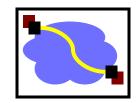


## 416 Distributed Systems

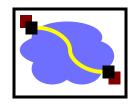
Time Synchronization
(Part 2: Lamport and vector clocks)
Feb 5, 2018

### Important Lessons (last lecture)



- Clocks on different systems will always behave differently
  - Skew and drift between clocks
- Time disagreement between machines can result in undesirable behavior
- Clock synchronization
  - Rely on a time-stamped network messages
  - Estimate delay for message transmission
  - Can synchronize to UTC or to local source
  - Clocks never exactly synchronized
- Often inadequate for distributed systems
  - might need totally-ordered events
  - might need millionth-of-a-second precision

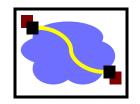
### Today's Lecture



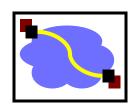
Need for time synchronization

- Time synchronization techniques
- Lamport Clocks

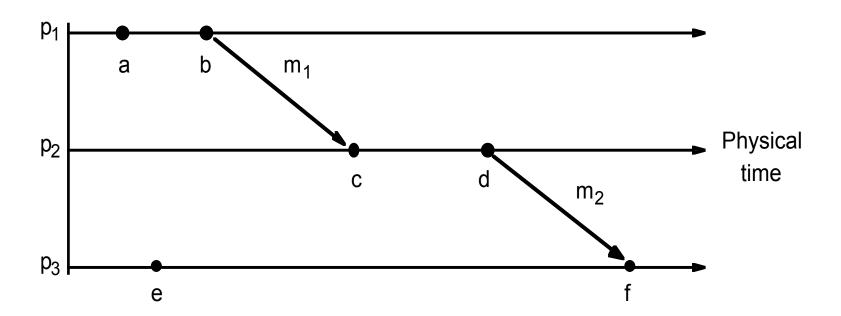
#### Logical time

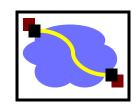


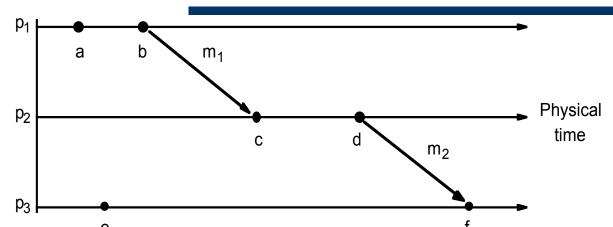
- Capture just the "happens before" relationship between events
  - Discard the infinitesimal granularity of time
  - Corresponds roughly to causality



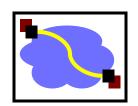
Events at three processes

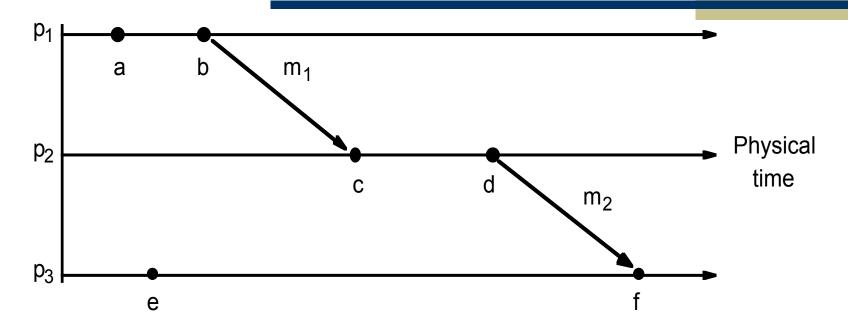




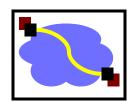


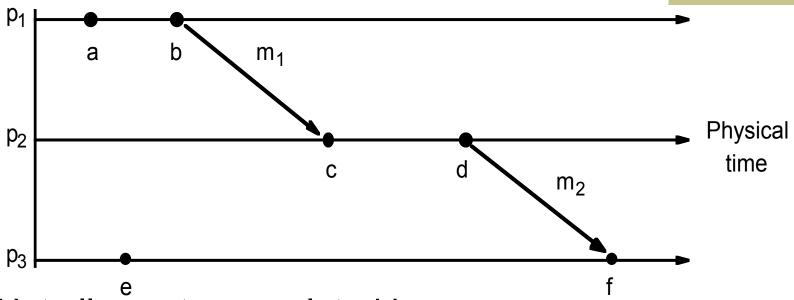
- Instead of synchronizing clocks, event ordering can be used
  - If two events occurred at the same process p<sub>i</sub> (i = 1, 2, ... N) then they occurred in the order observed by p<sub>i</sub>, that is the definition of:
     → i
  - When a message, m is sent between two processes, send(m) 'happens before' receive(m)
  - 3. The 'happened before' relation is transitive
- The happened before relation (→) is necessary for causal ordering



