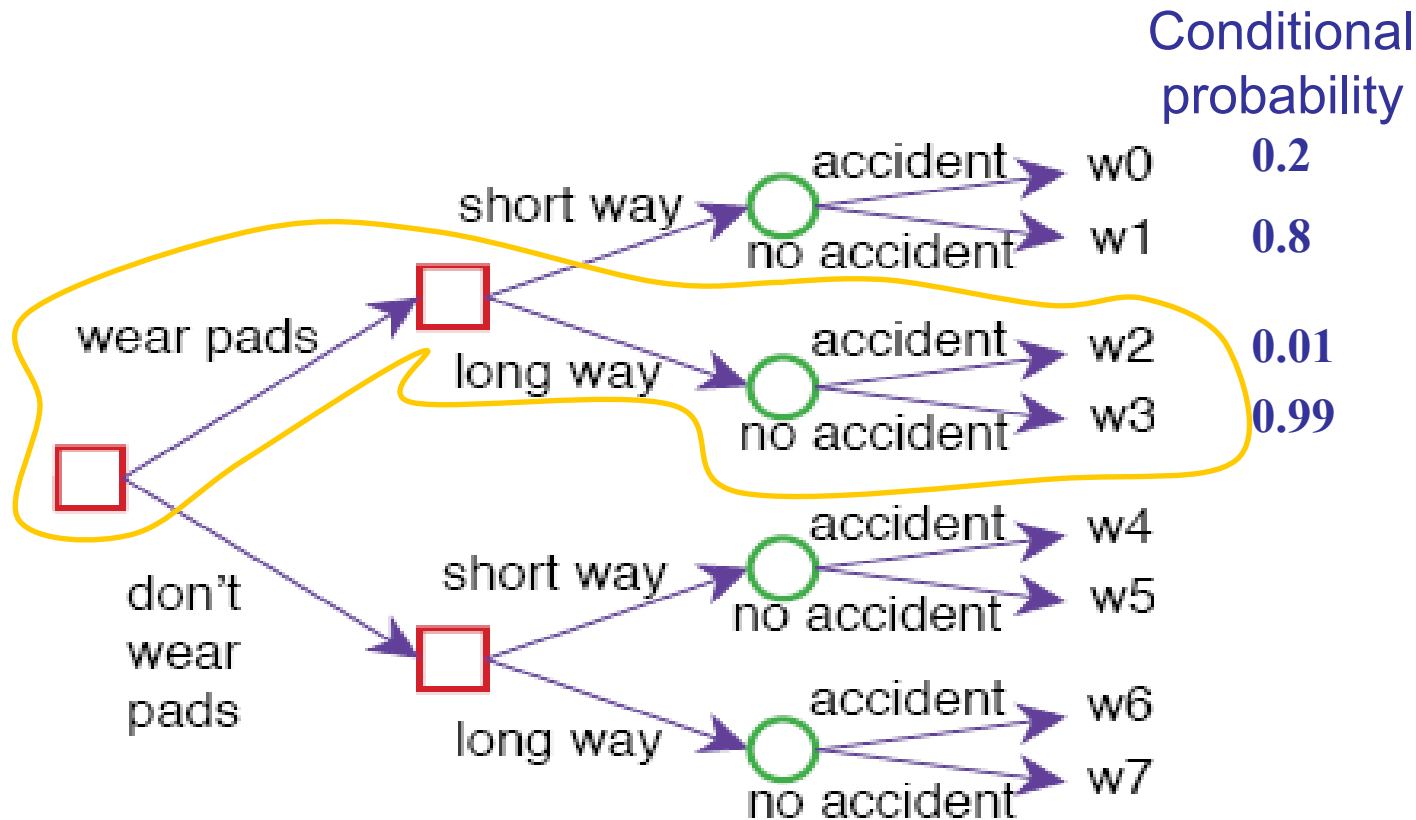
Possible worlds and decision variables

- A **possible world** specifies a value for each random variable and each decision variable
- For each assignment of values to all decision variables
 - the probabilities of the worlds satisfying that assignment sum to 1.



