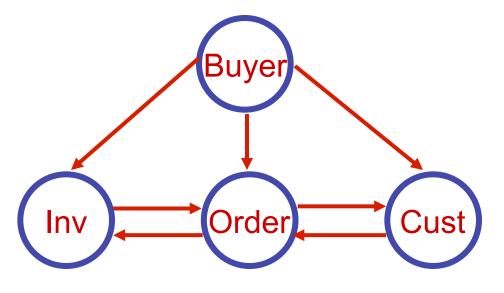
#### **Trans in Distributed Systems**

- A distributed transaction involves
  - \* updates at multiple nodes
  - \* and the messages between those nodes
- For example, buying widgets



#### Distributed Atomic Commit Requirements

- 1. All workers that reach a decision reach the same one
- 2. Workers cannot change their decisions on commit or abort once a decision is made
- 3. To commit all workers must vote commit
- 4. If all workers vote commit and there are no failures the transaction will commit
- 5. If all failures are repaired and there are no more failures each worker will eventually reach a decision (In fact it will be the same decision)

# **2PC and communication topologies**

#### • We have previously focused on centralized 2PC

- \* Why funnel messages through the coordinator?
- \* + None of the worker nodes can influence one another
- \* + Failure of a worker node independent
- \* Put trust in coordinator
- \* Hope coordinator does not fail
- Nothing stopping us from considering alternative communication topologies for 2PC!
- Why? Because other topologies may reduce time or message complexity for the basic 2PC protocol



## 2PC in other topologies

- Two extremes: linear and decentralized
- Linear 2PC: coordinator, and all workers in a single line/chain
  \* Build a protocol that has fewer messages (but more rounds!) than 2PC
- Decentralized 2PC: all workers can communicate with one another
  - \* Build a protocol that has fewer rounds (but more messages!) than 2PC



## Linear 2PC

- Alternative communication topologies in 2PC context
  - \* Why channel messages through the coordinator?
- Decentralized 2PC: all workers can communicate with one another
  - \* Build a protocol that has fewer rounds (but more messages!) than 2PC
- Linear 2PC: coordinator, and all workers in a single line/chain
  - \* C, W1, W2, W3, ... Wn
  - \* Build a protocol that has fewer messages (but more rounds!) than 2PC
  - \* C sends request + its vote to W1, W1 decided commit/abort, forward decision to W2. W2, determines outcome with its own decision, forward to W3, and so on.
  - \* Wn receives commit and decided commit  $\rightarrow$  tx commit! Forward this decision back to front of chain
  - \* Wn receives abort/decides abort -> tx abort! Forward this decision back
  - Note: linear 2PC bundles node/site failure with communication failure.

#### Linear 2PC

- Important note: linear 2PC bundles node/site failure with communication failure.
- Why is this important?
- Analysis for linear 2PC:
  - \* 2n rounds
  - \* 2n messages



#### **Decentralized 2PC**

- Alternative communication topologies in 2PC context
  - \* Why channel messages through the coordinator?
- Decentralized 2PC: all workers can communicate with one another
  - \* Build a protocol that has fewer rounds (but more messages!) than 2PC
  - \* Complete graph communication topology
  - \* Coordinate votes and sends it's decision (commit/abort) along with prepareToCommit to workers
  - \* Workers broadcast their choice to all other workers (n^2 messages!)
  - \* Workers collect votes, and figure out the final transaction outcome
- 2 rounds -- Can we do better than 2 rounds?
- Approx: n+(n+1)^2 messages (n=number of nodes)