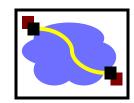


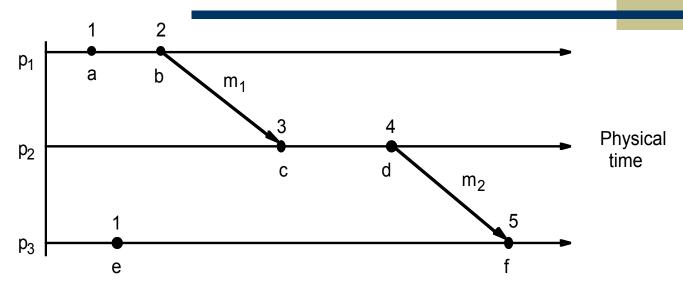
- $a \rightarrow b$  (at  $p_1$ )  $c \rightarrow d$  (at  $p_2$ )
- $b \rightarrow c$  because of  $m_1$
- also  $d \rightarrow f$  because of  $m_2$



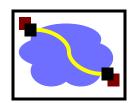


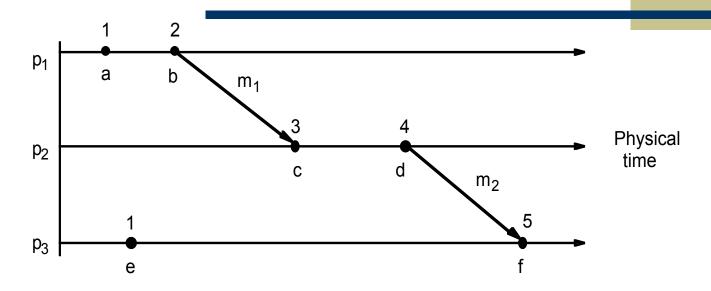
- Not all events are related by →
- Consider a and e (different processes and no chain of messages to relate them)
  - they are not related by →; they are said to be concurrent
  - written as a || e



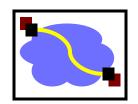


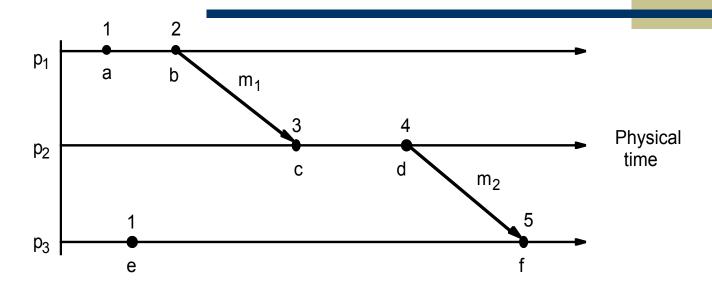
- A logical clock is a monotonically increasing software counter
  - It need not relate to a physical clock.
- Each process  $p_i$  has a logical clock,  $L_i$  which can be used to apply logical timestamps to events
  - Rule 0: initially all clocks are set to 0
  - Rule 1: L<sub>i</sub> is incremented by 1 before each event at process p<sub>i</sub>
  - Rule 2:
    - (a) when process  $p_i$  sends message m, it piggybacks  $t = L_i$
    - (b) when  $p_j$  receives (m,t) it sets  $L_j := max(L_j, t)$  and applies rule 1 before timestamping the event receive (m)