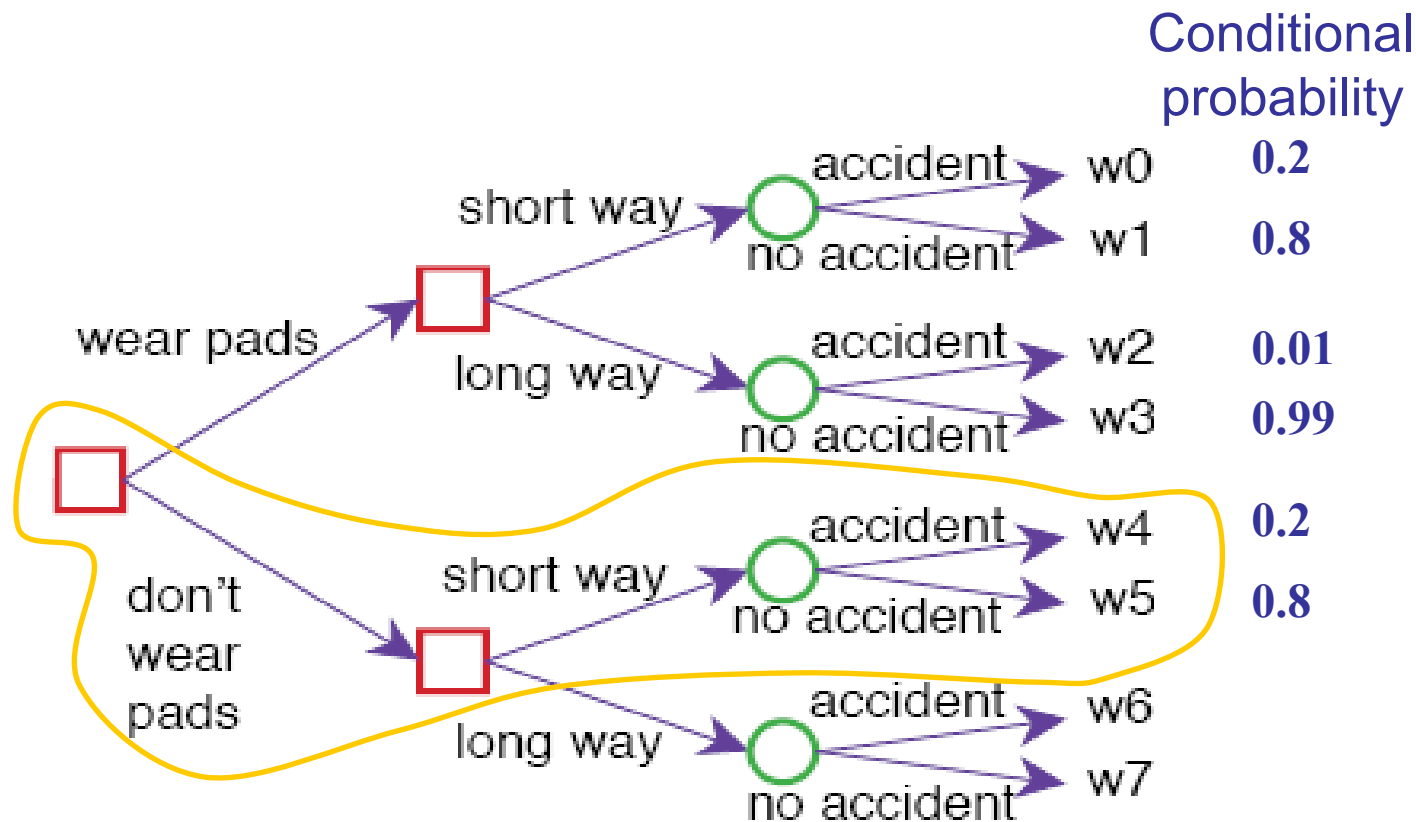
Possible worlds and decision variables

- A **possible world** specifies a value for each random variable and each decision variable
- For each assignment of values to all decision variables
 - the probabilities of the worlds satisfying that assignment sum to 1.



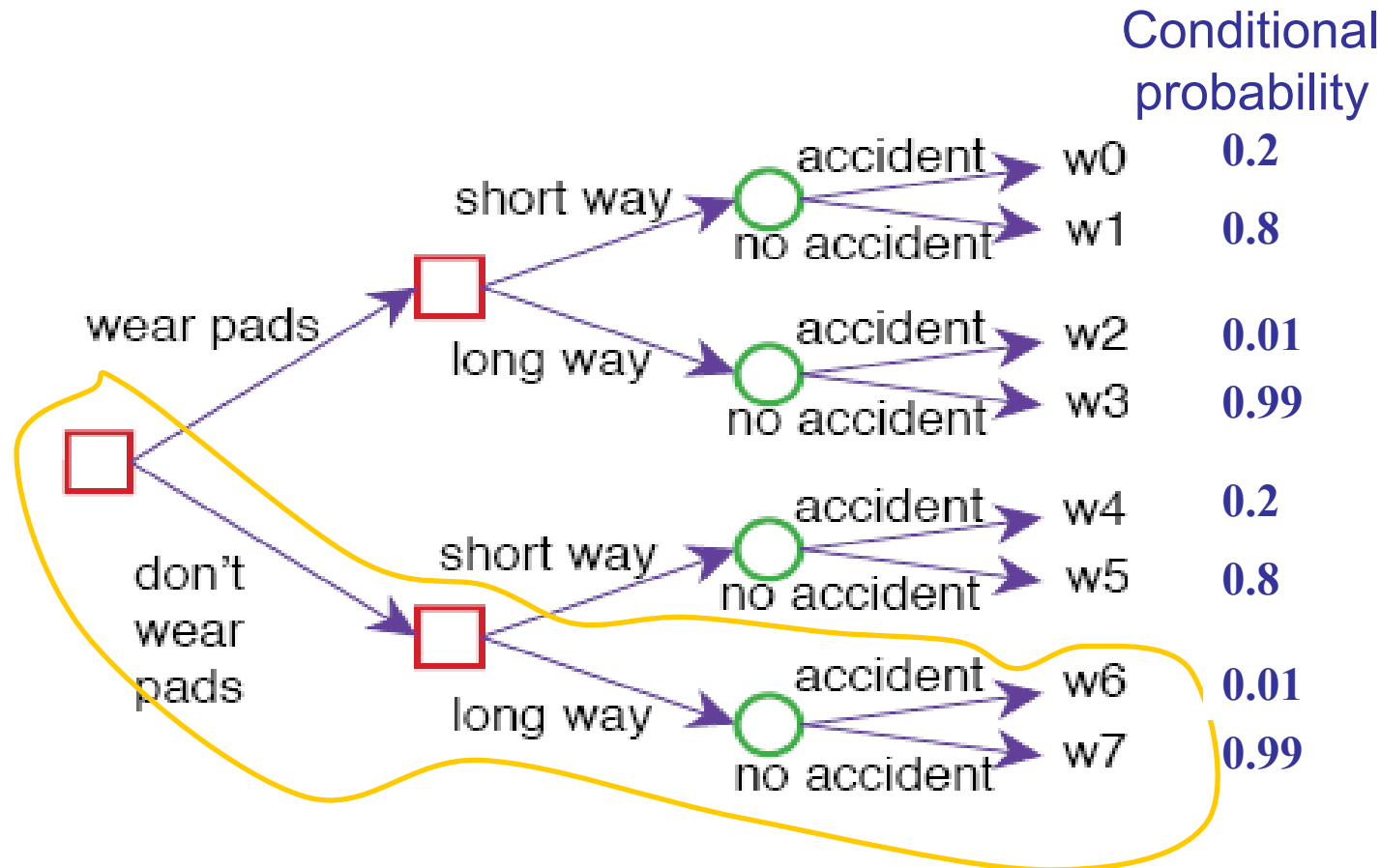
Possible worlds and decision variables

- A **possible world** specifies a value for each random variable and each decision variable
- For each assignment of values to all decision variables
 - the probabilities of the worlds satisfying that assignment sum to 1.