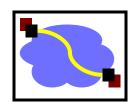


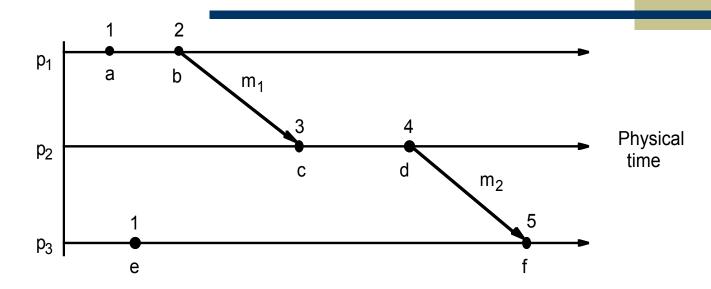
- each of p<sub>1</sub>, p<sub>2</sub>, p<sub>3</sub> has its logical clock initialised to zero,
- the clock values are those immediately after the event.
- e.g. 1 for a, 2 for b.
- for m<sub>1</sub>, 2 is piggybacked and c gets max(0,2)+1 = 3





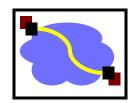
- e →e' (e happened before e') implies L(e)<L(e')</li>
   (where L(e) is Lamport clock value of event e)
- The converse is not true, that is L(e) < L(e') does not imply  $e \rightarrow e'$ . What's an example of this above?





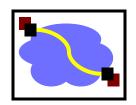
- $e \rightarrow e'$  (e happened before e') implies L(e) < L(e')
- The converse is not true, that is L(e)<L(e') does not imply e →e'</li>
  - e.g. L(b) > L(e) but  $b \parallel e$

## Lamport logical clocks



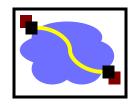
- Lamport clock L orders events consistent with logical "happens before" ordering
  - If  $e \rightarrow e'$ , then L(e) < L(e')
- But not the converse
  - *L*(*e*) < *L*(*e*') does not imply *e* → *e*'
- Similar rules for concurrency
  - L(e) = L(e') implies e | e' (for distinct e,e')
  - $e \parallel e'$  does not imply L(e) = L(e')
  - i.e., Lamport clocks arbitrarily order some concurrent events

### Total-order Lamport clocks



- Many systems require a total-ordering of events, not a partial-ordering
- Use Lamport's algorithm, but break ties using the process ID; one example scheme:
  - $L(e) = M * L_i(e) + i$ 
    - M = maximum number of processes
    - i = process ID

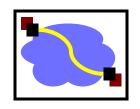
#### **Question Break**



- Why does Lamport's algorithm not produce a true total ordering?
- Is it true that  $L(e) \not < L(e')$  implies  $e \not\rightarrow e'$ ?

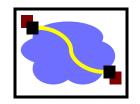
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### Today's Lecture



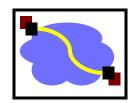
Need for time synchronization

- Time synchronization techniques
- Lamport Clocks

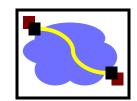


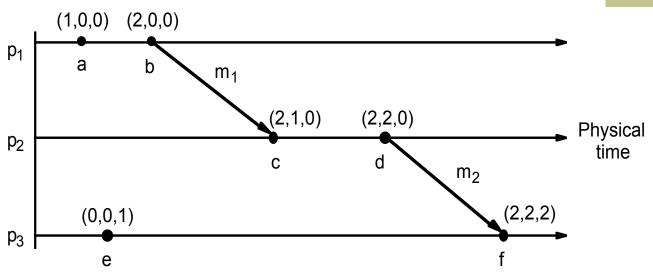
- Vector clocks overcome the shortcoming of Lamport logical clocks
  - L(e) < L(e') does not imply e happened before e'</li>
- Goal
  - Want ordering that matches happened before
  - V(e) < V(e') if and only if e → e'</li>
- Method
  - Label each event by vector V(e) [c<sub>1</sub>, c<sub>2</sub> ..., c<sub>n</sub>]
    - c<sub>i</sub> = # events in process i that precede e