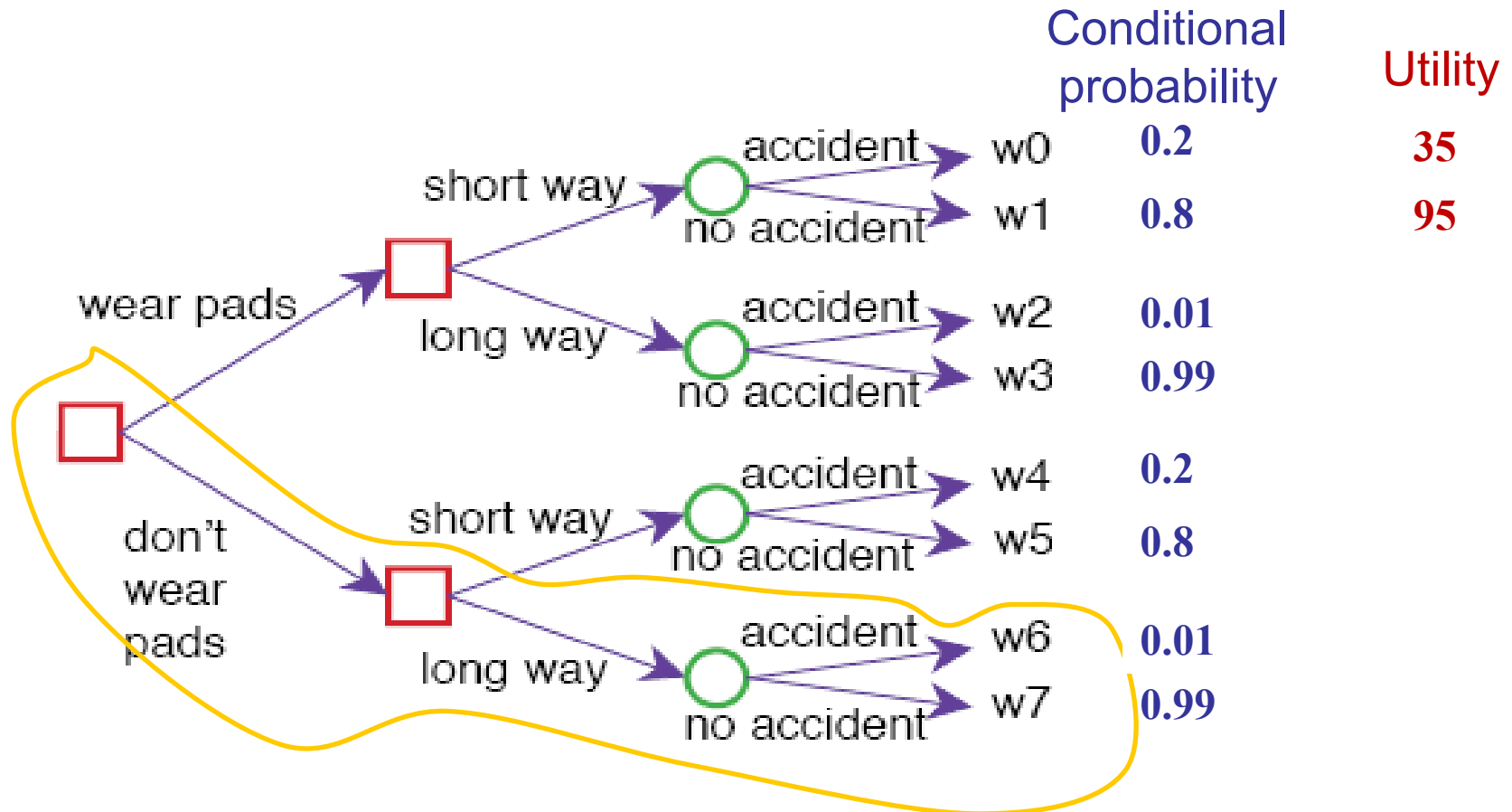
Possible worlds and decision variables

- A **possible world** specifies a value for each random variable and each decision variable
- For each assignment of values to all decision variables
 - the probabilities of the worlds satisfying that assignment sum to 1.



Possible worlds and decision variables

- A **possible world** specifies a value for each random variable and each decision variable
- For each assignment of values to all decision variables
 - the probabilities of the worlds satisfying that assignment sum to 1.

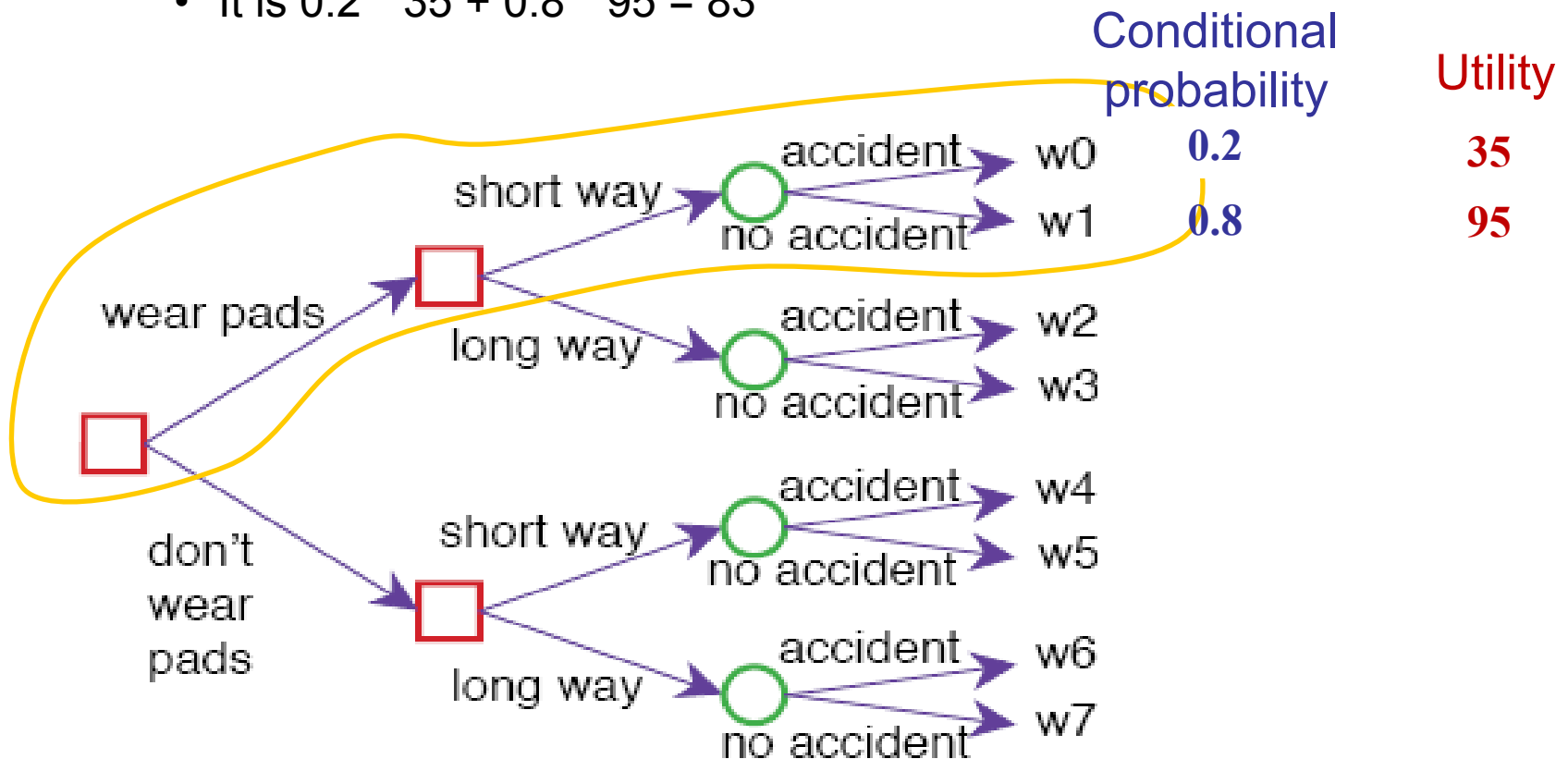


Utility

- **Utility**: a measure of desirability of possible worlds to an agent
 - Let U be a real-valued function such that $U(w)$ represents an agent's degree of preference for world w
 - Expressed by a number in $[0,100]$
- Simple goals can still be specified
 - Worlds that satisfy the goal have utility 100
 - Other worlds have utility 0
- Utilities can be more complicated
 - For example, in the robot delivery domains, they could involve
 - Amount of damage
 - Reached the target room?
 - Energy left
 - Time taken

Combining probabilities and utilities

- We can combine probability with utility
 - The expected utility of a probability distribution over possible worlds average utility, weighted by probabilities of possible worlds
 - What is the **expected utility** of Wearpads=yes, Way=short ?
 - It is $0.2 * 35 + 0.8 * 95 = 83$



Expected utility

- Suppose $U(w)$ is the utility of possible world w and $P(w)$ is the probability of possible world w

Definition (expected utility)

The **expected utility** is

$$E[U] = \sum_w P(w)U(w)$$

Definition (expected utility)