## Vector Clock Algorithm

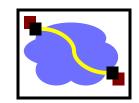


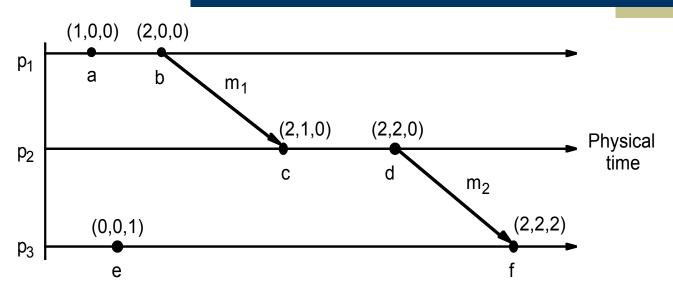
- Initially, all vectors [0,0,...,0]
- For event on process i, increment own c<sub>i</sub>
- Label message sent with local vector
- When process j receives message with vector [d<sub>1</sub>, d<sub>2</sub>, ..., d<sub>n</sub>]:
  - Set each local vector entry k to max(c<sub>k</sub>, d<sub>k</sub>)
  - Increment value of c<sub>i</sub>



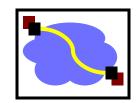


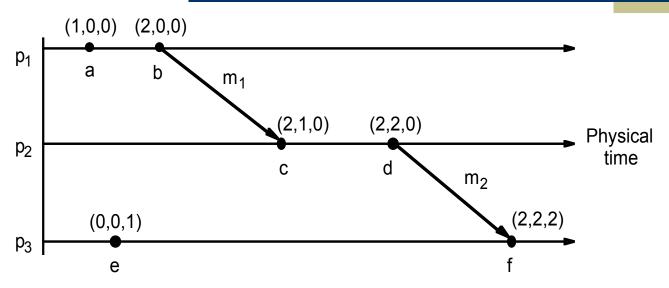
- At p<sub>1</sub>
  - a occurs at (1,0,0); b occurs at (2,0,0)
  - piggyback (2,0,0) on  $m_1$
- At  $p_2$  on receipt of  $m_1$  use max((0,0,0), (2,0,0)) = (2, 0, 0) and add 1 to own element = (2,1,0)
- Meaning of =, <=, max etc for vector timestamps</li>
  - compare elements pairwise





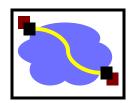
- Note that e → e' implies V(e)<V(e'). The converse is also true
- Can you see a pair of concurrent events; Can you infer they are concurrent from their vectors clocks?





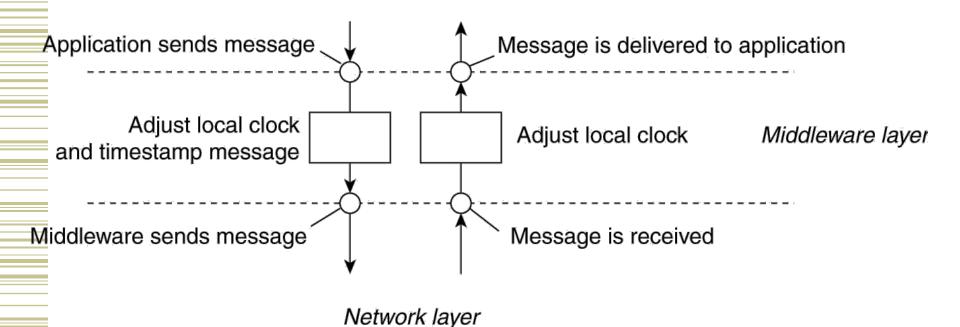
- Note that e → e' implies V(e)<V(e'). The converse is also true</li>
- Can you see a pair of concurrent events?
  - c II e (concurrent) because neither  $V(c) \leftarrow V(e)$  nor  $V(e) \leftarrow V(c)$

## Implementing logical clocks

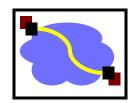


Positioning of logical timestamping in distributed systems.

Application layer

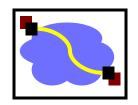


#### Distributed time



- Premise
  - The notion of time is well-defined (and measurable) at each single location
  - But the relationship between time at different locations is unclear
    - Can minimize discrepancies, but never eliminate them
- Reality
  - Stationary GPS receivers can get global time with <</li>
     1µs error
  - Few systems designed to use this; logical clocks key mechanism for ordering
    - Recent exception: (Spanner system from Google)

#### Important Points



- Physical Clocks
  - Can keep closely synchronized, but never perfect
- Logical Clocks
  - Encode happens before relationship (necessary for causality)
  - Lamport clocks provide only one-way encoding
  - Vector clocks precedence necessary for causality (but not sufficient: could have been caused by some event along the path, not all events)