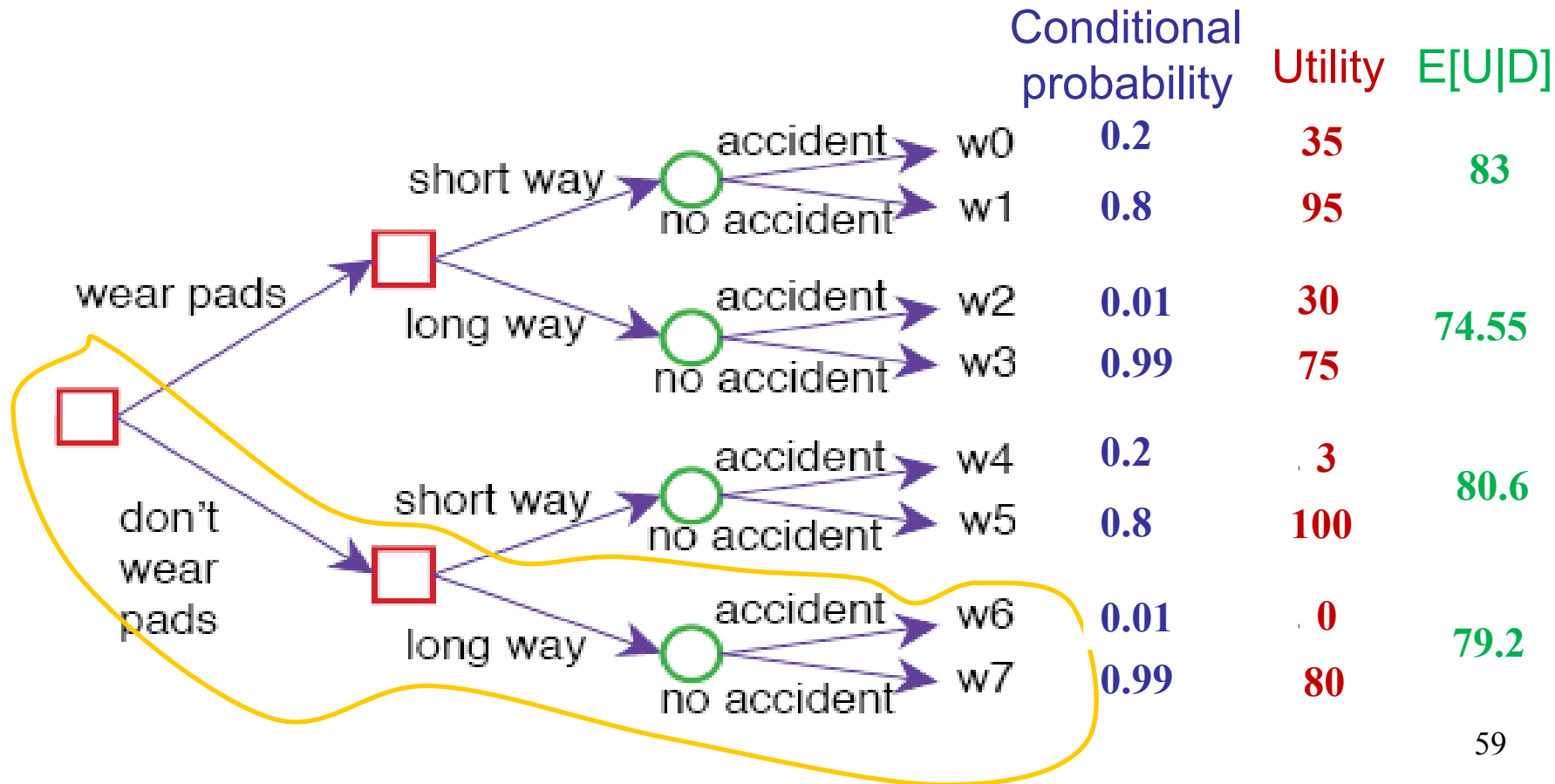
The **conditional expected utility** given e is

$$E[U|e] = \sum_w P(w|e)U(w)$$

Expected utility of a decision

- We write the **expected utility of a decision** as:

$$E[U|D = d] = \sum_w P(w|D = d)U(w)$$



Optimal single-stage decision

- Given a single decision variable D
 - the agent can choose $D=d_i$ for any value $d_i \in \text{dom}(D)$

Definition (optimal single-stage decision)

An **optimal single-stage decision** is the decision $D=d_{\max}$ whose expected value is maximal:

$$d_{\max} \in \operatorname{argmax}_{d_i \in \text{dom}(D)} E[U|D=d_i]$$

Learning Goals For Today's Class

- Variable elimination
 - Carry out variable elimination by using factor representation and using the factor operations
 - Define a Utility Function on possible worlds
 - Define and compute optimal one-off decisions
-
- Assignment 4 is due next Wednesday
 - Please complete the Teaching Evaluation